view_frames Result Recorded at time: 1507805921.010 base_link Broadcaster: /base_to_laser_link Broadcaster: /base_to_kinect_link Broadcaster: /base_to_arm_link Average rate: 10.264 Hz Average rate: 10.281 Hz Average rate: 10.275 Hz Most recent transform: 1507805921.106 (-0.096 sec old) Most recent transform: 1507805921.033 (-0.023 sec old) Most recent transform: 1507805921.068 (-0.058 sec old) Buffer length: 4.863 sec Buffer length: 4.871 sec Buffer length: 4.866 sec kinect2_link base_arm laser Broadcaster: /kinect2 Broadcaster: /robot_state_publisher Average rate: 93.679 Hz Average rate: 20.067 Hz Most recent transform: 1507805921.005 (0.005 sec old) Most recent transform: 1507805920.963 (0.048 sec old) Buffer length: 4.942 sec Buffer length: 4.884 sec geoJoint1 kinect2_rgb_optical_frame Broadcaster: /kinect2 Broadcaster: /robot_state_publisher Average rate: 93.679 Hz Average rate: 20.067 Hz Most recent transform: 1507805921.005 (0.005 sec old) Most recent transform: 1507805920.963 (0.048 sec old) Buffer length: 4.942 sec Buffer length: 4.884 sec geoJoint2 kinect2_ir_optical_frame Broadcaster: /robot_state_publisher Average rate: 20.067 Hz Most recent transform: 1507805920.963 (0.048 sec old) Buffer length: 4.884 sec geoJoint3 Broadcaster: /robot_state_publisher Average rate: 20.067 Hz Most recent transform: 1507805920.963 (0.048 sec old) Buffer length: 4.884 sec geoJoint4 Broadcaster: /robot_state_publisher Average rate: 20.067 Hz Most recent transform: 1507805920.963 (0.048 sec old) Buffer length: 4.884 sec geoJoint5 Broadcaster: /robot_state_publisher Average rate: 20.067 Hz Most recent transform: 1507805920.963 (0.048 sec old) Buffer length: 4.884 sec geoJoint6 Broadcaster: /robot state publisher Average rate: 50.202 Hz Most recent transform: 1507805921.496 (-0.485 sec old) Buffer length: 4.940 sec gripperBody Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 20.067 Hz Average rate: 20.067 Hz Most recent transform: 1507805920.963 (0.048 sec old) Most recent transform: 1507805920.963 (0.048 sec old) Buffer length: 4.884 sec Buffer length: 4.884 sec gripperFinger1 gripperFinger2