view_frames Result Recorded at time: 1507801743.563 kinect2_link base_link Broadcaster: /kinect2 Broadcaster: /robot_state_publisher Average rate: 98.896 Hz Average rate: 20.132 Hz Most recent transform: 1507801743.555 (0.008 sec old) Most recent transform: 1507801743.558 (0.005 sec old) Buffer length: 4.985 sec Buffer length: 4.967 sec geoJoint1 kinect2_rgb_optical_frame Broadcaster: /kinect2 Broadcaster: /robot_state_publisher Average rate: 98.896 Hz Average rate: 20.132 Hz Most recent transform: 1507801743.555 (0.008 sec old) Most recent transform: 1507801743.558 (0.005 sec old) Buffer length: 4.985 sec Buffer length: 4.967 sec geoJoint2 kinect2_ir_optical_frame Broadcaster: /robot_state_publisher Average rate: 20.132 Hz Most recent transform: 1507801743.558 (0.005 sec old) Buffer length: 4.967 sec geoJoint3 Broadcaster: /robot_state_publisher Average rate: 20.132 Hz Most recent transform: 1507801743.558 (0.005 sec old) Buffer length: 4.967 sec geoJoint4 Broadcaster: /robot_state_publisher Average rate: 20.132 Hz Most recent transform: 1507801743.558 (0.005 sec old) Buffer length: 4.967 sec geoJoint5 Broadcaster: /robot_state_publisher Average rate: 20.132 Hz Most recent transform: 1507801743.558 (0.005 sec old) Buffer length: 4.967 sec geoJoint6 Broadcaster: /robot_state_publisher Average rate: 50.200 Hz Most recent transform: 1507801744.049 (-0.485 sec old) Buffer length: 4.980 sec gripperBody Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 20.132 Hz Average rate: 20.132 Hz Most recent transform: 1507801743.558 (0.005 sec old) Most recent transform: 1507801743.558 (0.005 sec old) Buffer length: 4.967 sec Buffer length: 4.967 sec

gripperFinger2

gripperFinger1