## Polling Errors

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## Assuming unbiased polls

Most of you did something like this. For each poll k of state s at time t,  $Y_{stk}$  gives the two-party support share of a candidate.

$$E[Y_{stk}] = \theta_{s,t}$$
  
$$\theta_{s,t} \sim N(\theta_{s,t-1}, \sigma_{\theta})$$

Winner determined by  $\theta_{s,1} > 50\%$ .

# Checking bias

You could do this:

$$E[Y_{stk}] = \theta_{s,t} + \alpha_s$$
$$\theta_{s,t} \sim N(\theta_{s,t-1}, \sigma_{\theta})$$
$$\alpha_s \stackrel{iid}{\sim} N(\mu_{\alpha}, \sigma_{\alpha})$$

Winner determined by  $\theta_{s,1} > 50\%$ .

## How to set hyper parameters?

Could set  $\mu_{\alpha} = \text{mean}(b_1, \dots, b_S)$  and  $\sigma_{\alpha} = \text{sd}(b_1, \dots, b_S)$  where  $b_s$  is a point estimate of polling error in 2016 in state s (lots of analysts have made these). Could look at longer historical data by state.

Because the polling data cannot separate  $\theta$  and  $\alpha$ , sensitivity checks, particularly in  $\mu_{\alpha}$ , are very important. Could make a plot of P(Biden Win) vs  $\mu_{\alpha}$ .

#### How to estimate?

Note lack of information in data is a blessing and a curse. Curse is obvious, you can't learn them easily. But the blessing is you don't necessarily need to re-estimate your model.<sup>1</sup>

If you have your simulated draws of  $\theta_{s,1}$ , don't need to re-estimate model. For draw of  $\theta_{s,1}$ , subtract rnorm $(1,\mu_{\alpha},\sigma_{\alpha})$  and recompute who wins.

<sup>&</sup>lt;sup>1</sup>The priors do technically give you some identifiability, and a fully Bayesian approac would be to re-estimate the model many times for different priors on  $\alpha_s$ .