

Coach AI

BASKETBALL STRATEGIES

Revising strategies for a positionless game.

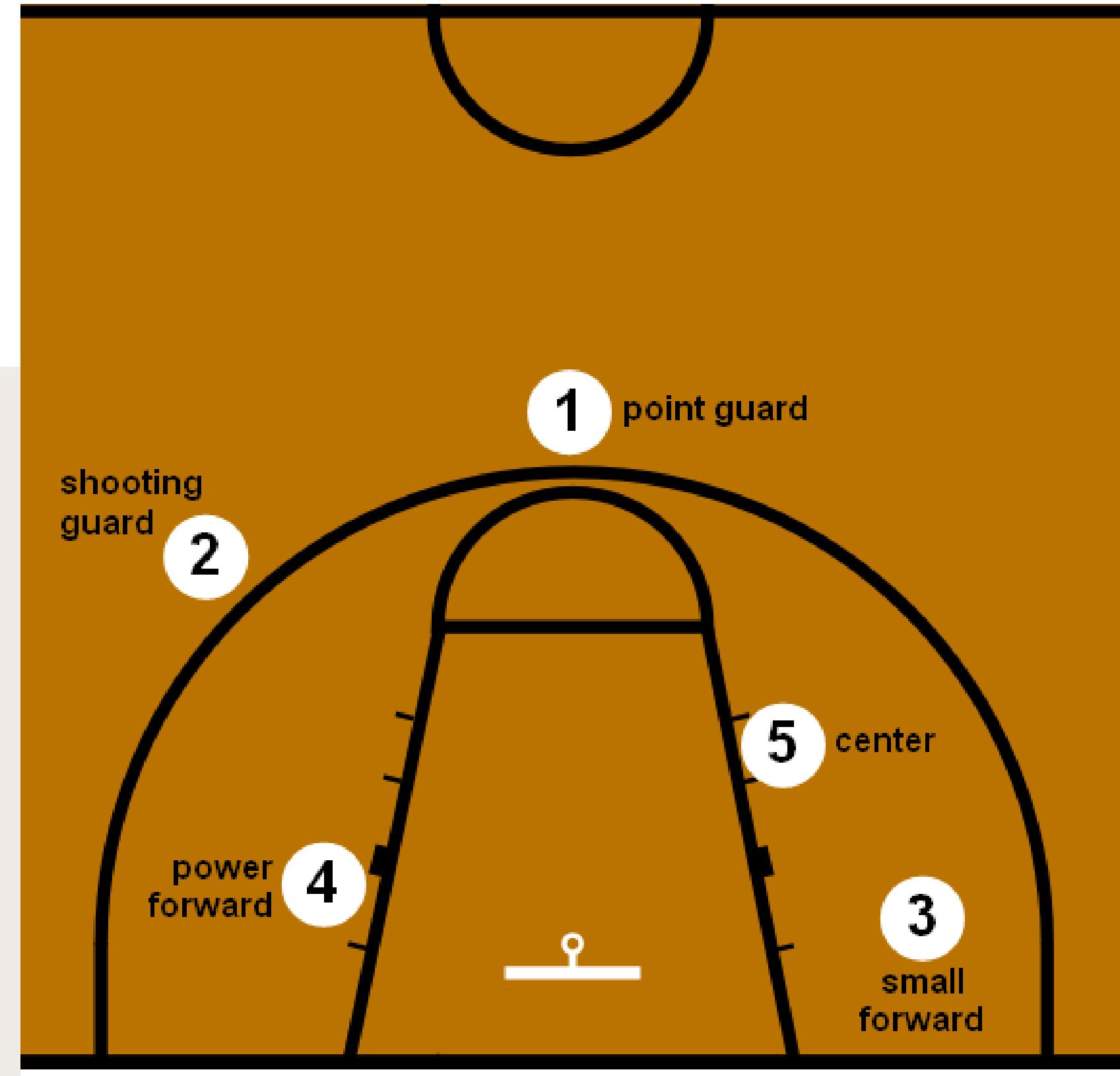


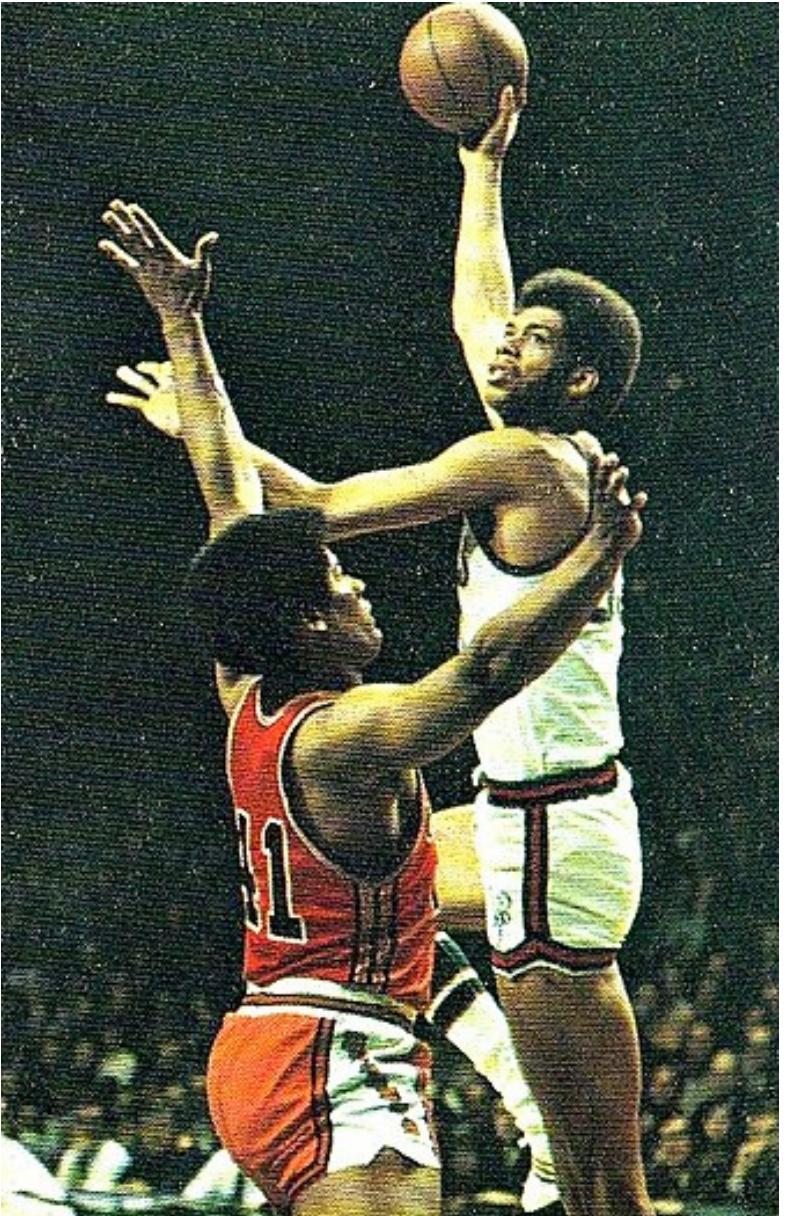
Background

Traditionally basketball has 5 different positions. One per player on the court.

TRADITIONAL POSITIONS:

- Point Guard
- Shooting Guard
- Small Forward
- Power Forward
- Center





Traditional NBA



Current NBA

Changes

With the addition of data science into the NBA and the success of the Warriors, there have been major changes to basketball strategy.

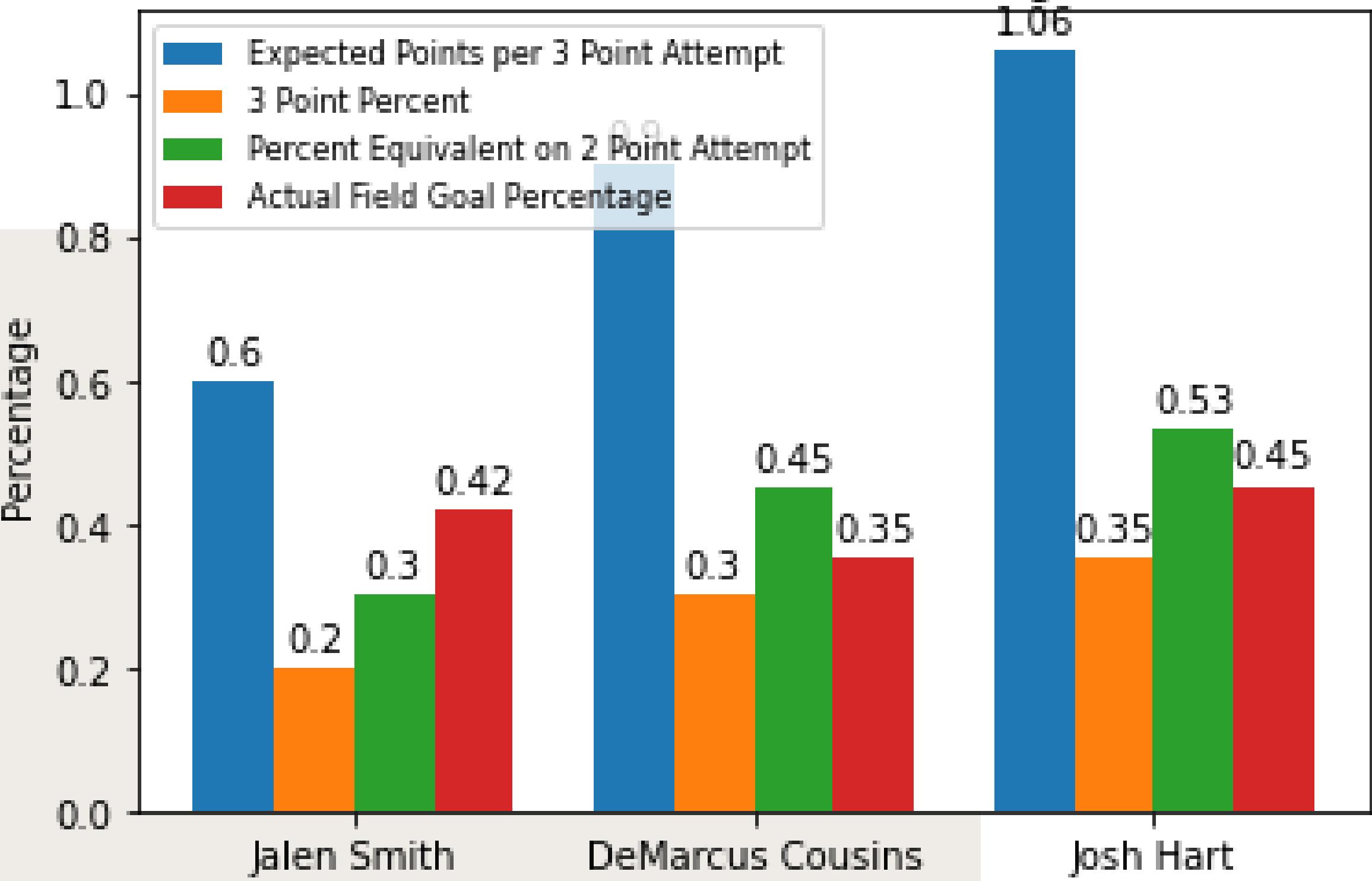
Field Goal Percentage

Players need to shoot a high 2-point field goal percentage to equal the expected value of a 3-point shot taken.

$$(3_{\text{PT}} \%) * 3 = 2 * (2_{\text{PT}} \%)$$

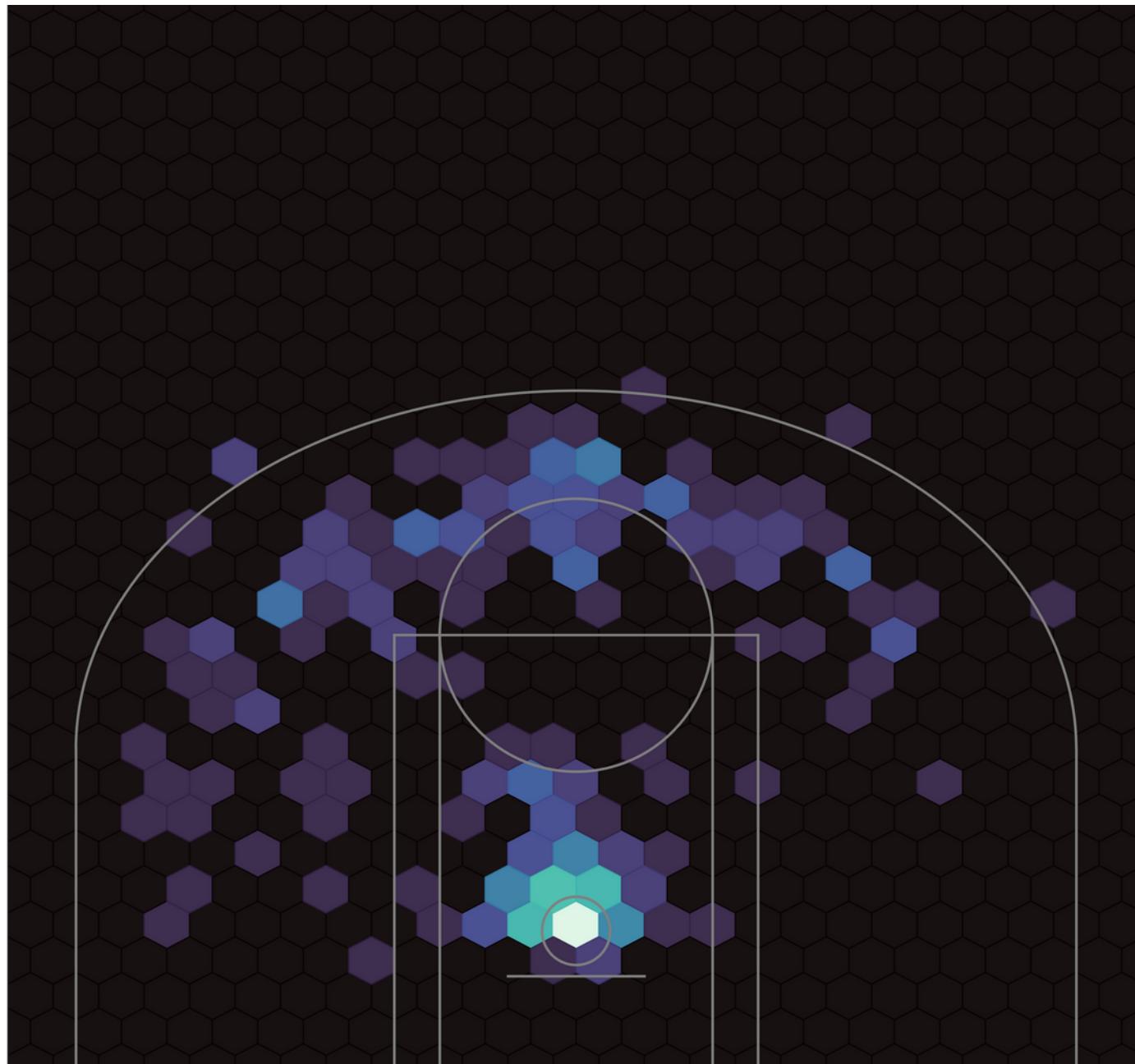
AS A RESULT, MANY MORE 3-POINTERS ARE TAKEN

Shooting Percentage and Expected Values
2 Point vs 3 Point Shooting



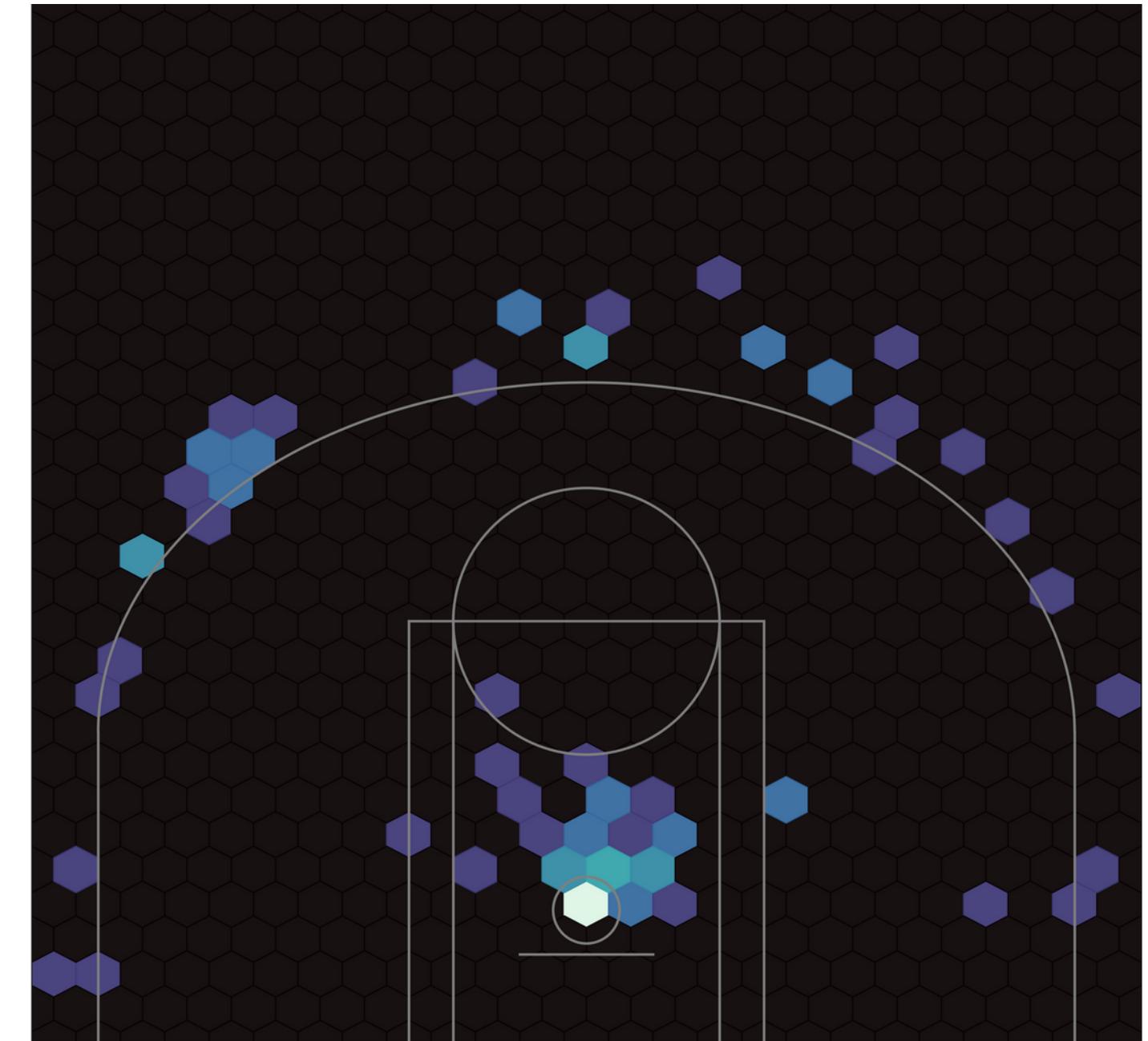
Shot Chart

BLAKE GRIFFIN



2015-2016

BLAKE GRIFFIN



2020-2021



Implementation

ARE TEAMS USING DATA WISELY
TO FORM STRATEGIES?

There are many papers, TED Talks, conferences that use NBA data & statistics in order to provide insights and try to give a team an edge in competition.

This project aims to analyze the decision making process by training AI agents to play a simplified game of basketball.

1:

Examples:

Joe Harris (SG/SF), Michael
Porter Jr (SF)

2:

Examples:

Nikola Jokic (C), Damian
Lillard (PG)

3:

Examples:

Nerlens Noel (C, PF), Rudy
Gobert (C)

4:

Examples:

RJ Hampton (PG), Patrick
Patterson (PF)

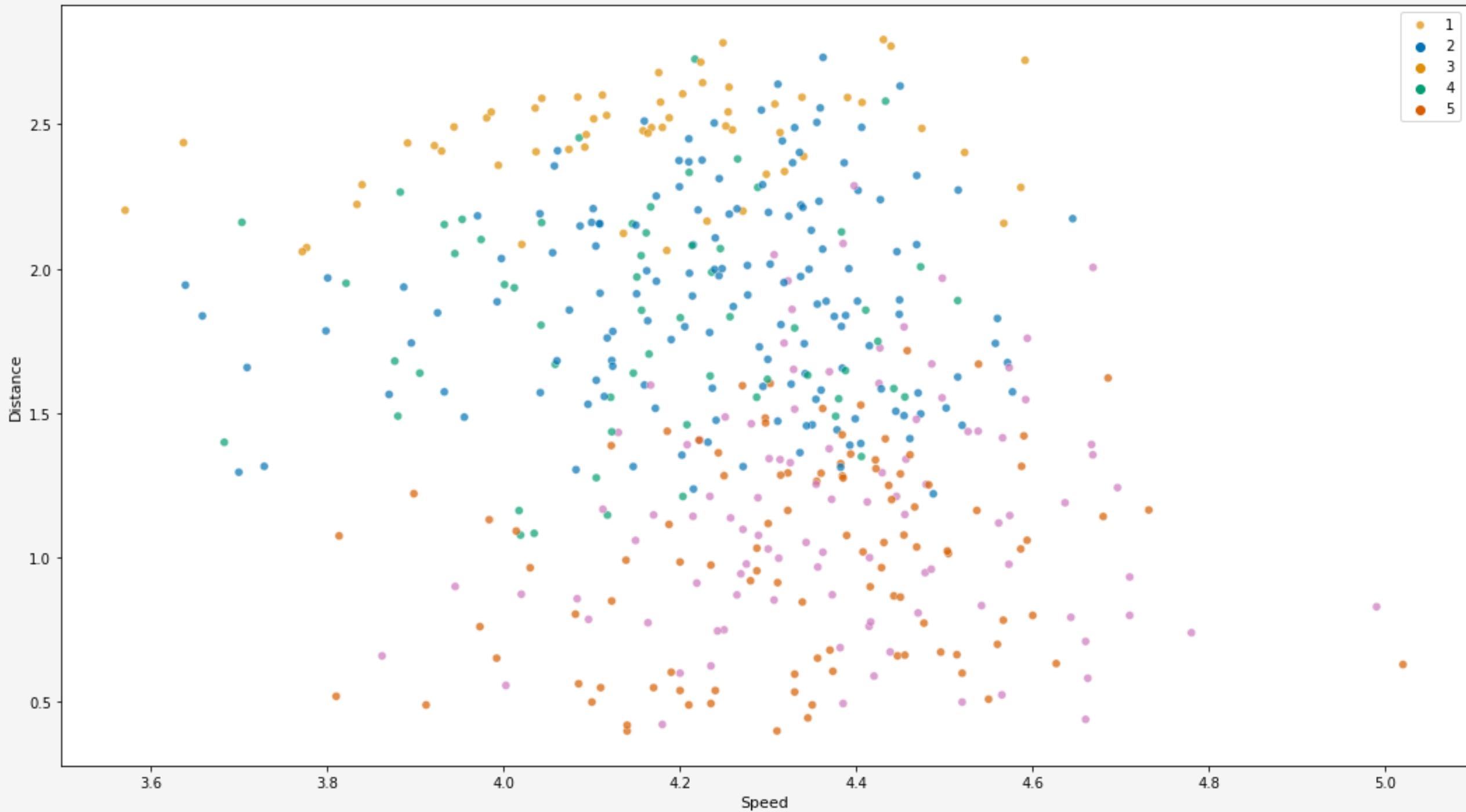
5:

Examples:

Jahlil Okafor (C) , Trey Lyles
(PF)

KMEANS CLUSTERING

Speed vs Distance: Player Movement





Inspiration

ALPHAGO & MUZERO

Researchers have developed chess playing models that play at a Grand Master level. These models played unconventional tactics and strategies that were later studied.

Reinforcement Learning

ENVIRONMENT CONCEPT

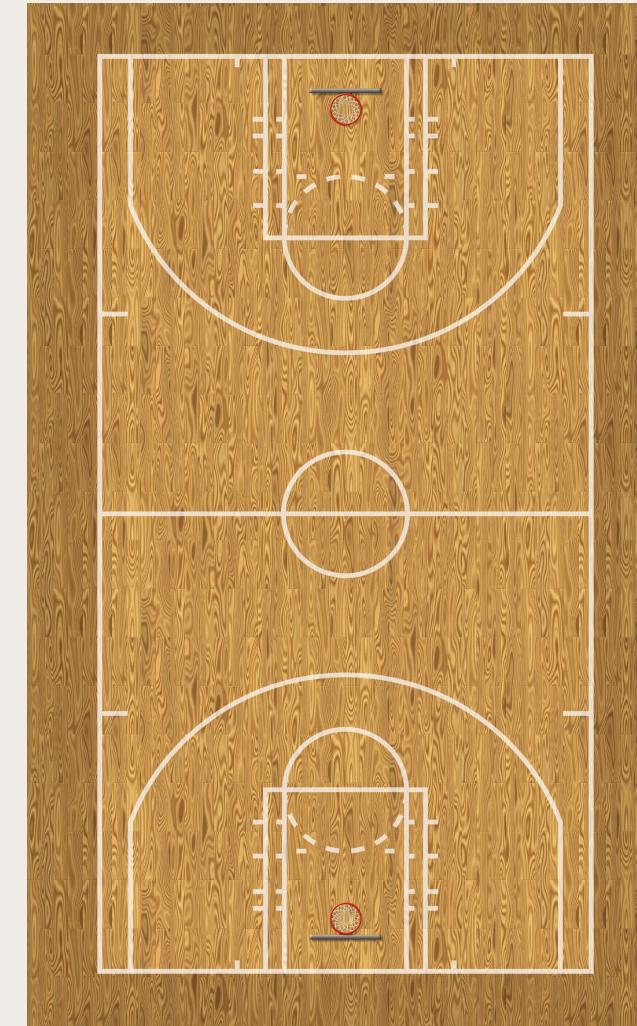
First we need an environment for our agents to operate in.

The environment defines the overall parameters, the legal actions an agent can take, and rewards for the agent's actions.

For example, the court size, moving on the court, or shooting the basketball and how much a made basket is worth.

Environment Modeling

Modeling Environment to train Agents



OBSERVATION SPACE

- X location for each player
- Y location for each player

ACTION SPACE

- Movement on x & y plane
- Shooting or Passing
- Steal or Block

Reinforcement Learning

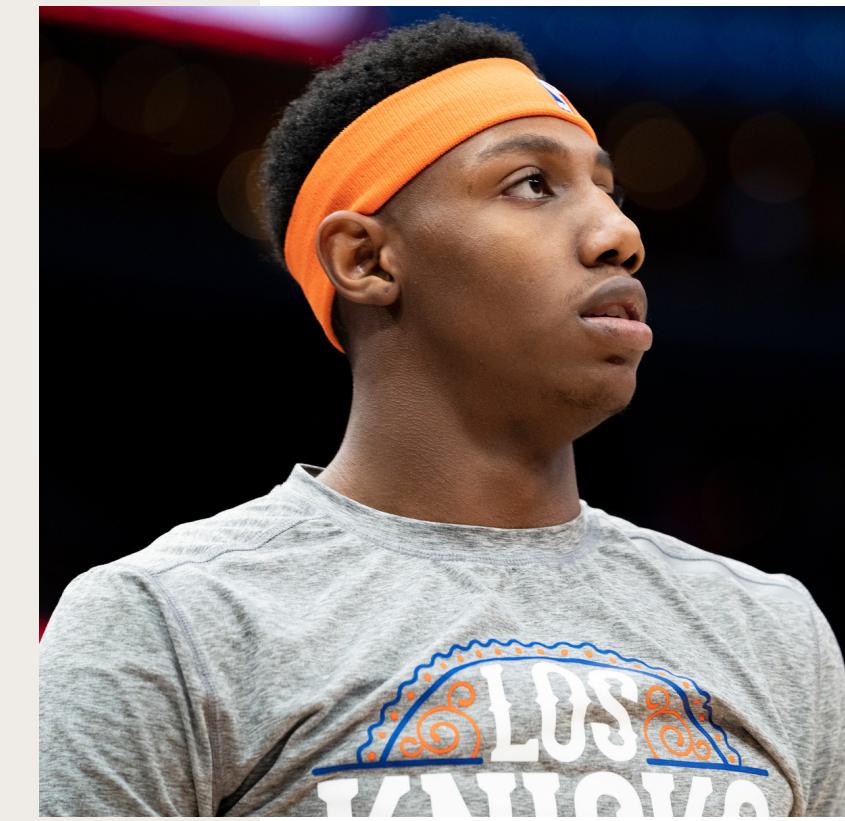
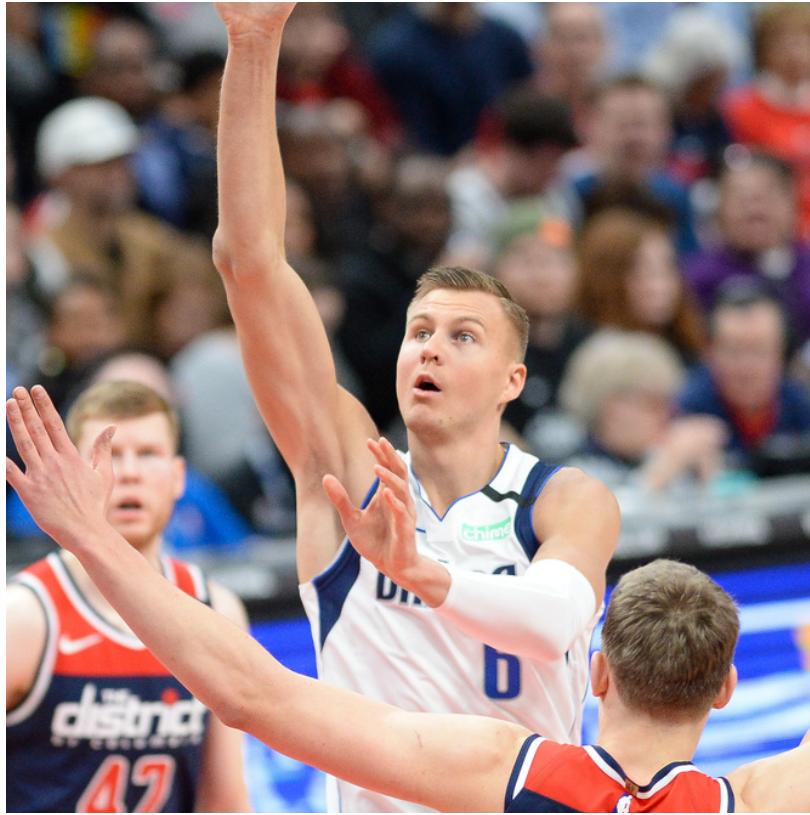
PLAYER CLASS

We also need to create a player class for the agents.

In this class we define attributes such as field goal percentages, or whether or not a player has the ball

To simplify the process, I decided to model a 2v2 Half-court game. The success of any given action is based on probabilities.

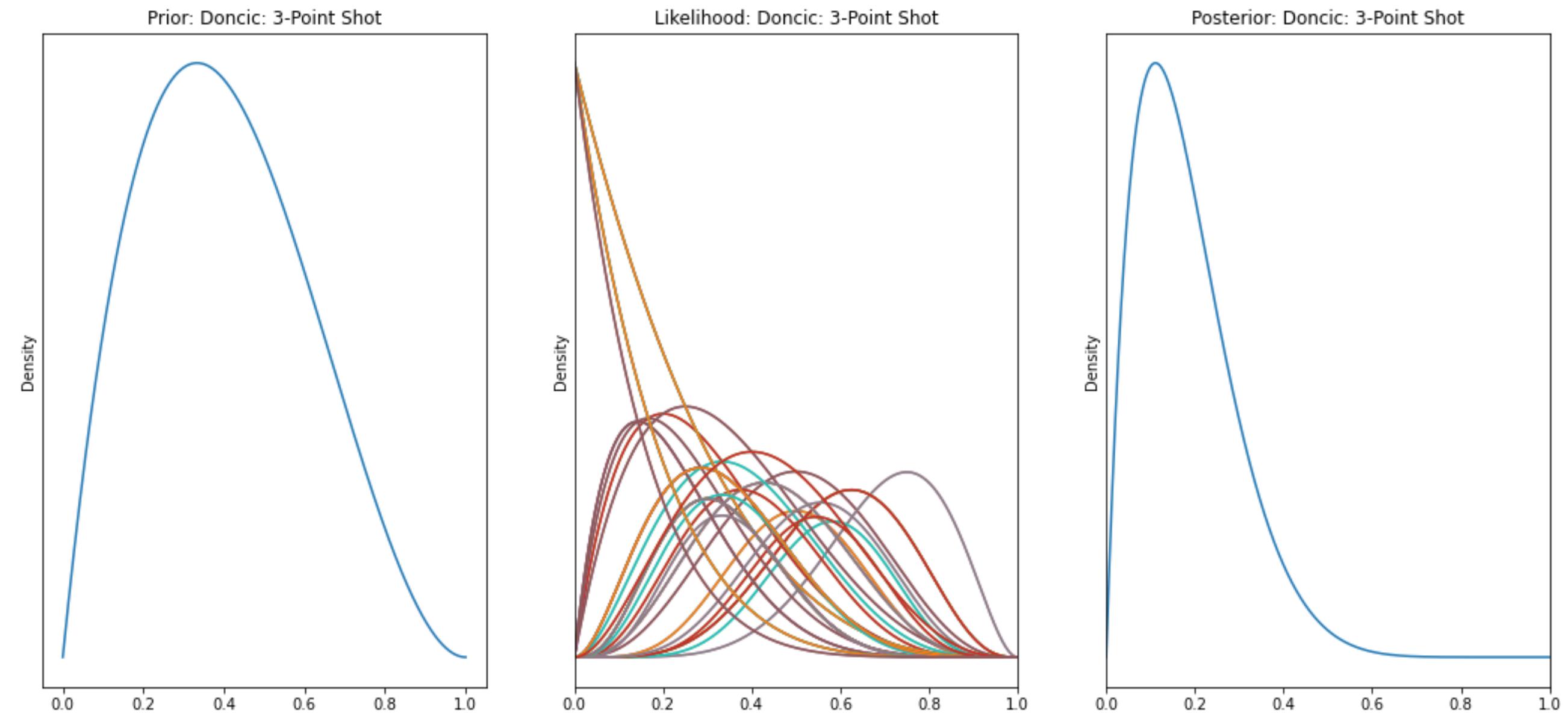
NYK VS DAL

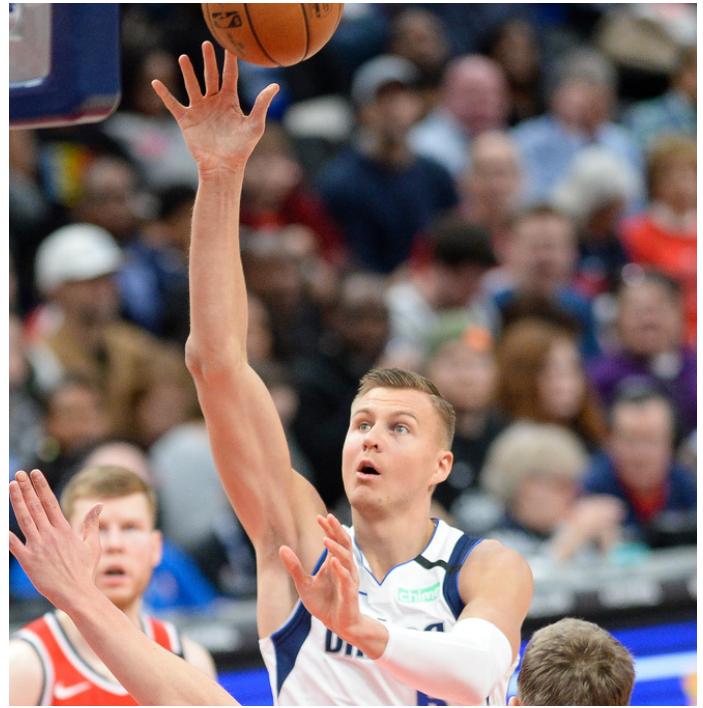




Using distributions of players shooting percentages to sample from in order to create a make probability in our environment.

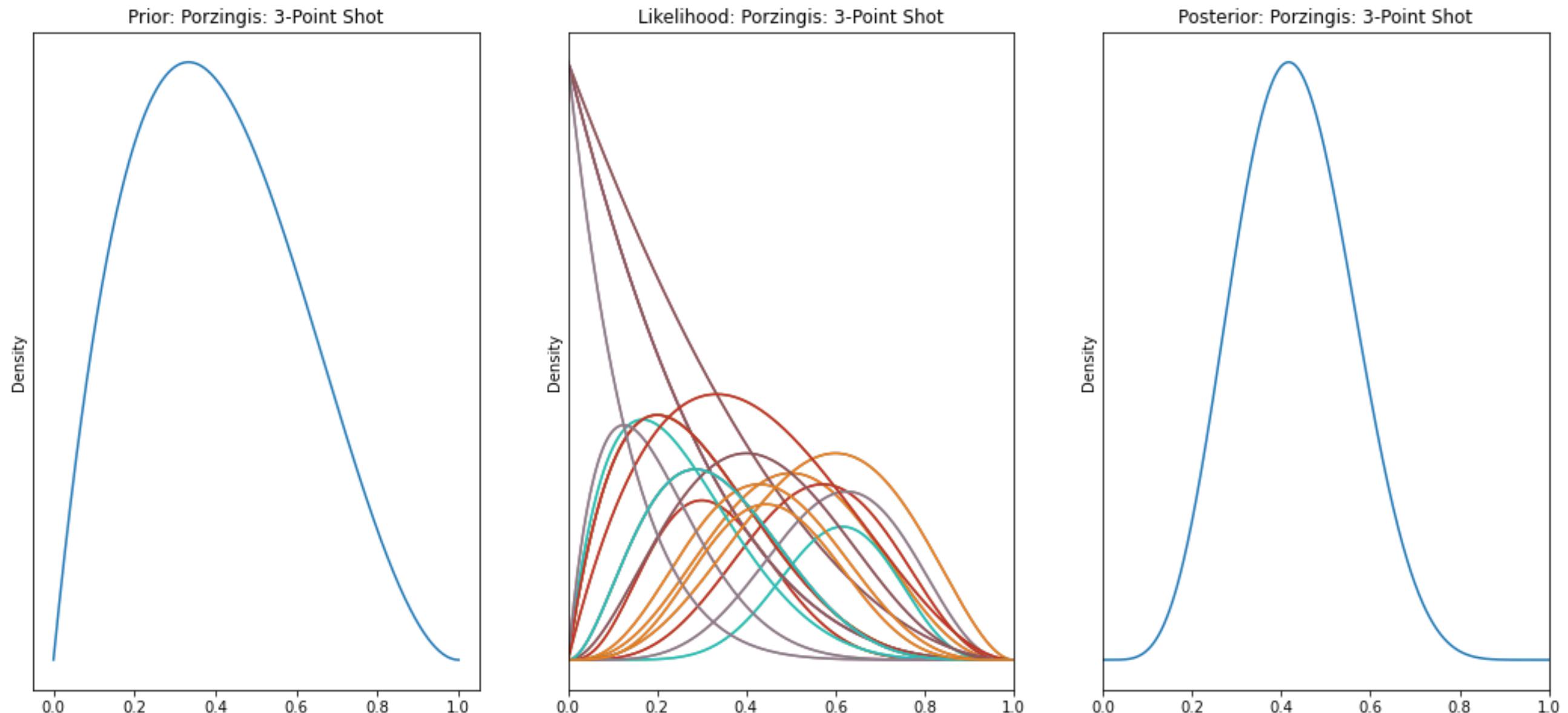
LUKA DONCIC: 3 POINT SHOOTING PERCENTAGE 2020-21 SEASON





Using distributions of players shooting percentages to sample from in order to create a make probability in our environment.

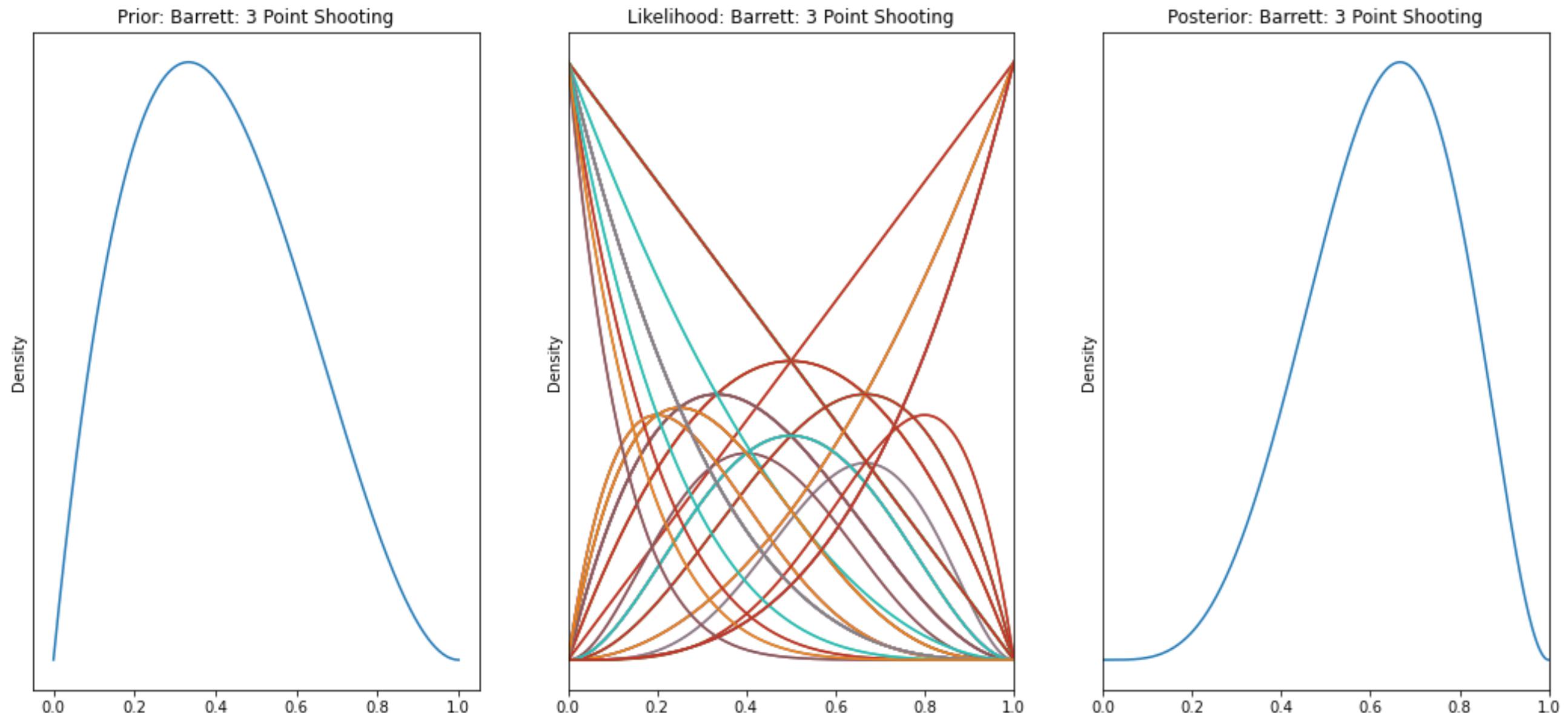
KRISTAPS PORZINGIS: 3 POINT SHOOTING PERCENTAGE 2020-21 SEASON





Using distributions of players shooting percentages to sample from in order to create a make probability in our environment.

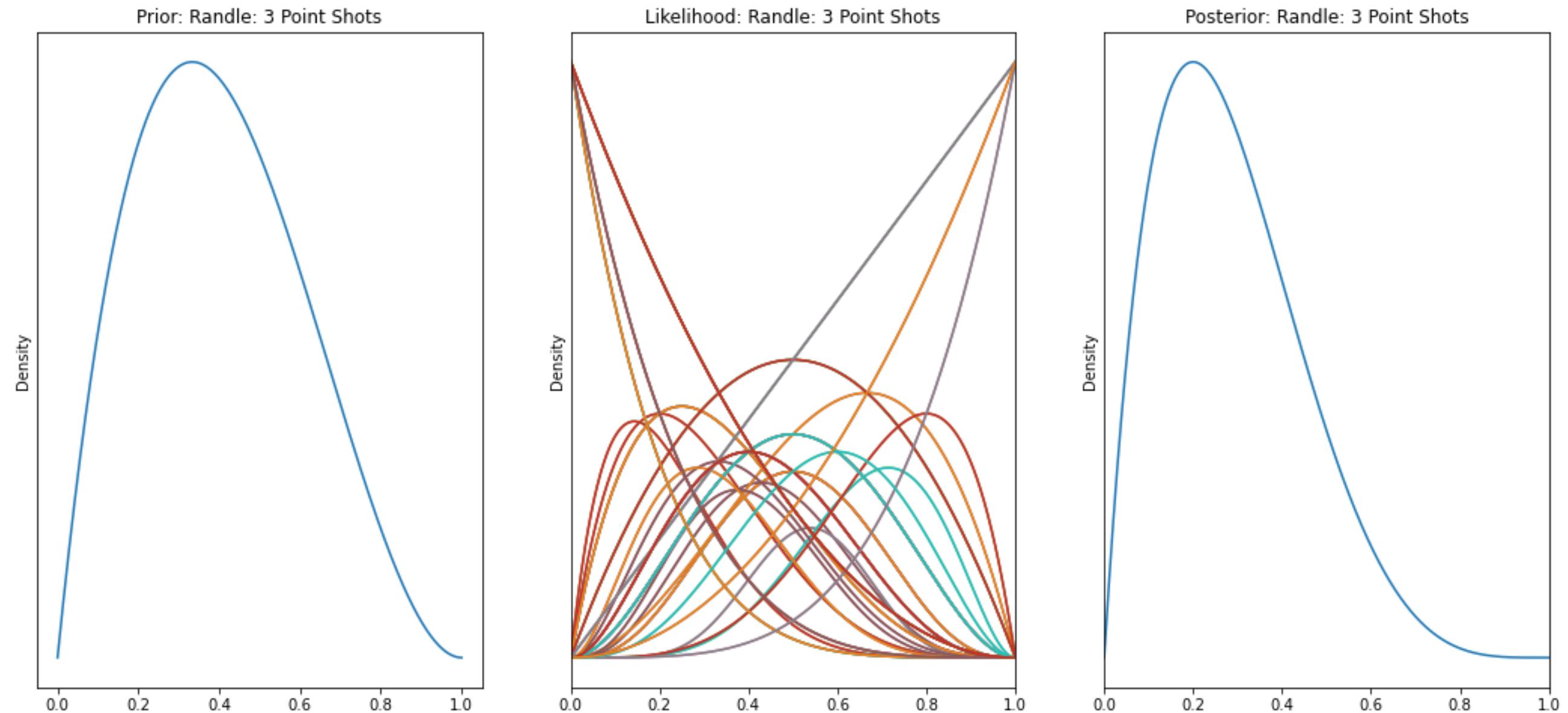
RJ BARRETT: 3 POINT SHOOTING PERCENTAGE 2020-21 SEASON





Using distributions of players shooting percentages to sample from in order to create a make probability in our environment.

JULIUS RANDLE: 3 POINT SHOOTING PERCENTAGE 2020-21 SEASON



Reinforcement Learning

AGENT CLASS

The agent class is where we actually define how the agents will learn.

To establish a baseline, we begin with the agents taking random decisions and output the reward.

We also want to make sure that the game is not too hard for the agents to score, but not too easy either.

Reinforcement Learning

Q LEARNING

Q-Learning is an off-policy algorithm. 'Q' stands for [quality](#), and the algorithm tries to learn the policy that maximizes reward.

A q-table is created with the states and actions as a reference table of the best actions to take (learned over many iterations.)

Our agent acts by referencing the table, or by exploring a random action and thus learning a bit more about the environment.

1:

Examples:

Joe Harris (SG/SF), Michael
Porter Jr (SF)

RESULTS

Next Steps

EXPANSION

Ideally the model would be expanded to 5v5 and could run through different scenarios, such as half court sets, out of bounds plays, or end of game scenarios.



THANK YOU