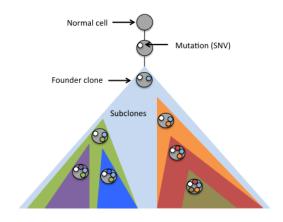
Nonparametric Clustering with Variational Inference for Tumor Heterogeneity

David Liu

Advisor: Prof Ben Raphael Reader: Prof Erik Sudderth

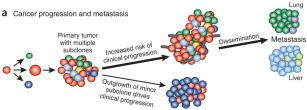
May 1, 2017

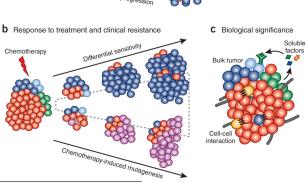
Cancer is an evolutionary disease.



Introduction Model Inference Methods Results Conclusion

Clinical significance.









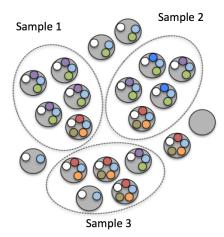
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 - Reference and variant reads.

Clonal mixture from bulk-sequencing data.

- We observe DNA bulk-sequencing data.
 - Reference and variant reads.
- Cluster mutations that occur with similar frequency.
 - Mutations from the same cluster should occur with the same frequency.

Multiple samples increase resolution.



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Let \mathbf{x}_n be general notation for $\{\mathbf{d}_n, \mathbf{v}_n\}$, where the use of the total or variant reads will be clear from context.

Assigning mutations to clusters

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Assigning mutations to clusters

Suppose that each SNV $n \in \{1, ..., N\}$ belongs to a cluster $k \in \{1, ..., K\}$, $K \leq N$.

- Latent variables \mathbf{z}_n , a 1-of-K indicator vector that denotes the cluster assignment of SNV n to cluster k.
- We don't know the number of clusters in advance.

Problem statement

SNV clustering problem

Suppose that for SNVs $n \in \{1, ..., N\}$ in samples $m \in \{1, ..., M\}$. Further suppose that there exists clones (clusters) $k \in \{1, ..., K\}$ and a true clustering \mathbf{z} . Given total reads $\mathbf{d}_1, ..., \mathbf{d}_n$ and variant reads $\mathbf{v}_1, ..., \mathbf{v}_n$, we seek to infer \mathbf{z} .

Observation model

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- Then

$$\mathbf{v_n} \sim egin{bmatrix} \mathrm{Bin}(v_{1n};d_{1n},\phi_{1k}) \ \mathrm{Bin}(v_{2n};d_{2n},\phi_{2k}) \ dots \ \mathrm{Bin}(v_{Mn};d_{Mn},\phi_{Mk}) \end{bmatrix} riangleq \mathbf{Bin}(\phi_{\mathbf{k}})$$

Dirichlet Process

Definition (Dirichlet Process)

For any measurable finite partition $\{B_i\}_{i=1}^n$ of a measurable set S ,

if
$$X \sim \mathrm{DP}(H, \alpha)$$

then $(X(B_1), \dots, X(B_n)) \sim \mathrm{Dir}(\alpha H(B_1), \dots, \alpha H(B_n))$

where Dir denotes the Dirichlet distribution.

• A non-parametric prior on the number of clusters.

Dirichlet Process

It is convenient to represent the Dirichlet Process in terms of its stick-breaking representation:

$$\pi_i(\mathbf{v}) = v_i \prod_{j=1}^{i-1} (1 - v_j)$$
 $DP = \sum_{i=1}^{\infty} \pi_i(\mathbf{v}) \delta_{\phi_i}$

where ϕ_i are the parameters for the realized distribution, and v_i are iid Beta $(1, \alpha)$.

We will use the stick breaking representation here.

Likelihood of data given its cluster membership:

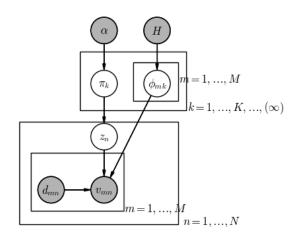
$$\Pr(\mathbf{x_n}|\phi_k) = \prod_{m=1}^{M} \operatorname{Bin}(v_{mn}; d_{mn}, \phi_k)$$

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$$\Pr(\mathbf{x_n}|\phi_k) = \prod_{m=1}^{M} \operatorname{Bin}(v_{mn}; d_{mn}, \phi_k)$$

Joint likelihood of observed data and cluster memberships:

$$\Pr(\mathbf{x_n}, \mathbf{z} | \boldsymbol{\pi}, \boldsymbol{\phi}) = \prod_{k=1}^K \prod_{m=1}^M \left(\pi_k \text{Bin}(v_{mn}; d_{mn}, \phi_{mk})\right)^{\mathbf{z}_{nk}}$$



The full cluster assignment posterior

$$p(\mathbf{z}|\mathbf{x}, \alpha, H) = \int p(\mathbf{x}|\phi)p(\phi|\mathbf{x}, \alpha, H) d\phi$$

involves a Dirichlet Process and is thus analytically intractable. We must use some sort of computational technique, such as variational inference, to perform inference on this posterior.

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- Generalized version of EM; deterministic given an initialization.
- Faster than MCMC.
- Scales well on large datasets.

Overview of Variational Inference: I

Let \mathbf{z} denote the latent variables, and \mathbf{x} denote the data. We seek to approximate the posterior $p(\mathbf{z}|\mathbf{x})$ from a family of distributions \mathcal{D} by solving the following optimization problem:

$$q^*(z) = \arg\min_{q(\mathbf{z}) \in \mathcal{D}} \mathrm{KL}\left(\left(q(\mathbf{z})||p(\mathbf{z}|\mathbf{x})\right)\right).$$

where KL is the KL-divergence, which measures the "distance" between two distributions.



Overview of Variational Inference: II

However, the KL-divergence requires us to compute the log evidence (which is intractable over the space of all z), since

$$\mathrm{KL}\left(q(\mathbf{z})\|p(\mathbf{z}\,|\,\mathbf{x})\right) = \mathrm{E}\left[\log q(\mathbf{z})\right] - \mathrm{E}\left[\log p(\mathbf{z},\mathbf{x})\right] + \log p(\mathbf{x}).$$

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Instead, we optimize the an objective function which is not dependent on $\log p(\mathbf{x})$, called the evidence lower bound (ELBO):

$$ELBO(q) = E[\log p(\mathbf{z}, \mathbf{x})] - E[\log q(\mathbf{z})].$$

The ELBO is a lower bound for the log evidence.

Overview of Variational Inference: III

The standard technique is to select a simple family of distributions for \mathcal{D} , the mean-field variational family. In this family, the latent variables \mathbf{z} are mutually independent so that the joint distribution factorizes:

$$q(\mathbf{z}) = \prod_{j=1}^m q_j(z_j).$$

where q_j is a bounded variation dependent only on z_j . The structure of the model will dictate the optimal form of q_i .

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Let \mathbf{z}_{-j} denote the set of latent variables \mathbf{z}_l such that $l \neq j$. Then we can show that

$$\begin{aligned} \text{ELBO}(q) &= \int \prod q_i(\mathbf{z}_i) \left(\log p(\mathbf{z}, \mathbf{x}) - \sum_i \log q_i(\mathbf{z}_i) \right) d\mathbf{z} \\ &\propto \int q_j(z_j) \mathbf{E}_{-j} \left[\log p(\mathbf{x}, \mathbf{z}) \right] d\mathbf{z}_j - \int q_j(z_j) \log q_j(\mathbf{z}_j) d\mathbf{z}_j \end{aligned}$$



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Now suppose that we fix z_{-j} and maximize the ELBO . It can be shown that

$$q_i^*(\mathbf{z}_j) \propto \exp\left(\mathbb{E}_{-j}\left[\log p(\mathbf{x}, \mathbf{z})\right]\right)$$





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By iterating through these coordinate updates, we reach a local optimum of the $\rm ELBO$.



¹Bishop 2006

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Recall that a distribution is in exponential form if it can parameterized by

$$f_X(x \mid \theta) = h(x) \exp \left(\theta^T \cdot T(x) - A(\theta)\right)$$

where T(x) are the sufficient statistics, θ are the natural parameters, $A(\theta)$ is the cumulant, and h(x) is the base measure.



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The intuition is that because $q^* \propto \exp(\mathbb{E}[\log(.)])$, then writing the distribution in exponential form reveals dependencies that hold for all exponential family members.



¹Hughes 2015

So why not always use variational inference?

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- MCMC, like Gibbs sampling, is typically easier to implement.
 - No need for painful derivations.

Existing methods

Model Selection

nference Method		Dirichlet Prior + Heuristic	Dirichlet Process Prior
		(Fixed K)	(countably infinite K)
	MCMC	(Many older methods)	PyClone
	VI	SciClone	This thesis

Table 1: A comparison of methods used to solve the clonal mixture problem.

VI for the DP/Binomial mixture model

By beta-binomial conjugacy,

$$egin{aligned} q(\phi_k) &= \prod_{m=1}^M q(\phi_{mk}) \ &= \prod_{m=1}^M \mathrm{Beta}(\phi_k | lpha_{mk}, eta_{mk}) \end{aligned}$$

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Thus, combined with the DP variational parameters,

$$q(\mathbf{z},\mathbf{v},\phi) = \prod_{k=1}^{K} q(\phi_k) \times \prod_{k=1}^{K} q(\mathbf{v}_k) \times \prod_{n=1}^{K} q(\mathbf{z}_n)$$
Observation: likelihoods Product of betas 2MK variational parameters
$$\{\alpha_{mk},\beta_{mk}\}_{m=1}^{M,K} \times \{q_{(\mathbf{v},\mathbf{v})}\}_{k=1}^{M,K} \times \{q_$$

Most of the details are in the thesis appendices.



MAP estimates

For each cluster we pool reads by cluster membership:

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and we can make MAP estimates by converting from the variational parameters back to the original parameters of the posterior:

$$\begin{split} \mathbf{z}_n^{\text{MAP}} &= \arg\max_k \hat{r}_{nk} \\ \phi_{mk}^{\text{MAP}} &= \frac{v_{mk}^{\text{pooled}} + \alpha_{mk} - 1}{d_{mk}^{\text{pooled}} + \alpha_{mk} + \beta_{mk} - 2}. \end{split}$$

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Everything was implemented in Python.

Coordinate ascent algorithm

Algorithm 1: CAVI FOR THE DP BINOMIAL MIXTURE MODEL

Input: Data \mathbf{x}_n , where each x_i is an integer vector with M entries.

 $\gamma_0, \gamma_1, \alpha_0, \beta_0$, hyperparameters

Output: Converged variational parameters

$$\{\alpha_{mk}, \beta_{mk}\}_{m=1,k=1}^{M,K}, \{\dot{\eta}_{k0}, \eta_{k1}\}_{k=1}^K, \{\hat{r}_{nk}\}_{n=1,k=1}^{N,K}$$

Initialize: $\alpha_0 = \beta_0 = \alpha_{mk} = \beta_{mk} = 1$, $\forall m, k$

$$\gamma_1 = \eta_1 = 1.0, \gamma_0 = \eta_0 = 1.5$$
 $\hat{r}_{nk} \leftarrow \text{kmeans++}(\mathbf{x})$

while the ELBO has not converged do

▷ Compute data-specific (local) parameters

$$\mathbf{E}_{q}[\log p(\mathbf{x}_{n}|\alpha_{mk},\beta_{mk})] \leftarrow \mathbf{E}_{q}[\log \left(\binom{d_{mn}+\nu_{mn}}{\nu_{mn}})(\phi_{k})^{\nu_{mn}}(1-\phi_{k})^{d_{mn}}\right)]$$

$$\hat{r}_{nk} \leftarrow \exp(S_{k})$$

Compute sufficient statistics

$$\begin{array}{lll} S_k = \sum_{n=1}^{N} \hat{r}_{nk} s(x_n) = \sum_{n=1}^{N} \hat{r}_{nk} \left[\begin{bmatrix} v_{1n} & d_{1n} \end{bmatrix} & \cdots & \begin{bmatrix} v_{Mn} & d_{Mn} \end{bmatrix} \end{bmatrix} \\ N_k = \sum_{n=1}^{N} \hat{r}_{nk} \\ N_k^2 = \sum_{k=1}^{N} N_k \end{bmatrix}$$

▷ Compute cluster-specific (global) parameters

$$\begin{array}{l} \eta_{k1} \leftarrow 1 + \sum_{n} \hat{r}_{nk} = 1 + N_{k} \\ \eta_{k0} \leftarrow \gamma + \sum_{n} \sum_{j=k+1}^{K} \hat{r}_{nj} = N_{k}^{>} \\ \alpha_{mk} \leftarrow (\alpha_{0} - 1) + S_{km} \\ \beta_{mk} \leftarrow (\beta_{0} - 1) + S_{km} \end{array}$$

Compute $ELBO(q) = \mathbb{E} [\log p(\mathbf{z}, \mathbf{x})] - \mathbb{E} [\log q(\mathbf{z})]$

Simulated Data

Number of clusters (K)	10
Number of SNVs (N)	100
Number of samples (M)	4, 5, 6
Coverage	50, 100, 1000

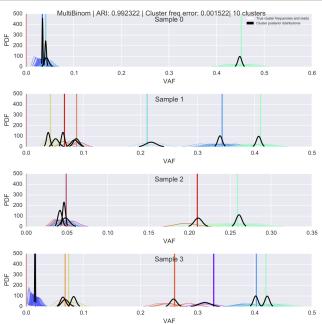
Parameters for the simulated datasets.

Evaluating results

The DP/VI coordinate ascent algorithm was benchmarked against SciClone (VI) and PyClone (DP/MCMC).

- Evaluate clustering: Adjusted Rand Index (ARI)
- Evaluate parameters: Cluster frequency error (CFE)

$$\mathsf{CFE}(\phi^{\mathsf{MAP}}) \triangleq \frac{1}{C} \sum_{c=1}^{C} \min_{k \in \{1, \dots, K\}} \left\| \phi_c^{\mathsf{MAP}} - \phi_k \right\|$$

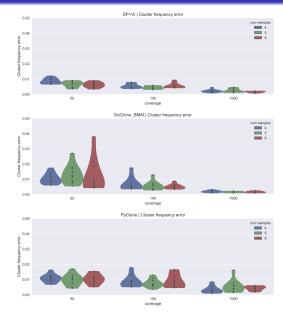


Cluster posteriors (black) and true clusters (colored, vertical lines) with x_n (colored beta curves).



troduction Model Inference Methods **Results** Conclusion

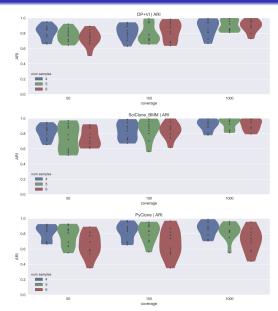
Cluster Frequency Error





ntroduction Model Inference Methods **Results** Conclusion

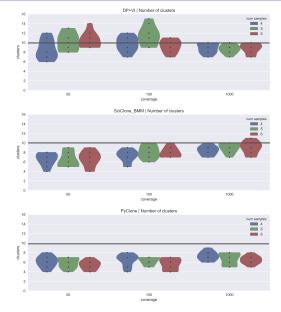
Adjusted Rand Index





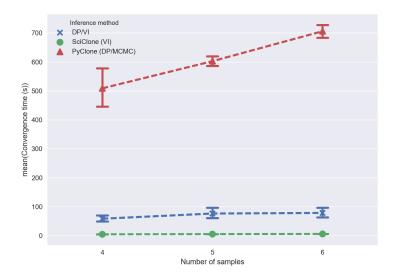
Model Results

Number of clusters





Runtime



The DP/VI method is:

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 - Added benefit: nonparametric prior.

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- Try on real data

Acknowledgments

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