

Validity of the Kronecker Model for MIMO Correlated Channels

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Abstract— The goal of this paper is to investigate the validity of the Kronecker model for MIMO correlated channels. First, mathematical and equivalent propagation conditions of validity are detailed. In a second part, we address several areas where the Kronecker model is not valid. We also review the one-ring model and experimental results dealing with the validation of the Kronecker model. Based on these scarce results, the preliminary conclusion is that the Kronecker model might not be valid for arrays larger than 2×2 when antenna correlations are high across both receive and transmit arrays. The paradox is that the Kronecker model has been developed and is being widely used to account for correlation. This is in strong contrast with the popular belief that the Kronecker model is valid in many indoor and outdoor cases.

I. INTRODUCTION

A well-known result of space-time signal processing is that the average channel capacity grows linearly with the number of antennas if the fades between pairs of transmit-receive antenna elements are independent and identically Rayleigh-distributed (Rayleigh i.i.d.). In practice, however, the MIMO channel can deviate significantly from the i.i.d. assumption, namely because channels can be correlated [1]. In the last years, many papers¹ have dealt with MIMO signal processing and information theory for correlated channels, using the extraordinarily popular Kronecker model as a general model for correlation. This leads to believe that the Kronecker model is representative of many typical cases, irrespective of the channel and the antenna arrays.

Most papers using the Kronecker model cite [2]–[5] as a justification. However, the discussion in [3], based on the one-ring model, is not as conclusive as it may seem at first sight. The same remark holds for the experimental results of [4]. These points are discussed in this paper. Then, [6] illustrated through experimental results that the Kronecker model might provide large underestimations of the mutual information.

The goal of the present contribution is to evaluate the validity of the Kronecker model from a theoretical point of view, with regard to several applications and experimental results. Incidentally, we show that previous experimental or simulation

results, obtained in particular cases, have been questionably extrapolated to a general rule. Section II details the mathematical and propagation-related conditions of validity of the Kronecker assumption. Section III addresses several applications, investigating whether the Kronecker model applies or not, and compares the derived conclusions with experimental results. In Section III, we also investigate a popular geometry-based model. This investigation is by no means an analysis of the validity of the one-ring model, but addresses the validity of the Kronecker representation for the geometry-based model under study. Indeed, one fact should be clear: analytical models of the MIMO channel are not *self-sufficient* (by contrast to physical models). They are convenient matrix representations of the channel which can be used e.g. in the analytical design of space-time codes. However, to use an analytical model in simulations, physical models or data to be used as input are still required (this is exemplified in Section II-A). Finally, we summarize a few preliminary guidelines relative to the use of the Kronecker model in the conclusion.

II. THEORETICAL BACKGROUND

A. Covariance Matrix

In this paper, we deal only with identically Rayleigh distributed channels. That means that there is no coherent fixed component, and that all channels convey the same average energy, normalized to unity. Furthermore, to reduce the number of parameters, we restrict the discussion to $n_r \times n_t = 2 \times 2$ MIMO channels. This restriction is only made to simplify notations, and all considerations below apply similarly to arbitrary array sizes. As a consequence, the channel matrix \mathbf{H} is expressed as:

$$\mathbf{H} = \begin{bmatrix} h_{11} & h_{12} \\ h_{21} & h_{22} \end{bmatrix}, \quad (1)$$

and its *average* Frobenius norm is equal to 4 (this is not the case for the instantaneous Frobenius norm). Since, for Rayleigh fading, second-order statistics fully describe the multi-antenna channel, a general model of \mathbf{H} is given by:

$$\text{vec}(\mathbf{H}) = \mathbf{R}^{1/2} \text{vec}(\mathbf{H}_w) \quad (2)$$

¹ The list of papers would be too long to cite them here. We invite the reader to refer to [1] for some of these papers.

where \mathbf{H}_w is the spatially white (Rayleigh i.i.d.) MIMO channel; $\mathbf{R} = \mathbf{R}^{1/2} \mathbf{R}^{H/2}$ is the covariance matrix defined as $\mathbf{R} = E\{\text{vec}(\mathbf{H})\text{vec}(\mathbf{H})^H\}$, with “vec” being the operator stacking the matrix \mathbf{H} into a vector columnwise; and the superscript H designates the conjugate transposition. Because all four channels are identically distributed (and normalized to provide unitary average energy), the covariance matrix \mathbf{R} contains 6 different parameters, as defined below:

$$\mathbf{R} = \begin{bmatrix} 1 & r_1 & t_1 & s_1 \\ r_1^* & 1 & s_2 & t_2 \\ t_1^* & s_2^* & 1 & r_2 \\ s_1^* & t_2^* & r_2^* & 1 \end{bmatrix} \quad (3)$$

In (3), parameters r_1, r_2, t_1, t_2 have been known for many years, since they represent the correlations between channels at two receive (resp. transmit) antennas at one side, but originating from (resp. impinging on) the same transmit (resp. receive) antenna at the other side of the link. They are the classical correlation coefficients of diversity-based systems (MISO and SIMO). Hence, they are referred to in the following as *antenna* correlations. The two remaining parameters s_1 and s_2 are defined as the *diagonal* correlations, or *cross*-correlations. They represent the correlations between channels originating from and impinging on different antennas at each side of the link [7].

The model outlined by equations (2) and (3) is not self-sufficient, as it does not give any indication on how to fill the matrix \mathbf{R} with quantitative parameters. To this end, experimental data or physical models (ray-tracing, geometry-based models, etc.) must be used in combination with (3). This is true for any analytical model, since, by essence, they only provide an analytical formalism to represent the MIMO channel matrix. Therefore, it does make sense to question the validity of a given analytical model with respect to a data source (experimental data, physical model, etc.), as investigated in Sections III-C and III-D.

A major drawback of expression (3) is that it is not easily tractable. As a first step towards simplification, it may be considered that, in many cases to be identified in the sequel, $r_1 = r_2$ and $t_1 = t_2$. Therefore, they can be denoted as r and t , and it is then possible to define 2×2 transmit (Tx) and receive (Rx) correlation matrices, \mathbf{R}_t and \mathbf{R}_r , as to decompose any MIMO system into two “interconnected” MISO/SIMO subsystems. This decomposition has naturally resulted in the development of a simpler and less general model of the covariance matrix,

$$\mathbf{R}_K = \mathbf{R}_t \otimes \mathbf{R}_r \quad (4)$$

where \otimes designates the Kronecker product, and

$$\mathbf{R}_t = \begin{bmatrix} 1 & t \\ t^* & 1 \end{bmatrix} \text{ and } \mathbf{R}_r = \begin{bmatrix} 1 & r \\ r^* & 1 \end{bmatrix}.$$

Replacing \mathbf{R} by the expression of \mathbf{R}_K in (2), the correlated channel matrix can be written as:

$$\mathbf{H} = \mathbf{R}_r^{1/2} \mathbf{H}_w \mathbf{R}_t^{1/2} \quad (5)$$

Expressions (4) and (5) are referred to as the Kronecker model. It can be seen that (5) is more tractable than (2), since the “vec” operator has been replaced by matrix multiplications.

B. Mathematical Validity Conditions

Mathematically, the Kronecker model is valid if and only if two conditions are jointly met, although contradictory statements can be found in the literature [5].

As stated above, the first condition is that the Tx (resp. Rx) correlation coefficients are (in magnitude) independent from the considered Rx (resp. Tx) antenna, so that $r_1 = r_2$ and $t_1 = t_2$. In [5], it is claimed that this first condition is the only one necessary for the Kronecker model to be valid. Yet, there is an additional condition [8], which is that the cross correlations must be equal to the product of Tx and Rx correlations, so \mathbf{R} is further simplified by considering that $s_1 = rt$ and $s_2 = r^*t$, which yields (4). Note that for real-valued correlations, a single diagonal correlation can be defined as $s = s_1 = s_2 = rt$.

C. Propagation Validity Conditions

Both conditions identified above can be translated into propagation-related conditions. The first condition on the antenna correlations can be interpreted as the following: $r_1 = r_2$ if both antennas of the Tx array are located not too far from each other, and have the same radiation pattern and the same orientation. A similar condition should be fulfilled by the Rx array to ensure that $t_1 = t_2$. Once the first condition is met, the second sufficient (and rigorously necessary) condition is equivalent of having all angles-of-departure (AoDs) coupled with all angles-of-arrival (AoAs) with the same profile, so that the joint AoA-AoD spectrum is the product of the marginal spectra. Indeed, if all AoDs couple into all AoAs, the knowledge of any given AoD does not provide any information on the corresponding AoA (and vice-versa). The distribution of AoA conditional to the AoD is equal to the AoA marginal distribution (the same holds true for the AoD distribution conditional to AoA), AoDs and AoAs are statistically independent². It is often affirmed that this occurs when the immediate surroundings to each array are responsible for the correlation between its antennas, but have no impact on the correlation at the other end of the link. Note that this affirmation is not necessarily natural. Indeed, it implies more than a physical separation between both surroundings, but implicitly rules out any unique coupling between them.

D. Comparison between Mathematical and Propagation Validity Conditions

We have shown that the propagation-related conditions imply that mathematical conditions are met, irrespective of the antenna arrays, provided that the array dimensions are not unreasonably large. Hence, any environment characterized by

- spatial stationarity regions larger than the array sizes (so the first condition will be met for all realistic arrays),

² This condition also holds true if the angle-spread at one side is very small, so that the angular spectrum at that side is well approximated by a δ -function. The second propagation validity condition is then automatically met.

and

- independent DoA and DoD spectra,

therefore yields a Kronecker channel matrix for **all** array sizes and/or configurations. Such propagation environments are defined here as *Kronecker-structured*. By contrast, the set of mathematical conditions do not imply that the environment is Kronecker-structured. That means that an environment providing a Kronecker channel matrix for given array configurations might not provide this structure for all array configurations. This is for example the case of any single-bounce channel, as discussed in Section III-C.

E. Equivalence with Virtual Channel Representation

MIMO channels can be represented by alternative models, such as the virtual channel representation. The virtual channel representation [9] is given by:

$$\mathbf{H} = \tilde{\mathbf{A}}_r (\tilde{\mathbf{\Omega}} \circ \mathbf{H}_w) \tilde{\mathbf{A}}_t^H \quad (7)$$

where $\tilde{\mathbf{A}}_r$ and $\tilde{\mathbf{A}}_t$ are steering matrices in the directions of the fixed virtual angles, $\tilde{\mathbf{\Omega}}$ is a real-valued coupling matrix obtained as the element-wise square-root of a power coupling matrix $\mathbf{\Omega}$, \mathbf{H}_w is a spatially white (Rayleigh i.i.d.) matrix and \circ is the element-wise Hadamard matrix multiplication.

The equivalence of the above model with the Kronecker model for (very) large array sizes has not only been proven in [10][11], but seems intuitive as well. Indeed, a large number of antennas at both sides results in a high number of virtual angles is large. So, for a maximally rich coupling matrix (all elements of $\mathbf{\Omega}$ are non-zero and of similar amplitude), all transmit virtual angles couple independently into all receive virtual angles. Through the high number of virtual angles, this is equivalent to the second propagation validity condition of Section II-C. Note that the number of antennas must be large enough, and that this equivalence does not validate the Kronecker model. Experimental results [12] suggest that the virtual channel model might be deficient in indoor environments, even for 8×8 systems.

III. APPLICATIONS

A. MIMO with Different Antenna Patterns

This scenario is found for macroscopic arrays, or when antenna patterns differ (although antennas are co-located), i.e. for narrow-beam antennas or when mutual coupling is accounted for. In the first case, when the antennas at one link end are separated by a large distance, each will experience different shadow fading conditions. The antenna correlation at that link end (say, at the terminal) can clearly be zero, as both transmitted signals will experience very different channels. Yet, the Kronecker representation is not valid in this case, because the correlation at the other end is not the same whether calculated from the first or the second terminal. For such systems, the first condition is evidently not met.

In the second case, when several antenna elements are located closely to each other, the electrical field generated by one antenna alters the current distribution on the other antennas. As

a consequence, the radiation pattern and input impedance of each array element are disturbed because of the other elements. This effect is known as antenna coupling. Intuitively, antenna coupling can be seen as a distortion of the original radiation patterns. Because these patterns will be different (though symmetrical, see [13]) when antenna coupling is significant, the first condition is again not met. Therefore, for compact arrays or, more generally, when antenna patterns differ across the array at one side of the link, the Kronecker model might not be applicable anymore.

B. Rayleigh-fading Dual-polarized Channels

Let us now consider a 2×2 dual-polarized slanted scheme, i.e. each array is made of two co-located antennas with orthogonal polarizations at $\pm 45^\circ$ [14]. It has been illustrated in [15] that the downlink dual-polarized channel can be represented by the following matrix:

$$\mathbf{H} \approx \alpha \begin{bmatrix} 1 & \mu\chi e^{j\phi} \\ \chi e^{j\phi} & \mu \end{bmatrix} \quad (8)$$

where α is a random time-varying fading variable (remember that antennas are co-located); ϕ is a random time varying angle uniformly distributed over $[0, 2\pi]$; μ and $\chi \in [0, 1]$ are random time-varying variables which represent respectively the ratio of the propagation loss in orthogonal components and the cross-polar discrimination (XPD). In slanted schemes, it is evident that $\mu = 1$ due to the array symmetry. Furthermore, experimental results [14] suggest that, for large receive-to-transmit distances, or in large excess path-loss areas, α is Rayleigh distributed (the Ricean K-factor describing fading is very low), and that $\chi \approx 1$ (the XPD is about 0 dB). So, in these cases, the dual-polarized channel matrix reduces to:

$$\mathbf{H} \approx \alpha \begin{bmatrix} 1 & e^{j\phi} \\ e^{j\phi} & 1 \end{bmatrix} \quad (9)$$

In (9), the matrix elements are Rayleigh-fading. The receive and transmit antenna correlations are also equal to zero, owing to the random phase-shift between co- and cross-polar components ($E\{e^{j\phi}\} = 0$). By contrast, the diagonal correlations are both equal to 1. The channel covariance matrix is then equal to:

$$\mathbf{R} = \begin{bmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 1 & 0 \\ 0 & 1 & 1 & 0 \\ 1 & 0 & 0 & 1 \end{bmatrix} \quad (10)$$

It is clear that such channels cannot be represented by the Kronecker model (which would yield i.i.d. channels). Furthermore, it has been shown in [15] that covariance matrices such as (10) maximize the ergodic capacity, and provide higher capacity than i.i.d. channels at any given receive SNR. This interesting behaviour, which has been observed in experimental results [14] for large excess path-loss conditions, cannot be explained at all by the Kronecker assumption, but requires the full-covariance representation.

C. One-Ring Model

The one-ring model is a popular geometry-based stochastic model, which has been proposed in the context of MIMO systems by [3] and [16]. It is true that the first condition is met for usual antenna spacings and omnidirectional antennas. Still, the one-ring model is single-bounce, therefore clearly violating the second condition, except in the very particular cases of an infinite range or a null ring radius (in this case, $t = 1$ in downlink scenarios). To illustrate this affirmation, let us apply the one-ring model of [3] to a 2×2 downlink scenario, with broadside antennas at the base station (BS). We denote by δ the ratio of the range to the radius of the ring. The set of equations (11) details the different correlation coefficients:

$$\begin{aligned} r &= J_0 \left[\frac{2\pi}{\lambda} \Delta_r \right] & s_1 &= J_0 \left[\frac{2\pi}{\lambda} \left(\frac{\Delta_r}{\delta} + \Delta_r \right) \right] \\ t &= J_0 \left[\frac{2\pi}{\lambda} \frac{\Delta_r}{\delta} \right] & s_2 &= J_0 \left[\frac{2\pi}{\lambda} \left(\frac{\Delta_r}{\delta} - \Delta_r \right) \right] \end{aligned} \quad (11)$$

where λ is the wavelength, and Δ_r and Δ_t are the Tx/Rx antenna spacings. Only four parameters are needed, as we assume that the first condition is fulfilled. As far as the second one is concerned, the single-bounce assumption naturally violates it. Exception is when δ approaches infinity: then, $t = 1$, while s_1 and $s_2 \cong r$ equal thus r . In this case, one side of the link is fully correlated, through a null angle-spread at Tx. By contrast, when Δ_r and Δ_t are chosen as the smallest possible values to force the Tx and Rx correlations to zero, the cross correlations s_1 and s_2 are respectively equal to -0.24 and 1 . Clearly, this channel is not Kronecker-structured, and the relative error on the Frobenius norm of the difference between \mathbf{R}_K and \mathbf{R} [17] is equal to 34 % in this case.

Are these results in contradiction with [3]? Actually, [3] only validates the Kronecker model in a particular scenario, considering that δ is large (so that s_1 and $s_2 \cong r$) and that Δ_r is significantly larger than 0.5λ , so that $r \cong 0$, as are thus s_1 and s_2 . For this particular scenario, the covariance matrix of the one-ring model has indeed a Kronecker structure. However, one side of the link is totally decorrelated through large antenna spacing at Rx. That highlights the paradox of the Kronecker model: although developed to represent arbitrary correlation, it only fits the one-ring downlink channel when the transmit side is fully correlated or the receive side is almost uncorrelated, provided that δ is (unrealistically?) large enough. The Kronecker model is thus representative of the one-ring model only in extreme cases, for which (5) reduces to:

$$\mathbf{H} = \mathbf{R}_r^{1/2} \mathbf{H}'_w \quad \text{or} \quad \mathbf{H} = \mathbf{H}_w \mathbf{R}_t^{1/2} \quad (12)$$

where \mathbf{H}'_w is a rank-1 matrix with n_r ($= 2$ here) independent complex Gaussian elements (i.e. all columns are identical).

Interestingly enough, a similar conclusion might possibly be reached for any single-bounce model, and, by extrapolation, for any real-world scenario where uniquely-linked propagation

mechanisms dominate³. Whether these mechanisms are dominant or not remains an open question, despite a number of experimental results presented below.

D. Experimental Data

Few experiments have truly investigated the validation of the Kronecker model, contrarily to the general belief. Before detailing these results, it must also be mentioned that any comparison relies on one or several metrics (mutual information, eigenvalue distributions, joint AoA-AoD spectrum, diversity order, etc.). Although the Kronecker model might adequately reproduce one given metric, it may simultaneously fail on another metric. Therefore, experimental validations described in the literature must be taken with caution, as they often rely on one particular metric. There is another reason why experimental validations should be taken cautiously. The MIMO channel matrix does not only depend on the propagation channel (i.e. the environment) but also on the configuration of the antenna array. This explains namely why the one-ring model has been associated with the Kronecker model in the past, since it was shown to be Kronecker-structured for a particular array configuration. We have shown that the one-ring model is however not Kronecker *per se*. The same remark applies with regard to experimental validations. It may be well possible that the experimental results validate the Kronecker, but this validation should *a priori* not be considered as a general property of the environment (as it is often the case). The results only hold true for the given range of antenna spacings that has been used in the experiment. The consequence is that the physical channel might not be Kronecker structured, but that the combination of the channel with the experimental antenna spacings could produce the Kronecker structure.

In [5], the Kronecker model is successfully validated in indoor microcellular and picocellular scenarios for 4×4 MIMO systems, based on the distributions of the eigenvalues. However, the closeness between measured and simulated distributions is not quantified. A more global analysis, based on the median error on each eigenvalue, yields errors below 1 dB for the largest eigenvalue, and 3.5 dB for the smallest eigenvalue in 90 % of the cases.

In [17], the Kronecker model is validated in an indoor environment for 2×2 and 3×3 setups, using a metric measuring the closeness of \mathbf{R} and \mathbf{R}_K . The error metric varies from 5 to 8 %, which is considered to be small enough to accept the separability assumption.

In [4], 16×16 MIMO downlink experimental results in downtown New York City enable to validate the Kronecker model using the mutual information as a metric. However, it must be pointed out that the measured Rx and Tx correlations seem pretty low in these measurements. As pointed out in the sequel, these results should not allow concluding on the general validity of the Kronecker model.

In [12], the validity of the Kronecker model is investigated for 2×2 , 4×4 and 8×8 indoor Rayleigh channels, based on

³ Uniquely-linked modes are not necessarily single-bounce, but are such that any AoD is linked to a different single AoA, and vice-versa.

different metrics. These results are, to the author's knowledge, the only ones presenting a full investigation on the validity of the Kronecker model. An interesting conclusion is that the validity of the Kronecker model decreases as the array sizes increase, which nuances the validation of [17]. Simulations at 20 dB SNR show that the Kronecker model generally underestimates the mutual information by more than 10 % for large arrays (8×8) and low capacity values (i.e. at non negligible correlation levels). Again, we observe that the Kronecker model fails when correlations are significant enough, although it is supposed to model correlated channels. Also, the diversity order is never well reproduced, even for small arrays.

IV. CONCLUSIONS

This paper has clearly detailed the conditions of validity of the popular Kronecker model for MIMO correlated channels, both on mathematical and propagation viewpoints. It is pointed out that two propagation conditions must be fulfilled for the Kronecker model to be *rigorously* valid for any antenna configuration. If one of these conditions is not met, it is still possible that the Kronecker model *still* be *valid* in some particular scenarios, strongly depending on the antenna spacings and array configurations. Therefore, it is really dangerous to conclude on the general Kronecker structure of a physical channel, since what is true for a given array configuration might not be true for another configuration. So, under which conditions may non Kronecker-structured environments be well represented by Kronecker channels?

Some channels (macroscopic MIMO, mutual coupling) are clearly not Kronecker-structured because the first condition is not met. These channels can hardly be represented by the Kronecker model.

For other scenarios (for which the first condition is met), the answer is less straightforward. If there are dominant uniquely-coupled propagation modes, the channel matrix will be Kronecker-structured when sufficiently large antenna spacings at one side allow for low antenna correlation across the array at that side. Note that this imposes the antenna spacing to "be in the tail" of the correlation-vs.-spacing curve, so this is a stronger condition than just cancelling the antenna correlation at that side. This constitutes the paradox of the Kronecker model: unless it is rigorously valid (including the case of channels with a very small angle-spread at one side only), it appears to be *approximately* valid only for low-correlated channels (at least at one side), although it is widely used to account precisely for arbitrary correlation effects. Furthermore, experimental results further suggest that the Kronecker approximation (applied in non Kronecker-structured propagation scenarios) yields better results for small array sizes. Naturally, we insist once again that the Kronecker model is valid for all array sizes and configurations in Kronecker-structured propagation scenarios.

The last question is: how important is the error introduced by the Kronecker model on the evaluation of system performance? It is illustrated in [12] that the Kronecker model might provide significant underestimations of the mutual information for indoor MIMO systems using large linear arrays, and does

not reproduce the diversity measure of the channel. Naturally, more investigations are needed, as it also depends on the considered metrics, the array configuration, etc.

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