Spy Your Mate

Project Report — 054327 - Wireless Internet | 054323 - Internet of Things

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Abstract—After a global pandemic, video streaming calls have become the normality in every situation. Even though the major providers usually encrypt the traffic, some information can be extracted by the packets that are sent between the parties through the internet. By aggregating the packets of a conversation and analyzing some of their features through a ML algorithm, we can infer if somebody is present in front of the camera or there is nobody.

I. INTRODUCTION

In this report I am going to illustrate the work done for the joint project of Wireless Internet and Internet of Things.

I was required to extract some information from a video call with a provider of my choice. In particular, I was requested to analyze the traffic generated by a webcam call and, from such traffic, identify whether a person or only the background is recorded in the video. I was asked to capture the network traffic and filter all the video call packets. Subsequently, I had to extract some important features from the captured packets, and use those features to train a model of Machine Learning. Finally, I had to predict the presence of a person in the background using the trained model and compare the prediction with the ground truth. For the comparison, I had to use a Node-RED chart.

II. METHOD

The first step was to choose a software for network traffic, hence I chose Wireshark¹. I recorded three vide calls. In the first one I was alone, in the other two I was with another person (different each

¹wireshark.org

time). The captures duration is more or less between 300 seconds and 420 seconds. For the video calls I used my laptop (Asus) and my smartphone (Samsung Galaxy S10). The provider I used was Zoom², as I am comfortable with it.

I needed both the IP addresses and the UDP ports to filter the packets of the video call. In Wireshark there is a convenient window under Statistics -> Conversations which shows you the conversations based on the chosen protocol. Clicking on UDP, I ordered the conversations in order to highlight the one with the highest number of packets (and bytes) transferred. It was easy to see which one is the actual video call, because there is a difference of several orders of magnitude in number of bytes exchanged. The addresses and the ports that I extracted from Wireshark can be seen at Table I.

A. Python Code

After extracting the addresses, I used them to filter out only the packets regarding the conversation between the parties. I used PyShark³ to manipulate the captures. The Python scripts are used to extract the packets, organize them in chunks of half a second, and save the chunks and their features on a csv file, later used for training or testing. The scripts are called in order by the prepare_*.py scripts. I divided them for convenience during debugging.

The training and testing is done by two scripts called script_ML_*.py. The cross validation is only used to understand if the features chosen are good to make an accurate prediction, and the

²zoom.us

³pypi.org/project/pyshark/

	Zoom IP Address	Zoom UDP Port	Local IP Address	Local UDP Port
Capture 1	149.137.11.203	8801	192.168.1.15	60235
Capture 2	149.137.11.142	8801	192.168.1.15	51541
Capture 3	149.137.10.223	8801	192.168.1.15	52409

TABLE I: Addresses for each capture.

second script is used to actually predict the results. I used the second capture (capture2_test.csv) to test the model and the other two captures to train it.

I incrementally added features to get a model each time more accurate, and I finally ended up with (TODO NUMBER OF FEATURES) features. Each of them represents a chunk of half a second packets:

- Average packet interval: the average time between one packet and the next.
- Average packet size: the average packet size in bytes.
- Inbound packets number: the total number of packets inbound (from the Zoom server to my laptop).
- Outbound pakeets number: the total number of packets outbound (from my laptop to the Zoom server).
- TODO more features

I used two different algorithms to train the model: logistic regression and random forest. The predictions are saved as CSV files to be later used in Node-RED.

B. Node-RED Flow

In Node-RED I was required to compare the ground truth with the actual prediction done in Python.

In order to do that, I read with Node-RED two different csv files (the capture file exported in csv and the prediction of python) and compared the results with the Chart of Node-RED. For comparing the results, I had to filter out the ground truth taking only the multiples of half a second. The prediction file, instead, had already been prepared with Python.

III. EXPERIMENTAL RESULTS