

Mathematics and Statistics

$$\int_{M}d\omega=\int_{\partial M}\omega$$

Mathematics 3F03 Advanced Differential Equations

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Lecture 31 Non-Existence of Periodic Orbits Monday 18 November 2013

Announcements

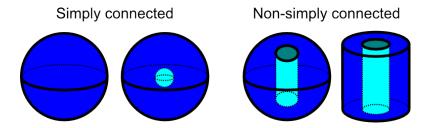
- Assignment 4 solutions were posted on Saturday.
- Assignment 5 was posted on Saturday (due this Friday, 22 Nov 2013, at 1:30pm).
 - Also look at Assignment 5 from 2011: includes problem on Poincaré Bendixson theorem and other relevant problems.
- Test 2 next Wednesday, 27 Nov 2013, at 11:30am.
 - Emphasis is on material covered since Test 1, including what we cover this week.
 - Location: T29 / 101

Simply Connected Domains in the plane

Simply connected Non-simply connected

- Any two points are connected by a path.
- Every closed curve can be continuously shrunk to a point.

Simply Connected Domains in \mathbb{R}^3



- More subtle than in 2D.
- We will be using this concept only in 2D.

Bendixson Negative Criterion

Theorem (Bendixson Negative Criterion)

Consider the planar differential equation X' = F(X), i.e.,

$$x' = f(x, y),$$

$$y' = g(x, y),$$

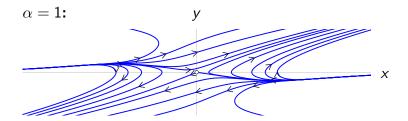
where $f,g:D\to\mathbb{R}$ are C^1 functions on a simply connected domain $D\subset\mathbb{R}^2$. If div $F\equiv\nabla\cdot F>0$ everywhere in D (or <0 everywhere in D) then $\not\exists$ periodic orbits lying entirely in D.

$$x' = xy^{2} + \sin y$$
$$y' = x^{2}y + \sin x + \alpha y$$

Does this system have periodic solutions?

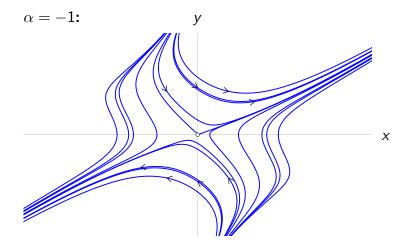
$$\nabla \cdot F = \left(\frac{\partial}{\partial x}, \frac{\partial}{\partial y} \right) \cdot (x', y') = y^2 + x^2 + \alpha$$

 \bullet $\alpha > 0 \implies \nabla \cdot F > 0 \quad \forall X \in \mathbb{R}^2 \implies \mathbb{Z}$ periodic orbits.



$$x' = xy^{2} + \sin y$$
$$y' = x^{2}y + \sin x + \alpha y$$

- $\nabla \cdot F = \left(\frac{\partial}{\partial x}, \frac{\partial}{\partial y}\right) \cdot (x', y') = y^2 + x^2 + \alpha$
- $\alpha < 0 \implies \nabla \cdot F < 0$ iff $||X|| < \sqrt{|\alpha|}$ \implies \nexists periodic orbits inside the disk of radius $\sqrt{|\alpha|}$.
- Also $\not\exists$ periodic orbits lying entirely in any simply connected domain outside the disk D.
- In principle, there might be periodic orbits on the boundary or encircling the disk *D*.
- Computer-generated phase portrait (next slide) suggests this is implausible, but that is not a proof.



$$x' = xy^{2} + \sin y$$
$$y' = x^{2}y + \sin x + \alpha y$$

- $\nabla \cdot F = \left(\frac{\partial}{\partial x}, \frac{\partial}{\partial y}\right) \cdot (x', y') = y^2 + x^2 + \alpha$
- $\alpha = 0 \implies \nabla \cdot F > 0 \quad \forall X \neq (0,0) \implies \not\exists$ periodic orbits lying entirely in any simply connected domain that does not include the origin.
- In principle, there might be periodic orbits that enclose the origin (or that pass through it).

Bendixson-Dulac Negative Criterion

Theorem (Bendixson-Dulac Negative Criterion)

Consider the planar differential equation X' = F(X), i.e.,

$$x' = f(x, y), \qquad y' = g(x, y),$$

where $f,g:D\to\mathbb{R}$ are C^1 functions on a simply connected domain $D\subset\mathbb{R}^2$. In addition, consider a C^1 scalar function $h:D\to\mathbb{R}$. If $\operatorname{div}(hF)\equiv\nabla\cdot(hF)>0$ everywhere in D (or <0 everywhere in D) then $\not\exists$ periodic orbits lying entirely in D and h is said to be a "Dulac function".

- $h \equiv 1$ yields the original Bendixson negative criterion.
- As with Lyapunov functions, there is no algorithm for discovering a Dulac function.

Example: Does this system have periodic orbits?

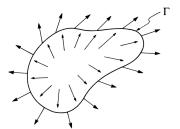
$$x' = \frac{1}{x^2 + y^2 + 1}, \qquad y' = \frac{y}{x^2 + y^2 + 1}$$

- $\nabla \cdot F = \frac{x^2 y^2 2x + 1}{(x^2 + y^2 + 1)^2}$
 - At $(x, y) = (0, 0), \nabla \cdot F = 1 > 0$.
 - At (x, y) = (0, 2), $\nabla \cdot F = -3/25 < 0$.
 - ∴ Bendixson's criterion rules out periodic orbits in some simply connected regions of the plane, but not in the whole plane.
- Dulac function?
 - Try $h(x, y) = x^2 + y^2 + 1$.
 - $\nabla \cdot (hF) = 1 > 0 \ \forall (x,y) \in \mathbb{R}^2.$
 - \blacksquare .: \exists periodic orbits anywhere in \mathbb{R}^2 .

Index Theory

Index Theory: Concept

Consider a simply connected domain $D \subset \mathbb{R}^2$ and a closed loop $\Gamma \subset D$ that contains no fixed points (equilibria) of X' = F(X).



Arrows represent values of the vector field F.

- As you slide all the way along Γ , the angle ϕ of the vector field changes by an integer number of full rotations: $\Delta \phi = 2k\pi$ $\exists k \in \mathbb{Z}$.
- **•** k is the **index** of Γ .

Index Theory: Formal Definition

Definition (Index of a closed curve Γ)

Consider a smooth, planar vector field, (x', y') = (f(x, y), g(x, y)), defined in a simply connected domain $D \subset \mathbb{R}^2$. Suppose Γ is a closed loop in D ($\Gamma \subset D$) and that Γ contains no fixed points of the vector field (*i.e.*, there is no point $(x_*, y_*) \in \Gamma$ such that $f(x_*, y_*) = g(x_*, y_*) = 0$). Then the index of Γ is

$$k = \frac{1}{2\pi} \oint_{\Gamma} d\phi \,,$$

which can be calculated in Cartesian coordinates via

$$k = \frac{1}{2\pi} \oint_{\Gamma} d\left(\arctan\frac{g(x,y)}{f(x,y)}\right) = \frac{1}{2\pi} \oint_{\Gamma} \frac{f \, dg - g \, df}{f^2 + g^2} \, .$$

Index Theory: Properties

- The index is the same if Γ is smoothly deformed, as long as it is not deformed through some fixed point of the vector field.
- The index of a fixed point is defined to be the index of a closed curve that contains only this one fixed point, and where no fixed points are on the closed curve.