

Mathematics 3F03

Advanced Differential Equations

Instructor: David Earn

Lecture 6

Second Order and Planar ODEs

18 September 2013

Announcements

- Assignment 1 due THIS FRIDAY, 20 Sep 2013, before class, in the appropriately labelled locker next to HH-105.
- **Putnam Mathematical Competition:** There will be an organizational meeting on Thursday 19 Sep 2013 in HH 410.

The William Lowell Putnam competition is a university-level mathematics competition held annually for undergraduate students at North American universities. More information can be found at <http://math.scu.edu/putnam> or on the undergraduate page of the Math department's website. This year's competition will occur on 7 Dec 2013. If you are interested in participating or learning more, drop by on Thursday 19 Sep and/or send email to Prof. Bradd Hart (hartb@mcmaster.ca).

Second Order ODEs

Warning: using ' for time derivative.

$$x'' = f(t, x, x'), \quad x(0) = x_0, \quad x'(0) = v_0.$$

- Example: *Forced Harmonic Oscillator*

$$mx'' = -bx' - kx + f(t)$$

- Usually forcing is periodic, e.g., $f(t) = \cos(2\pi t)$.

2nd order ODE equivalent to two coupled 1st order ODEs

$$x'' = f(t, x, x'), \quad x(0) = x_0, \quad x'(0) = v_0.$$

- Let $y = x'$, $y_0 = y(0) = x'(0)$
- $\therefore y' = x''$
- Equation becomes

$$\begin{aligned} x' &= y, & x(0) &= x_0 \\ y' &= f(t, x, y), & y(0) &= y_0 \end{aligned}$$

- We will study general ODEs in the plane:

$$\begin{aligned} x' &= f(t, x, y) & x(0) &= x_0 \\ y' &= g(t, x, y), & y(0) &= y_0 \end{aligned}$$

General Planar ODE

$$\begin{aligned}x' &= f(t, x, y) & x(0) &= x_0 \\y' &= g(t, x, y), & y(0) &= y_0\end{aligned}$$

Equivalently, in vector notation:

$$X' = F(t, X), \quad X_0 = X(0) = \begin{pmatrix} x_0 \\ y_0 \end{pmatrix} \in \mathbb{R}^2$$

This generalizes immediately to n dimensions...

General ODE in \mathbb{R}^n

$$\begin{array}{ll} x_1' = f_1(t, x_1, x_2, \dots, x_n) & x_1(0) = x_{1,0} \\ x_2' = f_2(t, x_1, x_2, \dots, x_n) & x_2(0) = x_{2,0} \\ \vdots & \vdots \\ x_n' = f_n(t, x_1, x_2, \dots, x_n) & x_n(0) = x_{n,0} \end{array}$$

Equivalently, in vector notation:

$$X' = F(t, X), \quad X_0 = X(0) = (x_{1,0}, x_{2,0}, \dots, x_{n,0}) \in \mathbb{R}^n$$

Very simple planar example

$$x' = y$$

$$y' = -x$$

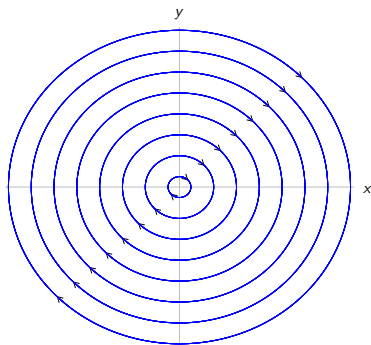
(Equivalent to $x'' = -x$)

■ Solution:

$$\begin{pmatrix} x(t) \\ y(t) \end{pmatrix} = a \begin{pmatrix} \sin t \\ \cos t \end{pmatrix}$$

■ Circular motion on a circle of radius a .

Solutions in the *phase plane* yield the *phase portrait*.



Interpretation as Vector Field

$$X' = F(t, X), \quad X_0 = X(0)$$

- X = point in plane (or in \mathbb{R}^n)
- $F(t, X)$ = vector field, i.e., magnitude and direction of “flow”
- **Note:** In 1D, it is common to draw the “slope field” (a 2D drawing) since the vectors in the vector field lie on top of each other. But I find vector field a more intuitive concept. The vector field lies on the *phase line* in 1D and on the *phase plane* in 2D.

Vector Field vs Direction Field

- *Vector Field* shows both magnitude and direction of flow
- *Direction Field* shows only direction of flow
 - All vectors have the same length.
 - Usually much easier to draw and interpret.
 - Does not show speed of flow
(though this can be represented using colour).
 - Computers are good at drawing such things...

Vector Field vs Direction Field

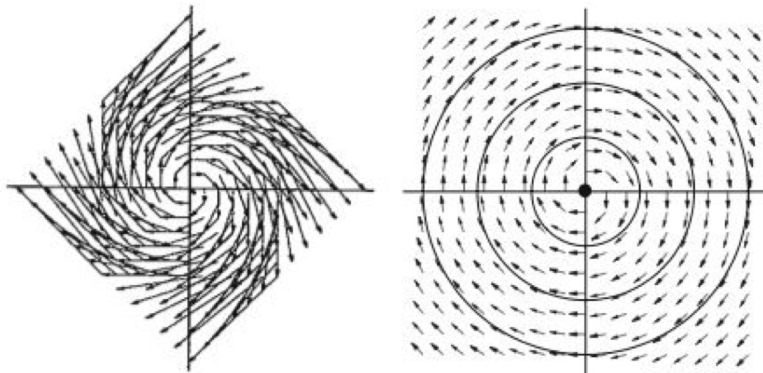


Figure 2.1 The vector field, direction field, and several solutions for the system $x' = y$, $y' = -x$.

Generalizing from the very simple planar ODE example

$$\begin{aligned}x' &= y \\ y' &= -x\end{aligned}$$

- Equation can also be written:

$$X' = AX, \quad \text{where } A = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}$$

- This generalizes to any **linear** ODE in any number of dimensions.*
- Not surprising that linear algebra will be useful.
- Less obvious, but true: linear algebra is also critical for studying **nonlinear** ODEs.