

Davide Boscaini, Ph.D.

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About

I am a tenure-track research scientist at the **Technologies of Vision** research unit of the **Fondazione Bruno Kessler** in Trento, Italy. My research interests are in 3D perception and understanding, with a focus on object 6D pose estimation and 3D scene segmentation.

Before joining FBK, I received a PhD in Computational Science from the **Università della Svizzera italiana** in Lugano, Switzerland, in 2017. During my PhD, under

the supervision of prof. **Michael Bronstein**, my research focused on extending deep learning techniques to geometric domains such as 3D shapes and graphs, contributing to the birth of a new research direction called **Geometric Deep Learning**. Prior to that, I obtained an M.S. in Mathematics from the **University of Verona**, Italy, in 2013, and a B.S. in Applied Mathematics from the same institution in 2010.

In a nutshell. 12+ years of experience. Cited more than 6,000 times, with an h-index of 15 and an i10-index of 18. Author of 40 scientific papers. Inventor of 3 US patents. Winner of 5 awards at the BOP Challenge in 2023 and 2024. Pioneer of Geometric Deep Learning, with works cited in modern deep learning textbooks.

Education

Ph.D. in Computational Science Università della Svizzera italiana	Sep. 2013 – Sep. 2017 <i>Lugano, Switzerland</i>
Dissertation on “Geometric Deep Learning for Shape Analysis”. Advisor: M.M. Bronstein. Co-advisor: J. Masci. Examiners: J. Schmidhuber, M. Ovsjanikov, P. Vanderghenst, K. Hormann	
M.S. in Mathematics University of Verona	Oct. 2010 – Mar. 2013 <i>Verona, Italy</i>
Dissertation on “Spectral Methods for Shape Analysis”. Advisor: G. Orlandi. Co-advisor: U. Castellani	
B.S. in Applied Mathematics University of Verona	Sep. 2007 – Oct. 2010 <i>Verona, Italy</i>
Dissertation on “Existence and multiplicity of the solutions of the Plateau problem”. Advisor: S. Baldo	

Awards

“Second place” for task-driven affordance grounding	SceneFun3D Challenge 2025
“Best overall method” for 6D detection of unseen objects	BOP Challenge 2024
“Best overall method” for 6D localization of unseen objects	BOP Challenge 2024
“Early-bird winner” of 6D detection of unseen objects	BOP Challenge 2024
“Early-bird winner” of 6D localization of unseen objects	BOP Challenge 2024
“Best method on TUD-L dataset” for the 6D localization of unseen objects	BOP Challenge 2023

Publications

CHIP: A multi-sensor dataset for 6D pose estimation of chairs in industrial settings	BMVC 2025
M. Nardon, M. Mujika, A. González, D. Sedano, J. Rueda, A. Caro, A. Caraffa, F. Poiesi, P.I. Chippendale, D. Boscaini	
Distilling 3D distinctive local descriptors for 6D pose estimation	IROS 2025
A. Hamza, A. Caraffa, D. Boscaini, F. Poiesi	
AI-driven visual monitoring of industrial assembly tasks	ICIAP 2025
M. Nardon, S. Messelodi, A. Granata, F. Poiesi, A. Danese, D. Boscaini	
Functionality understanding and segmentation in 3D scenes	CVPR 2025
J. Corsetti, F. Juliari, A. Fasoli, D. Boscaini, F. Poiesi	
<i>Highlight poster (3% acceptance rate). Awarded “Second place” for “Task-driven affordance grounding” at the SceneFun3D Challenge 2025</i>	
3D part segmentation via geometric aggregation of 2D visual features	WACV 2025
M. Garosi, R. Tedoldi, D. Boscaini, M. Mancini, N. Sebe, F. Poiesi	

- Wild Berry image dataset collected in Finnish forests and peatlands using drones** ECCV-W 2024
L. Riz, S. Povoli, A. Caraffa, D. Boscaini, M.L. Mekhalfi, P. Chippendale, M. Turtiainen, B. Partanen, L.S. Ballester, F.B. Noguera, A. Franchi, E. Castelli, G. Piccinini, L. Marchesotti, M.S. Couceiro, F. Poiesi
- FreeZe: Training-free zero-shot 6D pose estimation with geometric and vision foundation models** ECCV 2024
A. Caraffa, D. Boscaini, A. Hamza, F. Poiesi
An enhanced version of this work, FreeZe-v2, is the “early bird winner” in both 6D localization and 6D detection at the BOP Challenge 2024. An early version of this work, PoZe, won the “Best method on TUD-L dataset” award at the BOP Challenge 2023
- Exploring fine-grained retail product discrimination with zero-shot object classification using Vision-Language Models** RTSI 2024
A. Tur, A. Conti, C. Beyan, D. Boscaini, R. Larcher, S. Messelodi, F. Poiesi, E. Ricci
- Open-vocabulary object 6D pose estimation** CVPR 2024
J. Corsetti, D. Boscaini, C. Oh, A. Cavallaro, F. Poiesi
First open-vocabulary setting for object 6D pose estimation. Highlight poster (2.8% acceptance rate)
- Tracciamento 3D della palla da punti di vista multipli nella pallavolo** Ital-IA 2024
L. Riz, S. Povoli, D. Boscaini, S. Messelodi, F. Poiesi
- Detect, Augment, Compose, and Adapt: Four steps for unsupervised domain adaptation in object detection** BMVC 2023
M.L. Mekhalfi, D. Boscaini, F. Poiesi
- Revisiting Fully Convolutional Geometric Features for object 6D pose estimation** ICCV-W 2023
J. Corsetti, D. Boscaini, F. Poiesi
- PatchMixer: Rethinking network design to boost generalization for 3D point cloud understanding** IMAVIS, 2023
D. Boscaini, F. Poiesi
Novel network design that is intrinsically effective in generalisation across datasets unseen at training time
- Supervised tractogram filtering using geometric deep learning** MIA, 2023
P. Astolfi, R. Verhagen, L. Petit, E. Olivetti, S. Sarubbo, J. Masci, D. Boscaini, P. Avesani
- The MONET dataset: Multimodal drone thermal dataset recorded in rural scenarios** CVPR-W 2023
L. Riz, A. Caraffa, M. Bortolon, M.L. Mekhalfi, D. Boscaini, A. Moura, J. Antunes, A. Dias, H. Silva, A. Leonidou, C. Constantinides, C. Keleshis, D. Abate, F. Poiesi
- Learning general and distinctive 3D local deep descriptors for point cloud registration** TPAMI, 2023
F. Poiesi, D. Boscaini
State-of-the-art performance for point cloud registration in the transfer learning setting across 3DMatch, ETH, and KITTI datasets
- SHIELD: Safeguard heritage in endangered looted districts** Ital-IA 2022
M.L. Mekhalfi, N. Saljoughi, D. Boscaini, F. Poiesi
- Localisation of defects in volumetric CT scans of valuable wood logs** ICPR-W 2020
D. Boscaini, F. Poiesi, S. Messelodi, A. Younes, D. Grande
Selected for oral presentation
- Joint supervised and self-supervised learning for 3D real-world challenges** ICPR 2020
A. Alliegro, D. Boscaini, T. Tommasi
Selected for oral presentation (4.4% acceptance rate)
- Distinctive 3D local deep descriptors** ICPR 2020
F. Poiesi, D. Boscaini
- Shape consistent 2D keypoint estimation under domain shift** ICPR 2020
L.O. Vasconcelos, M. Mancini, D. Boscaini, S. Rota Bulò, B. Caputo, E. Ricci
- Novel-view human action synthesis** ACCV 2020
M. Lakhal, D. Boscaini, F. Poiesi, O. Lanz, A. Cavallaro

- Clustered dynamic graph CNN for biometric 3D hand shape recognition** IJCB 2020
J. Svoboda, P. Astolfi, D. Boscaini, J. Masci, M.M. Bronstein
- Tractogram filtering of anatomically non-plausible fibers with geometric deep learning** MICCAI 2020
P. Astolfi, R. Verhagen, L. Petit, E. Olivetti, J. Masci, D. Boscaini, P. Avesani
- Self-supervision for 3D real-world challenges** ECCV-W 2020
A. Alliegro, D. Boscaini, T. Tommasi
- Deciphering interaction fingerprints from protein molecular surfaces** Nature Methods, 2020
P. Gainza, F. Sverrisson, F. Monti, E. Rodolà, D. Boscaini, M.M. Bronstein, B.E. Correia
Advertised on the cover of the Feb 2020 issue of the journal
- Learning interaction patterns from surface representations of protein structure** NeurIPS-W 2019
P. Gainza, F. Sverrisson, F. Monti, E. Rodolà, D. Boscaini, M.M. Bronstein, B.E. Correia
- Structured domain adaptation for 3D keypoint estimation** 3DV 2019
L.O. Vasconcelos, M. Mancini, D. Boscaini, B. Caputo, E. Ricci
Oral presentation
- 3D shape segmentation with geometric deep learning** ICIAP 2019
D. Boscaini, F. Poiesi
Spotlight presentation
- Geometric deep learning on graphs and manifolds using mixture model CNNs** CVPR 2017
F. Monti*, D. Boscaini*, J. Masci, E. Rodolà, J. Svoboda, M.M. Bronstein
Oral presentation. First unified framework generalizing CNN architectures to non-Euclidean domains such as 3D shapes and graphs. Also available as technical report: arXiv:1611.08402. (indicates equal contribution)*
- Geometric deep learning** SIGGRAPH Asia Courses 2016
J. Masci, E. Rodolà, D. Boscaini, M.M. Bronstein, H. Li
- Learning shape correspondence with anisotropic convolutional neural networks** NeurIPS 2016
D. Boscaini, J. Masci, E. Rodolà, M.M. Bronstein
Presented also as a poster at the 3D Deep Learning Workshop (3DLL) 2016. Also available as technical report: arXiv:1605.06437
- Anisotropic diffusion descriptors** CGF, 2016
D. Boscaini, J. Masci, E. Rodolà, M.M. Bronstein, D. Cremers
Oral presentation at EUROGRAPHICS 2016
- Geodesic convolutional neural networks on Riemannian manifolds** ICCV-W 2015
J. Masci*, D. Boscaini*, M.M. Bronstein, P. Vandergheynst
Oral presentation at 3DRR 2015. First extension of the popular CNN paradigm to non-Euclidean domains. An early version of this work was published as the technical report arXiv:1501.06297 on January 2015. (indicates equal contribution)*
- Learning class-specific descriptors for deformable shapes using localized spectral convolutional networks** CGF, 2015
D. Boscaini, J. Masci, S. Melzi, M.M. Bronstein, U. Castellani, P. Vandergheynst
Oral presentation at SGP 2015
- Shape-from-operator: Recovering shapes from intrinsic operators** CGF, 2015
D. Boscaini, D. Eynard, D. Kourounis, M.M. Bronstein
Oral presentation at EUROGRAPHICS 2015. First approach able to synthesize the extrinsic geometry of a shape from intrinsic information. An early version of this work was published as the technical report arXiv:1406.1925 on June 2014
- Coulomb shapes: Using electrostatic forces for deformation-invariant shape representation** EUROGRAPHICS-W 2014
D. Boscaini, R. Girdziusas, M.M. Bronstein
Oral presentation at 3DOR 2014. Presented also as a poster at the International Computer Vision Summer School (ICVSS), 2014
- A sparse coding approach for local-to-global 3D shape description** The Visual Computer, 2014
D. Boscaini, U. Castellani
Invited paper. Journal extension of the 3DOR 2013 conference paper
- Local signatures quantization by sparse coding** EUROGRAPHICS-W 2013
D. Boscaini, U. Castellani
Oral presentation at 3DOR 2013. Presented also as a poster at SGP 2013
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Patents

US patent application No. 17675011

Clustered dynamic graph convolutional neural network for biometric 3D hand recognition

Inventors: J. Svoboda, P. Astolfi, D. Boscaini, J. Masci

US patent No. 10210430

Filed Feb. 19, 2019

System and a method for learning features on geometric domains (CIP)

Inventors: M.M. Bronstein, D. Boscaini, F. Monti • Acquired by Twitter Inc.

US patent No. 10013653

Filed Jul. 3, 2018

System and a method for learning features on geometric domains

Inventors: M.M. Bronstein, D. Boscaini, J. Masci, P. Vandergheynst • Acquired by Twitter Inc.

Invited talks

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| 3D object understanding on the shoulders of 2D foundation models
Shandong University, China • Invited by Fabio Poiesi | Jul. 29, 2025 |
| Object 6D pose estimation in the foundation models era
University of Trento, Italy • Master course in “Trends and Applications in Computer Vision”, Invited by Massimiliano Mancini | Nov. 22, 2024 |
| Object 6D pose estimation in the foundation models era
Politecnico di Torino, Italy • Invited by Francesca Pistilli | Jun. 6, 2024 |
| 3D object understanding on the shoulders of 2D foundation models
École Polytechnique, Paris, France • Invited by Maks Ovsjanikov | Mar. 28, 2024 |
| 3D deep learning to the test of real-world challenges
University of Pisa, Italy • Ph.D. event “Visions of Tomorrow” | Dec. 11, 2020 |
| 3D Deep Learning
Politecnico di Torino, Italy • Invited by Tatiana Tommasi | Dec. 11, 2019 |
| Geometric deep learning for 3D shape analysis
Politecnico di Torino, Italy • Invited by Barbara Caputo | May 13, 2019 |
| Geometric deep learning for shape analysis
Kos, Greece • Keynote at EUSIPCO 2017 | Sep. 2, 2017 |
| Geometric deep learning for shape analysis
FBK-TeV, Trento, Italy • Invited by Samuel Rota Bulò and Stefano Messelodi | Apr. 4, 2017 |
| Geometric deep learning for shape analysis
CNR-IMATI, Genoa, Italy • Invited by Michela Spagnuolo | Feb. 13, 2017 |
| Deep learning on geometric data
Zurich, Switzerland • SSSTC RiC big data research workshop | Feb. 16, 2016 |
| Deep learning on geometric data
Embedded Vision Systems (eVS), Verona, Italy • Invited by Roberto Marzotto | Feb. 8, 2016 |
| Deep learning on geometric data
Rainbow group, University of Cambridge, UK • Invited by Flora Tasse | Feb. 4, 2016 |
| Deep learning on geometric data
University of Cambridge, UK • C.A.K.E. seminar, Invited by Simone Parisotto | Feb. 3, 2016 |
| Convolutional neural networks on non-Euclidean domains
Potsdam, Germany • Keynote at SciCADE 2015 | Sep. 14, 2015 |
| Shape-from-operators: recovering shapes from intrinsic differential operators
TUM, Munich, Germany • Invited by Emanuele Rodolà | Nov. 26, 2014 |
| Shape-from-operators: recovering shapes from intrinsic differential operators
Disentis, Switzerland • USI-ICS retreat | Aug. 19, 2014 |

Teaching experience

Academic courses

Trends and Applications in Computer Vision

University of Trento, Fall 2023

Short courses and tutorials

Functional Maps: A Flexible Representation for Learning and Computing Correspondences	3DV 2018
Geometric Deep Learning	SIGGRAPH Asia 2016
Deep Learning for Shape Analysis	EUROGRAPHICS 2016

Teaching Assistantships

Computer Vision and Pattern Recognition	Università della Svizzera italiana, Spring 2017
Computer Vision and Pattern Recognition	Università della Svizzera italiana, Spring 2016
Large Scale Optimization	Università della Svizzera italiana, Spring 2016
Computer Graphics	Università della Svizzera italiana, Fall 2014
Geometric Image Processing and Computer Vision	Università della Svizzera italiana, Spring 2014
Calculus	Università della Svizzera italiana, Fall 2013
Mathematical Analysis 1, Mathematical Analysis 2	University of Verona, 2012–2013
Mathematical Analysis 1, Mathematical Analysis 2	University of Verona, 2011–2012
Mathematical Analysis 1	University of Verona, 2010–2011

Student supervision

Jaime Corsetti, PhD student at FBK and University of Trento	Nov. 2023–present
Project: Vision-language models for embodied AI	
Mattia Nardon, Master student at University of Trento	Mar.–Dec. 2024
Role: Internship and Master thesis advisor	
Project: AI-powered visual monitoring of Lego assembly tasks	
Alice Fasoli, Master student at University of Trento	Mar.–Dec. 2024
Role: Internship and Master thesis advisor	
Project: Retrieval-driven 6D pose estimation of unseen objects	
Matteo Minardi, Master student at University of Trento	Mar.–Oct. 2024
Role: Internship and Master thesis advisor	
Projects: Eye-gaze estimation using smart glasses, Study of the vision encoder role in VLMs	
Marco Garosi, Master student at University of Trento	Dec. 2023–Apr. 2024
Project: Zero-shot semantic segmentation of 3D objects	
Outcome: Publication at WACV 2025	
Riccardo Tedoldi, Master student at University of Trento	Dec. 2023–Apr. 2024
Project: Zero-shot semantic segmentation of 3D objects	
Outcome: Publication at WACV 2025	
Jaime Corsetti, Master student at University of Trento	2022–Oct. 2023
Projects: Open-vocabulary and Supervised object 6D pose estimation for RGBD images	
Outcome: Publication at CVPR 2024	
Safa Abbes, Master student at University of Trento	2022–2023
Role: Masther thesis coadvisor	
Project: Self-supervised domain adaptation for RGB images	
Antonio Alliegro, PhD student at Politecnico di Torino	2020–2021
Project: Self-Supervised domain adaptation for 3D point clouds	
Outcome: Publications at ECCV-W 2020 and ICPR 2021	
Pietro Astolfi, PhD student at FBK, UniTN, and IIT	2019–2021
Project: Geometric Deep Learning for brain structure analysis	
Outcome: Publications at MICCAI 2020, IJCB 2020, and MIA 2023	
Levi O. Vasconcelos, PhD student at UniTN and IIT	2019–2020
Project: Structured domain adaptation	
Outcome: Publications at 3DV 2019 and ICPR 2020	
Antonio Alliegro, Master student at Politecnico di Torino	2019–2020
Role: Masther thesis coadvisor	
Piero Cavalcanti, Master student at Politecnico di Torino	2019–2020
Role: Masther thesis coadvisor	
Myriam Bronstein, Master student at Università della Svizzera italiana	2016
Project: Machine learning methods on manifolds and graphs	
Fatemeh Chegini, Master student at Università della Svizzera italiana	2014–2015
Project: Spectral methods for cross-modal retrieval	

Academic service

Conferences revision activity

International Conference on Robotics and Automation (ICRA)	2022, 2020
International Conference on Pattern Recognition (ICPR)	2022, 2020
Symmetry and Geometry in Neural Representations (NeurIPS Workshops)	2022
International Conference on Image Analysis and Processing (ICIAP)	2022
International Conference on Machine Learning, Optimization, and Data Science (LOD)	2022
Symposium On Applied Computing (SAC)	2022
International Conference on 3D Vision (3DV)	2021, 2020, 2019, 2018
International Conference on Machine Learning, Optimization, and Data Science (LOD)	2021
International Conference on Machine Vision Applications (MVA)	2021, 2019
EUROGRAPHICS	2019, 2017, 2015
The British Machine Vision Conference (BMVC)	2018
Computer Vision and Pattern Recognition (CVPR)	2017
International Symposium on Vision, Modeling and Visualization (VMV)	2016
Neural Information Processing Systems (NeurIPS)	2016

Journal revision activity

Robotics and Automation Letters (RAL)	2022
Computer Graphics Forum (CGF)	2022
IEEE Transactions on Image Processing (TIP)	2022, 2021
IEEE Transactions on Transactions on Knowledge and Data Engineering (TKDE)	2022, 2021
Neural Processing Letters (NEPL)	2022
IEEE Transactions on Pattern Analysis and Machine Intelligence (PAMI)	2021, 2020
IEEE Transactions on Visualization and Computer Graphics (TVCG)	2020, 2018, 2017
Computers and Graphics	2019
Computer Vision and Image Understanding (CVIU)	2019, 2015
International Journal of Machine Learning and Cybernetics (JMCL)	2019
Pattern Recognition Letters	2019
The Visual Computer Journal (TVCJ)	2018, 2017, 2016
Computer Aided Geometric Design (CAGD)	2018
Computer-Aided Design (CAD)	2018
Sensors	2018
IPSJ Transactions on Computer Vision and Applications	2017

Area chair

British Machine Vision Conference (BMVC)	2025
British Machine Vision Conference (BMVC)	2024

Program committee

International Workshop on Advances in Drone Vision (ADV)	2025
Graph Models for Learning and Recognition (GMLR)	2022
Organized within the 37th ACM Symposium on Applied Computing, Brno (Czech Republic)	
