Davide Boscaini, Ph.D.

Mail: dboscaini@fbk.eu • Webpage: https://davideboscaini.github.io • GitHub: github.com/davideboscaini

About

I am a tenure-track research scientist at the Technologies of Vision research unit of the Fondazione Bruno Kessler in Trento, Italy. My research interests are in 3D perception and understanding, with a focus on object 6D pose estimation. According to Google Scholar, I have an h-index of 15 and my papers have been cited more than 5,800 times. I am the inventor of 3 US patents.

Before joining FBK, I received a PhD in Computational Science from the Università della Svizzera italiana

in Lugano, Switzerland, in 2017. During my PhD, under the supervision of prof. Michael Bronstein, my research focused on extending deep learning techniques to geometric domains such as 3D shapes and graphs, contributing to the birth of a new research direction called Geometric Deep Learning. Prior to that, I obtained an M.S. in Mathematics from the University of Verona, Italy, in 2013, and a B.S. in Applied Mathematics from the same institution in 2010.

Education

Ph.D. in Computational Science

Sep. 2013 - Sep. 2017

Università della Svizzera italiana

Lugano, Switzerland

Dissertation on "Geometric Deep Learning for Shape Analysis". Advisor: M.M. Bronstein. Co-advisor: J. Masci. Examiners: J. Schmidhuber, M. Ovsjanikov, P. Vandergheynst, K. Hormann

M.S. in Mathematics

Oct. 2010 - Mar. 2013

University of Verona

Verona, Italy

Dissertation on "Spectral Methods for Shape Analysis". Advisor: G. Orlandi. Co-advisor: U. Castellani

Sep. 2007 – Oct. 2010

B.S. in Applied Mathematics

University of Verona

Verona, Italy

Dissertation on "Existence and multiplicity of the solutions of the Plateau problem". Advisor: S. Baldo

Awards

"Second place" for task-driven affordance grounding	SceneFun3D Challenge 2025
"Best overall method" for 6D detection of unseen objects	BOP Challenge 2024
"Best overall method" for 6D localization of unseen objects	BOP Challenge 2024
"Early-bird winner" of 6D detection of unseen objects	BOP Challenge 2024
"Early-bird winner" of 6D localization of unseen objects	BOP Challenge 2024
"Best method on TUD-L dataset" for the 6D localization of unseen objections.	ects BOP Challenge 2023

Publications

Functionality understanding and segmentation in 3D scenes

CVPR 2025

J. Corsetti, F. Giuliari, A. Fasoli, D. Boscaini, F. Poiesi

Highlight poster (3% acceptance rate). Awarded "Second place" for "Task-driven affordance grounding" at the SceneFun3D Challenge 2025

3D part segmentation via geometric aggregation of 2D visual features

WACV 2025

M. Garosi, R. Tedoldi, D. Boscaini, M. Mancini, N. Sebe, F. Poiesi

Wild Berry image dataset collected in Finnish forests and peatlands using drones

ECCV-W 2024

L. Riz, S. Povoli, A. Caraffa, D. Boscaini, M.L. Mekhalfi, P. Chippendale, M. Turtiainen, B. Partanen, L.S. Ballester, F.B. Noguera, A. Franchi, E. Castelli, G. Piccinini, L. Marchesotti, M.S. Couceiro, F. Poiesi

FreeZe: Training-free zero-shot 6D pose estimation with geometric and vision foundation models

ECCV 2024

A. Caraffa, D. Boscaini, A. Hamza, F. Poiesi

An enhanced version of this work, FreeZe-v2, is the "early bird winner" in both 6D localization and 6D detection at the BOP Challenge 2024. An early version of this work, PoZe, won the "Best method on TUD-L dataset" award at the BOP Challenge 2023

Exploring fine-grained retail product discrimination with zero-shot object classification using Vision-Language Models RTSI 2024 A. Tur, A. Conti, C. Beyan, D. Boscaini, R. Larcher, S. Messelodi, F. Poiesi, E. Ricci Open-vocabulary object 6D pose estimation **CVPR 2024** J. Corsetti, D. Boscaini, C. Oh, A. Cavallaro, F. Poiesi First open-vocaulary setting for object 6D pose estimation. Highlight poster (2.8% acceptance rate) Tracciamento 3D della palla da punti di vista multipli nella pallavolo Ital-IA 2024 L. Riz, S. Povoli, D. Boscaini, S. Messelodi, F. Poiesi Selected for oral presentation Detect, Augment, Compose, and Adapt: Four steps for unsupervised domain adaptation in object detection **BMVC 2023** M.L. Mekhalfi, D. Boscaini, F. Poiesi **Revisiting Fully Convolutional Geometric Features** for object 6D pose estimation ICCV-W 2023 J. Corsetti, D. Boscaini, F. Poiesi PatchMixer: Rethinking network design to boost generalization for 3D point cloud understanding **IMAVIS**, 2023 D. Boscaini, F. Poiesi Novel network design that is intrinsically effective in generalisation across datasets unseen at training time Supervised tractogram filtering using geometric deep learning MIA, 2023 P. Astolfi, R. Verhagen, L. Petit, E. Olivetti, S. Sarubbo, J. Masci, D. Boscaini, P. Avesani The MONET dataset: Multimodal drone thermal dataset **CVPR-W 2023** recorded in rural scenarios L. Riz, A. Caraffa, M. Bortolon, M.L. Mekhalfi, D. Boscaini, A. Moura, J. Antunes, A. Dias, H. Silva, A. Leonidou, C. Constantinides, C. Keleshis, D. Abate, F. Poiesi Learning general and distinctive 3D local deep descriptors for point cloud registration TPAMI, 2023 F. Poiesi, D. Boscaini State-of-the-art performance for point cloud registration in the transfer learning setting across 3DMatch, ETH, and Kitti datasets Localisation of defects in volumetric CT scans of valuable wood logs ICPR-W 2020 D. Boscaini, F. Poiesi, S. Messelodi, A. Younes, D. Grande Selected for oral presentation Joint supervised and self-supervised learning for 3D real-world challenges ICPR 2020 A. Alliegro, D. Boscaini, T. Tommasi *Selected for oral presentation (4.4% accaptance rate)* Distinctive 3D local deep descriptors ICPR 2020 F. Poiesi, D. Boscaini Shape consistent 2D keypoint estimation under domain shift ICPR 2020 L.O. Vasconcelos, M. Mancini, D. Boscaini, S. Rota Bulò, B. Caputo, E. Ricci Novel-view human action synthesis ACCV 2020 M. Lakhal, D. Boscaini, F. Poiesi, O. Lanz, A. Cavallaro Clustered dynamic graph CNN for biometric 3D hand shape recognition IJCB 2020 J. Svoboda, P. Astolfi, D. Boscaini, J. Masci, M.M. Bronstein Tractogram filtering of anatomically non-plausible fibers with geometric deep learning MICCAI 2020 P. Astolfi, R. Verhagen, L. Petit, E. Olivetti, J. Masci, D. Boscaini, P. Avesani Self-supervision for 3D real-world challenges ECCV-W 2020 A. Alliegro, D. Boscaini, T. Tommasi Deciphering interaction fingerprints from protein molecular surfaces Nature Methods, 2020

P. Gainza, F. Sverrisson, F. Monti, E. Rodolà, D. Boscaini, M.M. Bronstein, B.E. Correira

Advertised on the cover of the Feb 2020 issue of the journal

Learning interaction patterns from surface representations of protein structure NeurIPS-W 2019

P. Gainza, F. Sverrisson, F. Monti, E. Rodolà, D. Boscaini, M.M. Bronstein, B.E. Correira

Structured domain adaptation for 3D keypoint estimation

3DV 2019

L.O. Vasconcelos, M. Mancini, D. Boscaini, B. Caputo, E. Ricci *Selected for oral presentation*

3D shape segmentation with geometric deep learning

ICIAP 2019

D. Boscaini, F. Poiesi

Selected for spotlight presentation

Geometric deep learning on graphs and manifolds using mixture model CNNs

CVPR 2017

F. Monti*, D. Boscaini*, J. Masci, E. Rodolà, J. Svoboda, M.M. Bronstein

Selected for oral presentation. First unified framework able to generalize CNN architectures to non-Euclidean domains such as shapes and graphs. Also available as technical report: arXiv:1611.08402. (* indicates equal contribution)

Geometric deep learning

SIGGRAPH Asia Courses 2016

J. Masci, E. Rodolà, D. Boscaini, M.M. Bronstein, H. Li

Learning shape correspondence with anisotropic convolutional neural networks NeurIPS 2016 D. Boscaini, J. Masci, E. Rodolà, M.M. Bronstein

Presented also as a poster at the 3D Deep Learning Workshop (3DLL) 2016. Also available as technical report: arXiv:1605.06437

Anisotropic diffusion descriptors

CGF, 2016

D. Boscaini, J. Masci, E. Rodolà, M.M. Bronstein, D. Cremers *Oral presentation at EUROGRAPHICS 2016*

Geodesic convolutional neural networks on Riemannian manifolds

ICCV-W 2015

J. Masci*, D. Boscaini*, M.M. Bronstein, P. Vandergheynst

Oral presentation at 3DRR 2015. It represents the first intrinsic extension of the popular CNN paradigm to non-Euclidean domains. An early version of this work was published as the technical report: arXiv:1501.06297 on January 2015. (* indicates equal contribution)

Learning class-specific descriptors for deformable shapes using localized spectral convolutional networks

CGF, 2015

D. Boscaini, J. Masci, S. Melzi, M.M. Bronstein, U. Castellani, P. Vandergheynst *Oral presentation at SGP 2015*

Shape-from-operator: Recovering shapes from intrinsic operators

CGF, 2015

D. Boscaini, D. Eynard, D. Kourounis, M.M. Bronstein

Oral presentation at EUROGRAPHICS 2015. First approach able to synthesize the extrinsic geometry of a shape from intrinsic information. An early version of this work was published as the technical report: arXiv:1406.1925 on June 2014

Coulomb shapes: Using electrostatic forces for deformation-invariant shape representation

EUROGRAPHICS-W 2014

D. Boscaini, R. Girdziusas, M.M. Bronstein

Oral presentation at 3DOR 2014. Presented also as a poster at the International Computer Vision Summer School (ICVSS), 2014

A sparse coding approach for local-to-global 3D shape description

The Visual Computer, 2014

D. Boscaini, U. Castellani

Invited paper. Journal extension of the 3DOR 2013 conference paper

Local signatures quantization by sparse coding

EUROGRAPHICS-W 2013

D. Boscaini, U. Castellani

Oral presentation at 3DOR 2013. Presented also as a poster at SGP 2013

Patents

US patent application No. 17675011

Clustered dynamic graph convolutional neural network for biometric 3D hand recognition

Inventors: J. Svoboda, P. Astolfi, D. Boscaini, J. Masci

US patent No. 10210430

Filed Feb. 19, 2019

System and a method for learning features on geometric domains (CIP)

Inventors: M.M. Bronstein, D. Boscaini, F. Monti • Acquired by Twitter Inc.

System and a method for learning features on geometric domains

Inventors: M.M. Bronstein, D. Boscaini, J. Masci, P. Vandergheynst • Acquired by Twitter Inc.

Object 6D pose estimation in the foundation models era Master course in "Trends and Applications in Computer Vision"; University of Trento, Ita Massimiliano Mancini	Nov. 22, 2024 aly • Invited by
Object 6D pose estimation in the foundation models era Politecnico di Torino, Torino, Italy • Invited by Francesca Pistilli	Jun. 6, 2024
3D object understanding on the shoulders of 2D foundation models École Polytechnique, Paris, France • Invited by Maks Ovsjanikov	Mar. 28, 2024
3D deep learning to the test of real-world challenges Ph.D. event "Visions of Tomorrow"; University of Pisa, Italy	Dec. 11, 2020
3D Deep Learning Politecnico di Torino, Italy • Invited by Tatiana Tommasi	Dec. 11, 2019
Geometric deep learning for 3D shape analysis Politecnico di Torino, Italy • Invited by Barbara Caputo	May 13, 2019
Geometric deep learning for shape analysis EUSIPCO 2017, Kos, Greece	Sep. 2, 2017
Geometric deep learning for shape analysis TeV group (FBK), Trento, Italy • Invited by Samuel Rota Bulò and Stefano Messelodi	Apr. 4, 2017
Geometric deep learning for shape analysis IMATI group (CNR), Genoa, Italy • Invited by Michela Spagnuolo	Feb. 13, 2017
Deep learning on geometric data SSSTC RiC big data research workshop, Zurich, Switzerland	Feb. 16, 2016
Deep learning on geometric data Embedded Vision Systems (eVS), Verona, Italy • Invited by Roberto Marzotto	Feb. 8, 2016
Deep learning on geometric data Rainbow group, University of Cambridge, UK • Invited by Flora Tasse	Feb. 4, 2016
Deep learning on geometric data C.A.K.E. seminar, University of Cambridge, UK • Invited by Simone Parisotto	Feb. 3, 2016
Convolutional neural networks on non-Euclidean domains SciCADE 2015, Potsdam, Germany	Sep. 14, 2015
Shape-from-operators: recovering shapes from intrinsic differential operators TUM, Munich, Germany • Invited by Emanuele Rodolà	Nov. 26, 2014
Shape-from-operators: recovering shapes from intrinsic differential operators ICS retreat, Disentis, Switzerland	Aug. 19, 2014

Teaching experience

Academic courses

Trends and Applications in Computer Vision

University of Trento, Fall 2023

Short courses and tutorials

Functional Maps: A Flexible Representation for Learning and Computing Correspondences 3DV 2018

Geometric Deep Learning SIGGRAPH Asia 2016

Deep Learning for Shape Analysis EUROGRAPHICS 2016

Teaching Assistantships

Computer Vision and Pattern Recognition	Università della Svizzera italiana, Spring 2017
Computer Vision and Pattern Recognition	Università della Svizzera italiana, Spring 2016
Large Scale Optimization	Università della Svizzera italiana, Spring 2016

Computer Graphics	Università della Svizzera italiana, Fall 20
Geometric Image Processing and Computer Vision	Università della Svizzera italiana, Spring 20
Calculus	Università della Svizzera italiana, Fall 20
Mathematical Analysis 1, Mathematical Analysis 2	University of Verona, 2012–20
Mathematical Analysis 1, Mathematical Analysis 2	University of Verona, 2011–20
Mathematical Analysis 1	University of Verona, 2010–20
·	Offiversity of Verolia, 2010–20
tudent supervision	
Jaime Corsetti, PhD student at FBK and University of Tr Role: PhD coadvisor Project: Vision-language models for embodied AI	rento Nov. 2023–prese
Mattia Nardon, Master student at University of Trento Role: Internship and Master thesis advisor	Mar.–Dec. 20
Project: AI-powered visual monitoring of Lego assen	-
Alice Fasoli, Master student at University of Trento Role: Internship and Master thesis advisor	Mar.–Dec. 20
Project: Retrieval-driven 6D pose estimation of unsee	
Matteo Minardi, Master student at University of Trento	Mar.–Oct. 20
Role: Internship and Master thesis advisor	udv of the vicion on codes vale in VI Me
Projects: Eye-gaze estimation using smart glasses, Str Marco Garosi, Master student at University of Trento	Dec. 2023–Apr. 20
Project: Zero-shot semantic segmentation of 3D object	*
Outcome: Publication at WACV 2025	
Riccardo Tedoldi, Master student at University of Trento	
Project: Zero-shot semantic segmentation of 3D object Outcome: Publication at WACV 2025 Lima Corretti Master stylent at University of Tranta	2022–Oct. 20
Jaime Corsetti, Master student at University of Trento Projects: Open-vocabulary and Supervised object 6D	
Outcome: Publication at CVPR 2024 Safa Abbes, Master student at University of Trento	2022–20
Role: Masther thesis coadvisor	
Project: Self-supervised domain adaptation for RGB	~
Antonio Alliegro, PhD student at Politecnico di Torino Project: Self-Supervised domain adaptation for 3D pe	
Outcome: Publications at ECCV-W 2020 and ICPR 20 Pietro Astolfi, PhD student at FBK, UniTN, and IIT)21 2019–2 1
Role: PhD coadvisor	2019–20
Project: Geometric Deep Learning for brain structure	e analysis
Outcome: Publications at MICCAI 2020, IJCB 2020, a	nd MIA 2023
Levi O. Vasconcelos, PhD student at UniTN and IIT	2019–20
Project: Structured domain adaptation Outcome: Publications at 3DV 2019 and ICPR 2020	
Antonio Alliegro, Master student at Politecnico di Torin	o 2019–20
Role: Masther thesis coadvisor	
Piero Cavalcanti, Master student at Politecnico di Torino	2019–20
Role: Masther thesis coadvisor	
Myriam Bronstein, Master student at Università della Sv	vizzera italiana 20
Project: Machine learning methods on manifolds and	d graphs
Fatemeh Chegini, Master student at Università della Svi	zzera italiana 2014–20
Project: Spectral methods for cross-modal retrieval	
demic service	
Conferences revision activity	
International Conference on Robotics and Automation (ICRA) 2022, 20
International Conference on Pattern Recognition (ICPR)	
	eurIPS Workshops) 20

International Conference on Image Analysis and Processing (ICIAP)	2022	
International Conference on Machine Learning, Optimization, and Data Science (
Symposium On Applied Computing (SAC)	2022	
International Conference on 3D Vision (3DV)	2021, 2020, 2019, 2018	
International Conference on Machine Learning, Optimization, and Data Science (
International Conference on Machine Vision Applications (MVA)	2021, 2019	
EUROGRAPHICS	2019, 2017, 2015	
The British Machine Vision Conference (BMVC)	2018	
Computer Vision and Pattern Recognition (CVPR)	2017	
International Symposium on Vision, Modeling and Visualization (VMV)	2016	
Neural Information Processing Systems (NeurIPS)	2016	
Journal revision activity		
Robotics and Automation Letters (RAL)	2022	
Computer Graphics Forum (CGF)	2022	
IEEE Transactions on Image Processing (TIP)	2022, 2021	
IEEE Transactions on Transactions on Knowledge and Data Engineering (TKDE)	2022, 2021	
Neural Processing Letters (NEPL)	2022	
IEEE Transactions on Pattern Analysis and Machine Intelligence (PAMI)	2021, 2020	
IEEE Transactions on Visualization and Computer Graphics (TVCG)	2020, 2018, 2017	
Computers and Graphics	2019	
Computer Vision and Image Understanding (CVIU)	2019, 2015	
International Journal of Machine Learning and Cybernetics (JMCL)	2019	
Pattern Recognition Letters	2019	
The Visual Computer Journal (TVCJ)	2018, 2017, 2016	
Computer Aided Geometric Design (CAGD)	2018	
Computer-Aided Design (CAD)	2018	
Sensors	2018	
IPSJ Transactions on Computer Vision and Applications	2017	
Area chair		
British Machine Vision Conference (BMVC)	2025	
British Machine Vision Conference (BMVC)	2024	
Program committee		
Graph Models for Learning and Recognition (GMLR)	2022	
Organized within the 37th ACM Symposium on Applied Computing, Brno (Czech Republic)		