motor type

G4x2

0,22 Nm 4,67 Arms

0,8 Nm 18,0 Arms

These are calculated curves.

continuous stall torque continuous stall current

peak stall torque

peak stall current

The actual motor performance might vary up to 5%

input:

stack length	L	5,00	*0,1 inch
maximum Current	Imax [Arms]	18	Arms
connection of coils	D/S	S	
number of turns	#	11	
copper fill factor	Kcu	31,0%	
saturation at max. current	Satt	3,1%	
bus voltage	Udc	48	V
rated speed	Nn	6000	rpm
kt-variation factor	km	1,00	
ambiente temperature	Tu	25,00	${\mathbb C}$
thermal resistance	Rth	2,969	K/W

① Mo [Nm]

① lo [Arms]

Mmax [Nm]

Imax [Arms]

stall data continuous data with: Duty Cycle = 100 % dT = 130 K

nominal values

rated torque	② Mn [Nm]	0,18 Nm
rated current	② In [Arms]	3,77 Arms
rated power	② Pn [W]	110 W
rated speed	② Nn [rpm]	6000 rpm

other data

theoretical no load speed	3 Ntheo [rpm]		rpm
maximum speed	Mmax [rpm]	89240	rpm
torque constant	kt [Nm/Arms]	0,047	Nm/Arms
EMK-constant	ke [Vpk/rad/s]	0,039	Vpk/rad/s
terminal to terminal resistance	S Rtt [Ohm]	0,682	Ohm
terminal to terminal inductance	© Ltt [mH]	0,452	mH
inductance Ld	© Ld [mH]	0,224	mH
inductance Lq	© Lq [mH]	0,233	mH
thermal resistance	⑤ Rth [℃/W]	2,969	℃/W
electr. time constant	⑤ T [ms]	0,662	ms
inertia w/o brake	J [kgcm²]	0,0827	kgcm ²
mass w/o brake	m [kg]	0,98	kg

brake

mass w/o brake	m [kg]	0,98 kg
·		
inertia with small brake	J [kgcm²]	0,1027 kgcm ²
inertia with big brake	J [kgcm²]	0,0827 kgcm ²
mass with small brake	m [kg]	1,18 kg
mass with big brake	m [kg]	1,18 kg

- ① With motor mounted on a steel plate 300 x 300 x 12 mm and 130 % dT between windings and still air ambient
- ② nominal speed at maximum continuous output power
- 3 speed, where EMF is equal to bus voltage 48 V
- speed, where EMF is 50 volts
- ⑤ measured at 25℃

ideal motor characteristic;



