# **Decision-theoretic Machine Learning**

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# **Agenda**

- 1 Introduction to Machine Learning
- 2 Binary Classification
- 3 Bipartite Ranking
- 4 Multi-Label Classification

#### **Outline**

- Multi-label classification
- 2 Simple approaches to multi-label classification
- 3 Beyond simple approaches
- 4 Other task losses
- 5 Rank loss minimization
- 6 Summary

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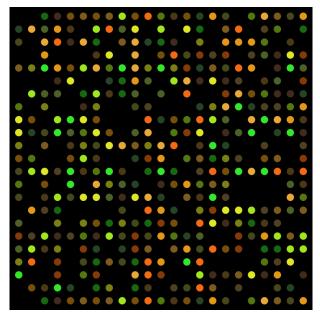
 A classification problem in which we consider more than one binary output variable.



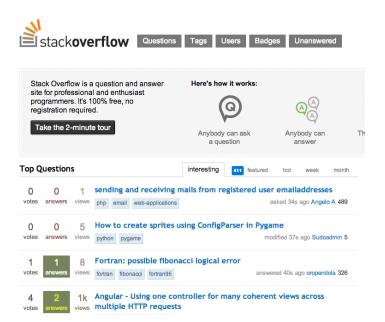
Image annotation: cloud? sky? tree?



Ecology: Prediction of the presence or absence of species



Gene function prediction



# Document tagging

• Multi-label classification: For a feature vector x predict accurately a vector of responses y using a function h(x):

$$x = (x_1, x_2, \dots, x_p) \xrightarrow{h(x)} y = (y_1, y_2, \dots, y_m) \in \mathcal{Y} = \{0, 1\}^m$$

- ullet Training data:  $\{(oldsymbol{x}_1,oldsymbol{y}_1),(oldsymbol{x}_2,oldsymbol{y}_2),\dots,(oldsymbol{x}_n,oldsymbol{y}_n)\}.$
- Predict a vector  $y = (y_1, y_2, \dots, y_m)$  for a given x.

	$x_1$	$x_2$	$y_1$	$y_2$	 $y_m$
$oldsymbol{x}_1$	5.0	4.5	1	1	0
$oldsymbol{x}_2$	2.0	2.5	0	1	0
:	:	:	:	:	:
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$\boldsymbol{x}$	4.0	2.5	?	?	?

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- Example x is coming from an unknown input distribution P(x).
- True outcome y is generated from P(y | x).
- Predicted outcome is given by  $\hat{y} = h(x)$ .
- The (task) loss of a single prediction is  $\ell(y, \hat{y})$ .

• The overall goal is to minimize the risk:

$$L_{\ell}(\boldsymbol{h}) = \mathbb{E}_{(\boldsymbol{x}, \boldsymbol{y})}(\ell(\boldsymbol{y}, \boldsymbol{h}(\boldsymbol{x})))$$

• The optimal prediction function, the so-called Bayes classifier, is:

$$\boldsymbol{h}_{\ell}^* = \operatorname*{arg\,min}_{\boldsymbol{h}} L_{\ell}(\boldsymbol{h})$$

• The **regret** of a classifier h with respect to  $\ell$  is defined as:

$$\operatorname{Reg}_{\ell}(\boldsymbol{h}) = L_{\ell}(\boldsymbol{h}) - L_{\ell}(\boldsymbol{h}_{\ell}^{*}) = L_{\ell}(\boldsymbol{h}) - L_{\ell}^{*}$$

- We use training examples  $\{x_i, y_i\}_1^n$  to find either:
  - ▶ a good approximation of h\*, or
  - ▶ a good estimation of P(y | x) (or a function of it).
- ullet In the second case, we need to apply an inference procedure to approximate  $h^st.$

# Main challenges

• Appropriate modeling of dependencies between labels

$$y_1, y_2, \ldots, y_m$$

 A multitude of multivariate loss functions defined over the output vector

$$\ell(\boldsymbol{y},\boldsymbol{h}(\boldsymbol{x}))$$

Marginal and conditional dependence:

$$P(\boldsymbol{y}) \neq \prod_{i=1}^{m} P(y_i)$$
  $P(\boldsymbol{y} \mid \boldsymbol{x}) \neq \prod_{i=1}^{m} P(y_i \mid \boldsymbol{x})$ 

marginal (in)dependence  $\not =$  conditional (in)dependence

ullet Marginal dependence eq conditional dependence

- Marginal dependence *→* conditional dependence
  - ► Consider two independent labels  $y_1$  and  $y_2$  generated by the same logistic model:

$$P(y_i = 1|\mathbf{x}) = (1 + \exp(-\phi f(\mathbf{x})))^{-1},$$

where  $\phi$  controls the Bayes error rate.

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$$P(\boldsymbol{y}|\boldsymbol{x}) = P(y_1|\boldsymbol{x})P(y_2|\boldsymbol{x}).$$

- ▶ Depending on the value of  $\phi$ , however, they will be stronger or weaker marginally dependent.
- ▶ For  $\phi \to \infty$  (Bayes error rate tends to 0), the marginal dependence increases towards the deterministic one  $(y_1 = y_2)$ .

 $\bullet \ \, \text{Marginal dependence} \not \leftarrow \text{conditional dependence} \\$ 

- - ► Consider two labels  $y_1$  and  $y_2$  and a single binary feature  $x_1$  with the joint distribution  $P(x_1, y_1, y_2)$  given as:

$x_1$	$y_1$	$y_2$	P	$x_1$	$y_1$	$y_2$	P
0	0	0	0.25	1	0	0	0
0	0	1	0	1	0	1	0.25
0	1	0	0	1	1	0	0.25
0	1	1	0.25	1	1	1	0

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0	1	0	0	1	1	0	0.25
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► The labels are conditionally dependent, since:

$$P(y_1 = 0|x_1 = 1)P(y_2 = 0|x_1 = 1) = 0.5 \times 0.5 = 0.25,$$

but the joint probability is

$$P(y_1 = 0, y_2 = 0 | x_1 = 1) = 0.$$

In fact  $y_1 = y_2$  for  $x_1 = 0$  and  $y_2 = 1 - y_1$  for  $x_1 = 1$ .

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► However, the labels are marginally independent, since

$$P(y_1) = P(y_2) = 0.5$$
, and  $P(y_1, y_2) = P(y_1)P(y_2)$ .

### Deterministic dependencies:

► Consider labels  $y_1$  and  $y_2$  with the following conditional distribution for a given x:

$$P(y_1 = 1, y_2 = 1 | \mathbf{x}) = 1,$$
  

$$P(y_1 = 0, y_2 = 1 | \mathbf{x}) = 0,$$
  

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- ▶ Are  $y_1$  and  $y_1$  conditionally dependent?
- ► No, since it holds:

$$P(y_1, y_2 \mid \boldsymbol{x}) = P(y_1 \mid \boldsymbol{x}) P(y_2 \mid \boldsymbol{x})$$

- Model similarities:
  - ▶ Similarities in the structural parts  $g_i(x)$  of the models:

$$f_i(\mathbf{x}) = g_i(\mathbf{x}) + \epsilon_i$$
, for  $i = 1, \dots, m$ 

- Structure imposed (domain knowledge) on targets
  - ► Chains,
  - ► Hierarchies,
  - ► General graphs,
  - ▶ ...

- Interdependence vs. hypothesis and feature space:
  - ▶ Regularization constraints the hypothesis space.
  - ► Modeling dependencies may increase the expressiveness of the model.
  - ▶ Using a more complex model on individual labels may also help.
  - ► Comparison of models is difficult in general, as they differ in many respects (e.g., complexity)!

#### Multivariate loss functions

Decomposable and non-decomposable losses over examples

$$L = \sum_{i=1}^{n} \ell(\boldsymbol{y}_i, \boldsymbol{h}(\boldsymbol{x}_i)) \quad L \neq \sum_{i=1}^{n} \ell(\boldsymbol{y}_i, \boldsymbol{h}(\boldsymbol{x}_i))$$

• Decomposable and non-decomposable losses over labels

$$\ell(\boldsymbol{y}, \boldsymbol{h}(\boldsymbol{x})) = \sum_{i=1}^{m} \ell(y_i, h_i(\boldsymbol{x})) \quad \ell(\boldsymbol{y}, \boldsymbol{h}(\boldsymbol{x})) \neq \sum_{i=1}^{m} \ell(y_i, h_i(\boldsymbol{x}))$$

- Different formulations of loss functions possible:
  - ► Set-based losses.
  - Ranking-based losses.

### Multi-label loss functions

- Subset 0/1 loss:  $\ell_{0/1}({m y},{m h}) = [\![{m y} 
  eq {m h}]\!]$
- Hamming loss:  $\ell_H(\boldsymbol{y}, \boldsymbol{h}) = \frac{1}{m} \sum_{i=1}^{m} \llbracket y_i \neq h_i \rrbracket$
- F-measure-based loss:  $\ell_F(\boldsymbol{y}, \boldsymbol{h}) = 1 \frac{2\sum_{i=1}^m y_i h_i}{\sum_{i=1}^m y_i + \sum_{i=1}^m h_i}$
- $\bullet \ \ \mathbf{Rank} \ \ \mathbf{loss} \colon \ \ell_{\mathrm{rnk}}(\boldsymbol{y},\boldsymbol{h}) = w(\boldsymbol{y}) \sum_{y_i > y_j} \left( \llbracket h_i < h_j \rrbracket + \frac{1}{2} \llbracket h_i = h_j \rrbracket \right)$

• ...

#### Relations between losses

- The set-based loss function  $\ell(\boldsymbol{y},\boldsymbol{h})$  should fulfill some basic conditions:
  - $\ell(y, h) = 0$  if and only if y = h.
  - $\ell(\boldsymbol{y}, \boldsymbol{h})$  is maximal when  $y_i \neq h_i$  for every  $i = 1, \dots, m$ .
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- In case of deterministic data (no-noise): the optimal prediction should have the same form for all loss functions and the risk for this prediction should be 0.
- In case of non-deterministic data (noise): the optimal prediction and its risk can be different for different losses.

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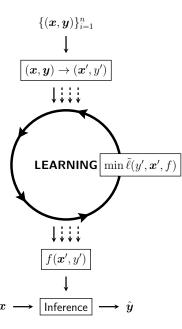
### Learning and inference with multi-label losses

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- Two approaches try to make this task easier
  - Reduction.
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### Learning and inference with multi-label losses

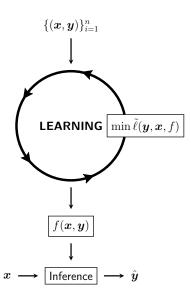
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- Therefore learning is a hard optimization problem.
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  - ► Reduction.
  - Surrogate loss minimization.
- Two phases in solving multi-label problems:
  - ▶ Learning: Estimate parameters of a scoring function f(x, y).
  - ▶ Inference: Use the scoring function f(x, y) to classify new instances by finding the best y for a given x.

#### Reduction



- Reduce the original problem into simple problems, for which efficient algorithmic solutions are available.
- Reduction to one or a sequence of problems.
- Plug-in rule classifiers.

#### Structured loss minimization



- Replace the task loss by a surrogate loss that is easier to cope with.
- Surrogate loss is typically a differentiable approximation of the task loss or a convex upper bound of it.

### Statistical consistency

- Analysis of algorithms in terms of their infinite sample performance.<sup>1</sup>
- We say that a proxy loss  $\tilde{\ell}$  is **consistent** (calibrated) with the task loss  $\ell$  when the following holds:

$$\operatorname{Reg}_{\tilde{\ell}}(\boldsymbol{h}) \to 0 \Rightarrow \operatorname{Reg}_{\ell}(\boldsymbol{h}) \to 0.$$

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.

- The definition concerns both surrogate loss minimization and reduction:
  - Surrogate loss minimization:  $\tilde{\ell} = \text{surrogate loss}$ .
  - lacktriangleright Reduction:  $\tilde{\ell}=$  loss used in the reduced problem.

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### Basic reductions: Binary relevance

• Binary relevance: Decomposes the problem to m binary classification problems:

$$(\boldsymbol{x}, \boldsymbol{y}) \longrightarrow (\boldsymbol{x}, y = y_i), \quad i = 1, \dots, m$$

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- Seems to be very simplistic.
- Ignores any dependencies.
- Is it good for any loss function?

#### Basic reductions: Label powerset

• Label powerset: Treats each label combination as a new meta-class in multi-class classification:

$$(\boldsymbol{x}, \boldsymbol{y}) \longrightarrow (\boldsymbol{x}, y = \text{metaclass}(\boldsymbol{y}))$$

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- Any multi-class classification algorithm can be used, but the number of classes is huge.
- Takes other labels into account, but ignores internal structure of classes (label vectors).

What about task losses minimized by BR and LP?

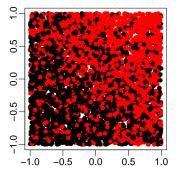
### Synthetic data

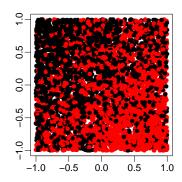
• Two independent models:

$$f_1(\mathbf{x}) = \frac{1}{2}x_1 + \frac{1}{2}x_2, \quad f_2(\mathbf{x}) = \frac{1}{2}x_1 - \frac{1}{2}x_2$$

• Logistic model to get labels:

$$P(y_i = 1) = \frac{1}{1 + \exp(-2f_i)}$$





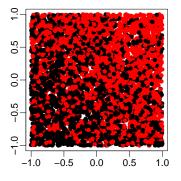
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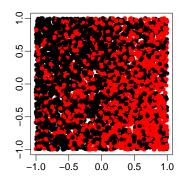
• Two dependent models:

$$f_1(\boldsymbol{x}) = \frac{1}{2}x_1 + \frac{1}{2}x_2$$
  $f_2(y_1, \boldsymbol{x}) = y_1 + \frac{1}{2}x_1 - \frac{1}{2}x_2 - \frac{2}{3}$ 

• Logistic model to get labels:

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### Results for two performance measures

- Hamming loss:  $\ell_H(\boldsymbol{y},\boldsymbol{h}) = \frac{1}{m} \sum_{i=1}^m \llbracket y_i \neq h_i 
  rbracket$  ,
- ullet Subset 0/1 loss:  $\ell_{0/1}(oldsymbol{y},oldsymbol{h}) = [\![oldsymbol{y} 
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Conditional independence					
CLASSIFIER	Hamming loss	Subset $0/1$ loss			
BR LR LP LR					
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	NDENCE
Hamming loss	Subset $0/1$ loss
0.4232	0.6723
0.4232	0.6725
	0.4232

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Conditional independence				
CLASSIFIER	Hamming loss	SUBSET 0/1 LOSS		
BR LR	0.4232	0.6723		
LP LR	0.4232	0.6725		

Conditional dependence					
CLASSIFIER	Hamming loss	Subset $0/1$ loss			
BR LR LP LR	0.3470 0.3610	0.5499 0.5146			

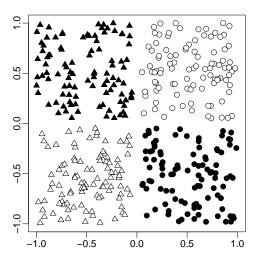
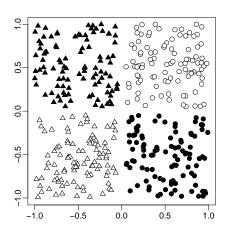


Figure : Problem with two targets: shapes ( $\triangle$  vs.  $\circ$ ) and colors ( $\square$  vs.  $\blacksquare$ ).

CLASSIFIER	Hamming Loss	SUBSET 0/1 LOSS
BR LR LP LR	$0.2399(\pm.0097)$ $0.0143(\pm.0020)$	$0.4751(\pm.0196)$ $0.0195(\pm.0011)$
BAYES OPTIMAL	0	0

CLASSIFIER	Hamming Loss	SUBSET 0/1 LOSS
BR LR LP LR BR MLRules	$0.2399(\pm.0097)$ $0.0143(\pm.0020)$ $0.0011(\pm.0002)$	$0.4751(\pm.0196) \\ 0.0195(\pm.0011) \\ \textbf{0.0020(\pm.0003)}$
BAYES OPTIMAL	0	0

- BR LR uses two linear classifiers: cannot handle the label color (□ vs. ■) – the XOR problem.
- LP LR uses four linear classifiers to solve 4-class problem (△, ▲, ∘, •): extends the hypothesis space.
- BR MLRules uses two non-linear classifiers (based on decision rules): XOR problem is not a problem.
- There is no noise in the data.
- Easy to perform unfair comparison.



#### Multi-label loss functions

• The conditional risk in multi-label classification of h at x:

$$L_{\ell}(\boldsymbol{h} \,|\, \boldsymbol{x}) = \mathbb{E}_{\boldsymbol{y}}\left[\ell(\boldsymbol{y}, \boldsymbol{h}(\boldsymbol{x}))\right] = \sum_{\boldsymbol{y} \in \mathcal{Y}} P(\boldsymbol{y} \,|\, \boldsymbol{x}) \ell(\boldsymbol{y}, \boldsymbol{h}(\boldsymbol{x}))$$

ullet The risk-minimizing classifier for a given x:

$$\boldsymbol{h}^*(\boldsymbol{x}) = \operatorname*{arg\,min}_{\boldsymbol{h}} L_{\ell}(\boldsymbol{h} \,|\, \boldsymbol{x})$$

• Let us start with Hamming loss and subset 0/1 loss ...<sup>2</sup>

K. Dembczyński, W. Waegeman, W. Cheng, and E. Hüllermeier. On loss minimization and label dependence in multi-label classification. *Machine Learning*, 88:5–45, 2012

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Marginal mode vs. joint mode.

$\boldsymbol{y}$	$P({m y})$		
$0\ 0\ 0\ 0$	0.30		
$0\ 1\ 1\ 1$	0.17	Marginal mode:	1111
$1\ 0\ 1\ 1$	0.18	Joint mode:	0 0 0 0
$1\ 1\ 0\ 1$	0.17		
$1\ 1\ 1\ 0$	0.18		

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• The following bounds hold for any P(y | x) and h:

$$\frac{1}{m}L_{0/1}(\boldsymbol{h}\,|\,\boldsymbol{x}) \leq L_H(\boldsymbol{h}\,|\,\boldsymbol{x}) \leq L_{0/1}(\boldsymbol{h}\,|\,\boldsymbol{x})$$

- The previous results may suggest that one of the loss functions can be used as a proxy (surrogate) for the other:
  - ► For some situations both risk minimizers coincide.
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  - ► For some situations both risk minimizers coincide.
  - ► One can provide mutual bounds for both loss functions.
- $\bullet$  However, the regret analysis of the worst case shows that minimization of the subset 0/1 loss may result in a large error for the Hamming loss and vice versa.

• The **regret** of a classifier with respect to  $\ell$  is defined as:

$$\operatorname{Reg}_{\ell}(\boldsymbol{h}) = L_{\ell}(\boldsymbol{h}) - L_{\ell}(\boldsymbol{h}_{\ell}^{*}),$$

where  $h_{\ell}^*$  is the Bayes classifier for a given loss  $\ell$ .

- Regret measures how worse is h by comparison with the optimal classifier for a given loss.
- To simplify the analysis we will consider the conditional regret:

$$\operatorname{Reg}_{\ell}(\boldsymbol{h} \mid \boldsymbol{x}) = L_{\ell}(\boldsymbol{h} \mid \boldsymbol{x}) - L_{\ell}(\boldsymbol{h}_{\ell}^* \mid \boldsymbol{x}).$$

- We will analyze the regret between:
  - lacktriangle the Bayes classifier for Hamming loss  $oldsymbol{h}_H^*$
  - lacktriangle the Bayes classifier for subset 0/1 loss  $m{h}_{0/1}^*$

with respect to both functions.

• It is a bit an unusual analysis.

• The following **upper bound** holds:

$$\operatorname{Reg}_{0/1}(\boldsymbol{h}_{H}^{*} \,|\, \boldsymbol{x}) = L_{0/1}(\boldsymbol{h}_{H}^{*} \,|\, \boldsymbol{x}) - L_{0/1}(\boldsymbol{h}_{0/1}^{*} \,|\, \boldsymbol{x}) < 0.5$$

- Moreover, this bound is tight.
- Example:

$oldsymbol{y}$	$P(\boldsymbol{y})$		
$0 \ 0 \ 0 \ 0$	0.02	Marginal mode:	0 0 0 0
$0\ 0\ 1\ 1$	0.49	Joint mode:	$0\ 0\ 1\ 1\ or\ 1\ 1\ 0\ 0$
$1\ 1\ 0\ 0$	0.49		

# Regret analysis

• The following **upper bound** holds m > 3:

$$\operatorname{Reg}_{H}(\boldsymbol{h}_{0/1}^{*} \mid \boldsymbol{x}) = L_{H}(\boldsymbol{h}_{0/1}^{*} \mid \boldsymbol{x}) - L_{H}(\boldsymbol{h}_{H}^{*} \mid \boldsymbol{x}) < \frac{m-2}{m+2}$$

- Moreover, this bound is tight.
- Example:

$oldsymbol{y}$				$P({m y})$
$\overline{0}$	0	0	0	0.170
0	1	1	1	0.166
1	0	1	1	0.166
1	1	0	1	0.166
1	1	1	0	0.166
1	1	1	1	0.166

D(.)

 $\begin{array}{lll} \text{Marginal mode:} & 1 \ 1 \ 1 \ 1 \\ \text{Joint mode:} & 0 \ 0 \ 0 \ 0 \end{array}$ 

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- $\bullet$  Minimization of the subset 0/1 loss may cause a high regret for the Hamming loss and vice versa.

• Binary relevance (BR)

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    - For subset 0/1 loss: label independence, high probability of the joint mode  $(>0.5), \ldots$
  - $\blacktriangleright$  Learning and inference is **linear** in m (however, faster algorithms exist).

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  - Similarly, by reducing to cost-sensitive multi-class classification LP can be used with almost any loss function.
  - ► LP may gain from the implicit expansion of the **feature** or **hypothesis space**.
  - ▶ Unfortunately, learning and inference is basically **exponential** in *m* (however, this complexity is constrained by the number of training examples).

- Both are commonly used.
- Hamming loss:
  - ► Not too many labels.
  - ► Well-balanced labels.
  - ► **Application**: Gene function prediction.
- Subset 0/1 loss:
  - ► Very restrictive.
  - ► Small number of labels.
  - ► Low noise problems.
  - ► **Application**: Prediction of diseases of a patient.



# **Outline**

- 1 Multi-label classification
- 2 Simple approaches to multi-label classification
- 3 Beyond simple approaches
- 4 Other task losses
- 5 Rank loss minimization
- 6 Summary

- Classical multi-class classification algorithms:
  - k-nearest neighbors,
  - Decision trees,
  - ► Logistic regression,
  - ► Multi-class SVMs,
  - ▶ ...
- Reduction algorithms:
  - ▶ 1 vs All,
  - ▶ 1 vs 1 and Weighted All-Pairs (WAP),
  - ▶ Directed acyclic graphs (DAG),
  - ► ECOC, PECOC, SECOC,
  - ► Filter Trees.
  - Conditional Probability Trees,
  - ▶ ...
- Can we adapt these algorithms to multi-label classification and different task losses in a more direct way?

• Naive reduction to 1 vs. All:

$$(\boldsymbol{x},\boldsymbol{y}) \longrightarrow (\boldsymbol{x},y = \mathrm{metaclass}(\boldsymbol{y}))$$

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We can exploit now the internal structure of label vectors!!!

• The model can be given by a scoring function f(x, y).

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- Different forms of f(x, y) are possible, for example:

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• Prediction is given by:

$$\boldsymbol{h}(\boldsymbol{x}) = \argmax_{\boldsymbol{y} \in \mathcal{Y}} f(\boldsymbol{x}, \boldsymbol{y})$$

- Generalization of logistic regression and SVMs for f(x, y):
  - ► Conditional random fields (CRFs),<sup>3</sup>
  - ► Structured support vector machines (SSVMs).<sup>4</sup>

John D. Lafferty, Andrew McCallum, and Fernando C. N. Pereira. Conditional random fields: Probabilistic models for segmenting and labeling sequence data. In *ICML*, pages 282–289, 2001

Y. Tsochantaridis, T. Joachims, T. Hofmann, and Y. Altun. Large margin methods for structured and interdependent output variables. *JMLR*, 6:1453–1484, 2005

• CRFs use logistic loss as a surrogate:

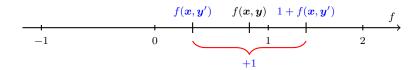
$$\tilde{\ell}_{\log}(\boldsymbol{y}, \boldsymbol{x}, f) = -\log P(\boldsymbol{y}|\boldsymbol{x}) = \log \left(\sum_{\boldsymbol{y} \in \mathcal{Y}} \exp(f(\boldsymbol{x}, \boldsymbol{y}))\right) - f(\boldsymbol{x}, \boldsymbol{y}).$$

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SSVMs minimize the structured hinge loss:

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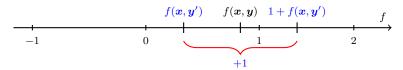


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- SSVMs and CRFs are quite similar to each other:
  - ► max vs. soft-max
  - ► margin vs. no-margin

- Follow the general LP strategy, but can exploit the internal structure of classes within scoring function f(x, y).
- Convex optimization problem, but its hardness depends on the structure of f(x,y).
- Similarly, the inference (also known as decoding problem) is hard in the general case.
- For sequence and tree structures, the problem can be solved in polynomial time.

## CRFs and SSVMs for different task losses

• In SSVMs, task loss  $\ell(y, y')$  can be used for margin rescaling:

$$\tilde{\ell}_h(\boldsymbol{y}, \boldsymbol{x}, f) = \max_{\boldsymbol{y}' \in \mathcal{Y}} \{\ell(\boldsymbol{y}, \boldsymbol{y}') + f(\boldsymbol{x}, \boldsymbol{y}')\} - f(\boldsymbol{x}, \boldsymbol{y}).$$

W. Gao and Z.-H. Zhou. On the consistency of multi-label learning. Artificial Intelligence, 199-200:22-44, 2013

A. Tewari and P.L. Bartlett. On the consistency of multiclass classification methods. JMLR, 8:1007-1025, 2007

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decompose to BR with SVMs.

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**Prove** why this is true.

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• In general SSVMs are inconsistent.<sup>5</sup>

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 CRFs are tailored for the subset 0/1 loss and cannot directly take other task losses into account.

<sup>&</sup>lt;sup>6</sup> P. Pletscher, C.S. Ong, and J.M. Buhmann. Entropy and margin maximization for structured output learning. In ECML/PKDD. Springer, 2010

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minimize Hamming loss ( $\rightarrow$  BR with logistic regression).

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Some works on incorporating margin into CRFs.<sup>6</sup>

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### SSVMs vs. BR

Table : SSVMs with pairwise term<sup>7</sup> vs. BR with LR<sup>8</sup>.

Dataset	SSVM Best	BR LR
SCENE YEAST SYNTH1 SYNTH2	$0.101\pm.003$ $0.202\pm.005$ $0.069\pm.001$ $0.058\pm.001$	0.102±.003 0.199±.005 0.067±.002 0.084±.001

• There is almost no difference between both algorithms.

<sup>&</sup>lt;sup>7</sup> Thomas Finley and Thorsten Joachims. Training structural SVMs when exact inference is intractable. In ICML. Omnipress, 2008

<sup>8</sup> K. Dembczyński, W. Waegeman, W. Cheng, and E. Hüllermeier. An analysis of chaining in multi-label classification. In ECAI. 2012

- Probabilistic classifier chains (PCCs)<sup>9</sup> are an efficient reduction method similar to conditional probability trees.<sup>10</sup>
- They estimate the joint conditional distribution  $P(y \mid x)$  as CRFs.
- Their idea is to repeatedly apply the product rule of probability:

$$P(y | x) = \prod_{i=1}^{m} P(y_i | x, y_1, ..., y_{i-1}).$$

J. Read, B. Pfahringer, G. Holmes, and E. Frank. Classifier chains for multi-label classification. Machine Learning Journal, 85:333–359, 2011

K. Dembczyński, W. Cheng, and E. Hüllermeier. Bayes optimal multilabel classification via probabilistic classifier chains. In *ICML*, pages 279–286. Omnipress, 2010

<sup>&</sup>lt;sup>10</sup> A. Beygelzimer, J. Langford, Y. Lifshits, G. B. Sorkin, and A. L. Strehl. Conditional probability tree estimation analysis and algorithms. In *UAI*, pages 51–58, 2009

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- They estimate the joint conditional distribution  $P(y \mid x)$  as CRFs.
- Their idea is to repeatedly apply the **product rule of probability**:

$$P(\boldsymbol{y} \mid \boldsymbol{x}) = \prod_{i=1}^{m} P(y_i \mid \boldsymbol{x}, y_1, \dots, y_{i-1}).$$

Example:

$$P(y_1, y_2 | \mathbf{x}) = \frac{P(y_1, \mathbf{x})}{P(\mathbf{x})} \frac{P(y_1, y_2, \mathbf{x})}{P(y_1, \mathbf{x})} = P(y_1 | \mathbf{x}) P(y_2 | y_1, \mathbf{x}).$$

<sup>10</sup> A. Beygelzimer, J. Langford, Y. Lifshits, G. B. Sorkin, and A. L. Strehl. Conditional probability tree estimation analysis and algorithms. In *UAI*, pages 51–58, 2009

J. Read, B. Pfahringer, G. Holmes, and E. Frank. Classifier chains for multi-label classification. Machine Learning Journal, 85:333–359, 2011

K. Dembczyński, W. Cheng, and E. Hüllermeier. Bayes optimal multilabel classification via probabilistic classifier chains. In *ICML*, pages 279–286. Omnipress, 2010

• PCCs follow a reduction to a sequence of subproblems:

$$(\boldsymbol{x}, \boldsymbol{y}) \longrightarrow (\boldsymbol{x}' = (\boldsymbol{x}, y_1, \dots, y_{i-1}), y = y_i), \quad i = 1, \dots, m$$

 Learning of PCCs relies on constructing probabilistic classifiers for estimating

$$P(y_i|\boldsymbol{x},y_1,\ldots,y_{i-1}),$$

independently for each i = 1, ..., m.

• Let us denote these estimates by

$$Q(y_i|\boldsymbol{x},y_1,\ldots,y_{i-1})$$
.

• The final model is:

$$Q(y | x) = \prod_{i=1}^{m} Q(y_i | x, y_1, ..., y_{i-1}).$$

- We can use scoring functions of the form  $f_i(x', y_i)$  and train logistic regression (or any probabilistic classifier) to get  $Q(y_i|x')$ .
- By using the linear models, the overall scoring function takes the form:

$$f(x, y) = \sum_{i=1}^{m} f_i(x, y_i) + \sum_{y_k, y_l} f_{k,l}(y_k, y_l)$$

 Theoretically the order of labels does not matter, but practically it may.

- $\bullet$  PCCs enable estimation of probability of any label vector y.
- To get such an estimate it is enough to compute:

$$Q(y | x) = \prod_{i=1}^{m} Q(y_i | x, y_1, \dots, y_{i-1})$$

• There is, however, a problem how to compute the optimal decision  $\boldsymbol{h}(\boldsymbol{x})$  (with respect to Q) for a given loss function.

- Inference in PCCs:
  - ► Greedy search,
  - ► Advanced search techniques: beam search, uniform-cost search,
  - ► Exhaustive search,
  - ► Sampling + inference.

# **Greedy search**

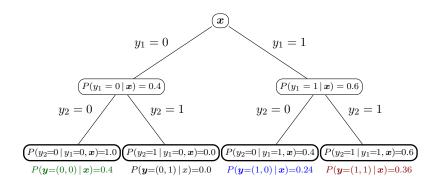
 Greedy search follows the chain by using predictions from previous steps as inputs in the consecutive steps:

```
 f_1: \boldsymbol{x} \mapsto \hat{y}_1 
 f_2: \boldsymbol{x}, \hat{y}_1 \mapsto \hat{y}_2 
 f_3: \boldsymbol{x}, \hat{y}_1, y_2 \mapsto \hat{y}_3 
 \vdots 
 f_m: \boldsymbol{x}, \hat{y}_1, \hat{y}_2, \dots, \hat{y}_{m-1} \mapsto \hat{y}_m
```

- Greedy search is fast (O(m)).
- Does not require probabilistic classifiers.
- ullet The resulting  $\hat{oldsymbol{y}}$  is neither the joint nor the marginal mode.
- $\bullet$  Optimal if labels are independent or the probability of the joint mode >0.5.

## **Greedy search**

• Greedy search fails for the joint mode and the marginal mode:

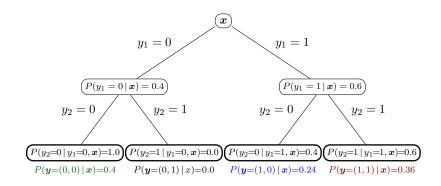


- Advanced search techniques: beam search,<sup>11</sup> a variant of uniform-cost search <sup>12</sup>
- Finding the joint mode relies on finding the most probable path in the tree.
- The use of a priority queue and a cut point gives a fast algorithm with provable guarantees.

<sup>&</sup>lt;sup>11</sup> A. Kumar, S. Vembu, A.K. Menon, and C. Elkan. Beam search algorithms for multilabel learning. In *Machine Learning*, 2013

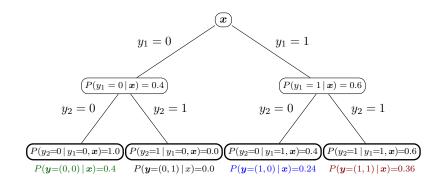
<sup>&</sup>lt;sup>12</sup> K. Dembczyński, W. Waegeman, W. Cheng, and E. Hüllermeier. An analysis of chaining in multi-label classification. In *ECAI*. 2012

Uniform-cost search



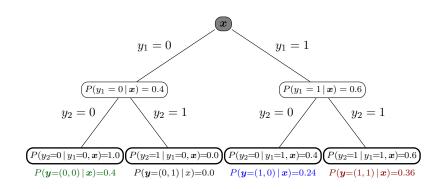
Priority list Q:

Uniform-cost search



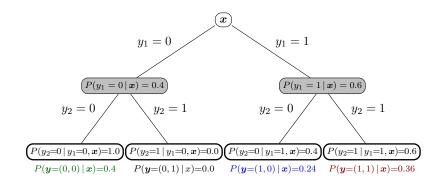
Priority list Q: root

Uniform-cost search



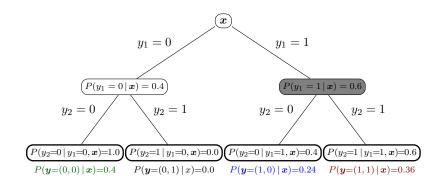
Priority list Q:

Uniform-cost search



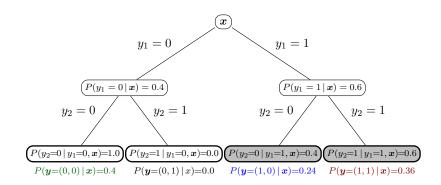
• Priority list Q: [(1),0.6], [(0),0.4]

Uniform-cost search



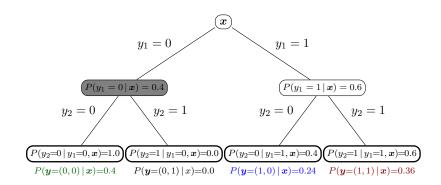
• Priority list *Q*: [(0),0.4]

Uniform-cost search



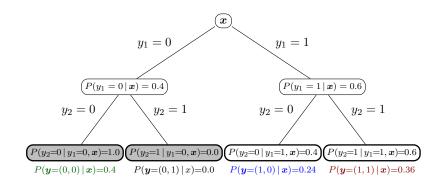
• Priority list Q: [(0),0.4], [(1,1),0.36], [(1,0),0.24]

Uniform-cost search



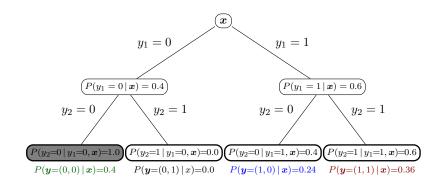
• Priority list *Q*: [(1,1),0.36], [(1,0),0.24]

Uniform-cost search



• Priority list Q: [(0,0),0.4], [(1,1),0.36], [(1,0),0.24], [(0,1),0.0]

Uniform-cost search

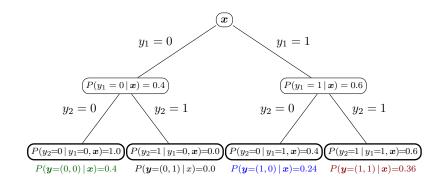


• Priority list Q: Solution is found

- $\epsilon$ -approximation inference: <sup>13</sup>
  - ▶ Insert items to priority queue Q with partial probabilities  $> \epsilon$ .
  - ► If solution has not been found, then perform greedy search from nodes without survived children.

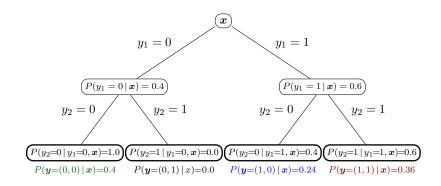
<sup>&</sup>lt;sup>13</sup> K. Dembczyński, W. Waegeman, W. Cheng, and E. Hüllermeier. An analysis of chaining in multi-label classification. In *ECAI*. 2012

 $\bullet$   $\epsilon = 0.5$ 



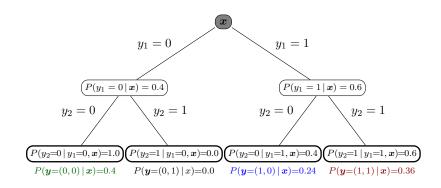
Priority list Q:

 $\bullet$   $\epsilon = 0.5$ 



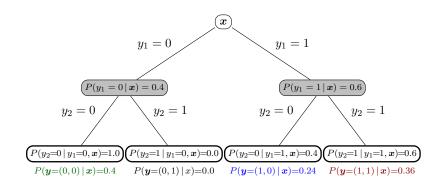
Priority list Q: root

 $\bullet$   $\epsilon = 0.5$ 



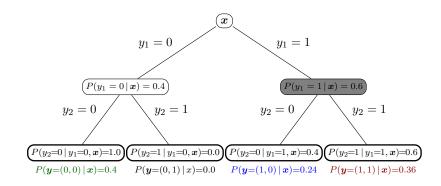
• Priority list Q:  $\epsilon = 0.5$ 

 $\bullet$   $\epsilon = 0.5$ 



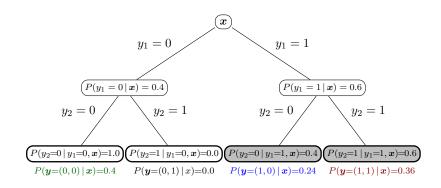
• Priority list Q: [(1),0.6],  $\epsilon = 0.5$ , [(0),0.4]

 $\bullet$   $\epsilon = 0.5$ 



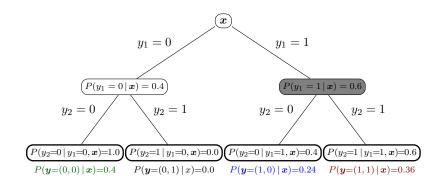
• Priority list Q:  $\epsilon = 0.5$ , [(0),0.4]

 $\bullet$   $\epsilon = 0.5$ 



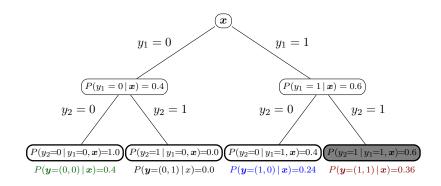
• Priority list Q:  $\epsilon = 0.5$ , [(0),0.4], [(1,1),0.36], [(1,0),0.24]

 $\bullet$   $\epsilon = 0.5$ 



Priority list Q: Start the greedy search from (1).

 $\bullet$   $\epsilon = 0.5$ 



• Priority list Q: Suboptimal solution (1,1) is found.

- For  $\epsilon = 0.5$ , it is equivalent to greedy search.
- For  $\epsilon = 0.0$ , it is equivalent to uniform-cost search.
- For a given  $\epsilon$ , the following guarantees can be given: <sup>14</sup>

**Theorem**: Let  $\epsilon=2^{-c}$ , where  $1\leq c\leq m$ . The label vector  $\hat{\boldsymbol{y}}$  will be returned in time  $\mathcal{O}(m2^c)$  with a guarantee that:

$$Q(\boldsymbol{y}^* \mid \boldsymbol{x}) - Q(\hat{\boldsymbol{y}} \mid \boldsymbol{x}) \le \epsilon - 2^{-m}$$

<sup>&</sup>lt;sup>14</sup> K. Dembczyński, W. Waegeman, W. Cheng, and E. Hüllermeier. An analysis of chaining in multi-label classification. In *ECAI*, 2012

- The  $\epsilon$ -approximate inference will always find the joint mode if its probability mass  $\geq \epsilon$ .
- In other words, the algorithm finds the solution in a linear time of  $1/p_{\rm max}$ , where  $p_{\rm max}$  is the probability mass of the joint mode.
- ullet For problems with low noise (high values of  $p_{
  m max}$ ), this method should work very fast.
- Greedy search has very bad guarantees:

$$Q(y^* | x) - Q(\hat{y} | x) \le 0.5 - 2^{-m}$$
.

## Regret bound for PCC

ullet The typical approach for estimating probabilities of  $oldsymbol{y}$  is minimization of the logistic loss:

$$\ell_{\log}(\boldsymbol{y}, \boldsymbol{x}, f) = -\log Q(\boldsymbol{y} | \boldsymbol{x}),$$

where f is a model that delivers estimate  $Q(\boldsymbol{y} \mid \boldsymbol{x})$  of  $P(\boldsymbol{y} \mid \boldsymbol{x})$ .

• By using the chain rule of probability, we get:

$$\ell_{\log}(\boldsymbol{y}, \boldsymbol{x}, f) = -\log \prod_{i=1}^{m} Q(y_i | \boldsymbol{x}, y_1, \dots, y_{i-1})$$

$$= -\sum_{i=1}^{m} \log Q(y_i | \boldsymbol{x}, y_1, \dots, y_{i-1}) = -\sum_{i=1}^{m} \log Q_i(\boldsymbol{y}),$$

where we use the notation  $Q_i(\mathbf{y}) = Q(y_i \mid \mathbf{x}, y_1, \dots, y_{i-1})$ .

 This is a sum of univariate log losses on a path from the root to the leaf corresponding to y.

## Regret bound for PCC

• **Theorem**: For all distributions and all PCCs trained with logistic regression f and used with the  $\epsilon$ -approximate inference algorithm,

$$\operatorname{Reg}_{0/1}(\operatorname{PCC}_{\epsilon}(f)) \le \sqrt{2m\overline{\operatorname{Reg}_{\log}}(f)} + \epsilon$$

where  $\overline{\mathrm{Reg}_{\mathrm{log}}}(f)$  is the average logistic regret over the paths from the root to the leafs.

## **PCC** for other losses

#### Exhaustive search:

- ▶ Compute the entire distribution  $Q(\boldsymbol{y} \,|\, \boldsymbol{x})$  by traversing the probability tree.
- ► Use an appropriate inference for a given loss \( \ell \) on the estimated joint distribution:

$$\hat{y} = \operatorname*{arg\,max}_{\boldsymbol{h} \in \mathcal{Y}} \sum_{\boldsymbol{y} \in \mathcal{Y}} Q(\boldsymbol{y} \,|\, \boldsymbol{x}) \ell(\boldsymbol{y}, \boldsymbol{h}(\boldsymbol{x}))$$

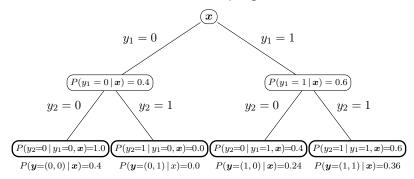
► This approach is extremely costly.

# Ancestral sampling:

- ► Sampling can be easily performed by using the probability tree.
- ► Make inference based on the empirical distribution.
- Hamming loss: estimate marginal probabilities.

### Probabilistic classifier chains

Exhaustive search and ancestral sampling:



• Sample: (1,1), (1,0), (0,0), (0,0), (1,1), (0,0), (1,0), (1,1), (0,0) . . .

## Probabilistic classifier chains

Table : PCC vs. SSVMs on Hamming loss and PCC vs. BR on subset 0/1 loss.

Dataset	PCC	SSVM Best	PCC	$_{ m BR}$
	Hamming loss		SUBSET 0/1 LOSS	
Scene	$0.104 \pm .004$	$0.101 \pm .003$	$0.385 {\pm}.014$	$0.509 \pm .014$
Yeast	$0.203 \pm .005$	$0.202 {\pm}.005$	$0.761 \pm .014$	$0.842 {\pm}.012$
Synth1	$0.067 \pm .001$	$0.069 \pm .001$	$0.239 \pm .006$	$0.240 \pm .006$
Synth2	$0.000 \pm .000$	$0.058 \pm .001$	$0.000 \pm .000$	$0.832 \pm .004$
Reuters	$0.060 \pm .002$	$0.045 \pm .001$	$0.598 \pm .009$	$0.689 \pm .008$
Mediamill	$0.172 \pm .001$	$0.182 \pm .001$	$0.885 \pm .003$	$0.902 {\pm} .003$

### Recurrent classifiers

- PCCs are similar to Maximum Entropy Markov Models (MEMMs)<sup>15</sup> introduced for sequence learning:
  - ▶ One logistic classifier that takes dependences up to the *k*-th degree.
  - ► Inference by dynamic programming.
- Searn<sup>16</sup> is another approach that is based on recurrent classifiers:
  - Linear inference.
  - ► Learning is performed in the iterative way to solve the egg and the chicken problem: output of the classifier is also used as input to the classifier.

<sup>&</sup>lt;sup>15</sup> A. K. McCallum, D. Freitag, and F. (2000) Pereira. Maximum entropy markov models for information extraction and segmentation. In *ICML*, 2000

<sup>&</sup>lt;sup>16</sup> H. Daumé III, J. Langford, and D. Marcu. Search-based structured prediction. *Machine Learning*, 75:297–325, 2009

## **Output search space**

- More advanced search techniques.
- Popular topic in structured output prediction.
- Search techniques for different task losses. 17

<sup>&</sup>lt;sup>17</sup> J.R. Doppa, A. Fern, and P. Tadepalli. Structured prediction via output space search. *JMLR*, 15:1317–1350, 2014

## PCC for multi-class classification

- PCC can be used for multi-class classification:
  - ► Map each class label to a label vector: binary coding, hierarchical clustering, . . .
  - ▶ The same idea as in conditional probability trees (CPT). 18
  - ▶ Label tree classifiers for efficient multi-class classification. 19

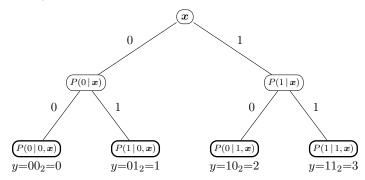
<sup>&</sup>lt;sup>18</sup> A. Beygelzimer, J. Langford, Y. Lifshits, G. B. Sorkin, and A. L. Strehl. Conditional probability tree estimation analysis and algorithms. In *UAI*, pages 51–58, 2009

<sup>&</sup>lt;sup>19</sup> S. Bengio, J. Weston, and D. Grangier. Label embedding trees for large multi-class tasks. In NIPS, pages 163–171. Curran Associates, Inc., 2010

J. Deng, S. Satheesh, A. C. Berg, and Fei Fei F. Li. Fast and balanced: Efficient label tree learning for large scale object recognition. In *NIPS*, pages 567–575. 2011

## PCC for multi-class classification

- We assign each class an integer from 0 to k-1 and code it by its binary representation on m bits.
- Example: k = 4,  $\mathcal{Y} = \{0, 1, 2, 3\}$ .
- k leaves, one for each class.



## Consistent and efficient label tree classifiers

- PCC: fast learning but inference can be costly.
- Greedy search is the most efficient, but is not consistent.
- ullet How to ensure a linear inference in m for any loss?

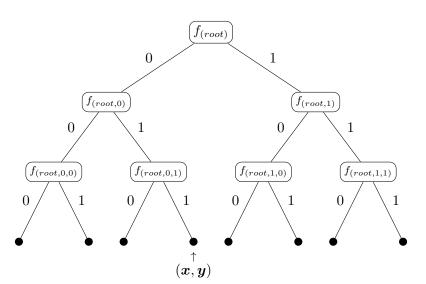
• Filter trees (FT)<sup>20</sup> have been originally introduced for cost-sensitive multi-class classification, but can be easily adapted to multi-label classification.

<sup>&</sup>lt;sup>20</sup> A. Beygelzimer, J. Langford, and P. D. Ravikumar. Error-correcting tournaments. In ALT, pages 247–262, 2009

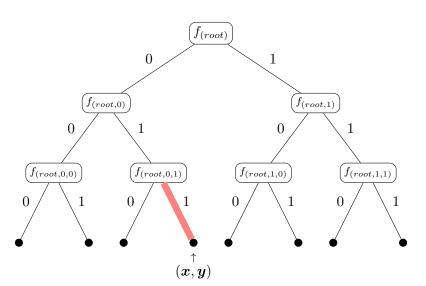
- Filter trees (FT)<sup>20</sup> have been originally introduced for cost-sensitive multi-class classification, but can be easily adapted to multi-label classification.
- They use a **bottom-up** learning algorithm to train the label tree.
- Based on a single elimination tournament on the set of classes/label combinations.

<sup>&</sup>lt;sup>20</sup> A. Beygelzimer, J. Langford, and P. D. Ravikumar. Error-correcting tournaments. In ALT, pages 247–262, 2009

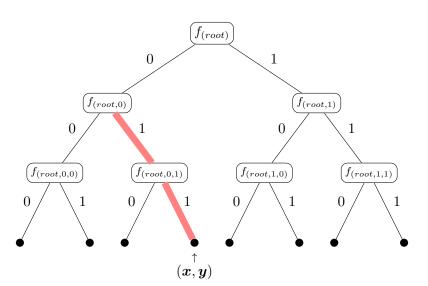
# Filter trees : Example



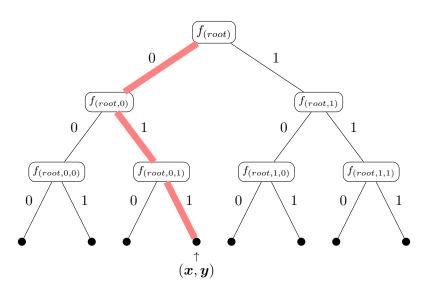
Filter trees: Example



Filter trees: Example



# Filter trees: Example



- FT are trained to predict  $y_{i+1}$  based on previous labels.
- FT implicitly transforms the underlying distribution P over multi-class/multi-label examples into a **specific distribution**  $P^{\rm FT}$  over weighted binary examples.
- The inference procedure of FT is straight-forward and uses the **greedy search**.
- FT are consistent for any cost function.

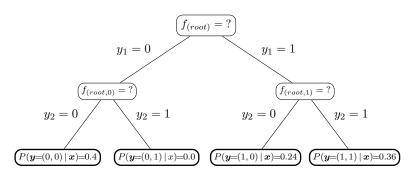
- Filter tree training:
  - 1: Input: training set  $\{(\boldsymbol{x}_i, \boldsymbol{y}_i)\}_{i=1}^n$ , importance-weighted binary learner Learn
  - 2: **for** each non-leaf node  $\boldsymbol{v} = (root, y_1, \dots, y_{i-1})$  in the order from leaves to root  $\operatorname{do}$
  - $S_{\boldsymbol{v}} = \emptyset$
  - 4: **for** each training example (x, y) **do**
  - 5: Let  $oldsymbol{y}_l$  and  $oldsymbol{y}_r$  be the two label vectors input to  $oldsymbol{v}$
  - 6:  $y_i \leftarrow \arg\min_{l,r} \{\ell(\boldsymbol{y}, \boldsymbol{y}_l), \ell(\boldsymbol{y}, \boldsymbol{y}_r)\}$
  - 7:  $w = |\ell(\boldsymbol{y}, \boldsymbol{y}_l) \ell(\boldsymbol{y}, \boldsymbol{y}_r)|$
  - 8:  $S_{\boldsymbol{v}} \leftarrow S_{\boldsymbol{v}} \cup (\boldsymbol{x}, y_i, w)$
  - 9: **end for**
  - 10:  $f_{\boldsymbol{v}} = Learn(S_{\boldsymbol{v}})$
  - 11: end for
  - 12: **return**  $f = \{f_{v}\}$

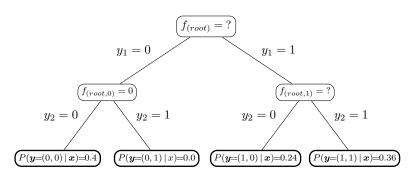
- Different training schemes possible:
  - Train a classifier in each node,
  - ► Train a classifier on each level,
  - Train one global binary classifier (in several loops).
- The tree in multi-label classification is given naturally, but the order of labels may influence the performance.
- In general case, training can be costly  $(O(2^m))$ , but efficient variants for multi-label classification exist.<sup>21</sup>
- Prediction is always linear in the number of labels (O(m)).

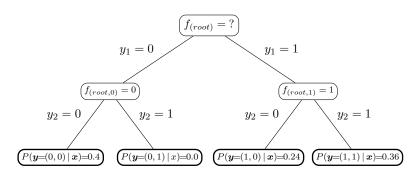
<sup>&</sup>lt;sup>21</sup> Chun-Liang Li and Hsuan-Tien Lin. Condensed filter tree for cost-sensitive multi-label classification. In *ICML*, pages 423–431, 2014

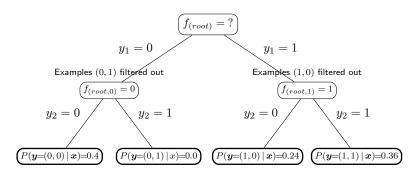
- $\bullet$  Filter trees for the subset 0/1 loss **filter out** all examples that are misclassified by the lower-level classifiers.
- Therefore, training in this case is also linear in the number of labels (O(m)).
- $f_{(root,y_1,...y_i)}(x)$  predicts  $y_{i+1}$  given that all classifiers below predict the subsequent labels correctly:

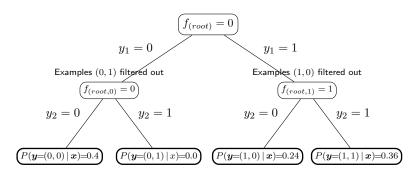
$$f_{(root,y_1,...y_i)}: \mathbf{x} \mapsto (y_{i+1} \mid y_{j+1} = f_{(root,y_1,...y_j)}: j = i+1,...,m-1)$$











## Regret bound for filter trees

- Let  $f_{m v}$  be a classifier for the binary classification problem induced at node  ${m v}$ .
- The average binary regret is defined as:

$$\overline{\operatorname{Reg}}_{0/1}(f, P^{\operatorname{FT}}) = \frac{1}{\sum_{\boldsymbol{v}} W_{\boldsymbol{v}}} \sum_{\boldsymbol{v}} \operatorname{Reg}_{0/1}(f_{\boldsymbol{v}}, P_{\boldsymbol{v}}^{\operatorname{FT}}) W_{\boldsymbol{v}},$$

where

$$W_{\boldsymbol{v}} = \mathbb{E}_{(\boldsymbol{x},\boldsymbol{y})} w_{\boldsymbol{v}}(\boldsymbol{x},\boldsymbol{y}).$$

• Theorem:<sup>22</sup> For all distributions and all FT classifiers trained with a binary classifier f, and any cost-matrix-based task loss  $\ell$ ,

$$\operatorname{Reg}_{\ell}(\operatorname{FT}(f)) \leq \overline{\operatorname{Reg}}_{0/1}(f, P^{\operatorname{FT}}) \sum_{v} W_{v}.$$

<sup>&</sup>lt;sup>22</sup> A. Beygelzimer, J. Langford, and P. D. Ravikumar. Error-correcting tournaments. In ALT, pages 247–262, 2009

# Regret bound for filter trees

• For subset 0/1 loss, we have

$$\sum_{\boldsymbol{v}} w_{\boldsymbol{v}}(\boldsymbol{x}, \boldsymbol{y}) \leq m,$$

since each training example (x, y) will appear in training at most once per level with importance weight 1.

• The regret bound has then the form:

$$\operatorname{Reg}_{\ell}(\operatorname{FT}(f)) \leq m \overline{\operatorname{Reg}}_{0/1}(f, P^{\operatorname{FT}}).$$

## **Outline**

- 1 Multi-label classification
- 2 Simple approaches to multi-label classification
- 3 Beyond simple approaches
- 4 Other task losses
- 5 Rank loss minimization
- 6 Summary

#### Maximization of the F-measure

- Applications: Information retrieval, document tagging, and NLP.
  - JRS 2012 Data Mining Competition: Indexing documents from MEDLINE or PubMed Central databases with concepts from the Medical Subject Headings ontology.



## Maximization of the F-measure

• The  $F_{\beta}$ -measure-based loss function ( $F_{\beta}$ -loss):

$$\ell_{F_{\beta}}(\boldsymbol{y}, \boldsymbol{h}(\boldsymbol{x})) = 1 - F_{\beta}(\boldsymbol{y}, \boldsymbol{h}(\boldsymbol{x}))$$

$$= 1 - \frac{(1 + \beta^2) \sum_{i=1}^{m} y_i h_i(\boldsymbol{x})}{\beta^2 \sum_{i=1}^{m} y_i + \sum_{i=1}^{m} h_i(\boldsymbol{x})} \in [0, 1].$$

- Provides a better balance between relevant and irrelevant labels.
- However, it **is not easy** to optimize.

# SSVMs for $F_{\beta}$ -based loss

- SSVMs can be used to minimize  $F_{\beta}$ -based loss.
- Rescale the margin by  $\ell_F(\boldsymbol{y}, \boldsymbol{y}')$ .
- Two algorithms:<sup>23</sup>

#### **RML**

No label interactions:

$$f(\boldsymbol{y}, \boldsymbol{x}) = \sum_{i=1}^{m} f_i(y_i, \boldsymbol{x})$$

Quadratic learning and linear prediction

Both are inconsistent.

### **SML**

Submodular interactions:

More complex (graph-cut and approximate algorithms)

J. Petterson and T. S. Caetano. Reverse multi-label learning. In NIPS, pages 1912–1920, 2010
J. Petterson and T. S. Caetano. Submodular multi-label learning. In NIPS, pages 1512–1520, 2011

Plug estimates of required parameters into the Bayes classifier:<sup>24</sup>

$$h^* = \underset{\boldsymbol{h} \in \mathcal{Y}}{\arg \min} \mathbb{E} \left[ \ell_{F_{\beta}}(\boldsymbol{Y}, \boldsymbol{h}) \right]$$
$$= \underset{\boldsymbol{h} \in \mathcal{Y}}{\arg \max} \sum_{\boldsymbol{y} \in \mathcal{Y}} P(\boldsymbol{y}) \frac{(\beta + 1) \sum_{i=1}^{m} y_{i} h_{i}}{\beta^{2} \sum_{i=1}^{m} y_{i} + \sum_{i=1}^{m} h_{i}}$$

- No closed form solution for this optimization problem.
- The problem cannot be solved naively by brute-force search:
  - ▶ This would require to check all possible combinations of labels  $(2^m)$
  - lacktriangle To sum over  $2^m$  number of elements for computing the expected value.
  - ▶ The number of parameters to be estimated (P(y)) is  $2^m$ .

<sup>&</sup>lt;sup>24</sup> W. Waegeman, K. Dembczynski, W. Cheng A. Jachnik, and E. Hüllermeier. On the Bayes-optimality of F-measure maximizers. *Minor revision*, 2014

Approximation needed?

<sup>&</sup>lt;sup>25</sup> N. Ye, K. Chai, W. Lee, and H. Chieu. Optimizing F-measures: a tale of two approaches. In ICML, 2012

<sup>&</sup>lt;sup>26</sup> K. Dembczyński, W. Waegeman, W. Cheng, and E. Hüllermeier. An exact algorithm for F-measure maximization. In NIPS, volume 25, 2011

<sup>&</sup>lt;sup>27</sup> K. Dembczynski, A. Jachnik, W. Kotlowski, W. Waegeman, and E. Hüllermeier. Optimizing the F-measure in multi-label classification: Plug-in rule approach versus structured loss minimization. In *ICML*, 2013

• Approximation needed? Not really. The exact solution is tractable!

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<sup>&</sup>lt;sup>27</sup> K. Dembczynski, A. Jachnik, W. Kotlowski, W. Waegeman, and E. Hüllermeier. Optimizing the F-measure in multi-label classification: Plug-in rule approach versus structured loss minimization. In *ICML*, 2013

Approximation needed? Not really. The exact solution is tractable!

#### LFP:

Assumes label independence.

Linear number of parameters:

 $P(y_i=1).$ 

Inference based on dynamic programming.<sup>25</sup>

Reduction to LR for each label.

## EFP:

No assumptions.

Quadratic number of parameters:

$$P(y_i = 1, s = \sum_i y_i).$$

Inference based on matrix multiplication and top k selection.<sup>26</sup> Reduction to multinomial LR for each label.

• EFP is consistent.<sup>27</sup>

<sup>&</sup>lt;sup>25</sup> N. Ye, K. Chai, W. Lee, and H. Chieu. Optimizing F-measures: a tale of two approaches. In ICML, 2012

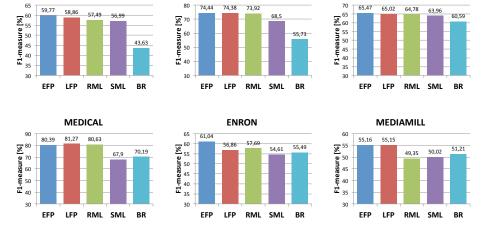
<sup>&</sup>lt;sup>26</sup> K. Dembczyński, W. Waegeman, W. Cheng, and E. Hüllermeier. An exact algorithm for F-measure maximization. In *NIPS*, volume 25, 2011

<sup>&</sup>lt;sup>27</sup> K. Dembczynski, A. Jachnik, W. Kotlowski, W. Waegeman, and E. Hüllermeier. Optimizing the F-measure in multi-label classification: Plug-in rule approach versus structured loss minimization. In *ICML*, 2013

### Maximization of the F-measure

**SCENE** 

IMAGE



YEAST

#### **Outline**

- 1 Multi-label classification
- 2 Simple approaches to multi-label classification
- 3 Beyond simple approaches
- 4 Other task losses
- 5 Rank loss minimization
- 6 Summary

#### Serena romps to fifth Wimbledon title against brave Radwanska

By Paul Gittings, CNN July 7, 2012 -- Updated 2220 GMT (0620 HKT)



STORY HIGHLIGHTS · Serena Williams wins fifth

Wimbledon crown · American beats Agnieszka

Radwanska battles respiratory

(CNN) -- Serena Williams fended off a stirring fightback from Agnieszka Radwanska to win her fifth Wimbledon singles title with a 6-1 5-7 6-2 victory Saturday

Radwanska of Poland 6-1 5-7 6- It was the 30-year-old American's 14th grand slam crown and her first since winning at the All England Club in 2010, but Poland's Radwanska made her fight every inch of the way.

#### Multi-label classification

politics	0
economy	0
business	0
sport	1
tennis	1
soccer	0
show-business	0
celebrities	1
:	
England	1
USA	1
Poland	1

Lithuania

#### Serena romps to fifth Wimbledon title against brave Radwanska

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#### STORY HIGHLIGHTS

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## Multi-label ranking

tennis sport England Poland USA politics

## • Ranking loss:

$$\ell_{\text{rnk}}(\boldsymbol{y}, \boldsymbol{f}) = w(\boldsymbol{y}) \sum_{(i,j): y_i > y_j} \left( \llbracket f_i(\boldsymbol{x}) < f_j(\boldsymbol{x}) \rrbracket + \frac{1}{2} \llbracket f_i(\boldsymbol{x}) = f_j(\boldsymbol{x}) \rrbracket \right),$$

where  $w(y) < w_{max}$  is a weight function.

	$X_1$	$X_2$	$Y_1$		$Y_2$			$Y_m$
$\overline{x}$	4.0	2.5	1		0			0
			$h_2$	>	$h_1$	>	 >	$h_m$

#### Ranking loss:

$$\ell_{\text{rnk}}(\boldsymbol{y}, \boldsymbol{f}) = w(\boldsymbol{y}) \sum_{(i,j): y_i > y_j} \left( \llbracket f_i(\boldsymbol{x}) < f_j(\boldsymbol{x}) \rrbracket + \frac{1}{2} \llbracket f_i(\boldsymbol{x}) = f_j(\boldsymbol{x}) \rrbracket \right),$$

where  $w(y) < w_{max}$  is a weight function.

The weight function  $w(\boldsymbol{y})$  is usually used to normalize the range of rank loss to [0,1]:

$$w(\boldsymbol{y}) = \frac{1}{n_+ n_-},$$

i.e., it is equal to the inverse of the total number of pairwise comparisons between labels.

#### Pairwise surrogate losses

 The most intuitive approach is to use pairwise convex surrogate losses of the form

$$\tilde{\ell}_{\phi}(\boldsymbol{y}, \boldsymbol{f}) = \sum_{(i,j): y_i > y_j} w(\boldsymbol{y}) \phi(f_i - f_j),$$

where  $\phi$  is

- ▶ an exponential function (BoosTexter)<sup>28</sup>:  $\phi(f) = e^{-f}$ , 
  ▶ logistic function (LLLR)<sup>29</sup>:  $\phi(f) = \log(1 + e^{-f})$ ,
- or hinge function (RankSVM)<sup>30</sup>:  $\phi(f) = \max(0, 1 f)$ .

<sup>&</sup>lt;sup>28</sup> R. E. Schapire and Y. Singer. BoosTexter: A Boosting-based System for Text Categorization. Machine Learning, 39(2/3):135-168, 2000

O. Dekel, Ch. Manning, and Y. Singer. Log-linear models for label ranking. In NIPS. MIT Press, 2004

<sup>&</sup>lt;sup>30</sup> A. Elisseeff and J. Weston. A kernel method for multi-labelled classification. In NIPS, pages 681–687, 2001

- This approach is, however, inconsistent for the most commonly used convex surrogates.<sup>31</sup>
- The **consistent** classifier can be, however, obtained by using univariate loss functions<sup>32</sup> . . .

<sup>&</sup>lt;sup>31</sup> J. Duchi, L. Mackey, and M. Jordan. On the consistency of ranking algorithms. In *ICML*, pages 327–334, 2010

W. Gao and Z.-H. Zhou. On the consistency of multi-label learning. *Artificial Intelligence*, 199-200:22–44, 2013

<sup>&</sup>lt;sup>32</sup> K. Dembczynski, W. Kotlowski, and E. Hüllermeier. Consistent multilabel ranking through univariate losses. In *ICML*, 2012

## Reduction to weighted binary relevance

• The Bayes ranker can be obtained by sorting labels according to:

$$\Delta_i^1 = \sum_{\boldsymbol{y} \colon y_i = 1} w(\boldsymbol{y}) P(\boldsymbol{y} \,|\, \boldsymbol{x}) \,.$$

- For  $w(y) \equiv 1$ ,  $\Delta_i^u$  reduces to marginal probabilities  $P(y_i = u \mid x)$ .
- The solution can be obtained with BR or its weighted variant in a general case.

## Reduction to weighted binary relevance

• Consider the sum of univariate (weighted) losses:

$$\tilde{\ell}_{\exp}(\boldsymbol{y}, \boldsymbol{f}) = w(\boldsymbol{y}) \sum_{i=1}^{m} e^{-y'f_i},$$

$$\tilde{\ell}_{\log}(\boldsymbol{y}, \boldsymbol{f}) = w(\boldsymbol{y}) \sum_{i=1}^{m} \log \left(1 + e^{-y'f_i}\right).$$

where  $y' = 2y_i - 1$ .

• The risk minimizer of these losses is:

$$f_i^*(\boldsymbol{x}) = \frac{1}{c} \log \frac{\Delta_i^1}{\Delta_i^0} = \frac{1}{c} \log \frac{\Delta_i^1}{W - \Delta_i^1},$$

which is a strictly increasing transformation of  $\Delta^1_i$ , where

$$W = \mathbb{E}_{\boldsymbol{y}}[w(\boldsymbol{y}) \,|\, \boldsymbol{x}] = \sum_{\boldsymbol{x}} w(\boldsymbol{y}) P(\boldsymbol{y} \,|\, \boldsymbol{x}) \,.$$

## Reduction to weighted binary relevance

- **Vertical reduction**: Solving m independent classification problems.
- Standard algorithms, like AdaBoost and logistic regression, can be adapted to this setting.
- AdaBoost.MH follows this approach for w = 1.33
- Besides its simplicity and efficiency, this approach is consistent (regret bounds have also been derived).<sup>34</sup>

<sup>&</sup>lt;sup>33</sup> R. E. Schapire and Y. Singer. BoosTexter: A Boosting-based System for Text Categorization. *Machine Learning*, 39(2/3):135–168, 2000

<sup>&</sup>lt;sup>34</sup> K. Dembczynski, W. Kotlowski, and E. Hüllermeier. Consistent multilabel ranking through univariate losses. In ICML, 2012

# Weighted binary relevance

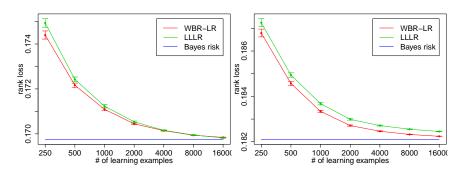


Figure: WBR LR vs. LLLR. Left: independent data. Right: dependent data.

- Label independence: the methods perform more or less en par.
- Label dependence: WBR shows small but consistent improvements.

#### Benchmark data

Table: WBR-AdaBoost vs. AdaBoost.MR (left) and WBR-LR vs LLLR (right).

DATASET	AB.MR	WBR-AB	LLLR	WBR-LR
IMAGE	0.2081	0.2041	0.2047	0.2065
EMOTIONS	0.1703	0.1699	0.1743	0.1657
SCENE	0.0720	0.0792	0.0861	0.0793
YEAST	0.2072	0.1820	0.1728	0.1736
MEDIAMILL	0.0665	0.0609	0.0614	0.0472

 WBR is at least competitive to state-of-the-art algorithms defined on pairwise surrogates.

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## Summary

- Multi-label classification.
- Simple approaches to multi-label classification.
- Task losses minimized by BR and LP.
- CRFs and SSVMs.
- PCC and Filter trees.
- Approaches for other loss functions: F-measure and rank loss.

# **Open challenges**

- Learning and inference algorithms for any task loss and output structure.
- Consistency of the algorithms.
- Large-scale datasets: number of instances, features, and labels.

#### **Conclusions**

- Take-away message:
  - ► Two main issues: loss minimization and label dependence.
  - ► Two main approaches: surrogate loss minimization and reduction.
  - ► Consistency of algorithms.
  - ► High regret between solutions for different losses.
  - ▶ Proper modeling of label dependence for different loss functions.
  - ► Be careful with empirical evaluations.
  - ▶ Independent models can perform quite well.
- For more check:

http://www.cs.put.poznan.pl/kdembczynski