

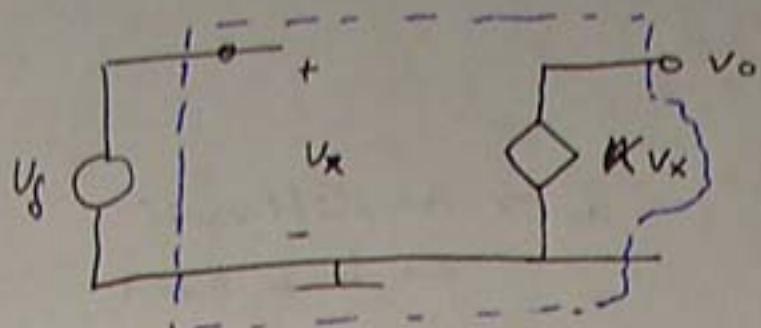
APUNTS PROPIETAT DE:
MÀRIUS SERRA LÓPEZ

PER QUALEVOV DUBTE O
CONSULTA RESPECTE ELS
APUNTS O EL QUE FACI FALTA
ESCRIURE A:
tirantloblanc84@hotmail.com

(l'assumpte ha de ser: Apunts ETSETB)

QUALEVOV ERROR PRESENT
S'ATTRIBUEIX AL PROFE DE
L'ASSIGNATURA QUE ME LA VA
IMPARTIR!!

MODEL:



$$K = 1 + \frac{R_2}{R_1}$$

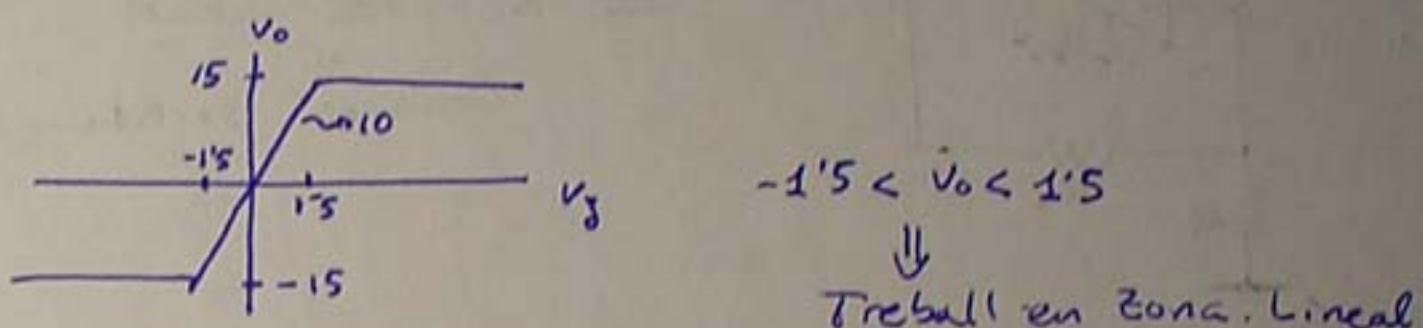
Amplificació en bucle tancat

- K es pot fixar a partir R_1, R_2
- K no depèn de A_0
- $K \ll A_0$
- Model valid $\Leftrightarrow |v_o| < v_{DC}$

Ex:

$$V_{DC} = 15V$$

$$\begin{cases} R_1 = 1K\Omega \\ R_2 = 9K\Omega \end{cases} \quad \left\{ \begin{array}{l} K = 10 \\ A_0 = 100 \end{array} \right.$$



$$-1.5 < v_o < 1.5$$

↓
Treball en zona lineal

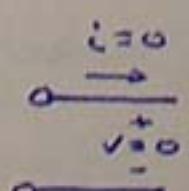
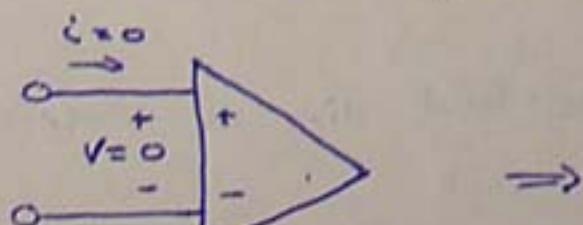
Valors exactes de v_i i v_o :

$$v_i = \frac{1}{\frac{A_0}{K} + 1} v_o = 9999 \cdot 10^{-5} v_o \Big|_{v_o=1V} = 100 \mu V \Rightarrow \text{compleix Hip} \\ < 150 \mu V$$

$$v_o = \frac{A_0}{\frac{A_0}{K} + 1} v_i \approx 10 v_i$$

Tècnica del curt-circuit virtual:

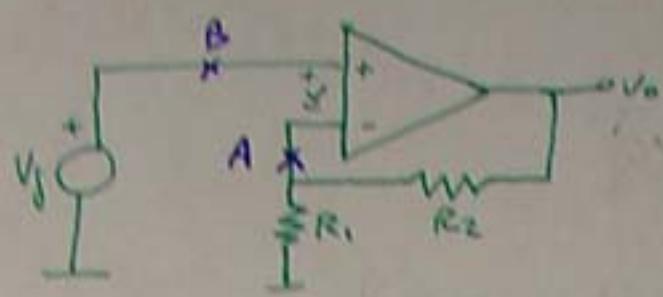
* Consisteix en suposar que $v=0$.



curtcircuit
virtual
c.c. i c.o.

cc → curtcircuit ($v=0$)
co → circuit obert ($i=0$)

Ex:

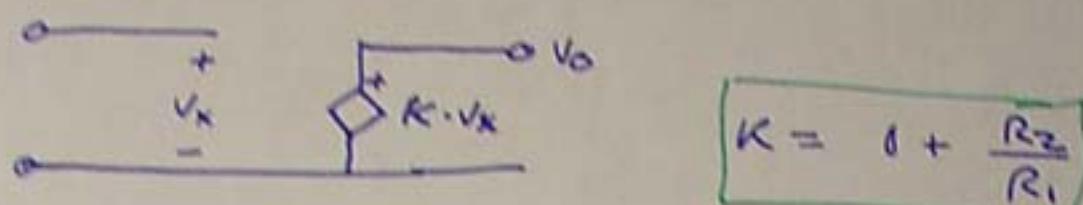


En el Node A hi ha una tensió V_f , que és el mateix que hi ha al Node B.

$$CCV \Rightarrow V = 0 \Rightarrow V_- = V_g$$

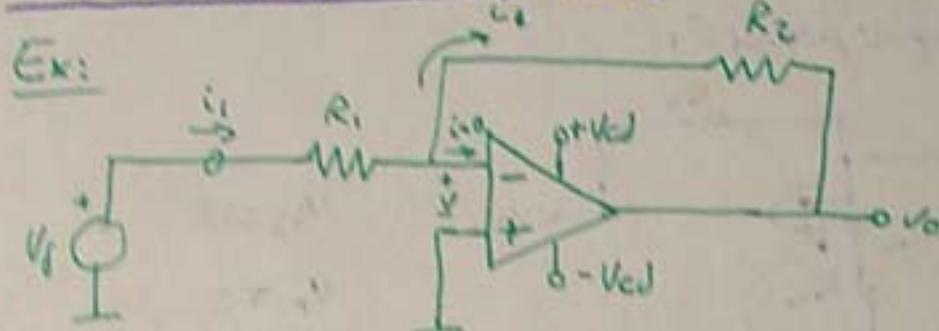
$$V_f = \frac{R_1}{R_1 + R_2} V_o \Rightarrow \boxed{V_f \left(1 + \frac{R_2}{R_1} \right) = V_o}$$

AMPLIFICADOR NO INVERSOR:



$$K = 1 + \frac{R_2}{R_1}$$

AMPLIFICADOR INVERSOR:



⇒ Tot el corrent que passa per R_1 , s'en va cap a R_2 .

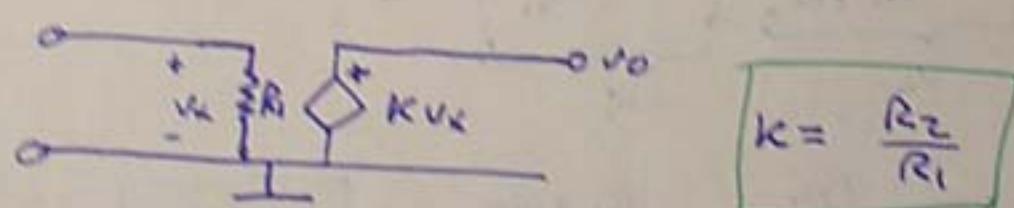
$$R_{eq} = \frac{V}{I_1} = \frac{V_f}{V_f/R_1} = R_1$$

$$CCV \Rightarrow V = 0 \Rightarrow V_- = 0$$

$$KVL \Rightarrow i_1 = \frac{V_f - 0}{R_1} = \frac{0 - V_o}{R_2}$$

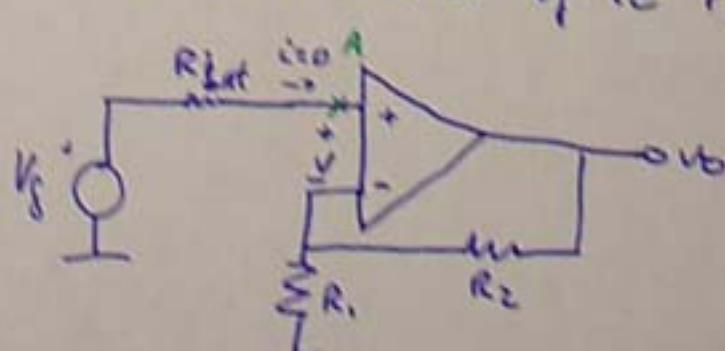
$$\boxed{V_o = -V_f \frac{R_2}{R_1}}$$

MODEL:



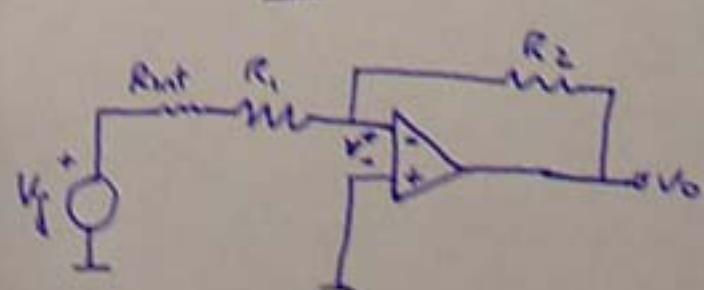
$$K = \frac{R_2}{R_1}$$

Ex: Que succeix si V_f té resistència?



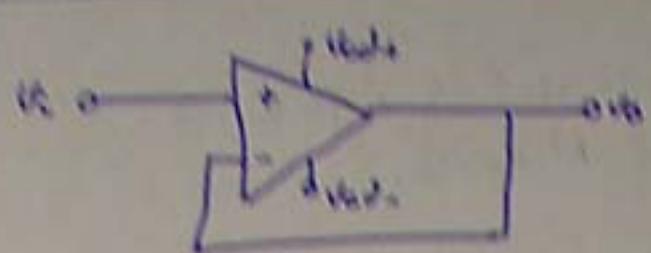
En A hi ha V_f volts. En R_{int} no can tensió.

$$V_o = V_f \frac{R_1 + R_{int}}{R_1} = V_f \left(1 + \frac{R_{int}}{R_1} \right) \Rightarrow \text{No té conseqüències.}$$



$$V_o = - \frac{R_2}{R_{int} + R_1} V_f \Rightarrow \text{Provoca una peruda d'amplificació.}$$

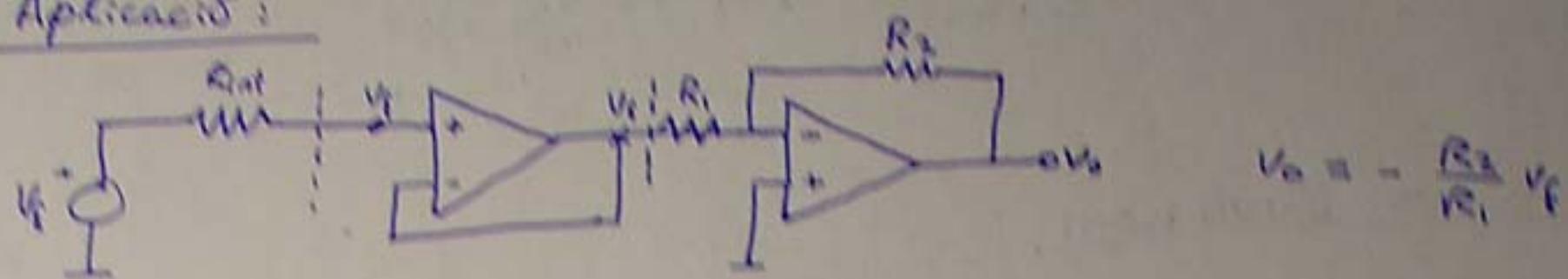
SEGUIDOR DE TENSIO:



caràcter d'avalant
 $V_{in} \Rightarrow V_{out} \Rightarrow V_{out} = V_{in}$

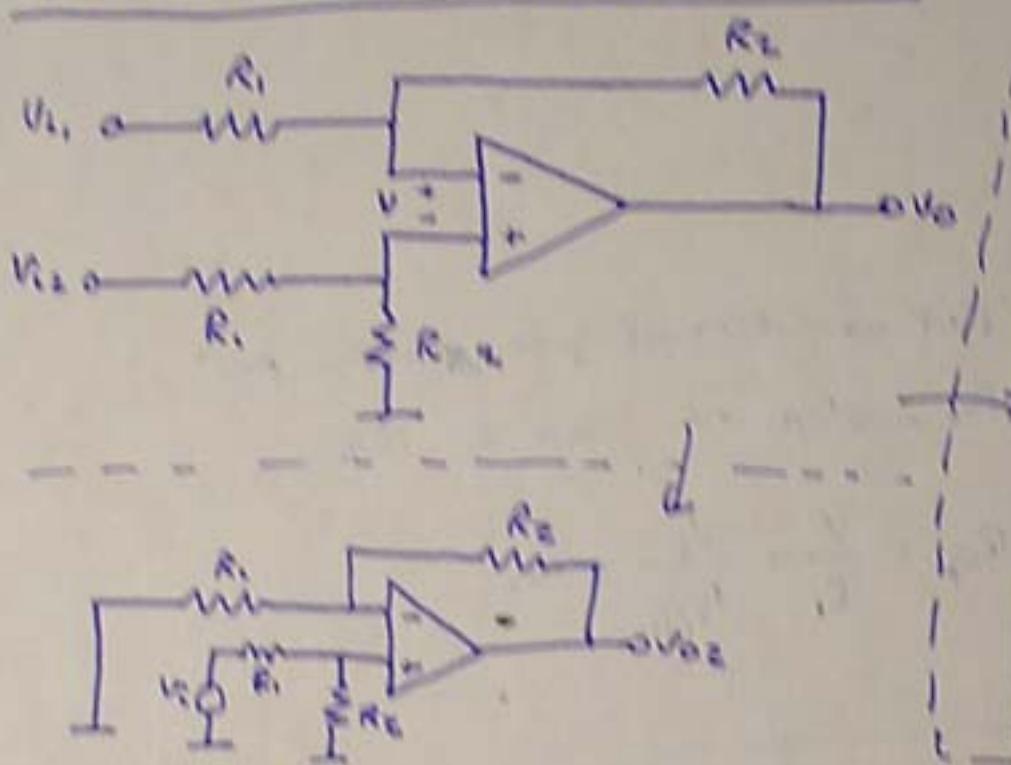
* També s'anomena etapa separatoria en anglès buffer.

Aplicacions:



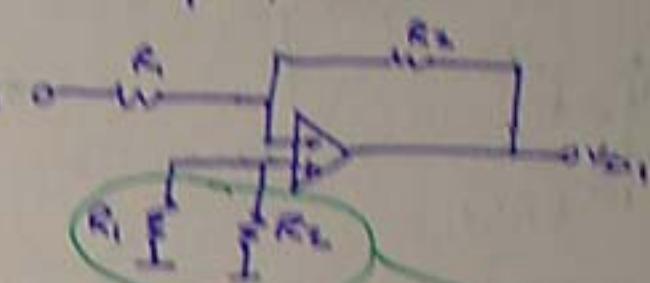
$$V_{out} = -\frac{R_2}{R_1} V_i$$

AMPLIFICADOR DIFERENCIAL:



~~Per~~ per CCV

per superposició:

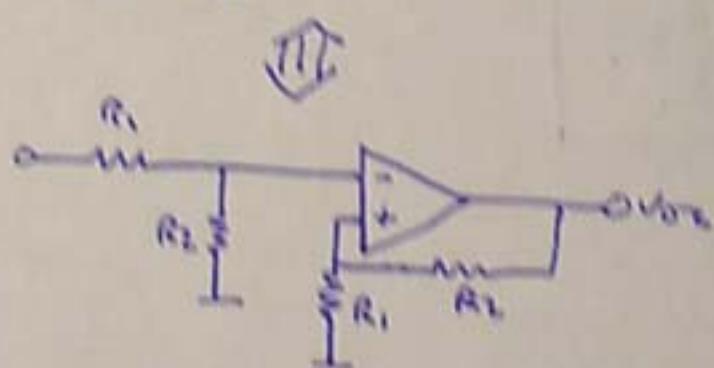


$$V_{out1} = 0$$

$$V_t = 0$$

$R_1 = R_2$ com
si no hi fosen

$$V_{out1} = -\frac{R_2}{R_1} V_{in1}$$



$$V_{out2} = \underbrace{V_{in2}}_{V_K} \frac{\underbrace{R_2}_{K}}{\underbrace{R_1 + R_2}_{1 + \frac{R_2}{R_1}}} \left(1 + \frac{R_2}{R_1} \right) =$$

$$V_{out2} = V_{in2} \frac{R_2}{R_1 + R_2} \cdot \frac{R_1 + R_2}{R_1} = \boxed{V_{in2} \frac{R_2}{R_1}}$$

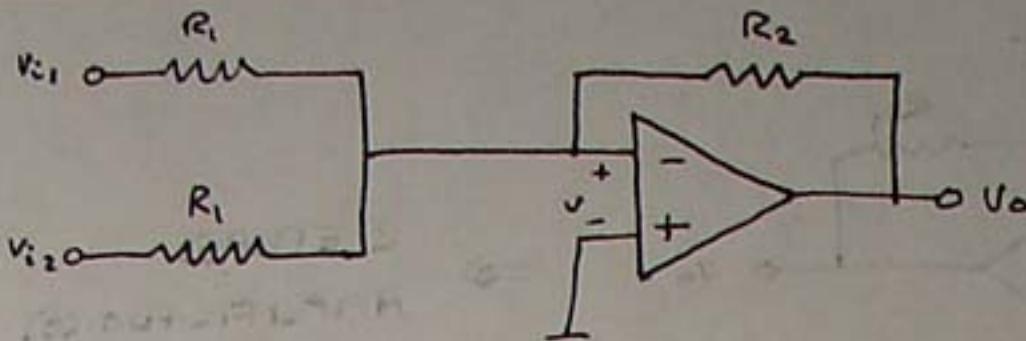
$$V_{out} = V_{out1} + V_{out2}$$

$$V_{out} = -\frac{R_2}{R_1} V_{in1} + \frac{R_2}{R_1} V_{in2}$$

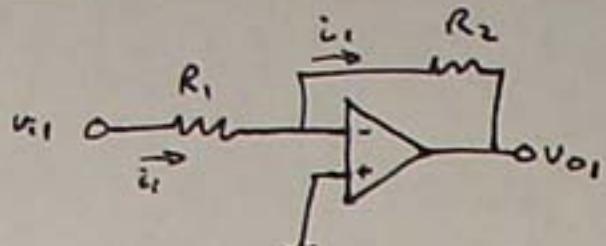
$$\boxed{V_{out} = \frac{R_2}{R_1} (V_{in2} - V_{in1})}$$

AMPLIFICADOR SOMADOR INVERSOR:

24-10-03 (23)



Superposición:



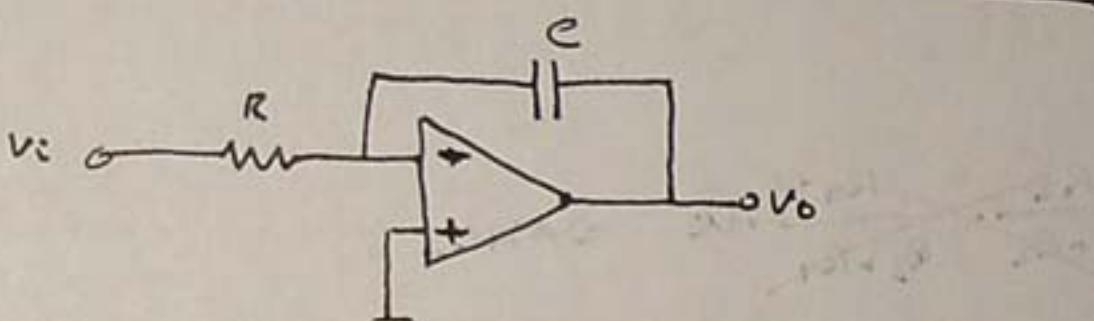
$$i_1 = \frac{v_{i1}}{R_1} = -\frac{v_{o1}}{R_2} \Rightarrow$$

$$v_{o1} = -\frac{R_2}{R_1} v_{i1}$$

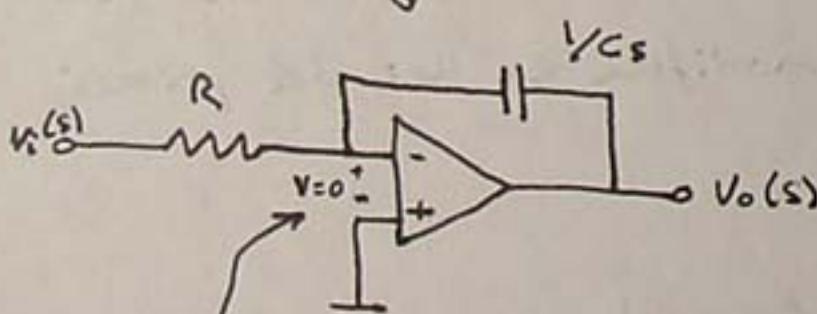
$$v_{o2} = -\frac{R_2}{R_1} v_{i2}$$

$$v_o = v_{o1} + v_{o2} = -\frac{R_2}{R_1} (v_{i1} + v_{i2})$$

AMPLIFICADOR INTEGRADOR INVERSOR:



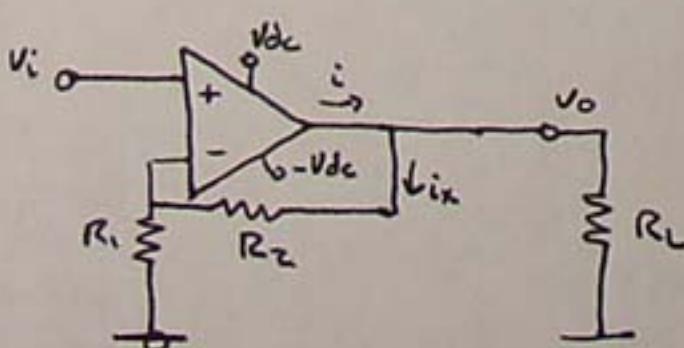
↓



CCV transformat = CCV

$$v_o(s) = -\frac{\frac{1}{Cs}}{R} v_e(s) = \underbrace{\frac{-1}{RCS}}_{H(s)} v_i(s)$$

EL OPERACIONAL TÉCNICOS:

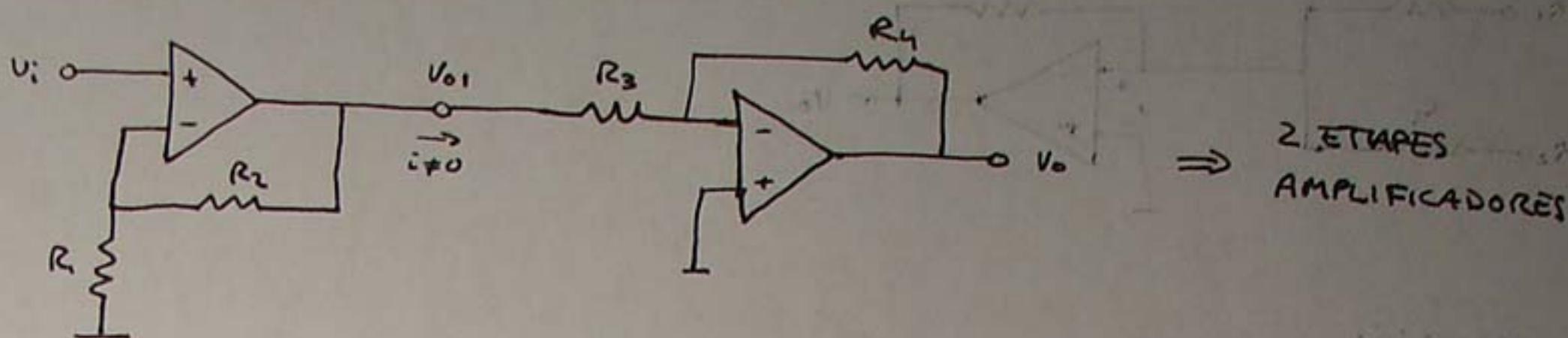


$$v_o = \left(1 + \frac{R_2}{R_1}\right) v_i \Rightarrow \text{No depen de } R_L$$

$i_{max} \approx 40mA \rightarrow$ Si es supera deixar de cumplir-se lo anterior o s'escanya.

$$i_x = \frac{-v_o}{R_1 + R_2}$$

CONEXIÓN EN CASCADA D'AO :



$$V_{O1} = \left(1 + \frac{R_2}{R_1}\right) V_i$$

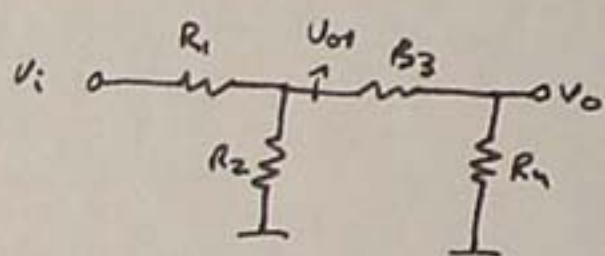
$$V_0 = -\frac{R_4}{R_3} V_{O1}$$

$$V_0 = \underbrace{\left(1 + \frac{R_2}{R_1}\right)}_{K_1} \underbrace{\left(-\frac{R_4}{R_3}\right)}_{K_2} V_i$$

$\underbrace{K_T}_{K_1 \cdot K_2}$

$$K_T = K_1 \cdot K_2$$

Ex:



$$V_0 = \frac{R_2}{R_1 + R_2} \cdot \frac{R_4}{R_3 + R_4} \cdot V_i \Rightarrow \text{FALS}$$

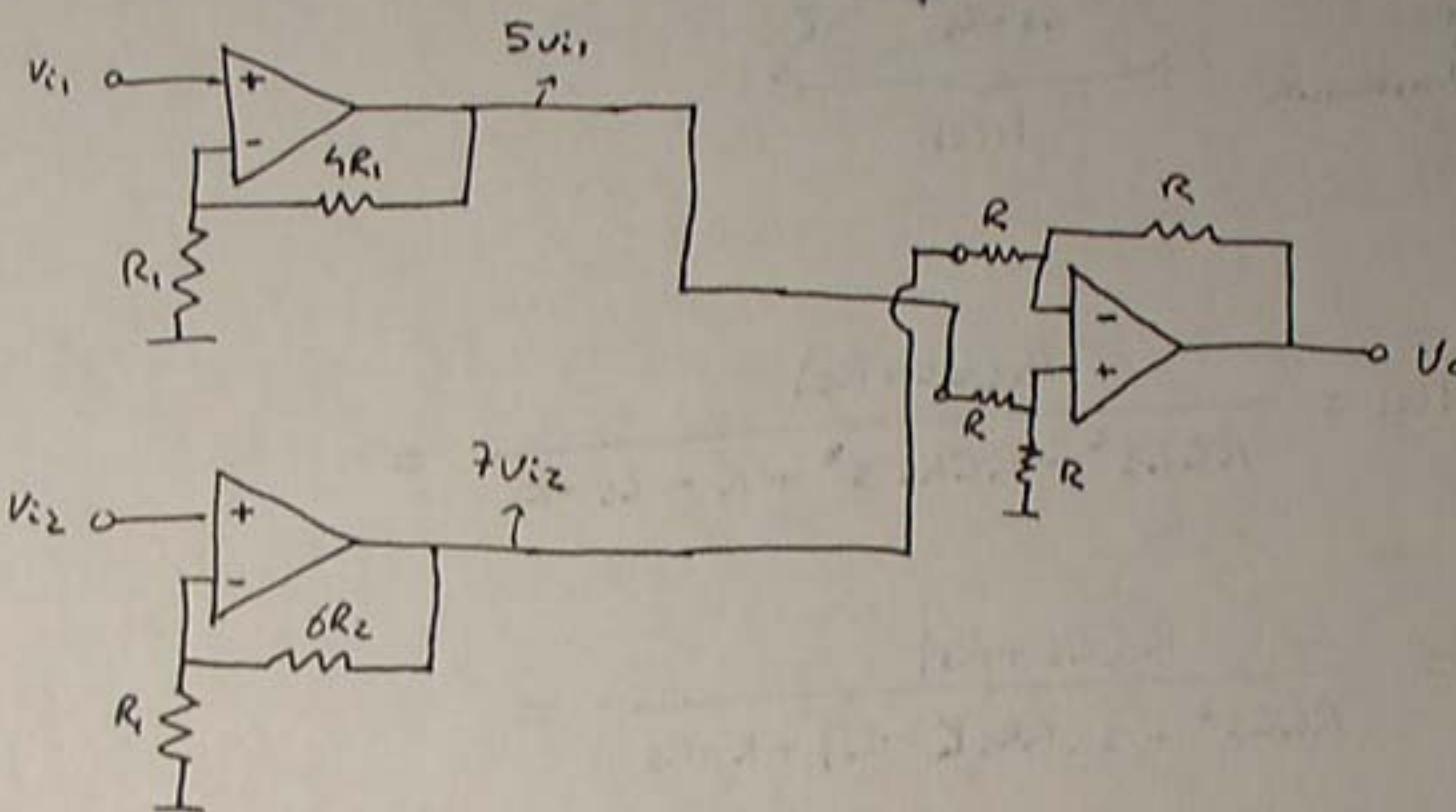
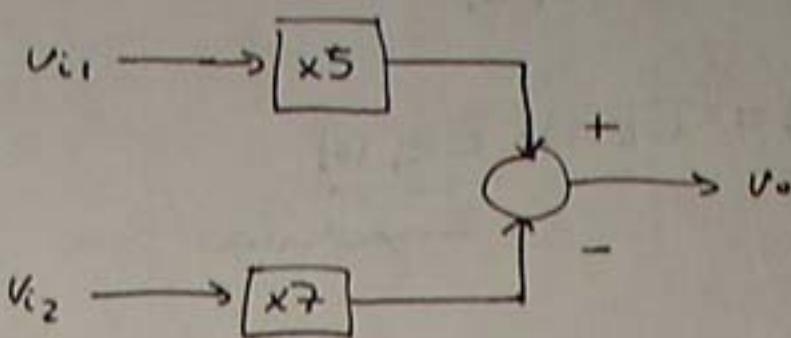
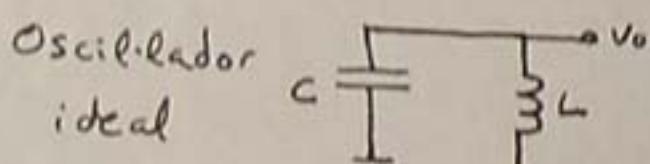
* És fals pels que el segon divisor de tensió absorbeix intensitat, i això modifica la del primer divisor de tensió.

* Això no succeeix en les etapes amplificadoras.

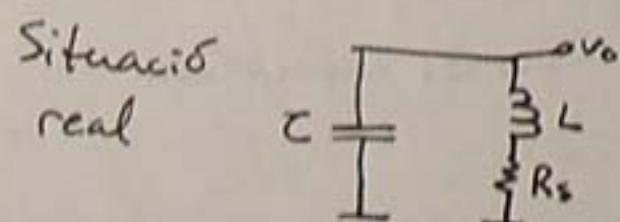
* Limit: si intercanviem les dues etapes anteriors, i hi possem un generador amb resistència interna, hi haurà problemes.

Exercici:

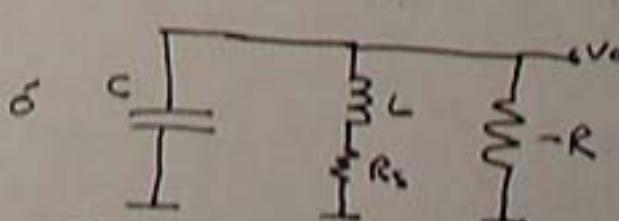
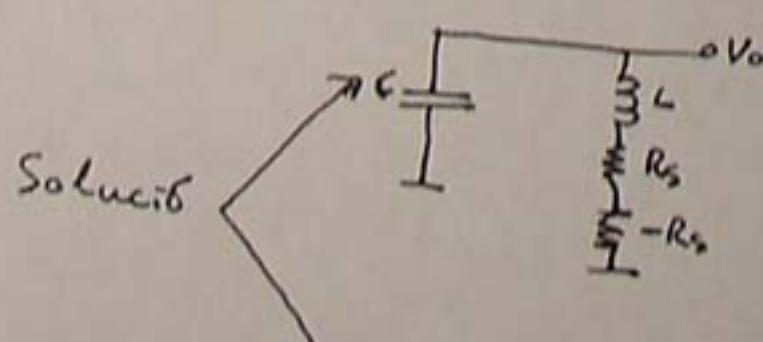
Fer un circuit que produeix: $U_o = 5U_{i_1} - 7U_{i_2}$

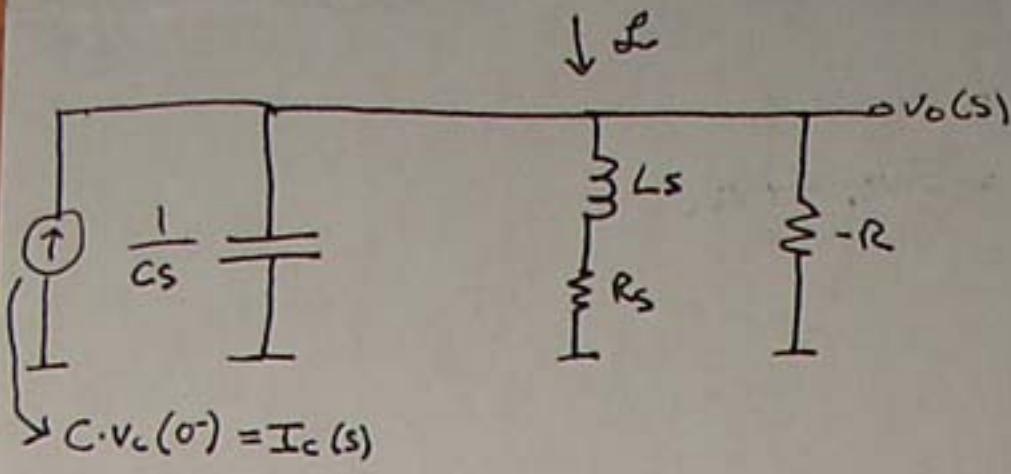
Oscil·lador sinusoidal amb R negativa:

S: $C \neq 0$
Resposta lliure
es manté en el temps



Resposta lliure que
s'atenua amb el temps.





$$H(s) = \frac{V_o(s)}{I_{c_2}(s)}$$

$$V_o(s) = I_c(s) \cdot \underbrace{Z_{ef}(s)}_{\text{Impedancia}}$$

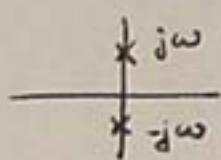
$$V_o(s) = I_c(s) \cdot \frac{1}{Y_{ef}(s)} = \frac{1}{Cs + \frac{1}{Ls + Rs} - \frac{1}{R}} \cdot I_c(s)$$

$\underbrace{\qquad\qquad\qquad}_{H(s)}$

Admitancia

Oscilador

$$H(s) = \frac{N(s)}{s^2 + \omega_0^2}$$



$$H(s) = \frac{R(Ls + Rs)}{RLCs^2 + RCRs s + R - Ls - Rs} =$$

$$= \frac{R(Ls + Rs)}{RLCs^2 + s(RRs - L) + R - Rs} =$$

$$= \dots \quad (\text{El que signi}) \dots$$

$$s^2 + \left(\frac{Rs}{L} - \frac{1}{RC} \right) s + \frac{1}{LC} \left(1 - \frac{Rs}{R} \right)$$

Condició d'oscilació:

$$\frac{Rs}{L} - \frac{1}{RC} = 0 \quad \boxed{R = \frac{L}{Rs C}}$$

$$\frac{1}{LC} \left(1 - \frac{Rs}{R} \right) > 0 \quad \begin{matrix} \text{Habitualment } R \gg Rs \\ \rightarrow \text{Es compleix} \end{matrix}$$

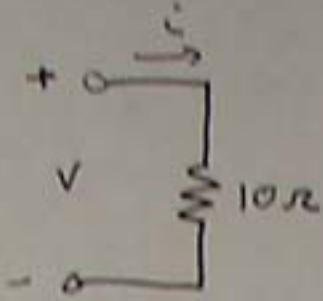
Freq. d'oscilació:

$$\omega_0 = \sqrt{\frac{1}{LC} \left(1 - \frac{Rs}{R} \right)} \approx \frac{1}{\sqrt{LC}} \quad \begin{matrix} R \gg Rs \\ \approx \end{matrix}$$

$$\frac{1}{LC} = \frac{Rs}{RLC}$$

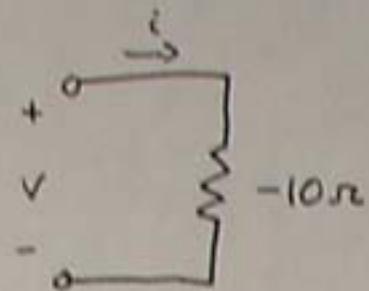
27)

Realització d'una resistència negativa:



$$V = 10i \Rightarrow \text{si } V > 0 \Rightarrow i > 0$$

$$P = Vi = 10i^2 \geq 0$$

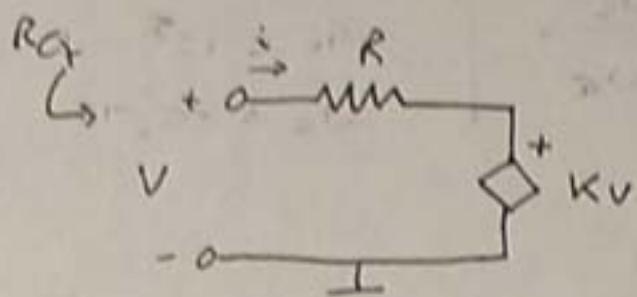


$$V = -10i \Rightarrow \text{si } V > 0 \Rightarrow i < 0$$

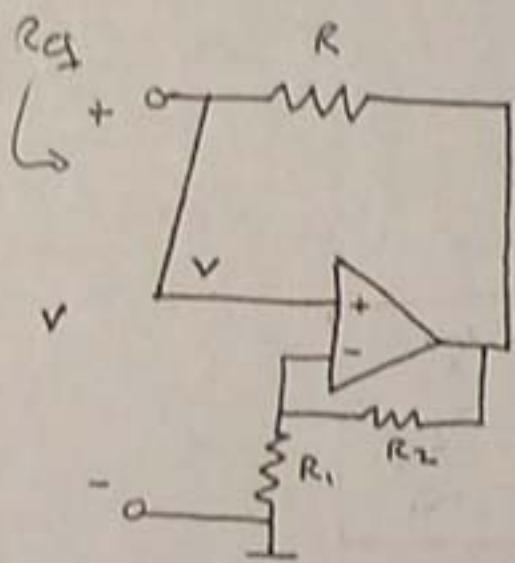
$$P = Vi = -10i^2 \leq 0$$

→ Una energia al circuit

com realitzar l'últim cas:



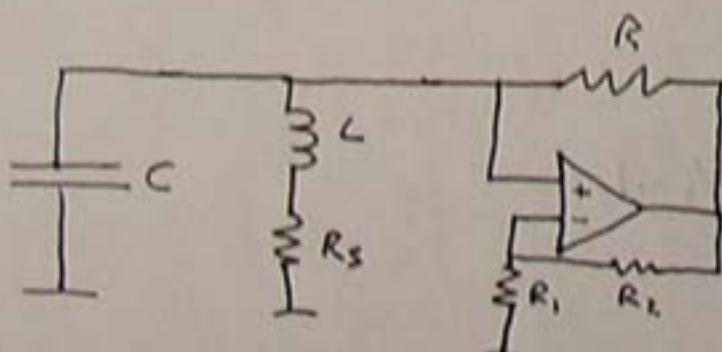
$$R_{eq} = \frac{V}{i} = \frac{V}{\frac{V-K_V}{R}} = \boxed{\frac{R}{1-K_V}} \Rightarrow \begin{array}{l} \text{Resistència} \\ \text{Negativa} \Rightarrow K > 1 \end{array}$$



$$K = 1 + \frac{R_2}{R_1}$$

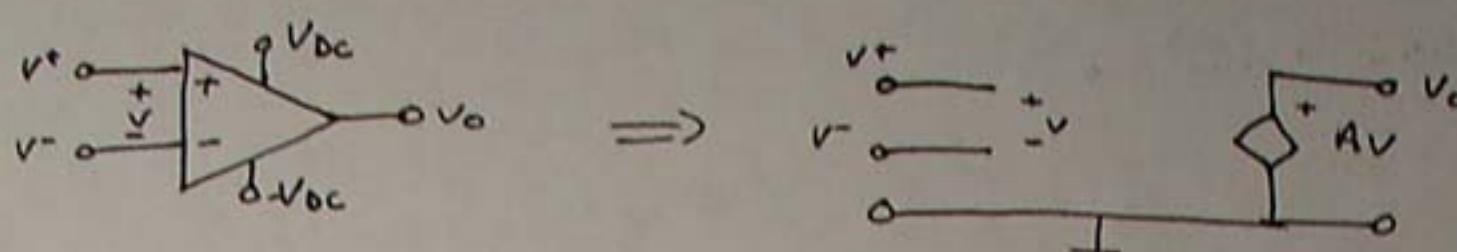
$$R_{eq} = \frac{R}{-\frac{R_2}{R_1}} = \frac{-R \cdot R_1}{R_2} \stackrel{R_1 = R_2}{=} -R$$

Circuit complet:

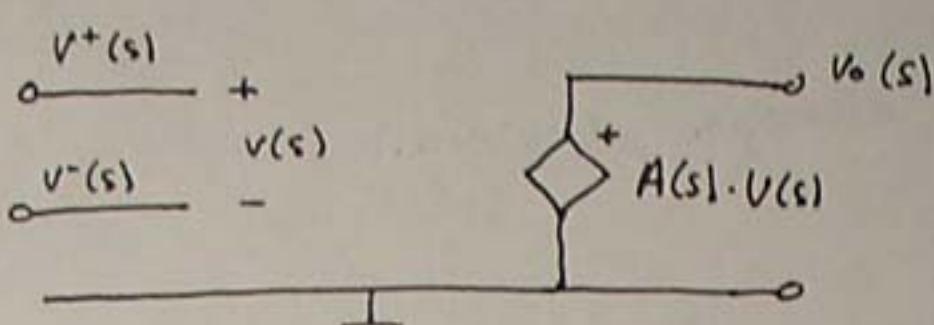


MODEL DINÀMIC DE L'AMPLIFICADOR OPERACIONAL:

Model simplificat:



Model + precís:



→ Domini transformat

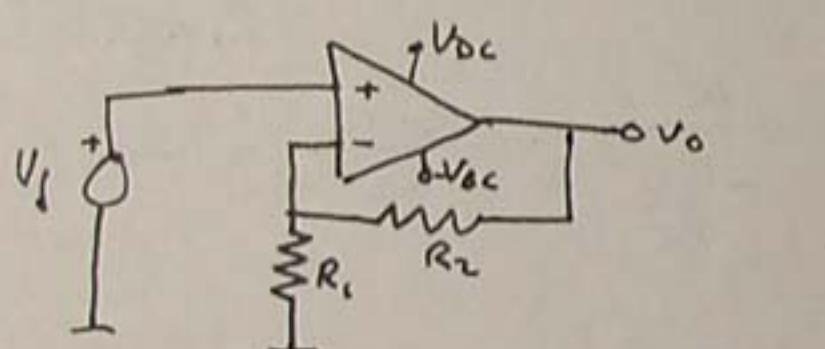
↳ Dif. amb el de dalt. $A(s) \rightarrow$ variable

$$A(s) = \frac{A_0 \omega_c}{s + \omega_c}$$

EN MATHI
 $A_0 \approx 10^5$
 $\omega_c = 80\pi$

$A(s) \equiv$ Funció de xarxa de l'A.O.

* Com afecta el nou model a l'A.O. NO INVERSOR:

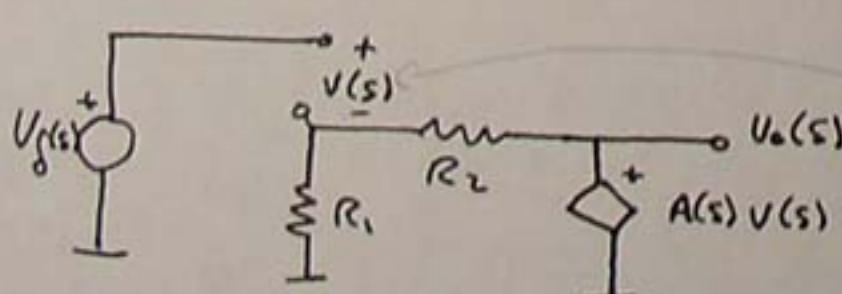


→ Model simplificat →

$$V_o = K \cdot V_f$$

$$K = 1 + \frac{R_2}{R_1}$$

↓ Model dinàmic



$$V_o(s) = H(s) \cdot V_f(s)$$

$$KVL: V_f(s) = A(s) \cdot V(s) \cdot \frac{R_1}{R_1 + R_2} + V(s) \rightarrow \frac{1}{K}$$

$$V_f(s) = \frac{1}{\frac{A(s)}{K} + 1} V_o(s)$$

$$V_o(s) = A(s) \cdot V_f(s) = \frac{A(s)}{\frac{A(s)s}{K} + 1} V_f(s) \quad (26)$$

$$\begin{aligned} H(s) &= \frac{A(s)}{\frac{A(s)s}{K} + 1} = \frac{\frac{A_0 \omega_c}{s + \omega_c}}{\frac{A_0 \omega_c s}{K(s + \omega_c)} + 1} = \frac{A_0 \omega_c}{\frac{A_0 \omega_c s}{K} + s + \omega_c} = \\ &= \frac{A_0 \omega_c}{s + \omega_c \left(\frac{A_0}{K} + 1 \right)} \xrightarrow[\substack{A_0 \\ K \gg 1}]{\approx} \frac{A_0 \omega_c}{s + \frac{A_0}{K} \omega_c} \rightarrow \text{1r ordre estable} \quad \begin{array}{c} -K \\ -\frac{A_0 \omega_c}{K} \end{array} \end{aligned}$$

Ex:

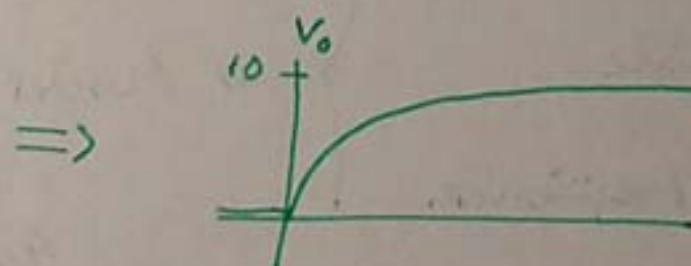
$$V_f(t) = u(t) \quad R_1 = 1 \text{ k}\Omega \quad R_2 = 9 \text{ k}\Omega \quad \Rightarrow K = 10$$

$$V_o(s) = H(s) \cdot V_f(s) = \frac{A_0 \omega_c}{s + \frac{A_0}{K} \omega_c} \cdot \frac{1}{s} = \frac{K}{s} - \frac{K}{s + \frac{A_0 \omega_c}{K}}$$

$$V_o(t) = K \cdot u(t) - K e^{-t/\tau} \cdot u(t) = K \left(1 - e^{-t/\tau} \right) u(t) =$$

$$\stackrel{\text{Valors}}{=} 10 \left(1 - e^{\frac{-t}{10 \cdot 10^{-6}}} \right) u(t)$$

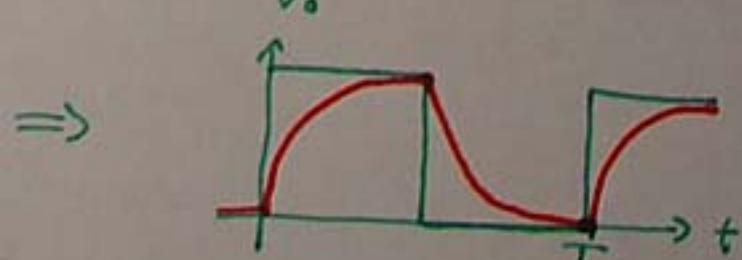
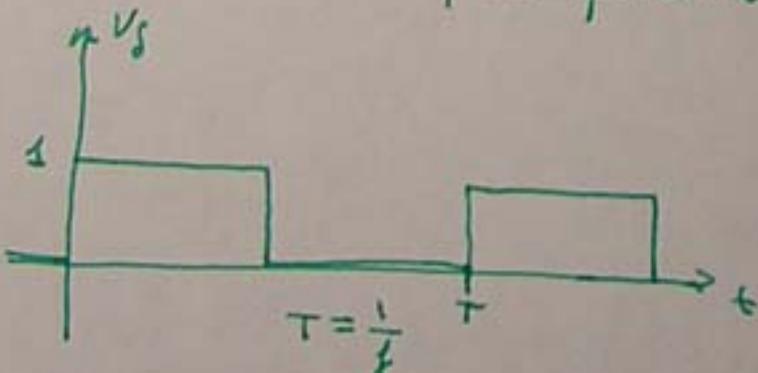
$$\boxed{\tau = \frac{K}{A_0 \omega_c}}$$



* Tenim un temps de resposta

* En regim permanent l'amplificació es manté

Ex: $V_f(t) \rightarrow$ Senyal quadrat

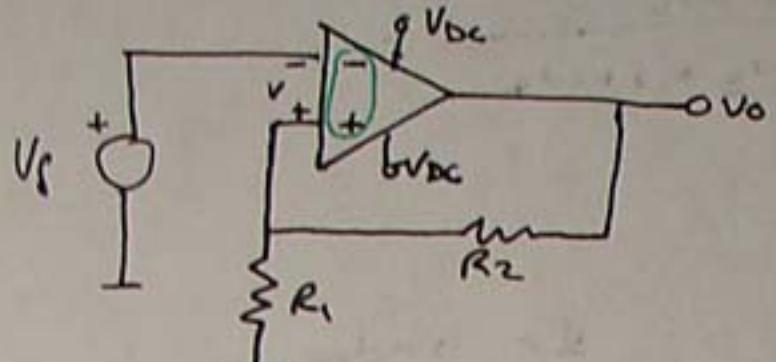


* Perque a V_o li hagi una senyal quadrada $\Rightarrow 4\tau \ll \frac{T_{min}}{2} \rightarrow 4\tau = \frac{T_{min}}{2} : 10$

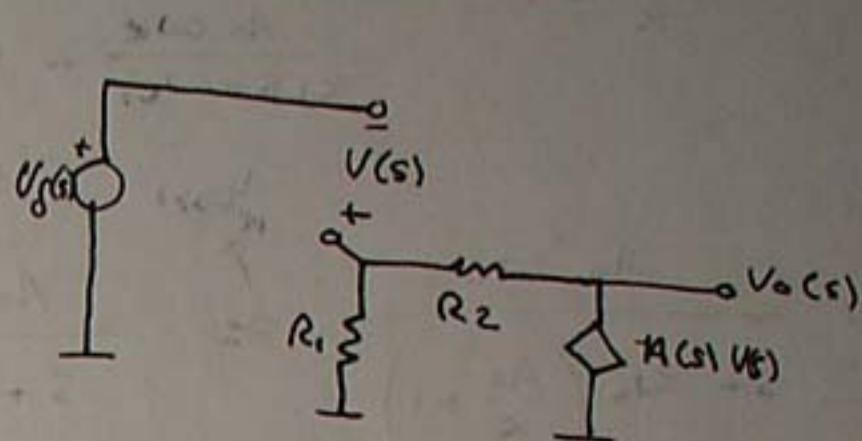
$$4\tau = \frac{1}{20 f_{\max}} \Rightarrow f_{\max} = \frac{1}{80\tau} = 10.4 \text{ kHz} \Rightarrow \mu A 741$$

$$\tau = 1.2 \mu s$$

* Com afecta la connexió entrada - sortida?



Model
Dinàmic



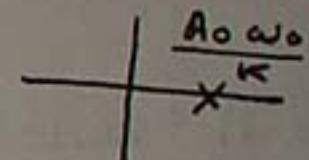
↓
Model simplificat \Rightarrow

$$V_o = K \cdot V_f$$

$$K = 1 + \frac{R_2}{R_1}$$

$$H(s) = \frac{A_0 \omega_c}{\frac{A_0}{K} \omega_c - s} = - \frac{A_0 \omega_c}{s - \frac{A_0}{K} \omega_c} \Rightarrow 1^{\text{r}} \text{ Ordre}$$

Inestable



↓
OPERA EN SATURACIÓ

Nota: Si intercanviem les entrades en qualsevol dels A_0 estudiats, aquests es tornen inestables; no funcionen com a tals.

CONCLUSIONS:

- 1) 3 retroalimentacions
- 2) Configuració és estable
- 3) Excació de baixa freqüència

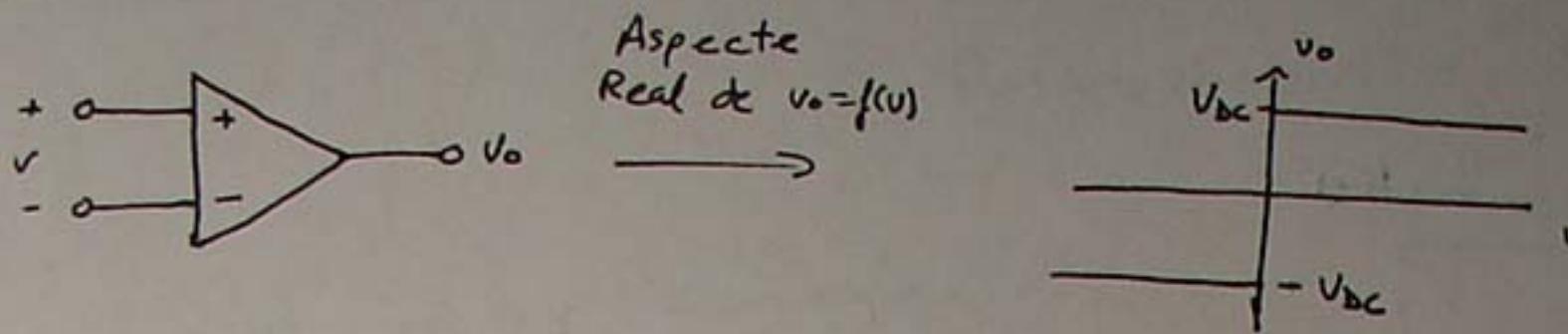
} \Rightarrow Model simplificat vàlid

↓
Anàlisi amb CCV

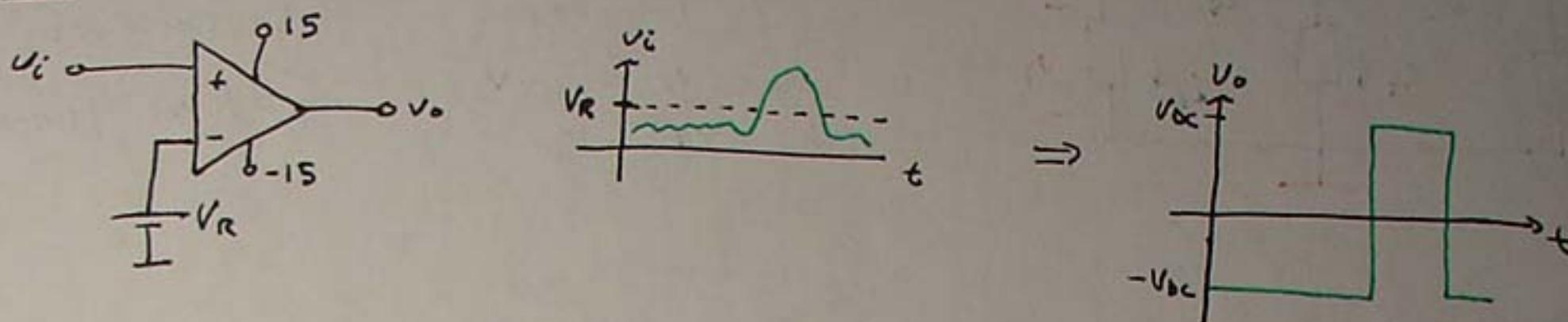


APLICACIÓ DE L'AO OPERANT EN ZONES DE SATURACIÓ:

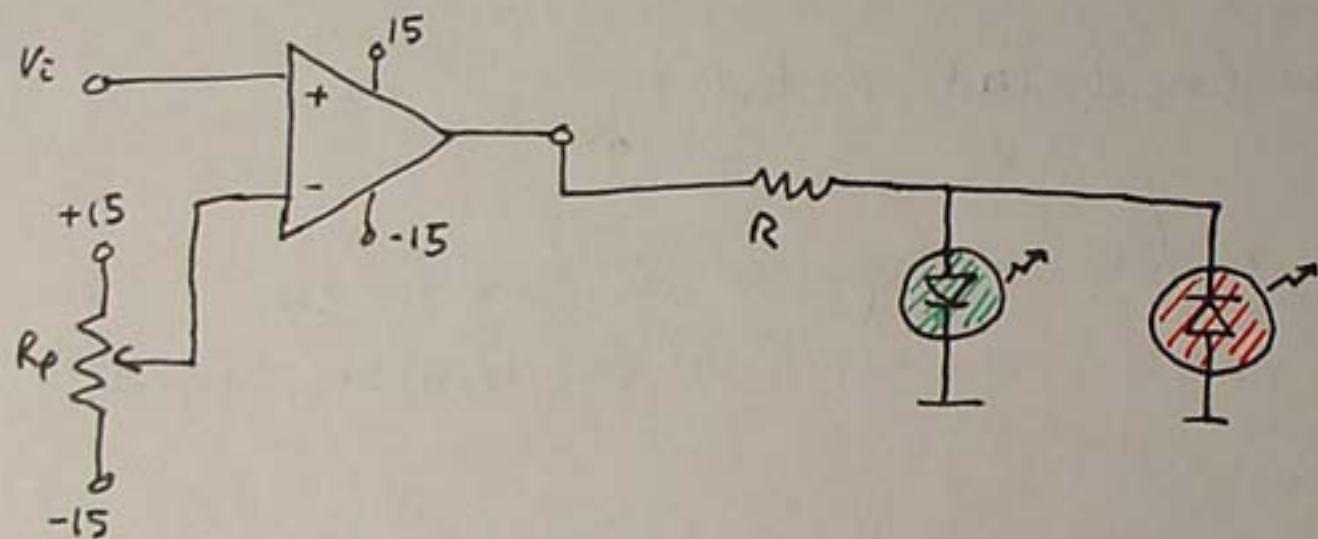
(27)



Ex: COMPARADOR



COMPARADOR AMB LLINDAR AJUSTABLE:



TEMA 4

P11, P17, P18

TEMA 5: ANÀLISI SISTÈMA DE CIRCUITS DINÀMICS:

Objectius: Disposar de sistemes mètodes d'anàlisi generals i eficients:

Aplicables a qualsevol circuit

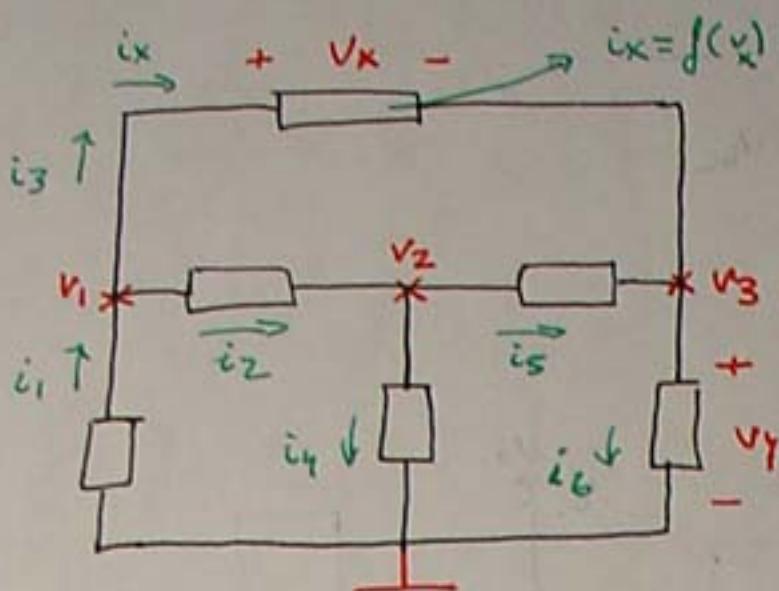
↓
Mínim nombre d'incògnites

↓
Base generadora

2 mètodes → TENSIONS NODALS
→ CORRENTS DE MALLA

MÉTODO DE LES TENSIONS MODALS:

Base generadora



Tensions nodals

- Comprovació que són base generadora.

a) Tensions:

$$v_x = v_1 - v_3$$

$$v_y = v_3$$

b) Corrents:

$$i_x = f(v_x) = f(v_1 - v_3)$$

Determinació:

N nodes $\rightarrow n = N-1$ tensions nodals

n Equacions líniesament independents

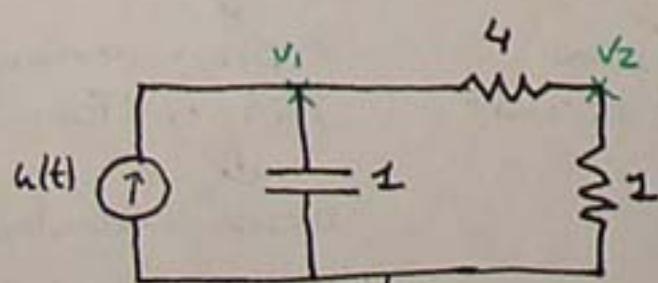
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KCL en els n nodes \Rightarrow Expressar els corrents en funció de les tensions nodals.

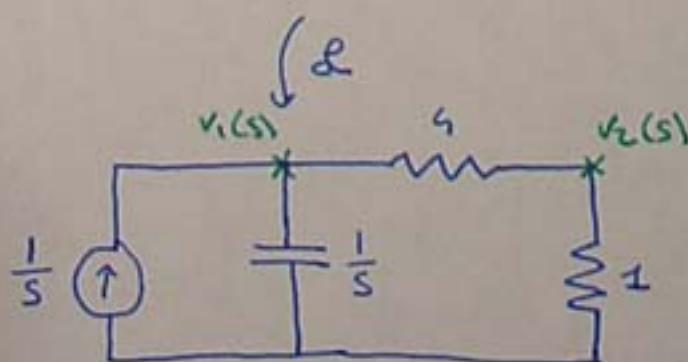
KCL

$$\begin{aligned} \textcircled{1} \quad & i_1 - i_2 - i_3 = 0 \\ \textcircled{2} \quad & i_2 - i_4 - i_5 = 0 \\ \textcircled{3} \quad & i_5 + i_3 - i_6 = 0 \end{aligned} \quad \left. \begin{array}{l} \\ \\ \end{array} \right\} \Rightarrow L \text{ Independents}$$

Exemple:



Determinar les tensions nodals v_1 , v_2



KCL

$$\textcircled{1} \quad \frac{V_1(s)}{1/s} + \frac{V_1(s) - V_2(s)}{4} = \frac{1}{s}$$

$$\textcircled{2} \quad \frac{V_1(s) - V_2(s)}{4} = \frac{V_2(s)}{1}$$

$$\begin{bmatrix} s + \frac{1}{5} & -\frac{1}{5} \\ -\frac{1}{5} & 1 + \frac{1}{5} \end{bmatrix} \begin{bmatrix} V_1(s) \\ V_2(s) \end{bmatrix} = \begin{bmatrix} \frac{1}{s} \\ 0 \end{bmatrix}$$

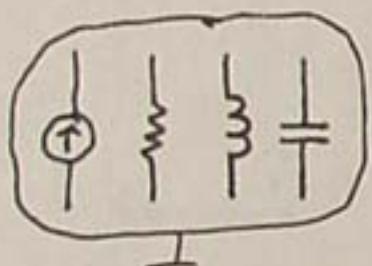
Kramer:

$$V_1(s) = \frac{\Delta_1}{\Delta} = \frac{\begin{bmatrix} \frac{1}{s} & -\frac{1}{5} \\ 0 & 1 + \frac{1}{5} \end{bmatrix}}{\begin{vmatrix} s + \frac{1}{5} & -\frac{1}{5} \\ -\frac{1}{5} & \frac{5}{5} \end{vmatrix}} = \frac{\frac{1}{s} + \frac{1}{4s}}{\frac{5}{5}s + \frac{5}{16} - \frac{1}{16}} = \frac{\frac{5}{5} \cdot \frac{1}{s}}{\frac{5}{5}s + \frac{1}{4}} = \frac{\frac{5}{5}}{s\left(\frac{5}{5}s + \frac{1}{4}\right)} = \frac{1}{s(s + \frac{1}{5})}$$

$$V_2(s) = \frac{\Delta_2}{\Delta} = \frac{\begin{bmatrix} s + \frac{1}{5} & \frac{1}{s} \\ -\frac{1}{5} & 0 \end{bmatrix}}{\frac{5}{5}s - \frac{1}{5}} = \frac{\frac{1}{5} \cdot \frac{1}{s}}{\frac{5}{5}s + \frac{1}{4}} = \frac{\frac{1}{5}}{s\left(\frac{5}{5}s + \frac{1}{4}\right)} = \frac{1}{s(5s + 1)} = \frac{1}{s(s + \frac{1}{5})}$$

$$V_1(s), V_2(s) \xrightarrow{\mathcal{L}^{-1}} v_1(t), v_2(t)$$

* Cas general:



$n = N-1$ tensions nodals

$$KCL \rightarrow Y(s) \cdot V(s) = I(s)$$

\nwarrow Admitància

Matríg d'admitàncies:

$$Y(s) = \begin{bmatrix} Y_{11}(s) & \dots & Y_{1n}(s) \\ \vdots & & \vdots \\ Y_{n1}(s) & \dots & Y_{nn}(s) \end{bmatrix}$$

$Y_{kk}(s) = \sum$ admittàncies connectades al node k .

$Y_{kl}(s) = -\sum_{k \neq l}$ admittàncies connectades als nodes k i l .

↳ "Entremig d'ells"

Vector de tensions:

$$V(s) = \begin{bmatrix} V_1(s) \\ \vdots \\ V_n(s) \end{bmatrix}$$

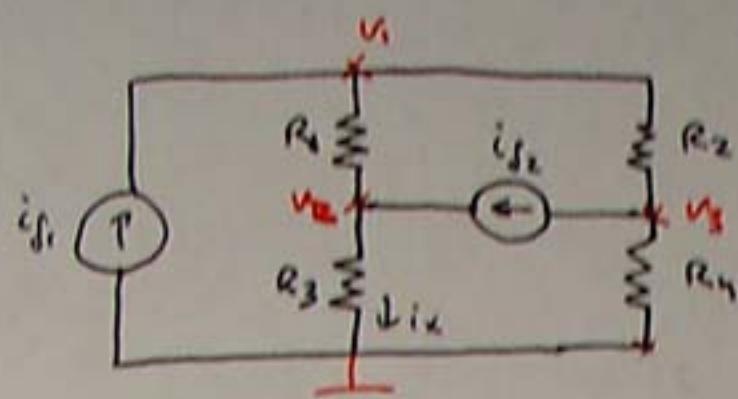
V_{ks} = Tensió al node k

Vector de corrents:

$$I(s) = \begin{bmatrix} I_1(s) \\ \vdots \\ I_n(s) \end{bmatrix}$$

$I_k(s) = \sum$ de corrents entrants al node k procedents de generadors independents.

Exemple 2:



Determinar i_{S2} :

$$R_1 = R_2 = R_3 = R_4 = 1 \text{ k}\Omega$$

$$i_{S2} = 2 \text{ mA} \quad i_{S1} = 1 \text{ mA}$$

$$G_m = \frac{1}{R_m}$$

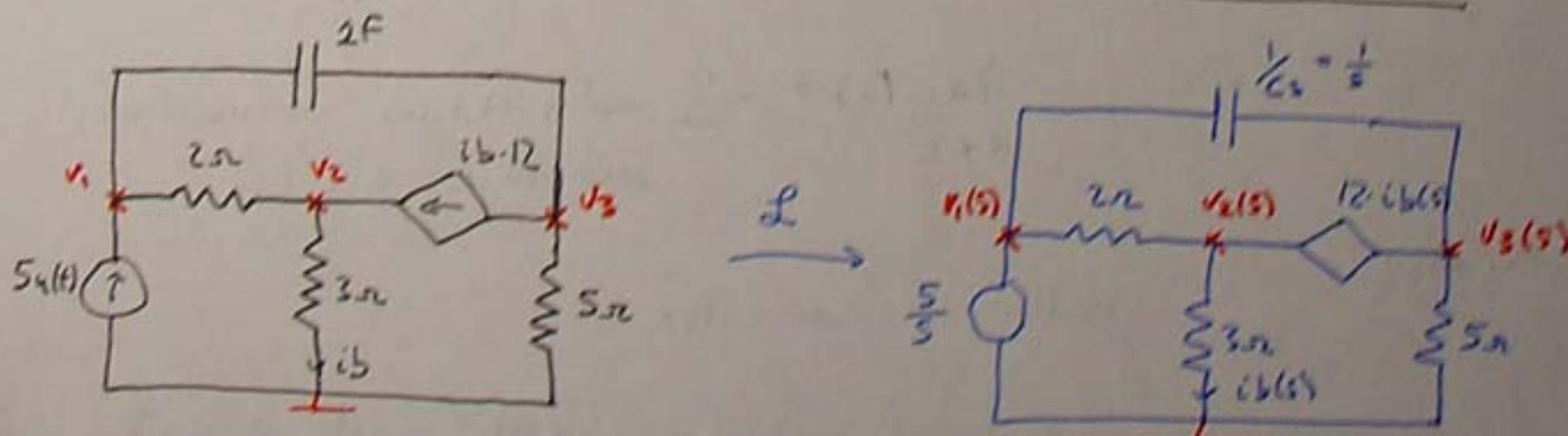
$$\begin{bmatrix} G_1 + G_2 & -G_1 & -G_2 \\ -G_1 & G_1 + G_3 & 0 \\ -G_2 & 0 & G_2 + G_4 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} i_{S1} \\ i_{S2} \\ -i_{S2} \end{bmatrix}$$

$$10^3 \cdot \begin{bmatrix} 2 & -1 & -1 \\ -1 & 2 & 0 \\ -1 & 0 & 2 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ -2 \end{bmatrix}$$

$$v_2 = \frac{\Delta_2}{\Delta} = \frac{\begin{vmatrix} 2 & 1 & -1 \\ -1 & 2 & 0 \\ -1 & 0 & 2 \end{vmatrix}}{\begin{vmatrix} 2 & -1 & -1 \\ -1 & 2 & 0 \\ -1 & 0 & 2 \end{vmatrix}} = \frac{6}{7} = \frac{3}{2}, \quad i_X = \frac{v_2}{R_3} = \frac{3/2}{1\text{k}} = 1500 \text{ mA}$$

-Mètode nodal amb fonts de corrent controlades:

31-10-03

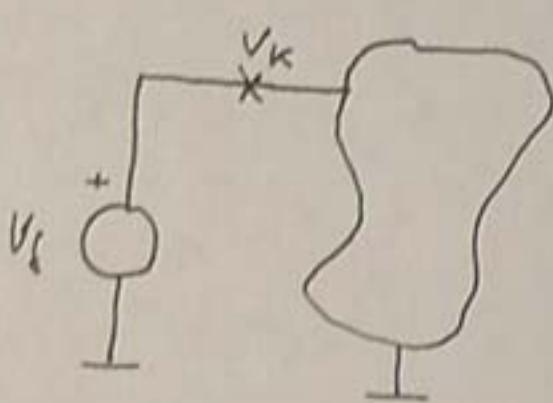


$$\begin{bmatrix} s + \frac{1}{2} & -\frac{1}{2} & -s \\ -\frac{1}{2} & \frac{1}{2} + \frac{1}{3} & 0 \\ -s & 0 & s + \frac{1}{5} \end{bmatrix} \begin{bmatrix} v_1(s) \\ v_2(s) \\ v_3(s) \end{bmatrix} = \begin{bmatrix} \frac{5}{s} \\ 12i_b(s) \\ -12i_b(s) \end{bmatrix} \xrightarrow{i_b = \frac{v_2}{5}} \begin{bmatrix} \frac{5}{s} \\ 9v_2(s) \\ -9v_2(s) \end{bmatrix}$$

U

$$\begin{bmatrix} s + \frac{1}{2} & -\frac{1}{s} & -s \\ -\frac{1}{2} & \frac{1}{2} + \frac{1}{3} - 4 & 0 \\ -s & 4 & s + \frac{1}{5} \end{bmatrix} \begin{bmatrix} v_1(s) \\ v_2(s) \\ v_3(s) \end{bmatrix} = \begin{bmatrix} \frac{s}{s} \\ 0 \\ 0 \end{bmatrix}$$

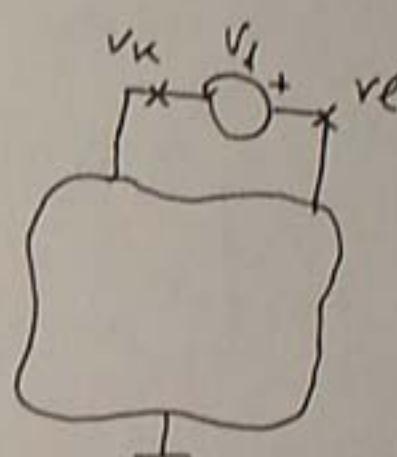
- Mètode nodal amb fonts de tensió:



$$v_K = v_f$$

1 incògnita menys

1 KCL menys



$$v_f = v_K + v_f$$

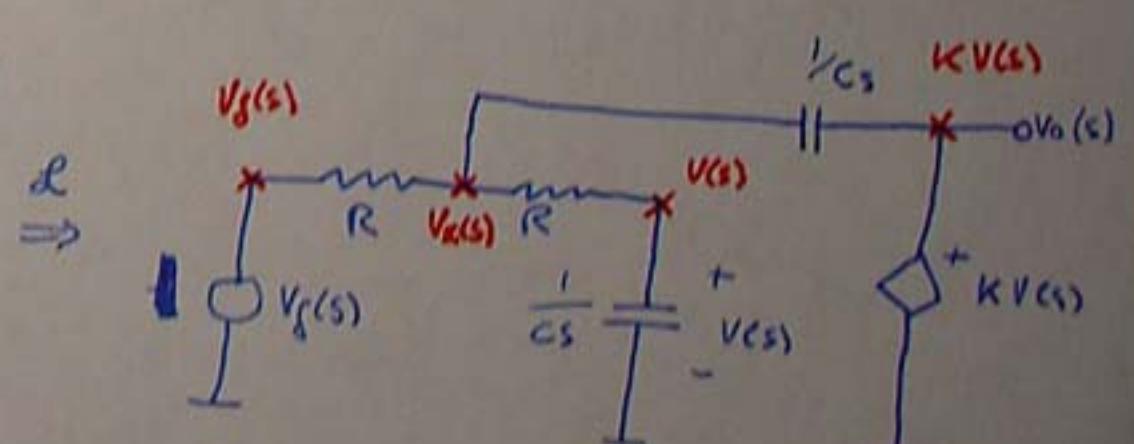
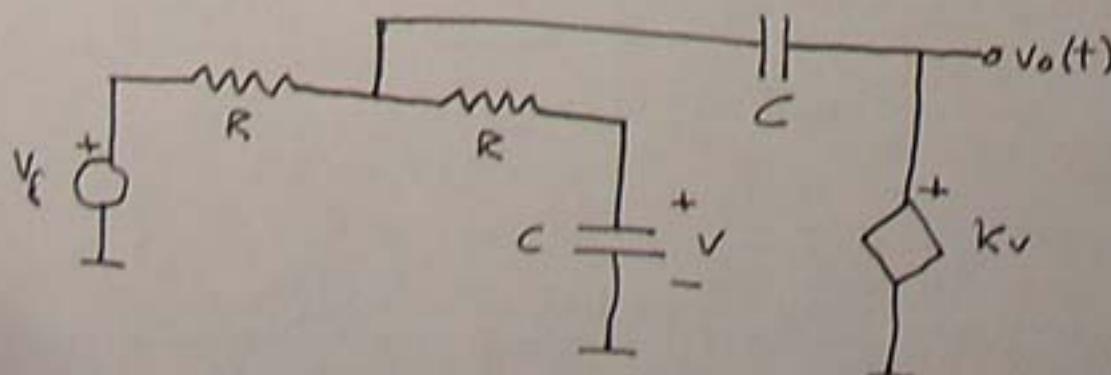
U

1 incògnita menys

1 KCL menys

Ex:

Circuit de Sallen-Key



* 4 tensions nodals \rightarrow 2 incògnites ($v_x(s)$, $v(s)$)

KCL

$$\left. \begin{aligned} V_x(s) - \frac{V_f(s) - V_x(s)}{R} &= \frac{+V_x(s) - V(s)}{R} + \frac{V_x(s) - KV(s)}{RC_s} \\ V(s) - \frac{V_x(s) - V(s)}{R} &= \frac{V(s)}{RC_s} \end{aligned} \right\}$$

Forma alternativa KCL de forma sistemática

KCL

$$\left. \begin{aligned} V_x(s) - (2G + Cs)V_x(s) - GV_f(s) - G V(s) - Cs KV(s) &= 0 \\ V(s) - G V_x(s) + (G + Cs)V(s) &= 0 \end{aligned} \right\}$$

SISTEMA:

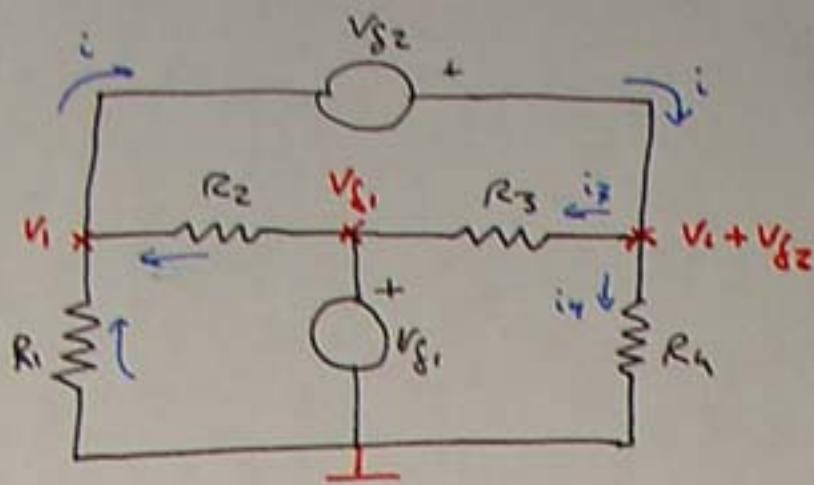
$$V(s) = \frac{\begin{bmatrix} 2G + Cs & -G - KV_s \\ -G & G + Cs \end{bmatrix} \begin{bmatrix} V_x(s) \\ V(s) \end{bmatrix}}{\begin{bmatrix} 2G + Cs & GV_f(s) \\ -G & 0 \end{bmatrix}} = \frac{G^2 \cdot V_f(s)}{2G^2 + 2GCS + G^2S^2 - (G^2 + GKV_s)} =$$

$$G = \frac{1}{RC}$$

$$= \frac{G^2 \cdot V_f(s)}{C^2 S^2 + CGS(3-K) + G^2} = \frac{\frac{1}{R^2} \cdot V_f(s)}{C^2 S^2 + \frac{C}{R} S(3-K) + \frac{1}{R^2}} =$$

$$= \frac{\frac{1}{(RC)^2} \cdot V_f(s)}{S^2 + \frac{(3-K)}{RC} S + \frac{1}{C^2 R^2}}$$

$$H(s) = \frac{V_o(s)}{V_f(s)} = \frac{KV(s)}{V_f(s)} = \frac{\frac{K}{(RC)^2}}{S^2 + \frac{3-K}{RC} S + \frac{1}{(RC)^2}}$$

Ex 2:

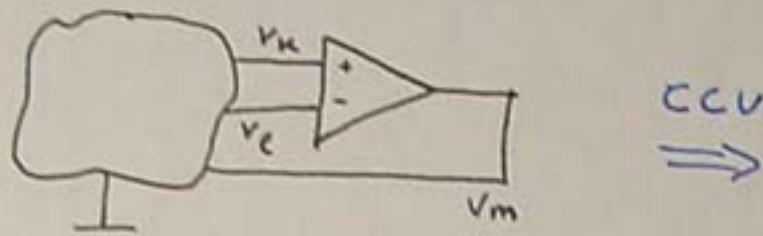
\Rightarrow Para analizar bien se sol aplicar KCL en los nodos de tensión desconocidos.

$$i = i_3 + i_4$$

$$\frac{0 - V_1}{R_1} + \frac{V_{S1} - V_1}{R_2} = \frac{V_1 + V_{S2} - V_{S1}}{R_3} + \frac{V_1 + V_{S2} - 0}{R_4} \quad \left. \begin{array}{l} \\ \text{Añadir } V_1 \end{array} \right\}$$

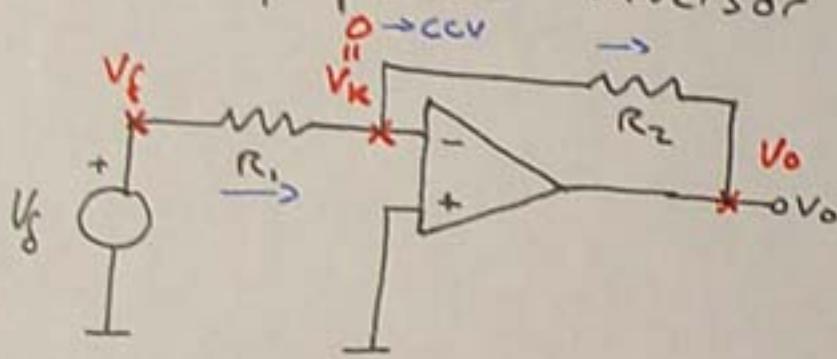
- Método nodal i A.O. :

(Zona lineal)



$$V_K = V_L \Rightarrow \text{Nótese } 2 \text{ incógnitas}$$

Ex: Amplificador inversor



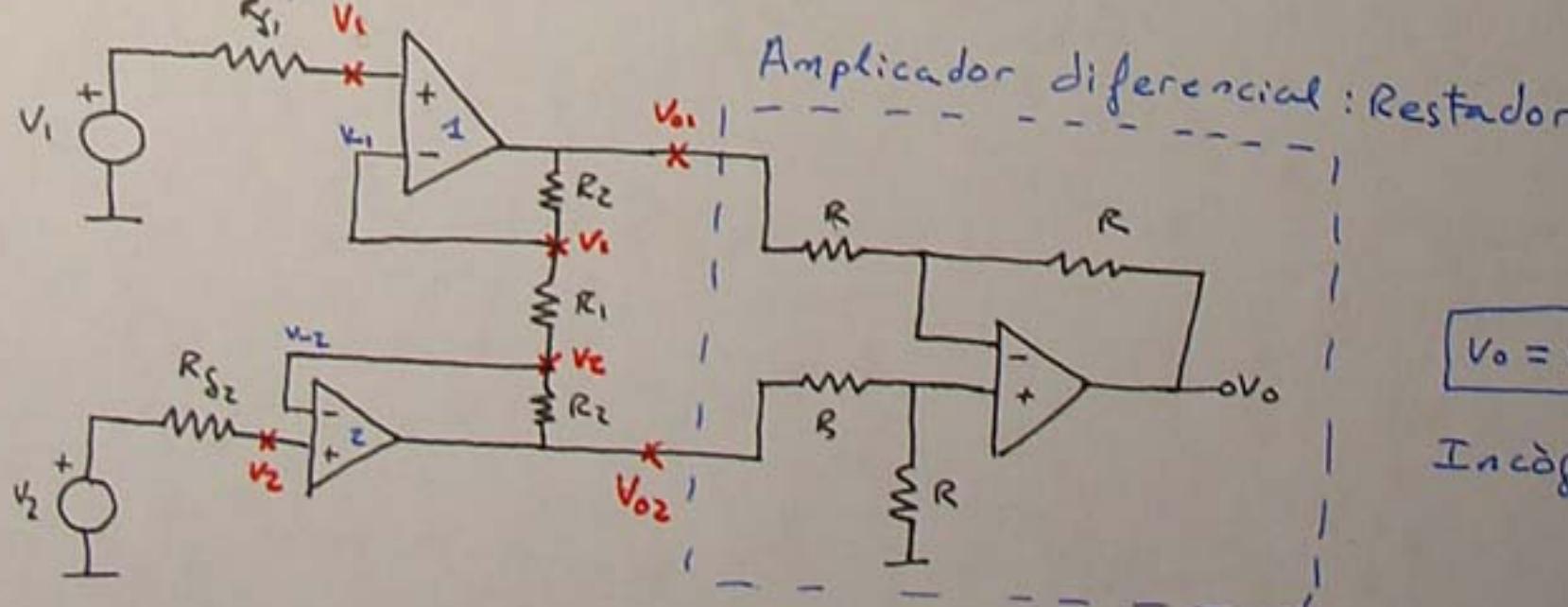
$$V_K \quad \frac{V_f - V_K}{R_1} = \frac{V_K - V_o}{R_2}$$

$$\frac{V_f}{R_1} = \frac{-V_o}{R_2} \Rightarrow \boxed{V_o = -V_f \frac{R_2}{R_1}}$$

PROBLEMA T4

(P11)

Recorda que no pasa corriente



$$\boxed{V_o = V_{o2} - V_{o1}}$$

Incógnitas V_{o1} e V_{o2}

KCL

$$V_{-1}) \quad \frac{V_{o1} - V_1}{R_2} = \frac{V_1 - V_2}{R_1} \quad \left. \begin{array}{l} \\ V_{o1} \end{array} \right\}$$

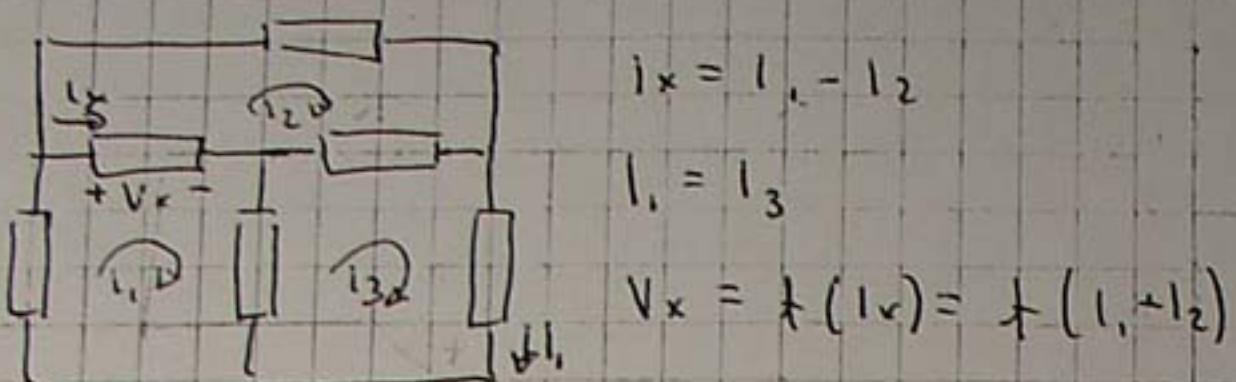
$$\frac{V_1 - V_2}{R_1} = \frac{V_2 - V_{o2}}{R_2} \quad \left. \begin{array}{l} \\ V_{o2} \end{array} \right\}$$

$$V_{o1} = V_1 \left(\frac{R_2}{R_1} + R_2 \right) - V_2 \frac{R_2}{R_1}$$

$$V_{o2} = V_1 \left(-\frac{R_2}{R_1} \right) + V_2 \left(\frac{R_2}{R_1} + R_2 \right)$$

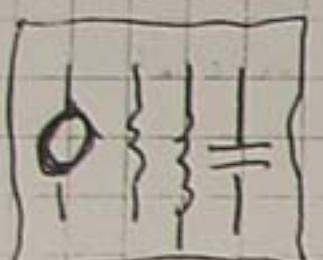
Mètode dels corrents de malla.

Baix generadora \rightarrow corrents de malla



Mètode aplicable només a circuits plans

cas General



m mallas \Rightarrow m corrents de mallas \Rightarrow

m equacions aplicant KVL

Expressar les tensions en funció dels corrents.

$$\Sigma(z) \cdot I(s) = V(s)$$

b

imatge de impedàncies

$$Z(s) = \begin{bmatrix} Z_{11}(s) & \dots & Z_{1m}(s) \\ \vdots & \ddots & \vdots \\ Z_{m1}(s) & \dots & Z_{mm}(s) \end{bmatrix}$$

$Z_{kk}(s)$ = Suma de impedàncies que treben al recorrer la malla n^o k

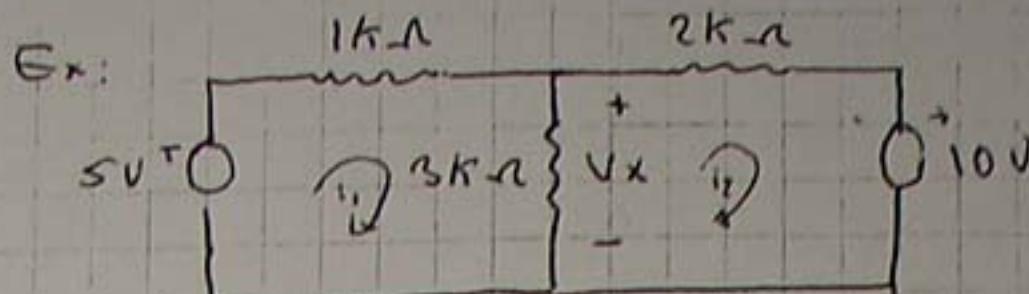
$Z_{kl}(s)$ = -Σ impedàncies compartides entre les mallas k y l

Vector de corrents $I(s) = \begin{bmatrix} I_{k1} \\ \vdots \\ I_{km} \end{bmatrix}$...

I_k = corrent de malla k

Vector de tensions $V(s) = \begin{bmatrix} V_{k1} \\ \vdots \\ V_{km} \end{bmatrix}$

V_k = Σ tensions amb polaritat creixent, provenents de generadores tensió independents



Calcula V_x pel mètode de mallas

$$\begin{bmatrix} 4 & -3 \\ -3 & 5 \end{bmatrix} \begin{bmatrix} i_1 \\ i_2 \end{bmatrix} = \begin{bmatrix} 5 \\ -10 \end{bmatrix}$$

$\begin{matrix} 1 & 3 \\ K & R \\ 2 & 3 \end{matrix}$

$$\left. \begin{aligned} i_1 &= \frac{5 - 3}{11} = -0.18 \text{ mA} \\ i_2 &= \frac{-25}{11} = -2.27 \text{ mA} \end{aligned} \right\}$$

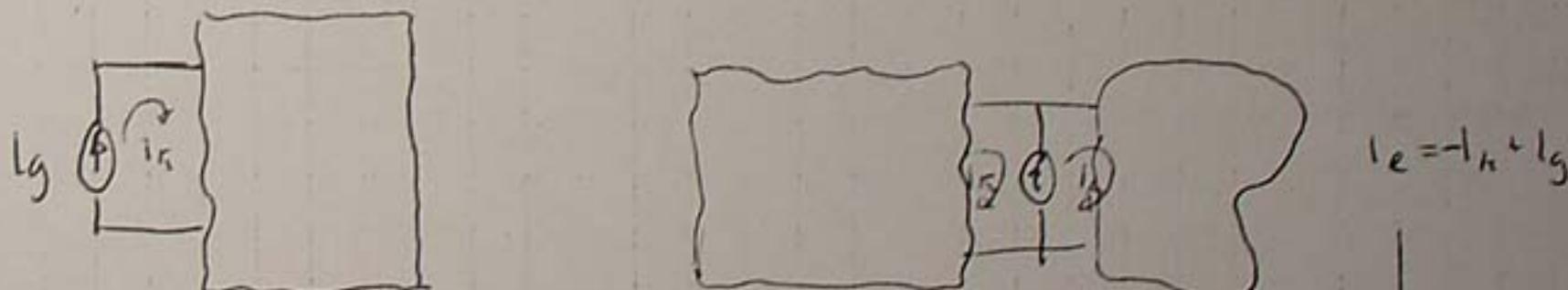
$$V_x = 3(i_1 - i_2) = 3(-0.18 + 2.27) = 5.45 \text{ V}$$

- Mètode de mallas amb fonts de tensió controlades.

Idem mètode de nodes

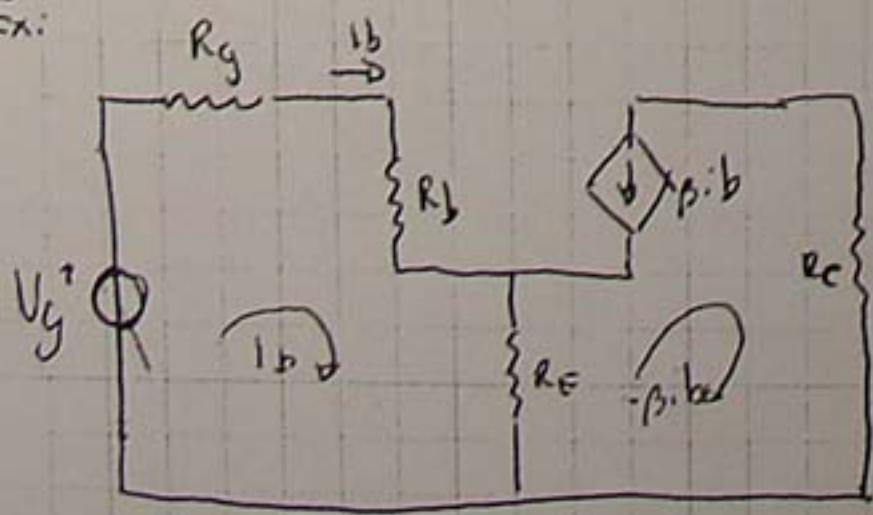
Construir sist. \Rightarrow Reagrupar variables
equacions directament (corrents de malla)

- Mètode de mallas amb fonts de corrents



$$I_K = I_g \Rightarrow 1 \text{ incògnita menys} \Rightarrow 1 \text{ KVL menys}$$

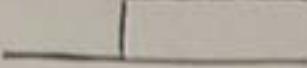
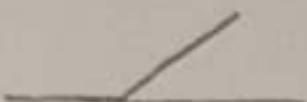
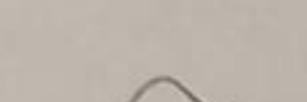
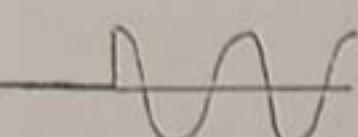
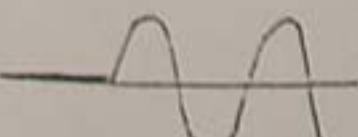
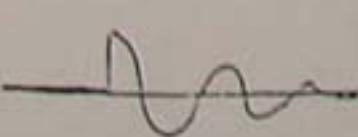
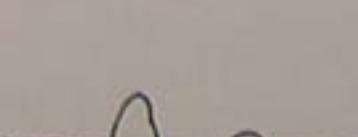
Ex:

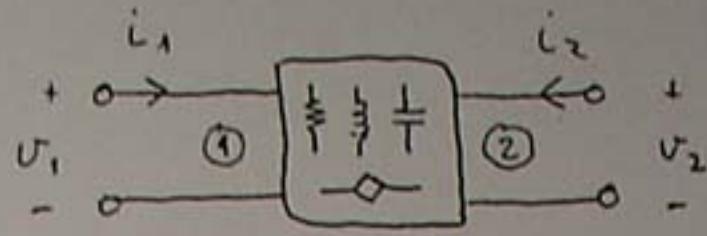


$$\begin{aligned} &+ 2 \text{ mallas} \\ &V_o = ? \quad 1 \text{ incògnita} \rightarrow 1 \text{ ecuació} \\ &\text{KVL } R_g \cdot i_b + R_b \cdot i_b + R_E (\beta + 1) \cdot i_b = V_S \Rightarrow \\ &\Rightarrow [R_g + R_b + R_E (\beta + 1)] \cdot i_b = V_S \end{aligned}$$

$$i_b = \frac{V_S}{R_g + R_b + R_E (\beta + 1)} \Rightarrow V_o = i_b \cdot R_E$$

TAULA DE TRANSFORMADES BÀSIQUES

	$U(t)$	$V(s)$
De Ptm de Dirac		$\delta(t)$
esglao unitari		$U(t)$
Rampa		$t U(t)$
exponencial		$e^{-at} U(t)$
		$t e^{-at} U(t)$
		$\cos \omega_0 t U(t)$
		$\sin \omega_0 t U(t)$
		$e^{-at} \cos \omega_0 t U(t)$
		$e^{-at} \sin \omega_0 t U(t)$



→ 6 maneres de caracteritzar un biport:

Paràmetres

Forma matricial

IMPEDÀNCIA

$$\begin{bmatrix} V_1(s) \\ V_2(s) \end{bmatrix} = \underline{\underline{Z}}(s) \begin{bmatrix} I_1(s) \\ I_2(s) \end{bmatrix}$$

ADMITÀNCIA

$$\begin{bmatrix} I_1(s) \\ I_2(s) \end{bmatrix} = \underline{\underline{Y}}(s) \begin{bmatrix} V_1(s) \\ V_2(s) \end{bmatrix} \quad \underline{\underline{Y}}(s) = \underline{\underline{Z}}^{-1}(s)$$

HÍBRIDS - 1

$$\begin{bmatrix} V_1(s) \\ I_2(s) \end{bmatrix} = \underline{\underline{H}}(s) \begin{bmatrix} I_1(s) \\ V_2(s) \end{bmatrix}$$

HÍBRIDS - 2

$$\begin{bmatrix} I_1(s) \\ V_2(s) \end{bmatrix} = \underline{\underline{H}}'(s) \begin{bmatrix} V_1(s) \\ I_2(s) \end{bmatrix} \quad \underline{\underline{H}}'(s) = \underline{\underline{H}}^{-1}(s)$$

TRANSMISSIÓ - 1

$$\begin{bmatrix} V_1(s) \\ I_1(s) \end{bmatrix} = \underline{\underline{T}}(s) \begin{bmatrix} V_2(s) \\ -I_2(s) \end{bmatrix}$$

TRANSMISSIÓ - 2

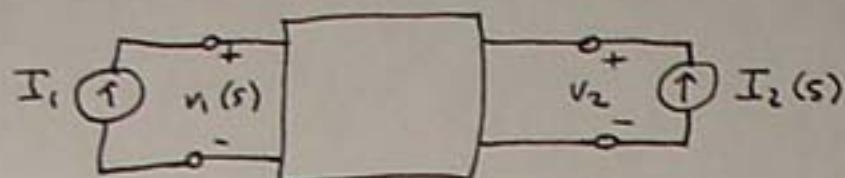
$$\begin{bmatrix} V_2(s) \\ -I_2(s) \end{bmatrix} = \underline{\underline{T}}'(s) \begin{bmatrix} V_1(s) \\ I_1(s) \end{bmatrix} \quad \underline{\underline{T}}'(s) = \underline{\underline{T}}^{-1}(s)$$

BIPOTS:

4 terminals, 2 parts.

{ L }

Superposició:

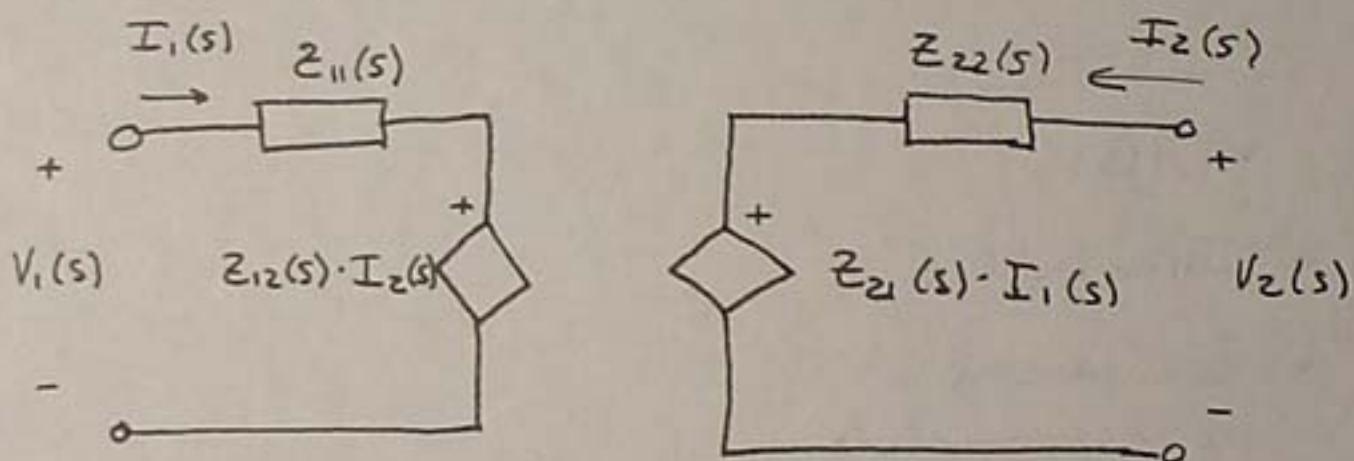


$$V_1(s) = Z_{11}(s) \cdot I_1(s) + Z_{12}(s) \cdot I_2(s)$$

$$V_2(s) = Z_{21}(s) \cdot I_1(s) + Z_{22}(s) \cdot I_2(s)$$

$$\begin{bmatrix} V_1(s) \\ V_2(s) \end{bmatrix} = \begin{bmatrix} Z_{11}(s) & Z_{12}(s) \\ Z_{21}(s) & Z_{22}(s) \end{bmatrix} \begin{bmatrix} I_1(s) \\ I_2(s) \end{bmatrix}$$

$$V(s) = \underline{Z}(s) \cdot \underline{I}(s)$$

Matriu de paràmetres Z (impedancia)Model equivalent:Interpretació física dels paràmetres Z :

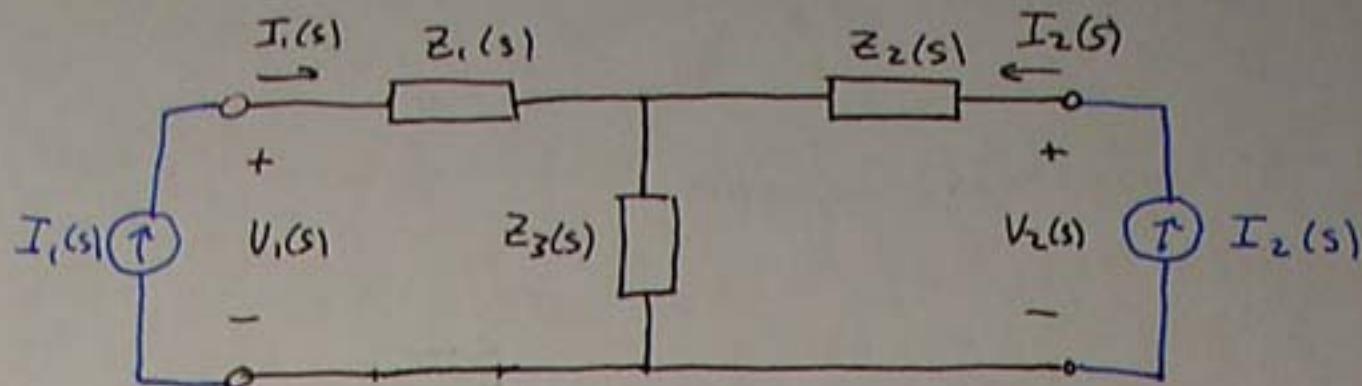
$$Z_{11}(s) = \left. \frac{V_1(s)}{I_1(s)} \right|_{I_2(s)=0}$$

$$Z_{22}(s) = \left. \frac{V_2(s)}{I_2(s)} \right|_{I_1(s)=0}$$

$$Z_{12}(s) = \left. \frac{V_1(s)}{I_2(s)} \right|_{I_1(s)=0}$$

$$Z_{21}(s) = \left. \frac{V_2(s)}{I_1(s)} \right|_{I_2(s)=0}$$

Ex:



Matríg d'impedàncies.

$$V_1(s) = I_1(s) \cdot Z_1(s) + Z_3(s) (I_1(s) + I_2(s))$$

$$V_2(s) = I_2(s) \cdot Z_2(s) + Z_3(s) (I_1(s) + I_2(s))$$

$$\begin{bmatrix} V_1(s) \\ V_2(s) \end{bmatrix} = \begin{bmatrix} Z_1(s) + Z_3(s) & Z_3(s) \\ Z_3(s) & Z_2(s) + Z_3(s) \end{bmatrix} \begin{bmatrix} I_1(s) \\ I_2(s) \end{bmatrix}$$

EXÀMEN DEL 5-II-03 :

1

Resistius

- * $H(s) = K$ tant
- * Estables
- * Resposta combinació lineal de l'excitació
- * Sistema d'eq. algebraics
- * Resp. lliure

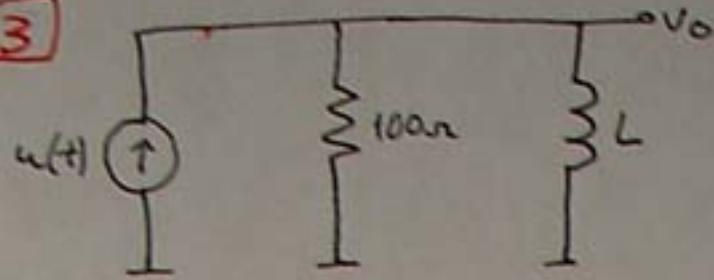
Dinàmics

- * $H(s)$
- * Inestables
- * En general no es compleix
- * Sistema d'equacions integrodiferencials.
- * Resp. lliure + Forçada

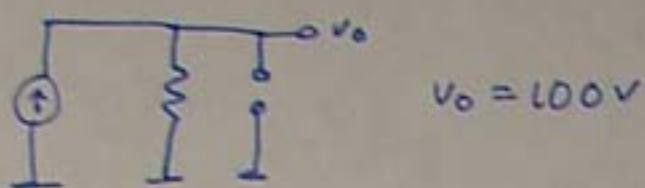
2

$$\mathcal{L}\{10 \cdot \cos 4t \cdot u(t)\} = \frac{10s}{s^2 + 16}$$

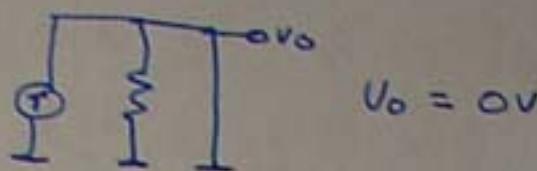
$$N(s) = K(s^2 + 16)$$

3

$$L = ? \quad v_o(L) > 50 \quad \approx 10\text{ms}$$

36 $t=0$ 

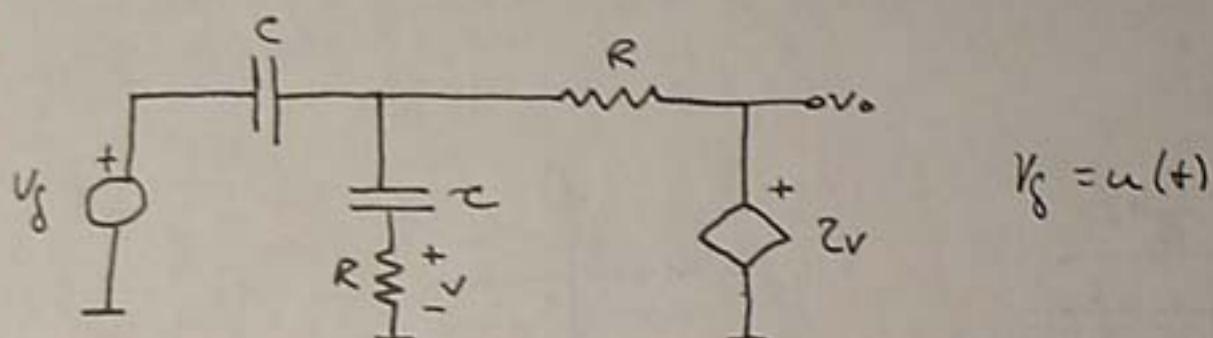
$$v_o = 100\text{V}$$

 $t=\infty$ 

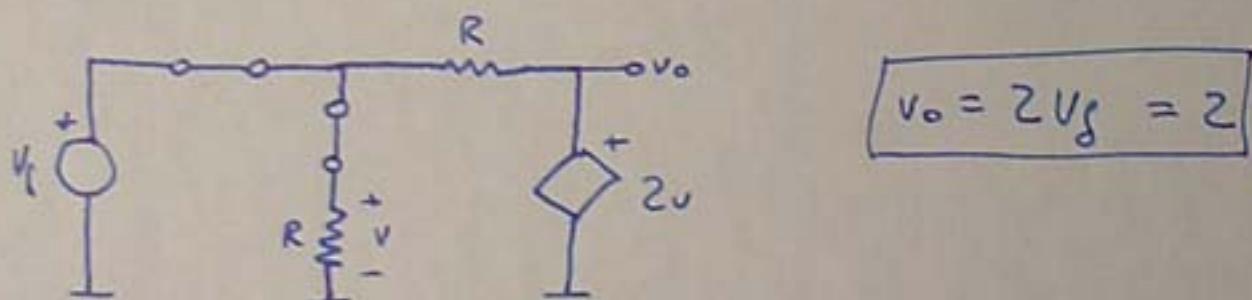
$$v_o = 0\text{V}$$

$$v_o(t) = 100 e^{-\frac{Rt}{L}} \cdot u(t) = 100 \cdot e^{-\frac{100t}{L}} \cdot u(t)$$

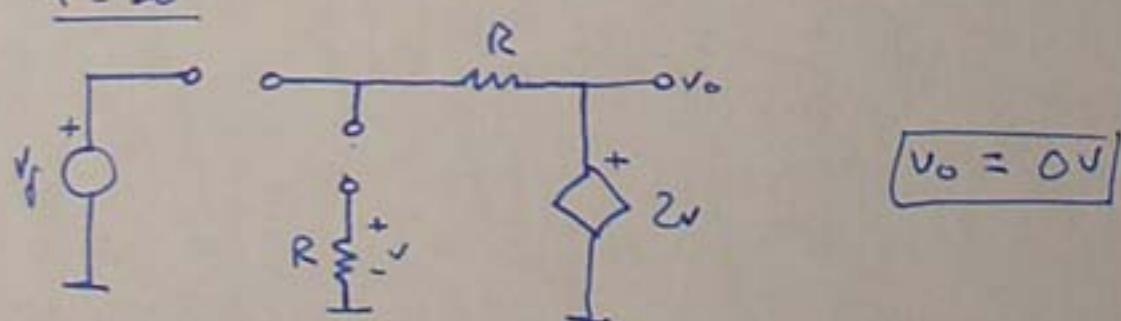
$$\boxed{L = 1.94\text{H}}$$

5

$$v_g = u(t)$$

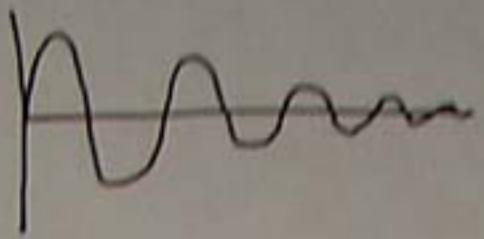
 $t=0$ 

$$\boxed{v_o = 2v_g = 2}$$

 $t=\infty$ 

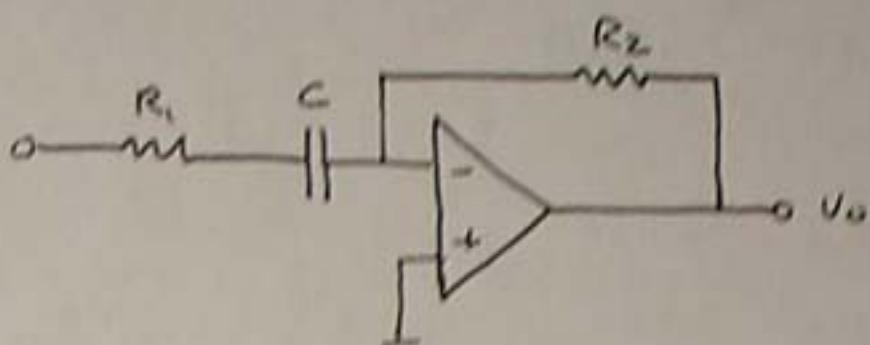
$$\boxed{v_o = 0\text{V}}$$

5



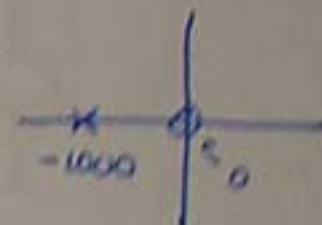
- 2º ordre, pols complexes, subesmorteit
- Estable
- $H(0) = 0 \quad * \quad z = N(s)$
- $H(\infty) = 0 \quad * \quad D(s) \text{ comenja amb } s^2$

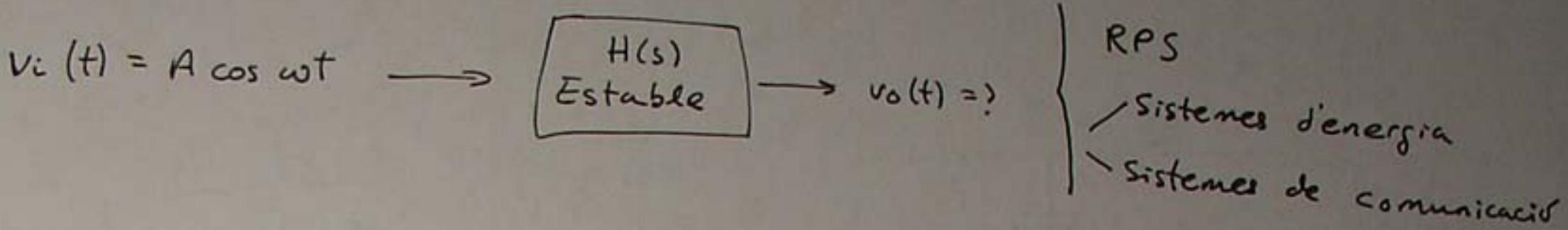
6



Amplificador inversor:

$$H(s) = - \frac{R_2}{R_1 + \frac{1}{Cs}} = - \frac{\frac{R_2 s}{R_1}}{s + \frac{1}{R_1 C}}$$



TEMA 6:RÈGIM PERMANENT SINUSOIDAL:

$$v_o(s) = H(s) \cdot v_i(s) = H(s) \cdot \frac{As}{s^2 + \omega^2}$$

$$v_o(t) = \mathcal{L}^{-1} \left\{ H(s) \cdot v_i(s) \right\} = \mathcal{L}^{-1} \left\{ \underbrace{\frac{K_1}{s-p_1} + \dots + \frac{K_n}{s-p_n}}_{U_{line}} + \underbrace{\frac{K}{s-j\omega} + \frac{K^*}{s+j\omega}}_{Forçada} \right\}$$

** La part lineal s'usa en PK estem < RPS ($t = \infty$)*

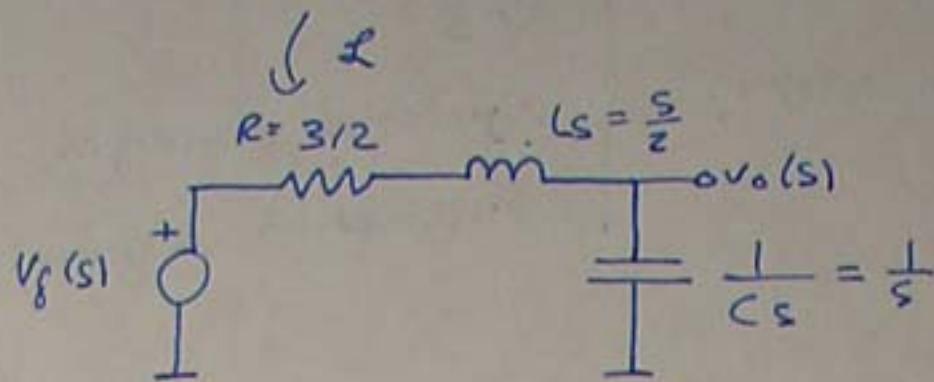
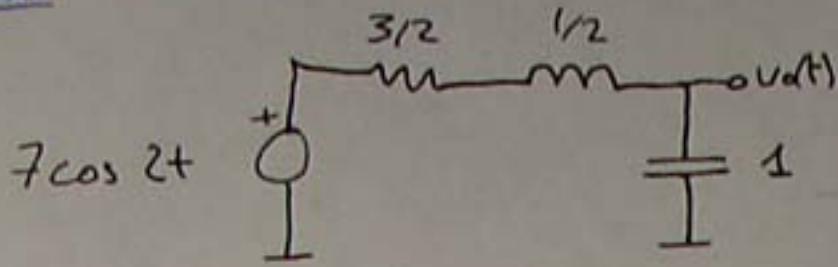
$$\begin{aligned} K &= \left[H(s) \cdot v_i(s) \cdot (s - j\omega) \right]_{s=j\omega} = \left[H(s) \cdot \frac{As}{s^2 + \omega^2} (s - j\omega) \right]_{s=j\omega} = \\ &= \left[\frac{H(s) \cdot As}{s + j\omega} \right]_{s=j\omega} = \frac{H(j\omega) \cdot A_j \omega}{2j\omega} = \frac{A}{2} H(j\omega) = \frac{A}{2} |H(j\omega)| \cdot e^{j \arg(H(j\omega))} \end{aligned}$$

$$v_o(t) = \mathcal{L}^{-1} \left\{ \frac{K}{s-j\omega} + \frac{K^*}{s+j\omega} \right\} = 2 \cdot \frac{A}{2} \left| H(j\omega) \right| e^{j\omega t} \cdot \cos(\omega t + \arg(H(j\omega)))$$

$v_o(t) = A \cdot |H(j\omega)| \cdot \cos(\omega t + \arg H(j\omega))$

- mateixa freq. que $v_i(t)$
- sinusoidal
- canvia amplitud i fase

E_{K2}



$$1) \quad H(s) = \frac{V_o(s)}{V_f(s)} = \frac{\frac{1}{s}}{\frac{3}{2} + \frac{5}{2} + \frac{1}{s}} = \frac{2}{s^2 + 3s + 2}$$

$$2) \quad |H(j\omega)|, \arg(H(j\omega))$$

$$\omega = 2$$

$$H(z_j) = \frac{2}{(z_j)^2 + 3z_j + 2} = \frac{2}{-4 + 6j + 2} = \frac{2}{-2 + 6j} = \frac{1}{-1 + 3j} = \\ = \frac{1}{\sqrt{10}} e^{j \operatorname{arctg}(-3)}$$

$$v_o(t) = \frac{7}{\sqrt{10}} \cos(2t - \operatorname{arctg}(-3))$$

REPRESENTACIÓ FASORIAL:

$$v(t) = A \cos(\omega t + \phi)$$

$$v(t) = A \cos(\omega t + \phi) = \operatorname{Re} [A e^{j(\omega t + \phi)}] = \operatorname{Re} [\underbrace{A e^{j\phi}}_{\bar{V}} \cdot e^{j\omega t}] = \operatorname{Re} [\bar{V} e^{j\omega t}]$$

Fasor associat a $v(t)$

$$\bar{V} \cong A e^{j\phi}$$

1) Representació "compacta"

2) Suma de senyals sinusoidals

$$v_s(t) = v_1(t) + v_2(t) = A_1 \cos(\omega t + \phi_1) + A_2 \cos(\omega t + \phi_2) = \textcircled{4}$$

$$\textcircled{4} = \operatorname{Re} \left[\underbrace{A_1 e^{j\phi_1}}_{\bar{V}_1} \cdot e^{j\omega t} \right] + \operatorname{Re} \left[\underbrace{A_2 e^{j\phi_2}}_{\bar{V}_2} \cdot e^{j\omega t} \right] = \operatorname{Re} \left[(\bar{V}_1 + \bar{V}_2) e^{j\omega t} \right]$$

$$\bar{V}_s = \bar{V}_1 + \bar{V}_2$$

$$v_s(t) = |\bar{V}_s| \cdot \cos(\omega t + \arg \bar{V}_s)$$

3)

$$v_i(t) = A \cos(\omega t + \phi) \rightarrow \boxed{\begin{matrix} H(s) \\ \text{ESTABLE} \end{matrix}} \rightarrow v_o(t) = A |H(j\omega)| \cdot \cos(\omega t + \phi + \arg H(j\omega))$$

$$\bar{V}_i = A e^{j\phi}$$

$$\bar{V}_o = e^{j\phi} A |H(j\omega)| \cdot e^{j\arg H(j\omega)}$$

$$\bar{V}_o = \bar{V}_i \cdot H(j\omega)$$

$$V_o(s) = H(s) \cdot V_i(s)$$

SIMILITUD

CIRCUIT TRANSFORMAT FASORIAL:

CONNEXIONS:

KVL

$$\sum_k v_k(t) = 0 \xrightarrow{\text{RPS}} \sum_k A_k \cos(\omega t + \phi_k) = \operatorname{Re} \left[\sum_k A_k e^{j\phi_k} e^{j\omega t} \right] =$$

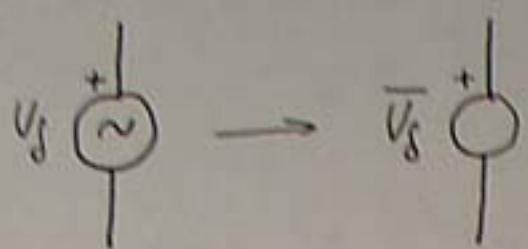
$$= \operatorname{Re} \left[\left(\sum_k \bar{V}_k \right) e^{j\omega t} \right] = 0 \Rightarrow \boxed{\sum_k \bar{V}_k = 0}$$

Fasors compleixens
Kirtchoff

KCL

$$\boxed{\sum_k \bar{I}_k = 0}$$

ELEMENTS:



El mateix per:
 - Fonts de corrent
 - Fonts controlades

$$\begin{array}{c} \left. \begin{array}{l} \downarrow i \\ R \\ \uparrow v \\ \downarrow - \end{array} \right\} \\ v = iR \end{array} \xrightarrow{\mathcal{L}} V(s) = \underbrace{R \cdot I(s)}_{H(s)} \xrightarrow{RPS} \boxed{\bar{V} = R \cdot \bar{I}}$$

$$\begin{array}{c} \left. \begin{array}{l} \downarrow i \\ L \\ \uparrow v \\ \downarrow - \end{array} \right\} \\ v = L \frac{di}{dt} \end{array} \xrightarrow{\mathcal{L}} V(s) = \underbrace{Ls \cdot I(s)}_{H(s)} \xrightarrow{RPS} \boxed{\bar{V} = jL\omega \cdot \bar{I}}$$

$$\boxed{Z = \frac{\bar{V}}{\bar{I}} = jL\omega}$$

Ex:

$$\bar{I} = A e^{j\phi} \Rightarrow \bar{V} = j\omega L \cdot A \cdot e^{j\phi} = AL\omega \cdot e^{j\frac{\pi}{2}} \cdot e^{j\phi} = AL\omega \cdot e^{j(\phi + \frac{\pi}{2})}$$

- * La impedància creix amb ω
 - $\rightarrow \omega=0 \rightarrow Z=0$ circuit
 - $\rightarrow \omega=\infty \rightarrow Z=\infty$ circuit obert
- * Adelanta la tensió $\frac{\pi}{2}$ respecte del corrent

$$\begin{array}{c} \left. \begin{array}{l} \downarrow i \\ C \\ \uparrow v \\ \downarrow - \end{array} \right\} \\ v = \frac{1}{C} \int i(t) dt \end{array} \xrightarrow{\mathcal{L}} V(s) = \frac{I(s)}{Cs} \xrightarrow{RPS} \boxed{\bar{V} = \frac{1}{jC\omega} \cdot \bar{I}}$$

$$\boxed{Z = \frac{\bar{V}}{\bar{I}} = \frac{1}{j\omega C}}$$

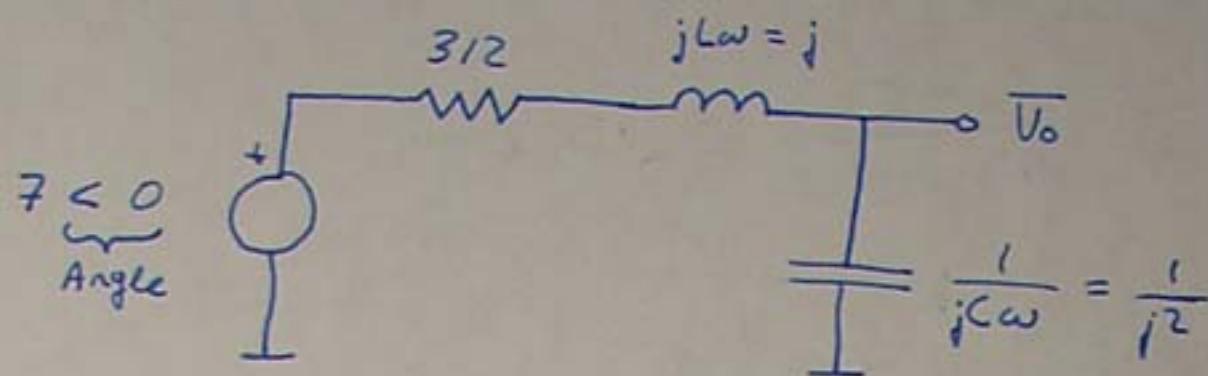
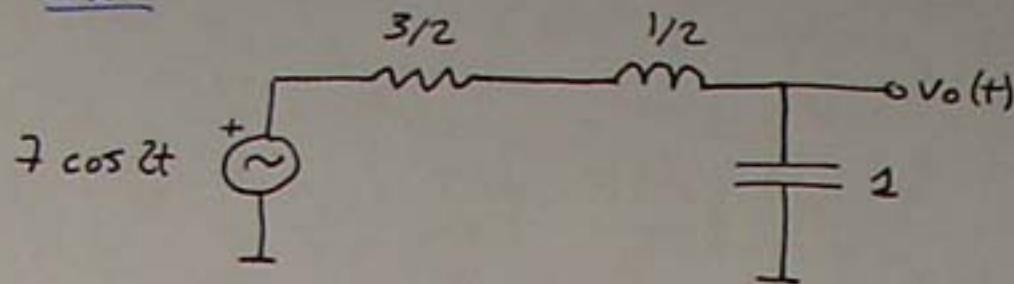
Ex:

$$\bar{I} = A e^{j\phi} \Rightarrow \bar{V} = \frac{1}{j\omega C} A e^{j\phi} = \frac{A}{\omega C} e^{j\frac{\pi}{2}} \cdot e^{j\phi} = \frac{A}{\omega C} e^{j(\phi - \frac{\pi}{2})}$$

- * La impedància disminueix amb ω
 - $\rightarrow \omega=0 \rightarrow Z=\infty$ circuit obert
 - $\rightarrow \omega=\infty \rightarrow Z=0$ curt circuit
- * Retarda la tensió $\frac{\pi}{2}$ respecte del corrent

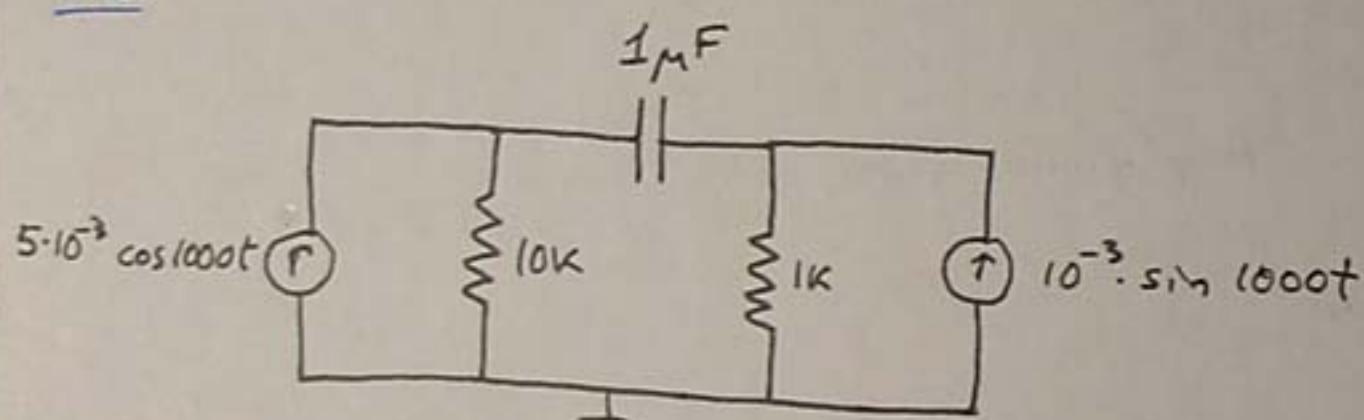
Ex:

Z	f
$16M\Omega$	$1KHz$
16Ω	$1Ghz$

Ex:

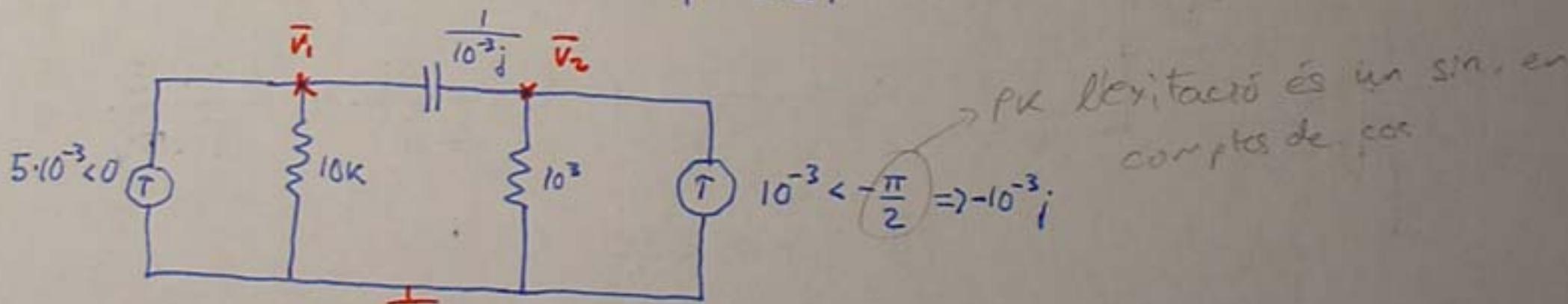
$$\begin{aligned}\bar{V}_o &= 7 \frac{\frac{1}{j^2}}{\frac{1}{j^2} + \frac{3}{2} + j} = \\ &= \frac{7}{1 + 3j - 2} = \frac{7}{-1 + 3j} = \frac{7 \cos 1'9}{\sqrt{10} < 1'9} \\ &= \frac{7}{\sqrt{10}} < -1'9 \text{ radians}\end{aligned}$$

$$V(t) = \frac{7}{\sqrt{10}} \cos(2t - 1'9)$$

Ex:

Determine les tensions nodals:

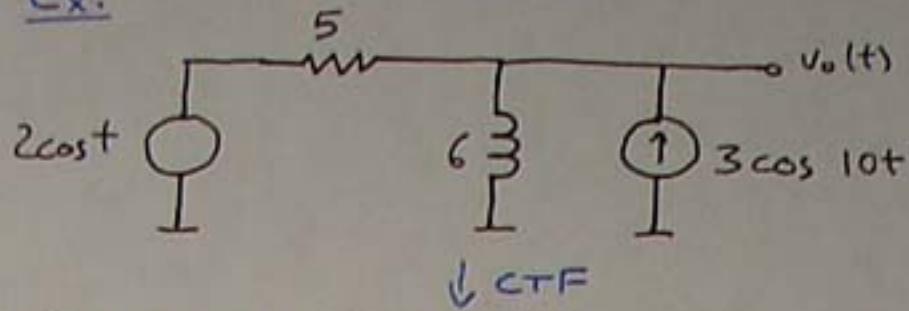
CTF (Circuit transformat fàsorial)



$$\begin{bmatrix} 10^{-4} + 10^{-3}j & -10^{-3}j \\ -10^{-3}j & 10^{-3} + 10^{-3}j \end{bmatrix} \begin{bmatrix} \bar{V}_1 \\ \bar{V}_2 \end{bmatrix} = \begin{bmatrix} 5 \cdot 10^{-3} \\ -10^{-3}j \end{bmatrix}$$

$\bar{V}_1 = 7'07 < -0'79$
$\bar{V}_2 = 4'53 < -0'11$

Ex:

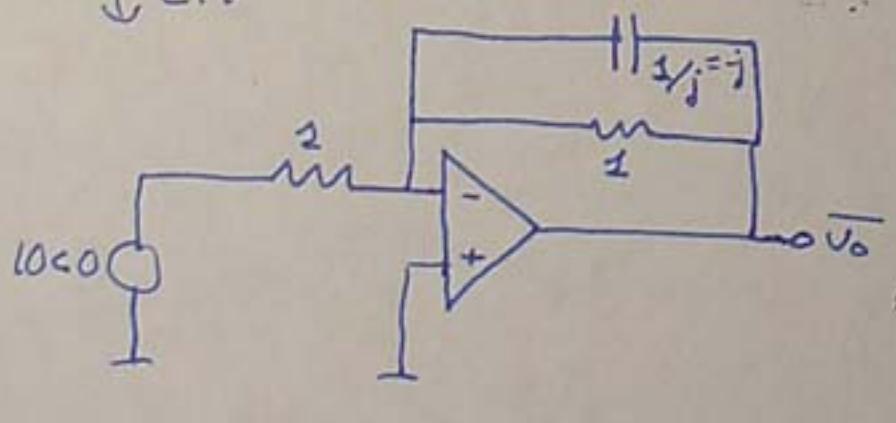
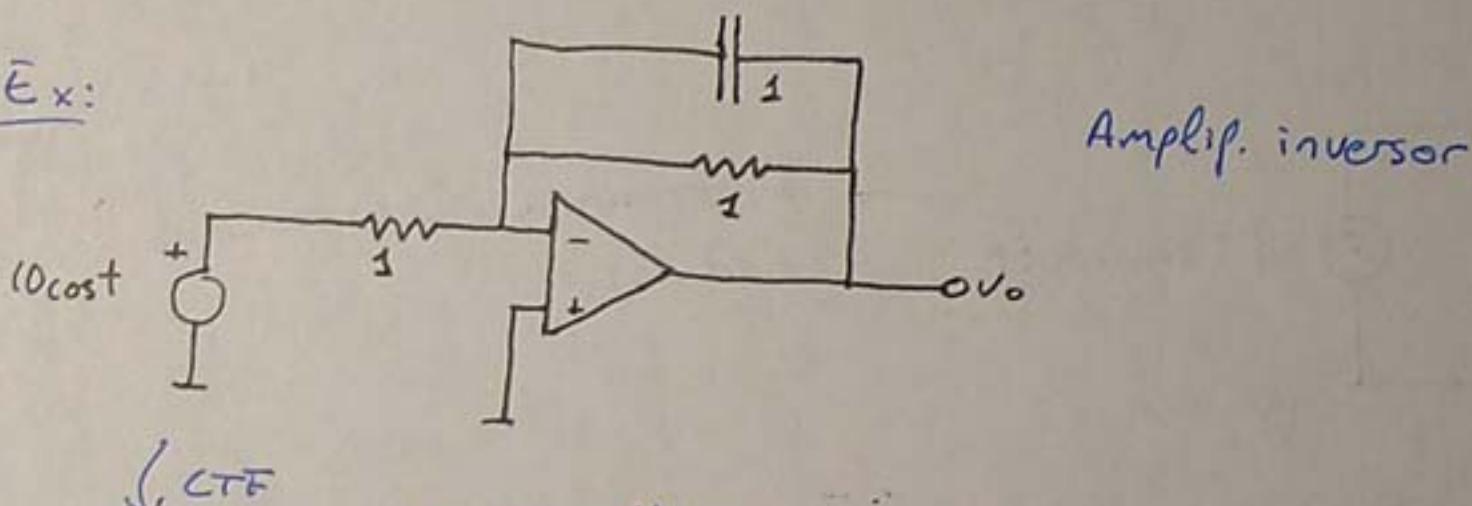


Superposition:

$$\begin{aligned} & \text{Circuit for } 2\cos(t): \quad \text{Output } \bar{V}_{o1} = \frac{6j}{5+6j} \cdot 2 = \frac{12 \angle \frac{\pi}{2}}{7'81 \angle 0'88} = 1'54 \angle 0'69 \\ & \text{Circuit for } 3\cos(10t): \quad \text{Output } \bar{V}_{o2} = 3 \frac{4j \cdot 5}{5+6j} = \frac{500 \angle \frac{\pi}{2}}{60'2 \angle 8'49} = 14'9 \angle 0'08 \end{aligned}$$

$$u_o(t) = 1'54 \cdot \cos(t + 0'69) + 14'9 \cdot \cos(10t + 0'08)$$

Ex:



$$\begin{aligned} \bar{V}_o &= -\frac{-j}{1-j} 10 = \frac{10j}{1-j} = \frac{10 \angle \frac{\pi}{2}}{\sqrt{2} \angle 45^\circ} \\ \bar{V}_o &= 7'07 \angle \frac{3\pi}{4} \end{aligned}$$

$$u_o(t) = 7'07 \cdot \cos\left(t + \frac{3\pi}{4}\right)$$

Titulació

Assignatura

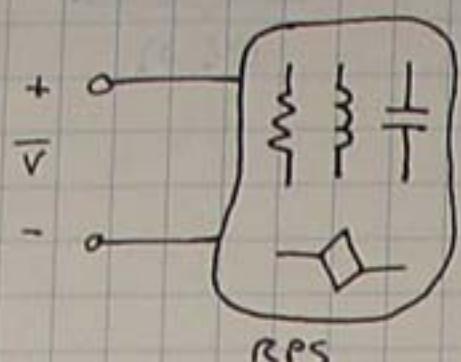
SERRA LÓPEZ

Cognoms

MARIUS

Nom

Pàgina 40 de

IMMITÀNCIES FASORIALS:IMPEDÀNCIA:

$$Z(j\omega) = \frac{\bar{V}}{\bar{I}} = R(\omega) + jX(\omega) \quad (\omega)$$

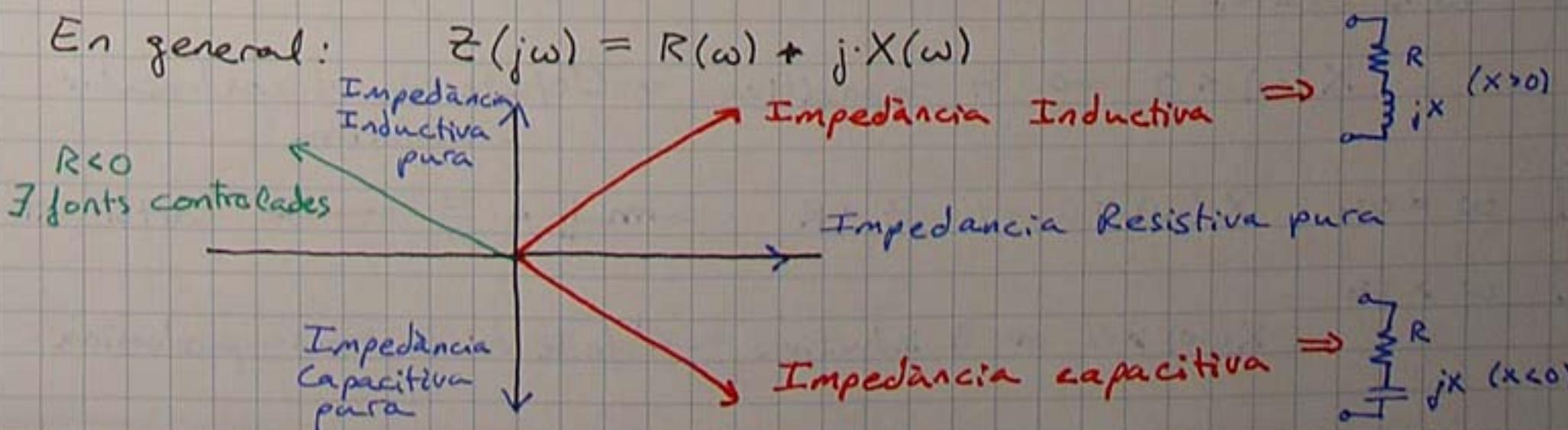
↑ ↑
Resistència Reactància

ADMITÀNCIA:

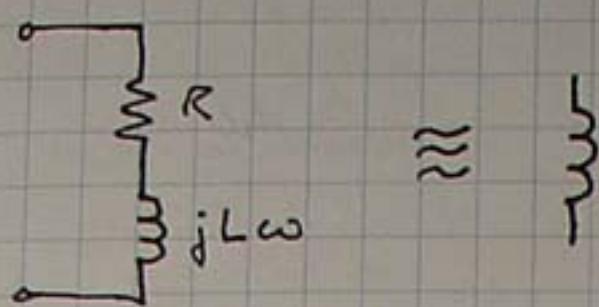
$$Y(j\omega) = \frac{\bar{I}}{\bar{V}} = \frac{1}{Z(\omega)} = G(\omega) + jB(\omega) \quad (\omega)$$

↑ ↑
Conductància Susceptància

Element	$Z(\omega_j)$	$Y(\omega_j)$
	R	$\frac{1}{R}$
	$jL\omega$	$\frac{-j}{L\omega}$
	$-\frac{j}{C\omega}$	$jC\omega$



Ex: Model d'una bobina



$$Z(j\omega) = R + jL\omega$$

$$Y(j\omega) = \frac{1}{Z(j\omega)} = \frac{1}{R + jL\omega} =$$

$$= \frac{R - j\omega L}{R^2 + (\omega L)^2} = \frac{R}{R^2 + (\omega L)^2} - j \frac{\omega L}{R^2 + (\omega L)^2}$$

$$G(\omega)$$

$$B(\omega)$$

Factor de qualitat:

$$Q_b \triangleq \frac{L\omega}{R}$$

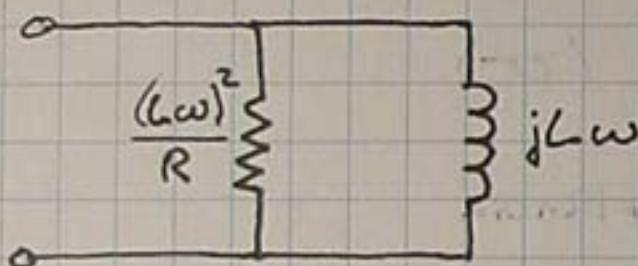
\Rightarrow Si $Q_b \gg 1 \rightarrow (L\omega \gg R)$

$$Y(j\omega) = \frac{R}{(L\omega)^2} - j \frac{1}{L\omega}$$

G_1

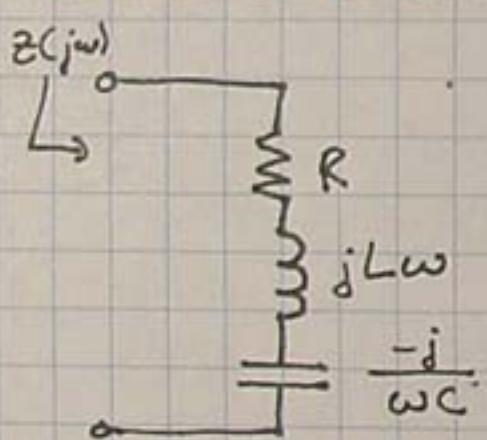
$$G_1 = \frac{R}{(L\omega)^2}$$

$$R_1 = \frac{(L\omega)^2}{R} = Q_b^2 \cdot R$$



$$G_1 = \frac{1}{R_1}$$

RESONÀNCIA:



$$Z(j\omega) = R + j(L\omega - \frac{1}{\omega C})$$

$X(\omega)$

Freq. de resonància fa que: $X(\omega_r) = 0$

$$L\omega_r = \frac{1}{C\omega_r}$$

$$\omega_r = \frac{1}{\sqrt{LC}}$$

→ freqüència de ressonància

CASOS:

1) $\omega < \omega_0 = \omega_r$

$X(\omega) < 0 \Rightarrow Z$ capacitiva → l'efecte de el condensador predomina

2) $\omega = \omega_0 \quad X(\omega) = 0 \Rightarrow Z = R$ $\text{---} \parallel \text{---} \equiv \text{---}$ circuit unit

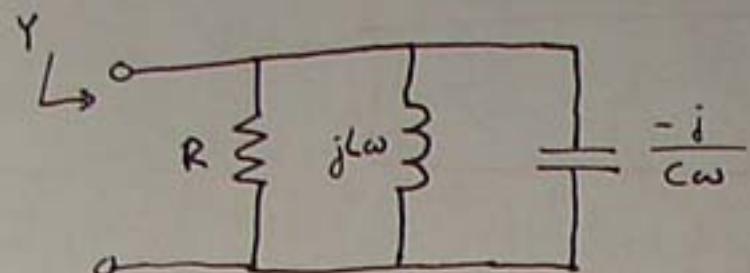
3) $\omega > \omega_0$

$X(\omega) > 0 \Rightarrow Z$ inductiva → l'efecte de la bobina predomina

Ex: Circuit resonant paral·lel

14-11-03

40



$$Y(j\omega) = \frac{1}{R} + \frac{1}{jL\omega} + jC\omega$$

$$Y(j\omega) = \frac{1}{R} + j \left(C\omega - \frac{1}{L\omega} \right)$$

Freq. de ressonància fa que: $B(\omega_r) = 0$

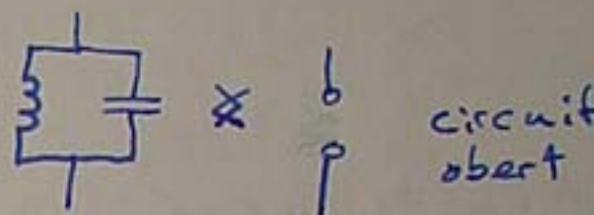
CASOS:

1) $\omega < \omega_r = \omega_0$

$B(\omega) < 0 \Rightarrow Y, Z$ inductiva

2) $\omega = \omega_r$

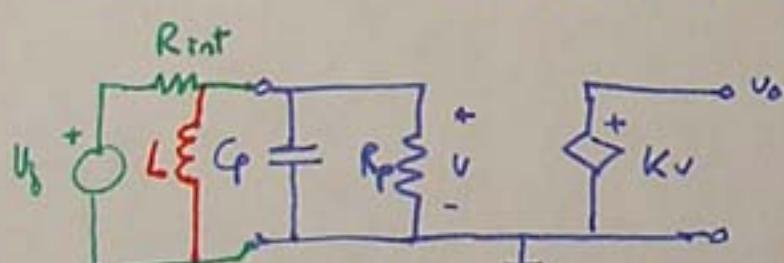
$$B(\omega) = 0 \Rightarrow Y = \frac{1}{R} \quad Z = R$$



3) $\omega > \omega_r$

$B(\omega) > 0 \Rightarrow Y, Z$ capacitiva

Ex: AMPLIFICADOR D'ALTA FREQUÈNCIA



$$\omega \gg 0$$

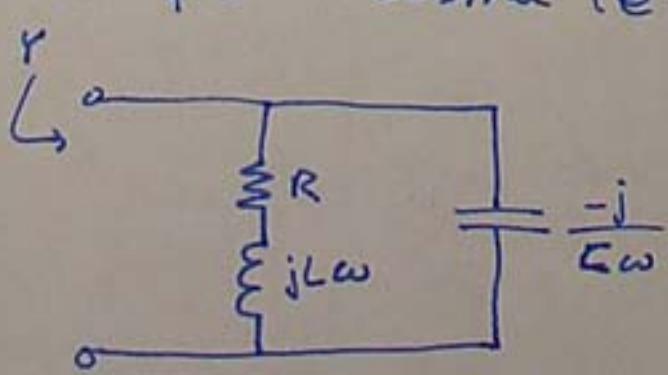
$$\omega \approx \frac{1}{jC_p\omega} \rightarrow 0 \quad / \quad v \rightarrow 0 \quad / \quad u_o \rightarrow 0$$

SOLUCIÓ:

- Si posem una bobina en paral·lel i fem que LC estigui en ressonància per així neutralitzar els dos elements.

Ex:

Com que la bobina té resistència:



$$Y(j\omega) = \frac{1}{R + jL\omega} + jC\omega = \frac{R - jL\omega}{R^2 + (L\omega)^2} + jC\omega$$

$$= \frac{R}{R^2 + (L\omega)^2} + j \left(C\omega - \frac{L\omega}{R^2 + (L\omega)^2} \right)$$

$$B(\omega_r) = 0 \Rightarrow$$

$$\omega_r = \sqrt{\frac{1}{LC} + \left(\frac{R}{L}\right)^2}$$

$$Y(\omega_r) = \frac{RC}{L}$$

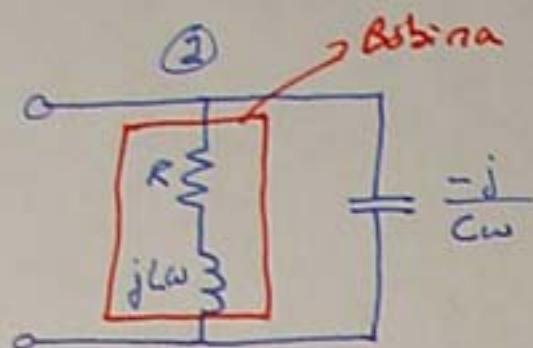
$$Z(\omega_r) = \frac{L}{RC}$$

Pera

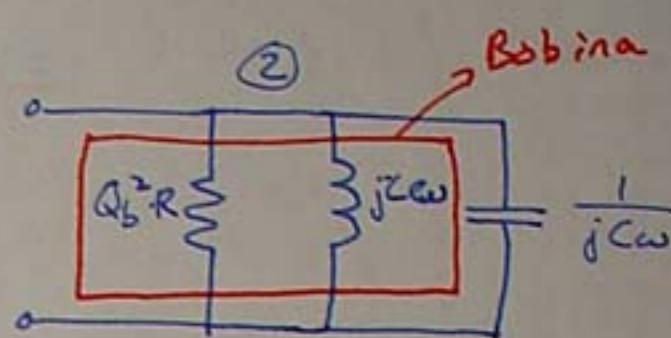
$$Q_b = \frac{L\omega}{R} \gg 1$$

MODEL D'UNA BOBINADA

$$R \cdot Q_b = \frac{C\omega^2}{R}$$



X



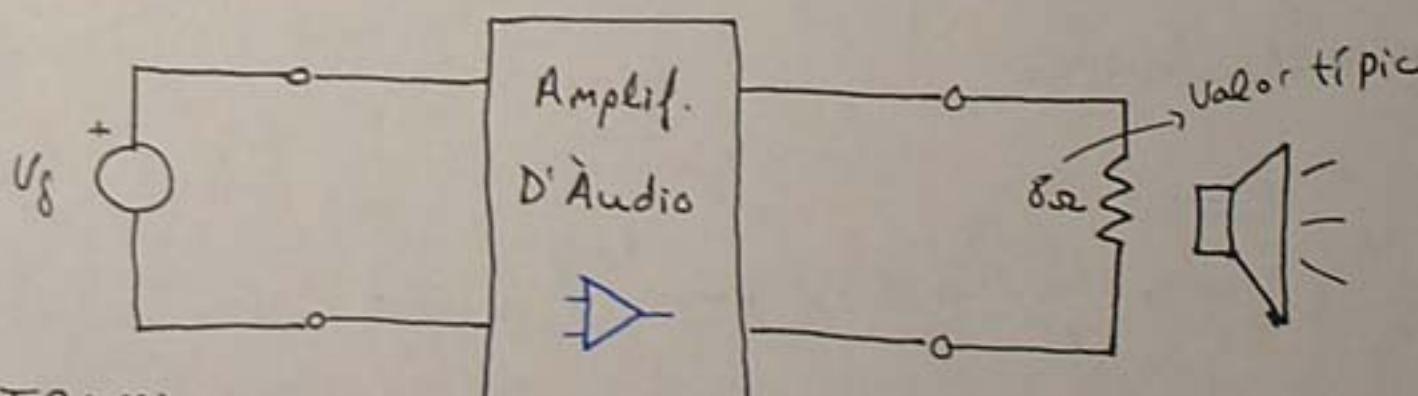
$$\text{A més si } \omega_0 = \omega_r$$

Problemes:
P2, P3, P6

$$\omega_r = \frac{1}{\sqrt{LC}} \Rightarrow Z(j\omega_r) = Q_b^2 \cdot R \quad \begin{cases} \leq Q_b^2 \cdot R \\ \text{Valid per ②} \end{cases}$$

EXEMPLE D'AMPLIFICACIÓ: AMPLIFICADOR D'ÀUDIO

- Senyal d'àudio: senyal capaç de ser captat per l'oïda. Ex: veu, música, etc...
- Amplificador d'àudio: present a (walkman, diskman, reproductor MP3, Hi-Fi...)



TRANSDUCTOR

- Capsa del walkman
- Convertidor A/D
(x → tensió)

TRANSDUCTOR

- Altavoces
(tensió → pressió)

RESTRICCIÓ DE DISSENY:

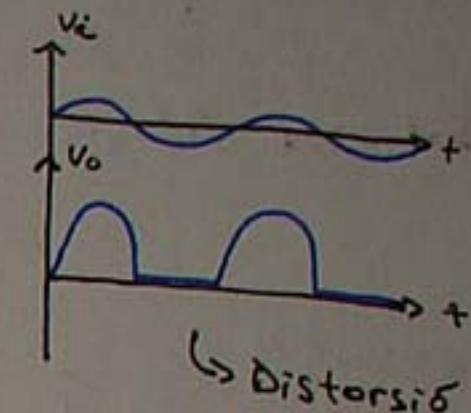
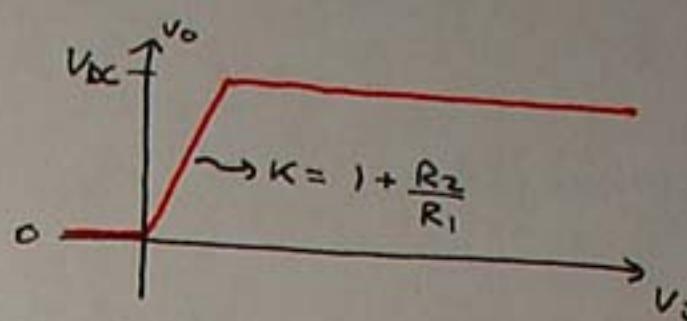
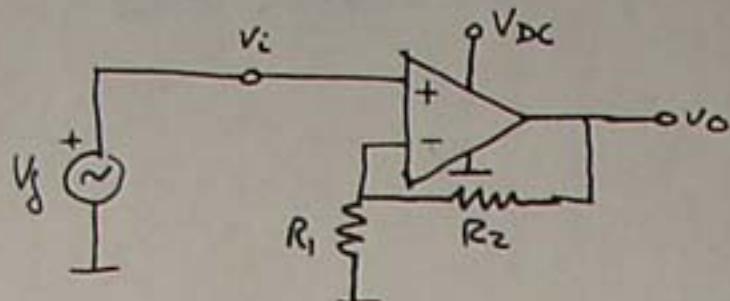
- Ha de ser capaç d'amplificar senyals sinusoidals de freq. entre 15-20Hz i 15-20kHz (freq. audibles).

- Restriccions addicionals (no imprescindible)

Alimentació unipolar \Rightarrow Una única bateria o Font de tensió.

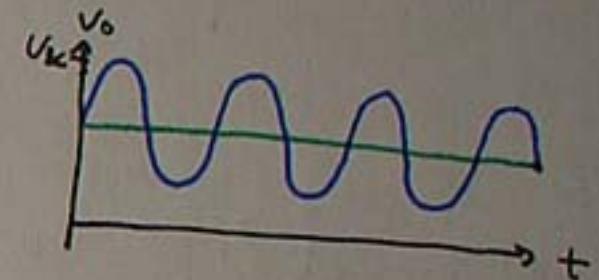
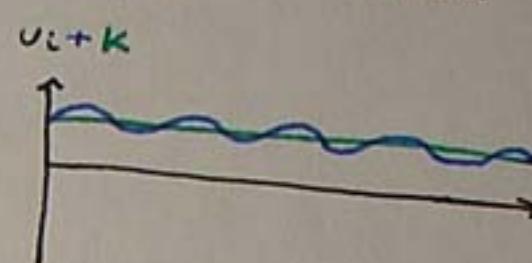
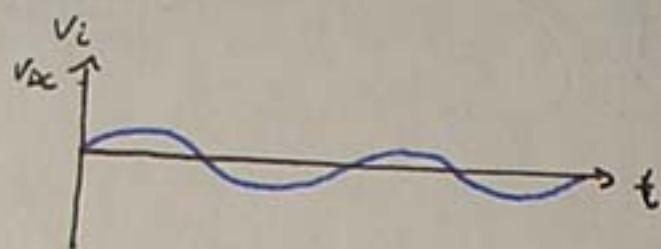
(42)

PRIMER MODEL:

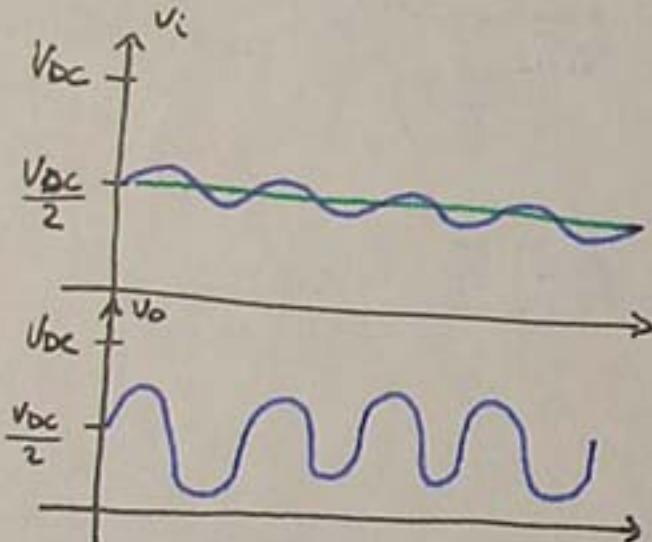


* Distorsió: El senyal de sortida no és = al de entrada.

* Solució: ① Sumar a V_i una senyal constant que fas $V_i > 0$ ut



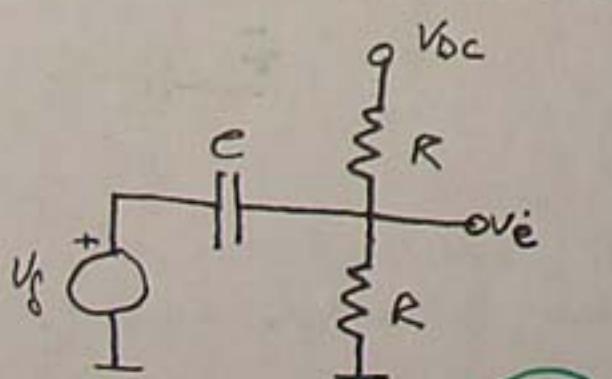
② Solució habitual



$$\text{a)} \text{ Sumar } \frac{V_{DC}}{2} \text{ a } V_g \Rightarrow V_i = \frac{V_{DC}}{2} + V_g$$

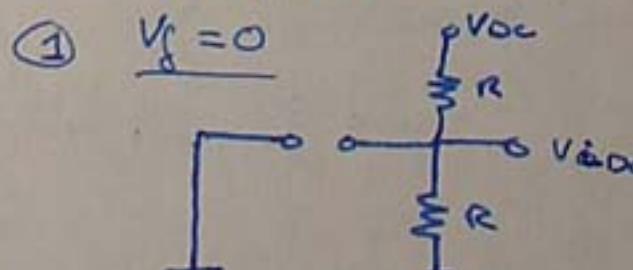
b) Amplificar el component AC

CIRCUIT PER AL CAS a):

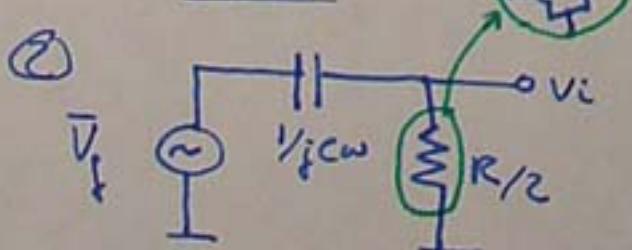


Superposició:

①



$$V_{i,DC} = \frac{V_{DC}}{2}$$



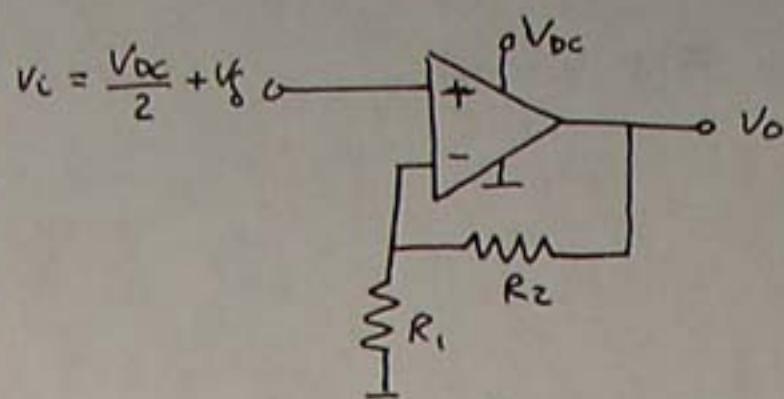
$$V_{i,AC} = V_g \frac{R/2}{\frac{R}{2} - j_{CW}} \approx V_g$$

$$\boxed{V_{i,AC}(+) = V_g(+)}$$

$$\frac{R}{2} \gg \frac{1}{j_{CW}}$$

$$\boxed{V_i = V_{i,DC} + V_{i,AC} = \frac{V_{DC}}{2} + V_g}$$

CIRCUIT PER EL CAS b):

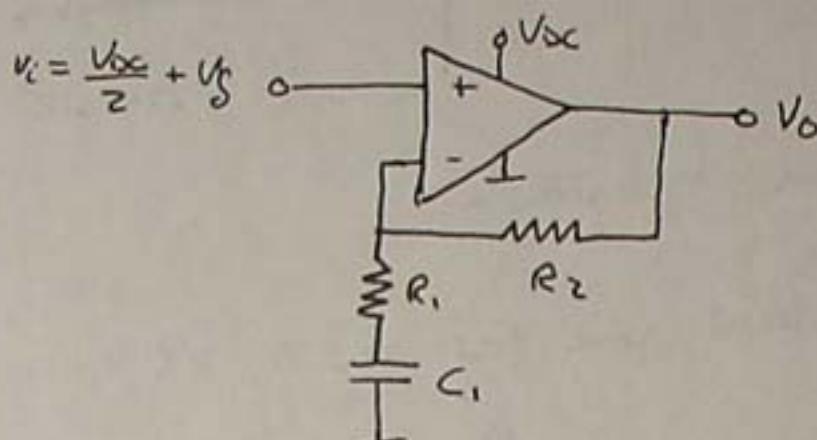


$$v_i = \frac{V_{DC}}{2} + v_g$$

$v_o = K v_i = \underbrace{\frac{15 V_{DC}}{2}}_{\text{Saturation}} + 15 v_g$

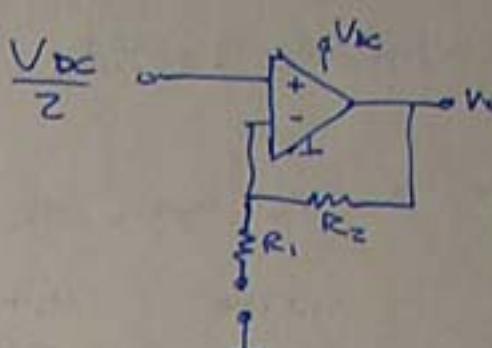
Saturació \Rightarrow No zona lineal

Solució: Afegir un condensador

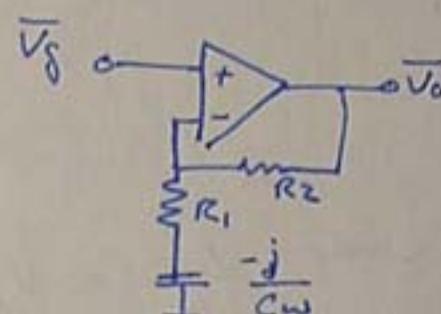
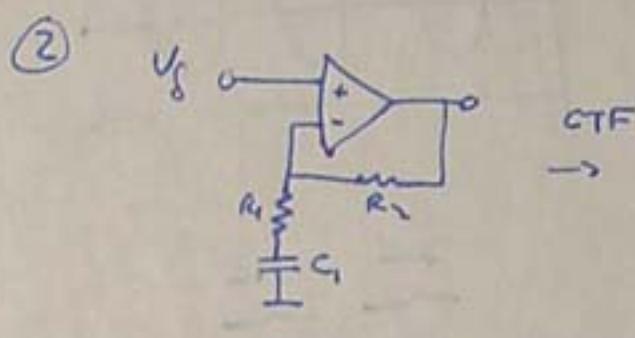


Superposició:

①



$$V_{o,DC} = \left(1 + \frac{R_2}{R_1}\right) \frac{V_{DC}}{2} = \frac{V_{DC}}{2}$$



$$\bar{V}_o = \left(1 + \frac{R_2}{R_1 - \frac{j}{C_1 \omega}}\right) \bar{V}_g$$

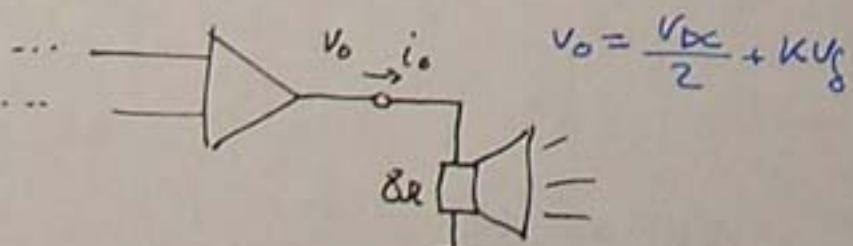
$$\bar{V}_o = \left(1 + \frac{R_2}{R_1}\right) \bar{V}_g = K \bar{V}_g$$

$\frac{1}{C_1 \omega} \ll R_1$

$$V_{o,AC}(t) = K \cdot V_g(t)$$

$$V_{o,T} = V_{o,AC} + V_{o,DC} = K \cdot V_g(t) + \frac{V_{DC}}{2}$$

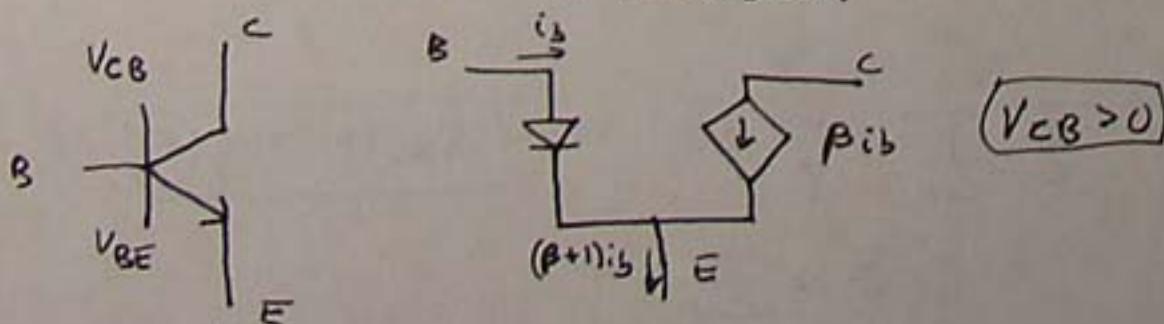
AMPLIFICADOR D'ÀUDIO ACTUAL:



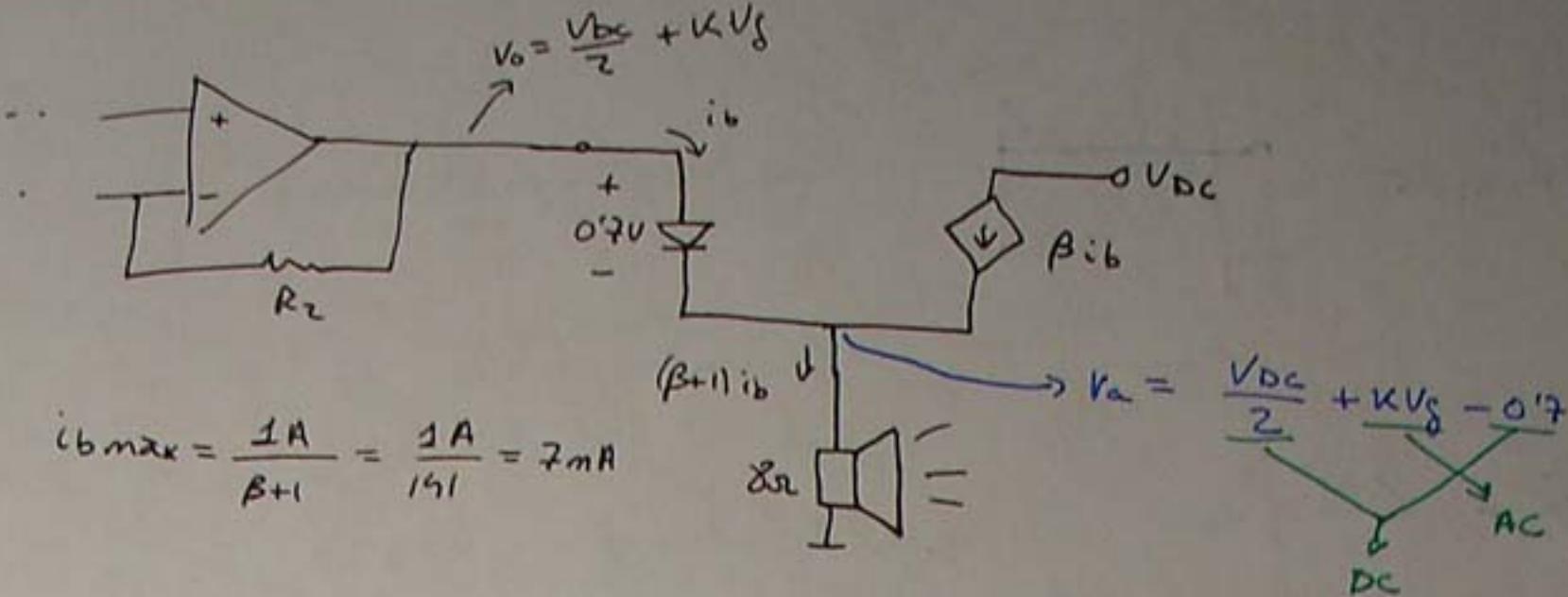
$$V_{o,\max} \approx V_{DC} = 8V$$

$$i_{o,\max} = \frac{8V}{8\Omega} = 1A \rightarrow \text{El amplificador no pot donar tants corrents.}$$

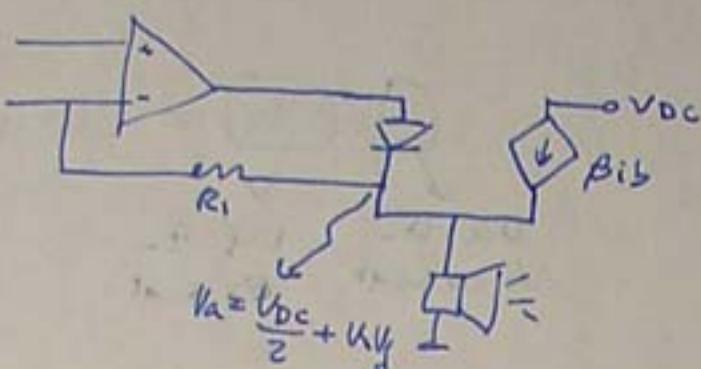
SOLUCIÓ: Utilitzar un transistor:



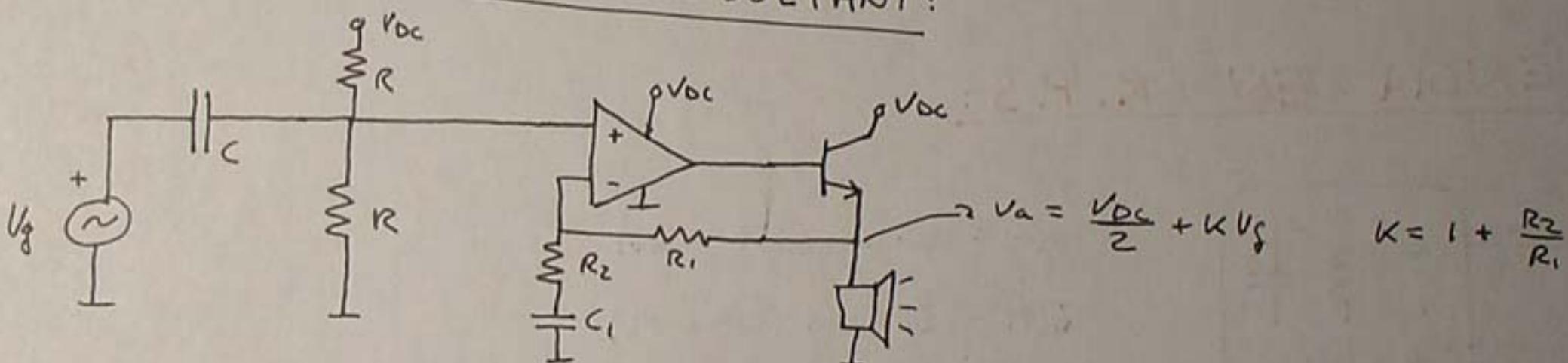
POSIBLE SOLUCIÓ:



PETITA MILLORA:



AMPLIFICADOR D'ÀUDIO RESULTANT:



POTÈNCIA LLIURADA A L'ALTAVEU:

$$P_a(+)=v_a(+)\cdot i_a(+) = \frac{V_a^2(+)}{8R_2} = \frac{1}{8} \left[\frac{V_{DC}^2}{4} + (KA)^2 \cos^2(\omega t) + V_{DC} \cdot KA \cdot \cos(\omega t) \right] =$$

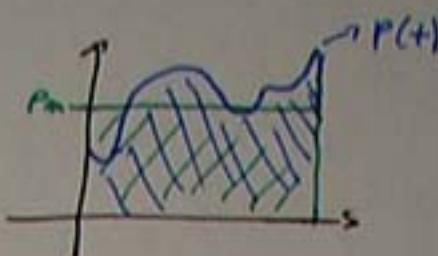
$$V_S = A \cos \omega t$$

$$V_a^2(+) = \frac{V_{DC}^2}{2^2} + KA^2 \cos^2 \omega t + V_{DC} KA \cos \omega t$$

$$= \frac{1}{8} \left[\frac{V_{DC}^2}{4} + \underbrace{\frac{(KA)^2}{2} + \frac{(KA)^2}{2} \cos 2\omega t}_{\cos^2 t = \frac{1}{2} + \frac{1}{2} \cos 2t} + V_{DC} \cdot KA \cdot \cos \omega t \right]$$

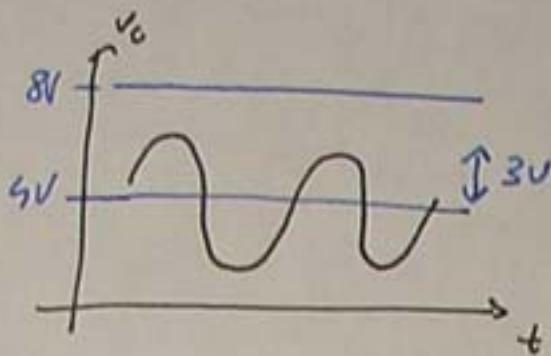
Potència mitja:

$$P_m = \frac{1}{T} \int_0^T P(t) dt$$



Les àrees són iguals

$$P_m = \frac{1}{8} \left[\frac{V_{DC}^2}{4} + \frac{(KA)^2}{2} \right] \rightarrow \text{La resta de termes no hi surt per la seva àrea és nul·la.}$$



$$V_{DC} = 8V$$

$$KA = 3V$$

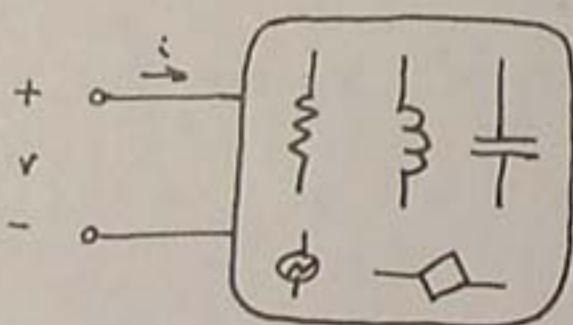
$$P_m = \frac{V_{DC}^2}{32} + \frac{(KA)^2}{16} = \underline{2} + \underline{0'56} = 2'56W$$

↓
Del DC
No es sent
↓
Del AC
Es sent

$$P_m (\text{sonora}) \approx 0'56W$$

* Podrem controlar el volum fent R_2 variable. VOLUM \equiv + AMPLIFICACIÓ

POTÈNCIA EN R.P.S.:



$$v(t) = V_p \cdot \cos(\omega t + \phi_v)$$

$$i(t) = I_p \cdot \cos(\omega t + \phi_i)$$

- Potència instantània:

$$P(t) = v(t) \cdot i(t) = V_p \cdot I_p \cdot \cos(\omega t + \phi_v) \cdot \cos(\omega t + \phi_i)$$

$$P(t) = \boxed{\frac{V_p \cdot I_p}{2} [\cos(2\omega t + \phi_v + \phi_i) + \cos(\phi_v - \phi_i)]}$$

- Potència mitja:

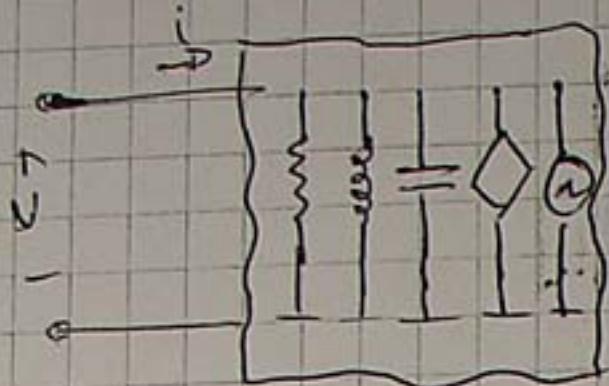
$$P_m = \frac{1}{2} V_p \cdot I_p \cdot \cos \phi$$

$$\phi = \phi_v - \phi_i$$

$$\left. \begin{array}{ll} \phi = 0 & P_m > 0 \\ \phi = \frac{\pi}{2} & P_m = 0 \\ \phi = \pi & P_m < 0 \end{array} \right\}$$

FACTOR DE POTÈNCIA:
 $\cos \phi$

Potencia en R.P.S



$$V(t) = V_p \cos(\omega t + \phi_v)$$

$$I(t) = I_p \cos(\omega t + \phi_i)$$

Potencia instantánea.

$$p(t) = V(t) \cdot I(t) = \boxed{\frac{1}{2} V_p I_p [\cos(2\omega t + \phi_v + \phi_i) + \cos(\phi_v + \phi_i)]}$$

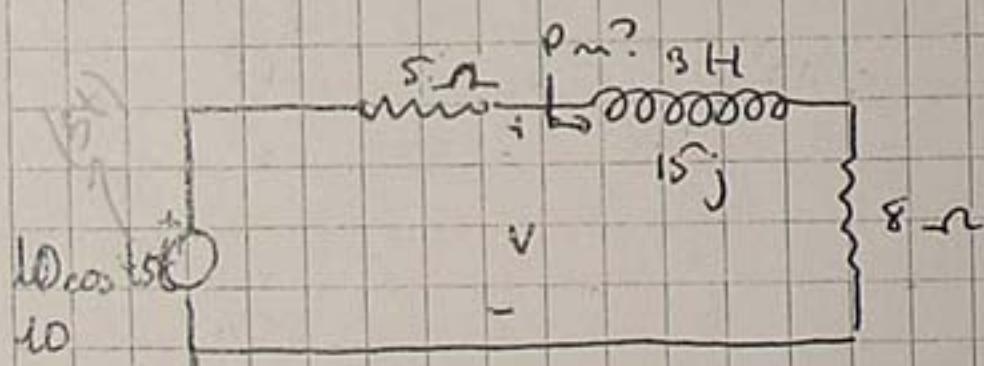
Potencia mitja

$$\boxed{P_m = \frac{1}{2} V_p I_p \cos \phi} \quad \phi = \phi_v - \phi_i \quad \phi = 0 \quad P_m \geq 0$$

$$\phi = \frac{\pi}{2} \quad P_m = 0$$

$$\phi = \pi \quad P_m \leq 0$$

Ex:



$$I = \frac{10}{13 + 15j} = \frac{10 \angle 0^\circ}{19.15 \angle 49^\circ} = 0.5 \angle -49^\circ$$

$$\vec{V} = z \cdot \vec{I} = 17 \angle 62^\circ \cdot 0.5 \angle -49^\circ = 8.5 \angle 13^\circ$$

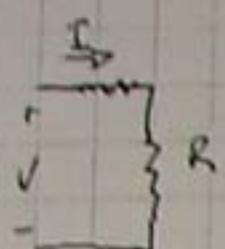
$$z = 17 + 15j = 17 \angle 62^\circ$$

$$P_m = \frac{1}{2} V_p I_p \cos \phi = \frac{1}{2} 8.5 \cdot 0.5 \cdot \cos(13^\circ - (-49^\circ)) = 1W$$

⑥ Potència en R.P.S

- Potència dissipada per alguns elements

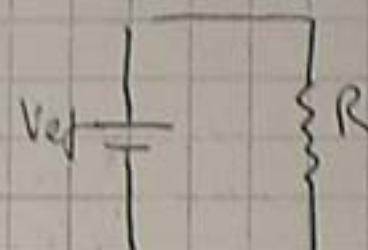
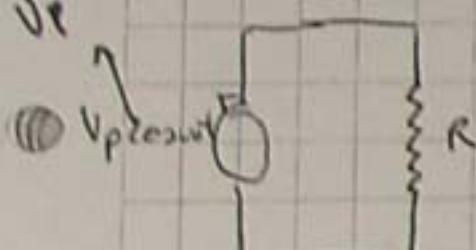
Resistor:



$$P_m = \frac{1}{2} V_p \cdot I_p \cos \phi = \boxed{\frac{1}{2} V_p \cdot I_p + \frac{1}{2} R I_p^2 + \frac{1}{2} \frac{V_p^2}{R}}$$

- Valor eficaç

$V_p \cdot \cos \phi$



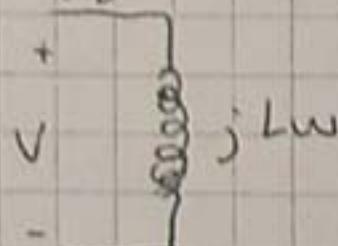
$$P_m = \frac{1}{2} \frac{V_p^2}{R} \Rightarrow P_m = \frac{V_e I_e}{R}$$

↓

$$V_e(t) = \frac{V_p}{\sqrt{2}}$$

$$I_e(t) = \frac{I_p}{\sqrt{2}}$$

Inductor:



$$P_m = \frac{1}{2} V_p \cdot I_p \cos \phi$$

$$\bar{V} = j L \omega \bar{I} \rightarrow V_p = L \omega I_p$$

$$\hookrightarrow \phi_v = \frac{\pi}{2} + \phi_i \quad \phi = \phi_v - \phi_c = \frac{\pi}{2}$$

$$P_m = \frac{1}{2} V_p I_p \cos (\frac{\pi}{2}) = 0$$

Condensador:

$$\text{Idem } \phi = \frac{\pi}{2} \quad P_m = 0$$

⑦

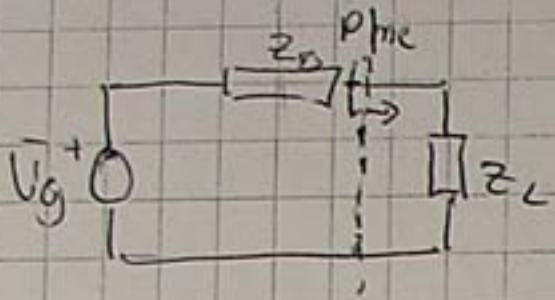
Potencia en valores eficaces

$$P_m = \underbrace{V_{ef} \cdot I_{ef} \cos \phi}_{P_m} (\omega)$$

$$P_m = V_{ef} \cdot I_{ef}$$

$\cos \phi \rightarrow$ Factor de potencia $P_{aparente}$

MÁXIMA TRANSFERENCIA DE POTENCIA



Quin valor de Z_L maximiza P_{me}

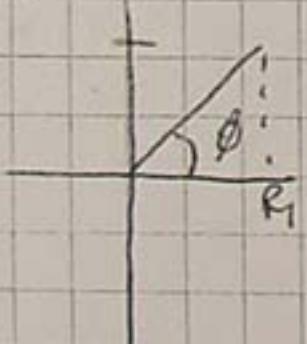
$$Z_g = R_g + j X_g$$

Generador, Carga $Z_L = R_L + j X_L$

$$\bar{V} = \bar{V}_g \cdot \frac{R_L + j X_L}{R_g + R_L + j(X_g - X_L)} \Rightarrow V_p = |\bar{V}| = V_{gp} \cdot \frac{\sqrt{R_L^2 + X_L^2}}{\sqrt{(R_g + R_L)^2 + (X_g - X_L)^2}}$$

$$\bar{I} = \bar{V}_g \cdot \frac{1}{R_g + R_L + j(X_g - X_L)} \Rightarrow I_p = |\bar{I}| = V_{gp} \cdot \frac{1}{\sqrt{(R_g + R_L)^2 + (X_g - X_L)^2}}$$

$$j X_L - Z_L$$



$$\cos \phi = \frac{|I|}{\sqrt{R_L^2 + X_L^2}}$$

$$P_m = \frac{1}{2} V_p I_p \cos \phi \Rightarrow \frac{1}{2} V_{gp}^2 \cdot \frac{\sqrt{R_L^2 + X_L^2}}{(R_g + R_L)^2 + (X_g - X_L)^2} \cdot \frac{R_L^2}{\sqrt{R_L^2 + X_L^2}}$$

$$P_m = \frac{1}{2} V_{gp}^2 \cdot \frac{R_L}{(R_g + R_L)^2 + (X_g - X_L)^2}$$

$$\text{Maximizar el } P_m \Rightarrow X_L = -X_g \Rightarrow m = 2 = \frac{1}{2} V_{gp}^2 \cdot \frac{R_L}{(R_g + R_L)^2}$$