Qué sabemos:

Algoritmos

Órdenes de los algoritmos

DRY

Algoritmos + estructuras de datos = programas

Pilas

Colas

Calculadora postfija

Hoy:

Necesidad de entender los requisitos

Vector

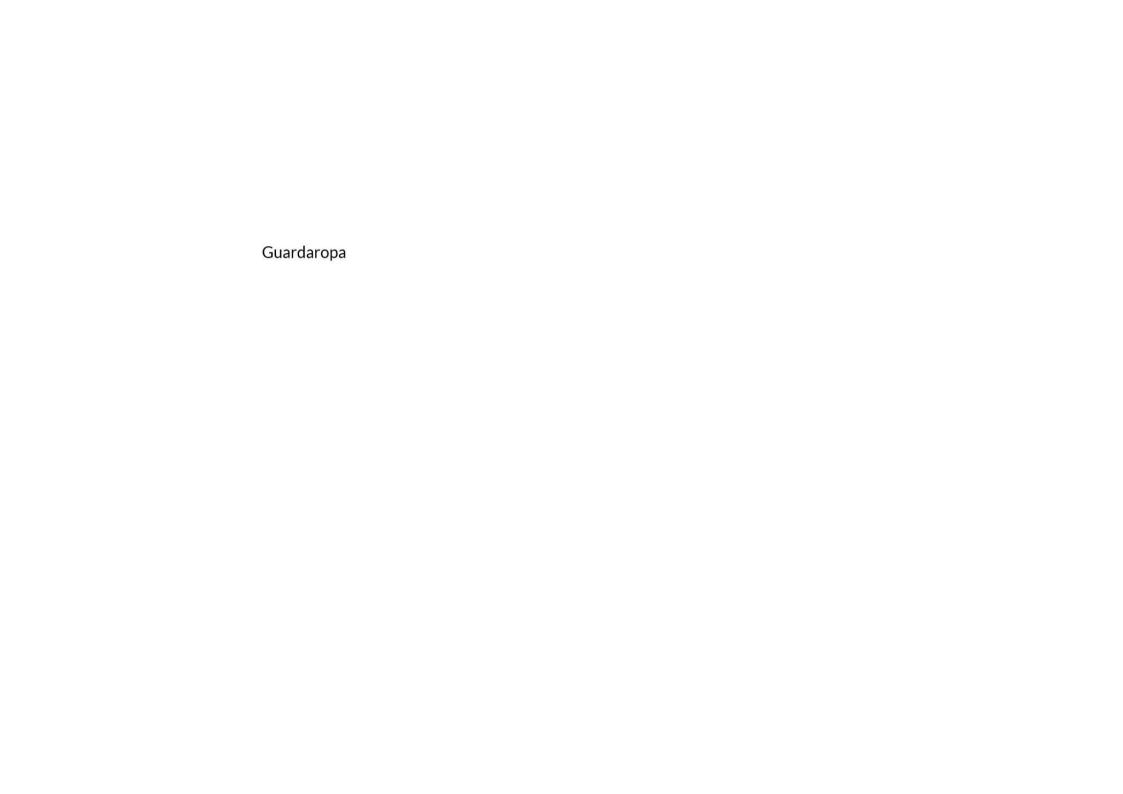
Size vs Capacity

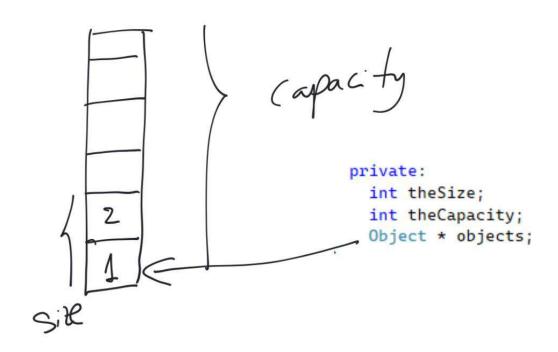
Iteradores

Programar

Common Data Structure Operations

Data Structure	Time Complexity								Space Complexity
	Average				Worst				Worst
	Access	Search	Insertion	Deletion	Access	Search	Insertion	Deletion	
Array	Θ(1)	Θ(n)	Θ(n)	Θ(n)	0(1)	0(n)	0(n)	0(n)	0(n)
Stack	Θ(n)	Θ(n)	Θ(1)	0(1)	0(n)	0(n)	0(1)	0(1)	O(n)
Queue	Θ(n)	Θ(n)	Θ(1)	Θ(1)	0(n)	0(n)	0(1)	0(1)	O(n)
Singly-Linked List	Θ(n)	Θ(n)	Θ(1)	Θ(1)	0(n)	0(n)	0(1)	0(1)	0(n)
Doubly-Linked List	Θ(n)	Θ(n)	Θ(1)	Θ(1)	0(n)	0(n)	0(1)	0(1)	0(n)
Skip List	Θ(log(n))	Θ(log(n))	$\Theta(\log(n))$	$\Theta(\log(n))$	0(n)	0(n)	0(n)	0(n)	O(n log(n))
Hash Table	N/A	0(1)	Θ(1)	0(1)	N/A	0(n)	0(n)	0(n)	O(n)
Binary Search Tree	Θ(log(n))	Θ(log(n))	O(log(n))	O(log(n))	0(n)	0(n)	0(n)	0(n)	0(n)
Cartesian Tree	N/A	Θ(log(n))	Θ(log(n))	$\Theta(\log(n))$	N/A	0(n)	0(n)	0(n)	0(n)
B-Tree	Θ(log(n))	Θ(log(n))	Θ(log(n))	Θ(log(n))	0(log(n))	0(log(n))	0(log(n))	0(log(n))	0(n)
Red-Black Tree	Θ(log(n))	Θ(log(n))	Θ(log(n))	Θ(log(n))	O(log(n))	O(log(n))	O(log(n))	O(log(n))	0(n)
Splay Tree	N/A	Θ(log(n))	Θ(log(n))	Θ(log(n))	N/A	O(log(n))	O(log(n))	O(log(n))	0(n)
AVL Tree	Θ(log(n))	Θ(log(n))	Θ(log(n))	Θ(log(n))	0(log(n))	0(log(n))	0(log(n))	O(log(n))	0(n)
KD Tree	Θ(log(n))	$\Theta(\log(n))$	Θ(log(n))	Θ(log(n))	0(n)	0(n)	0(n)	0(n)	0(n)





```
public:
    explicit vector( int initSize = 0 ).: theSize( initSize ), theCapacity( initSize + SPARE_CAPACITY )
    { objects = new Object[ theCapacity ]; }
```

```
~vector( )
{ delete [ ] objects; }
```

```
bool empty( ) const
  { return size( ) == 0; }
int size( ) const
  { return theSize; }
int capacity( ) const
  { return theCapacity; }
```

```
template <class Object>
    const Object & vector<Object>::back( ) const

{
    if( empty( ) )
        throw UnderflowException( "Cannot call back on empty vector" );
    return objects[ theSize - 1 ];
}
```

```
auto v = vector (int>();
v [7] )
```

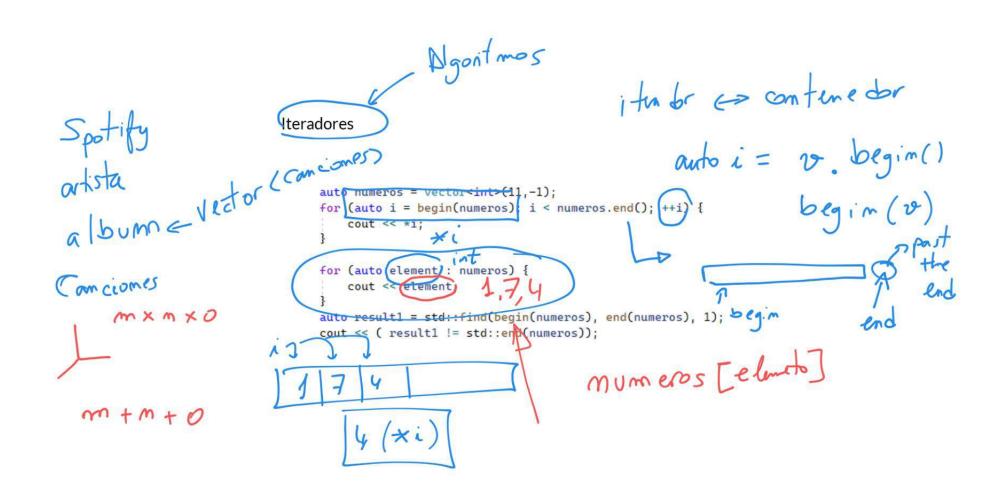
```
template <class Object>
  void vector<Object>::pop_back()

{
   if( empty( ) )
        throw UnderflowException( "Cannot call pop_back on empty vector" );
   theSize--;
}
```

```
template <class Object>
=void vector<Object>::push_back( const Object & x )
{
   if( theSize == theCapacity )
      reserve( 2 * theCapacity + 1 );
   objects[ theSize++ ] = x;
}
```

```
template <class Object>
    void vector<Object>::resize( int newSize )

{
    if( newSize > theCapacity )
        reserve( newSize * 2 );
    theSize = newSize;
}
```



```
// Iterator stuff: not bounds checked
typedef Object * iterator;
typedef const Object * const_iterator;
```

```
iterator begin()
  { return &objects[ 0 ]; }
const_iterator begin( ) const
  { return &objects[ 0 ]; }
iterator end( )
  { return &objects[ size( ) ]; }
const_iterator end( ) const
  { return &objects[ size( ) ]; }
```