

**Games AI**  
**Lecture 6.2**



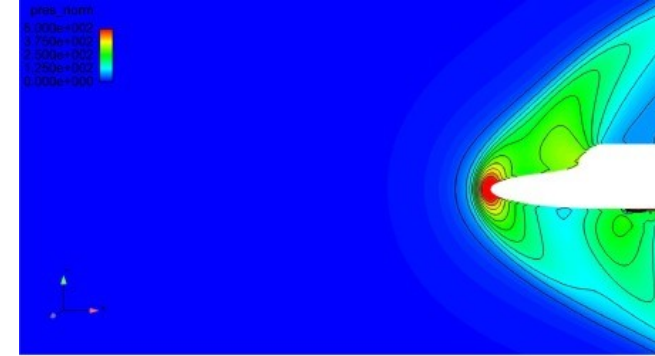
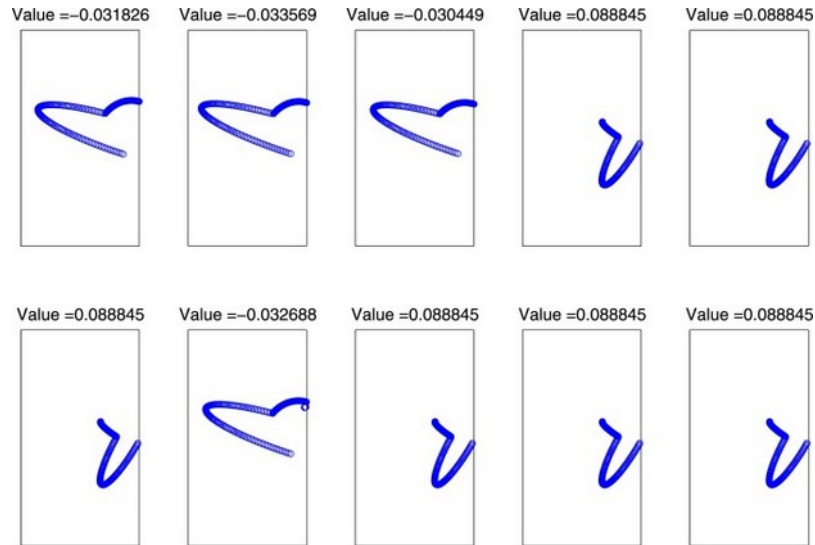
**Evolutionary Algorithms**



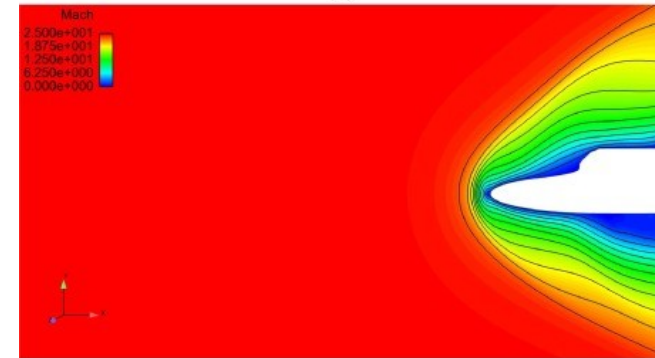
- Last lecture we described PCG as a search problem
  - 1) You have a **generative space** defined by your algorithm
  - 2) Sometimes this space includes both good and bad content.
  - 3) If you can score how “good” content is with an **evaluation function** then you can **search** for high-scoring content.
    - This is an **optimisation** problem

- Why evolution?
  - Engineers often copy solutions in nature
  - What is the best problem solver in nature?
    - **The evolutionary process**

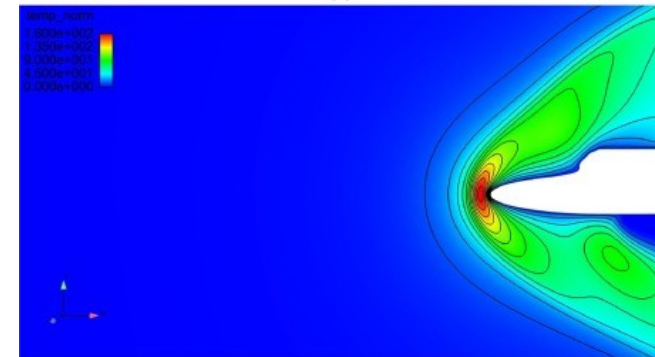
- So you can... find the optimal design for hypersonic re-entry vehicle nosecone



(a)



(b)



(c)

- Or... evolve a more efficient antenna for an unusual purpose



- Or... tune parameters for **rules and FSMs**

```
if (enemy.distance <= 5)
```

```
    attackWithKnife()
```

```
else if (enemy.distance > 5 AND enemy.distance <=30)
```

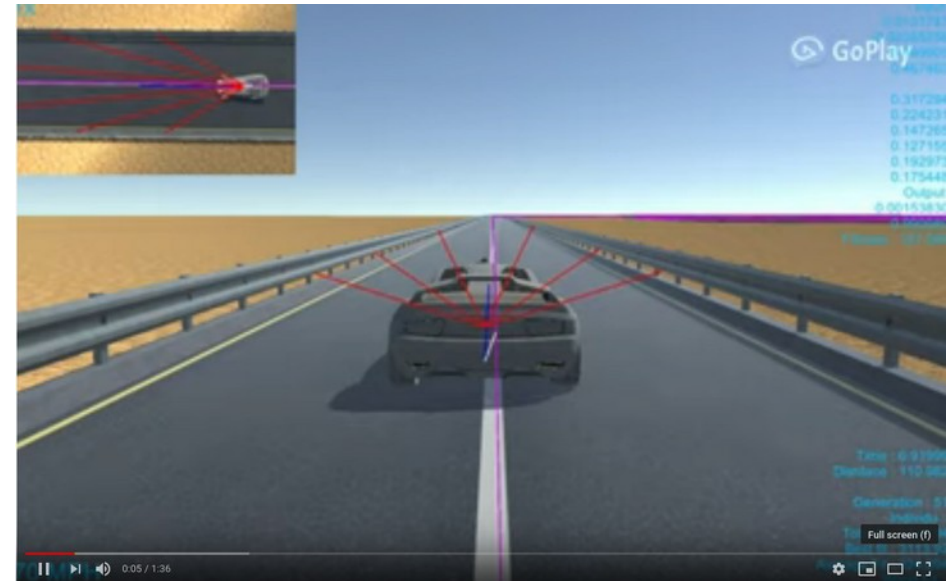
```
    attackWithSubmachineGun()
```

```
else attackWithRifle()
```

- Or... tune parameters that **define AI personality** (e.g. unit preference, scientific advance preference, offense vs. defense, etc.)
- Ponsen, Marc, and Pieter Spronck. Improving adaptive game AI with evolutionary learning. Diss. Masters Thesis, Delft University of Technology, 2004.  
<http://citeseerx.ist.psu.edu/viewdoc/download?doi=10.1.1.109.6055&rep=rep1&type=pdf>



- Or... **evolve agents** using e.g neuroevolution (evolution of neural networks)
  - [https://youtu.be/\\_1TOKKgAock](https://youtu.be/_1TOKKgAock)





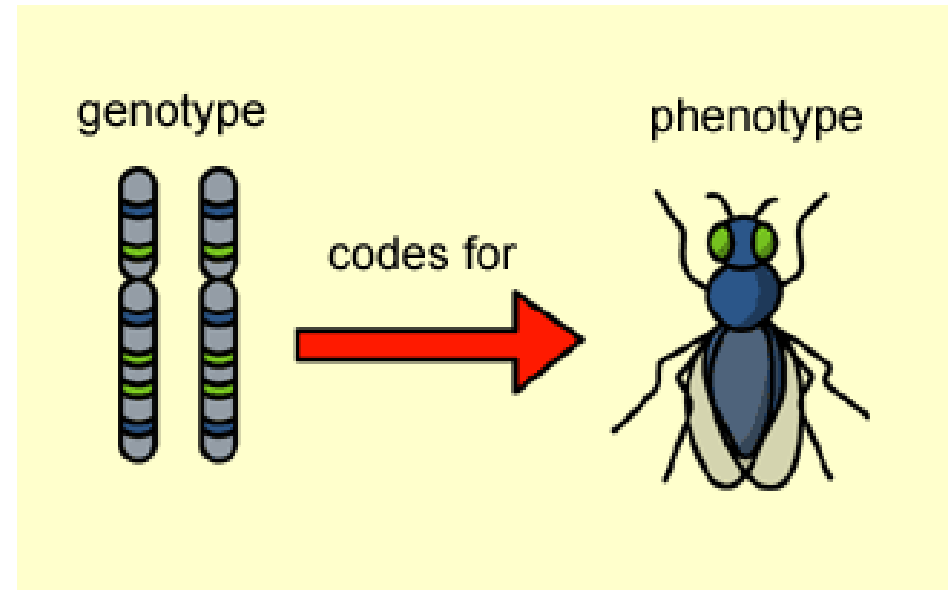
Natural evolution



- Darwinian natural selection:
  - **Competition-based selection**
  - **Phenotypic variation**
    - Behavioural and physical traits that affect an individual's fitness



- Success in survival and reproduction is determined by **phenotypical** properties
- **Phenotypic variations** are always caused by **genotypic variations**
- Phenotypes never influence genetic information
  - **No learning within individuals**



- Change happens through reproduction by the mechanisms of:
  - Mutation
  - Recombination

- **Adaptive landscape**
  - Metaphor of a space where height corresponds to fitness
    - **Global Optimum** = best
    - **Local Optimum** = better than neighbours

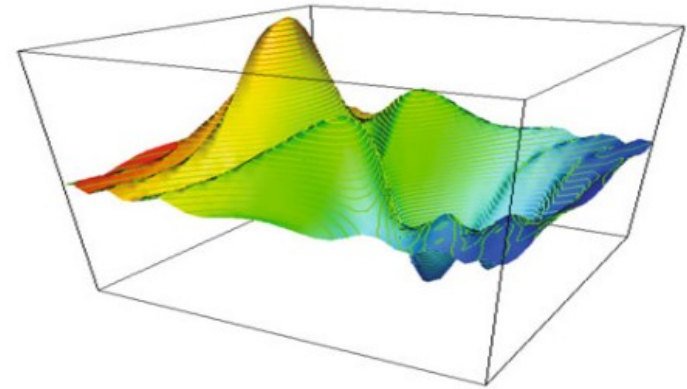


Fig. 2.2. Illustration of Wright's adaptive landscape with two traits

- **Each individual is a sample** of the space of all possible living things
  - Produced by forces of **variation**
  - Evaluated by forces of **selection**
    - Prove viable to live
    - Prove viable to reproduce
- In algorithmic terms this is a “**generate and test**” method.

## Intro to Evolutionary Algorithms



What?

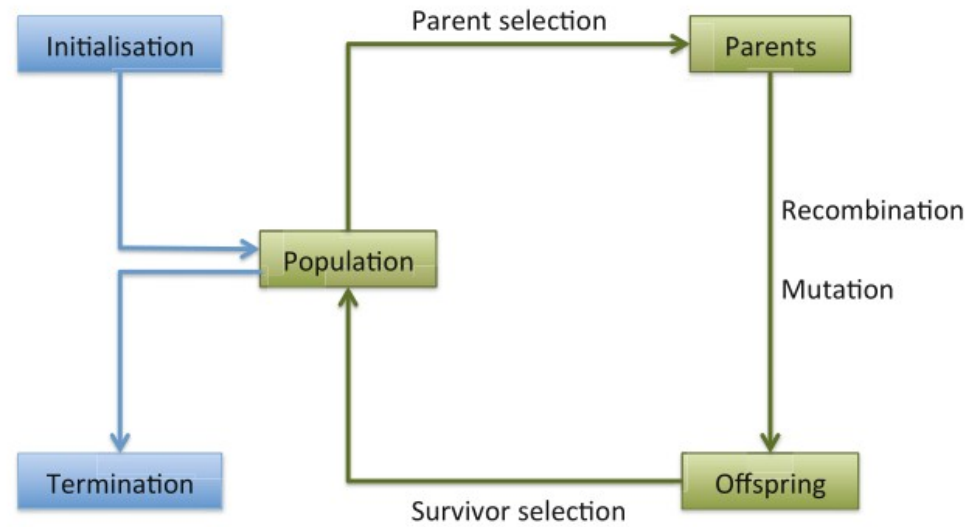
MAGIKARP is evolving!

- In an Evolutionary Algorithm, a solution is described by a **genotype**
  - This might be a string, enum[], number[]...
  - e.g. **parameter values** for a PCG algorithm
  - e.g. **weights** for a neural network
- This data (genotype) is interpreted to create the **phenotype** (e.g. level map, AI behaviour, game audio)



- Evolutionary Algorithms (EAs) are:
  - **Population based**
    - (You keep hold of a bunch of possible solutions at the same time)
  - **Stochastic**
    - (Involves randomness)
  - Most use **recombination**
    - (You mix together different solutions to try and find a better one)

- Why EAs work
  - **Variation** (recombination and mutation) create diversity and novelty
  - **Selection** acts as a force to increase the mean quality of solutions



**Fig. 3.2.** The general scheme of an evolutionary algorithm as a flowchart

BEGIN

*INITIALISE* population with random candidate solutions;

*EVALUATE* each candidate;

REPEAT UNTIL ( *TERMINATION CONDITION* is satisfied ) DO

1 *SELECT* parents;

2 *RECOMBINE* pairs of parents;

3 *MUTATE* the resulting offspring;

4 *EVALUATE* new candidates;

5 *SELECT* individuals for the next generation;

OD

END

**Fig. 3.1.** The general scheme of an evolutionary algorithm in pseudocode

- Components of EAs
  - **representation** (definition of individuals)
  - **evaluation function** (or fitness function)
  - **population**
  - **parent selection mechanism**
  - **variation operators**, recombination and mutation
  - **survivor selection mechanism** (replacement)
  - **termination condition**

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- **Representation:** What is your genome?
  - **Strings** in a finite alphabet (genetic algorithms)
  - **Real-valued vectors** (evolution strategies)
  - **Finite state machines** (classical evolutionary programming)
  - **Trees** (genetic programming)
- Different approaches may suit different problems better depending on the natural way to encode the candidate solutions

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- **Evaluation Function**
  - Function that **assigns quality measure to genotypes**
    - **Evaluate phenotype** for quality.
  - Represent requirements that population should adapt to meet (i.e. defines what improvement means)

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- **Population**
  - holds possible solution
    - A multiset of genotypes (almost always a constant size)
  - Individuals do not change or adapt, population does
  - Selection operators **work at the population level**
    - Best individual **of a given population** is selected

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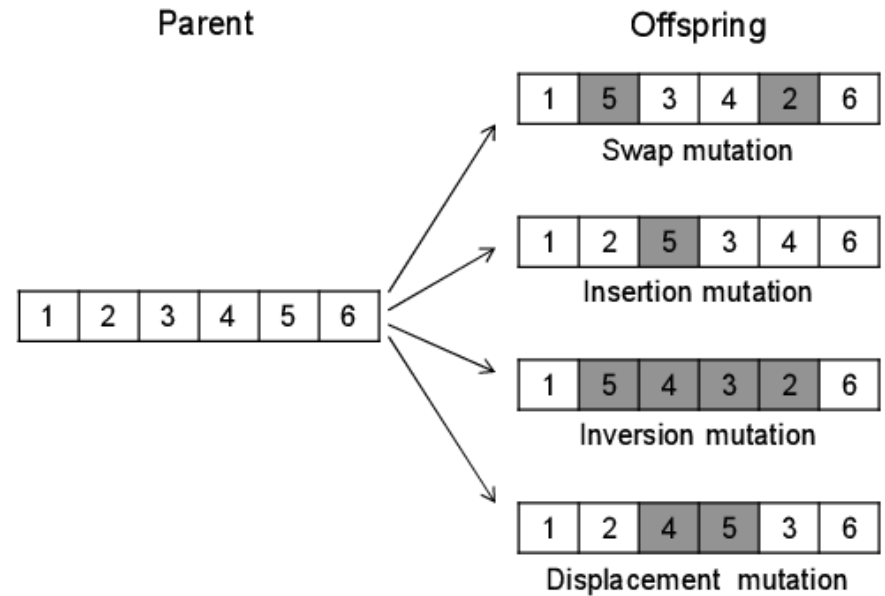
- **Parent selection / mate selection**
  - Distinguish among individuals based on quality
  - Allow better individuals to become parents of next generation
  - Probabilistic – fitter individuals more likely to be selected as parents
    - Often still give low-fitness individuals a small chance, otherwise search becomes too greedy and gets stuck in **local optima**.

- Components of EAs
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- **Variation operators**
  - Create new individuals from old ones
  - The “generate” in “generate and test”
  - **Mutation** and **Crossover** (recombination)

- **Mutation**

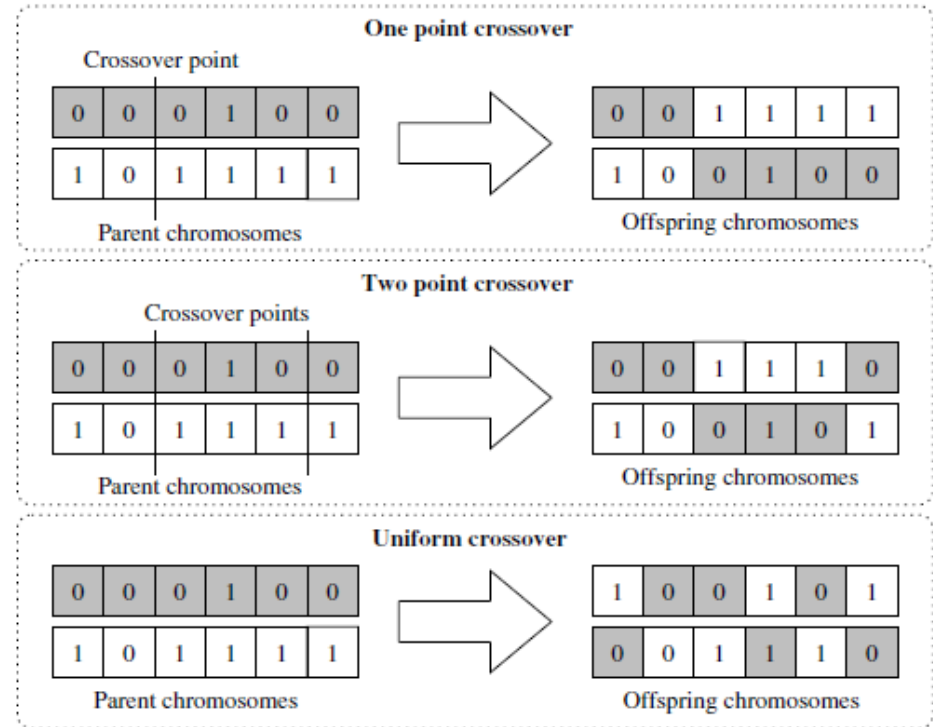
- Randomly change part of the genotype
- Stochastic
- Unbiased
- Provides the gene-pool with “fresh blood”





- **Crossover**

- Merges information in two or more parents
- Random recombinations
- Hopefully take good qualities of each parent



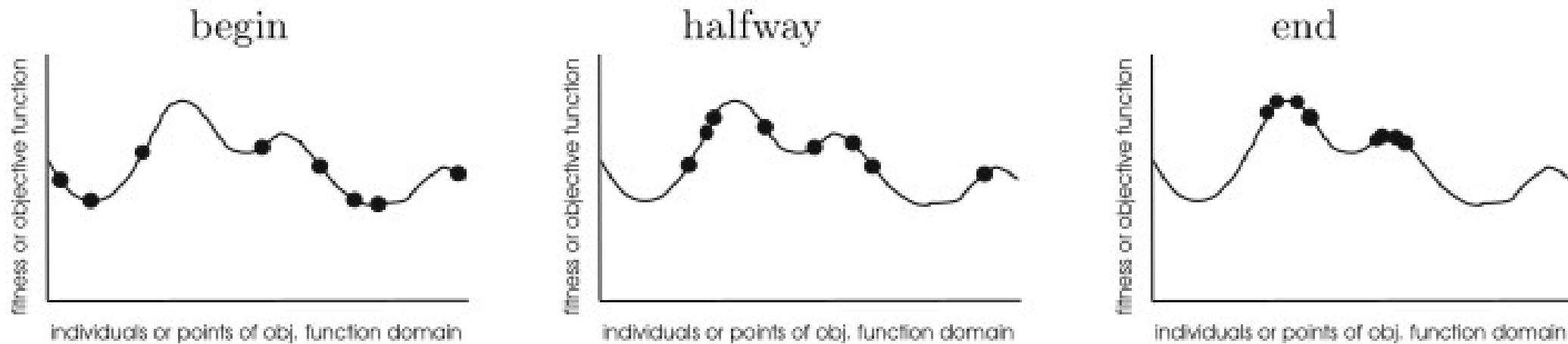
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- **Survivor selection** / replacement strategy
  - Decide which of older generations to keep
  - Based on **fitness values**
    - e.g. keep top % of new and old generation combined
  - Or based on **age**
    - e.g. only keep newest generation

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- **Termination condition**
  - Stop when we find **optimum fitness** (if you guarantee reaching it)
  - Otherwise
    - 1) Limit **CPU time**
    - 2) Limit total number of **fitness evaluations**
    - 3) Check if **fitness improvement remains low** for a given period of time (i.e. for a number of generations or fitness evaluations)
    - 4) Check if the **population diversity drops** below a given threshold

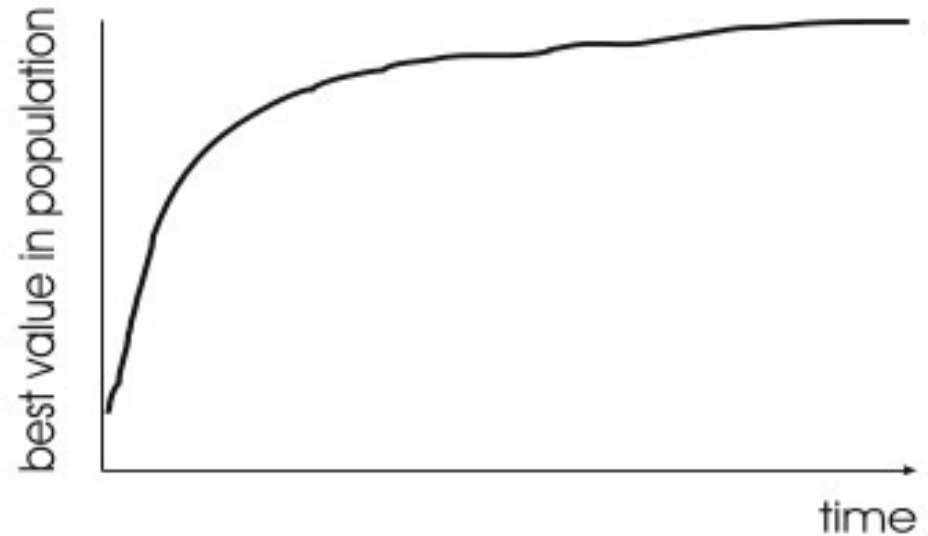
## How do EAs behave?



**Fig. 3.4.** Typical progress of an EA illustrated in terms of population distribution. For each point  $x$  in the search space  $y$  shows the corresponding fitness value.

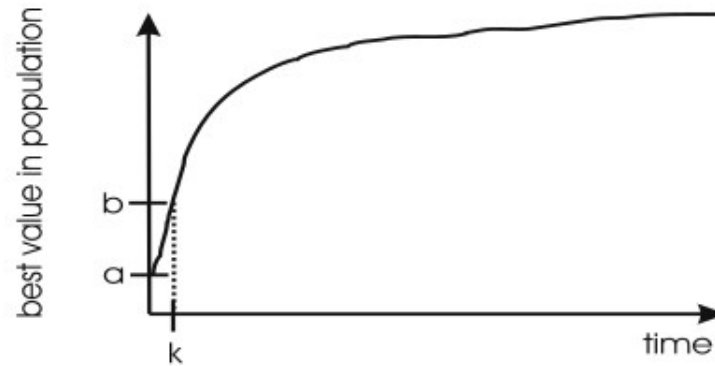
- **Exploration:** generation of individuals in untested space
- **Exploitation:** concentrating in vicinity of known good solutions
- **Premature convergence:** losing population diversity too quickly and getting stuck in a local optimum.

- EAs are **anytime**
  - You can interrupt them at... any time
  - Get the best solution so far, even if suboptimal



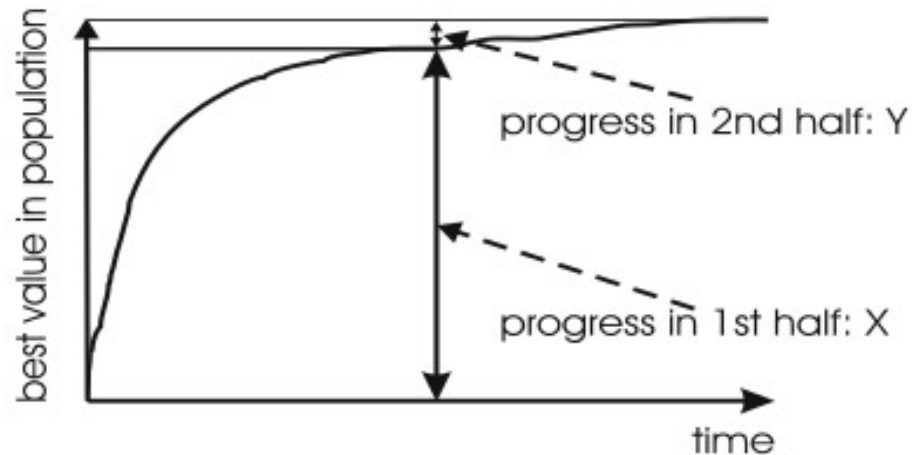


- **Improvement is often rapid at start**
- You can initialise your population with **heuristics**, but it might not be worth the effort



**Fig. 3.6.** Illustration of why heuristic initialisation might not be worth additional effort. Level *a* shows the best fitness in a randomly initialised population; level *b* belongs to heuristic initialisation

- **Improvement slows down**, so long runs may be not worth i t



**Fig. 3.7.** Why long runs might not be worth performing. *X* shows the fitness increase in the first half of the run, while *Y* belongs to the second half

- Designing and tuning EAs is an art:
  - Population size
  - Number of generations
  - Fitness function
  - Representation
  - Mutation rate
  - Crossover operations
  - Selection procedure
  - Number of solutions to keep

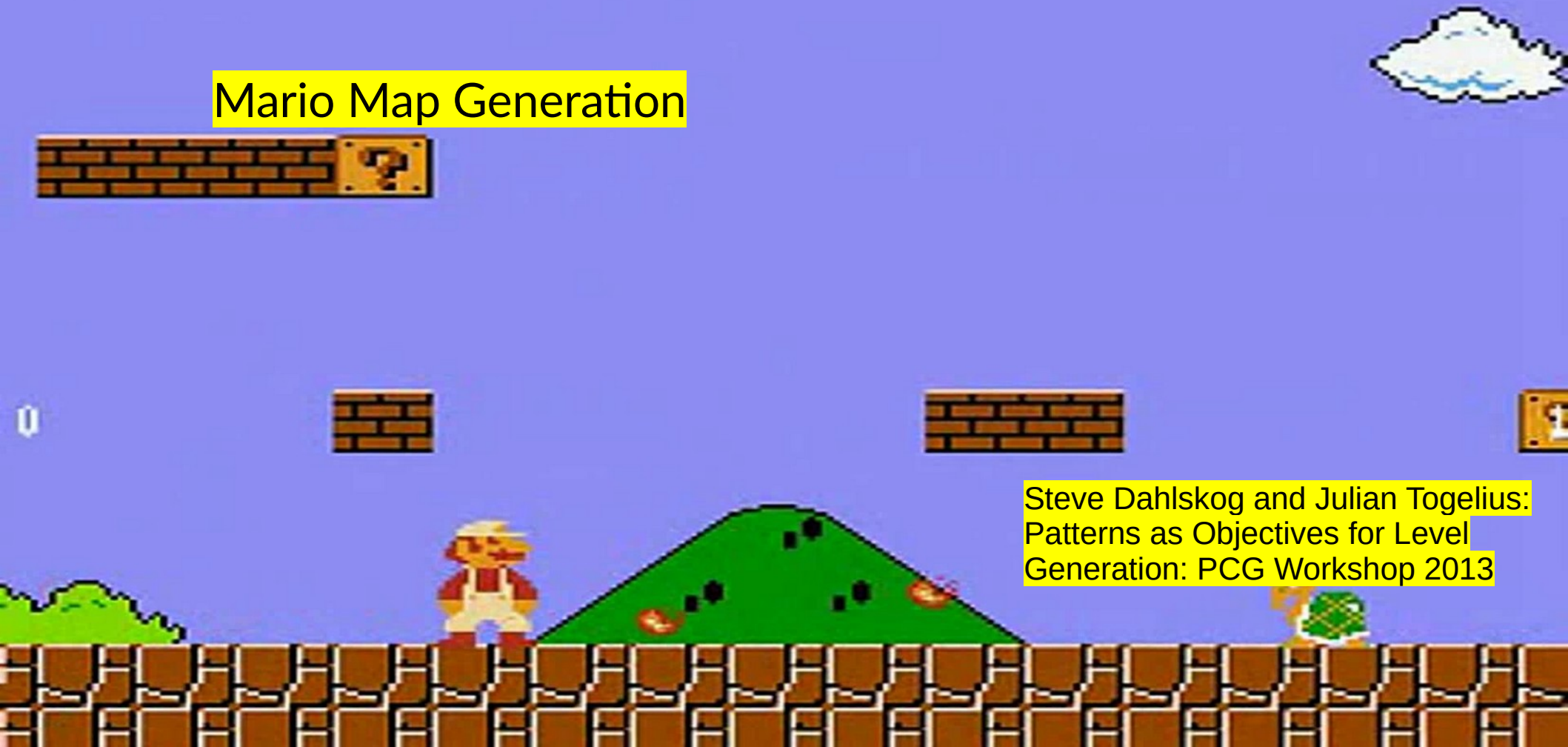
MARIO  
003600

0 x 03

WORLD  
1-1

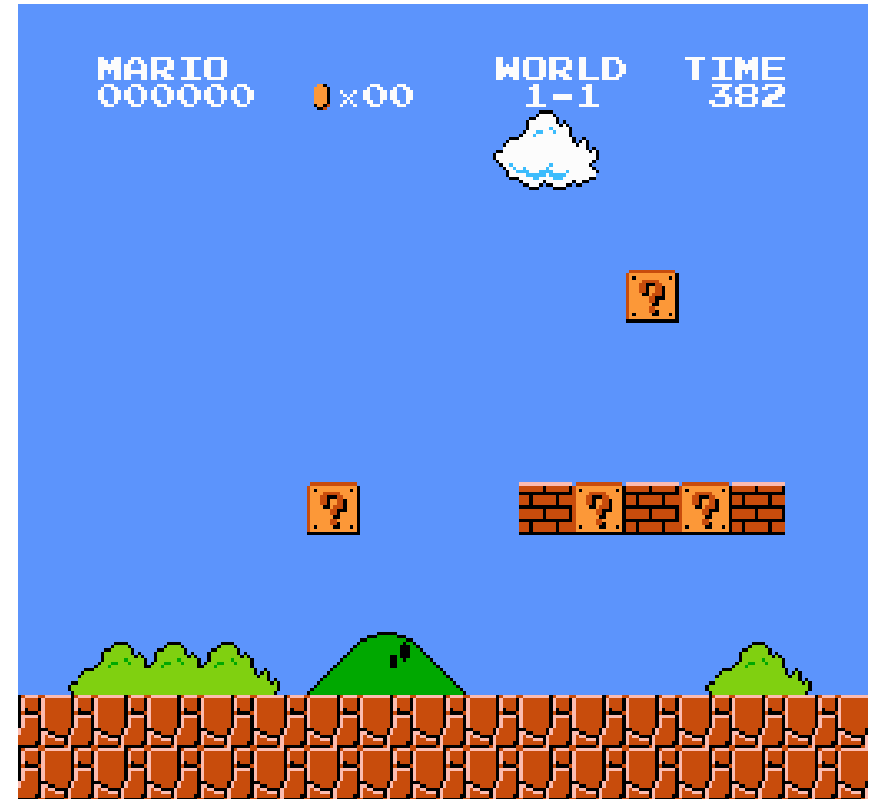
TIME  
288

## Mario Map Generation



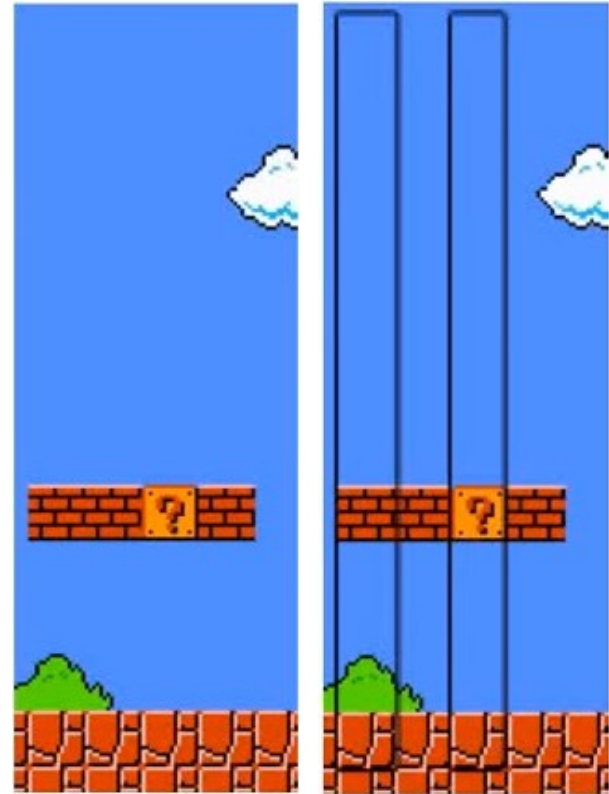
Steve Dahlskog and Julian Togelius:  
Patterns as Objectives for Level  
Generation: PCG Workshop 2013

- Representation attempt 1
  - 2D grid of integers storing value for each grid cell
    - Direct mapping to phenotype
    - But “good” space is tiny proportion of search space



- Representation attempt 2
  - A range of integers, each representing the height of an obstacle
    - 0 = hole in the ground
    - 10 = maximum height of obstacle
  - But most obstacles in SMB are close to the ground.

- Representation attempt 3
  - Represent mario level as string of symbols, each symbol corresponds to a column of blocks that existed in the original SMB



- Fitness function
  - Look for level design patterns in the output that match patterns in the original SMB

**Table 2: Patterns supported in the fitness function.**

Enemies	
Enemy	Low
2-Horde	Low
3-Horde	Low
4-Horde	Low
Roof	Medium
Gaps	
Gaps	Low
Multiple gaps	By stacking
Variable gaps	By stacking
Gap enemy	Low-Medium by stacking
Pillar gap	Pillar High
Valleys	
Valley	Low
Pipe valley	Medium
Empty valley	By stacking
Enemy valley	By stacking
Roof valley	By stacking
Multiple paths	
2-Path	Medium-High
3-Path	Medium-High
Risk and Reward	By stacking
Stairs	
Stair up	Low
Stair down	Low
Empty stair valley	Low
Enemy stair valley	By stacking
Gap stair valley	By stacking



- Population of 200 (randomly initialised)
- Rank by fitness, top 50% kept
- One point crossover between pairs in rank order (best breeds with second best)
- Mutation: inject a random character in a random position
- 10,000 generations







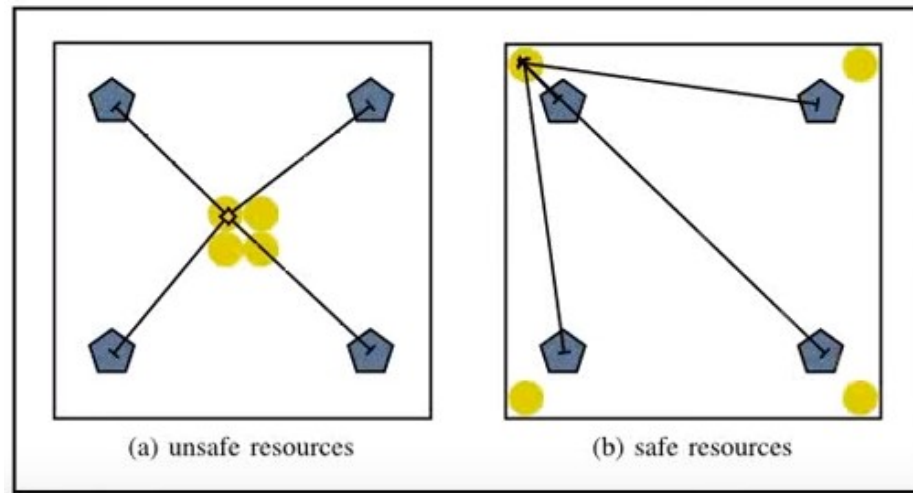
## Starcraft Map Generation

Julian Togelius, Mike Preuss, Nicola Beume, Simon Wessing, Johan Hagelbäck, Georgios N. Yannakakis and Corrado Grappiolo (2013):  
**Controllable Procedural Map Generation via Multiobjective Evolution.**  
Genetic Programming and Evolvable Machines. Springer.

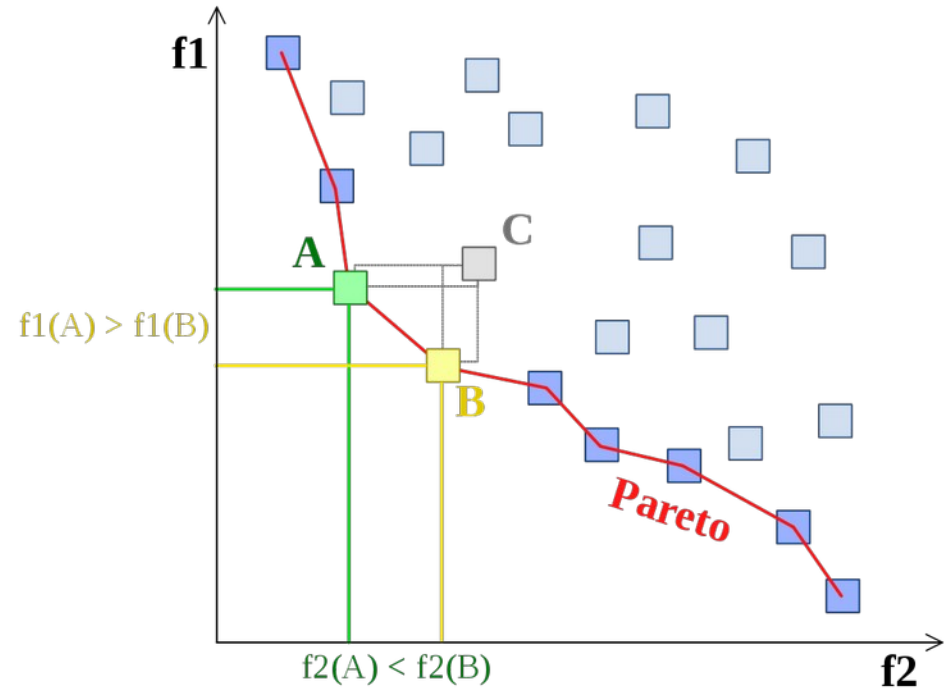
- Evolution of RTS maps
  - Desirable
    - Playability
    - Fairness
    - Skill differentiation
    - Interestingness



- Fairness fitness function
  - Distance from base to closest resource
  - Resource ownership
  - Resource safety
  - Resource fairness



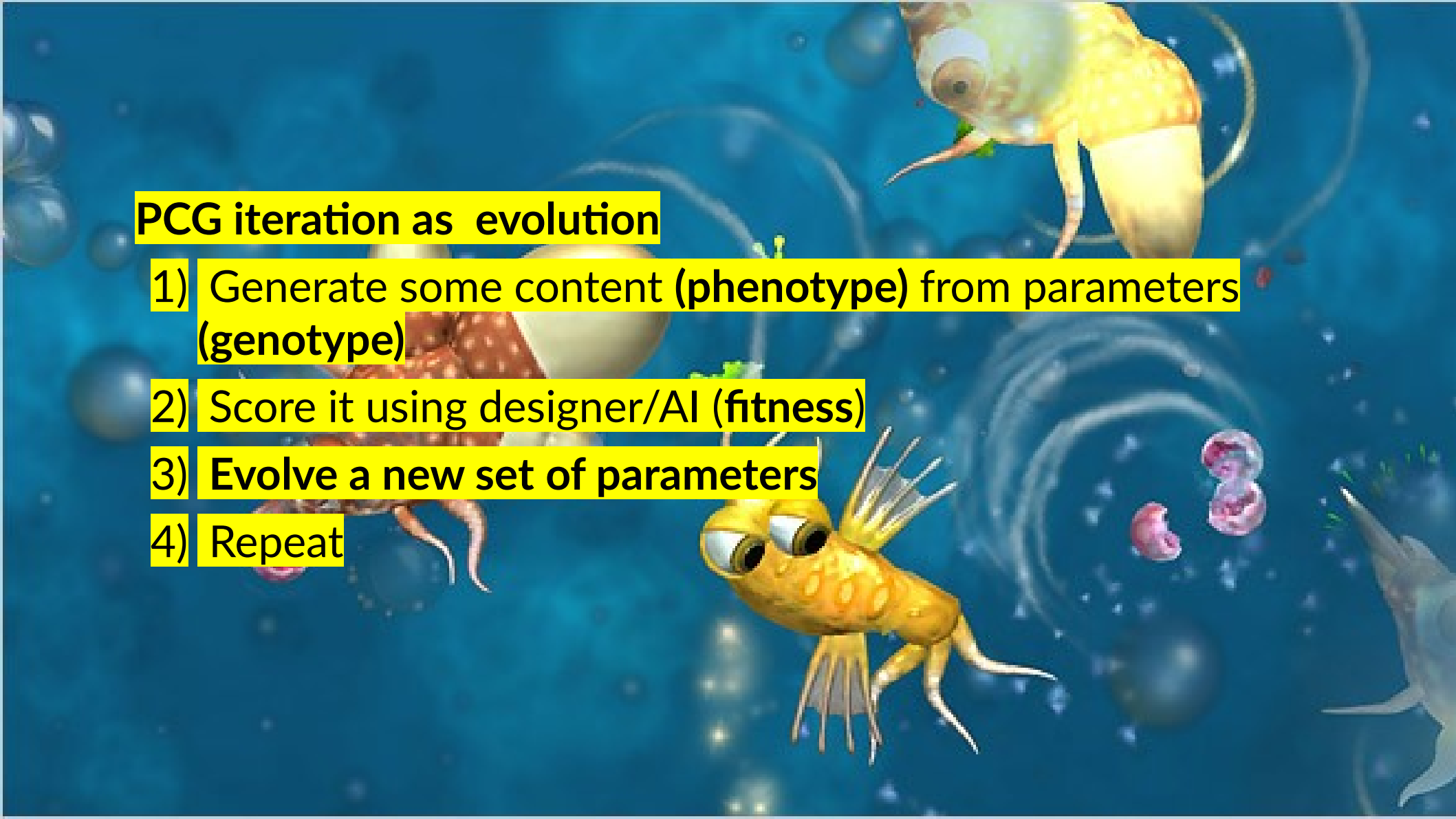
- Multiobjective EAs have multiple objectives
  - **Pareto front** between them
  - The point at which increasing one objective will decrease another
  - Not always desirable – sometimes you want to look for solutions that are good for **any** of the objectives





## PCG iteration as evolution

- 1) Generate some content (**phenotype**) from parameters (**genotype**)
- 2) Score it using designer/AI (**fitness**)
- 3) **Evolve a new set of parameters**
- 4) Repeat



- Eiben & Smith, 2015.  
*Introduction to Evolutionary Computing* (Second Edition)  
Springer
- Yannakakis and Togelius,  
2018. *Artificial Intelligence and Games*. Springer
- ...and the links throughout  
the slides

