

Lunch & Learn:

Modeling Aircraft Systems

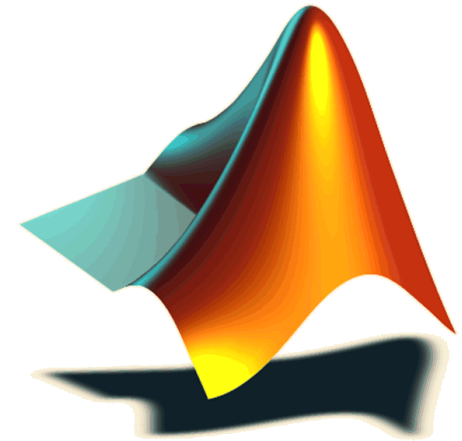


Lockheed Martin Aeronautics ~ Palmdale, CA
June 17, 2015

From MathWorks

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 - 508-647-1203

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 - Application Engineer
- **David Meissner**
 - Application Engineer
- **Chad Van Fleet**
 - Pilot Engineer
- **Pascal Gahinet**
 - MathWorks Development: Controls



Please note...

- Today's slides & demos will be available (Follow-up Email)
- Feedback Forms...
 - Need Anything???
 - How can we help you???
- Giveaways...



MathWorks Product Overview



Corp License 339958 – MATLAB Based Products

352 MATLAB

12 Parallel Computing Toolbox

Math, Statistics, and Optimization

14 Symbolic Math Toolbox

2 Partial Differential Equation Toolbox

28 Statistics Toolbox

16 Curve Fitting Toolbox

15 Optimization Toolbox

2 Global Optimization Toolbox

3 Neural Network Toolbox

Control System Design & Analysis

29 Control System Toolbox

6 System Identification Toolbox

5 Fuzzy Logic Toolbox

5 Robust Control Toolbox

1 Model Predictive Control Toolbox

16 Aerospace Toolbox

Signal Processing & Communications

44 Signal Processing Toolbox

19 DSP System Toolbox

13 Communications System Toolbox

4 Wavelet Toolbox

12 Fixed-Point Toolbox

4 RF Toolbox

2 Phased Array System Toolbox



Image Processing and Computer Vision

31 Image Processing Toolbox

2 Computer Vision System Toolbox

1 Image Acquisition Toolbox

18 Mapping Toolbox

Test & Measurement

4 Data Acquisition Toolbox

8 Instrument Control Toolbox

1 Image Acquisition Toolbox

Code Generation

13 MATLAB Coder

1 HDL Coder

3 HDL Verifier

1 Filter Design HDL Coder

Application Deployment

2 Spreadsheet Link EX

6 MATLAB Compiler

1 MATLAB Builder JA

1 MATLAB Builder NE

Database Access and Reporting

4 MATLAB Report Generator

12 Database Toolbox

Corp License 339958 – Simulink Based Products



76	Simulink
	Fixed-Point Modeling
3	Simulink Fixed Point
	Event-Based Modeling
23	Stateflow
6	SimEvents
	Physical Modeling
10	Simscape
3	SimHydraulics
6	SimMechanics
9	SimPowerSystems
4	SimRF
	Control System Design and Analysis
6	Simulink Control Design
3	Simulink Design Optimization
16	Aerospace Blockset
	Signal Processing and Communications
19	DSP System Toolbox
13	Communications System Toolbox
4	SimRF
2	Computer Vision System Toolbox

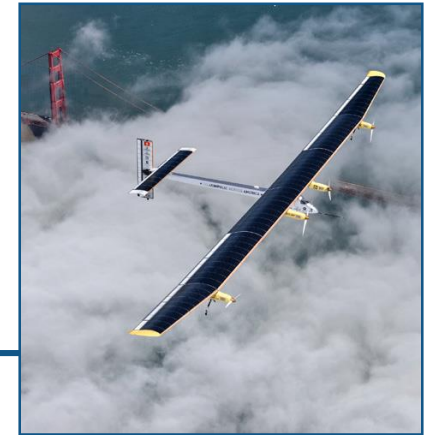
	Code Generation
7	Simulink Coder
7	Embedded Coder
1	HDL Coder
	Rapid Prototyping and HIL Simulation
2	xPC Target
2	Real-Time Windows Target
	Verification, Validation, and Test
6	Simulink Verification and Validation
0	Simulink Code Inspector
1	Simulink Design Verifier
2	SystemTest
3	HDL Verifier
	Simulation Graphics and Reporting
3	Gauges Blockset
4	Simulink 3D Animation
3	Simulink Report Generator

To see your license #,
type "ver" in MATLAB

Key Messages

- Design and Analyze Electrical and Power Systems
- Develop and Implement Logic and Controls
- Perform Verification and Validation

Solar Impulse Develops Advanced Solar-Powered Airplane



The HB-SIA aircraft on a test flight over San Francisco Bay.

Photo © Solar Impulse | Revillard | Rezo.ch

Challenge

Develop a solar-powered aircraft capable of circumnavigating the globe

Solution

Use MATLAB and Simulink to create system models for trade studies and design tradeoff analysis, and aircraft dynamics models for high-fidelity simulations and pilot training

Results

- Key design decisions made early
- Vital pilot training enabled
- Models reused and shared throughout development

“Simulations with MATLAB and Simulink were essential to assessing feasibility and evaluating broad design tradeoffs as well as making detailed design decisions—like the size of control surfaces and the vertical tail—that directly affect aircraft dynamics and handling qualities.”

Ralph Paul
Solar Impulse

GasTOPS Develops and Tests Propulsion Control Algorithms for the USS Makin Island



The USS Makin Island.

Challenge

Develop the propulsion control algorithms for the USS Makin Island

Solution

Use Model-Based Design with MATLAB and Simulink to model the ship's main systems, develop and verify control algorithms, and generate code for onboard training and HIL test setups

Results

- Time-to-simulation cut by two-thirds
- Key design issues identified early
- Models reused multiple times

“We mitigate risk by simulating complex marine and aircraft systems before they are built. To reduce costs, we automate simulations with MATLAB and reuse models throughout development. Understanding multidomain systems through simulations in Simulink and SimPowerSystems is invaluable to our business.”

Shaun Horning
GasTOPS

NASA Interns Develop Guidance, Navigation, and Control Software for Quadcopter with Model-Based Design

Challenge

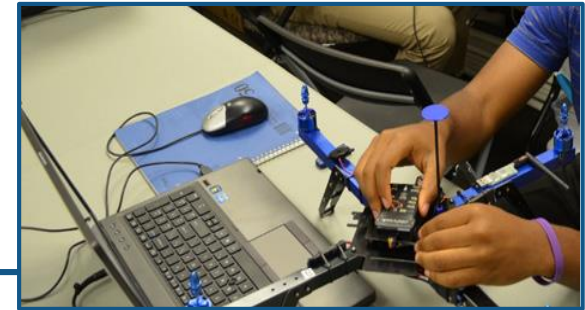
Give engineering interns hands-on work experience in the aerospace field

Solution

Create a program in which interns use Model-Based Design to model, simulate, implement, and fly GNC algorithms for multirotor aircraft

Results

- GNC algorithms developed and implemented in 10 weeks
- Hardware integration streamlined
- Practical engineering experience acquired

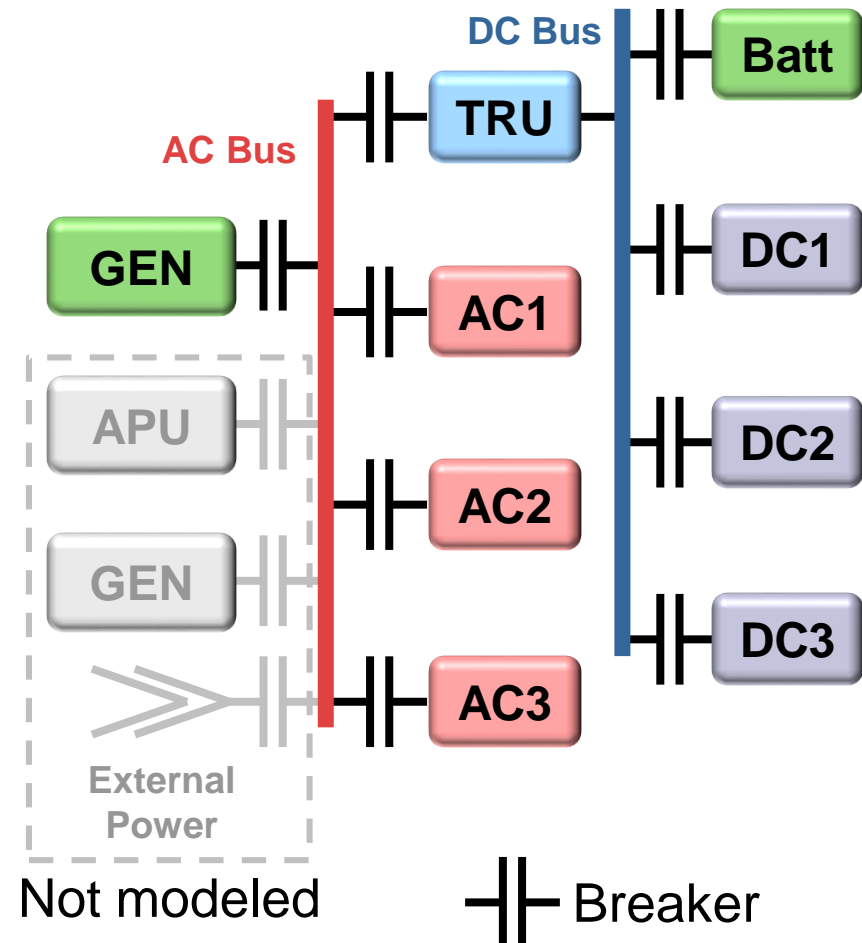


NASA intern working with the quadcopter vehicle and ArduPilot Mega 2.5 hardware.

Model-Based Design makes both working engineers and interns at NASA MSFC more productive. The students have more fun because they can run the GNC algorithms they create in Simulink on a real processor and quickly get things done.

Aircraft Power Network

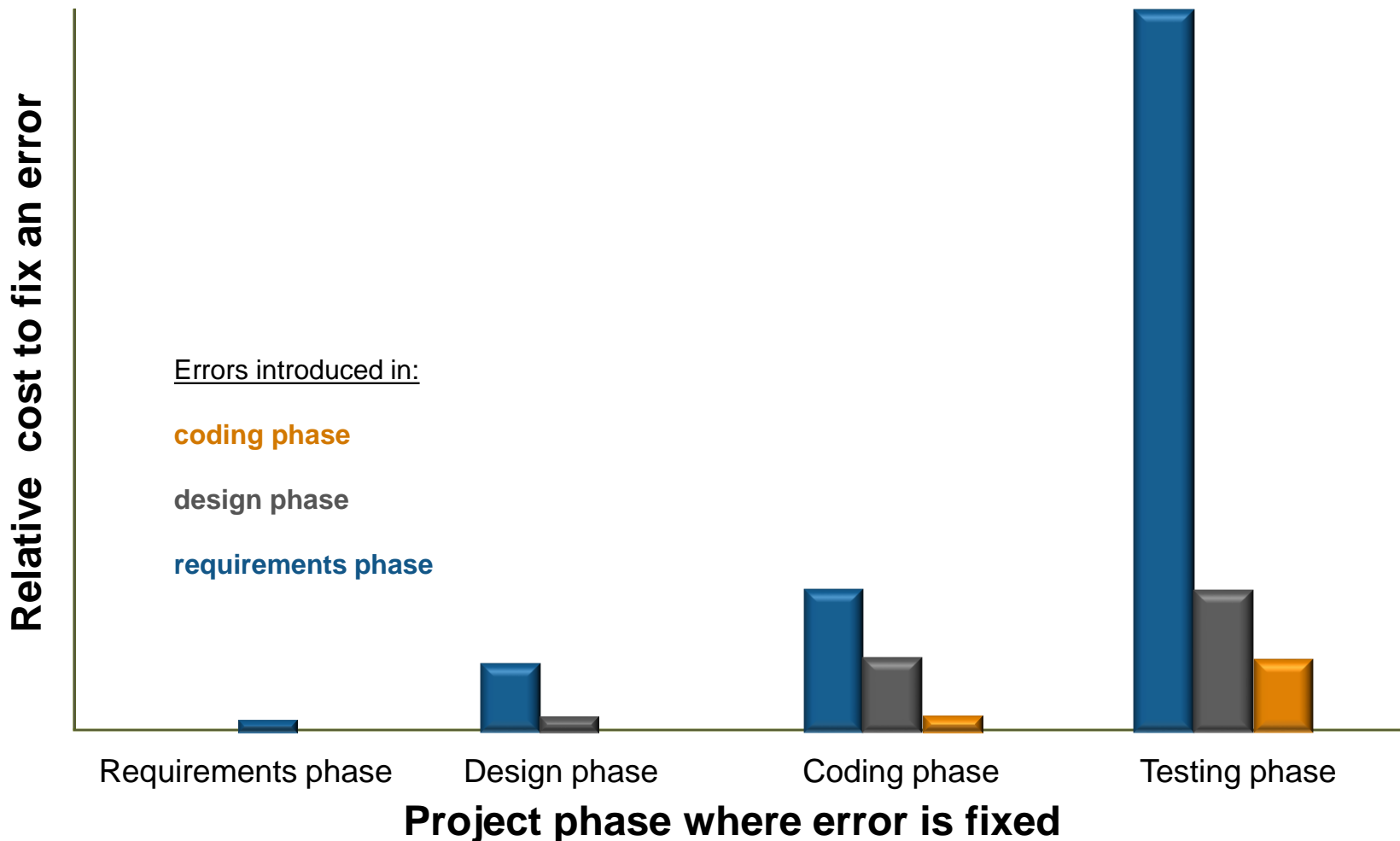
- Half-aircraft model
 - One generator
 - AC bus with loads
 - TRU (Transformer-Rectifier Unit)
 - DC bus with loads and battery
- Breakers open and close during flight cycle



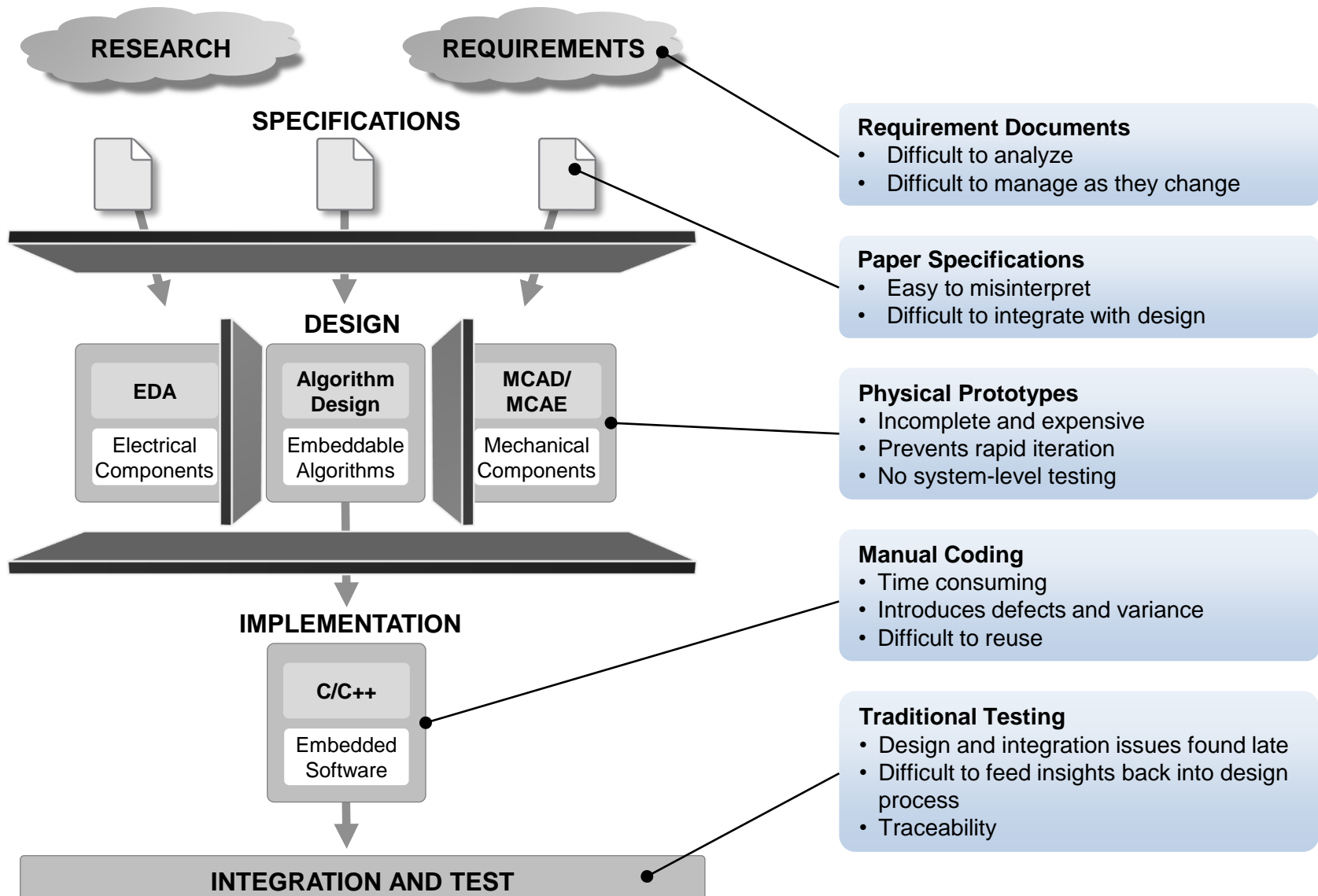
Agenda

- Intro / Overview
- Aircraft Power Network
- Physical Modeling
- Modeling Electronics and Power Systems
- Summary / Additional Resources

What is the Most Expensive Project Stage to Find Errors In?



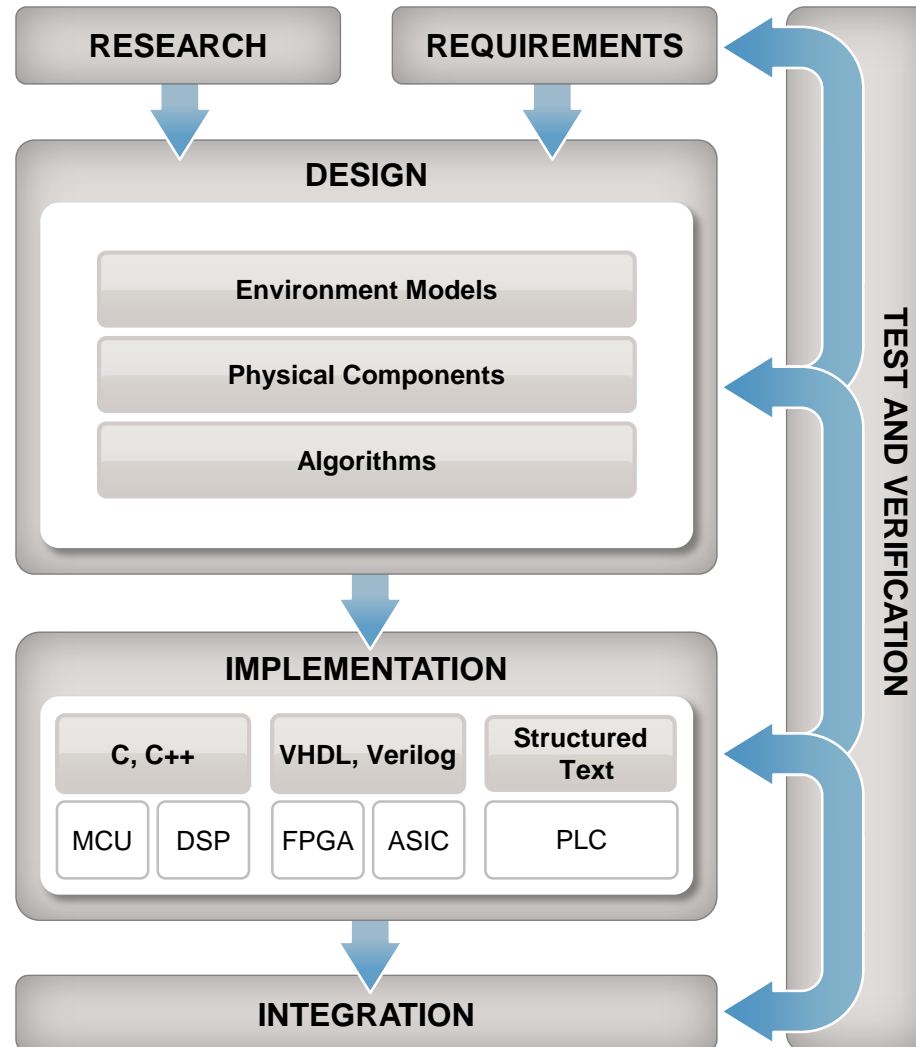
Traditional Development Process



Systems Engineering Categories

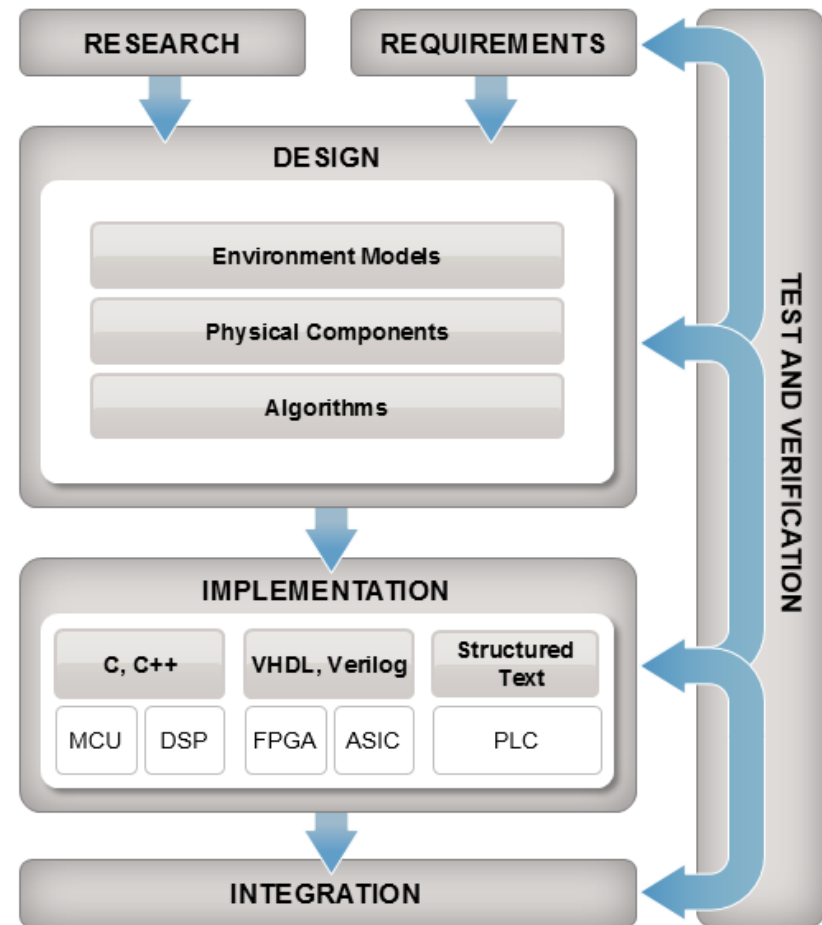
1. Mission / Purpose Definition (MD)
2. Requirements Engineering (RE)
3. System Architecting (SA)
4. System Integration (SI)
5. Verification and Validation (VV)
6. Technical Analysis (TA)
7. Scope Management (SM)
8. Technical Leadership / Management (TM)

Model-Based Design



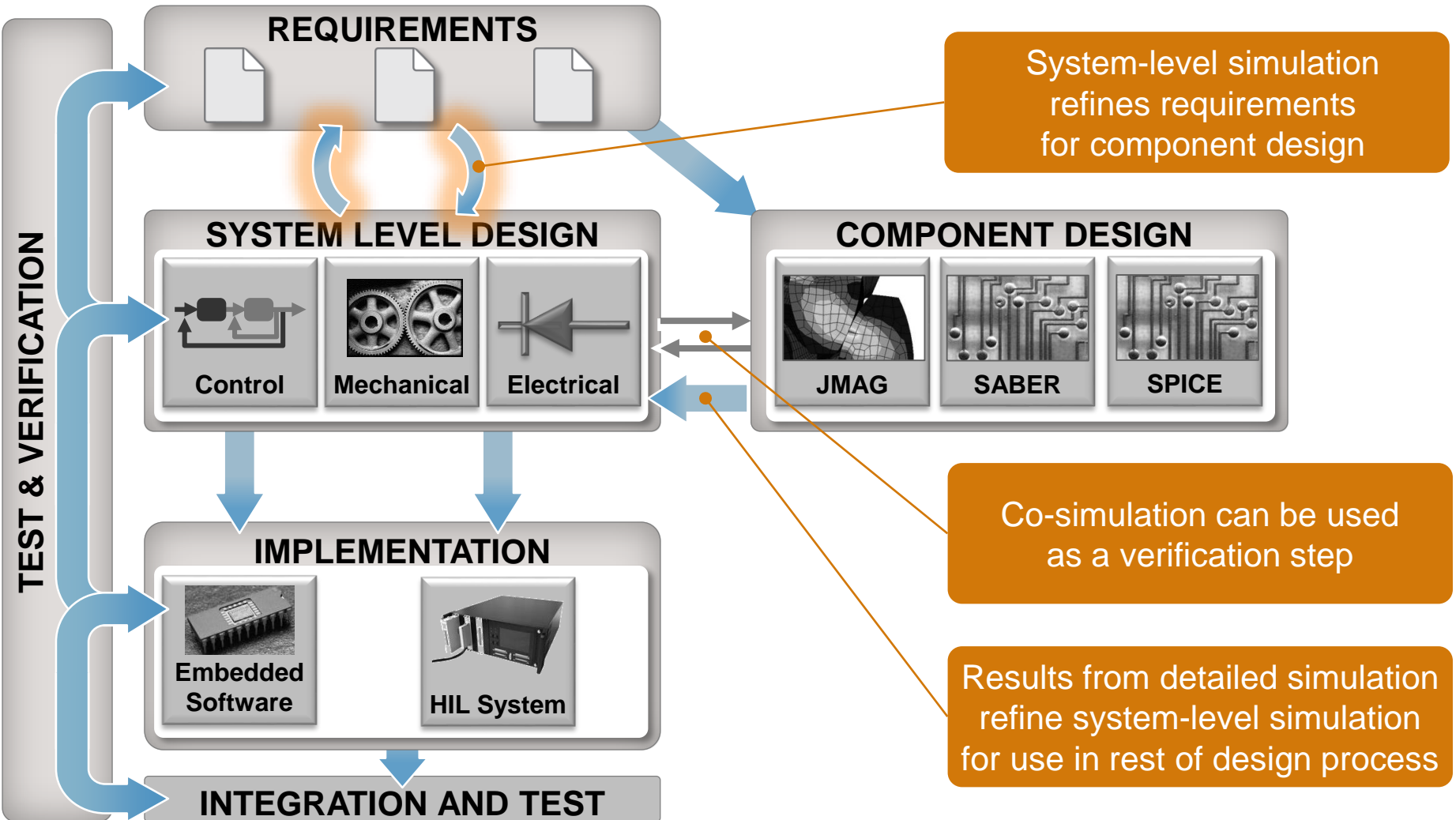
Systems Engineering and MBD

1. Mission
/ Purpose Definition
2. Requirements Engineering
3. System Architecting
4. System Integration
5. Verification and Validation
6. Technical Analysis
7. Scope Management
8. Technical Leadership
/ Management



Model-Based Design

System and Component Level Design

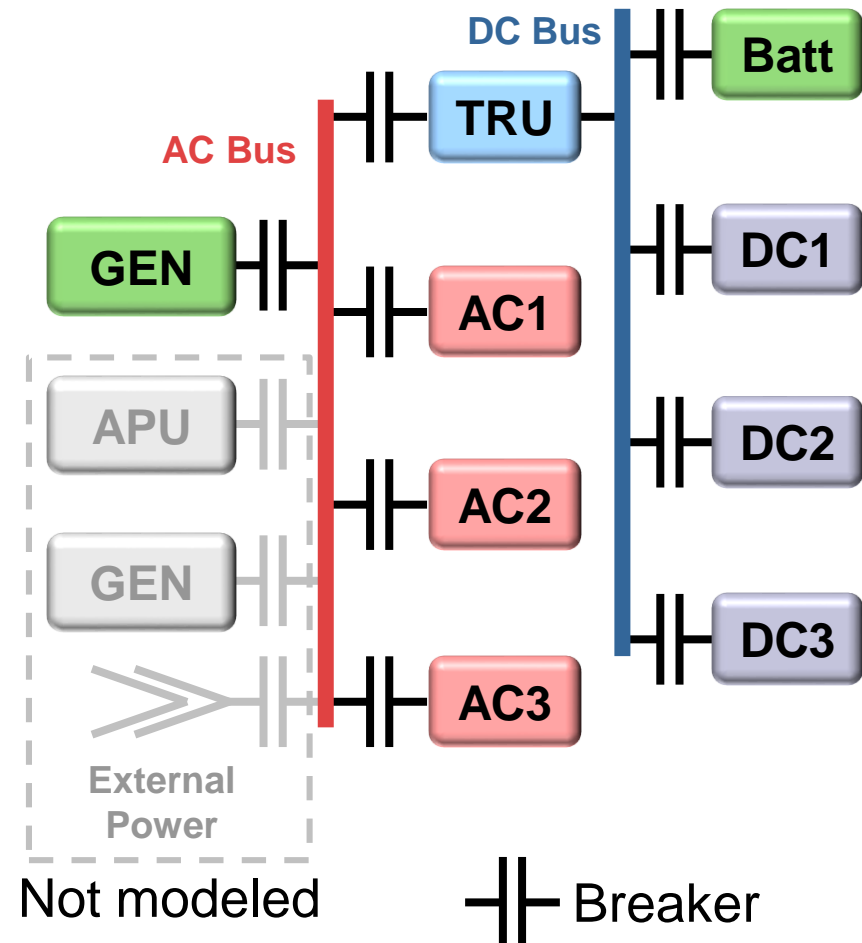


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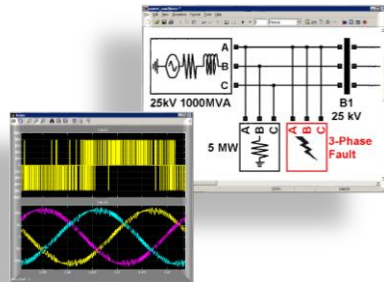
Aircraft Power Network

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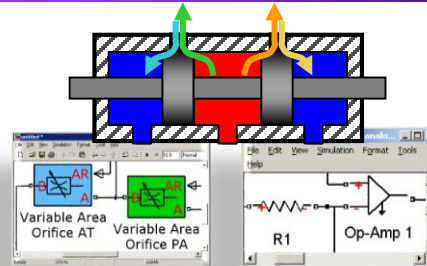
Physical Modeling

SimPowerSystems™



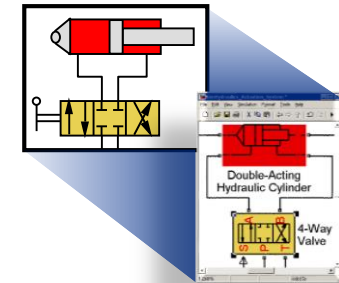
Electrical power systems

Simscape™



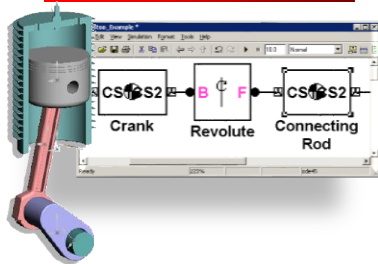
Multi-domain physical systems

SimHydraulics®



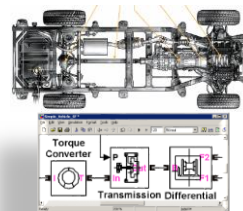
Fluid power and control

SimMechanics™



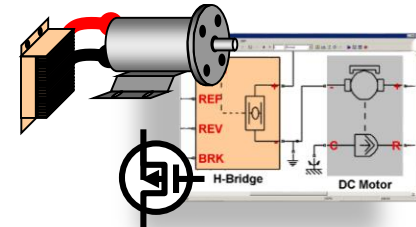
Mechanical dynamics (3-D)

SimDriveline™



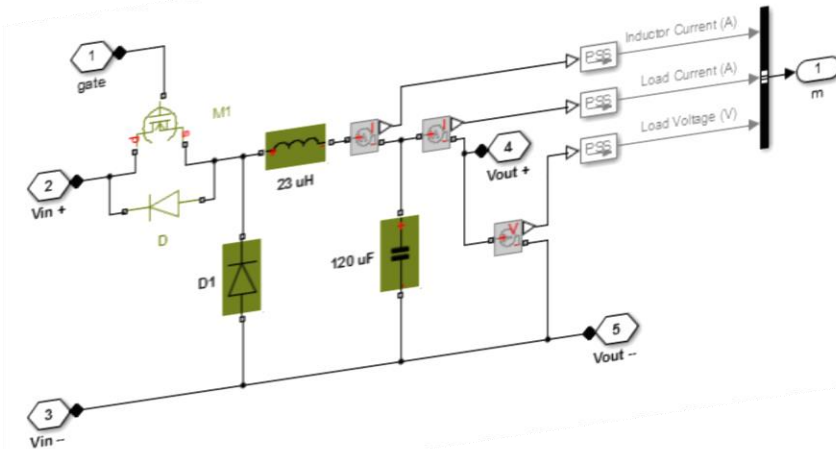
Drivetrain systems (1-D)

SimElectronics™



Electromechanical and electronic systems

Modeling Electronics and Power Systems



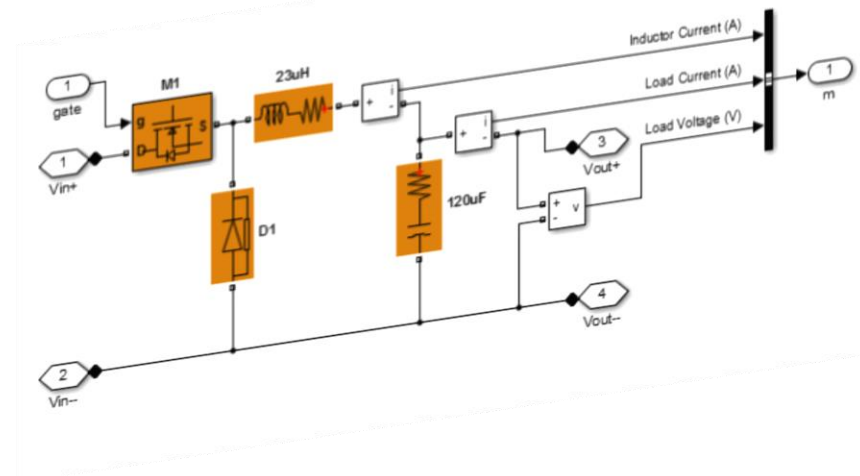
SimElectronics

Simultaneous nonlinear equations solution
 SPICE level switching device models
 Include switching losses
 Include parasitic current effects
 Include temperature effects
 Higher fidelity simulation

```
>> se_dcdcbuckconverter
```

SimPowerSystems

Piecewise linear systems solution
 Multiphase bridges and pulse generators
 Detailed and average voltage models
 Transient and harmonic analysis
 Faster simulation



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>> sps_dcdcbuckconverter
```


SimElectronics or SimPowerSystems?

SimElectronics

SimPowerSystems

SimElectronics Semiconductor Devices

SimPowerSystems Specialized Technology Power Electronics

The collector and base currents are [1]:

$$I_C = -IS \left[\left(e^{-qV_{BE}/(kT_{m1})} - e^{-qV_{BC}/(kT_{m1})} \right) \left(1 + \frac{V_{BC}}{V_A} \right) - \frac{1}{\beta_R} \left(e^{-qV_{BC}/(kT_{m1})} - 1 \right) \right]$$

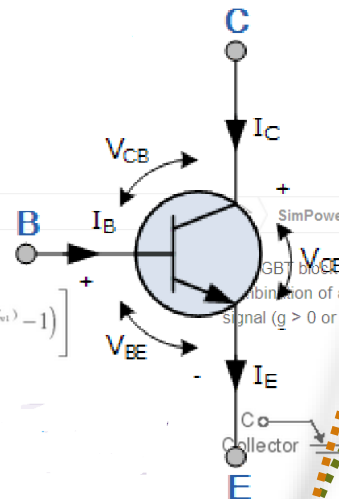
$$I_B = -IS \left[\frac{1}{\beta_F} \left(e^{-qV_{BE}/(kT_{m1})} - 1 \right) + \frac{1}{\beta_R} \left(e^{-qV_{BC}/(kT_{m1})} - 1 \right) \right]$$

Where:

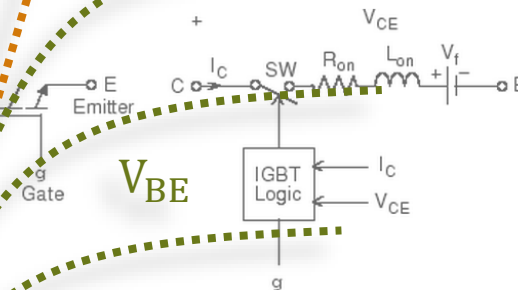
- I_B and I_C are base and collector currents, defined as positive into the device.
- IS is the saturation current.
- V_{BE} is the base-emitter voltage and V_{BC} is the base-collector voltage.
- β_F is the ideal maximum current gain BF
- β_R is the ideal maximum current gain BR
- V_A is the forward Early voltage VAF
- q is the elementary charge on an electron ($1.6021766 \times 10^{-19}$ Coulombs).
- k is the Boltzmann constant ($1.3806503 \times 10^{-23}$ J/K).
- T_{m1} is the transistor temperature, as defined by the Measurement temperature parameter value.

I_{CE}

V_{CE}



IGBT block implements a semiconductor device controllable by the gate signal. The IGBT is simulated as a series combination of a resistor R_{on} , inductor L_{on} , and a DC voltage source V_f in series with a switch controlled by a logical signal ($g > 0$ or $g = 0$).



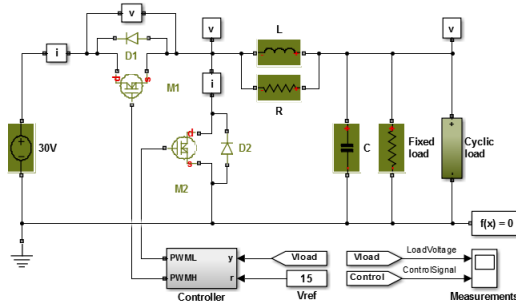
The IGBT turns on when the collector-emitter voltage is positive and greater than V_f and a positive signal is applied at the gate input ($g > 0$). It turns off when the collector-emitter voltage is positive and a 0 signal is applied at the gate input ($g = 0$).

The IGBT device is in the off state when the collector-emitter voltage is negative. Note that many commercial IGBTs do not have the reverse blocking capability. Therefore, they are usually used with an antiparallel diode.

SimElectronics or SimPowerSystems?

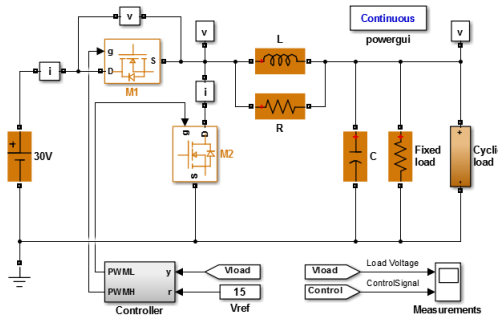
SimElectronics

Synchronous Buck Converter

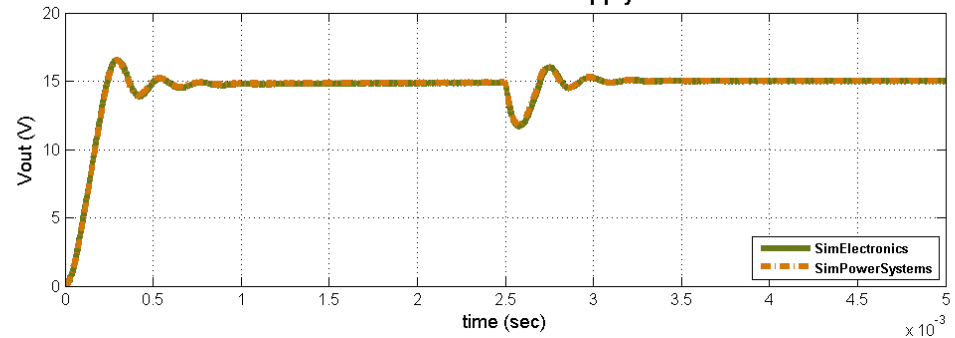


SimPowerSystems

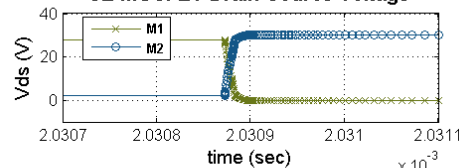
Synchronous Buck Converter



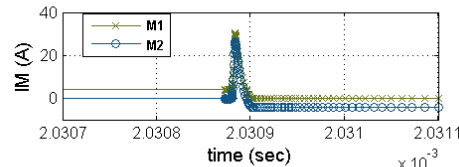
Switched Power Supply



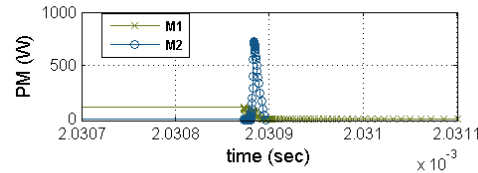
SE MOSFET Drain-Source Voltage



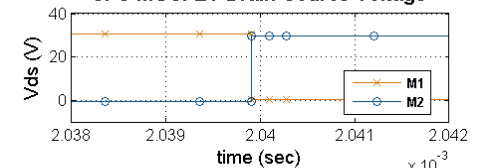
SE MOSFET Drain-Source Current



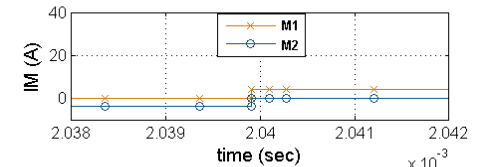
SE MOSFET Power



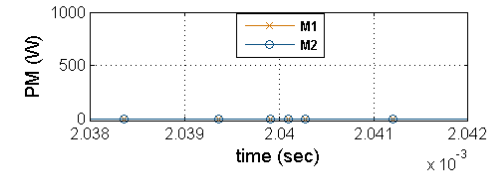
SPS MOSFET Drain-Source Voltage



SPS MOSFET Drain-Source Current



SPS MOSFET Power



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>> edit compare_powersupply
```

Logic and Controls

- Implement and Debug Logic Graphically
- Develop and Test Controls
- Code Generation

- Examples:
 - Synchronizing Breaker
 - Voltage Regulator

Verification and Validation

- Requirements Traceability
- Design Validation and Analysis
- Test and Verification

- Examples:
 - Aircraft Power Network
 - Managing Requirements for Fault-Tolerant Fuel Control System
 - Code Generation Verification Workflow with Simulink Test

Verification and Validation

- Model and Code Coverage
- Design Error and Bug Detection
- Certification, Standards and Code Proving

- Examples:
 - Top-Level Model Coverage Report
 - Find Defects from the Polyspace Environment
 - Workflow for Tool Qualification

Summary

- Design and Analyze Electrical and Power Systems
- Develop and Implement Logic and Controls
- Perform Verification and Validation

Additional Resources



- Videos and Webinars
 - [Aircraft Power Network](#) (4:58)
 - [Automatic Report Generation for Aircraft Power Network](#) (2:30)
 - [Running Parallel Simulations of Aircraft Flight Cycles](#) (5:00)
 - [Aircraft Power Network Development with MBD](#) (46:41)
- Example: [Aircraft Power Network on MATLAB Central](#)
- Documentation: ([SimElectronics](#)) ([SimPowerSystems](#))
- Tutorials: [Build and Simulate a Simple Circuit](#)
- Training: [Physical Modeling: Electrical Power Systems](#)
- Consulting: [Proven Solutions from MathWorks Consulting](#)


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MATLAB Answers

User Community

File Exchange

Find and Share Code

Blogs

Learn from Experts

Cody

Play Coding Game

Trendy

Track and Plot Trends

Thank You for Attending Today!

- Point of Contact
 - Cole Stephens, Lockheed Martin Account Manager
 - Cole.Stephens@mathworks.com
 - 508-647-1203

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 - MATLAB for Data Processing and Visualization



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pick up a give-away

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