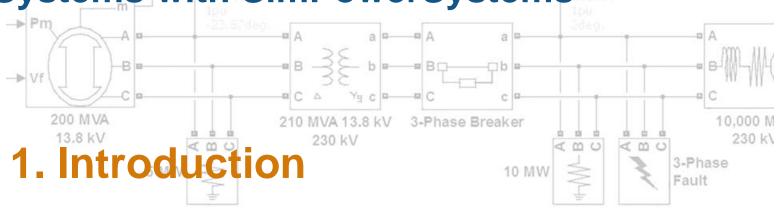


SimPowerSystems Hands-on Workshop: Modeling and Simulation of Electrical Power Systems with SimPowerSystems™





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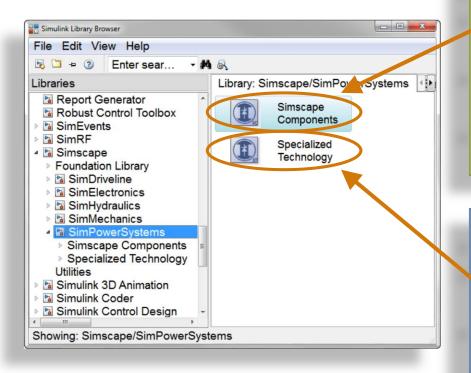


Outline

- SimPowerSystems component libraries
- How does SimPowerSystems work?



SimPowerSystems component libraries

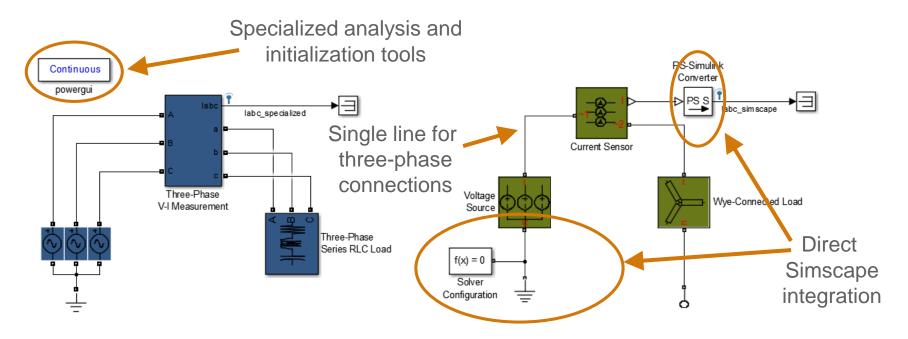


- Simscape based components
- Simultaneous linear and nonlinear network equations solution
- Direct Simscape integration for multi-domain modeling
- Create custom components using the Simscape Language
- Simulink based components
- Sequential solution of linear and nonlinear equations
- Continuous, discrete and phasor solver modes
- Large number of detailed electric and electronic components library
- Specialized analysis and initialization tools



SimPowerSystems component libraries

- >> threephase specialized
- >> threephase simscape



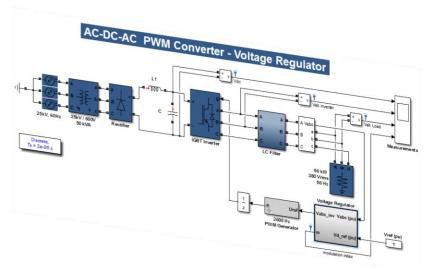
Specialized Technology

Simscape Components

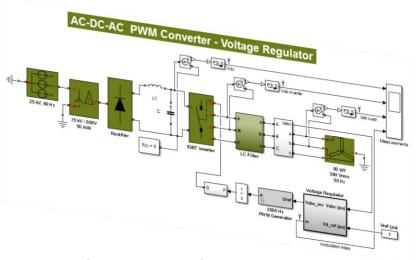


SimPowerSystems component libraries

- >> acdcac specialized
- >> acdcac simscape



Specialized Technology

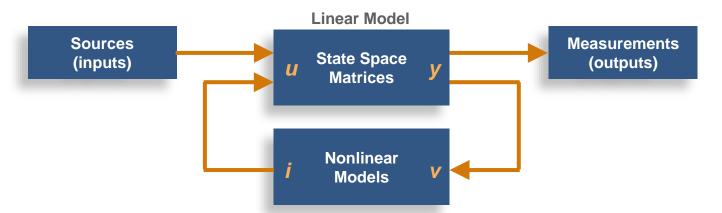


Simscape Components



Specialized Technology

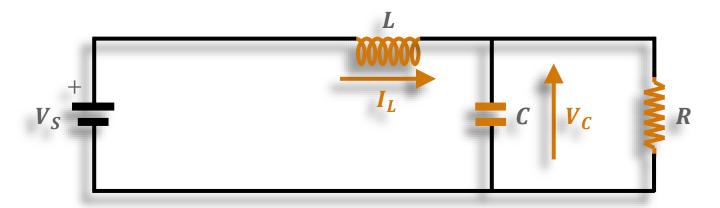
- The SimPowerSystems network is analyzed and a state-space model of the linear part of the network is created
- Any nonlinear elements are integrated as feedback elements around the linear state-space model



 This is all handled automatically by the powergui, but the user can also access the relevant analysis functions



Consider a simple RLC network



$$I_C = C \frac{dV_C}{dt}$$
, $V_L = L \frac{dI_L}{dt}$, $V_R = RI_R = V_C$

node currents: $I_C = I_L - I_R$

loop voltages: $V_L = V_S - V_C$



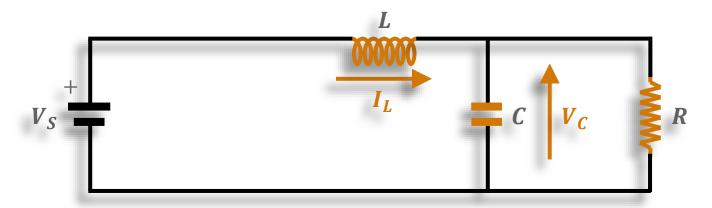
$$C\frac{dV_C}{dt} = I_L - \frac{1}{R}V_C$$

$$L\frac{dI_L}{dt} = V_S - V_C$$

>> rlc simulinkFinish



Consider a simple RLC network

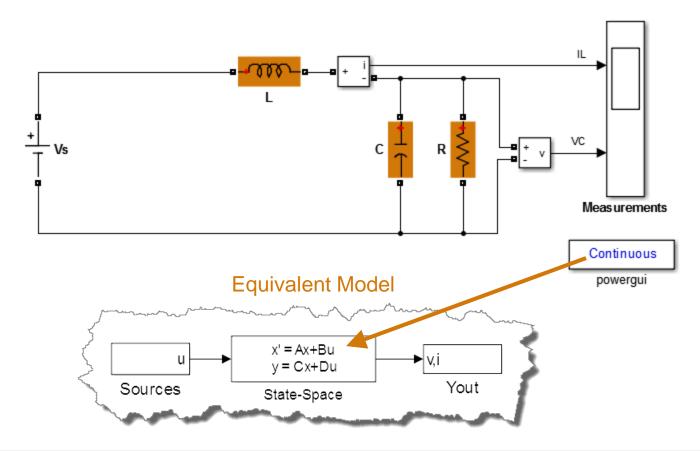


$$\frac{d}{dt} \begin{bmatrix} V_C \\ I_L \end{bmatrix} = \begin{bmatrix} -1/RC & 1/C \\ -1/L & 0 \end{bmatrix} \begin{bmatrix} V_C \\ I_L \end{bmatrix} + \begin{bmatrix} 0 \\ 1/L \end{bmatrix} V_S$$

$$y = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} V_C \\ I_L \end{bmatrix} + \begin{bmatrix} 0 \\ 0 \end{bmatrix} V_S$$



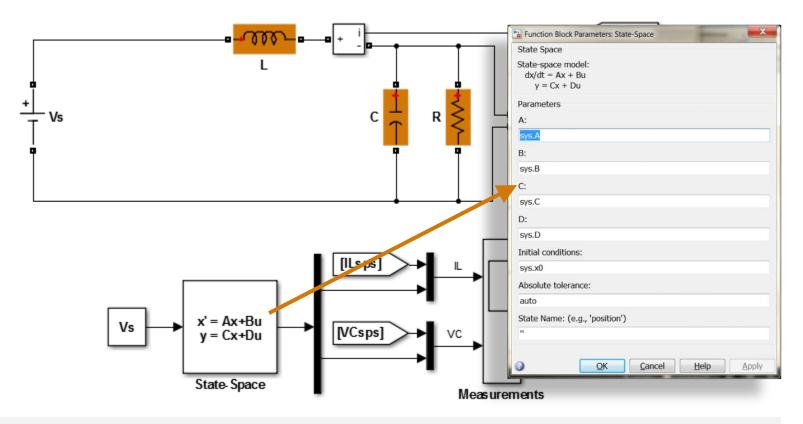
Consider a simple RLC network



>> sys = power_analyze('rlc_sps','structure');



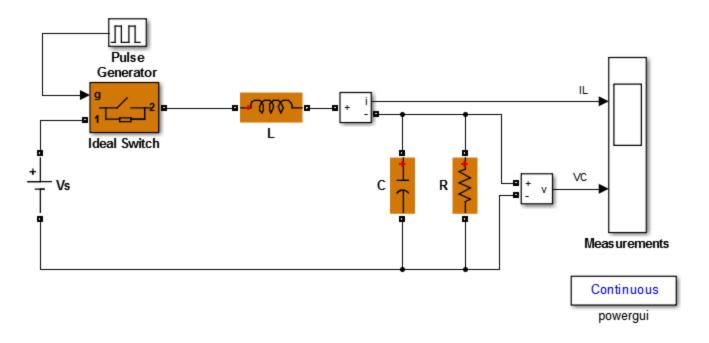
Consider a simple RLC network



>> rlc_sps_sl



Introduce an ideal switch



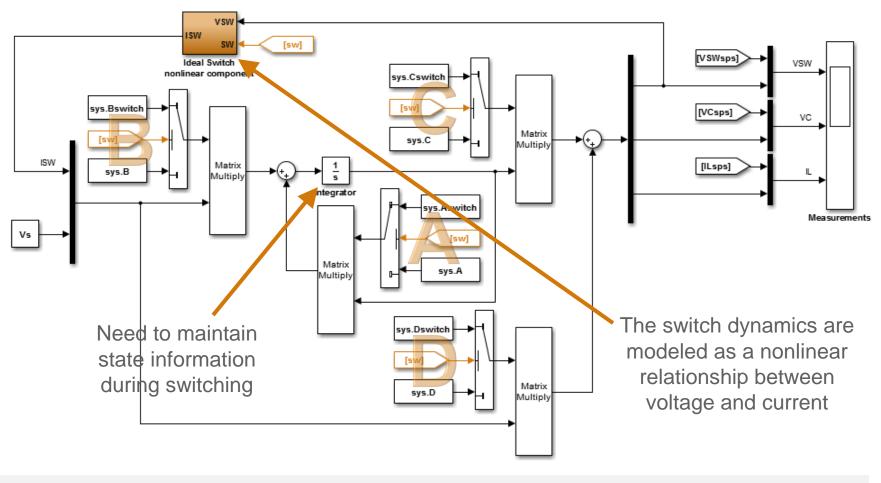
[A,B,C,D] system with the switch open

 $[A_{switch}, B_{switch}, C_{switch}, D_{switch}]$

>> sys = power_analyze('rlc_switch_sps','structure');



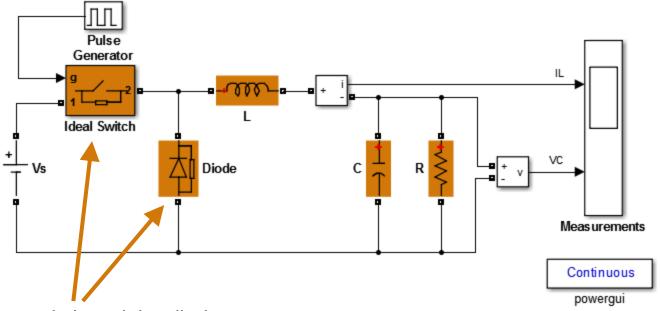
Introduce an ideal switch



>> rlc_switch_sps_sl



Introduce a diode to mitigate flyback

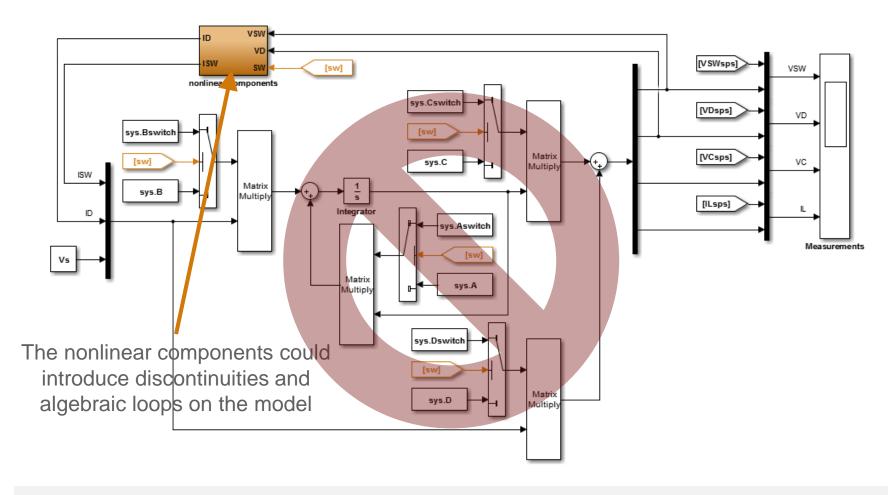


Both the switch and the diode are nonlinear elements and must be placed in the feedback path of the state-space model

>> rlc_diode_sps



Introduce a diode to mitigate flyback



>> rlc_diode_sps_sl



Introduce a diode to mitigate flyback

