

# Variational Autoencoder

Mark Chang

# Original Paper

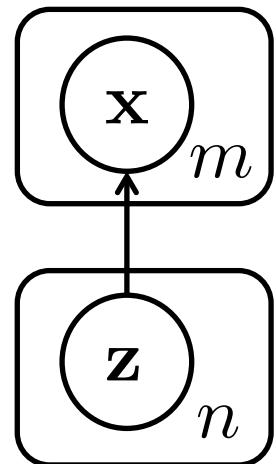
- Title:
  - Auto-Encoding Variational Bayes
- Author:
  - Diederik P. Kingma
  - Max Welling
- Organization:
  - Machine Learning Group, Universiteit van Amsterdam

# Outlines

- Variational Inference
- Variational Autoencoder
- Experiment
- Further Research

# Variational Inference

- Problem Definition
  - Observable Data:  $\mathbf{x} = \{x_1, x_2, \dots, x_m\}$
  - Hidden Variable:  $\mathbf{z} = \{z_1, z_2, \dots, z_n\}$
  - Posterior Distribution of hidden variable given some data:



$$p(\mathbf{z}|\mathbf{x}) = \frac{p(\mathbf{z}, \mathbf{x})}{p(\mathbf{x})} = \frac{p(\mathbf{x}|\mathbf{z})p(\mathbf{z})}{\int p(\mathbf{x}|\mathbf{z})p(\mathbf{z})d\mathbf{z}}$$

Intractable to compute

# Variational Inference

- Solutions for Intractable Posterior
  - Monte Carlo Sampling
    - Metropolis Hasting
    - Gibbs Sampling
  - **Variational Inference**

# Variational Inference

- Approximate  $p(\mathbf{z}|\mathbf{x})$  by  $q(\mathbf{z})$
- Minimize the KL Divergence:

$$D_{KL}[q(\mathbf{z})||p(\mathbf{z}|\mathbf{x})] = \int q(\mathbf{z}) \log \frac{q(\mathbf{z})}{p(\mathbf{z}|\mathbf{x})} d\mathbf{z}$$

# Evidence(Variational) Lower Bound

$$\begin{aligned} D_{KL}[q(\mathbf{z})||p(\mathbf{z}|\mathbf{x})] &= \int q(\mathbf{z})\log\frac{q(\mathbf{z})}{p(\mathbf{z}|\mathbf{x})}d\mathbf{z} \\ &= \int q(\mathbf{z})\log\frac{q(\mathbf{z})p(\mathbf{x})}{p(\mathbf{z}, \mathbf{x})}d\mathbf{z} \\ &= \int q(\mathbf{z})\log\frac{q(\mathbf{z})}{p(\mathbf{z}, \mathbf{x})}d\mathbf{z} + \int q(\mathbf{z})\log p(\mathbf{x})d\mathbf{z} \\ &= \int q(\mathbf{z})(\log q(\mathbf{z}) - \log p(\mathbf{z}, \mathbf{x}))d\mathbf{z} + \log p(\mathbf{x}) \\ &= -(E_{q(\mathbf{z})}[\log p(\mathbf{z}, \mathbf{x})] - E_{q(\mathbf{z})}[\log q(\mathbf{z})]) + \log p(\mathbf{x}) \end{aligned}$$

A horizontal brace under the last two terms of the equation, specifically under  $E_{q(\mathbf{z})}[\log p(\mathbf{z}, \mathbf{x})]$  and  $E_{q(\mathbf{z})}[\log q(\mathbf{z})]$ .

Evidence Lower Bound (ELBO):  $L[q(\mathbf{z})]$

# Evidence Lower Bound

$$D_{KL}[q(\mathbf{z})||p(\mathbf{z}|\mathbf{x})] = -L[q(\mathbf{z})] + \log p(\mathbf{x})$$

$$\log p(\mathbf{x}) = D_{KL}[q(\mathbf{z})||p(\mathbf{z}|\mathbf{x})] + L[q(\mathbf{z})]$$

Minimize  $D_{KL}[q(\mathbf{z})||p(\mathbf{z}|\mathbf{x})]$

is equal to Maximize  $L[q(\mathbf{z})]$

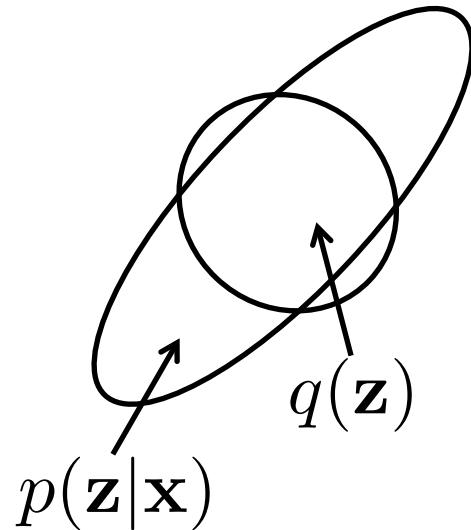
# Mean-Field Variational Inference

- Q can be factorized:

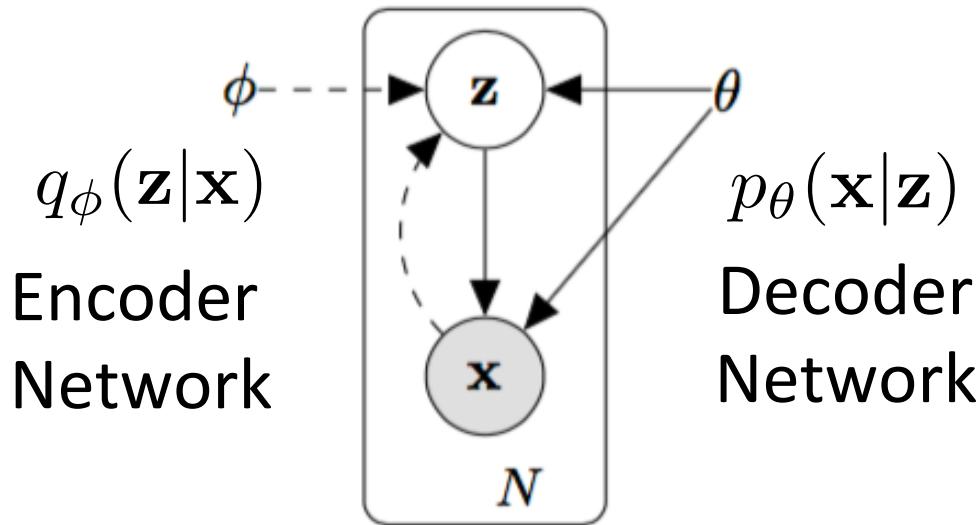
$$q(\mathbf{z}) = \prod_i q(z_i | \theta_i)$$

$$\forall i, \int q(z_i | \theta_i) dz_i = 1$$

Minimize  
 $D_{KL}[q(\mathbf{z}) || p(\mathbf{z} | \mathbf{x})]$



# Variational Autoencoder



Minimize:  $D_{KL}[q_\phi(\mathbf{z}|\mathbf{x}) || p_\theta(\mathbf{z}|\mathbf{x})]$

Intractable:  $p_\theta(\mathbf{z}|\mathbf{x}) = \frac{p_\theta(\mathbf{x}|\mathbf{z})p_\theta(\mathbf{z})}{p_\theta(\mathbf{x})}$

# Variational Autoencoder

Marginal Likelihood:

$$\log p_{\theta}(\mathbf{x}) = D_{KL}[q_{\phi}(\mathbf{z}|\mathbf{x}) || p_{\theta}(\mathbf{z}|\mathbf{x})] + L(\theta, \phi, \mathbf{x})$$

Variational Lower Bound:

$$\begin{aligned} L(\theta, \phi, \mathbf{x}) &= E_{q_{\phi}(\mathbf{z}|\mathbf{x})}[\log p_{\theta}(\mathbf{x}, \mathbf{z}) - \log q_{\phi}(\mathbf{z}|\mathbf{x})] \\ &= E_{q_{\phi}(\mathbf{z}|\mathbf{x})}[\log p_{\theta}(\mathbf{z}) + \log p_{\theta}(\mathbf{x}|\mathbf{z}) - \log q_{\phi}(\mathbf{z}|\mathbf{x})] \\ &= E_{q_{\phi}(\mathbf{z}|\mathbf{x})}[\log \frac{p_{\theta}(\mathbf{z})}{q_{\phi}(\mathbf{z}|\mathbf{x})} + p_{\theta}(\mathbf{x}|\mathbf{z})] \\ &= -D_{KL}[q_{\phi}(\mathbf{z}|\mathbf{x}) || p_{\theta}(\mathbf{z})] + E_{q_{\phi}(\mathbf{z}|\mathbf{x})}[\log p_{\theta}(\mathbf{x}|\mathbf{z})] \end{aligned}$$

# Monte Carlo Gradient Estimator

Gradient of  $L(\theta, \phi, \mathbf{x})$  contains  $\nabla_{\phi} E_{q_{\phi}(\mathbf{z}|\mathbf{x})}[\log p_{\theta}(\mathbf{x}|\mathbf{z})]$   
which is Intractable

Use Monte Carlo Gradient Estimator :

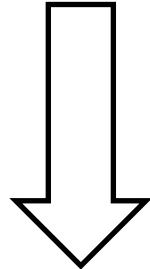
$$\begin{aligned}\nabla_{\phi} E_{q_{\phi}(\mathbf{z})}[f(\mathbf{z})] &= \nabla_{\phi} \int q_{\phi}(\mathbf{z}) f(\mathbf{z}) d\mathbf{z} \\ &= \int q_{\phi}(\mathbf{z}) f(\mathbf{z}) \frac{\nabla_{\phi} q_{\phi}(\mathbf{z})}{q_{\phi}(\mathbf{z})} d\mathbf{z} = \int q_{\phi}(\mathbf{z}) f(\mathbf{z}) \nabla_{\phi} \log q_{\phi}(\mathbf{z}) d\mathbf{z} \\ &= E_{q_{\phi}(\mathbf{z})}[f(\mathbf{z}) \nabla_{\phi} \log q_{\phi}(\mathbf{z})] \\ &\approx \frac{1}{L} \sum_{l=1}^L f(\mathbf{z}) \nabla_{\phi} \log q_{\phi}(\mathbf{z}^{(l)}) \quad \text{where } \mathbf{z}^{(l)} \sim q_{\phi}(\mathbf{z})\end{aligned}$$

# Objective Function

$$L(\theta, \phi, \mathbf{x}^{(i)}) = -D_{KL}[q_\phi(\mathbf{z}|\mathbf{x}^{(i)})||p_\theta(\mathbf{z})] + E_{q_\phi(\mathbf{z}|\mathbf{x}^{(i)})}[\log p_\theta(\mathbf{x}^{(i)}|\mathbf{z})]$$

Monte Carlo Gradient Estimator

$$\tilde{L}(\theta, \phi, \mathbf{x}^{(i)}) \approx L(\theta, \phi, \mathbf{x}^{(i)})$$

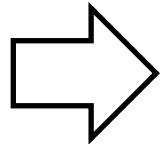


$$\tilde{L}(\theta, \phi, \mathbf{x}^{(i)}) = -D_{KL}[q_\phi(\mathbf{z}|\mathbf{x}^{(i)})||p_\theta(\mathbf{z})] + \frac{1}{L} \sum_{l=1}^L \log p_\theta(\mathbf{x}^{(i)}|\mathbf{z}^{(i,l)})$$

where  $\mathbf{z}^{(l)} \sim q_\phi(\mathbf{z}|\mathbf{x}^{(i,l)})$

# Reparameterization Trick

$$\mathbf{z} \sim q_\phi(\mathbf{z}|\mathbf{x})$$



auxiliary variable

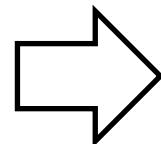
$$\epsilon \sim p(\epsilon)$$

deterministic variable

$$\mathbf{z} = g_\phi(\epsilon, \mathbf{x})$$

Example:

$$z \sim p(z|x) = \mathcal{N}(\mu, \sigma^2)$$



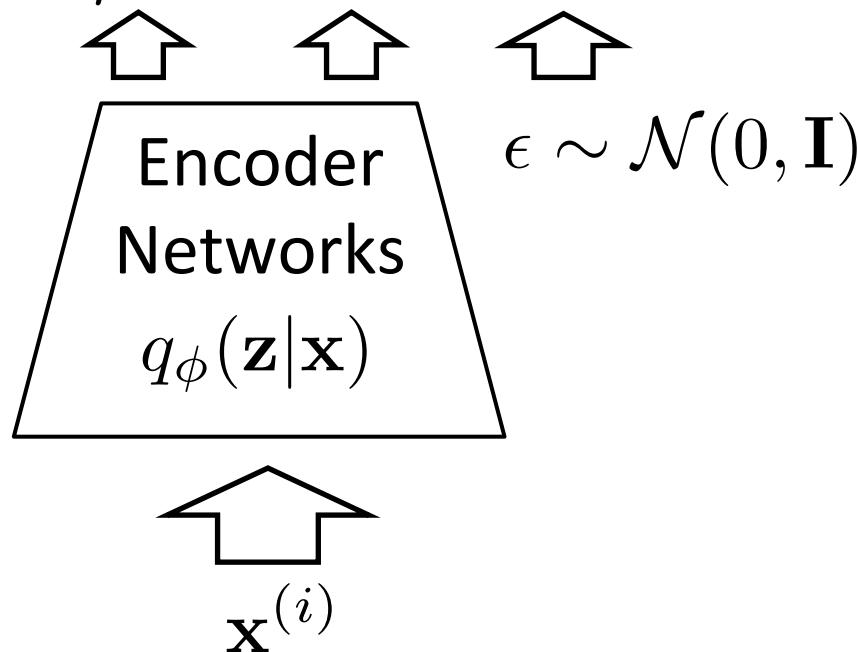
$$\epsilon \sim \mathcal{N}(0, 1)$$

$$z = \mu + \sigma\epsilon$$

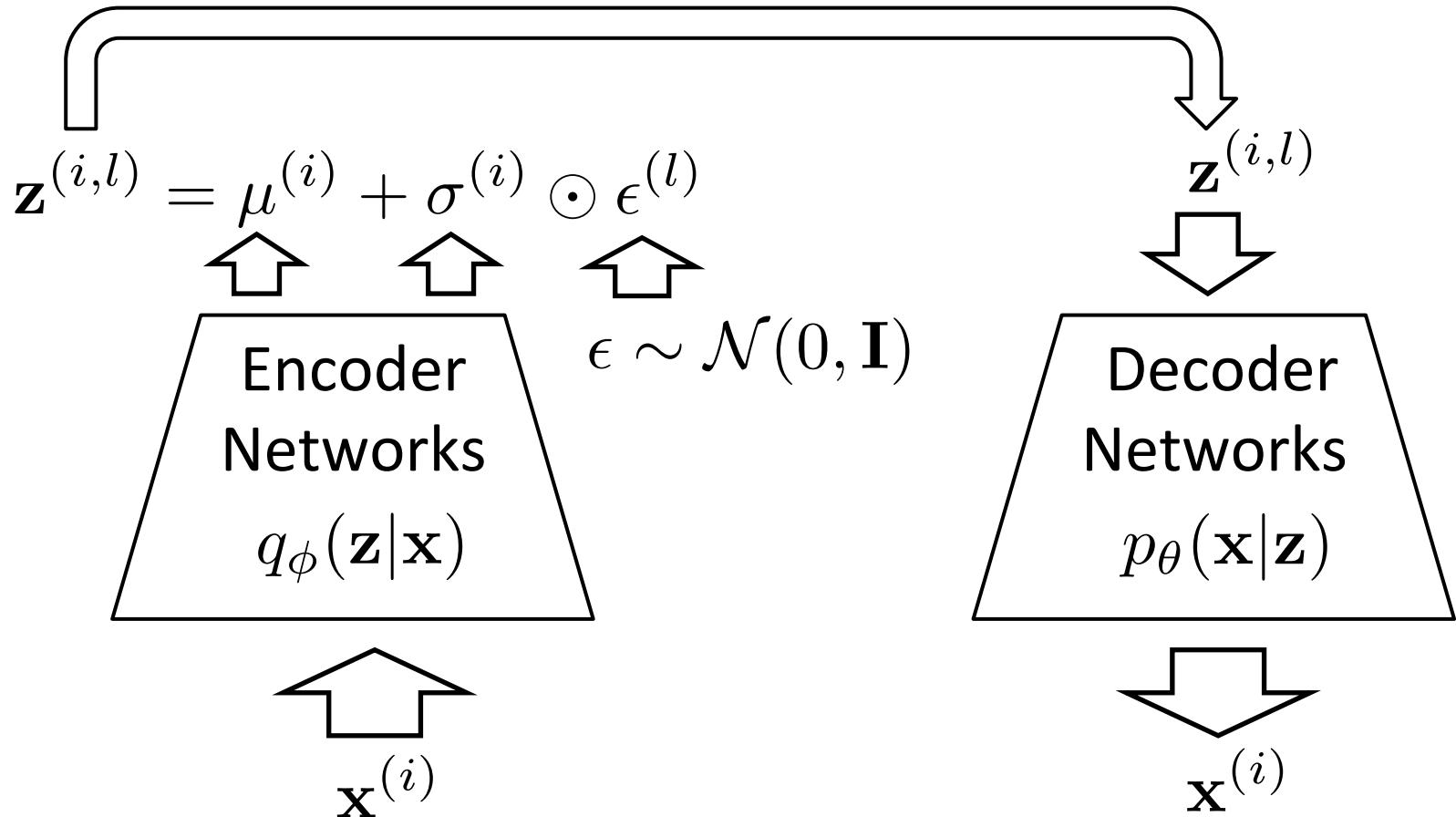
# Reparameterization Trick

$$\log q_{\phi}(\mathbf{z}|\mathbf{x}^{(i)}) = \log \mathcal{N}(\mathbf{z}, \mu^{(i)}, \sigma^{2(i)} \mathbf{I})$$

$$\mathbf{z}^{(i,l)} = \mu^{(i)} + \sigma^{(i)} \odot \epsilon^{(l)}$$

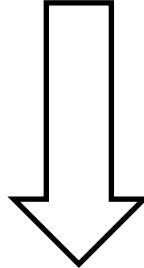


# Reparameterization Trick



# Objective Function

$$\tilde{L}(\theta, \phi, \mathbf{x}^{(i)}) = -D_{KL}[q_\phi(\mathbf{z}|\mathbf{x}^{(i)})||p_\theta(\mathbf{z})] + \frac{1}{L} \sum_{l=1}^L (\log p_\theta(\mathbf{x}^{(i)}|\mathbf{z}^{(i,l)})$$

$$q_\phi(\mathbf{z}|\mathbf{x}^{(i)}) = \mathcal{N}(\mathbf{z}, \mu^{(i)}, \sigma^{2(i)}\mathbf{I})$$
$$p_\theta(\mathbf{z}) = \mathcal{N}(\mathbf{z}, 0, \mathbf{I})$$


$$\tilde{L}(\theta, \phi, \mathbf{x}^{(i)}) = \frac{1}{2} \sum_{j=1}^J (1 + \log((\sigma_j^{(i)})^2) - (\mu_j^{(i)})^2 - (\sigma_j^{(i)})^2) + \frac{1}{L} \sum_{l=1}^L (\log p_\theta(\mathbf{x}^{(i)}|\mathbf{z}^{(i,l)})$$


Regularization

Reconstruction  
Error

# Training

---

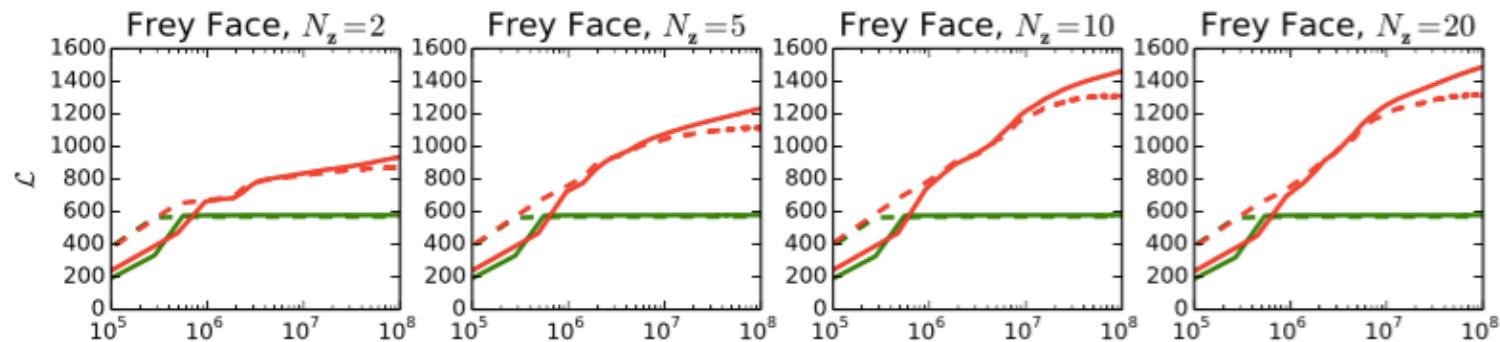
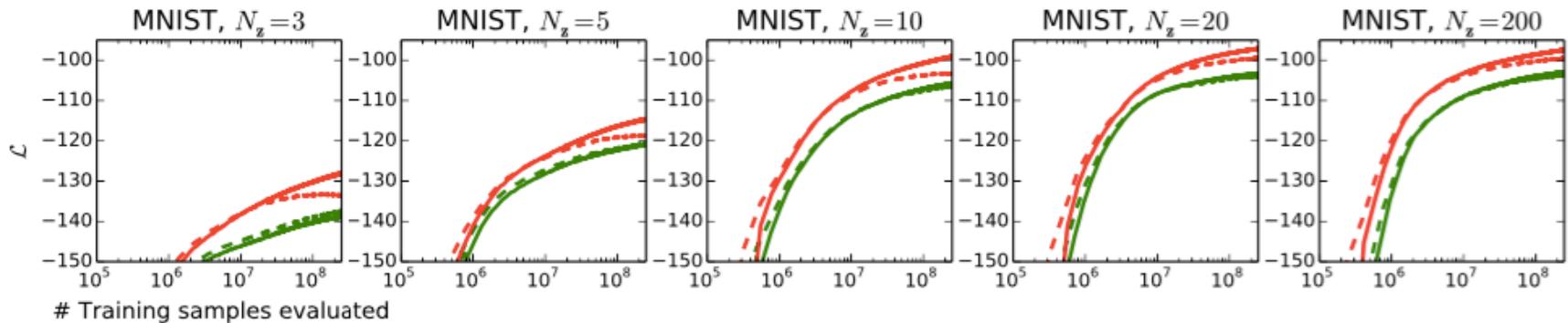
**Algorithm 1** Minibatch version of the Auto-Encoding VB (AEVB) algorithm. Either of the two SGVB estimators in section 2.3 can be used. We use settings  $M = 100$  and  $L = 1$  in experiments.

---

```
 $\theta, \phi \leftarrow$  Initialize parameters  
repeat  
   $\mathbf{X}^M \leftarrow$  Random minibatch of  $M$  datapoints (drawn from full dataset)  
   $\epsilon \leftarrow$  Random samples from noise distribution  $p(\epsilon)$   
   $\mathbf{g} \leftarrow \nabla_{\theta, \phi} \tilde{\mathcal{L}}^M(\theta, \phi; \mathbf{X}^M, \epsilon)$  (Gradients of minibatch estimator (8))  
   $\theta, \phi \leftarrow$  Update parameters using gradients  $\mathbf{g}$  (e.g. SGD or Adagrad [DHS10])  
until convergence of parameters  $(\theta, \phi)$   
return  $\theta, \phi$ 
```

---

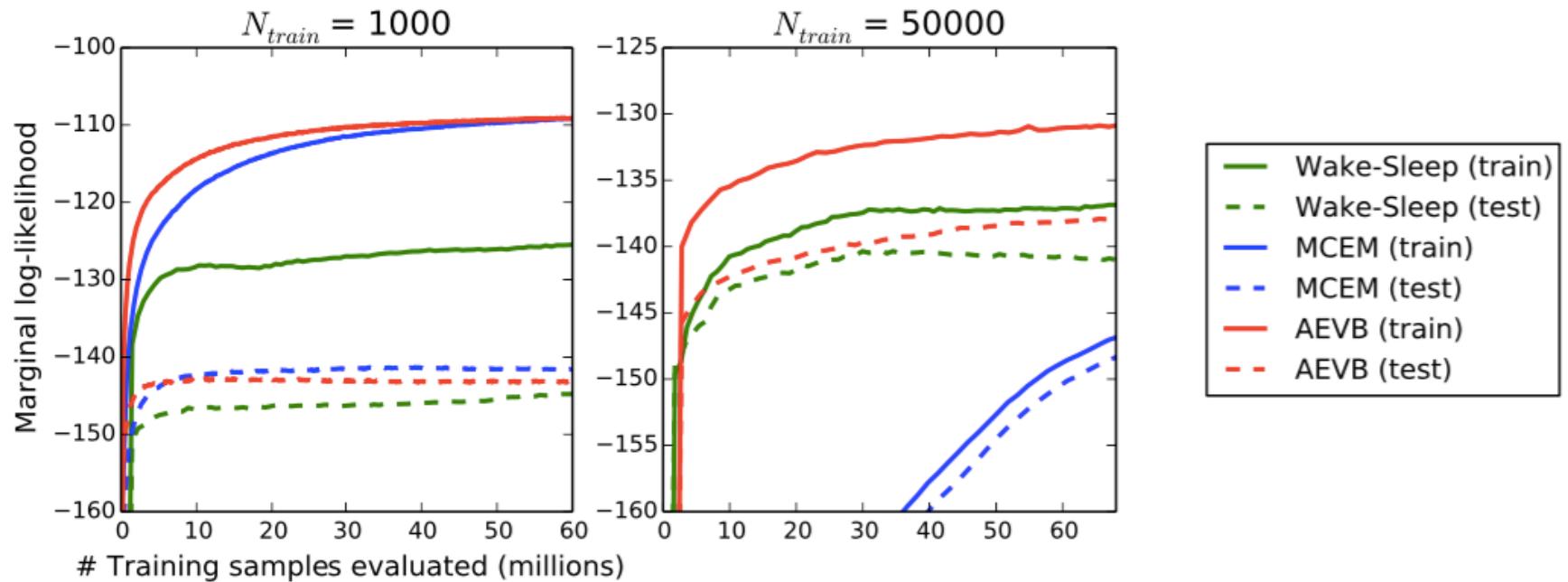
# Experiment



- · Wake-Sleep (test)
- Wake-Sleep (train)
- · AEVB (test)
- AEVB (train)

Horizontal axis: size of training data  
Vertical axis: evidence Lower Bound  
 $N_z$ : dimensions of hidden variables

# Experiment



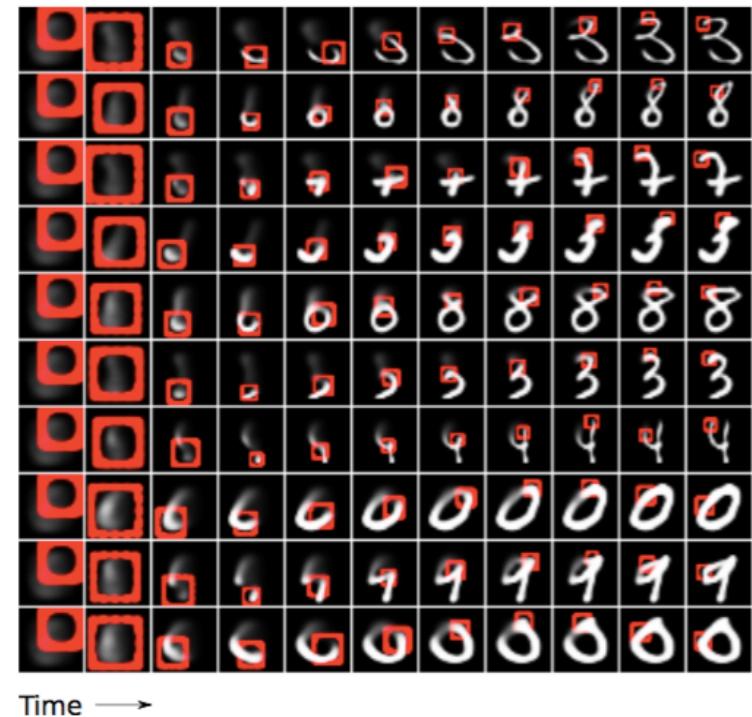
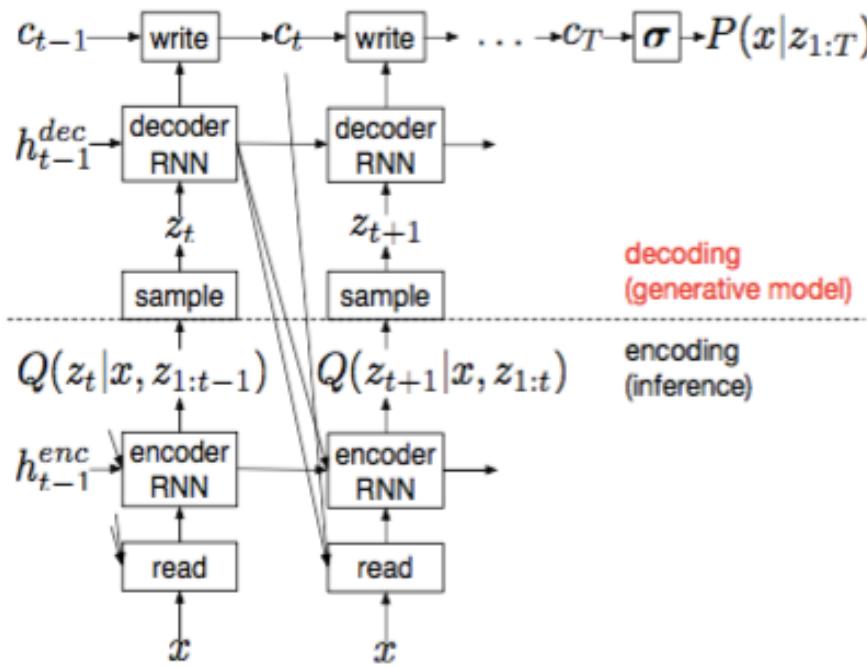
# Experiment

# Visualization of 2d latent space

# Further Research

## DRAW: A Recurrent Neural Network For Image Generation

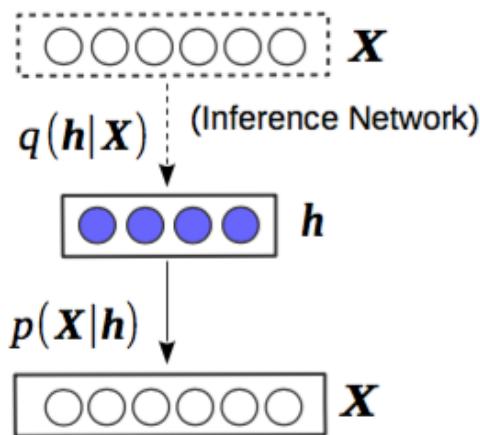
Karol Gregor, Ivo Danihelka, Alex Graves, Danilo Jimenez Rezende and Daan Wierstra



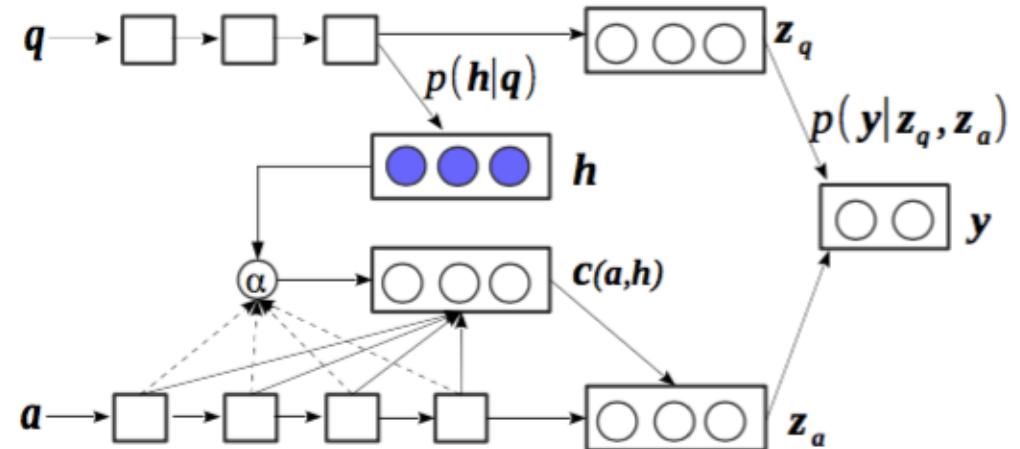
# Further Research

## Neural Variational Inference for Text Processing

Yishu Miao, Lei Yu & Phil Blunsom



Neural Variational Document Model

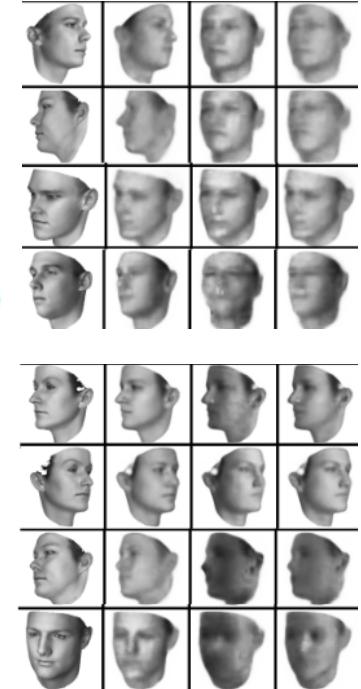
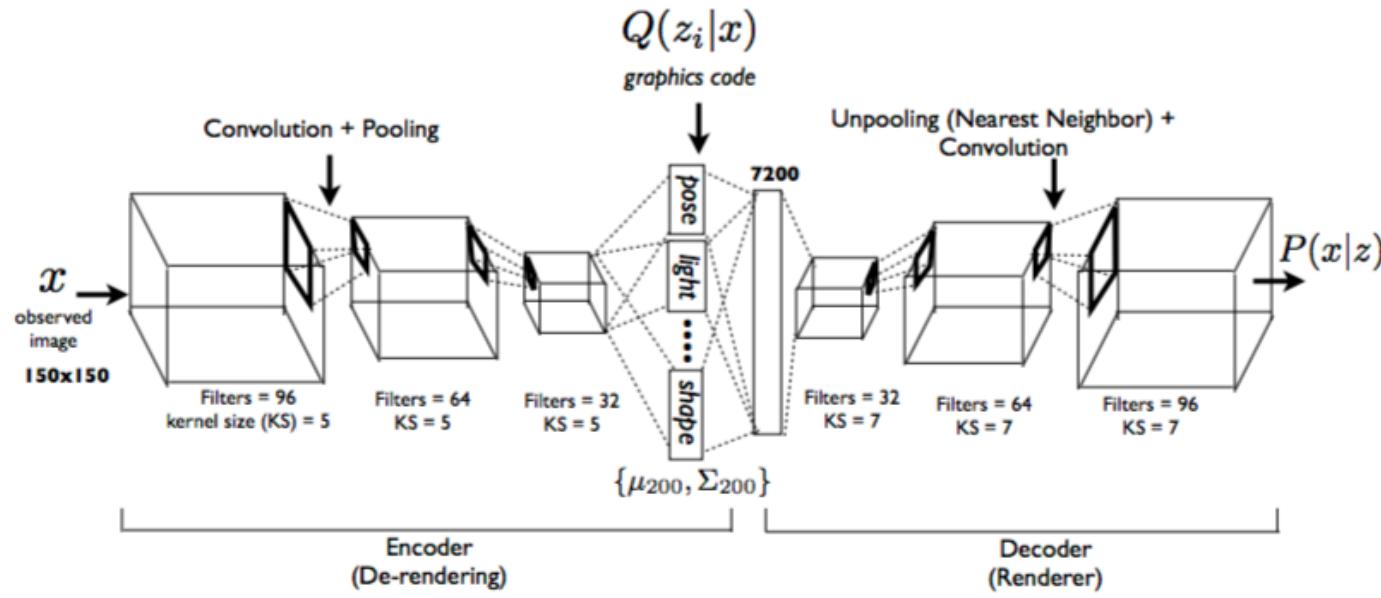


Neural Answer Selection Model

# Further Research

## Deep Convolutional Inverse Graphics Network

Tejas D. Kulkarni, William F. Whitney, Pushmeet Kohli, Joshua B. Tenenbaum



# Source Code

- [https://jmetzen.github.io/2015-11-27/  
vae.html](https://jmetzen.github.io/2015-11-27/vae.html)

# Reference

- Charles Fox, Stephen Roberts. A Tutorial on Variational Bayesian Inference.
  - [http://www.orchid.ac.uk/eprints/40/1/  
fox\\_vbtut.pdf](http://www.orchid.ac.uk/eprints/40/1/fox_vbtut.pdf)
- Diederik P Kingma, Max Welling. Auto-Encoding Variational Bayes.
  - <https://arxiv.org/pdf/1312.6114v10.pdf>