

$$\boxed{11} \quad 1. \quad \bar{G}(s)G_c(s) = \frac{K}{s+p} \cdot \frac{1}{s} = K \cdot \underbrace{\frac{1}{s(s+p)}}_{G(s)}$$

2. 1 because of pole in  $G(s)$  at the origin

$$3. \quad \Delta_{cl}(s) = s(s+p) + K \\ = s^2 + ps + K$$

asympt. stable for  $p > 0, K > 0$  via Hurwitz criterion.

$$4. \quad s^2 + 2\zeta\omega_n s + \omega_n^2 = s^2 + ps + K$$

$$2\zeta\omega_n = p$$

$$\omega_n^2 = K$$

$$\omega_n = \sqrt{K}$$

$$\zeta = \frac{p}{2\omega_n}$$

$$= \frac{p}{2\sqrt{K}}$$

12 1. (b) b/c for a type 1 system,  $e_{ss} = 0$  to a unit step.

$$\begin{aligned} 2. e_{ss} &= \frac{1}{K_v}, \quad K_v = \lim_{s \rightarrow 0} s K G(s) \\ &= \lim_{s \rightarrow 0} s \cdot K \cdot \frac{1}{s(s+p)} \\ &= \frac{K}{p} \end{aligned}$$

$\therefore e_{ss} = \frac{p}{K} \Rightarrow$  (b) is correct.

$$3. T_s = \frac{4}{f_{wn}} \leq 8 \qquad e_{ss} = \frac{p}{K} \leq \frac{1}{16}$$

$$\frac{1}{2} \leq f_{wn}$$

$$\frac{1}{2} \leq \frac{p}{2}$$

$$10p \leq K$$

$$10 \cdot 2 \not\leq 16$$

$$1 \leq p \leftarrow p=2 \text{ satisfies this}$$

$K=16, p=2$   
does not  
satisfy ss error  
criteria.

4. Please see next page.

$$5. Y(s) = \frac{G(s)}{1+KG(s)} \cdot D(s) + \frac{KG(s)}{1+KG(s)} \cdot R(s)$$

$$\frac{N(s)}{D(s)+KN(s)} = \frac{1}{s^2+ps+K}$$

$$y_{ss} = \lim_{s \rightarrow 0} s \cdot \frac{1}{s^2+ps+K} \cdot \frac{1}{s} = \frac{1}{K}$$

$\therefore$  (a) is correct.

4. This plot shows steady-state error, not marginal stability. We know the system is asymptotically stable. It should converge to 0 if there is perfect tracking, but because this system is type 1, perfect tracking is not possible.

