

Unsupervised Support Vector Machines

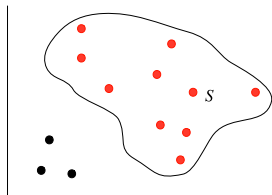
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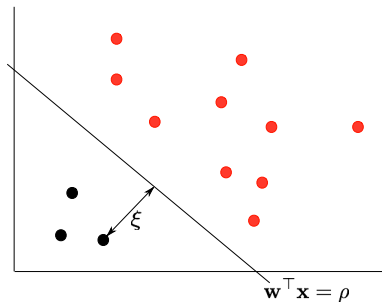
- Idea of SV Novelty Detection:

Assume some dataset drawn from a latent probability distribution P . Estimate a simple subset S of input space such that the probability that a test point drawn from P lies outside of S equals some a priori specified ν between 0 and 1. (Schölkopf et al 2001).



- The problem is classical, and it can be solved from the point of view of SLT by imposing positiveness in S and negativeness in the complement while at the same time maximizing a margin.

- The strategy adopted assumes that almost all the data can be separated from the origin with a hyperplane, and only a small subset with probability ν will be in the space between the hyperplane and the origin. In order to confine the *normal data* in the smallest possible space, we maximize the distance of the hyperplane to the center.



- This is very restrictive, but the limitations disappear when the formulation is extended to kernel spaces.
- The formulation of the primal optimization is

$$\begin{aligned} & \text{Minimize } \|\mathbf{w}\|^2 + \frac{1}{N\nu} \sum_{n=1}^N \xi_n - \rho \\ & \text{subject to } \begin{cases} \mathbf{w}^\top \mathbf{x}_n \geq \rho - \xi_n \\ \xi_n \geq 0 \end{cases} \end{aligned}$$

- The corresponding dual is

$$\begin{aligned} & \text{Minimize } \boldsymbol{\alpha}^\top \mathbf{K} \boldsymbol{\alpha} \\ & \text{subject to } \begin{cases} 0 \leq \alpha_n \leq \frac{1}{N\nu} \\ \sum_{n=1} \alpha_i = 1 \end{cases} \end{aligned}$$

- This minimization can be solved by QP.
- Since any \mathbf{x}_n for which $0 < \alpha_n < \frac{1}{N\nu}$ satisfies the equality $\mathbf{w}^\top \mathbf{x}_n + \rho = 0$, ρ can be easily recovered.

Assume the solution of

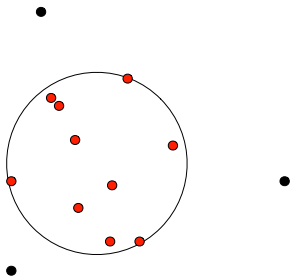
$$\mathbf{w}^\top \mathbf{x}_n \geq \rho - \xi_n$$

satisfies $\rho \neq 0$. The following statements hold:

- (i) ν is an upper bound on the fraction of outliers.
- (ii) ν is a lower bound on the fraction of SVs.
- (iii) Suppose the data were generated independently from a distribution $P(\mathbf{x})$ which does not contain discrete components. With probability 1, asymptotically, ν equals both the fraction of SVs and the fraction of outliers.

The concept of the SVDD is the following:

- Assume a data set containing N objects, \mathbf{x}_i , and a compact description of this data is required.
- The description is given by a sphere of center \mathbf{a} radius R , with minimum radius and which contains all (or most of) the data.
- The most outlying objects are allowed to be outside the sphere.



- The corresponding optimization problem is

$$\begin{aligned} & \text{Minimize } R^2 + C \sum_{n=1}^N \xi_n \\ & \text{subject to } \begin{cases} \|\mathbf{x}_n - \mathbf{a}\|^2 \leq R^2 + \xi_n \\ \xi_n \geq 0 \end{cases} \end{aligned}$$

- The solution is found by incorporating the constraints to the functional through Lagrange multipliers.

- The dual functional is

$$\begin{aligned} & \text{Minimize} \quad -\boldsymbol{\alpha}^\top \mathbf{K} \boldsymbol{\alpha} + \boldsymbol{\alpha}^\top \mathbf{z} \\ & \text{subject to} \quad \begin{cases} \sum_{n=1}^N \alpha_n = 1 \\ \mathbf{a} = \sum_{n=1}^N \alpha_n \mathbf{x}_n \\ 0 \leq \alpha_n \leq 1 \end{cases} \end{aligned}$$

where \mathbf{z} is a vector containing all dot products $\mathbf{x}_n^\top \mathbf{x}_n$

- The radius R can be obtained with equation $\|\mathbf{x}_n - \mathbf{a}\|^2 = R^2$ which will be satisfied for any \mathbf{x}_n on the margin (this is, with $0 < \alpha_n < C$).

- These two approaches are very restrictive to special distributions that satisfy:
 - The data is separable from the origin (SVND)
 - The data is contained in a *small* sphere of radius R (SVDD).
- Obviously, practical cases do not fit these properties. The algorithms are described in Reproducing Kernel Hilbert Spaces where these conditions can be satisfied.
- For the case of the square exponential kernel

$$\langle \varphi(\mathbf{x}_n)^\top \varphi(\mathbf{x}_m) \rangle = k(\mathbf{x}_n, \mathbf{x}_m) = \exp\left(\frac{\|\mathbf{x}_n - \mathbf{x}_m\|^2}{2\sigma^2}\right)$$

both algorithms are equivalent.

- The RKHS versions are to be developed in next chapter.