

11 a)  $s^2 \Theta(s) \cdot J = -k_1 s \Theta(s) - k_0 \Theta(s) + F(s)$

$$\Theta(s) [J \cdot s^2 + k_1 s + k_0] = F(s)$$

$$\Theta(s) = \frac{1}{Js^2 + k_1 s + k_0} \cdot F(s)$$

$$s H(s) = V \cdot \Theta(s)$$

$$H(s) = \frac{V}{s} \cdot \frac{1}{Js^2 + k_1 s + k_0} \cdot F(s)$$

$$\frac{H(s)}{F(s)} = \frac{V}{Js^2 + k_1 s + k_0}$$

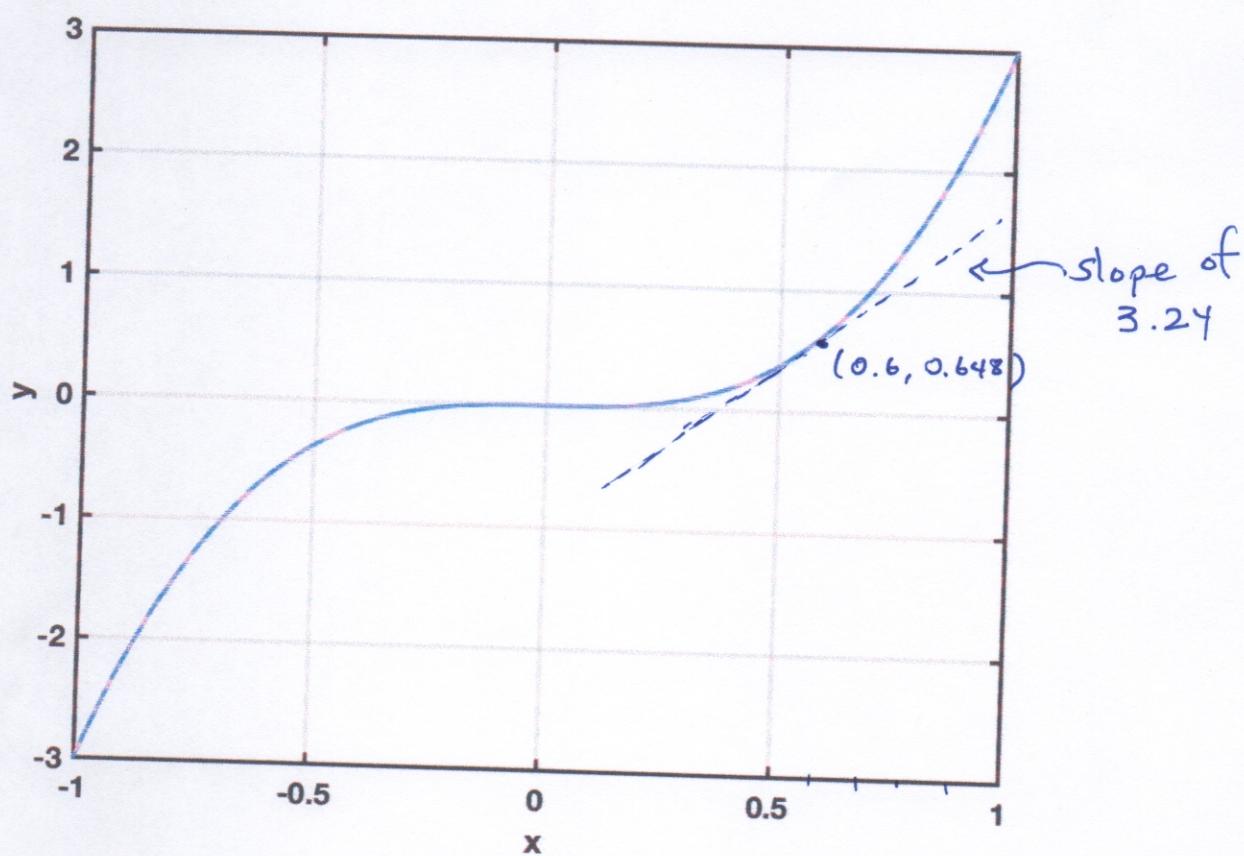
12  $f(x) = 3x^3, \quad x_0 = 0.6$

$$f(x_0) = 3 \cdot 0.6^3 = 0.648$$

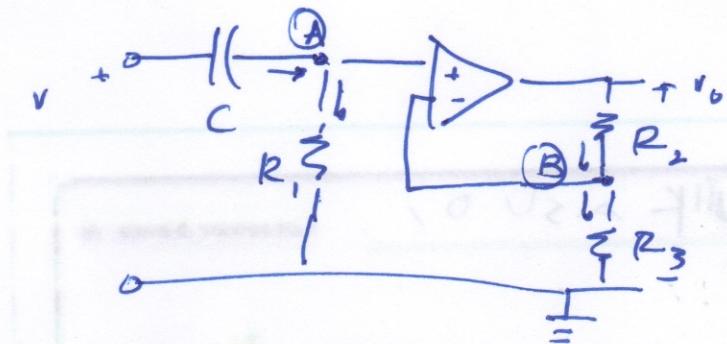
$$f(x) - f(x_0) \approx \frac{\partial f}{\partial x} \Big|_{x=x_0} \cdot (x - x_0)$$

$$\underbrace{y - 0.648}_{\Delta y} \approx \underbrace{9x^2 \Big|_{x=0.6}}_{\Delta x} \underbrace{(x - 0.6)}_{\Delta x}$$

Linearization:  $\Delta y = 3 \cdot 24 \cdot \Delta x$



13



1)

$$\text{KVL at } \textcircled{A}: C \left( \frac{dv}{dt} - \frac{dv_A}{dt} \right) = \frac{v_A}{R_1}$$

$$\text{KVL at } \textcircled{B}: \frac{v_o - v_B}{R_2} = \frac{v_B}{R_3}$$

Op-Amp properties:  $v_A = v_B$

$$\Rightarrow \text{A. } C s [v(s) - v_A(s)] = \frac{v_A(s)}{R_1}$$

$$R_1 C s v(s) = v_A(s) [1 + R_1 C s]$$

$$v(s) = v_A(s) \frac{(1 + R_1 C s)}{R_1 C s}$$

$$\Rightarrow \text{B. } \frac{v_o(s) - v_A(s)}{R_2} = \frac{v_A(s)}{R_3}$$

$$R_3 v_o(s) - R_3 v_A(s) = v_A(s) \cdot R_2$$

$$R_3 v_o(s) = v_A(s) (R_2 + R_3)$$

$$\frac{R_3}{R_2 + R_3} \cdot v_o(s) = v_A(s)$$

$$\therefore V(s) = \frac{1 + R_1 C s}{R_1 C s} \cdot \frac{R_3}{R_2 + R_3} \cdot V_o(s)$$

$$\frac{V_o(s)}{V(s)} = \frac{R_1 C s}{1 + R_1 C s} \cdot \frac{R_2 + R_3}{R_3}$$

$$= \frac{\left(\frac{R_2 + R_3}{R_3}\right) \cdot R_1 C \cdot s}{1 + R_1 C s}$$

$$= \frac{\left(\frac{1}{R_1 C}\right)\left(\frac{R_2 + R_3}{R_3}\right) \cdot R_1 C \cdot s}{s + \frac{1}{R_1 C}}$$

← proper form.

$$b) V(s) = \frac{1}{s}, \quad \frac{V_o(s)}{V(s)} = \frac{1 \cdot 3 \cdot 1 \cdot s}{s+1} = \frac{3s}{s+1}$$

$$\therefore V_o(s) = \frac{V_o(s)}{V(s)} \cdot V(s)$$

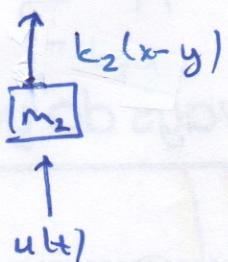
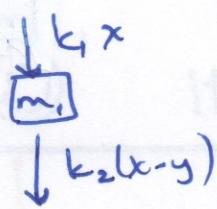
$$= \frac{3s}{s+1} \cdot \frac{1}{s}$$

$$= \frac{3}{s+1} \Rightarrow v_o(t) = \begin{cases} 3e^{-t} & \text{for } t \geq 0 \\ 0 & \text{otherwise.} \end{cases}$$

14

Presure "+" is ↑, + to assess FBD, so that  $x > 0, y > 0, x-y > 0$ ,

a)



i.e., the top spring is in compression & the bottom in tension.

$$\sum F = m_1 a$$

$$m_1 \ddot{x}(t) = -k_1 x(t) - k_2(x(t) - y(t))$$

$$\ddot{x}(t) = -2x(t) + y(t)$$

$$\sum F = m_2 a$$

$$m_2 \ddot{y}(t) = k_2(x(t) - y(t)) + u(t)$$

$$\ddot{y}(t) = x(t) - y(t) + u(t)$$

$$b) \quad s^2 x(s) = -2x(s) + y(s)$$

$$s^2 y(s) = x(s) - y(s) + u(s)$$

$$x(s)[s^2 + 2] = y(s)$$

$$y(s)[s^2 + 1] = x(s) + u(s)$$

↔

$$= \frac{1}{s^2 + 1} (x(s) + u(s))$$

$$x(s)((s^2 + 2)(s^2 + 1) - 1) = u(s)$$

$$\frac{x(s)}{u(s)} = \frac{1}{s^4 + 3s^2 + 1}$$

5.

The screenshot shows a MATLAB diary window titled "diary.txt". The window contains the following command-line history:

```
>> conv([1 1],[1 4])
ans =
    1     5     4
>> roots([1 5 4])
ans =
    -4
    -1
>> G = tf(4, [1 5 4])
G =
    4
    -----
    s^2 + 5 s + 4
Continuous-time transfer function.
>> step(G)
```

## Step Response

