

# Algorithm Implementation

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# Pseudocode

- **When documenting an algorithm in a language such as C, programmers use descriptive variable names such as: speed, volume, size, count, amount, etc. After the program is compiled, these variable names correspond to memory locations.**
- **To efficiently execute code, a compiler will attempt to keep the variables that are referenced most often in processor registers because access is much faster than access to memory.**

# Pseudocode Guidelines

- **When using pseudocode to document an assembly language program, you should use the names of the registers you intend to use in the assembly language code.**
- **It is advisable to create a cross reference table between the processor register name and what it is being used for in the program and comments should also document the usage.**
- **We use register names in pseudocode because the purpose of the pseudocode is to document the assembly language program.**

# Pseudocode Guidelines

- You will find that as you develop the pseudocode, it is a simple process to translate pseudocode into assembly language code.
- For (t0=1; t0 < s0; t0++) do {this block of code};

# Pseudocode Details

- Pseudocode for assembly language programs will have the appearance of C in terms of control structures and arithmetic expressions, but descriptive variable names will usually only appear in the **LOAD ADDRESS (la)** instruction where there is a reference to a symbolic memory address.
- In assembly language you define and allocate space for variables in the data segment of memory using assembler directives such as *.word* and *.space*.

# MIPS Assembly Language Syntax

**[label:] Op-Code [operand], [operand], [operand] [#comment]**

| Label  | Op-Code | Dest. | S1,   | S2   | Comment        |
|--------|---------|-------|-------|------|----------------|
| chico: | add     | \$a0, | \$t0, | \$t1 | # a0 = t0 + t1 |

# Pseudocode to Assembly

## Translation an Arithmetic Expression

**\$s0 = srt ( \$a0 \* \$a0 + \$a1 \* \$a1 )**

### Hypotenuse:

|             |                         |   |
|-------------|-------------------------|---|
| <b>mult</b> | <b>\$a0, \$a0</b>       | <b># Square \$a0</b>  |
| <b>mflo</b> | <b>\$t0</b>             | <b># t0 = Lower 32-bits of product</b>                              |
| <b>mult</b> | <b>\$a1, \$a1</b>       | <b># Square \$a1</b>  |
| <b>mflo</b> | <b>\$t1</b>             | <b># t1 = Lower 32-bits of product</b>                              |
| <b>add</b>  | <b>\$a0, \$t0, \$t1</b> | <b># a0 = t0 + t1</b>   |
| <b>jal</b>  | <b>srt</b>              | <b># Call the square root function</b>                              |
| <b>move</b> | <b>\$s0, \$v0</b>       | <b># By convention, the result of sqr<br/># is returned in \$v0</b> |

# Area of a Circle

$$\text{\$s0} = \pi * \text{\$t8} * \text{\$t8}$$

Area:

```
li $t0, 314159    # Load immediate Pi scaled up 100,000
mult $t8, $t8      # Radius squared
mflo $t1          # Move lower 32-bits of product in
                  # Low register to $t1
mult $t1, $t0      # Multiply by scaled Pi
mflo $s0          # Move lower 32-bits of product in
                  # Low register to $s0
li $t1, 100000    # Load immediate scale factor of 100,000
div $s0, $t1       # Divide by scale factor
mflo $s0          # Truncated integer result left in $s0
```



# Translation of an “if ... then ... else ...” Control Structure

if (\$t8 < 0) then

{ \$s0 = 0 - \$t8; \$t1 = \$t1 + 1 }

else

{ \$s0 = \$t8; \$t2 = \$t2 + 1 }

bgez \$t8, else

# if (\$t8 is greater than or  
# equal to zero) branch to else

sub \$s0, \$zero, \$t8

# \$s0 gets the negative of \$t8

addi \$t1, \$t1, 1

# increment \$t1 by 1

b next

# branch around the else code

else:

move \$s0, \$t8

# \$s0 gets a copy of \$t8

addi \$t2, \$t2, 1

# increment \$t2 by 1

next:

# Translation of a “while” Control Structure

```
while ($a1 < $a2) do  
    { $a1 = $a1 + 1  
    $a2 = $a2 - 1}
```

**while:**

```
bgeu $a1, $a2, done    # If( $a1 >= $a2) Branch to done  
addi $a1, $a1, 1       # $a1 = $a1 + 1  
addi $a2, $a2, -1      # $a2 = $a2 - 1  
b while                # Branch to while
```

**done:**

# Translation of a “for” Loop Control Structure

```
$a0 = 0;  
for ( $t0 =10; $t0 > 0; $t0 = $t0 -1) do  
    {$a0 = $a0 + $t0}
```

```
li $a0, 0          # $a0 = 0  
li $t0, 10         # Initialize loop counter to 10
```

**loop:**

```
add $a0, $a0, $t0  
addi $t0, $t0, -1 # Decrement loop counter  
bgtz $t0, loop    # If ($t0 > 0) Branch to loop
```

# Translation of a “switch” Control Structure

**Typical structure using c++ types of I/O – (For illustration only.)**

```
$s0 = 32;  
top:   cout << “Input a value from 1 to 3”  
       cin >> $v0  
       switch ($v0)  
       { case(1):{$s0 = $s0 << 1; break;}  
       case(2):{$s0 = $s0 << 2; break;}  
       case(3):{$s0 = $s0 << 3; break;}  
       default: goto top; }  
       cout << $s0
```

```

.data
.align 2
jumptable: .word top, case1, case2, case3
prompt:    .asciiz "\n\n Input a value from 1 to 3: "
.text

top:
    li $v0, 4                # Code to print a string
    la $a0, prompt
    syscall
    li $v0, 5                # Code to read an integer
    syscall
    blez $v0, top            # Default for less than one
    li $t3, 3
    bgt $v0, $t3, top        # Default for greater than 3
    la $a1, jumtable         # Load address of jumtable
    sll $t0, $v0, 2          # Compute word offset (multiply by 4)
    add $t1, $a1, $t0        # Form a pointer into jumtable
    lw $t2, 0($t1)           # Load an address from jumtable
    jr $t2                   # Jump to specific case "switch"
case1:    sll $s0, $s0, 1     # Shift left logical one bit
          b output
case2:    sll $s0, $s0, 2     # Shift left logical two bits
          b output
case3:    sll $s0, $s0, 3     # Shift left logical three bits

```

**output:**

```
li $v0, 1    # Code to print an integer is 1
move $a0, $s0    # Pass argument to system in $a0
syscall      # Output result
```

# A Few Words on Overflow Detection

- **With 2's complement numbers, when adding numbers of the same sign, the sum must have the same sign as the operands.**
- **A carry at the most significant bit does not signify that a signed overflow has occurred.**
- **With unsigned integers, when a carry occurs at the most significant bit, this is an unsigned overflow.**

# Assembler Directives

- **Give the programmer the ability to establish some initial data structures that will be accessed by the computer at run time.**
- **They begin with “.”**
- **Examples:**
  - .align – align the next datum on a  $2^n$  byte boundary
  - .ascii string – store string in memory with no null termination
  - .asciiz string – store string with null termination
  - .data – items stored in the data segment
  - .text – items stored in the text segment



# Assembler Directives

To allocate space in memory for a one-dimensional array of 1024 integers, the following construct is used in the C language:

```
int ARRAY[1024] ;
```

In MIPS assembly language, the corresponding construct is:

```
.data
```

```
ARRAY: .space 4096
```

# Assembler Directives

To initialize a memory array before program execution begins with a set of 16 values corresponding to the powers of 2 (  $2^N$  with N going from 0 to 15) , the following construct is used in the C language:

```
Int Pof2[16] = { 1, 2, 4, 8, 16, 32, 64, 128, 256, 512, 1024, 2048, 4096, 8192, 16384, 32768 }
```

In MIPS assembly language the corresponding construct is:

```
.data
```

```
Pof2:    .word 1, 2, 4, 8, 16, 32, 64, 128, 256, 512, 1024, 2048, 4096, 8192, 16384, 32768
```

Here is an example of how MIPS code can be written to access element two in the array and place a copy of the value in reg. \$s0. The load address la macro instruction is used to initialize a pointer in “\$a0” with the base address of the array labeled “Pof2.”

```
la $a0, Pof2      # a0 = &Pof2  
lw $s0, 8($a0)    # s0 = MEM[a0 + 8]
```