## ECE 345 / ME 380: Introduction to Control Systems Collaborative Quiz #1 Grading Sheet

Dr. Oishi

17.5 25

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This quiz is open-note and open-book. Calculators and Matlab are allowed. No partial credit will be awarded. For each of the questions, clearly write the correct answer.

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- (d)  $A_P = \begin{bmatrix} 0 & 1 \\ -\frac{mgl}{I} & 0 \end{bmatrix}, B_P = \begin{bmatrix} 0 \\ 1 \end{bmatrix}, C_P = \begin{bmatrix} -\frac{1}{I} & 0 \end{bmatrix}, D_P = 0$
- - (b) G(s) = H(s), because a transfer function can be represented by many different state-space models.

- (d) The input indirectly affects the generated torque  $\tau(t)$  and the flywheel angular velocity
- We would require a lower inertia to allow the flywheel to spin up at higher acceleration, z(thop) is

inversely proportional to the flywheel inertia.

## Statement of Effort

By providing my name below, I pledge that I have written this quiz as per the indicated instructions, and fully participated in the group.

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$$Ts^{2}\theta(s) = -mgl\theta(s) - t(s)$$

$$Ts^{2}\theta(s) + mgl\theta(s) = -t(s)$$

$$\theta(s)[Ts^{2} + mgl] = -t(s)$$

$$G(s) = \frac{O(s)}{T(s)} = -\frac{1}{Ts^2 + mgl}$$

$$= -\frac{\frac{1}{T}}{s^2 + \frac{mgl}{T}}$$

$$H(s) = C(sT - A)^{-1}B + D$$

$$= \begin{bmatrix} -\frac{1}{T} & 0 \end{bmatrix} \begin{bmatrix} S & -1 \\ \frac{mgl}{T} & S \end{bmatrix}^{-1} \begin{bmatrix} 0 \\ 1 \end{bmatrix} + Q$$

$$= \begin{bmatrix} -\frac{1}{T} & 0 \end{bmatrix} \frac{1}{S^2 + \frac{mgl}{T}} \begin{bmatrix} S & 1 \\ -\frac{mgl}{T} & \overline{S} \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$= \begin{bmatrix} -\frac{1}{T} & 0 \end{bmatrix} \frac{1}{S^2 + \frac{mgl}{T}} \begin{bmatrix} (S)(0) + (1)(1) \\ -\frac{mgl}{T} & \overline{S} \end{bmatrix} = \begin{bmatrix} -\frac{1}{T} & 0 \end{bmatrix} \frac{1}{S^2 + \frac{mgl}{T}} \begin{bmatrix} 1 \\ S \end{bmatrix} = \begin{bmatrix} -\frac{1}{T} & 0 \end{bmatrix} \frac{1}{S^2 + \frac{mgl}{T}} \begin{bmatrix} 1 \\ S \end{bmatrix} = \begin{bmatrix} -\frac{1}{T} & 0 \end{bmatrix} \frac{1}{S^2 + \frac{mgl}{T}} \begin{bmatrix} 1 \\ S \end{bmatrix}$$