

Time-average Autocorrelation For Energy Signals

$$\phi(\tau) \triangleq \lim_{T \rightarrow \infty} \int_{-T}^T x(\lambda) \cdot x(\lambda + \tau) d\lambda$$

\uparrow time \uparrow time shift.

For Power Signals

$$R(\tau) = \langle x(t) \cdot x(t + \tau) \rangle \xrightarrow{\text{average}}$$

$$\triangleq \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T x(t) \cdot x(t + \tau) dt$$

For Periodic Signals

$$R(\tau) = \frac{1}{T_0} \int_{T_0} x(t) \cdot x(t + \tau) dt$$

\downarrow autocorrelation function $\downarrow \int_0^{T_0}$

Total Power of a Signal.

$$R(0) = \langle x^2(t) \rangle = \int_{-\infty}^{+\infty} S(f) df$$

\uparrow power spectral density.

Properties

1) $R(0) = \langle x^2(t) \rangle \geq R(\tau)$

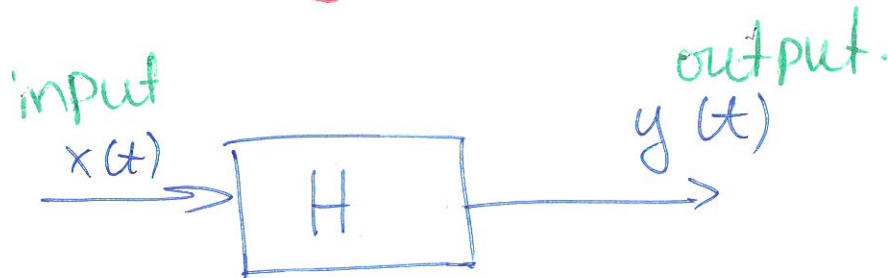
2) $R(-\tau) = R(\tau)$

3) If $x(t)$ does not contain any periodic component, $\lim_{|\tau| \rightarrow \infty} R(\tau) = [\langle x(t) \rangle]^2$

4) If $x(t)$ periodic with $T_0 \Rightarrow R(z)$ periodic with $\textcircled{2}$
 T_0

5) $R(z) \leftrightarrow \textcircled{S(f)} \rightarrow$ non-negative

Signals & Systems



$$y(t) = H[x(t)]$$

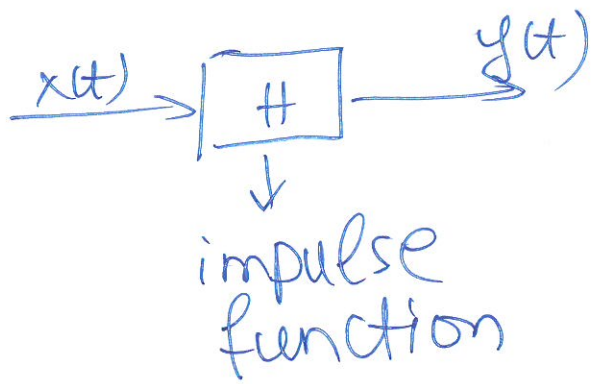
Superposition Property.

$$\begin{aligned} y(t) &= H[a_1 x_1(t) + a_2 x_2(t)] \\ &= a_1 H[x_1(t)] + a_2 H[x_2(t)] \\ &= a_1 y_1(t) + a_2 y_2(t) \end{aligned}$$

Time-invariant Property

$$y(t - t_0) = H[x(t - t_0)]$$

(3)



$$h(t) \triangleq H[\delta(t)]$$

↑ impulse response function.

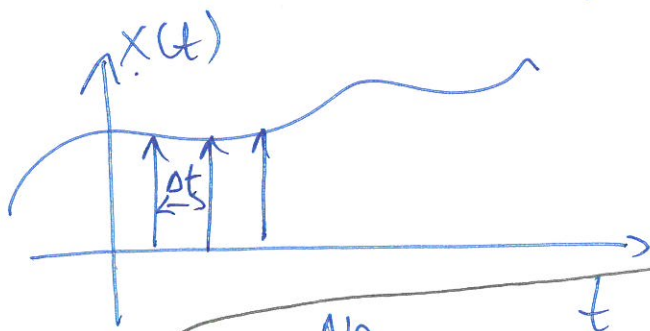
$$h(t) \leftrightarrow H[f]$$

input: $x(t) = \sum_{n=1}^N a_n \delta(t - t_n)$

output: $y(t) = \sum_{n=1}^N a_n h(t - t_n)$

Single output → single output

$$y(t) = H[x(t)]$$



$$\tilde{x}(t) = \sum_{n=N_1}^{N_2} x(n\Delta t) \cdot \delta(t - n\Delta t)$$

Approximation

$$\tilde{y}(t) = \sum_{n=N_1}^{N_2} x(n\Delta t) h(t - n\Delta t) \Delta t$$

$$\Delta t \rightarrow 0.$$

④

$$y(t) = \int_{-\infty}^{+\infty} x(\tau) \cdot h(t - \tau) d\tau$$

① Causal System If the system does not respond before an input is applied.

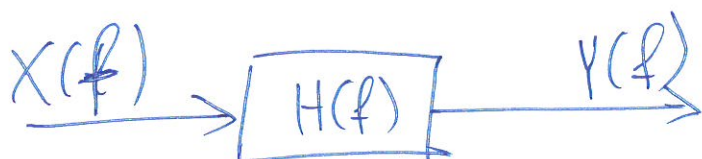
$$h(t - \tau) = 0, \quad t < \tau$$

Bounded input Bounded Output (BIBO)

→ Stable

$$\int_{-\infty}^{+\infty} |h(t)| dt < \infty$$

$$h(t) \leftrightarrow H(f) = |H(f)| e^{j \angle H(f)}$$



$$Y(f) = H(f) \cdot X(f)$$

Symmetry ~~System~~ Properties

(5)

$$|H(f)| = |H(-f)| \quad \text{even}$$

$$\angle H(f) = -\angle H(-f) \quad \text{odd}$$

Periodic Signal: $x(t) = A \cdot e^{j2\pi f_0 t}$ input

$$y(t) = \int_{-\infty}^{+\infty} h(\tau) \cdot A \cdot \underline{e^{j2\pi f_0 (t-\tau)}} d\tau$$

$$= A \cdot e^{j2\pi f_0 t} \left[\int_{-\infty}^{+\infty} h(\tau) \cdot e^{-j2\pi f_0 \tau} d\tau \right]$$

$$= A \cdot e^{j2\pi f_0 t} \cdot H(f_0)$$

Energy
Spectral
Density

$$G_y(f) = |H(f)|^2 \cdot G_x(f)$$

Power
Spectral
Density

$$S_y(f) = |H(f)|^2 \cdot S_x(f)$$