

October 30

6.  $S(f) = 8\delta(f-30) + 8\delta(f+30)$

$R(t) = ?$

$P = ? = 16W$

$\mathcal{F}^{-1}[S(f)] = 16 \cos(2\pi 30t) = 16 \cos(60\pi t)$

7.  $H_1(f) = \frac{1}{10 + j2\pi f} = e^{-10t} u(t)$

$H_2(f) = \frac{10 + j2\pi f}{10 + j2\pi f} = e^{-j20\pi f} \frac{1}{10 + j2\pi f}$   
 $= e^{-10(t-10)} u(t-10)$

8.  $h(t) = \cos(40\pi t) u(t)$

$\int_{-\infty}^{\infty} |h(t)| dt = \int_0^{\infty} |\cos(40\pi t)| dt = \infty$   
 Not BIBO Stable

9.  $x(t) = A e^{j\omega_0 t} \hat{x}(t)$

$= A \cos(\omega_0 t) + A j \sin(\omega_0 t)$

$\hat{x}(t) = A \sin(\omega_0 t) - A j \cos(\omega_0 t) = -A j (\cos(\omega_0 t) + j \sin(\omega_0 t))$   
 $= -j A e^{j\omega_0 t}$

$\lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T x(t) \cdot \hat{x}(t) dt = \lim_{T \rightarrow \infty} \frac{-jA^2}{2T} \int_{-T}^T e^{j\omega_0 t} dt$   
 $= \lim_{T \rightarrow \infty} \frac{-jA^2}{2T} \frac{1}{j\omega_0} [e^{j\omega_0 t}]_{-T}^T = \lim_{T \rightarrow \infty} \frac{-A^2}{2T \omega_0} [e^{j\omega_0 T} - e^{-j\omega_0 T}]$   
 $= \lim_{T \rightarrow \infty} \frac{-A^2}{2 \omega_0} \frac{\sin(2\omega_0 T)}{T} = \frac{-A^2}{2 \omega_0} \cdot 0 = 0$

10.  $x_c(t) = 50 \cos(2\pi 150t) \cdot 10 \cos(2\pi 160t) \cdot 10 \cos(2\pi 140t)$   
 $= 50 \cos(2\pi 150t) \cdot 20 \cos(2\pi 150t) \cos(2\pi 10t)$

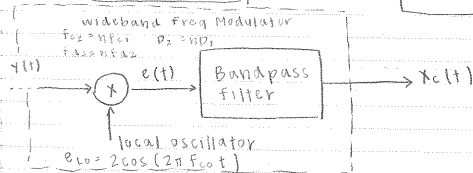
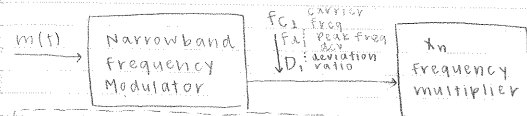
$x_c(t) = A_c (1 + m \cos(2\pi f_m t)) \cdot \cos(2\pi f_c t)$

$= 50 \cos(2\pi 150t) [1 + \frac{20}{50} \cos(2\pi 10t)]$

$a = \frac{20}{50} \quad P_{\text{car}} = \frac{50^2}{2} = \frac{2500}{2} = 1250W$

$P = \frac{10^2}{2} + \frac{10^2}{2} = 100$

Narrow Band  $\rightarrow$  wideband Modulation



$y(t) = A_c \cos(2\pi n f_c t + n \phi(t))$

$e(t) = A_c \cos(2\pi (n f_{c1} \pm f_{\omega}) + n \phi(t)) + A_c \cos(2\pi (n f_{c1} - f_{\omega}) t + n \phi(t))$

Bandpass Filter: center frequency  $\rightarrow$   $n f_{c1} + f_{\omega}$  or  $n f_{c1} - f_{\omega}$

## Demodulation of angle-modulated signals

received signal  $x_r(t) = A_c \cos(2\pi f_c t + \varphi(t))$

output of an ideal frequency demodulator  $y_o(t) = \frac{1}{2\pi} K_D \frac{d\varphi}{dt}$

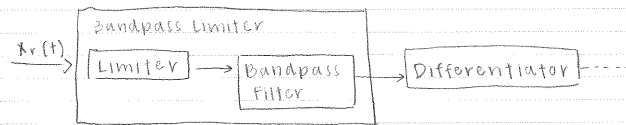
information of my original message signal

demodulation constant

for FM  $\varphi(t) = 2\pi f_d \int_0^t m(a) da$

output of an ideal phase demodulator  $y_d(t) = K_D \cdot f_d m(t)$

FM Demodulator



$e(t) \rightarrow$  Envelope Detector  $y_o(t) = A_c \frac{d\varphi}{dt} = A_c 2\pi f_d m(t)$

$K_D$

$$x_r(t) = A_c \cos(2\pi f_c t + \varphi(t))$$

$$c(t) = \frac{dx_r(t)}{dt} = -A_c \left[ \underbrace{2\pi f_c}_{\text{constant}} + \frac{d\varphi}{dt} \right] \sin(2\pi f_c t + \varphi(t))$$

Envelope

$$\cos(a+b) = \cos a \cos b - \sin a \sin b$$

## Interference in Angle Modulation

Input to the demodulator  $x_r(t) = A_c \cos(2\pi f_c t) + A_i \cos[2\pi(f_c + f_i)t]$

interference tone

$$= A_c \cos(2\pi f_c t) + A_i \cos(2\pi f_c t) \cos(2\pi f_i t) - A_i \sin(2\pi f_c t) \sin(2\pi f_i t)$$

$$= R(t) \cos(2\pi f_c t + \psi(t))$$

$$R(t) = \sqrt{[A_c + A_i \cos(2\pi f_i t)]^2 + [A_i \sin(2\pi f_i t)]^2}$$

$$\psi(t) = \tan^{-1} \left[ \frac{A_i \sin(2\pi f_i t)}{A_c + A_i \cos(2\pi f_i t)} \right]$$

if  $A_c \gg A_i$

$$R(t) = A_c + A_i \cos(2\pi f_i t)$$

$$\psi(t) = \tan^{-1} \left( \frac{A_i \sin(2\pi f_i t)}{A_c} \right)$$

$$x_r(t) = A_c \left[ 1 + \frac{A_i}{A_c} \cos(2\pi f_i t) \right] \cos(2\pi f_c t + \psi(t))$$

PM demodulation

$$y_o = K_D \frac{A_i}{A_c} \sin(2\pi f_i t)$$

FM demodulation

$$y_d(t) = \frac{1}{2\pi} K_D \frac{d}{dt} \left( \frac{A_i \sin(2\pi f_i t)}{A_c} \right)$$

pulse width Modulation

message signal = 0

smaller width  
negative values  
of signal



$$\frac{T_s}{2}$$

larger width  
for positive  
values of the signal