

Lab 7 - Code Design II

Saturday, April 18, 2020 10:52 AM

Operation:

// Ambient Temperature controls operational mode

Initialize Continuous loop

- Read ambient temperature and convert to °F

```
while(1) {
/* ----- read temp data ----- */

RestartI2C1();           // Send the stop condition
IdleI2C1();              // Wait to complete

MasterWriteI2C1 ((SlaveAddress << 1) | 0x01); // transmit a read command
IdleI2C1();              // Wait to complete

rd_cnt = MastergetsI2C1( 2, in_char_p, 152); // read two bytes

StopI2C1();              // Stop I2C bus
IdleI2C1();              // wait to complete

/* ---- calculate temp in degrees F ----- */

a = (short int) i2c_data[0]; // cast bytes to 16 bits
b = (short int) i2c_data[1];
raw_temp = b | (a << 8);      // combine bytes to 9 bit result
degc = raw_temp / 256;        // shift out ls 7 bits of 0 - degrees C
degf = ((degc * 9) / 5) + 32;  // Convert to Farenheit
```

- | | |
|------------------------------------|---------------|
| If ambient temperature is >= 80 °F | // Overheated |
|------------------------------------|---------------|

- o Flash message on LCD Display
- o Transmit message to terminal with CR and LF
- o Clear LEDs
- o Set overheat flag

```
if (degf >= TEMP_LIMIT) {

    // LCD module clear display command sequence
    SPI1BUF=0x1b; // Display clear - first send escape char
    c_buffer = "j"; // command sequence for clear
    putsSPI1(2,c_buffer); // write out string
    DelayMs(200); // wait for display to clear

    putsSPI1(12,buffer1); // write out overheated string
    DelayMs(500); // wait - output will blink
```

```

SPI1BUF=0x1b;           // Display clear - first send escape char
c_buffer = "j";         // command sequence for clear
putsSPI1(2,c_buffer);   // write out string
DelayMs(200);           // wait for display to clear

if (!temp_limit) {
    temp_limit = 1;

    /* write OVER Heated to UART2 - only once */
    WriteUART2(13);      // carriage return - move cursor left
    putsUART2(buffer2);   // write out Overheated string
}
led_bits = 0;           // set power to zero
mPORTEWrite(led_bits);  // write bits to output port

```

- Else

- o Read buttons and convert to level 0..7
- o Delay for switch bounce
- o Set output LEDs corresponding to power level
- o Display temperature on LCD Display
- o Display temperature on Terminal - stay on same line

```

else {
    temp_limit = 0;      // reset flag in normal operation

    sprintf(str,"%d",degf); // convert int to ASCII string

    /* ===== for now just display temp ===== */

    SPI1BUF=0x1b;        // cursor reset - first send escape char
    c_buffer="j";         // command sequence for clear screen
                           // and reset cursor
    putsSPI1(2,c_buffer); // write out string

    DelayMs(100);         // wait for display to reset
    putsSPI1(strlen(str),str); // write out string
    DelayMs(100);         // wait for display to reset

    // Read buttons
    power = 0;             // determine power value each iteration
    button_in12 = PORTReadBits (IOPORT_G, BIT_6|BIT_7);
    button_in3 = PORTReadBits (IOPORT_A, BIT_0);

    if (button_in12 != 0){
        // drive both LD1 and LD2 high if both buttons pressed
        if (((button_in12 & 0x0040) != 0) && ((button_in12 & 0x0080) != 0))
            power = 3;
        else {
            //drive LD1 high if only BTN1 pressed
            if ((button_in12 & 0x0040) != 0)        // BTN1 pressed?

```

```

        power = 1;;
        //drive LD2 high if only BTN2 pressed
        if ((button_in12 & 0x0080) != 0) // BTN2 pressed
            power = 2;
    }
}
// Handle BTN3 separately
if(button_in3 !=0)
    power += 4;

/* power level determined - now illuminate LEDs */
switch (power) {
    case 0:
        led_bits = 0;
        break;
    case 1:
        led_bits = 0x1;
        break;
    case 2:
        led_bits = 0x3;
        break;
    case 3:
        led_bits = 0x7;
        break;
    case 4:
        led_bits = 0xf;
        break;
    case 5:
        led_bits = 0x1f;
        break;
    case 6:
        led_bits = 0x3f;
        break;
    case 7:
        led_bits = 0x7f;
        break;
    default:
        led_bits = 0;
        break;
}

mPORTEWrite(led_bits);           // write bits to output
port

WriteUART2(13 );    // carriage return - move cursor left
putsUART2(str);     // write out temp string

```