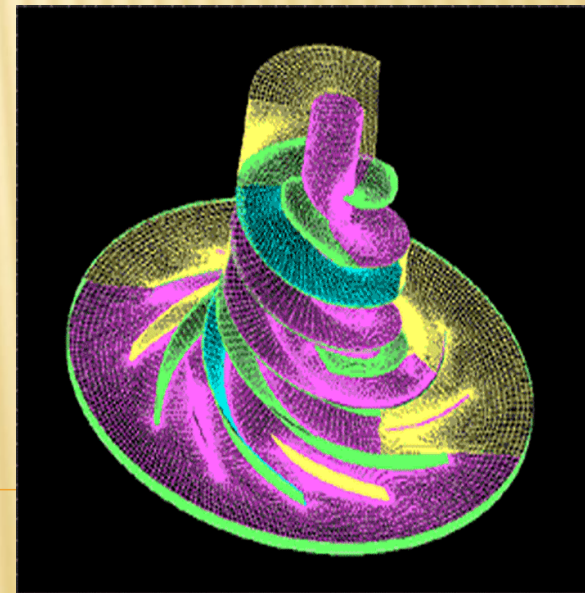
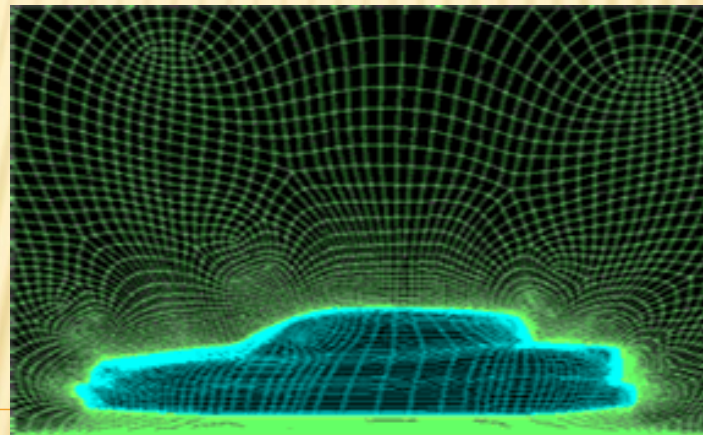
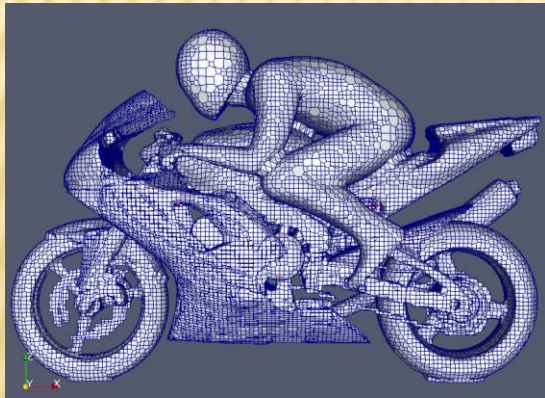


# Pre-processing in openfoam, mesh generation.



# Different ways of creating the mesh.

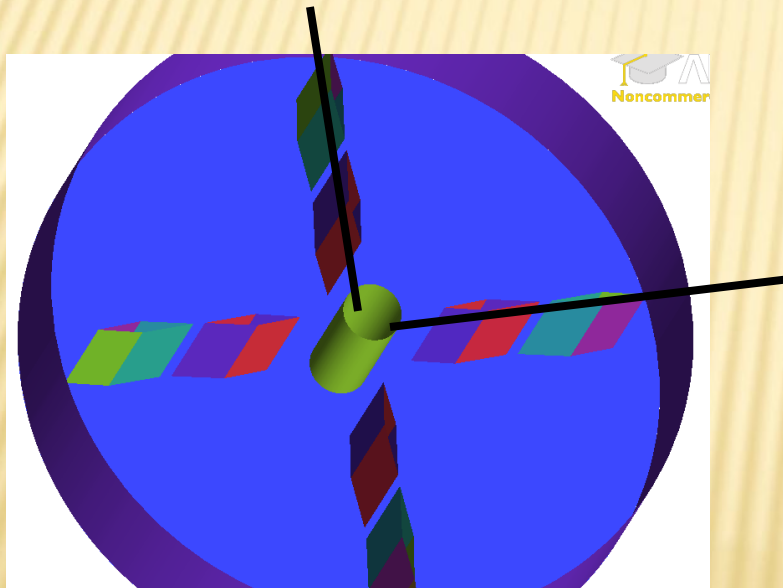
## Outline

- ✗ Using **SnappyHexMesh**, an OpenFOAM mesh generation tool.
- ✗ Using **blockMesh**, **m4** and **python**.
- ✗ Importing the mesh from **external software**.



# A tutorial for snappyHexMesh.

- ✗ SnappyHexMesh generates a 3D mesh from a .stl file.  
( triangulated surface geometry)
- ✗ For this tutorial, a simplified pump geometry is chosen.



For more simplicity in computations, the symmetry of the geometry is used, and only one quarter of the pump is meshed.

# A tutorial for snappyHexMesh.

- ✗ Download the tutorial from Håkan's webpage.
- ✗ Source OpenFOAM 2.2.x with alias OF22x or  
`export FOAM_INST_DIR=/chalmers/sw/unsup64/OpenFOAM;`  
`. $FOAM_INST_DIR/OpenFOAM-2.2.x/etc/bashrcHani`
- ✗ To check if the right OpenFOAM was called:  
*which SimpleFoam*  
*It should point to simpleFoam in OpenFOAM-2.2.x*
- ✗ In the tutorial case, you should find:
  1. The .stl file located in constant/triSurface.
  2. A dictionary called snappyHexMeshDict in system/.

# A tutorial for snappyHexMesh.

- ✗ Requirement for snappyHexMesh to work:
  - ✗ snappyHexMeshDict in /system/
  - ✗ Geometry data in constant/triSurface
  - ✗ Hexahedral base mesh (decomposed if running in parallel)
  - ✗ decomposeParDic file in /system/
  - ✗ All system dictionaries (e.g. controlDict, fvSchemes, fvSolutions)

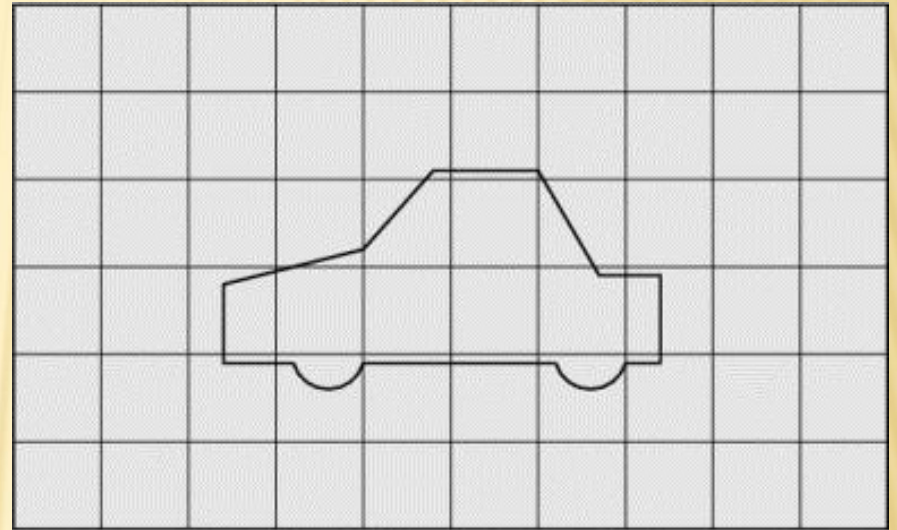
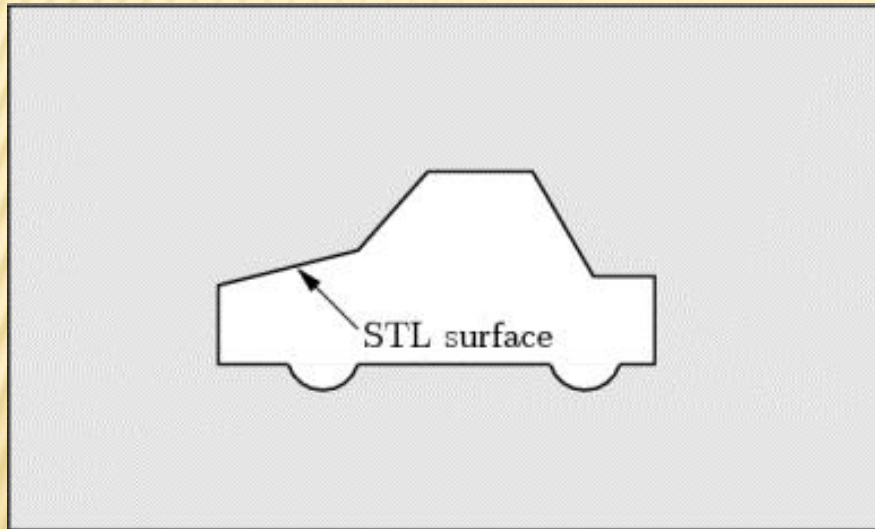


# A tutorial for snappyHexMesh.

- ✖ 5 simple steps:
  - ✖ Create base mesh
  - ✖ Refine base mesh
  - ✖ Remove unused cells
  - ✖ Snap mesh to surface
  - ✖ Add layers

# snappyHexMesh: step 1

- ✗ Creation of a grid surrounding the stl surface.



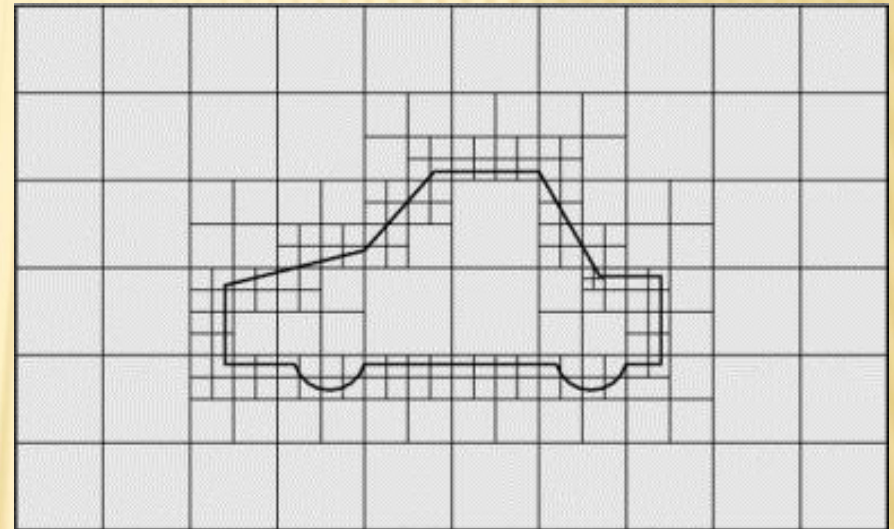
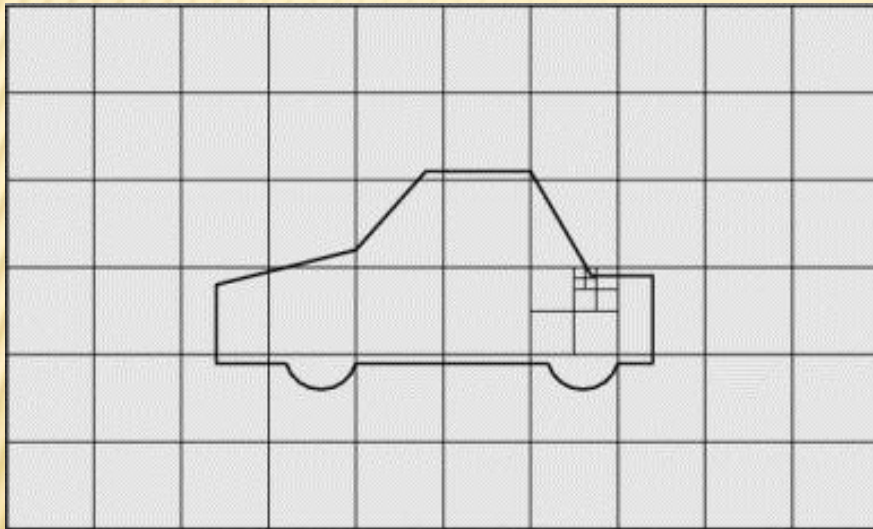
## Characteristics of the grid:

- ✓ *The aspect ratio of the grid cells should be around 1.*
- ✓ *More than one cell in the z direction.*
- ✓ *At least on cell's edge should intersect the surface.*
- ✓ *There can not be empty patches, it is a 3D mesher.*



# SnappyHexMesh: step 2

## ✗ Refine the base mesh.



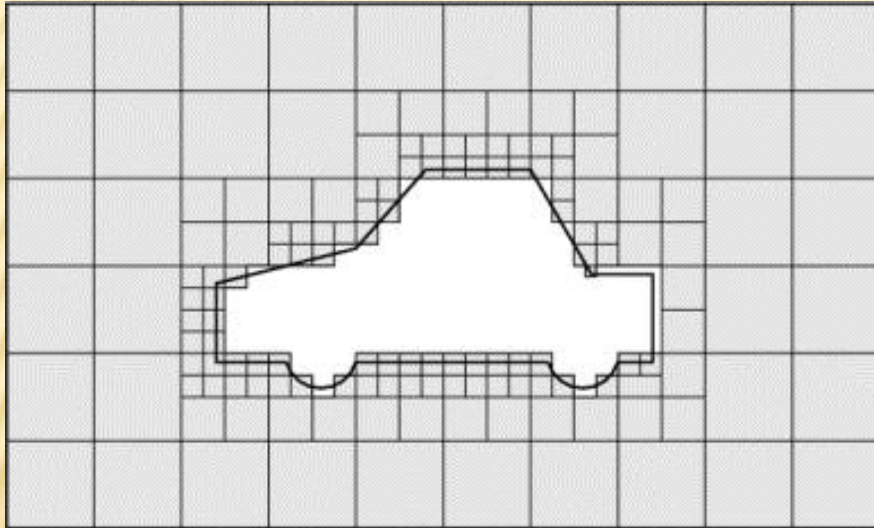
- Start the splitting from **locationInMesh** feature.
- This edge must be **inside the region to be meshed** and **must not coincide with a cell face**.
- Splitting the cells around the surface according to :

```
refinementSurfaces
{
    file.stl
    {
        level (2 2); // default (min max) refinement for surface
    }
}
```

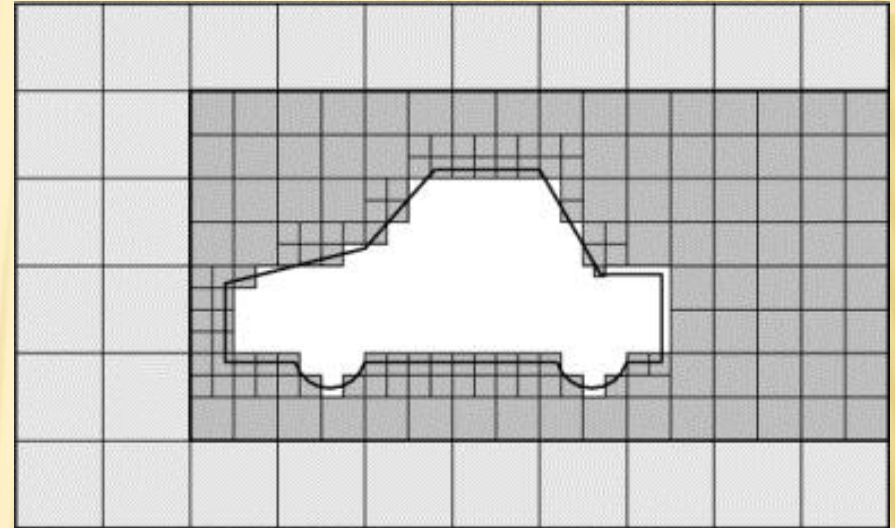


# Snappyhexmesh: step 3

## ✖ Remove unused cells.



- Keep the side of the mesh defined by **locationInMesh**.
- Remove all cells that have above 50% of their volumes in the meshed region.



The region refined is specified by:

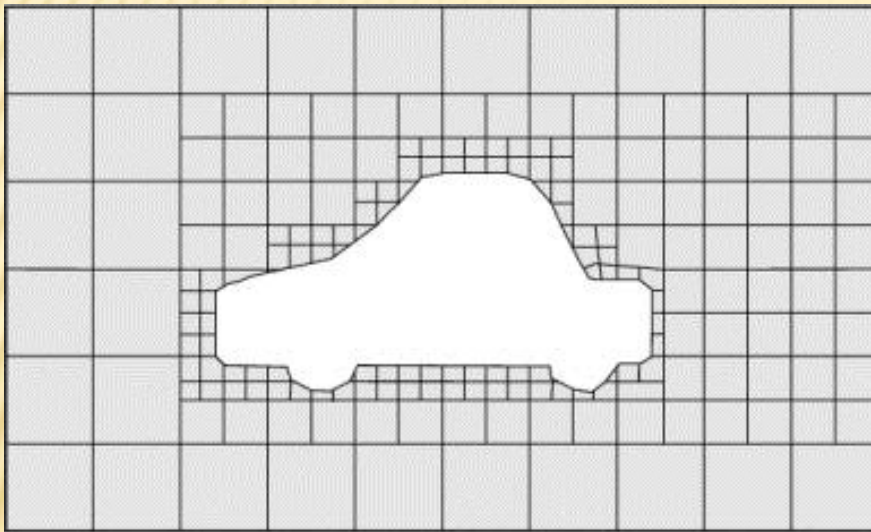
- ❖ **inside**: inside the volume region.
- ❖ **outside**: outside the volume region.
- ❖ **distance**: according to distance to the surface.

The region is defined first as geometry.

**This first step is saved into the time folder 1.**

# Snappyhexmesh: step 4

## ✗ Snapping to surface.



The steps to snap to surface are:

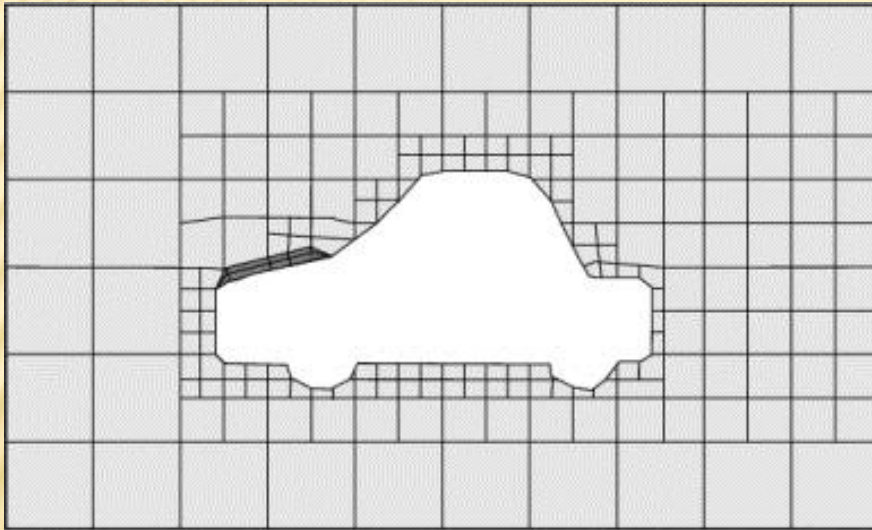
1. **Snap** the vertices onto the STL surface.
2. **Solve** for relaxation of the internal mesh.
3. **Iterate** using the snapControls in SnappyHexMeshDict.

**This second step is saved into the time folder 2.**



# Snappyhexmesh: step 5

## ✕ Boundary layer addition.



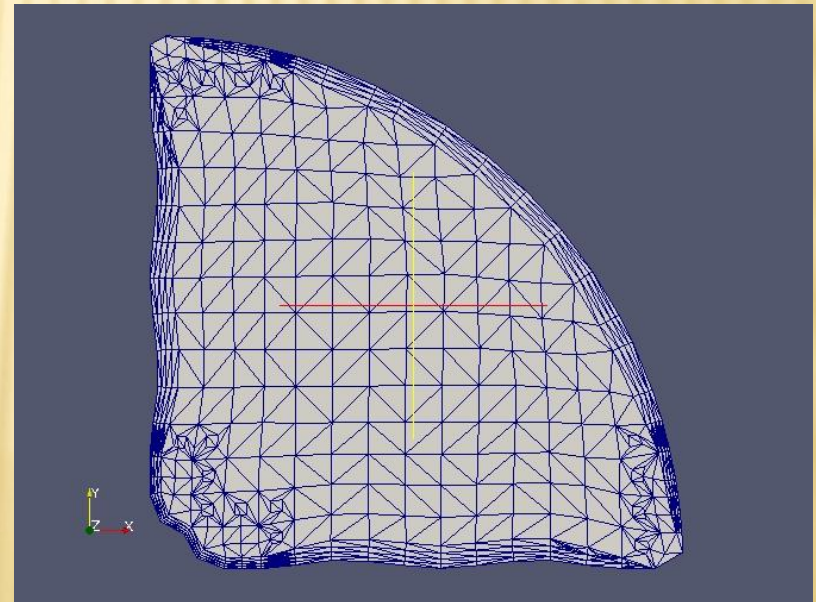
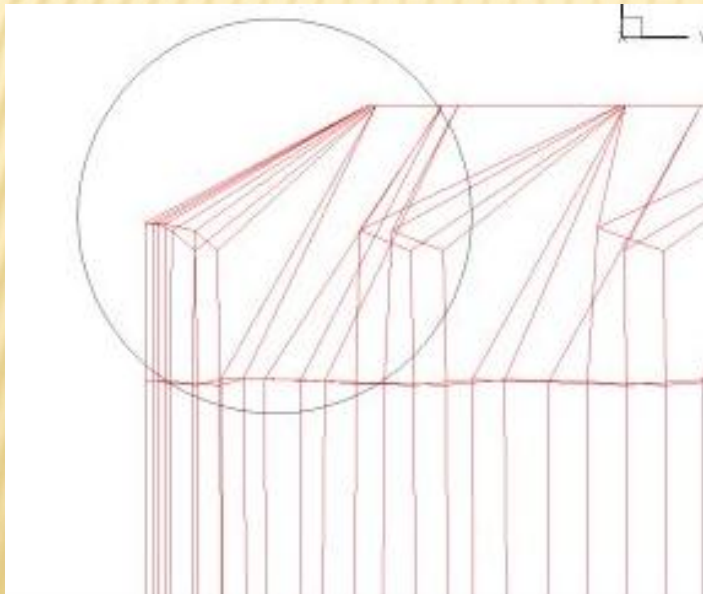
**The boundary are applied on patches, not on surface!!**

- ❖ Mesh projection back from the surface using a specified thickness normal to the surface.
- ❖ Solve for relaxation of the internal mesh with the latest projected boundary vertices.
- ❖ Check if validation criteria are validated.
- ❖ If the validation criteria can be satisfied, insert mesh layers.

**This last step is saved into the time folder 3.**

# Snappyhexmesh: pros and cons.

- ✗ Possibilities of multiple refinements that make it very robust.
- ✗ It runs in parallel.
- ✗ Need of a good quality STL surface, with more than one region/patch.
- ✗ The feature line is now available. SurfaceFeatureExtract
- ✗ A Boundary Layer mesh is not easy to obtain, it requires experience and trial and error method.

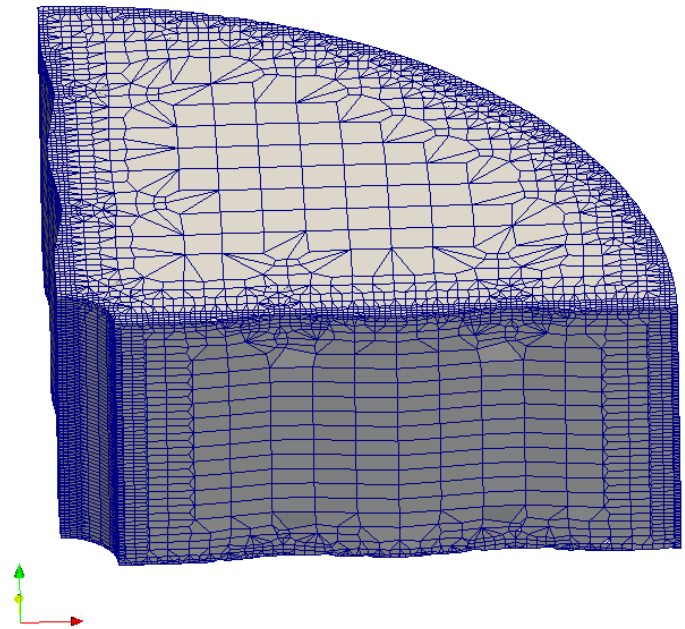
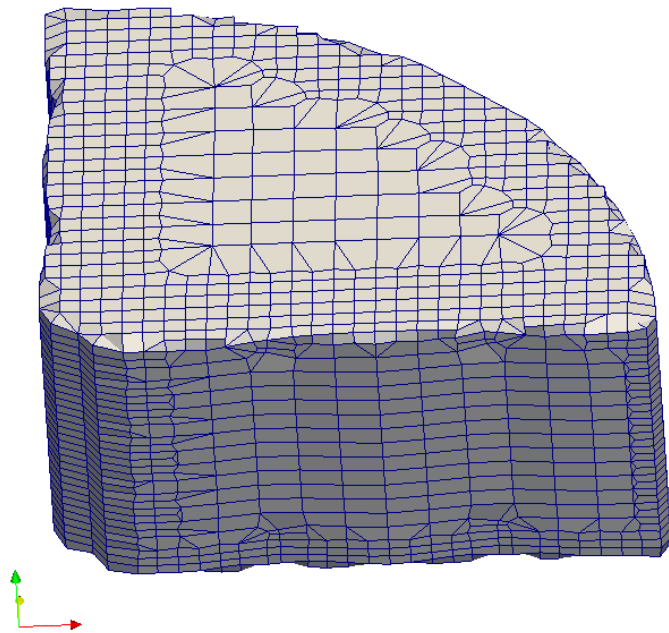




# SurfaceFeatureExtract

- ✗ Need a dictionary in system/ called ExtractFeatureDict.
- ✗ In the test case, the executable is surfaceFeatureExtract.
- ✗ Create a \*.emesh in constant/triSurface, and a new folder in constant/ called extendedFeatureEdgeMesh if the option writeObj is selected in surfaceExtractFeatureDict .
- ✗ In the snappyHexMeshDict dictionary, specify in features:  
{  
 file "pump\_simplified.eMesh";  
 level 3; // level of refinement  
}

# SurfaceFeatureExtract



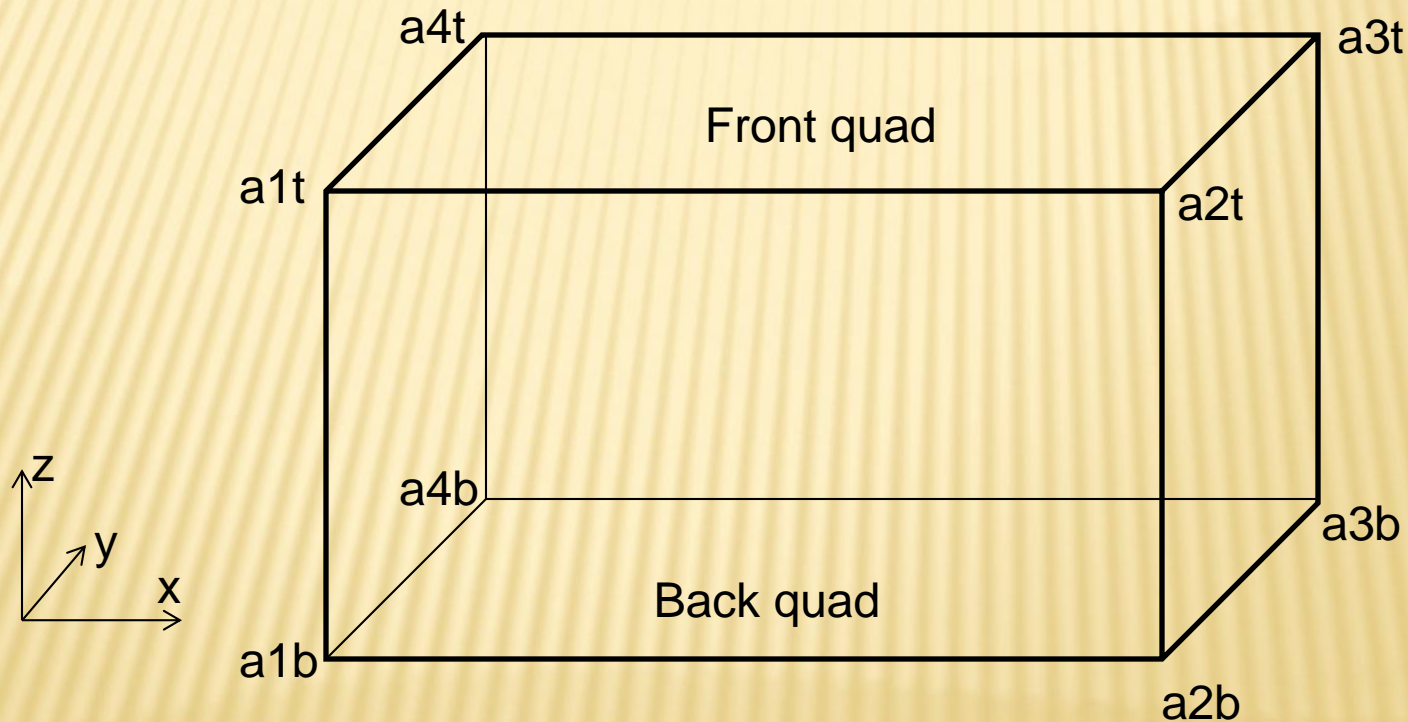


# EXTERNAL LINKS FOR SNAPPYHEXMESH

- ✖ <http://www.openfoam.org/docs/user/snappyHexMesh.php>
- ✖ <http://openfoamwiki.net/images/f/f0/Final-AndrewJacksonSlidesOFW7.pdf>

# blockMesh/m4

- ✖ m4: allow a parametrization of the case, easy to change.
- ✖ Let us take an example. Simple geometry: a pipe . The m4 file is found in `m4_python/mesh/2D.m4`.





# blockMesh/m4: pros and cons.

- ✗ Very easy way to create an simple geometry.
- ✗ The parametrization with m4 allows to create different geometries from the same m4 file.
- ✗ Not enough precision in the meshing parameters.
- ✗ Easy to go wrong on the orientation of the faces and blocks.

# Python

- ✖ **Python** is a general-purpose, high-level programming language. It emphasizes code readability.
- ✖ Like other dynamic languages, Python is often used as a scripting language.
- ✖ Commonly coupled with OpenFOAM, very useful to execute, analyse, manipulate parameters/simulations in OpenFOAM.
- ✖ Most commonly used python library in OpenFOAM is pyFoam.

# Using Python to create a test case

- ✖ Main script: `./ChooseShape.py`
- ✖ Needs 2 arguments. To know which one:  
`./ChooseShape.py -h`
- ✖ `arg1` is (2D, 3D, symmetry), `arg2` is (rectangle, cylinder)
- ✖ Call an other script in pythonScript folder:  
`geometrySetup.py`
- ✖ The script generates the chosen geometry, changes the m4 file, and do blockMesh



# Using Python

- ✖ Many different useful applications
- ✖ pyFoam is a very useful compilation of library.  
[http://openfoamwiki.net/index.php/Contrib\\_PyFoam](http://openfoamwiki.net/index.php/Contrib_PyFoam)
- ✖ Interesting tutorial by Eric Paterson,  
[http://www.personal.psu.edu/egp11/Eric\\_Paterson/Blog/Entries/2009/2/2\\_Python\\_Scripting\\_for\\_Gluing\\_CFD\\_Applications\\_A\\_Case\\_Study\\_Demonstrating\\_Automation\\_of\\_Grid\\_Generation%2C\\_Parameter\\_Variation%2CFlow\\_Simulation%2C\\_Analysis%2C\\_and\\_Plotting.html](http://www.personal.psu.edu/egp11/Eric_Paterson/Blog/Entries/2009/2/2_Python_Scripting_for_Gluing_CFD_Applications_A_Case_Study_Demonstrating_Automation_of_Grid_Generation%2C_Parameter_Variation%2CFlow_Simulation%2C_Analysis%2C_and_Plotting.html). It can also be found at  
[http://www.tfd.chalmers.se/~hani/kurser/OS\\_CFD\\_2009/](http://www.tfd.chalmers.se/~hani/kurser/OS_CFD_2009/)
- ✖ post-processing example for turbomachinery can be found at  
[http://openfoamwiki.net/index.php/Sig\\_Turbomachinery/\\_Timisoara\\_Swirl\\_Generator#Post-processing\\_using\\_Python](http://openfoamwiki.net/index.php/Sig_Turbomachinery/_Timisoara_Swirl_Generator#Post-processing_using_Python)

# Import the mesh: pros and cons

- ✗ Need of an other software to create the mesh.
- ✗ Few converters:
  - + **fluentMeshToFoam**, **fluent3DMeshToFoam** for Gambit mesh types.
  - + **starToFoam** for STAR-CD mesh types.
  - + **ideasToFoam** for I-DEAS mesh types
  - + **cfx4ToFoam** for CFX mesh types.
  - + **CGNSToFoam** for CGNS files (can import more than meshes), developped by users.