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Cubesat Constellation Astrea

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1 Satellite design

1.1 Structure and mechanics

The design and operation of a CubeSat is a complex process that must be completed keeping in mind the huge differences between all subsystems as well as the role they will play during the lifetime of the mission. And since these systems will operate in space, they have to be prepared and certified to withstand extreme temperature and radiation conditions. A.2

The satellite used by Astrea must have high compatibility between all the systems to avoid potential problems and has to be tested (either all the systems together or one by one). Their correct functioning has to be ensured, especially the critical systems such as the solar arrays, batteries and antennas should be fully operational for at least four years.

1.1.1 Structure

The mission of the structure is to sustain and protect all the electronic devices carried by the satellite. In order to ensure that all the electronic and mechanical systems can be mounted upon the structure, a high compatibility between these systems is required; therefore, the structure must be very flexible regarding the arrangement of the subsystems.

The structure chosen is manufactured by **Innovative Solutions In Space (ISIS)**. Among its features it is worth mentioning that it can withstand the high range of temperature it will face in the space (from -40°C to 80°C) and it is highly compatible; almost every physical system used can be placed within the structure or on its faces (such as the antennas or the deployable solar arrays). Finally, the mass of the structure is relatively low, and given that the mass of the other subsystems is sometimes a drawback, it is plus point.

1.1.2 Thermal protection

The CubeSat is vulnerable to suffer extreme temperatures while operating in space, both below zero and above zero. The thermal protection system consists of a set of layers (MLI) made of insulating materials and it aims to protect the CubeSat from potential thermal shocks. The satellite must remain within an optimal range of temperature, despite of the variation of the external temperature, in order to work properly. Furthermore, the thermal protection system should also dissipate the heat produced by the other systems.

1.2 Electrical Power System

Dunmore Aerospace has been chosen to provide us its MLI product. The product, **Dunmore Aerospace Satkit**, has been designed for small satellites operating in LEO and it will provide the CubeSat with the protection required during operation.

1.1.3 Options chosen for the structure and thermal protection

The options chosen are presented in the table 1.1.

System	Brand and model	Price per unit (€)	N. of units
3U Structure	ISIS	3900	1
Thermal Protection	Dunmore Satkit	1000	1

Table 1.1: Options chosen for the structure and thermal protection

1.2 Electrical Power System

The electric power system of the satellite must provide and manage the energy generated efficiently in order to have all the systems operating under normal conditions during the lifetime of the mission. The EPS of the Cubesat is, probably, the most fundamental requirement of the satellite, since its failure would result in a mission failure. Therefore, the role of this system is to control and distribute power to the Cubesat, to supply a continuous source of electrical power during the length of the mission, to protect the satellite against electrical bus failiures and to monitor and communicate the status of the EPS to the on-board computer.

1.2.1 Estimation of the power required

To select the adequate electrical power systems it is essential that the power consumed by the CubeSat is known *a priori*. Thus, to select the solar arrays and the batteries, as well as the power management system, an estimation of the power consumed has to be made.

The total estimated power required is 52W. The calculations and reasoning can be checked on the **ANNEX**.

1.2.2 Solar arrays

Given that the space of a 3U CubeSat is very limited, the primary source of electrical power has to be photovoltaic cells. The photovoltaic cells will collect and convert the energy of the sun into electrical energy and they have to be fully efficient for at least four years.

1.2 Electrical Power System

Every cubesat will come with at least 4 deployable solar panels (manufactured by **EXA-Agencia Espacial Civil Ecuatoriana** providing it with 67.2W of power, approximately, to supply peak demands during the lifetime of the mission. Note that these 4 deployable solar panels are a basic requirement. If more space is available on the faces of the satellite, additional panels can be placed providing extra power.

1.2.3 Power management system

The role of the power management system is to distribute the power and supply the energy to the different systems used in the CubeSat. Since the systems of the CubeSat have different power and energy needs, the power management system has to be highly compatible and must have a number of buses high enough to supply the different voltage and intensity required to the systems.

The selected option for the mission is the **NanoPower P60** by **Gomspace**, a high-power EPS for small satellites that comes with 1 motherboard, 1 ACU module (Array Conditioning Unit) and 1 PDU (Power Distribution Unit), allowing multiple configurations in just one motherboard; saving a lot of space.

1.2.4 Batteries

Batteries are essential for a proper mission operation. They will provide the spacecraft subsystems with the power needed when the solar arrays are working less efficiently or not properly. Astrea is looking for decent capacity batteries that provide a slightly high typical energy and power supply, since all the systems will not usually operate under peak conditions. Additionally, through the lifetime of the mission, the solar arrays will face an important unfavorable condition; in the worst case scenario, the satellite will be in the dark during half of the period of the orbit. So, it is clear that the batteries are a critical system of the CubeSat

Astrea has chosen the **BA01/D** batteries manufactured by **EXA-Agencia Espacial Civil Ecuatoriana**. The CubeSat will have two of these batteries, with a total capacity of 28800mAh or 106,4Wh.

As mentioned above, if the satellite was in the dark during half of the period of the orbit, the estimated energy that it would need would be 50W. Thereby, the capacity of the batteries is more than enough to supply the required energy in the worst case scenario. In fact, they will supply energy when the energy demand of the CubeSat is higher than the energy collected by

1.3 Propulsion Systems

the solar cells. And logically, they will store the energy collected by the solar arrays when the energy demand of the systems is lower than the energy collected.

1.2.5 Options chosen for the EPS

Finally, the options chosen are presented in the table A.5.

System	Brand and model	Price per unit (€)	N. of units
Solar arrays	EXA	17000	4
Additional solar arrays	-	4000-12000	depends
Batteries	EXA	6300	2
Power Management	Gomspace NanoPower P60	16000	1

Table 1.2: Options studied for the Electric Power System

1.3 Propulsion Systems

Thruster is a main part of the structure because it is needed to allow the satellite to realise different maneuvers how incorporate it adequately to the orbit after the deployment of the rocket, can obtain the optimal orientation or to maintain the satellite in the orbital and avoid its fallen.

The main parameters that must consider are thrust, total specific impulse, power required, weight of the propulsion subsystem and its volume.

At the moment, the most used and more modern thrusters for satellites are: ionic, pulsed plasma, electrothermal and green monopropellant thrusters. An important aspect to consider is that the goal is to reduce the mass required although this will cause minor accelerations than conventional engines but it will be suitable for small satellites.

BGT-X5 has been chosen how the CubeSat thruster. With the high thrust and delta V that BGT-X5 provides, the CubeSat will be able to carry out the necessary actions to keep the satellite in orbit, to relocate the satellite or to change its orbit.

The option chosen is presented in the table below 1.3.

System	Brand and model	Price per unit (€)
Propulsion	Busek BGT-X5	50000)

Table 1.3: Option chosen for the propulsion system

1.4 Attitude and Orbital Control Systems

Attitude and orbital control subsystem is needed to enable the satellite to keep a specific position within its orbit and to control the antennas in order to remain oriented to assigned area, because the satellite tends to change its orientation due to torque. The AOCS receives telecommands from the central computer and acquires measurements (satellite attitude and orbital position) from sensors. We will also refer to the attitude control as ADACS (Attitude Determination and Attitude control system).

Attitude control for CubeSats relies on miniaturizing technology without significant performance degradation. Tumbling typically occurs as soon as a CubeSat is deployed, due to asymmetric deployment forces and bumping with other CubeSats. Some CubeSats operate normally while tumbling, but those that require pointing in a certain direction or cannot operate safely while spinning, must be detumbled. Systems that perform attitude determination and control include **reaction wheels, magnetorquers, thrusters, star trackers, Sun sensors, Earth sensors, angular rate sensors, and GPS receivers and antennas**. Combinations of these systems are typically seen in order to take each method's advantages and mitigate their shortcomings. (*wikipedia extract, [?]*).

Pointing in a specific direction is necessary for Earth observation, orbital maneuvers, maximizing solar power, and some scientific instruments. Directional pointing accuracy can be achieved by sensing Earth and its horizon, the Sun, or specific stars. Determination of a CubeSat's location can be done through the use of on-board GPS, which is relatively expensive for a CubeSat, or by relaying radar tracking data to the craft from Earth-based tracking systems (*wikipedia extract, [?]*).

1.4.1 Orbital Control

Orbital control will be achieved as a combination of two systems. ADCS will orient the thrust, this thrust will be given by the propulsion system and all the operation will be controlled on the On-Board Computer. Principally, the orbit control will be necessary to mitigate orbital debris effect on every satellite.

1.4.2 Option chosen for the Attitude and Orbital Control System

Decision Taking into account that we need: low power consumption, low, weight and size, high pointing accuracy and really versatile systems that can integrate multiple subsystems; **CUBE ADCS** is chosen. It has the lowest mass and power consumption, it also offers a

1.4 Attitude and Orbital Control Systems

higher attitude determination systems and integrates also and On-Board Computer (OBC).
<http://www.cubespace.co.za/cubecomputer>

A Appendices

A.1 Satellite design

A.2 Structure

There are several types of commercial structures. According to the needs of the project, the structure that Astrea is looking for has to be very flexible regarding the placement of the subsystems. It has to adapt to the needs of the project continuously given that the satellite do not have a typical configuration.

A basic schematics can be found in the figure A.1.

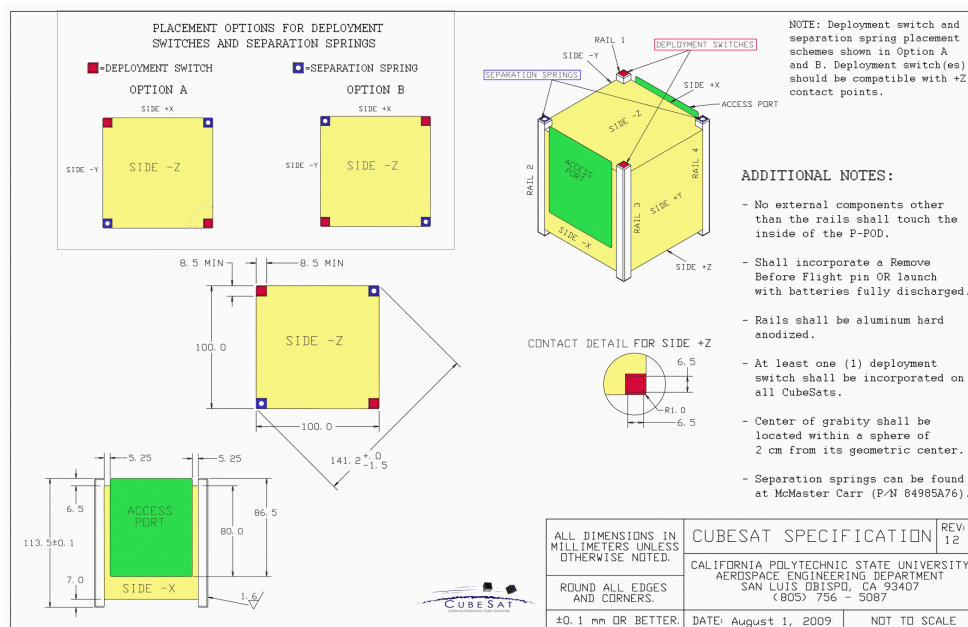


Figure A.1: Dimensions of a 1U CubeSat. Source [?]

The two most interesting options that were considered when the structure had to be chosen are presented below.

Brand and model	Features	Total price (€)
Structure		
ISIS 3U structure	Low mass (304.3g) Highly compatible High temperature range	3900

A.4 Electrical Power System

Gomspace GOMX-Platform	High mass (1500g) Comes fully equipped (basic systems) High temperature range	11000
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Table A.1: Options studied for the structure

A.3 Thermal protection

The thermal protection system consists of various insulating materials that aim to protect the CubeSat from potential thermal shocks. Currently, the most used element as thermal protection in the aerospace industry is the multilayer insulation (MLI), a set of multiple thin insulation layers. The MLI fulfills all the requirements of this mission and its main objective is to reduce the heat generated by radiation, given that the heat generated by convection or conduction does not have such a high impact on the on-board systems.

A few options were studied when the thermal protection had to be selected. These options are presented in A.2 red in this section, the table A.1 is presented below.

Brand and model	Features	Total price (€)
Thermal protection		
Dunmore Aerospace Satkit	Lightweight Durability Made for small satellites	1000
Dupont Kapton Aircraft Thermal	Lightweight Durability Non-flammable	1200

Table A.2: Options studied for the thermal protection

A.4 Electrical Power System

The electric power system of the satellite must provide and manage the energy generated efficiently in order to have all the systems operating under normal conditions during the lifetime of the mission. The EPS of the Cubesat is, probably, the most fundamental requirement of the satellite, since its failure would result in a mission failure.

The energy collection system and the power management and collection systems compose the EPS and their role is to control and distribute power to the Cubesat, to supply a continuous source of electrical power during the length of the mission, to protect the satellite against

A.4 Electrical Power System

electrical bus failiures and to monitor and communicate the status of the EPS to the on-board computer.

A.4.1 Estimation of the power required

To select the adequate electrical power systems it is essential that the power consumed by the CubeSat is known *a priori*. Thus, to select the solar arrays and the batteries, as well as the power management system, an estimation of the power consumed has to be made.

The vast majority of the time the satellite will work under typical operation conditions. However, the estimation of the power consumption provided in the table A.3 has been made for typical-high conditions in order to have a power margin and a more reliable estimation.

System (number of units)	Typical power consumption per unit (W)
Payload	
Patch antenna (8)	4
Payload power consumption	32
Electrical Power System	
NanoPower P60 Power Module (1)	2
Battery (2)	-
Solar arrays (4)	-
EPS power consumption	2
Data Handling Systems	
Transceiver inner-satellite (3)	4
Transceiver space to ground (1)	4
Data handling system (1)	4
DHS power consumption	15
Propulsion and ACDS	
Thruster (1)	20
ADACS (1)	3
OACDS power consumption	3
Estimated total power consumption	52

Table A.3: Estimation of the power consumption under typical working conditions

Additionally, it is worth mentioning that the thrusters are not included in the final estimated power. The thruster will only be active for shorts periods of time to maintain the orbit, and when it ignites, the other subsystems will not perform in typical conditions. The CubeSat will manage to send only the essential information to the other satellites and, since it

A.4 Electrical Power System

is unlikely that their thruster is ignited, the communication is ensured during the maneuver.

A.4.2 Solar arrays

Given that the space of a 3U CubeSat is very limited, the primary source of electrical power has to be photovoltaic cells. The photovoltaic cells will collect and convert the energy of the sun into electrical energy and they have to be correctly selected to prevent failure given their importance.

The solar arrays used must have a decent efficiency and capacity to collect the energy from the sun, have to keep their mass relatively low, must have a protective radiation shield to ensure their full efficiency for at least 4 years, a proper deployment system, the ability to withstand space conditions and also must be highly compatible with all the other systems used, especially the power management system (the *NanoPower P60*).

The option selected for the mission is a set of deployable solar panels provided by **EXA (Agencia Espacial Civil Ecuatoriana)**. These solar arrays fulfill all the requirements mentioned above: they are low mass (135g per unit), they have a protective radiation shield (NEMEA Anti Radiation Shield protects the solar panels of EM, High Gamma, X-Ray, Alfa, Beta and low neutron radiation) they can withstand a very high temperature range (from -80°C to 130°C) ensuring that they can operate in space, they have a gentle release and deployment system with artificial muscles (developed by EXA) and they provide a power of 16.8W each ($19.2\text{V}@0.5\text{A}$).

Every cubesat will come with at least 4 deployable solar panels providing it with 67.2W of power, approximately, to supply peak demands during the lifetime of the mission. Additionally, it is worth mentioning that these solar arrays are compatible with the hardware used (the structure and the power management system).

Note that these 4 deployable solar panels are a basic requirement. If more space is available on the faces of the satellite, additional 1U non-deployable solar arrays (giving an extra power of 2.3W per array, approximately) or 1U deployable arrays (giving an extra power of 16.8W or 10W) will be placed. They are also low mass equipment (about 80g per array) as the deployable solar arrays and highly compatible with the CubeSat. Their current and voltage are different but given that the CubeSat will be equipped with the NanoPower P60, that should not be a problem. The only drawback of these arrays is that they may be only fully operational for 2 years in LEO. However, that does not mean they will not work anymore after these 2 years; it means that they will start losing efficiency.

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A.4.3 Power management system

The role of the power management system is to distribute the power and supply the energy to the different systems used in the CubeSat. Since the systems of the CubeSat have different power and energy needs, the power management system has to be highly compatible and have a number of buses high enough to supply the different voltage and intensity required to the systems.

The selected option for the mission is the **NanoPower P60** by **Gomspace**, a high-power EPS for small satellites that comes with 1 motherboard, 1 ACU module (Array Conditioning Unit) and 1 PDU (Power Distribution Unit), allowing multiple configurations in just one motherboard; saving a lot of space.

The motherboard supports up to 4 ACU and PDU modules and has different regulated outputs (3.3V and 5V). It means that with one single motherboard, several conditioning and distributing units can be connected. That ensures that additional equipment (ACU and PDU) could be linked to the motherboard if something failed in the assembly process.

The ACU module 6 different inputs per unit with a high voltage solar input (up to 16V or 32V). Additionally, each input can withstand a maximum current of 2A and current and voltage inputs are measured on each input channel and the measurements can be communicated to the onboard computer.

The PDU module has 9 different outputs per unit that are highly configurable. Each module has 3 configurable output voltages (3.3V, 5V, 8V, 12V, 18V, 24V) and each of the outputs can withstand a maximum current of 1A or 2A (programmable). Additionally, like the ACU module, current and voltage outputs are measured on each output channel and can be effectively communicated to the onboard computer.

All these features make the **NanoPower P60** a very efficient and configurable power management unit that fulfills the mission requirements. Furthermore, given this capacity to configure each input and output channel and the high number of channels that it has, the compatibility between all the systems used in the satellite is ensured. Additionally, the communication between this system and the onboard computer in order to detect potential failures is a really adequate feature.

With the NanoPower P60 we aim to distribute the energy to all of the subsystems of the CubeSat.

A.4 Electrical Power System

A.4.4 Batteries

Batteries are essential for a proper mission operation. They will provide the spacecraft subsystems with the power needed when the solar arrays are working less efficiently or not properly. Astrea is looking for decent capacity batteries that provide a slightly high typical energy and power supply, since all the systems will not usually operate under peak conditions. Additionally, through the lifetime of the mission, the solar arrays will face an important unfavorable condition; in the worst case scenario, the satellite will be in the dark during half of the period of the orbit. So, it is clear that the batteries are a critical system of the CubeSat

Among all the commercial options, Astrea has chosen the **BA01/D** batteries manufactured by **EXA-Agencia Espacial Civil Ecuatoriana**. The CubeSat will have two of these batteries, with a total capacity of 28800mAh or 106,4Wh. Each battery has a total of 16 cells, highly stackable and with a very low mass (155g per unit). They also come with unique thermal transfer bus, that will transfer the heat of the other subsystems to the batteries to keep their temperature under efficient working conditions.

The output voltage can be configured (3.7V and 7.4V) and they are perfectly compatible with the solar arrays. Furthermore, they come with a protective radiation shield (NEMEA) that ensures at least 4 years working under full efficiency conditions in a LEO. It is also worth mentioning that if the company that will assemble the CubeSat faces problems during this part of the process, the batteries can be customized by contacting EXA.

As mentioned above, if the satellite was in the dark during half of the period of the orbit, the estimated energy that it would need would be 50W. Thereby, the capacity of the batteries is more than enough to supply the required energy in the worst case scenario. In fact, they will supply energy when the energy demand of the CubeSat is higher than the energy collected by the solar cells. And logically, they will store the energy collected by the solar arrays when the energy demand of the systems is lower than the energy collected.

A.4.5 Study of the commercial available options and options chosen

A broad marked study is needed since all the options have to be considered. For this reason, and with the aim to show all the information and features of each system that has been considered in this section, the table A.4 is presented below.

Brand and model	Features	Total price (€) per unit
Solar arrays		

A.4 Electrical Power System

EXA-Agencia Espacial Ecuatoriana	Total power of 67.2W (4units) Mass of 270g (p.unit) Included thermal protection At least 4 years lifetime	17000
ISIS	Total power of 30W (4units) Mass of 150g (p.unit) No thermal protection At least 2 years lifetime	9000
Power management		
Crystalspace P1 Vasik	Mass of 80g Full redundancy Low volume 6x outputs Up to 10W input High temperature range	5400
Gomspace NanoPower P60	Mass of 176g 9x configurable outputs 6x inputs per module EMI shielding High temperature range	16000
Batteries		
Gomspace NanoPower BP4	Total capacity of 77Wh (2u) Automatic heat regulation Highly stackable Mass of 270g (p.unit)	3250
EXA-Agencia Espacial Ecuatoriana	Total capacity of 106.4Wh (2u) Automatic heat regulation Highly stackable Total mass of 155g	6300

Table A.4: Options studied for the Electric Power System

Finally, the options chosen are presented in the table A.5.

System	Brand and model	Price per unit (€)	N. of units
Solar arrays	EXA	17000	4
Additional solar arrays	-	4000-12000	depends
Batteries	EXA	6300	2

A.4 Electrical Power System

Power Management	Gomspace NanoPower P60	16000	1
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Table A.5: Options studied for the Electric Power System