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# Causal Statistical Decision Problems

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## 1 Notes on category theoretic probability and string diagrams

Category theoretic treatments of probability theory often start with *probability monads* (for a good overview, see [Jacobs, 2018]). A monad on some category  $C$  is a functor  $T : C \rightarrow C$  along with natural transformations called the unit  $\eta : 1_C \rightarrow T$  and multiplication  $\mu : T^2 \rightarrow T$ . Roughly, functors are maps between categories that preserve identity and composition structure and natural transformations are "maps" between functors that also preserve composition structure. The monad unit is similar to the identity element of a monoid in that application of the identity followed by multiplication yields the identity transformation. The multiplication transformation is also (roughly speaking) associative.

An example of a probability monad is the discrete probability monad given by the functor  $\mathcal{D} : \mathbf{Set} \rightarrow \mathbf{Set}$  which maps a countable set  $X$  to the set of functions from  $X \rightarrow [0, 1]$  that are probability measures on  $X$ , denoted  $\mathcal{D}(X)$ .  $\mathcal{D}$  maps a measurable function  $f$  to  $\mathcal{D}f : X \rightarrow \mathcal{D}(X)$  given by  $\mathcal{D}f : x \mapsto \delta_{f(x)}$ . The unit of this monad is the map  $\eta_X : X \rightarrow \mathcal{D}(X)$  given by  $\eta_X : x \mapsto \delta_x$  (which is equivalent to  $\mathcal{D}1_X$ ) and multiplication is  $\mu_X : \mathcal{D}^2(X) \rightarrow \mathcal{D}(X)$  where  $\mu_X : \Omega \mapsto \sum_{\phi} \Omega(\phi)\phi$ .

For continuous distributions we have the Giry monad on the category  $\mathbf{Meas}$  of measurable spaces given by the functor  $\mathcal{G}$  which maps a measurable space  $X$  to the set of probability measures on  $X$ , denoted  $\mathcal{G}(X)$ . Other elements of the monad (unit, multiplication and map between morphisms) are the "continuous" version of the above.

Of particular interest is the Kleisli category of the monads above. The Kleisli  $C_T$  category of a monad  $T$  on category  $C$  is the category with the same objects and the morphisms  $X \rightarrow Y$  in  $C_T$  is the set of morphisms  $X \rightarrow TY$  in  $C$ . Thus the morphisms  $X \rightarrow Y$  in the Kleisli category  $\mathbf{Set}_{\mathcal{D}}$  are morphisms  $X \rightarrow \mathcal{D}(Y)$  in  $\mathbf{Set}$ , i.e. stochastic matrices, and in the Kleisli category  $\mathbf{Meas}_{\mathcal{G}}$  we have Markov kernels. Composition of arrows in the Kleisli categories correspond to Matrix products and "kernel products" respectively.

Both  $\mathcal{D}$  and  $\mathcal{G}$  are known to be *commutative* monads, and the Kleisli category of a commutative monad is a symmetric monoidal category.

Diagrams for symmetric monoidal categories consist of wires with arrows, boxes and a couple of special symbols. The identity object (which we identify with the set  $\{*\}$ ) is drawn as nothing at all  $\{*\} := \square$  and identity maps are drawn as bare wires:

$$\text{Id}_X := \begin{array}{c} \uparrow \\ \square \end{array}_X \quad (1)$$

We draw Kleisli arrows from the unit (i.e. probability distributions)  $\mu : \{*\} \rightarrow X$  as triangles and Kleisli arrows  $\kappa : X \rightarrow Y$  (i.e. Markov kernels  $X \rightarrow \Delta(\mathcal{Y})$ ) as boxes. We draw the Kleisli arrow

32  $\mathbb{1}_X : X \rightarrow \{*\}$  (which is unique for each  $X$ ) as below

$$\mu := \begin{array}{c} \uparrow X \\ \triangleleft \mu \end{array} \quad \kappa := \begin{array}{c} \uparrow Y \\ \boxed{\kappa} \end{array} \quad (2)$$

33 The product of objects in **Meas** is given by  $(X, \mathcal{X}) \cdot (Y, \mathcal{Y}) = (X \times Y, \mathcal{X} \otimes \mathcal{Y})$ , which we will  
 34 often write as just  $X \times Y$ . Horizontal juxtaposition of wires indicates this product, and horizontal  
 35 juxtaposition also indicates the tensor product of Kleisli arrows. Let  $\kappa_1 : X \rightarrow W$  and  $\kappa_2 : Y \rightarrow Z$ :

$$(X \times Y, \mathcal{X} \otimes \mathcal{Y}) := \begin{array}{c} \uparrow X \quad \uparrow Y \\ \hline \end{array} \quad \kappa_1 \otimes \kappa_2 := \begin{array}{c} \uparrow W \quad \uparrow Z \\ \boxed{\kappa_1} \quad \boxed{\kappa_2} \\ \hline X \quad Y \end{array} \quad (3)$$

36 Composition of arrows is achieved by “wiring” boxes together. For  $\kappa_1 : X \rightarrow Y$  and  $\kappa_2 : Y \rightarrow Z$   
 37 we have

$$\kappa_1 \kappa_2(x; A) = \int_Y \kappa_2(y; A) \kappa_1(x; dy) := \begin{array}{c} \uparrow Z \\ \boxed{\kappa_2} \\ \hline \boxed{\kappa_1} \\ \hline X \end{array} \quad (4)$$

38 Symmetric monoidal categories have the following coherence theorem[Selinger, 2010]:

39 **Theorem 1.1** (Coherence (symmetric monoidal)). *A well-formed equation between morphisms in*  
 40 *the language of symmetric monoidal categories follows from the axioms of symmetric monoidal*  
 41 *categories if and only if it holds, up to isomorphism of diagrams, in the graphical language.*

42 Isomorphism of diagrams for symmetric monoidal categories (somewhat informally) is any planar  
 43 deformation of a diagram including deformations that cause wires to cross. We consider a diagram  
 44 for a symmetric monoidal category to be well formed only if all wires point upwards.

45 In fact the Kleisli categories of the probability monads above have (for each object) unique *copy*:  
 46  $X \rightarrow X \times X$  and *erase*:  $X \rightarrow \{*\}$  maps that satisfy the *commutative comonoid axioms* that (thanks  
 47 to the coherence theorem above) can be stated graphically. These differ from the copy and erase maps  
 48 of *finite product* or *cartesian* categories in that they do not necessarily respect composition of arrows.

$$\text{Erase} = \mathbb{1}_X := \begin{array}{c} * \\ \downarrow \end{array} \quad \text{Copy} = x \mapsto \delta_{x,x} := \begin{array}{c} \swarrow \quad \searrow \\ \downarrow \end{array} \quad (5)$$

$$\begin{array}{c} \swarrow \quad \searrow \\ \downarrow \end{array} = \begin{array}{c} \swarrow \quad \searrow \\ \downarrow \end{array} := \begin{array}{c} \swarrow \quad \searrow \\ \downarrow \end{array} \quad (6)$$

$$\begin{array}{c} * \\ \downarrow \end{array} = \begin{array}{c} * \\ \downarrow \end{array} = \begin{array}{c} \uparrow \end{array} \quad (7)$$

$$\begin{array}{c} \swarrow \quad \searrow \\ \downarrow \end{array} = \begin{array}{c} \swarrow \quad \searrow \\ \downarrow \end{array} \quad (8)$$

49 Finally,  $\{*\}$  is a terminal object in the Kleisli categories of either probability monad. This means  
 50 that the map  $X \rightarrow \{*\}$  is unique for all objects  $X$ , and as a consequence for all objects  $X, Y$  and all  
 51  $\kappa : X \rightarrow Y$  we have

$$\begin{array}{c} * \\ \boxed{\kappa} \\ \downarrow \\ X \end{array} = \begin{array}{c} * \\ \downarrow \\ X \end{array} \quad (9)$$

52 This is equivalent to requiring for all  $x \in X$   $\int_Y \kappa(x; dy) = 1$ . In the case of  $\mathbf{Set}_{\mathcal{D}}$ , this condition is  
 53 what differentiates a stochastic matrix from a general positive matrix (which live in a larger category  
 54 than  $\mathbf{Set}_{\mathcal{D}}$ ).

55 Thus when manipulating diagrams representing Markov kernels in particular (and, importantly, not  
 56 more general symmetric monoidal categories) diagram isomorphism also includes applications of 6,  
 57 7, 8 and 9.

58 A particular property of the copy map in  $\mathbf{Meas}_{\mathcal{G}}$  (and probably  $\mathbf{Set}_{\mathcal{D}}$  as well) is that it commutes with  
 59 Markov kernels iff the markov kernels are deterministic [Fong, 2013].

## 60 1.1 Disintegration and Bayesian inversion

61 *Disintegration* is a key operation on probability distributions (equivalently arrows  $\{*\} \rightarrow X$ ) in  
 62 the categories under discussion. It corresponds to “finding the conditional probability” (though  
 63 conditional probability is usually formalised in a slightly different way).

64 Given a distribution  $\mu : \{*\} \rightarrow X \otimes Y$ , a disintegration  $c : X \rightarrow Y$  is a Markov kernel that satisfies

$$\begin{array}{c} X \quad Y \\ \downarrow \quad \downarrow \\ \boxed{\mu} \\ \downarrow \\ \mu \end{array} = \begin{array}{c} X \quad Y \\ \downarrow \quad \downarrow \\ \boxed{c} \\ \downarrow \\ \mu \end{array} \quad (10)$$

65 Disintegrations always exist in  $\mathbf{Set}_{\mathcal{D}}$  but not in  $\mathbf{Meas}_{\mathcal{G}}$ . They do exist in the latter if we restrict  
 66 ourselves to standard measurable spaces. If  $c_1$  and  $c_2$  are disintegrations  $X \rightarrow Y$  of  $\mu$ , they are equal  
 67  $\mu$ -A.S. In fact, this equality can be strengthened somewhat - they are equal almost surely with respect  
 68 to any distribution that shares the “ $X$ -marginal” of  $\mu$ .

69 Given  $\sigma : \{*\} \rightarrow X$  and a channel  $c : X \rightarrow Y$ , a Bayesian inversion of  $(\sigma, c)$  is a channel  $d : Y \rightarrow X$   
 70 such that

$$\begin{array}{c} X \quad Y \\ \downarrow \quad \downarrow \\ \boxed{c} \\ \downarrow \\ \sigma \end{array} = \begin{array}{c} X \quad Y \\ \downarrow \quad \downarrow \\ \boxed{d} \\ \downarrow \\ \sigma \end{array} \quad (11)$$

71 We can obtain disintegrations from Bayesian inversions and vice-versa.

72 Clerc et al. [2017] offer an alternative view of Bayesian inversion which they claim doesn’t depend  
 73 on standard measurability conditions, but there is a step in their proof I didn’t follow.

## 74 1.2 Generalisations

75 Cho and Jacobs [2019] make use of a larger “CD” category by dropping 9. I’m not completely clear  
 76 whether you end up with arrows being “Markov kernels for general measures” or something else (can  
 77 we have negative arrows?). This allows for the introduction of “observables” or “effects” of the form

$$\begin{array}{c} \triangle \\ \downarrow \\ f \end{array}$$

79 Jacobs et al. [2019] make use of an embedding of  $\mathbf{Set}_D$  in  $\mathbf{Mat}(\mathbb{R}^+)$  with morphisms all positive  
80 matrices (I'm not totally clear on the objects, or how they are self-dual - this doesn't seem to be  
81 exactly the same as the category of finite dimensional vector spaces). This latter category is compact  
82 closed, which - informally speaking - supports the same diagrams as symmetric monoidal categories  
83 with the addition of “upside down” wires.

### 84 1.3 Key questions for Causal Theories

85 **generalised disintegrations** : Of key importance to our work is generalising the notion of disinte-  
86 gration (and possibly Bayesian inversion) to general kernels  $X \rightarrow Y$  rather than restricting ourselves  
87 to probability distributions  $\{*\} \rightarrow Y$ . We will define generalised disintegrations as a straightforward  
88 analogy regular disintegrations, but the conditions under which such disintegrations exist are more  
89 restrictive than for regular disintegrations.

90 A kernel  $c : X \rightarrow Y$  is a *generalised disintegration* (“g-disintegration”) of  $\kappa$  from  $X$  to  $Y$  if the  
91 following holds:

$$(12)$$

92 In contrast to regular disintegrations, generalised disintegrations “usually” do not exist. Consider  
93  $D = X = Y = \{0, 1\}$  and

$$\kappa : \begin{cases} 1 \mapsto \delta_1 \otimes \delta_1 \\ 0 \mapsto \delta_1 \otimes \delta_0 \end{cases} \quad (13)$$

94 There is clearly no kernel  $c : X \rightarrow Y$  that simultaneously satisfies  $\delta_1 c = \delta_1$  if  $D = 1$  and  $\delta_0 c = \delta_0$   
95 if  $D = 0$ . However, we can define particular g-disintegrations that do generically exist subject to  
96 some regularity conditions (recall that ordinary disintegrations are shown to exist only in the context  
97 of standard measurable spaces). Given  $\kappa : D \rightarrow X \times Y$ , define the *canonical extension*  $\kappa_{id}$ :

$$(14)$$

98 The canonical extension takes a copy of the input and maps it to the output.

99 **Theorem 1.2.** For all  $\kappa : D \rightarrow X \times Y$ , if  $D$  is countable and  $X \times Y$  is standard measurable, a  
100 g-disintegration of  $\kappa_{id}$  exists in the following three directions: from  $D \rightarrow X \times Y$ , from  $D \times X \rightarrow Y$   
101 and from  $D \times Y \rightarrow X$ .

102 *Proof.* For  $D \rightarrow X \times Y$ , we note that  $\kappa$  is always a disintegration:

$$(15)$$

103  $D \times X \rightarrow Y$  and  $D \times Y \rightarrow X$  are symmetric directions, so we will argue only for  $D \times X \rightarrow Y$ .  
104 For all  $y \in D$  we have a disintegration  $c_y : X \rightarrow Y$  of  $\delta_y \kappa$  by standard measurability of  $X \times Y$ .

105 Define  $c : D \times X \rightarrow Y$  by  $c : (y, x) \mapsto c_y(x)$ . Clearly,  $c(y, x)$  is a probability distribution on  $Y$   
 106 for all  $(y, x) \in D \times X$ . It remains to show  $c(\cdot)^{-1}(B)$  is measurable for all  $B \in \mathcal{B}([0, 1])$ . But  
 107  $c(\cdot)^{-1}(B) = \cap_{y \in D} c_y(\cdot)^{-1}(B)$ . The right hand side is measurable by measurability of  $c_y(\cdot)^{-1}(B)$   
 108 and the properties of a  $\sigma$ -algebra, so  $c$  is a Markov kernel. By the definition of  $c_y$ , we have for all  
 109  $y \in D$

$$(16)$$

$$(17)$$

110 Which implies

$$(18)$$

111 □

112 **Conjecture:** This can be generalised to any  $\kappa$  that is determined by its values on a countable set of  
 113 points along with some notion of continuity. This seems likely to be true. In a more general setting, I  
 114 think I could find a counterexample, but the converse also seems unlikely.

115 The extension of *conditional independence* to g-disintegrations becomes a directional relationship.  
 116 Suppose we have  $\kappa : D \rightarrow X \times Y$  and a disintegration  $c : D \times X \rightarrow Y$ . We say  $Y$  is directionally  
 117 conditionally independent (DCI) of  $D$  given  $X$  if

118 Generalised disintegrations facilitate the following construction of a “graphical model”:

119 Suppose we have two causal theories,  $\mathcal{T}^*$  and  $\mathcal{T}$  both with signature  $E \times D \rightarrow E$ , and  $\mathcal{T}$  is a decision  
 120 randomised version of  $\mathcal{T}^*$  (i.e.  $\mathcal{T} = \{(\lambda\kappa, \mu) | (\kappa, \mu) \in \mathcal{T}^*\}$  for some  $\lambda : D \rightarrow D$ ). We will construct  
 121 a graphical model from  $\mathcal{T}^*$  and  $\mathcal{T}$  in three steps:

122 First, we assume *reproducibility* in the stronger theory  $\mathcal{T}^*$ . That is, for all  $(\kappa, \mu) \in \mathcal{T}^*$  we suppose  
 123 there exists  $\gamma \in \Delta(D)$  such that  $\gamma\kappa = \mu$ .

125 Second, we will assume certain *generalised conditional independences* hold for the stronger theory  
 126  $\mathcal{T}^*$  (we have not defined these, but they are the obvious generalisation of standard conditional  
 127 independence lifted to g-disintegrations). Because we’re constructing a graphical model, we will  
 128 assume these are a “DAG-compatible” set, though we are under no obligation to do so. I conjecture  
 129 we can illustrate these independences graphically. Suppose we have random variables  $X : E \rightarrow X$ ,  
 130  $Y : E \rightarrow Y$  and  $Z : E \rightarrow Z$ , and we assume we have at least the generalised CIs implied by the

I don’t think reproducibility is quite the right assumption, but it is good enough for now

131 following diagram for all  $(\kappa, \mu) \in \mathcal{T}^*$ :

$$\kappa = \begin{array}{c} \begin{array}{c} Z \\ \downarrow \\ \boxed{c_{Z|Y}} \\ \swarrow \quad \searrow \\ Y \quad \quad X \\ \swarrow \quad \searrow \\ \boxed{c_{Y|X}} \\ \swarrow \quad \searrow \\ X \quad \quad \end{array} \\ \downarrow \\ \begin{array}{c} \text{**} \\ \downarrow \\ \boxed{\kappa} \\ \downarrow \\ E \end{array} \end{array} \quad (19)$$

132 The above diagram is typed incorrectly, but we can always construct a kernel  $\kappa_{XYZ}$  that maps to  
 133  $X \times Y \times Z$ .

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