
Causal Statistical Decision Problems

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1 Notes on category theoretic probability and string diagrams

Category theoretic treatments of probability theory often start with *probability monads* (for a good overview, see [Jacobs, 2018]). A monad on some category C is a functor $T : C \rightarrow C$ along with natural transformations called the unit $\eta : 1_C \rightarrow T$ and multiplication $\mu : T^2 \rightarrow T$. Roughly, functors are maps between categories that preserve identity and composition structure and natural transformations are "maps" between functors that also preserve composition structure. The monad unit is similar to the identity element of a monoid in that application of the identity followed by multiplication yields the identity transformation. The multiplication transformation is also (roughly speaking) associative.

An example of a probability monad is the discrete probability monad given by the functor $\mathcal{D} : \mathbf{Set} \rightarrow \mathbf{Set}$ which maps a countable set X to the set of functions from $X \rightarrow [0, 1]$ that are probability measures on X , denoted $\mathcal{D}(X)$. \mathcal{D} maps a measurable function f to $\mathcal{D}f : X \rightarrow \mathcal{D}(X)$ given by $\mathcal{D}f : x \mapsto \delta_{f(x)}$. The unit of this monad is the map $\eta_X : X \rightarrow \mathcal{D}(X)$ given by $\eta_X : x \mapsto \delta_x$ (which is equivalent to $\mathcal{D}1_X$) and multiplication is $\mu_X : \mathcal{D}^2(X) \rightarrow \mathcal{D}(X)$ where $\mu_X : \Omega \mapsto \sum_{\phi} \Omega(\phi)\phi$.

For continuous distributions we have the Giry monad on the category \mathbf{Meas} of measurable spaces given by the functor \mathcal{G} which maps a measurable space X to the set of probability measures on X , denoted $\mathcal{G}(X)$. Other elements of the monad (unit, multiplication and map between morphisms) are the "continuous" version of the above.

Of particular interest is the Kleisli category of the monads above. The Kleisli C_T category of a monad T on category C is the category with the same objects and the morphisms $X \rightarrow Y$ in C_T is the set of morphisms $X \rightarrow TY$ in C . Thus the morphisms $X \rightarrow Y$ in the Kleisli category $\mathbf{Set}_{\mathcal{D}}$ are morphisms $X \rightarrow \mathcal{D}(Y)$ in \mathbf{Set} , i.e. stochastic matrices, and in the Kleisli category $\mathbf{Meas}_{\mathcal{G}}$ we have Markov kernels. Composition of arrows in the Kleisli categories correspond to Matrix products and "kernel products" respectively.

Both \mathcal{D} and \mathcal{G} are known to be *commutative* monads, and the Kleisli category of a commutative monad is a symmetric monoidal category.

Diagrams for symmetric monoidal categories consist of wires with arrows, boxes and a couple of special symbols. The identity object (which we identify with the set $\{*\}$) is drawn as nothing at all $\{*\} := \square$ and identity maps are drawn as bare wires:

$$\text{Id}_X := \begin{array}{c} \uparrow \\ \square \end{array}_X \quad (1)$$

We draw Kleisli arrows from the unit (i.e. probability distributions) $\mu : \{*\} \rightarrow X$ as triangles and Kleisli arrows $\kappa : X \rightarrow Y$ (i.e. Markov kernels $X \rightarrow \Delta(\mathcal{Y})$) as boxes. We draw the Kleisli arrow

32 $\mathbb{1}_X : X \rightarrow \{*\}$ (which is unique for each X) as below

$$\mu := \begin{array}{c} \uparrow X \\ \triangle \end{array} \quad \kappa := \begin{array}{c} \uparrow Y \\ \square \end{array} \quad (2)$$

33 The product of objects in **Meas** is given by $(X, \mathcal{X}) \cdot (Y, \mathcal{Y}) = (X \times Y, \mathcal{X} \otimes \mathcal{Y})$, which we will
 34 often write as just $X \times Y$. Horizontal juxtaposition of wires indicates this product, and horizontal
 35 juxtaposition also indicates the tensor product of Kleisli arrows. Let $\kappa_1 : X \rightarrow W$ and $\kappa_2 : Y \rightarrow Z$:

$$(X \times Y, \mathcal{X} \otimes \mathcal{Y}) := \begin{array}{c} \uparrow X \quad \uparrow Y \end{array} \quad \kappa_1 \otimes \kappa_2 := \begin{array}{c} \uparrow W \quad \uparrow Z \\ \square \kappa_1 \quad \square \kappa_2 \\ \downarrow X \quad \downarrow Y \end{array} \quad (3)$$

36 Composition of arrows is achieved by “wiring” boxes together. For $\kappa_1 : X \rightarrow Y$ and $\kappa_2 : Y \rightarrow Z$
 37 we have

$$\kappa_1 \kappa_2(x; A) = \int_Y \kappa_2(y; A) \kappa_1(x; dy) := \begin{array}{c} \uparrow Z \\ \square \kappa_2 \\ \downarrow Y \\ \square \kappa_1 \\ \downarrow X \end{array} \quad (4)$$

38 Symmetric monoidal categories have the following coherence theorem[Selinger, 2010]:

39 **Theorem 1.1** (Coherence (symmetric monoidal)). *A well-formed equation between morphisms in*
 40 *the language of symmetric monoidal categories follows from the axioms of symmetric monoidal*
 41 *categories if and only if it holds, up to isomorphism of diagrams, in the graphical language.*

42 Isomorphism of diagrams for symmetric monoidal categories (somewhat informally) is any planar
 43 deformation of a diagram including deformations that cause wires to cross. We consider a diagram
 44 for a symmetric monoidal category to be well formed only if all wires point upwards.

45 In fact the Kleisli categories of the probability monads above have (for each object) unique *copy*:
 46 $X \rightarrow X \times X$ and *erase*: $X \rightarrow \{*\}$ maps that satisfy the *commutative comonoid axioms* that (thanks
 47 to the coherence theorem above) can be stated graphically. These differ from the copy and erase
 48 maps of *finite product* or *cartesian* categories in that they do not necessarily respect composition of
 49 morphisms.

$$\text{Erase} = \mathbb{1}_X := \begin{array}{c} * \\ \uparrow \end{array} \quad \text{Copy} = x \mapsto \delta_{x,x} := \begin{array}{c} \swarrow \quad \searrow \\ \uparrow \end{array} \quad (5)$$

$$\begin{array}{c} \swarrow \quad \searrow \\ \uparrow \end{array} = \begin{array}{c} \swarrow \quad \searrow \\ \uparrow \end{array} := \begin{array}{c} \swarrow \quad \searrow \\ \uparrow \end{array} \quad (6)$$

$$\begin{array}{c} * \\ \uparrow \end{array} = \begin{array}{c} * \\ \uparrow \end{array} = \begin{array}{c} \uparrow \end{array} \quad (7)$$

$$\begin{array}{c} \swarrow \quad \searrow \\ \uparrow \end{array} = \begin{array}{c} \swarrow \quad \searrow \\ \uparrow \end{array} \quad (8)$$

50 Finally, $\{*\}$ is a terminal object in the Kleisli categories of either probability monad. This means
 51 that the map $X \rightarrow \{*\}$ is unique for all objects X , and as a consequence for all objects X, Y and all
 52 $\kappa : X \rightarrow Y$ we have

$$\begin{array}{c} * \\ \boxed{\kappa} \\ \downarrow \\ X \end{array} = \begin{array}{c} * \\ \downarrow \\ X \end{array} \quad (9)$$

53 This is equivalent to requiring for all $x \in X$ $\int_Y \kappa(x; dy) = 1$. In the case of $\mathbf{Set}_{\mathcal{D}}$, this condition is
 54 what differentiates a stochastic matrix from a general positive matrix (which live in a larger category
 55 than $\mathbf{Set}_{\mathcal{D}}$).

56 Thus when manipulating diagrams representing Markov kernels in particular (and, importantly, not
 57 more general symmetric monoidal categories) diagram isomorphism also includes applications of 6,
 58 7, 8 and 9.

59 A particular property of the copy map in $\mathbf{Meas}_{\mathcal{G}}$ (and probably $\mathbf{Set}_{\mathcal{D}}$ as well) is that it commutes with
 60 Markov kernels iff the markov kernels are deterministic [Fong, 2013].

61 1.1 Disintegration and Bayesian inversion

62 *Disintegration* is a key operation on probability distributions (equivalently arrows $\{*\} \rightarrow X$) in
 63 the categories under discussion. It corresponds to “finding the conditional probability” (though
 64 conditional probability is usually formalised in a slightly different way).

65 Given a distribution $\mu : \{*\} \rightarrow X \otimes Y$, a disintegration $c : X \rightarrow Y$ is a Markov kernel that satisfies

$$\begin{array}{c} X \quad Y \\ \downarrow \quad \downarrow \\ \boxed{\mu} \\ \downarrow \\ \mu \end{array} = \begin{array}{c} X \quad Y \\ \downarrow \quad \downarrow \\ \boxed{c} \\ \downarrow \\ \mu \end{array} \quad (10)$$

66 Disintegrations always exist in $\mathbf{Set}_{\mathcal{D}}$ but not in $\mathbf{Meas}_{\mathcal{G}}$. They do exist in the latter if we restrict
 67 ourselves to standard measurable spaces. If c_1 and c_2 are disintegrations $X \rightarrow Y$ of μ , they are equal
 68 μ -A.S. In fact, this equality can be strengthened somewhat - they are equal almost surely with respect
 69 to any distribution that shares the “ X -marginal” of μ .

70 Given $\sigma : \{*\} \rightarrow X$ and a channel $c : X \rightarrow Y$, a Bayesian inversion of (σ, c) is a channel $d : Y \rightarrow X$
 71 such that

$$\begin{array}{c} X \quad Y \\ \downarrow \quad \downarrow \\ \boxed{c} \\ \downarrow \\ \sigma \end{array} = \begin{array}{c} X \quad Y \\ \downarrow \quad \downarrow \\ \boxed{d} \\ \downarrow \\ \sigma \end{array} \quad (11)$$

72 We can obtain disintegrations from Bayesian inversions and vice-versa.

73 Clerc et al. [2017] offer an alternative view of Bayesian inversion which they claim doesn’t depend
 74 on standard measurability conditions, but there is a step in their proof I didn’t follow.

75 1.2 Generalisations

76 Cho and Jacobs [2019] make use of a larger “CD” category by dropping 9. I’m not completely clear
 77 whether you end up with arrows being “Markov kernels for general measures” or something else (can
 78 we have negative arrows?). This allows for the introduction of “observables” or “effects” of the form

$$\begin{array}{c} \triangle \\ \downarrow \\ f \end{array}$$

79

80 Jacobs et al. [2019] make use of an embedding of $\mathbf{Set}_{\mathcal{D}}$ in $\mathbf{Mat}(\mathbb{R}^+)$ with morphisms all positive
 81 matrices (I’m not totally clear on the objects, or how they are self-dual - this doesn’t seem to be
 82 exactly the same as the category of finite dimensional vector spaces). This latter category is compact
 83 closed, which - informally speaking - supports the same diagrams as symmetric monoidal categories
 84 with the addition of “upside down” wires.

85 1.3 Key questions for Causal Theories

86 We will first define *labeled diagrams*. Rather than labelling the wires of our diagrams with *spaces* (as is
 87 typical [Selinger, 2010]), we assign a unique label to each “wire segment” (with some qualifications).
 88 That is, we assign a unique label to each bare wire in the diagram with the following additional
 89 qualifications:

I’m sure one of the papers I read mentioned labeled diagrams, I just couldn’t find it when I looked for it

- 90 • If we have a box in the diagram representing the identity map, the incoming and outgoing
 91 wires are given the same label
- 92 • If we have a wire crossing in the diagram, the diagonally opposite wires are given the same
 93 label
- 94 • The input wire and the *two* output wires of the copy map are given the same label

95 Given two diagrams G_1 and G_2 that are isomorphic under transformations licenced by the axioms of
 96 symmetric monoidal categories and commutative comonoid axioms, suppose we have a labelling of
 97 G_1 . We can label G_2 using the following translation rule:

- 98 • For each box in G_2 , we can identify a corresponding box in G_1 via labels on each box. For
 99 each such pair of boxes, we label the incoming wires of the G_2 box with the labels of the
 100 G_1 box preserving the left-right order. We do likewise for outgoing wires.

101 These rules will lead to a unique labelling of G_2 with all wire segments are labelled. We would like
 102 for these rules to yield the following:

- 103 • For any sequence of diagram isomorphisms beginning with G_1 and ending with G_2 , we end
 104 up with the same set of labels
- 105 • If we label G_2 according to the rules above then relabel G_1 from G_2 according to the same
 106 rules we retrieve the original labels of G_1

107 We do not prove these properties here, but motivate them via the following considerations:

- 108 • These properties obviously hold for the wire segments into and out of boxes
- 109 • The only features a diagram may have apart from boxes and wires are wire crossings, copy
 110 maps and erase maps
- 111 • The labeling rule for wire crossings respects the symmetry of the swap map
- 112 • The labeling rule for copy maps respects the symmetry of the copy map and the property
 113 described in Equation 8

114 We will follow the convention whereby “internal” wire labels are omitted from diagrams.

115 Note also that each wire that terminates in a free end can be associated with a random variable.
 116 Suppose for $N \in \mathbb{N}$ we have a kernel $\kappa : A \rightarrow \Delta(\times_{i \in N} X_i)$. Define by p_j ($j \in [N]$) the projection
 117 map $p_j : \times_{i \in N} X_i \rightarrow X_j$ defined by $p_j : (x_0, \dots, x_N) \mapsto x_j$. p_j is a measurable function, hence
 118 a random variable. Define by π_j the projection kernel $\mathcal{G}(\pi_j)$ (that is, $\pi_j : \mathbf{x} \mapsto \delta_{p_j(\mathbf{x})}$). Note that
 119 $\kappa(y; p_j^{-1}(A)) = \int_{X_j} \delta_{p_j(\mathbf{x})}(A) \kappa(y; d\mathbf{x}) = \kappa \pi_j$. Diagrammatically, π_j is the identity map on the j -th
 120 wire tensored with the erase map on every other wire. Thus the j -th wire carries the distribution
 121 associated with the random variable p_j . We will therefore consider the labels of the “outgoing” wires
 122 of a diagram to denote random variables (though there are obviously many random variables not
 123 represented by such wires). We will additionally distinguish wire labels from spaces by font - wire
 124 labels are sans serif A, B, C, X, Y, Z while spaces are serif A, B, C, X, Y, Z .

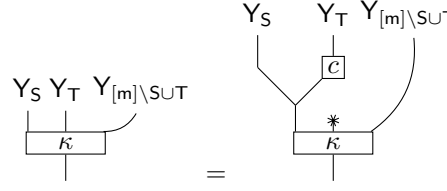
Wire labels appear to have a key advantage over random variables: they allow us to “forget” the sample space as the correct typing is handled automatically by composition and erasure of wires

126 **generalised disintegrations** : Of key importance to our work is generalising the notion of disinte-
 127 gration (and possibly Bayesian inversion) to general kernels $X \rightarrow Y$ rather than restricting ourselves
 128 to probability distributions $\{\ast\} \rightarrow Y$. We will define generalised disintegrations as a straightforward
 129 analogy regular disintegrations, but the conditions under which such disintegrations exist are more
 130 restrictive than for regular disintegrations.

131 **Definition 1.2** (Label signatures). If a kernel $\kappa : X \rightarrow \Delta(Y)$ can be represented by a diagram
 132 G with incoming wires X_1, \dots, X_n and outgoing wires Y_1, \dots, Y_m , we can assign the kernel a “label
 133 signature” $\kappa : X_1 \otimes \dots \otimes X_n \dashrightarrow Y_1 \otimes \dots \otimes Y_m$ or, for short, $\kappa : X_{[n]} \dashrightarrow Y_{[m]}$. Note that this
 134 signature associates each label with a unique space - the space of X_1 is the space associated with the
 135 left-most wire of G and so forth. We will implicitly leverage this correspondence and write with X_1
 136 the space associated with X_1 and so forth. Note that while X_1 is by construction always different from
 137 X_2 (or any other label), the space X_1 may coincide with X_2 - the fact that labels always maintain
 138 distinctions between wires is the fundamental reason for introducing them in the first place.

139 There might actually be some sensible way to consider κ to be transforming the measurable
 functions of a type similar to $\otimes_{i \in [n]} X_i$ to functions of a type similar to $\otimes_{i \in [m]} Y_i$ (or vice
 versa - perhaps related to Clerc et al. [2017]), but wire labels are all we need at this point

140 **Definition 1.3** (Generalised disintegration). Given a kernel $\kappa : X \rightarrow \Delta(Y)$ with label signature
 141 $\kappa : X_{[n]} \dashrightarrow Y_{[m]}$ and disjoint subsets $S, T \subset [m]$, a kernel c is a *g-disintegration from S to T* if
 142 it’s type is compatible with the label signature $c : Y_S \dashrightarrow Y_T$ and we have the identity (omitting
 143 incoming wire labels):



$$(12)$$

144 I have introduced without definition additional labeling operations here: first, each label has
 a particular space associated with it (in order to license the notion of “type compatible with
 label signature”), and we have supposed labels can be “bundled”.

145 In contrast to regular disintegrations, generalised disintegrations “usually” do not exist. Consider
 146 $X = \{0, 1\}$, $Y = \{0, 1\}^2$ and κ has label signature $X_1 \dashrightarrow Y_{\{1,2\}}$ with

$$\kappa : \begin{cases} 1 \mapsto \delta_1 \otimes \delta_1 \\ 0 \mapsto \delta_1 \otimes \delta_0 \end{cases} \quad (13)$$

147 κ imposes contradictory requirements for any disintegration $c : \{0, 1\} \rightarrow \{0, 1\}$ from $\{1\}$ to $\{2\}$:
 148 equality for $X_1 = 1$ requires $c(1; \cdot) = \delta_1$ while equality for $X_1 = 0$ requires $c(1; \cdot) = \delta_0$. Subject
 149 to some regularity conditions (similar to standard Borel conditions for regular disintegrations),
 150 we can define g-disintegrations of a canonically related kernel that do generally exist; intuitively,
 151 g-disintegrations exist if they take the “input wires” of κ as input wires themselves.

152 **Lemma 1.4** (Right inverses are deterministic kernels). *Given $\kappa : X \rightarrow \Delta(Y)$ for countable*
 153 *X and standard measurable Y . A right inverse κ^\dagger exists iff there exists a measurable function*
 154 *$f : Y \rightarrow X$ such that for all $x \in X$, $y \in Y$, $f(y) = x$ κ_x -almost surely. Moreover, in such a case*
 155 *$\kappa^\dagger(y; A) = \delta_{f(y)}(A)$.*

156 *Proof.* Suppose we have such a function f . We immediately have measurability: $f^{-1}(A)$ for all
 157 measurable A is a countable union of supports which are themselves measurable. Furthermore,
 158 $\int_Y \kappa(x; dy) \delta_{f(y)}(A) = \delta_x(A)$ so $\delta_{f(y)}(A)$ is a right inverse of κ as needed.

159 Suppose we have a right inverse κ^\dagger . By definition, $\int_Y \kappa(x; dy) \kappa^\dagger(y; A) = \delta_x(A) \stackrel{\kappa_x - A.S.}{=}$
 160 $\int_Y \kappa(x; dy) \delta_x(A)$. □

161 **Theorem 1.5.** Given countable X , standard measurable Y , $n, m \in \mathbb{N}$, $S, T \subset [m]$ a g -disintegration
 162 exists from S to T for all $\kappa : X \rightarrow Y$ with label signature $X[n] \dashrightarrow Y[m]$ iff $\kappa\pi_S$ is right-invertible.

163 *Proof.* For $D \rightarrow X \times Y$, we note that κ is always a disintegration:

$$\begin{array}{c}
 \begin{array}{c} XY D \\ \hline \kappa \end{array} \\
 D
 \end{array}
 =
 \begin{array}{c}
 \begin{array}{c} XY D \\ \hline \kappa \end{array} \\
 D
 \end{array}
 \quad (14)$$

164 Given $\kappa : D \rightarrow X \times Y$, define the *canonical extension* κ_{id} :

$$\begin{array}{c}
 \begin{array}{c} XY D \\ \hline \kappa \end{array} \\
 D
 \end{array}
 := \kappa_{id} \quad (15)$$

165 The canonical extension takes a copy of the input and maps it to the output.

166 $D \times X \rightarrow Y$ and $D \times Y \rightarrow X$ are symmetric directions, so we will argue only for $D \times X \rightarrow Y$.
 167 For all $y \in D$ we have a disintegration $c_y : X \rightarrow Y$ of $\delta_y \kappa$ by standard measurability of $X \times Y$.
 168 Define $c : D \times X \rightarrow Y$ by $c : (y, x) \mapsto c_y(x)$. Clearly, $c(y, x)$ is a probability distribution on Y
 169 for all $(y, x) \in D \times X$. It remains to show $c(\cdot)^{-1}(B)$ is measurable for all $B \in \mathcal{B}([0, 1])$. But
 170 $c(\cdot)^{-1}(B) = \cap_{y \in D} c_y(\cdot)^{-1}(B)$. The right hand side is measurable by measurability of $c_y(\cdot)^{-1}(B)$
 171 and the properties of a σ -algebra, so c is a Markov kernel. By the definition of c_y , we have for all
 172 $y \in D$

$$\begin{array}{c}
 \begin{array}{c} XY D \\ \hline \kappa \end{array} \\
 \delta_y
 \end{array}
 =
 \begin{array}{c}
 \begin{array}{c} X Y D \\ \hline c_y \end{array} \\
 \begin{array}{c} \kappa \\ \delta_y \end{array}
 \end{array}
 \quad (16)$$

$$\begin{array}{c}
 \begin{array}{c} X Y D \\ \hline \kappa \end{array} \\
 \delta_y
 \end{array}
 =
 \begin{array}{c}
 \begin{array}{c} X Y D \\ \hline c \end{array} \\
 \begin{array}{c} \kappa \\ \delta_y \end{array}
 \end{array}
 \quad (17)$$

173 Which implies

$$\begin{array}{c}
 \begin{array}{c} XY D \\ \hline \kappa \end{array} \\
 \delta_y
 \end{array}
 =
 \begin{array}{c}
 \begin{array}{c} X Y D \\ \hline c \end{array} \\
 \begin{array}{c} \kappa \\ \delta_y \end{array}
 \end{array}
 \quad (18)$$

174 Note that the only other (non-trivial) disintegrations do not feature D as an “input wire”. All such

175 □

176 **Conjecture:** This can be generalised to any κ that is determined by its values on a countable set of
 177 points along with some notion of continuity. This seems likely to be true. In a more general setting, I
 178 think I could find a counterexample, but the converse also seems unlikely.

179 The extension of *conditional independence* to g-disintegrations becomes a directional relationship.
 180 Suppose we have $\kappa : D \rightarrow X \times Y$ and a disintegration $c : D \times X \rightarrow Y$. We say Y is directionally
 181 conditionally independent (DCI) of D given X if

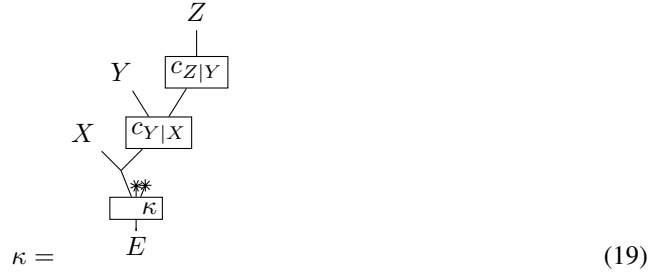
182 Generalised disintegrations facilitate the following construction of a “graphical model”:

183 Suppose we have two causal theories, \mathcal{T}^* and \mathcal{T} both with signature $E \times D \rightarrow E$, and \mathcal{T} is a decision
 184 randomised version of \mathcal{T}^* (i.e. $\mathcal{T} = \{(\lambda\kappa, \mu) | (\kappa, \mu) \in \mathcal{T}^*\}$ for some $\lambda : D \rightarrow D$). We will construct
 185 a graphical model from \mathcal{T}^* and \mathcal{T} in three steps:

186 First, we assume *reproducibility* in the stronger theory \mathcal{T}^* . That is, for all $(\kappa, \mu) \in \mathcal{T}^*$ we suppose
 187 there exists $\gamma \in \Delta(\mathcal{D})$ such that $\gamma\kappa = \mu$.

188

189 Second, we will assume certain *generalised conditional independences* hold for the stronger theory
 190 \mathcal{T}^* (we have not defined these, but they are the obvious generalisation of standard conditional
 191 independence lifted to g-disintegrations). Because we’re constructing a graphical model, we will
 192 assume these are a “DAG-compatible” set, though we are under no obligation to do so. I conjecture
 193 we can illustrate these independences graphically. Suppose we have random variables $X : E \rightarrow X$,
 194 $Y : E \rightarrow Y$ and $Z : E \rightarrow Z$, and we assume we have at least the generalised CIs implied by the
 195 following diagram for all $(\kappa, \mu) \in \mathcal{T}^*$:



I don't think reproducibility is quite the right assumption, but it is good enough for now

196 The above diagram is typed incorrectly, but we can always construct a kernel κ_{XYZ} that maps to
 197 $X \times Y \times Z$.

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