# **Building Verified Program Analyzers in Coq**

**Lecture 1: Motivations and Examples** 

**David Pichardie - INRIA Rennes / Harvard University** 

The increasing complexity of safety critical systems requires efficient validation techniques

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- Manual verifications
  - do not scale

manual verification

yesterday

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- Automatic bug finders
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manual verification	bug finders
yesterday	today

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- Automatic, sound verifiers
  - find all bugs, may raise false alarms
     ex: the Astrée static analyzer

http://www.astree.ens.fr/



~1M loc of a critical controlcommand software analyzed

0 false alarms

manual verification	bug finders	sound verifiers
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- Automatic bug finders
  - may miss some bugs
- Automatic, sound verifiers
  - find all bugs, may raise false alarms
     ex: the Astrée static analyzer
- Formally-verified verifiers
  - the verifier comes with a soundness proof
  - that is machine checked

http://www.astree.ens.fr/



~1M loc of a critical controlcommand software analyzed

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manual verification	bug finders	sound verifiers	verified verifiers
yesterday	today	tomorrow	after tomorrow

A simple idea:

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Program and prove your verifier in the same language!

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Which language?

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Which language?







First face:



#### First face:

• a proof assistant that allows to interactively build proof in constructive logic



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#### Second face:



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a functional programming language with a very rich type system



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 a functional programming language with a very rich type system example:

```
sort: \forall 1: list int, { l': list int | Sorted l' \land PermutationOf l l' }
```



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a proof assistant that allows to interactively build proof in constructive logic

#### Second face:

 a functional programming language with a very rich type system example:

```
sort: \forall 1: list int, { l': list int | Sorted l' \land PermutationOf l l' }
```

with an extraction mechanism to Ocaml

```
sort: int list \rightarrow int list
```

### Coming soon...



The next lecture will provide a short introduction to Coq

You may want to install the tool on you computer during this first lecture (but please, try to keep focused nevertheless...)

Instructions for installation:

http://www.irisa.fr/celtique/pichardie/teaching/digicosme13

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We program the static analyzer inside Coq

```
Definition analyzer (p:program) := ...
```

Static Analyzer

Logical Framework (here Coq)

We program the static analyzer inside Coq

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We state its correctness wrt. a formal specification of the language semantics

```
Theorem analyser_is_sound : \forall p, analyser p = Yes \rightarrow Sound(p)
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Static Analyzer

Language Semantics

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We interactively and mechanically prove this theorem

```
Proof. ... (* few days later *) ... Qed.
```

Static Analyzer

Language Semantics

Soundness Proof

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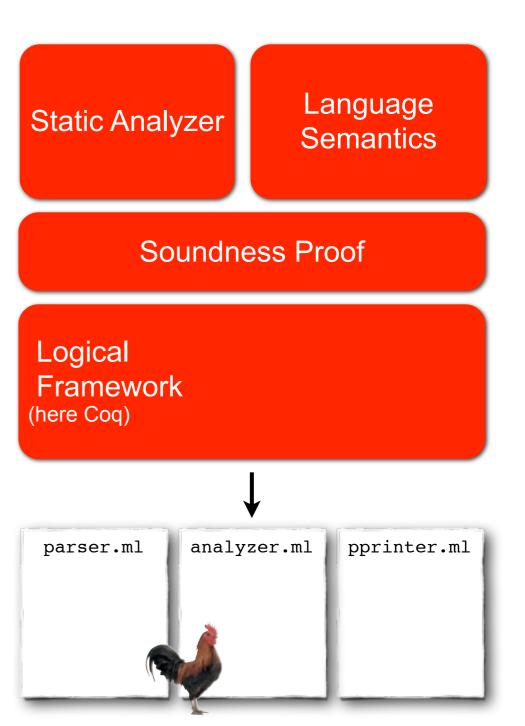
```
Theorem analyser_is_sound : \forall p, analyser p = Yes \rightarrow Sound(p)
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We interactively and mechanically prove this theorem

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Proof. ... (* few days later *) ... Qed.
```

We extract an OCaml implementation of the analyzer

```
Extraction analyzer.
```



### A Posteriori Validation

An important tool in our toolbox

We program the full static analyzer inside Coq

```
Definition analyzer (p:program) :=
    ...
    let x := complex_computation p in
    ...
...
...or ...
```

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Definition analyzer (p:program) :=
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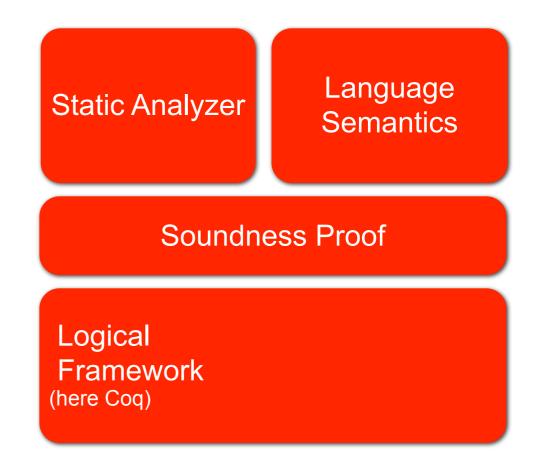
... or we program some parts in Coq, other parts in OCaml and use a verified validator

Ideally we also prove (on paper) that if the external implementation implements correctly a well-known algorithm then the validator will always succeed (completeness)

### Trusted Computing Base (TCB)

- 1. Formal specification of the programming language semantics
  - (informally) shared by any end-user programmer, compiler, static analyzer
  - less specialized than static analyzer's abstract semantics

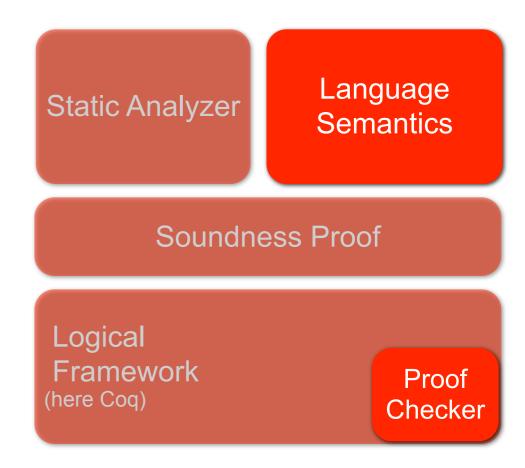
- 2. Logical Framework
  - only the proof checker needs to be trusted
  - we don't trust sophisticated decision procedures



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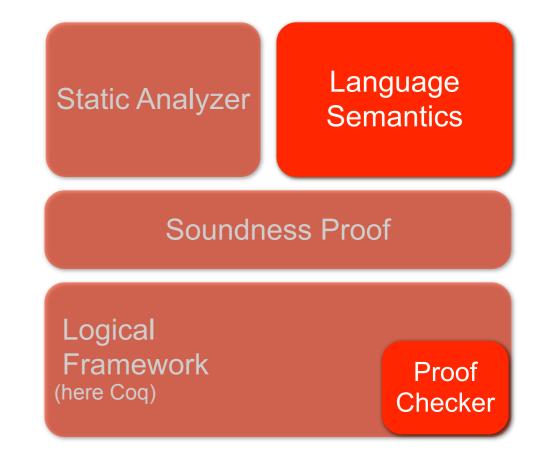
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Still a large code base but at least a foundational code base: logic & semantics

### Using Proof Assistants in PL Research

We distinguish two approaches

- 1. Accompany a research paper with a machine checked proof
  - increase the trust in a scientific result
  - facilitate the review process
- 2. Help building highly reliable *meta-programs* (programs that manipulate programs: compilers, program verifiers, type checkers...)
  - require to program the tool inside the proof assistant (generic interface, efficient data-structures)
  - must scale to realistic languages with large formal semantics

### Verified PL Stacks: Achievements

Some major achievements have changed our expectations about programming language mechanized proofs

- M6: JVM bytecode interpreter in ACL2 (Liu)
- Jinja: source & bytecode Java, compiler, BCV in Isabelle/HOL (Klein & Nipkow, and extensions by Lochbihler)
- CompCert: realistic C compiler in Coq (Leroy, Blazy et al.)
- Verified Software ToolChain: extension of CompCert for concurrent C programs (Appel et al.)
- seL4: verified OS kernel in Isabelle/HOL (Klein, Norrish et al.)

### Verified Static Analysis: Objectives

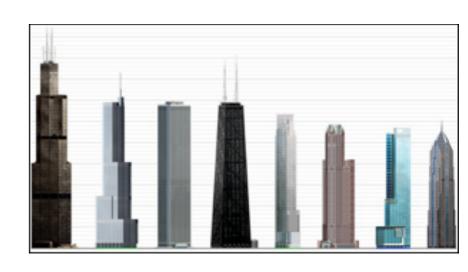
#### We identify two major objectives

- 1. building new proof methods for the working (mechanized) semanticist
  - using Abstract Interpretation theory, we can provide generic interfaces between analyses
  - we have to discover new a posteriori validation algorithms (sound and efficient)



#### 2. building big proofs

- proving in the small will not give us all the lessons we want to learn
- large case studies are important to build a new proof engineering knowledge



### These Lectures

### Lecture 1

Motivations

Examples of verified analysers

### Lecture 2

Coq crash course

### Lecture 3

Verified abstract interpreter for a simple imperative language

### Lecture 4

CompCert

A verified value analysis for CompCert

# Some example of verified static analysers

#### Lecture objectives

- Show examples of challenging verified static analysis
- Complement your knowledge on static analysis

#### Two examples

- Information flow type system
- data-race static analysis

These analyses target the Java (bytecode) language

# A Certified Non-Interference Java Bytecode Verifier

G. Barthe, D. Pichardie and T. Rezk, A Certified Lightweight Non-Interference Java Bytecode Verifier, ESOP'07

# Motivations: Bytecode Verification

#### Java bytecode verification

- checks that applets are correctly formed and correctly typed,
- using a static analysis of bytecode programs

#### But Java bytecode verifier (and more generally Java security model)

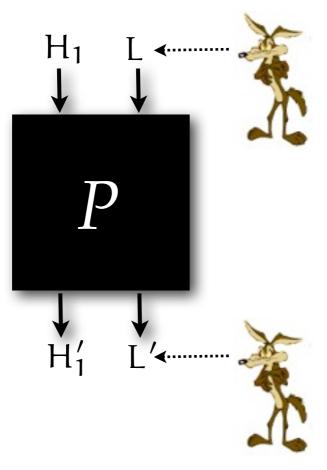
- only concentrates on who accesses sensitive information,
- not how sensitive information flows through programs

#### In this work

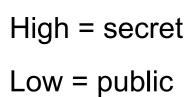
- We propose an information flow type system for a sequential JVM-like language, including classes, objects, arrays, exceptions and method calls.
- We prove in Coq that it guarantees the semantical non-interference property on method input/output.

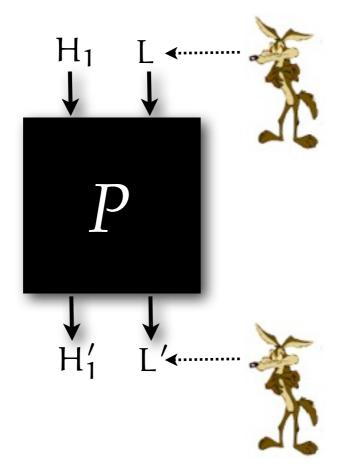
"Low-security behavior of the program is not affected by any high-security data." Goguen&Meseguer 1982

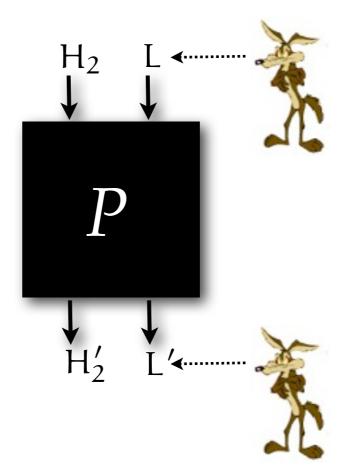
High = secret Low = public



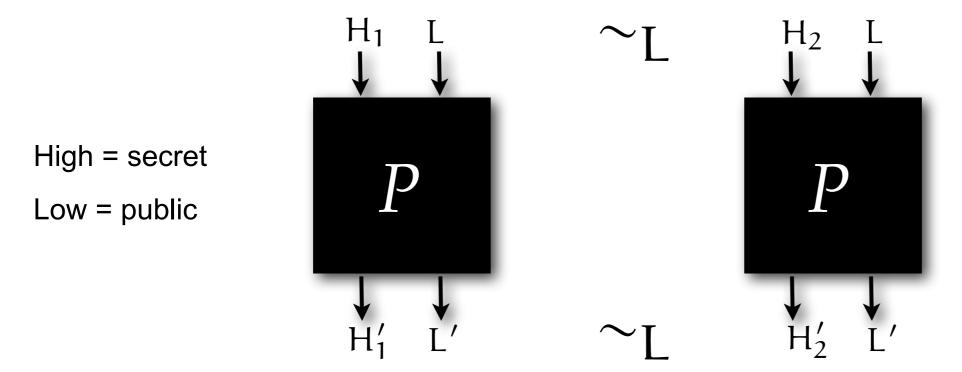
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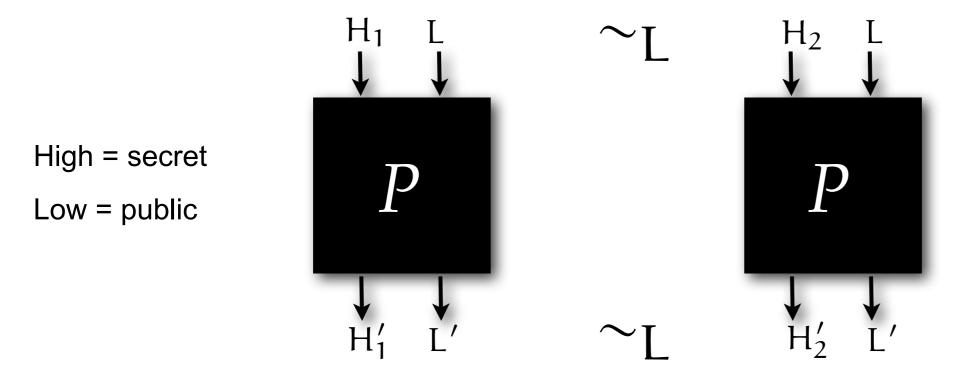


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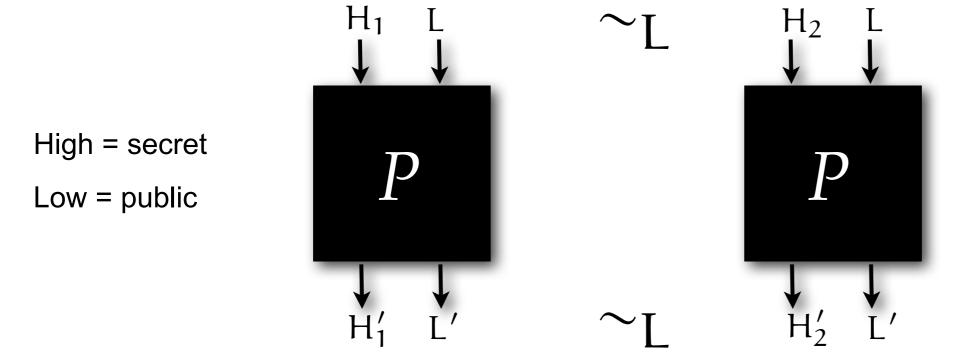
 $\forall s_1 \ s_2, \ s_1 \sim_L s_2 \Longrightarrow [\![P]\!](s_1) \sim_L [\![P]\!](s_2)$ 

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 $\forall s_1 \ s_2, \ s_1 \sim_L s_2 \Longrightarrow \llbracket P \rrbracket (s_1) \sim_L \llbracket P \rrbracket (s_2)$  if inputs are equivalent for the attacker...

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 $\forall s_1 \ s_2, \ s_1 \sim_L s_2 \Longrightarrow \llbracket P \rrbracket (s_1) \sim_L \llbracket P \rrbracket (s_2)$  if inputs are equivalent for the attacker...

# Example of information leaks

```
Explicit flow:
    public int{L} foo(int{L} 1; int{H} h) {
        return h;
    }
Implicit flow:
    public int{L} foo(int{L} 11; int{L} 12; int{H} h) {
        if (h==0) {return 11;} else {return 12;};
    }
```

We use here the Jif (http://www.cs.cornell.edu/jif) syntax:

 a security-typed extension of Java (source) with support for information flow.

# Information flow type systems

#### Previous work

- Non-interference can be enforced by a type system [Volpano97]
- The type system is sound: it rejects every interferent programs

$$WellTyped(P) \implies NonInterferent(P)$$

# Information flow type systems

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D. Volpano and G. Smith, *A Type-Based Approach to Program Security*, Theory and Practice of Software Development, 1997.

CONST 
$$\frac{x \in \mathbb{V}_{\tau}}{\vdash n : L}$$
  $VAR \frac{x \in \mathbb{V}_{\tau}}{\vdash x : \tau}$   $BINOP \frac{\vdash e_1 : \tau \quad \vdash e_2 : \tau}{\vdash e_1 \circ e_2 : \tau}$ 

$$EXP-SUBTYP \frac{\vdash e : \tau_1 \quad \tau_1 \sqsubseteq \tau_2}{\vdash e : \tau_2}$$

$$ASSIGN \frac{x \in \mathbb{V}_{\tau} \quad \vdash e : \tau}{\vdash x := e : \tau} \quad SEQ \frac{\vdash S_1 : \tau \quad \vdash S_2 : \tau}{\vdash S_1 ; S_2 : \tau}$$

$$IF \frac{\vdash e : \tau \quad \vdash S_1 : \tau \quad \vdash S_2 : \tau}{\vdash \text{ if } e \text{ then } S_1 \text{ else } S_2 : \tau} \quad WHILE \frac{\vdash e : \tau \quad \vdash S : \tau}{\vdash \text{ while } e \text{ do } S : \tau}$$

$$STM-SUBTYP \frac{\vdash S : \tau_2 \quad \tau_1 \sqsubseteq \tau_2}{\vdash S : \tau_1}$$

# Information flow type \$

# k2 < sgn.(resExceptionType) np -> handler i np = None -> texec i (Vaload t) (Some np) (L.Simple k1::L.Array k2 ke::st) None vaload\_iob\_caught : forall i te t k1 k2 ke st, (forall j, region i (Some iob) j -> k1 U k2 <= se j) -> handler i iob = Some te -> texec i (Vaload t) (Some iob) (L.Simple k1::L.Array k2 ke::st) (Some (L.Simple (k1 U k2) vaload\_iob\_uncaught : forall i t k1 k2 ke st, (forall j, region i (Some iob) j -> k1 U k2 <= se j) ->

texec i (Vaload t) (Some iob) (L.Simple k1::L.Array k2 ke::st) None

texec i (Vastore t) (Some ase) (kv::L.Simple ki::L.Array ka ke::st)

(Valdad t) (Some np) (L.Simple k1::L.Array k2 ke::st) (Some (L.Simple k2::nil))

Vastore t) None (kv::L.Simple ki::L.Array ka ke::st) (Some (elift m i ke st))

#### Previous work

handling

- Non-interference can be enforced by a type system [Volpano97]
- The type system is sound: it rejects every

```
WellTyped(P) \implies
```

Achievements: mechanized proof of a type of the control of the con

(forall j, region i (Some np) j -> ka <= se j) ->

k1 U k2 <= sgn.(resExceptionType) iob ->

vastore: forall i t kv ki ka ke st,

vaload\_np\_caught : forall i te t k1 k2 ke st,
(forall j, region i (Some np) j -> k2 <= se j) ->

handler i np = Some te ->

handler i iob = None ->

- unstructured control flow
- operand stack
- exceptions
- objects and array dynamically allocated join ki ka) <= sgn.(resExceptionType) iob ->
- classes and virtual method calls

#### (Preliminary) experiments:

we have extracted the type ckecker and use small case study

```
vastore ase uncaught : forall i t ki ka (kv ke:L.t') st,
 (forall j, region i (Some ase) j -> (L.join kv (L.join ki ka)) <= se j) ->
 (L.join kv (L.join ki ka)) <= sgn.(resExceptionType) ase ->
 handler i ase = None ->
 texec i (Vastore t) (Some ase) (kv::L.Simple ki::L.Array ka ke::st) None
 vastore_iob_caught : forall i te t ki ka (kv ke:L.t') st,
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 (forall j, region i (Some iob) j -> (L.join ki ka) <= se j) ->
 texec i (Vastore t) (Some iob) (kv::L.Simple ki::L.Array ka ke::st) None
 vload : forall i t x st,
 texec i (Vload t x) None st (Some (L.join' (se i) (sgn.(lvt) x)::st))
 vstore : forall i t x k st,
 se i \le sgn.(lvt) x \rightarrow
 L.leql' k (sqn.(lvt) x) ->
 texec i (Vstore t x) None (k::st) (Some st)
vreturn : forall i x k kv st,
```

66 typing rules...

(Some (L.Simple (L.join kv (L.join ki ka))::nil)

# Some reading

- A. Myers. Expressing and Enforcing Security with Programming Languages. PLDI'06 tutorial.
- A. Sabelfeld and A. Myers. *Language-Based Information-Flow Security*. IEEE Journal on Selected Areas in Communication, 2003
- D. Volpano and G. Smith. *A Type-Based Approach to Program Security.* Theory and Practice of Software Development, 1997
- A. Sabelfeld and D.Sands. *Declassification: Dimensions and principles*. Journal of Computer Security, 2009.
- T. H. Austin and C. Flanagan. *Efficient purely-dynamic information flow analysis*. PLAS 2009

# A Certified Data Race Analysis for Java Bytecode

F. Dabrowski and D. Pichardie, A Certified Data Race Analysis for a Java-like Language, TPHOLs 2009

### Data Races

A fundamental issue in multi-threaded programming

Definition: the situation where two different processes attempt to access to the same memory location and at least one access is a write.

#### Leads to tricky bugs

 difficult to reproduce and identify via manual code review or program testing

Wanted: sequentially consistent (SC) executions

- each thread accesses instantly a common shared memory
- the execution can be modelled with an interleaving of thread actions

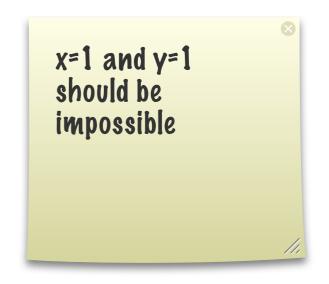
The Java specification gives very surprising semantics to programs with races

Only data-race-free programs are guaranteed to have only SC executions

```
C.f = C.g = 0;

1: x = C.g; | 1: y = C.f;

2: C.f = 1; | 2: C.g = 1;
```



```
C.f = C.g = 0;

1: x = C.g; | 1: y = C.f;

2: C.f = 1; | 2: C.g = 1;
```

```
x=1 and y=1
should be
impossible
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```
1: x = C.g; 1: y = C.f;

2: C.f = 1; 2: C.g = 1;

1: y = C.f; 1: x = C.g;

2: C.g = 1; 2: C.f = 1;
```

```
C.f = C.g = 0;

1: x = C.g; | 1: y = C.f;

2: C.f = 1; | 2: C.g = 1;
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```
1: x = C.g; 1: y = C.f; 1: y = C.f;

2: C.f = 1; 2: C.g = 1; 1: x = C.g; ...

1: y = C.f; 1: x = C.g; 2: C.g = 1;

2: C.g = 1; 2: C.f = 1;
```

```
C.f = C.q = 0;
1: x = C.g; | 1: y = C.f;
2: C.f = 1; | 2: C.g = 1;
```

```
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should be
impossible
```

Interleaving semantics gives only sequentially consistent execution,

```
1: x = C.g; 1: y = C.f; 1: y = C.f; 2: C.g = 1;
2: C.f = 1; 2: C.g = 1; 1: x = C.g; ... 2: C.f = 1;
1: y = C.f; 1: x = C.g; 2: C.g = 1; 1: x = C.g;
2: C.g = 1; 2: C.f = 1; 2: C.f = 1; 1: y = C.f;
```

but such program may also lead to sequentially inconsistent execution

#### Origins:

- Multicore cache mechanisms
- Agressive compiler optimizations

x=1 and y=1is a legal outcome according to Java specification!

## Java Data-Race-Free Guarantee

The Java specification guarantees that if all SC execution of a program are race-free then the program will only exhibits these executions

A date-race verifier must infer automatically that a program is race free

the verifier computes a set of potential races

$$verifier_{DR}: program \rightarrow \mathcal{P}(races)$$

if this set is empty, the program must be free of races

$$verifier_{DR}(P) = \emptyset \implies Races(P) = \emptyset$$

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 computable 
$$\operatorname{not-computable}$$

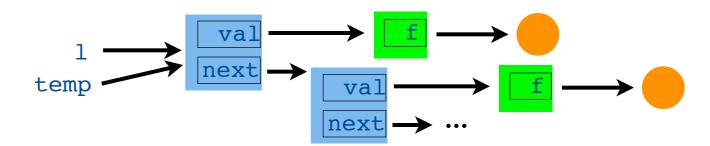
```
class List{ T val; List next; }
class Main() {
 void main(){
   List 1 = null;
   while (*) {
     List temp = new List();
1: temp.val = new T();
2: temp.val.f = new A();
3:
   temp.next = 1;
     1 = temp }
   while (*) {
     T t = new T();
   t.data = 1;
4:
     t.start();
5:
    t.f = ...;}
   return;
class T extends java.lang.Thread {
 A f;
 List data;
 void run(){
   while(*){
6: List m = this.data;
7: while (*) { m = m.next; }
     synchronized(m) { m.val.f = ...;}}
8:
   return; }}
```

#### A Challenging Example

```
class List{ T val; List next; }
class Main() {
  void main(){
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    temp.val = new T();
1:
    temp.val.f = new A();
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3:
     l = temp 
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      t.start();
     t.f = ...;}
5:
    return;
class T extends java.lang.Thread {
 A f;
 List data;
 void run(){
    while(*){
     List m = this.data;
6:
  while (*) { m = m.next; }
7:
      synchronized(m) { m.val.f = ...;}}
    return; }}
```

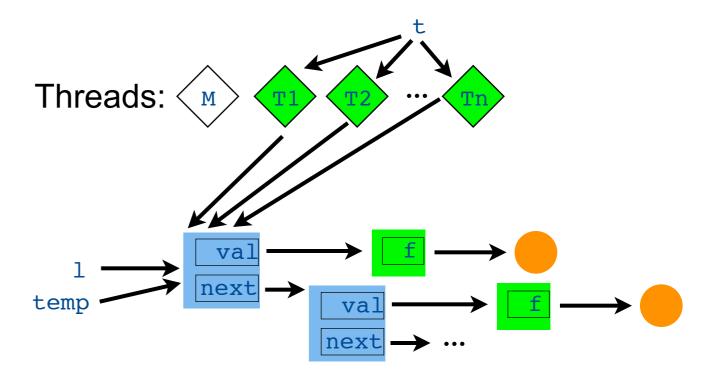
I. We create a link list 1

Threads: (M)



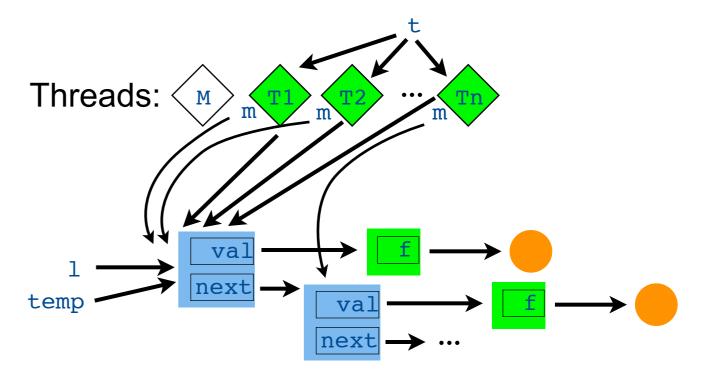
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     t.data = 1;
4:
     t.start();
     t.f = ...;}
5:
    return;
class T extends java.lang.Thread {
 A f;
 List data;
 void run(){
    while(*){
     List m = this.data;
6:
     while (*) { m = m.next; }
7:
      synchronized(m) { m.val.f = ...;}}
    return; }}
```

- I. We create a link list 1
- 2. We create several threads that all share the list 1



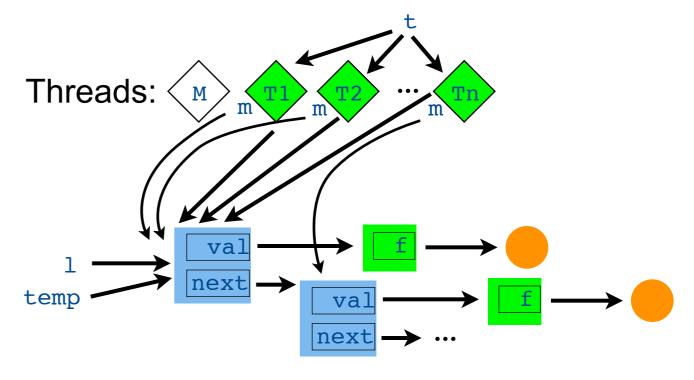
```
class List{ T val; List next; }
class Main() {
  void main(){
    List 1 = null;
    while (*) {
      List temp = new List();
   temp.val = new T();
1:
   temp.val.f = new A();
2:
    temp.next = 1;
3:
      1 = temp }
    while (*) {
      T t = new T();
      t.data = 1;
4:
      t.start();
      t.f = ...;}
5:
    return;
class T extends java.lang.Thread {
 A f;
 List data;
 void run(){
    while(*){
    List m = this.data;
6:
   while (*) { m = m.next; }
7:
      synchronized(m){ m.val.f = ...;}}
    return; } }
```

- I. We create a link list 1
- 2. We create several threads that all share the list 1
- 3. Each thread chooses a cell, takes a lock on it and updates it.



```
class List{ T val; List next; }
class Main() {
  void main(){
    List 1 = null;
    while (*) {
      List temp = new List();
    temp.val = new T();
1:
   temp.val.f = new A();
2:
    temp.next = 1;
3:
      1 = temp }
    while (*) {
      T t = new T();
      t.data = 1;
4:
      t.start();
      t.f = ...;
5:
    return;
class T extends java.lang.Thread {
 A f;
 List data;
 void run(){
    while(*){
     List m = this.data;
6:
     while (*) { m = m.next; }
7:
      synchronized(m) { m.val.f = ...;}}
    return; }}
```

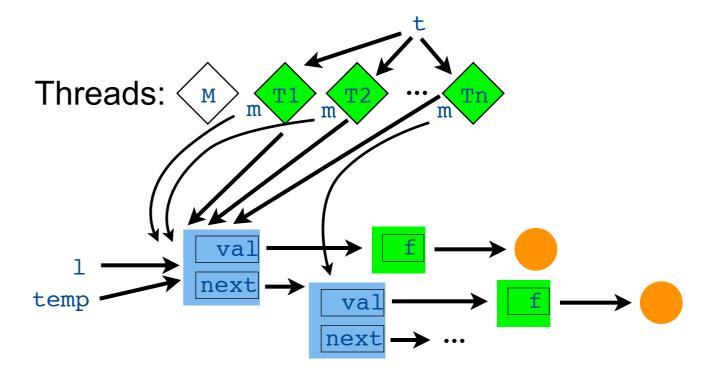
- I. We create a link list 1
- 2. We create several threads that all share the list 1
- 3. Each thread chooses a cell, takes a lock on it and updates it.



#### A Challenging Example

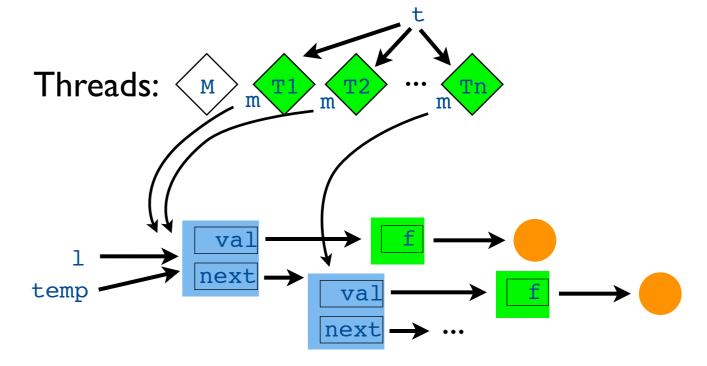
```
class List{ T val; List next; }
class Main() {
  void main(){
    List 1 = null;
    while (*) {
      List temp = new List();
    temp.val = new T();
1:
   temp.val.f = new A();
2:
    temp.next = 1;
3:
      1 = temp }
    while (*) {
      T t = new T();
      t.data = 1;
4:
      t.start();
      t.f = ...;
5:
    return;
class T extends java.lang.Thread {
 A f;
 List data;
 void run(){
    while(*){
     List m = this.data;
6:
     while (*) { m = m.next; }
7:
      synchronized(m) { m.val.f = ...; } }
    return; }}
```

Even on a simple program like this one, only a combination of static analyses will be able to prove data race freeness



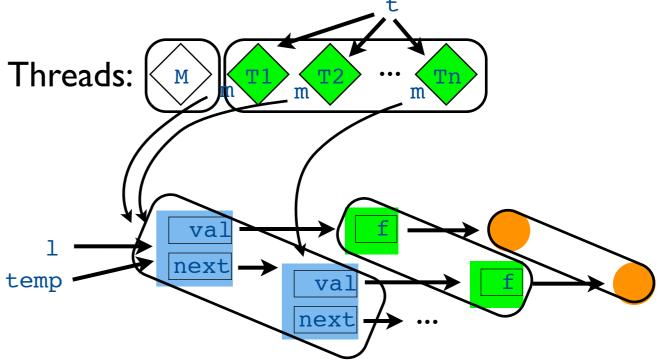
## Points-to abstraction

```
class List{ T val; List next; }
class Main() {
 void main(){
    List 1 = null;
    while (*) {
   h1 List temp = new List();
   h2 temp.val = new T();
1:
   h3 temp.val.f = new A();
2:
      temp.next = 1;
3:
      1 = temp }
   while (*) {
   h4 T t = new T();
      t.data = 1;
4:
      t.start();
     t.f = ...;}
5:
    return;
class T extends java.lang.Thread {
 A f;
 List data;
 void run(){
    while(*){
     List m = this.data;
6:
7: while (*) { m = m.next; }
      synchronized(m) { m.val.f = ...;}}
    return; }}
```



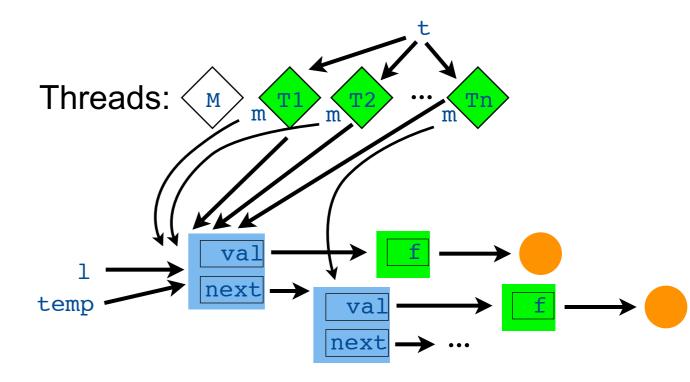
## Points-to abstraction

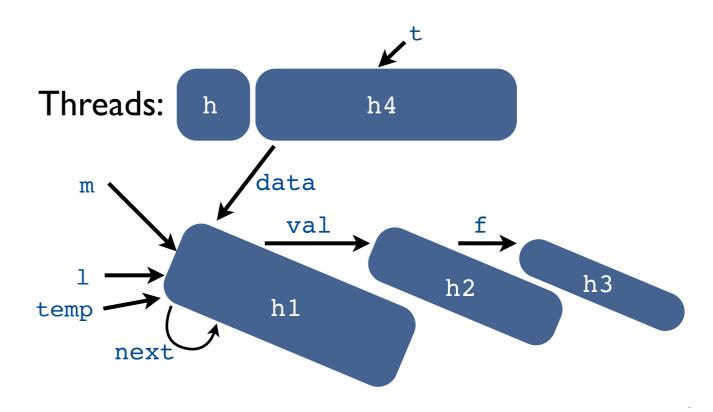
```
class List{ T val; List next; }
class Main() {
 void main(){
    List 1 = null;
    while (*) {
   h1 List temp = new List();
   h2 temp.val = new T();
   h3 temp.val.f = new A();
2:
     temp.next = 1;
3:
      1 = temp }
   while (*) {
   h4 T t = new T();
      t.data = 1;
4:
      t.start();
     t.f = ...;}
5:
    return;
class T extends java.lang.Thread {
 A f;
 List data;
 void run(){
    while(*){
     List m = this.data;
6:
7: while (*) { m = m.next; }
      synchronized(m) { m.val.f = ...;}}
    return; }}
```



## Points-to abstraction

```
class List{ T val; List next; }
class Main() {
  void main(){
    List 1 = null;
    while (*) {
   h1 List temp = new List();
   h2 temp.val = new T();
1:
   h3 temp.val.f = new A();
2:
      temp.next = 1;
3:
      1 = temp }
    while (*) {
    h4 T t = new T();
4:
      t.data = 1;
      t.start();
      t.f = ...;}
5:
    return;
class T extends java.lang.Thread {
  A f;
  List data;
  void run(){
    while(*){
      List m = this.data;
6:
      while (*) { m = m.next; }
7:
      synchronized(m) { m.val.f = ...;}}
    return; }}
```





#### Effective Static Data Race Detection for Java

Naik's PhD 2008

Original pairs

Reachable pairs

Aliasing pairs

Escaping pairs

Unlocked pairs

```
class List{ T val; List next; }
class Main() {
 void main(){
   List 1 = null;
   while (*) {
     List temp = new List();
1: temp.val = new T();
2: temp.val.f = new A();
3: temp.next = 1;
     1 = temp 
   while (*) {
     T t = new T();
4: t.data = 1;
     t.start();
     t.f = ...;}
   return;
class T extends java.lang.Thread {
 A f;
 List data;
 void run(){
   while(*){
     List m = this.data;
6:
7: while (*) { m = m.next; }
     synchronized(m) { m.val.f = ...;}}
   return; } }
```

### Effective Static Data Race Detection for Java

Naik's PhD 2008

Original pairs

```
(1,val,1) (1,val,2) (2,f,2) (3,next,3)
(4,data,4) (5,f,5) (2,f,5) (5,f, 8) (4,data,6)
(3,next, 7) (1,val, 8) (2,f, 8) (8,f, 8)
```

Reachable pairs

The first set of potential races is based on field safety

Aliasing pairs

Escaping pairs

Unlocked pairs

```
class List{ T val; List next; }
class Main() {
 void main(){
   List 1 = null;
   while (*) {
     List temp = new List();
     temp.val = new T();
2: temp.val.f = new A();
3: temp.next = 1;
     1 = temp }
   while (*) {
     T t = new T();
4: t.data = 1;
     t.start();
     t.f = ...;
   return;
class T extends java.lang.Thread {
 A f;
 List data;
 void run(){
   while(*){
     List m = this.data;
6:
7: while (*) { m = m.next; }
      synchronized(m) { m.val.f = ...;}}
    return; } }
```

### Effective Static Data Race Detection for Java

Naik's PhD 2008

Original pairs

```
(1,val,1) (1,val,2) (2,f,2) (3,next,3)
(4,data,4) (5,f,5) (2,f,5) (5,f,8) (4,data,6)
(3,next, 7) (1,val, 8) (2,f,8) (8,f,8)
```

Reachable pairs

Aliasing pairs

The pairs that may be reachable from the program entry and that may concern two distinct threads

Escaping pairs

Unlocked pairs

```
class List{ T val; List next; }
class Main() {
  void main(){
   List 1 = null;
   while (*) {
     List temp = new List();
     temp.val = new T();
2: temp.val.f = new A();
3: temp.next = 1;
      1 = temp }
   while (*) {
      T t = new T();
     t.data = 1;
     t.start();
      t.f = ...;
   return;
class T extends java.lang.Thread {
 A f;
 List data;
 void run(){
   while(*){
     List m = this.data;
6:
7: while (*) { m = m.next; }
      synchronized(m) { m.val.f = ...;}}
    return; } }
```

Naik's PhD 2008

Original pairs

```
(1,val,1) (1,val,2) (2,f,2) (3,next,3)
(4,data,4) (5,f,5) (2,f,5) (5,f,8) (4,data,6)
(3,next,7) (1,val,8) (2,f,8) (8,f,8)
```

Reachable pairs

```
(1, 1) (1, 2) (2, 2) (3, 1, 3)
(4, 1, 4) (5, 5) (2, 5) (5, f, 8) (4, data, 6)
(3, next, 7) (1, val, 8) (2, f, 8) (8, f, 8)
```

Aliasing pairs

```
(1,val,1) (1,val,2) (2,f,2) (3,next,3)
(4,data,4) (5,f,5) (2,f,5) (5,f,8) (4,data,6)
(3,next, 7) (1,val, 8) (2,f, 8) (8,f, 8)
```

Escaping pairs

Using a points-to abstraction we compute the pairs that may touch the same heap location

Unlocked pairs

```
class List{ T val; List next; }
class Main() {
  void main(){
   List 1 = null;
   while (*) {
     List temp = new List();
     temp.val = new T();
2: temp.val.f = new A();
3: temp.next = 1;
      1 = temp }
   while (*) {
      T t = new T();
4: t.data = 1;
     t.start();
5:
      t.f = ...;
   return;
class T extends java.lang.Thread {
 A f;
 List data;
  void run(){
   while(*){
     List m = this.data;
6:
7:
     while (*) { m = m.next; }
      synchronized(m) { m.val.f = ...;}}
8:
    return; } }
```

Naik's PhD 2008

Original pairs

```
(1,val,1) (1,val,2) (2,f,2) (3,next,3)
(4,data,4) (5,f,5) (2,f,5) (5,f,8) (4,data,6)
(3,next, 7) (1,val, 8) (2,f,8) (8,f,8)
```

Reachable pairs

Aliasing pairs

```
(1,val,1) (1,val,2) (2,f,2) (3,next,3)
(4,data,4) (5,f,5) (2,5) (5,8) (4,data,6)
(3,next, 7) (1,val, 8) (2,f, 8) (8,f, 8)
```

Escaping pairs

```
(1,1) (1,1) (2,1) (3,1) (4,1) (4,1) (4,1) (5,1) (2,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1
```

Unlocked pairs

The pairs of program points where the target location may be shared at that points

```
class List{ T val; List next; }
class Main() {
  void main(){
   List 1 = null;
   while (*) {
      List temp = new List();
      temp.val = new T();
2: temp.val.f = new A();
3: temp.next = 1;
      1 = temp }
   while (*) {
      T t = new T();
      t.data = 1;
      t.start();
5:
      t.f = ...;
   return;
class T extends java.lang.Thread {
 A f;
 List data;
 void run(){
   while(*){
     List m = this.data;
6:
     while (*) { m = m.next; }
7:
      synchronized(m) { m.val.f = ...; } }
    return; }}
```

Naik's PhD 2008

Original pairs

```
(1,val,1) (1,val,2) (2,f,2) (3,next,3)
(4,data,4) (5,f,5) (2,f,5) (5,f,8) (4,data,6)
(3,next,7) (1,val,8) (2,f,8) (8,f,8)
```

Reachable pairs

Aliasing pairs

```
(1,val,1) (1,val,2) (2,f,2) (3,next,3)
(4,data,4) (5,f,5) (2,5) (5,6) (4,data,6)
(3,next, 7) (1,val, 8) (2,f, 8) (8,f, 8)
```

Escaping pairs

```
(1,1) (1,1) (2,1) (3,1) (3,1) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0) (4,0
```

Unlocked pairs

```
(1,val,1) (1,val,2) (2,f,2) (3,next,3)
(4,data,4) (5,f,5) (2,f,5) (5,f,8) (4,data,6)
(3,next, 7) (1,val, 8) (2,f,8) (858)
```

```
class List{ T val; List next; }
class Main() {
 void main(){
   List 1 = null;
   while (*) {
     List temp = new List();
     temp.val = new T();
2: temp.val.f = new A();
3: temp.next = 1;
     1 = temp }
   while (*) {
     T t = new T();
4: t.data = 1;
     t.start();
     t.f = ...;
   return;
class T extends java.lang.Thread {
 A f;
 List data;
 void run(){
   while(*){
     List m = this.data;
6:
7:
     while (*) { m = m.next; }
8:
      synchronized(m) { m.val.f = ...; } }
```

Pairs that may not be guarded by the same lock

#### Naik's PhD 2008

Original pairs

```
(1,val,1) (1,val,2) (2,f,2) (3,next,3)
(4,data,4) (5,f,5) (2,f,5) (5,f,8) (4,data,6)
(3,next, 7) (1,val, 8) (2,f,8) (8,f,8)
```

Reachable pairs

Aliasing pairs

```
(1,val,1) (1,val,2) (2,f,2) (3,next,3)
(4,data,4) (5,f,5) (2,5) (5,6) (4,data,6)
(3,next, 7) (1,val, 8) (2,f, 8) (8,f, 8)
```

Escaping pairs

```
(1,1) (1,1) (2,1) (3,1) (3,1) (4,1) (4,1) (4,1) (5,1) (2,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1) (5,1
```

Unlocked pairs

```
(1,val,1) (1,val,2) (2,f,2) (3,next,3)
(4,data,4) (5,f,5) (2,f,5) (5,f,8) (4,data,6)
(3,next, 7) (1,val, 8) (2,f,8) (858)
```

```
class List{ T val; List next; }
class Main() {
  void main(){
   List l = null;
   while (*) {
```

If each original pair has been removed at least one time, the program is data-race free

```
5: t.f = ...;}
    return;
    }
}

class T extends java.lang.Thread {
    A f;
    List data;
    void run() {
        while(*) {
        List m = this.data;
        vhile (*) { m = m.next; }
        synchronized(m) { m.val.f = ...;}}
    return;}
```

#### Naik's PhD 2008

Original pairs

```
(1,1,1) (1,1,2) (2,1,2) (3,1,2,1,3) (4,0,4,4) (5,1,5) (2,1,5) (5,1,8) (4,0,4,6) (3,1,2,1,7) (1,1,2,8) (2,1,8) (8,1,8)
```

Reachable pairs

```
(1,val,1) (1,val,2) (2,f,2) (3,next,3)
(4,data,4) (5,f,5) (2,f,5) (5,f, 8) (4,data,6)
(3,next, 7) (1,val, 8) (2,f, 8) (8,f, 8)
```

Aliasing pairs

```
(1,val,1) (1,val,2) (2,f,2) (3,next,3)
(4,data,4) (5,f,5) (2,f,5) (5,f, 8) (4,data,6)
(3,next, 7) (1,val, 8) (2,f, 8) (8,f, 8)
```

Escaping pairs

```
(1,val,1) (1,val,2) (2,f,2) (3,next,3)
(4,data,4) (5,f,5) (2,f,5) (5,f,8) (4,data,6)
(3,next, 7) (1,val, 8) (2,f,8) (8,f,8)
```

Unlocked pairs

```
(1,val,1) (1,val,2) (2,f,2) (3,next,3)
(4,data,4) (5,f,5) (2,f,5) (5,f,8) (4,data,6)
(3,next,7) (1,val,8) (2,f,8) (8,f,8)
```

```
class List{ T val; List next; }
class Main() {
  void main(){
   List l = null;
   while (*) {
```

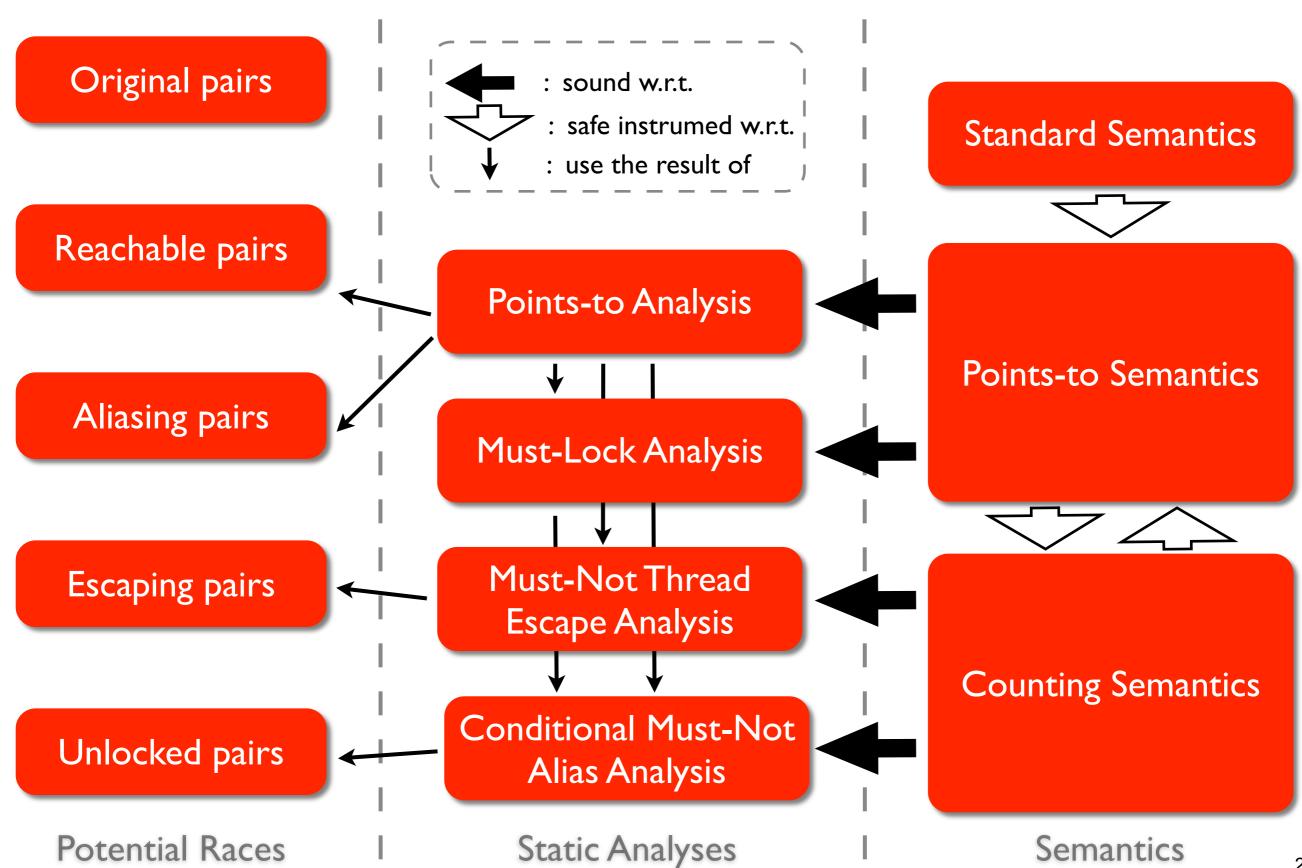
If each original pair has been removed at least one time, the program is data-race free

```
5: t.f = ...;}
return;
```

This program is data-race free!

```
7: while (*) { m = m.next; }
8: synchronized(m) { m.val.f = ...; } }
return; } }
```

## **Proof Architecture**



# Some reading

- J. Choi, A. Loginov, and V. Sarkar. Static datarace analysis for multithreaded object-oriented programs. Tech. report, IBM Research Division, 2001.
- M. Naik, A. Aiken, and J. Whaley. Effective static race detection for java. PLDI '06
- M. Naik and A. Aiken. Conditional must not aliasing for static race detection. POPL'07
- M. Naik. Effective static race detection for java. PhD thesis, Stanford university, 2008.
- C. Flanagan and S. N. Freund. FastTrack: efficient and precise dynamic race detection. Communication of the ACM 2010
- H. Boehm and S. V. Adve. You Don't Know Jack about Shared Variables or Memory Models. Communication of the ACM 2012

## Conclusions

#### Lessons learned

- Mechanized proof can handle more than toy static analyses
  - printing and proofreading these kind of proof would have been very difficult
- Realistic analyses are generally a composition of several sub-analyses
  - mechanized proof make explicit the interactions between them
- Proving correct of a realistic analysis is time consuming
  - about 1.5 man year effort and 15K loc for each proof...

#### Methodology

- Each verified analysis increases our knowledge about how to best formalize a static analysis in a proof assistant
  - avoid mechanically proving theorems that are not directly useful for soundness (termination, completeness)
  - design modular proofs with robust interfaces (intermediate semantics, module functors)

## These Lectures

## Lecture 1

**Motivations** 

Examples of verified analysers

### Lecture 2

Coq crash course

### Lecture 3

Verified abstract interpreter for a simple imperative language

## Lecture 4

CompCert

A verified value analysis for CompCert

[Extra slides if we have enough time]

An important tool in our toolbox

We program the full static analyzer inside Coq

```
Definition analyzer (p:program) :=
    ...
let x := complex_computation p in
    ...
```

... or ...

An important tool in our toolbox

We program the full static analyzer inside Coq

```
Definition analyzer (p:program) :=
    ...
let x := complex_computation p in
    ...
```

... or we program some parts in Coq, other parts in OCaml and use a verified validator

More formally, instead of proving a function  $f\in A\to B$  satisfies a spec  $R\subseteq A\times B$   $\forall a\forall b, (a,f(a))\in R$ 

We define a validator  $f?\in A\times B\to \{{\rm true},{\rm false}\}$  and prove  $\forall a\forall b,f?(a,b)={\rm true}\implies (a,b)\in R$ 

Then every time we need a proof that f(a) is correct for a given input a, we check if  $f?(a,f(a))=\mathrm{true}$ 

Example: CompCert register allocator

```
Definition regalloc
  (f: function) (live: node → regset) : option (reg → loc) :=
  let g := interf_graph f live in
  let coloring := graph_coloring f g in
  if check_coloring g coloring
  then Some (alloc_of_coloring coloring g)
  else None.
```

Example: CompCert register allocator

The function takes a RTL function, the result of a live analysis and returns a location (machine register or in memory)

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The function may fail!

Example: CompCert register allocator

else None.

The function takes a RTL function, the result of a live analysis and returns a location (machine register or in memory)

```
The function may fail!
Definition regalloc
  (f: function) (live: node 	o regset) : option (reg 	o loc) :=
                                            Computation of an interference graph
  let g := interf_graph f live in
                                            between RTL registers: an edge between
                                            each registers with overlapping live ranges.
  let coloring := graph_coloring f g in
  if check_coloring g coloring
  then Some (alloc_of_coloring coloring g)
```

Example: CompCert register allocator

else None.

The function takes a RTL function, the result of a live analysis and returns a location (machine register or in memory)

then Some (alloc\_of\_coloring coloring g)

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Example: CompCert register allocator

The function takes a RTL function, the result of a live analysis and returns a location (machine register or in memory)

```
The function may fail!
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                                               Computation of an interference graph
  let g := interf_graph f live in
                                               between RTL registers: an edge between
                                                each registers with overlapping live ranges.
  let coloring := graph_coloring f g in 
                                                       Graph coloring by an
                                                       external program
  if check_coloring g coloring_
                                            The validator simply verify that each edge
                                            connects nodes with different colors
  then Some (alloc_of_coloring coloring g)
  else None.
```

Example: CompCert register allocator

The function takes a RTL function, the result of a live analysis and returns a location (machine register or in memory)

```
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                                                         Graph coloring by an
                                                         external program
  if check_coloring g coloring_
                                             The validator simply verify that each edge
                                              connects nodes with different colors
  then Some (alloc_of_coloring coloring g)
  else None.
                    If the validator fails, the whole function fails
```

More advanced pattern

More formally, instead of proving a function  $f\in A\to B$  satisfies a spec  $R\subseteq A\times B$   $\forall a\forall b, (a,f(a))\in R$ 

We define a validator  $f? \in A \times B \times C \to \{\text{true}, \text{false}\}$  and prove  $\forall a \forall b \forall c, f? (a,b,c) = \text{true} \implies (a,b) \in R$ 

Then every time we need a proof that f(a) is correct for a given input a, we check if

$$f?(a, f(a), solver(a, f(a))) = true$$

More advanced pattern

More formally, instead of proving a function  $f\in A\to B$  satisfies a spec  $R\subseteq A\times B$   $\forall a\forall b, (a,f(a))\in R$ 

We define a validator  $f? \in A imes B imes C o \{ {
m true}, {
m false} \}$  and prove

$$\forall a \forall b \forall c, f? (a,b,c) = \text{true} \implies (a,b) \in R$$
 computation hint

Then every time we need a proof that  $f(\boldsymbol{a})$  is correct for a given input  $\boldsymbol{a}$  , we check if

$$f?(a, f(a), solver(a, f(a))) = true$$

More advanced pattern

More formally, instead of proving a function  $f\in A\to B$  satisfies a spec  $R\subseteq A\times B$   $\forall a\forall b, (a,f(a))\in R$ 

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Then every time we need a proof that  $f(\boldsymbol{a})$  is correct for a given input  $\boldsymbol{a}$  , we check if

$$f?(a,f(a),solver(a,f(a))) = {\rm true}$$
 
$${\rm untrusted}$$

More advanced example: Farkas proof

Some static analyses or optimisers need to prove unsat. of linear formula

UNSAT
$$(1 \le x' + 2y \le 4 \land x = x' + 1 \land x + 2y < 2)$$
?

Just validating a yes/no result would be too hard

More advanced example: Farkas proof

Some static analyses or optimisers need to prove unsat. of linear formula

UNSAT 
$$\begin{pmatrix} -1 & +x' & +2y & \geq & 0 \\ 0 & & \geq & 0 \\ -1 & -x' & +x & = & 0 \\ 2 & -x & -2y & > & 0 \end{pmatrix} ?$$

Just validating a yes/no result would be too hard

More advanced example: Farkas proof

Some static analyses or optimisers need to prove unsat. of linear formula

UNSAT 
$$\begin{pmatrix} -1 & +x' & +2y & \geq & 0 \\ 0 & & \geq & 0 \\ -1 & -x' & +x & = & 0 \\ 2 & -x & -2y & > & 0 \end{pmatrix} ?$$

Just validating a yes/no result would be too hard

(simplex)

More advanced example: Farkas proof

Some static analyses or optimisers need to prove unsat. of linear formula

UNSAT 
$$\begin{pmatrix} -1 & +x' & +2y & \geq & 0 \\ 0 & & \geq & 0 \\ -1 & -x' & +x & = & 0 \\ 2 & -x & -2y & > & 0 \end{pmatrix} ?$$

Just validating a yes/no result would be too hard

UNSAT 
$$\begin{pmatrix} 1 \times ( & -1 & +x' & +2y & \geq & 0) \\ 0 \times ( & 4 & -x' & -2y & \geq & 0) \\ -1 \times ( & 1 & +x' & -x & = & 0) \\ 1 \times ( & 2 & -x & -2y & > & 0) \end{pmatrix}$$
Hint computed with an external tool (simplex) 
$$\begin{pmatrix} -1 & +x' & +2y & \geq & 0 \\ 4 & -x' & -2y & \geq & 0 \\ 1 & +x' & -x & = & 0 \\ 2 & -x & -2y & > & 0 \end{pmatrix} ?$$

More advanced example: Farkas proof

Some static analyses or optimisers need to prove unsat. of linear formula

UNSAT 
$$\begin{pmatrix} -1 & +x' & +2y & \geq & 0 \\ 0 & & & \geq & 0 \\ -1 & -x' & +x & & = & 0 \\ 2 & & -x & -2y & > & 0 \end{pmatrix} ?$$

Just validating a yes/no result would be too hard

UNSAT 
$$\begin{pmatrix} 1 \times (& -1 & +x' & & +2y & \geq & 0) \\ 0 \times (& 4 & -x' & & -2y & \geq & 0) \\ -1 \times (& 1 & +x' & -x & & = & 0) \\ 1 \times (& 2 & & -x & -2y & > & 0) \end{pmatrix}$$

$$\Leftrightarrow$$
Hint computed with an external tool (simplex)

UNSAT (0 > 0)?

#### Discussion

#### A validator may fail if

- The external tool contains bugs
  - ⇒ we must be able to abort the current computation
- The validator is not smart enough (incompleteness)

#### Some validator are complete

- The graph coloring validator is complete wrt any graph coloring algorithm
- The Farkas checker validator is complete if coefficients are rational (incomplete on integers)
- Other example: SSA generation
  In Gilles Barthe, Delphine Demange, and David Pichardie. A formally
  verified SSA-based middle-end, ESOP 2012, we provide a complete
  validator for SSA generation based on dominance frontier
  computation