### Abstract Interpretation (an introduction)

SCSSE Summer School 2017

Part 1

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these slides are available at http://www.irisa.fr/celtique/pichardie/teaching/ecnu-2017-part1.pdf



## Static program analysis

### The goals of static program analysis

- to prove properties about the run-time behaviour of a program
- ▶ in a fully automatic way
- without actually executing this program

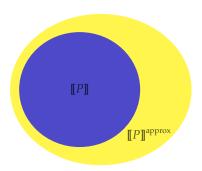
### Applications

- code optimisation
- error detection (array out of bound access, null pointers)
- proof support (invariant extraction)

### **Abstract Interpretation**

A theory which unifies a large variety of static analysis

- formalises the approximated analyse of programs
- allows to compare relative precision of analyses
- facilitates the conception of sophisticated analyses
- discovered by Patrick Cousot and Radhia Cousot in 1977



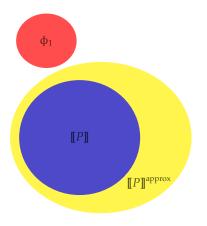
 $\llbracket P \rrbracket$ : concrete semantics (e.g. set of reachable states)

P | approx : analyser result (here over-approximation)

(not computable)

(computable)





▶ *P* is safe w.r.t.  $\phi_1$  and the analyser proves it

$$\llbracket P \rrbracket \cap \varphi_1 = \emptyset$$
  $\llbracket P \rrbracket^{approx} \cap \varphi_1 = \emptyset$ 

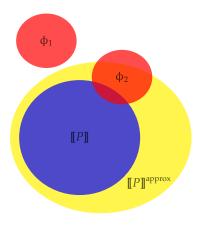
[P]: concrete semantics (e.g. set of reachable states)

 $\phi_1$ : erroneous/dangerous set of states

 $[P]^{approx}$ : analyser result (here over-approximation)

(not computable)
(computable)
(computable)

putubic)



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$$\llbracket P \rrbracket \cap \varphi_1 = \emptyset$$
  $\llbracket P \rrbracket^{\operatorname{approx}} \cap \varphi_1 = \emptyset$ 

P is unsafe w.r.t. φ<sub>2</sub> and the analyser warns about it

$$[\![P]\!] \cap \varphi_2 \neq \emptyset$$
  $[\![P]\!]^{approx} \cap \varphi_2 \neq \emptyset$ 

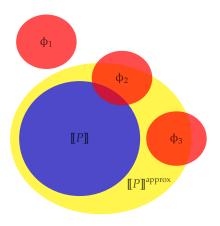
[P]: concrete semantics (e.g. set of reachable states)

 $\phi_1, \phi_2$ : erroneous/dangerous set of states

analyser result (here over-approximation)

(not computable) (computable)

(computable)



▶ *P* is safe w.r.t.  $\phi_1$  and the analyser proves it

$$\llbracket P \rrbracket \cap \varphi_1 = \emptyset$$
  $\llbracket P \rrbracket^{\operatorname{approx}} \cap \varphi_1 = \emptyset$ 

▶ *P* is unsafe w.r.t.  $\phi_2$  and the analyser warns about it

$$[\![P]\!] \cap \varphi_2 \neq \emptyset$$
  $[\![P]\!]^{approx} \cap \varphi_2 \neq \emptyset$ 

**but** *P* is safe w.r.t.  $\phi_3$  and the analyser can't prove it (this is called a *false alarm*)

$$\llbracket P \rrbracket \cap \varphi_3 = \emptyset \qquad \llbracket P \rrbracket^{approx} \cap \varphi_3 \neq \emptyset$$

 $\llbracket P \rrbracket$ : concrete semantics (e.g. set of reachable states)

erroneous/dangerous set of states  $\phi_1, \phi_2, \phi_3$ :  $[P]^{approx}$ :

analyser result (here over-approximation)

(not computable) (computable) (computable)



```
1: x = 100;

2: res = 1;

3: while (x>0) {

4: res = res * x;

5: x = x - 1;

6: };

7: y = 1 / res;
```

```
ightharpoonup at point 2, x = 100
1: x = 100;
2: res = 1;
                          res = 1
3: while (x>0) {
4: res = res * x;
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```
ightharpoonup at point 3 (before entering the loop), x = 100 and
```

```
1: x = 100;

2: res = 1;

3: while (x>0) {

4: res = res * x;

5: x = x - 1;

6: };

7: y = 1 / res;

• at point 2, x = 100

• at point 3 (before entering the loop), x = 100 and res = 100 × 99 × ··· × x
```

```
1: x = 100;

2: res = 1;

3: while (x>0) {

4: res = res * x;

5: x = x - 1;

6: };

7: y = 1 / res;

• at point 2, x = 100

• at point 3 (before entering the loop), x = 100 and res = 1

• at point 5, x > 0 and res = 100 \times 99 \times \cdots \times x

• at point 6, x \ge 0 and res = 100 \times 99 \times \cdots \times (x + 1)
```

```
1: x = 100;

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3: while (x>0) {

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- ▶ at point 2, x = 100
- ▶ at point 3 (before entering the loop), x = 100 and res = 1
- ▶ at point 5, x > 0 and  $res = 100 \times 99 \times \cdots \times x$
- ▶ at point 6,  $x \ge 0$  and  $res = 100 \times 99 \times \cdots \times (x+1)$
- at point 7, x = 0 and res = 100! Hence, we can prove there is no division by zero at point 7.

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```
at point 2, x = 100 (yes/no?), x > 0 (yes/no?), x < 10 (yes/no?)</p>
```

```
at point 3 (before entering the loop), x = 100 × res
(yes/no?)
```

```
1: x = 100;

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at point 2, x = 100 (yes/no?), x > 0 (yes/no?), x < 10 (yes/no?)</p>
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- at point 3 (before entering the loop), x = 100 × res (yes/no?)
- at point 7, x > 0 (yes/no), res > 0 (yes/no?), res > x (yes/no?)
   But only the property res > 0 can prove the absence of division by zero.

#### A **correct** static analysis could says:

```
1: x = 100;

2: res = 1;

3: while (x>0) {

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- at point 2, x = 100 (yes/no?), x > 0 (yes/no?), x < 10 (yes/no?)</p>
- at point 3 (before entering the loop), x = 100 × res (yes/no?)
- at point 7, x > 0 (yes/no), res > 0 (yes/no?), res > x
   (yes/no?)

But only the property res > 0 can prove the absence of division by zero.

res > x will raise a false alarm.

Abstract interpretation executes programs on state properties instead of states.

- A state property is a subset in  $\mathcal{P}(\mathbb{Z}^2)$  of  $(\mathbf{x}, \mathbf{y})$  values.
- When a point is reached for a second time we make an union with the previous property.
- We "execute" the program until stability
  - It may take an infinite number of steps...
  - But the limit always exists (explained later)

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```
x = 0; y = 0;
     {(0,0)}
while (x<6) {
    if (?) {
        y = y+2;
        {
        };
        {
        x = x+1;
        {
}</pre>
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```
x = 0; y = 0;
       \{(0,0),(1,0),(1,2)\}
while (x<6) {
  if (?) {
       \{(0,0),(1,0),(1,2)\}
    v = v+2:
       \{(0,2),(1,2),(1,4)\}
  };
       \{(0,0),(0,2),(1,0),(1,2),(1,4)
  x = x+1:
       \{(1,0),(1,2)\}
```

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       \{(0,0),(1,0),(1,2)\}
while (x<6) {
  if (?) {
       \{(0,0),(1,0),(1,2)\}
    v = v+2:
       \{(0,2),(1,2),(1,4)\}
  };
       \{(0,0),(0,2),(1,0),(1,2),(1,4)\}
  x = x+1;
       \{(1,0),(1,2),(2,0),(2,2),(2,4)\}
```

Abstract interpretation executes programs on state properties instead of states.

## Collecting semantics

- A state property is a subset in  $\mathcal{P}(\mathbb{Z}^2)$  of  $(\mathbf{x}, \mathbf{y})$  values.
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- We "execute" the program until stability
  - It may take an infinite number of steps...
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```
x = 0; y = 0;
        \{(0,0),(1,0),(1,2),\dots\}
while (x<6) {
  if (?) {
        \{(0,0),(1,0),(1,2),\ldots\}
    y = y+2;
        \{(0,2),(1,2),(1,4),\dots\}
  };
        \{(0,0),(0,2),(1,0),(1,2),(1,4),\dots\}
  x = x+1:
        \{(1,0),(1,2),(2,0),(2,2),(2,4),\ldots\}
        \{(6,0),(6,2),(6,4),(6,6),\ldots\}
```

Abstract interpretation executes programs on state properties instead of states.

#### Approximation

 The set of manipulated properties may be restricted to ensure computability of the semantics.
 Example: sign of variables

$$P ::= x C 0 \land y C 0$$

$$C ::= \langle | \leq | = | \rangle | \geqslant$$

```
x = 0; y = 0;
        \mathbf{x} = 0 \land \mathbf{v} = 0
while (x<6) {
  if (?) {
    y = y+2;
  };
  x = x+1;
```

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```
x = 0; y = 0;

x = 0 ∧ y = 0

while (x<6) {

if (?) {

x = 0 ∧ y = 0

y = y+2;

};

x = x+1;
```

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```
x = 0; y = 0;
x = 0 \land y = 0
while (x<6) {
   if (?) {
        x = 0 \land y = 0
        y = y+2;
        x = 0 \land y > 0 over-approximation!
};

x = x+1;
}
```

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```
x = 0; y = 0;

x = 0 \wedge y = 0

while (x<6) {

if (?) {

x = 0 \wedge y = 0

y = y+2;

x = 0 \wedge y > 0

};

x = 0 \wedge y \geqslant 0

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while (x<6) {
  if (?) {
          x = 0 \land v = 0
     y = y+2;
          x = 0 \land v > 0
  };
          \mathbf{x} = 0 \land \mathbf{y} \geqslant 0
  x = x+1:
          x > 0 \land y \geqslant 0 over-approximation!
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```
x = 0; y = 0;
          x \geqslant 0 \land y \geqslant 0
while (x<6) {
   if (?) {
          \mathbf{x} = 0 \land \mathbf{v} = 0
     y = y+2;
          x = 0 \land v > 0
  };
          \mathbf{x} = 0 \land \mathbf{y} \geqslant 0
   x = x+1:
          x > 0 \land y \ge 0
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```
x = 0; y = 0;
          x \geqslant 0 \land y \geqslant 0
while (x<6) {
  if (?) {
         x \ge 0 \land v \ge 0
     y = y+2;
         x = 0 \land v > 0
  };
          \mathbf{x} = 0 \land \mathbf{y} \geqslant 0
  x = x+1:
          x > 0 \land y \ge 0
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  };
         x \ge 0 \land y \ge 0
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         x \geqslant 0 \land y \geqslant 0
while (x<6) {
  if (?) {
         x \geqslant 0 \land y \geqslant 0
     y = y+2;
         x \ge 0 \land v > 0
  };
         x \ge 0 \land y \ge 0
  x = x+1:
         x > 0 \land y \ge 0
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```
x = 0; y = 0;
         x \geqslant 0 \land y \geqslant 0
while (x<6) {
  if (?) {
         x \geqslant 0 \land y \geqslant 0
     y = y+2;
         x \ge 0 \land v > 0
  };
         x \ge 0 \land y \ge 0
  x = x+1:
         x > 0 \land y \ge 0
         x \ge 0 \land v \ge 0
```

## An other example : the interval analysis

For each point k and each numeric variable x, we infer an interval in which x must belong to.

Example: insertion sort, array access verification

```
assert(T.length=100); i=1;
                                           \{i \in [1, 100]\}
while (i<T.length) {</pre>
                                           \{i \in [1,99]\}
     p = T[i]; j = i-1;
                                           \{i \in [1,99], j \in [-1,98]\}
     while (0 \le j \text{ and } T[j] > p) {
                                           \{i \in [1,99], i \in [0,98]\}
           T[j]=T[j+1]; j = j-1;
                                           \{i \in [1,99], i \in [-1,97]\}
     };
                                           \{i \in [1,99], i \in [-1,98]\}
     T[i+1]=p; i = i+1;
                                           \{i \in [2, 100], j = [-1, 98]\}
};
                                           \{i = 100\}
```

## An other example : the polyhedral analysis

For each point k and we infer invariant linear equality and inequality relationships among variables.

Example: insertion sort, array access verification

```
assert(T.length>=1); i=1;
                                           \{1 \le i \le T.length\}
while i<T.length {</pre>
                                           \{1 \le i \le T.length - 1\}
     p = T[i]; j = i-1;
                                           \{1 \leq i \leq T.length - 1 \land -1 \leq i \leq i - 1\}
     while 0<=j and T[j]>p {
                                           \{1 \leq i \leq T.length - 1 \land 0 \leq i \leq i - 1\}
           T[j]=T[j+1]; j = j-1;
                                           \{1 \le i \le T.length - 1 \land -1 \le i \le i - 2\}
     };
                                           \{1 \le i \le T.length - 1 \land -1 \le i \le i - 1\}
     T[i+1]=p; i = i+1;
                                           \{2 \leq i \leq T.length + 1 \land -1 \leq i \leq i - 2\}
};
                                           \{i = T.length\}
```

## This lecture

- Introduction
- 2 The While language
- Control flow graph
- 4 Collecting semantics
- **5** Approximate analysis : an informal presentation

Introduction



- Introduction
- 2 The While language

- Introduction
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# While syntax

```
\begin{array}{ccc} Exp ::= & n \\ & | & ? \\ & | & x \\ & | & Exp \circ Exp \end{array}
                                                                        n \in \mathbb{Z}
                                                                       x \in \mathbb{V}
                                                                        o \in \{+, -, \times\}
 Test ::= Exp c Exp
           Test and Test
           | Test or Test
Stm ::= {}^{l}[x := Exp]
                                                                        l \in \mathbb{P}
          | ^{l}[skip]
           if <sup>1</sup>[Test] { Stm } { Stm }
           | while <sup>l</sup>[Test] { Stm }
              Stm; Stm
Prog ::= [Stm]^{end}
                                                                        end \in \mathbb{P}
```

 $\mathbb{P}$ : set of program points  $\mathbb{V}$ : set of program variables



# While syntax : example

# Syntax : Ocaml code

| Or of test \* test

```
type var = string
type binop =
  | Add | Sub | Mult
                                       type label = int
type expr =
                                       type stmt =
  | Const of int
                                         | Assign of label * var * expr
  | Unknown
                                          Skip of label
  | Var of var
                                          If of label * test * stmt * stmt
  | Binop of binop * expr * expr
                                          While of label * test * stmt
                                          Sea of stmt * stmt
type comp = Eq | Neq | Le | Lt
                                      type program = stmt * label
type test =
  | Comp of comp * expr * expr
  | And of test * test
```

## While semantics

#### Semantic domains

$$\begin{array}{ccc} \textit{Env} & \stackrel{\text{\tiny def}}{=} & \mathbb{V} \to \mathbb{Z} \\ \textit{State} & \stackrel{\text{\tiny def}}{=} & \mathbb{P} \times \textit{Env} \end{array}$$

#### Semantics of expressions

$$\mathcal{A}[\![e]\!] \rho \in \mathcal{P}(\mathbb{Z}), \quad e \in Exp, \ \rho \in Env$$

$$\mathcal{A}[\![n]\!] \rho = \{n\}$$

$$\mathcal{A}[\![?]\!] \rho = \mathbb{Z}$$

$$\mathcal{A}[\![x]\!] \rho = \{\rho(x)\}, \ x \in \mathbb{V}$$

$$\mathcal{A}[\![e_1 \ o \ e_2]\!] \rho = \{v_1 o \ v_2 \ | \ v_1 \in \mathcal{A}[\![e_1]\!] \rho, \ v_2 \in \mathcal{A}[\![e_2]\!] \rho\}$$

$$o \in \{+, -, \times\}$$

Remark :  $A[\cdot]$   $\rho$  is non-deterministic because of the expression ?.

## Semantics of tests

$$\begin{split} \mathbb{B}[\![t]\!] & \rho \in \mathcal{P}(\mathbb{B}), \quad t \in \textit{Test}, \ \rho \in \textit{Env} \quad \mathbb{B} = \{\mathsf{tt}, \mathsf{ff}\} \\ & \frac{v_1 \in \mathcal{A}[\![e_1]\!] \rho \quad v_2 \in \mathcal{A}[\![e_2]\!] \rho \quad v_1 \; \overline{c} \; v_2}{\mathsf{tt} \in \mathcal{B}[\![e_1 \; c \; e_2]\!] \rho} \\ & \frac{v_1 \in \mathcal{A}[\![e_1]\!] \rho \quad v_2 \in \mathcal{A}[\![e_2]\!] \rho \quad \neg (v_1 \; \overline{c} \; v_2)}{\mathsf{ff} \in \mathcal{B}[\![e_1 \; c \; e_2]\!] \rho} \\ & \frac{b_1 \in \mathcal{B}[\![t_1]\!] \rho \quad b_2 \in \mathcal{B}[\![t_2]\!] \rho}{b_1 \wedge_{\mathbb{B}} b_2 \in \mathcal{B}[\![t_1 \; \mathsf{and} \; t_2]\!] \rho} \\ & \frac{b_1 \in \mathcal{B}[\![t_1]\!] \rho \quad b_2 \in \mathcal{B}[\![t_2]\!] \rho}{b_1 \vee_{\mathbb{B}} b_2 \in \mathcal{B}[\![t_1 \; \mathsf{or} \; t_2]\!] \rho} \end{split}$$



## Structural Operational Semantics

Small-step semantics

$$\frac{v \in \mathcal{A}\llbracket a \rrbracket \rho}{(^{l}[x := a], \rho) \Rightarrow \rho[x \mapsto v]} \qquad \overline{(^{l}[\mathsf{nop}], \rho) \Rightarrow \rho}$$

$$\frac{(S_{1}, \rho) \Rightarrow \rho'}{(S_{1}; S_{2}, \rho) \Rightarrow (S_{2}, \rho')} \qquad \frac{(S_{1}, \rho) \Rightarrow (S_{1}', \rho')}{(S_{1}; S_{2}, \rho) \Rightarrow (S_{1}'; S_{2}, \rho')}$$

$$\frac{\mathsf{tt} \in \mathcal{B}\llbracket b \rrbracket \rho}{(\mathsf{if}^{\;l}[b] \; \mathsf{then} \; S_{1} \; \mathsf{else} \; S_{2}, \rho) \Rightarrow (S_{1}, \rho)}$$

$$\frac{\mathsf{ff} \in \mathcal{B}\llbracket b \rrbracket \rho}{(\mathsf{if}^{\;l}[b] \; \mathsf{then} \; S_{1} \; \mathsf{else} \; S_{2}, \rho) \Rightarrow (S_{2}, \rho)}$$

$$\frac{\mathsf{tt} \in \mathcal{B}\llbracket b \rrbracket \rho}{(\mathsf{while}^{\;l}[b] \; \mathsf{do} \; S, \rho) \Rightarrow (S; \; \mathsf{while}^{\;l}[b] \; \mathsf{do} \; S, \rho)}$$

$$\frac{\mathsf{ff} \in \mathcal{B}\llbracket b \rrbracket \rho}{(\mathsf{while}^{\;l}[b] \; \mathsf{do} \; S, \rho) \Rightarrow \rho}$$



# Program point manipulation

We define the entry point of a statement:

$$\begin{array}{rcl} & entry\left(^{l}[x:=e]\right) & = & entry\left(^{l}[\mathtt{skip}]\right) = l \\ entry\left(\mathtt{if}^{\;l}[t]\left\{\,S_{1}\,\right\}\left\{\,S_{2}\,\right\}\right) & = & entry\left(\mathtt{while}^{\;l}[t]\left\{\,S\,\right\}\right) = l \\ & entry\left(S_{1};\,S_{2}\right) & = & entry(S_{1}) \end{array}$$

We define the set of points of a statement :

$$labels (^{I}[x := e]) = labels (^{I}[skip]) = \{I\}$$

$$labels (if^{I}[t] \{ S_1 \} \{ S_2 \}) = \{I\} \cup labels(S_1) \cup labels(S_2)$$

$$labels (while^{I}[t] \{ S \}) = \{I\} \cup labels(S)$$

$$labels (S_1; S_2) = labels(S_1) \cup labels(S_2)$$

## SOS-Reachable states

#### Reachable states:

$$\llbracket [P]^{\text{end}} \rrbracket_{\text{SOS}} = \left\{ (k, \rho) \middle| \begin{array}{l} \exists \rho_0 \in Env, \\ \exists S \in Stm, \ (P, \rho_0) \Rightarrow^* (S, \rho) \text{ and } k = \text{entry}(S) \\ \text{or } (P, \rho_0) \Rightarrow^* \rho \text{ and } k = \text{end} \end{array} \right\}$$

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# A flowchart representation of program

The standard program model in static analysis: the *control flow graph*.

The graph model used here:

- ▶ the nodes are program point  $k \in \mathbb{P}$ ,
- the edges are labeled with basic instructions

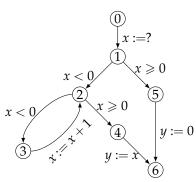
```
Instr ::= x := Exp assignment
| assume Test execution continues only if
the test succeds
```

- ▶ formally, a cfg is a triplet  $(k_{init}, S, k_{end})$  with
  - $k_{\text{init}} \in \mathbb{P}$ : the entry point,
  - $k_{\text{end}} \in \mathbb{P}$ : the exit point,
  - $S \subseteq \mathbb{P} \times Instr \times \mathbb{P}$  the set of edges.

Remark: data-flow analyses are generally based on other versions of control flow graphs (instructions are put in nodes).

## While syntax : example

```
[^{0}[x := ?];
if ^{1}[x < 0] {
    while ^{2}[x < 0] {
        ^{3}[x := x + 1];
    };
    ^{4}[y := x];
} else {
        ^{5}[y := 0];
};]^{6}
```



assume is left implicit

## Control flow graph generation (1/2)

 $\mathit{cfg}_l(S)$  computes the edges of the control flow graph of S using l as final label.

$$\begin{array}{rcl} \textit{cfg}_l & \in & \textit{Stm} \rightarrow \mathbb{P}(\mathbb{P} \times \textit{Instr} \times \mathbb{P}), & l \in \mathbb{P} \\ \textit{cfg}_{l'}\left({}^l[x := e]\right) & = & \{(l, x := e, l')\} \\ \textit{cfg}_{l'}\left({}^l[\mathsf{skip}]\right) & = & \{(l, \mathsf{assume} \ T, l')\} & \text{with} \ T \equiv 0 = 0 \\ \textit{cfg}_{l'}\left(\mathsf{if}^{\ l}[t] \left\{ S_1 \right\} \left\{ S_2 \right\} \right) & = & \{(l, \mathsf{assume} \ t, entry(S_1))\} \cup \\ & & \{(l, \mathsf{assume} \ neg(t), entry(S_2))\} \cup \textit{cfg}_{l'}(S_1) \cup \textit{cfg}_{l'}(S_2) \\ \textit{cfg}_{l'}\left(\mathsf{while}^{\ l}[t] \left\{ S \right\} \right) & = \\ & & \textit{cfg}_{l'}\left(S_1; \ S_2 \right) & = \\ & & & \textit{cfg} \in & \textit{Prog} \rightarrow \mathbb{P} \times \mathbb{P}(\mathbb{P} \times \textit{Instr} \times \mathbb{P}) \times \mathbb{P} \end{array}$$

 $cf_{\mathcal{Q}}([P]^{end}) = (entry(P), cf_{\mathcal{Q}_{end}}(P), end)$ 

## Control flow graph generation (1/2)

 $\mathit{cfg}_l(S)$  computes the edges of the control flow graph of S using l as final label.

$$cfg_l \in Stm \rightarrow \mathcal{P}(\mathbb{P} \times Instr \times \mathbb{P}), \quad l \in \mathbb{P}$$

$$cfg_{l'}\left(^{l}[x := e]\right) = \{(l, x := e, l')\}$$

$$cfg_{l'}\left(^{l}[skip]\right) = \{(l, assume \ T, l')\} \quad \text{with } T \equiv 0 = 0$$

$$cfg_{l'}\left(\text{if }^{l}[t] \{ S_1 \} \{ S_2 \}\right) = \{(l, assume \ t, entry(S_1))\} \cup \\ \{(l, assume \ neg(t), entry(S_2))\} \cup cfg_{l'}(S_1) \cup cfg_{l'}(S_2)$$

$$cfg_{l'}\left(\text{while }^{l}[t] \{ S \}\right) = \{(l, assume \ t, entry(S))\} \cup \\ cfg_{l'}\left(S_1; S_2\right) =$$

$$cfg(S) \cup \{(l, assume \ neg(t), l')\}$$

$$cfg_{l'}\left(S_1; S_2\right) =$$

$$cfg(S) \cup \{(l, assume \ neg(t), l')\}$$

## Control flow graph generation (1/2)

 $\mathit{cfg}_l(S)$  computes the edges of the control flow graph of S using l as final label.

$$cfg_l \in Stm \rightarrow \mathcal{P}(\mathbb{P} \times Instr \times \mathbb{P}), \quad l \in \mathbb{P}$$

$$cfg_{l'} \left( {}^{l}[x := e] \right) = \left\{ (l, x := e, l') \right\}$$

$$cfg_{l'} \left( {}^{l}[skip] \right) = \left\{ (l, assume \ T, l') \right\} \quad \text{with } T \equiv 0 = 0$$

$$cfg_{l'} \left( \text{if }^{l}[t] \left\{ S_1 \right\} \left\{ S_2 \right\} \right) = \left\{ (l, assume \ t, entry(S_1)) \right\} \cup \\ \left\{ (l, assume \ neg(t), entry(S_2)) \right\} \cup cfg_{l'}(S_1) \cup cfg_{l'}(S_2)$$

$$cfg_{l'} \left( \text{while }^{l}[t] \left\{ S \right\} \right) = \left\{ (l, assume \ t, entry(S)) \right\} \cup \\ cfg_{l}(S) \cup \left\{ (l, assume \ neg(t), l') \right\}$$

$$cfg_{l'} \left( S_1; S_2 \right) = cfg_{entry(S_2)}(S_1) \cup cfg_{l'}(S_2)$$

$$cfg \in Prog \rightarrow \mathbb{P} \times \mathcal{P}(\mathbb{P} \times Instr \times \mathbb{P}) \times \mathbb{P}$$

$$cfg([P]^{end}) = (entry(P), cfg_{end}(P), end)$$

## Control flow graph generation (2/2)

#### Test negation:

$$neg(e_1 = e_2) = e_1 \neq e_2$$
  
 $neg(e_1 \neq e_2) = e_1 = e_2$   
 $neg(e_1 < e_2) = e_2 \leq e_1$   
 $neg(e_1 \leq e_2) = e_2 < e_1$   
 $neg(t_1 \text{ and } t_2) = neg(t_1) \text{ or } neg(t_1)$   
 $neg(t_1 \text{ or } t_2) = neg(t_1) \text{ and } neg(t_1)$ 

# Small-step semantics of cfg

We first define the semantics of instructions :  $\stackrel{i}{\rightarrow} \subseteq Env \times Env$ 

$$\frac{v \in \mathcal{A}[\![a]\!]\rho}{\rho \xrightarrow{x := a} \rho[x \mapsto v]} \qquad \frac{\mathsf{tt} \in \mathcal{B}[\![t]\!]\rho}{\rho \xrightarrow{\mathsf{assume } t} \rho}$$

Then, a small-step relation  $\rightarrow_{cfg} \subseteq State \times State$  for a  $cfg = (k_{init}, S, k_{end})$ 

$$\frac{(k_1,i,k_2) \in S \qquad \rho_1 \xrightarrow{i} \rho_2}{(k_1,\rho_1) \rightarrow_{cfg} (k_2,\rho_2)}$$

Reachable states for control flow graphs

$$[\![(k_{\text{init}}, S, k_{\text{end}})]\!]_{\text{CFG}} = \{ (k, \rho) \mid \exists \rho_0 \in \textit{Env}, \ (k_{\text{init}}, \rho_0) \rightarrow^*_{(k_{\text{init}}, S, k_{\text{end}})} (k, \rho) \}$$



# Correctness of cfg

#### Lemma

For any  $l \in \mathbb{P}$ ,  $S, S' \in Stm$  and  $s, s' \in State$ 

$$(S,s)\Rightarrow s' \ \textit{iff} \ \exists i \in Instr, s \stackrel{i}{
ightarrow} s' \ \textit{and} \ (entry(S), i, l) \in \textit{cfg}_l(S)$$

$$(S,s)\Rightarrow (S',s') \ iff \ \exists i \in Instr, s \xrightarrow{i} s' \ and \ (entry(S),i,entry(S')) \in cfg_l(S)$$

#### Theorem

For all program p,

$$[[cfg(p)]]_{CFG} = [[p]]_{SOS}$$

From now on, we write  $[\![p]\!]$  instead of  $[\![cfg(p)]\!]_{CFG}$  and we confound cfg(p) and p.

### Proof of the lemma (1/4)

### Auxiliary lemmas:

- $b \in \mathcal{B}[t] \rho$  implies  $\neg b \in \mathcal{B}[neg(t)] \rho$ . Proof: by induction on t.
- ②  $(S, \rho) \Rightarrow (S', \rho')$  implies  $cfg_l(S') \subseteq cfg_l(S)$ . Proof: by induction on  $(S, \rho) \Rightarrow (S', \rho')$ .

# Proof of the lemma (2/4)

We prove that  $(S, \rho) \Rightarrow \rho'$  implies  $\exists i \in Instr, \rho \xrightarrow{i} \rho'$  and  $(entry(S), i, l) \in cfg_l(S)$  by case analysis on  $(S, \rho) \Rightarrow \rho'$ .

- $(l'[x:=a], \rho) \Rightarrow \rho[x \mapsto v]$  with  $v \in \mathcal{A}[a][\rho]$  and  $cfg_l(S) = \{(l', x:=a, l)\}$ . Hence  $\rho \xrightarrow{x:=a} \rho[x \mapsto v]$  and since entry(S) = l' we have  $(entry(S), i, l) \in cfg_l(S)$ .
- $(l'[\mathsf{nop}], \rho) \Rightarrow \rho$  and therefore  $cfg_l(S) = \{(l', \mathsf{assume}\ T, l)\}$ . Hence,  $\rho \xrightarrow{\mathsf{assume}\ T} \rho$  and, since entry(S) = l', we have  $(entry(S), i, l) \in cfg_l(S)$ .
- (while l'[t] do S,  $\rho$ )  $\Rightarrow$   $\rho$  with  $\mathbf{ff} \in \mathbb{B}[\![t]\!] \rho$  and  $cfg_l$  (while l'[t]  $\{S\}$ ) =  $\{(l', \mathsf{assume}\ t, entry(S))\} \cup cfg_{l'}(S) \cup \{(l', \mathsf{assume}\ neg(t), l)\}.$ Hence  $\rho \xrightarrow{\mathsf{assume}\ neg(t)} \rho$  since  $\mathsf{tt} \in \mathbb{B}[\![neg(t)]\!] \rho$ .

  Furthermore, entry(S) = l' so we have  $(entry(S), \mathsf{assume}\ neg(t), l) \in cfg_l(S)$ .

# Proof of the lemma (3/4)

We prove that  $(S, \rho) \Rightarrow (S', \rho')$  implies  $\exists i \in Instr, \rho \xrightarrow{i} \rho'$  and  $(entry(S), i, entry(S')) \in cfg_l(S)$  by induction on  $(S, \rho) \Rightarrow (S', \rho')$ .

- $(S_1; S_2, \rho) \Rightarrow (S_2, \rho')$  because  $(S_1, \rho) \Rightarrow \rho'$  and  $cfg_l(S_1; S_2) = cfg_{entry(S_2)}(S_1) \cup cfg_l(S_2)$ . Using the previous result with  $entry(S_2)$ , we know there exists  $i \in Instr$  such that  $\rho \stackrel{i}{\rightarrow} \rho'$  and  $(entry(S_1), i, entry(S_2)) \in cfg_{entry(S_2)}(S_1) \subseteq cfg_l(S_1; S_2)$  and  $entry(S_1; S_2) = entry(S_1)$ .
- $(S_1; S_2, \rho) \Rightarrow (S_1'; S_2, \rho')$  because  $(S_1, \rho) \Rightarrow (S_1', \rho')$  and  $cfg_l(S_1; S_2) = cfg_{entry(S_2)}(S_1) \cup cfg_l(S_2)$ . Using induction hypothesis with  $entry(S_2)$  instead of l, we know there exists  $i \in Instr$  such that  $\rho \xrightarrow{i} \rho'$  and  $(entry(S_1), i, entry(S_1')) \in cfg_{entry(S_2)}(S_1) \subseteq cfg_l(S_1; S_2)$  and  $entry(S_1: S_2) = entry(S_1)$ . We easily conclude since  $entry(S_1: S_2) = entry(S_1)$  and  $entry(S_1'; S_2) = entry(S_1')$  and as a consequence  $(entry(S_1: S_2), i, entry(S_1'; S_2)) \in cfg_l(S_1; S_2)$ .



### Proof of the lemma (4/4)

• (if l'[t] then  $S_1$  else  $S_2$ ,  $\rho$ )  $\Rightarrow$  ( $S_1$ ,  $\rho$ ) with  $\mathbf{tt} \in \mathcal{B}\llbracket b \rrbracket \rho$  and (l', assume t, entry( $S_1$ ))  $\in$  cfg $_l(S)$ . Hence  $\rho \xrightarrow{\text{assume } t} \rho$  and (entry(S), assume t, entry( $S_1$ ))  $\in$  cfg $_l(S)$  since entry(S) = l'.

**>** . . .

Exercise : Prove the other direction :  $\exists i, \dots$  implies ...

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### **Collecting Semantics**

We will consider a collecting semantics that give us the set of reachable states  $\llbracket p \rrbracket_k^{\text{col}}$  at each program points k.

$$\forall k \in \mathbb{P}, \ [\![p]\!]_k^{\text{col}} = \{ \ \rho \mid (k, \rho) \in [\![p]\!] \}$$

#### **Theorem**

 $[p]^{col}$  may be characterized as the least fixpoint of the following equation system.

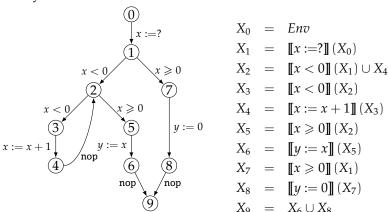
$$\forall k \in labels(p), \ X_k = X_k^{init} \cup \bigcup_{(k',i,k) \in p} \llbracket i \rrbracket (X_{k'})$$

with 
$$X_k^{\text{init}} = \begin{cases} Env & \text{if } k = k_{\text{init}} \\ \emptyset & \text{otherwise} \end{cases}$$
 and

$$\forall i \in \mathit{Instr}, \ \forall X \subseteq \mathit{Env}, \ \llbracket i \rrbracket \left( X \right) = \left\{ \ \rho_2 \ | \ \exists \rho_1 \in X, \ \rho_1 \xrightarrow{i} \rho_2 \ \right\} = post \left[ \xrightarrow{i} \left( X \right) \right]$$

# Example

For the following program,  $[\![P]\!]^{\mathrm{col}}$  is the least solution of the following equation system :



# **Fixpoint Lattice Theory**

### Theorem (Knaster-Tarski)

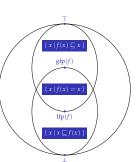
In a complete lattice  $(A, \sqsubseteq, \bigsqcup)$ , for all monotone functions  $f \in A \to A$ , the least fixpoint lfp(f) of f exists and is  $\bigcap \{x \in A \mid f(x) \sqsubseteq x\}$ .

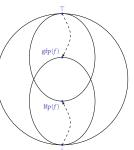
### Theorem (Kleene fixpoint theorem)

In a complete lattice  $(A, \sqsubseteq, \bigsqcup)$ , for all continuous function  $f \in A \to A$ , the least fixpoint lfp(f) of f is equal to  $||\{f^n(\bot) | n \in \mathbb{N}\}|$ .

### **Theorem**

Let  $(A, \sqsubseteq)$  a poset that verifies the ascending chain condition and f a monotone function. The sequence  $\bot, f(\bot), \ldots, f^n(\bot), \ldots$  eventually stabilises. Its limit is the least fixpoint of f.





# Collecting semantics and exact analysis

The  $(X_k)_{i=1..N}$  are hence specified as the least solution of a fixpoint equation system

$$X_k = F_k(X_1, X_2, \dots, X_N)$$
 ,  $k \in labels(p)$ 

or, equivalently  $\vec{X} = \vec{F}(\vec{X})$ .

### Exact analysis:

- ▶ Thanks to Knaster-Tarski, the least solution exists (complete lattice, *F*<sub>k</sub> are monotone functions),
- ▶ Kleen fixpoint theorem ( $F_k$  are continuous functions) says it is the limit of

$$X_k^0 = \emptyset$$
 ,  $X_k^{n+1} = F_k(X_1^n, X_2^n, \dots, X_N^n)$ 

### Uncomputable problem:

- ightharpoonup Representing the  $X_k$  may be hard (infinite sets)
- ► The limit may not be reachable in a finite number of steps



# Approximate analysis

#### Exact analysis:

```
Least solution of X = F(X) in the complete lattice (\mathcal{P}(Env)^N, \subseteq, \cup, \cap) or limit of X^0 = \bot, X^{n+1} = F(X^n)
```

### Approximate analysis:

- ▶ Static approximation : we replace the concrete lattice  $(\mathcal{P}(Env), \subseteq, \cup, \cap)$  by an abstract lattice  $(L^{\sharp}, \sqsubseteq^{\sharp}, \sqcup^{\sharp}, \sqcap^{\sharp})$ 
  - whose elements can be (efficiently) represented in computers,
  - ▶ in which we know how to compute  $\sqcup^{\sharp}$ ,  $\sqcap^{\sharp}$ ,  $\sqsubseteq^{\sharp}$ , . . .

and we "transpose" the equation X = F(X) of  $\mathfrak{P}(Env)^N$  into  $(L^{\sharp})^N$ .

▶ Dynamic approximation: when  $L^{\sharp}$  does not verifies the ascending chain condition, the iterative computation may not terminate in a finite number of steps (or sometimes too slowly). In this case, we can only approximate the limit (see widening/narrowing).

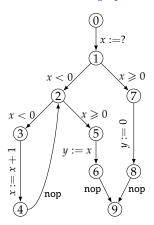
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# Just put some <sup>‡</sup>...

From  $\mathcal{P}(Env)$  to  $Env^{\sharp}$ 

#### control flow graph



#### collecting semantics

$$X_4 = [x := x + 1](X_3)$$

$$X_5 = [x \ge 0](X_2)$$
  
 $X_6 = [y := x](X_5)$ 

$$X_6 = [y := x](X_5)$$
  
 $X_7 = [x \ge 0](X_1)$ 

$$X_8 = [y := 0](X_7)$$

$$X_9 = X_6 \cup X_8$$

$$X_1^{\sharp} = [x := ?]^{\sharp} (X_0^{\sharp})$$

$$X_2^\sharp \quad = \quad \llbracket x < 0 \rrbracket^\sharp \, (X_1^\sharp) \sqcup^\sharp \, X_4^\sharp$$

$$X_3^{\sharp} = \llbracket x < 0 \rrbracket^{\sharp} (X_2^{\sharp})$$

$$X_4^{\sharp} = [x := x + 1]^{\sharp} (X_3^{\sharp})$$

$$X_5^{\sharp} = \llbracket x \geqslant 0 \rrbracket^{\sharp} (X_2^{\sharp})$$

$$\begin{array}{rcl} X_6^{\sharp} & = & \llbracket y := x \rrbracket^{\sharp} \left( X_5^{\sharp} \right) \\ X_7^{\sharp} & = & \llbracket x \geqslant 0 \rrbracket^{\sharp} \left( X_1^{\sharp} \right) \end{array}$$

$$X_8^{\sharp} = \llbracket y := 0 \rrbracket^{\sharp} (X_7^{\sharp})$$

$$X_9^{\sharp} = X_6^{\sharp} \sqcup^{\sharp} X_8^{\sharp}$$

# Abstract semantics: the ingredients

- ► A lattice structure  $(Env^{\sharp}, \sqsubseteq_{Env}^{\sharp}, \sqcup_{Env}^{\sharp}, \sqcap_{Env}^{\sharp}, \perp_{Env}^{\sharp}, \top_{Env}^{\sharp})$ 
  - $\sqsubseteq_{Env}^{\sharp}$  is an approximation of  $\subseteq$
  - ▶  $\sqcup_{Env}^{\sharp}$  is an approximation of  $\cup$
  - ▶  $\sqcap_{Env}^{\sharp}$  is an approximation of  $\cap$
  - $\perp_{Env}^{\sharp}$  is an approximation of  $\emptyset$
  - $ightharpoonup T_{Env}^{\sharp}$  is an approximation of Env
- ▶ For all  $x \in \mathbb{V}$ ,

$$\llbracket x :=? \rrbracket^{\sharp} \in Env^{\sharp} \to Env^{\sharp}$$
 an approximation of  $\llbracket x :=? \rrbracket$ 

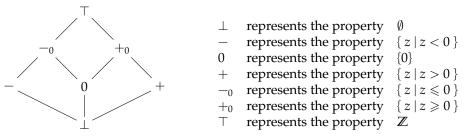
- ▶ For all  $x \in \mathbb{V}$ ,  $e \in Exp$ ,
  - $[\![x:=e]\!]^\sharp \in Env^\sharp \to Env^\sharp$  an approximation of  $[\![x:=e]\!]$
- ▶ For all  $t \in Test$ ,

$$[t]^{\sharp} \in Env^{\sharp} \to Env^{\sharp}$$
 an approximation of  $[t]$ 

▶ A concretisation  $\gamma \in Env^{\sharp} \to \mathcal{P}(Env)$  that explains which property  $\gamma(x^{\sharp}) \in \mathcal{P}(Env)$  is represented by each abstract element  $x^{\sharp} \in Env^{\sharp}$ .



# An abstraction by signs



 $Env^{\sharp} \stackrel{\text{def}}{=} \mathbb{V} \to Sign$ : a sign is associated to each variable.

# An abstraction by signs: example

with

$$\begin{aligned} succ^{\sharp}(\bot) &= &\bot\\ succ^{\sharp}(-) &= &-_0\\ succ^{\sharp}(0) &= ≻^{\sharp}(+) = succ^{\sharp}(+_0) = +\\ succ^{\sharp}(-_0) &= ≻^{\sharp}(\top) = \top \end{aligned}$$

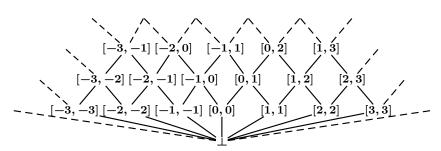


# Abstraction by intervals

$$Int \stackrel{\text{def}}{=} \{ [a,b] \mid a,b \in \overline{\mathbb{Z}}, \ a \leqslant b \} \cup \{\bot\}$$

with 
$$\overline{\mathbb{Z}} = \mathbb{Z} \cup \{-\infty, +\infty\}$$
.

 $\perp$  represents  $\emptyset$  and [a,b] the property  $\{z \mid a \leqslant z \leqslant b\}$ .



 $Env^{\sharp} \stackrel{\text{def}}{=} \mathbb{V} \to Int$ : an interval is associated to each variable.

# Abstraction by intervals : example

$$\begin{array}{lllll} X_{0}^{\sharp} & = & \top_{Env}^{\sharp} & & & & & & & & & & & & & & \\ X_{1}^{\sharp} & = & [\![x:=?]\!]^{\sharp} \, (X_{0}^{\sharp}) & & & & & & & & & \\ X_{1}^{\sharp} & = & [\![x:=?]\!]^{\sharp} \, (X_{0}^{\sharp}) & & & & & & & & \\ X_{1}^{\sharp} & = & X_{0}^{\sharp} [x \mapsto [-\infty, +\infty]] & & & & & \\ X_{2}^{\sharp} & = & [\![x:=x \mapsto 0]\!]^{\sharp} \, (X_{1}^{\sharp}) & & & & & & \\ X_{3}^{\sharp} & = & [\![x:=x \mapsto 1]\!]^{\sharp} \, (X_{2}^{\sharp}) & & & & & & \\ X_{3}^{\sharp} & = & X_{2}^{\sharp} [x \mapsto X_{2}^{\sharp} (x) \sqcap^{\sharp} [-\infty, -1]] & \downarrow^{\sharp} \, X_{4}^{\sharp} \\ & = & [\![x:=x \mapsto 1]\!]^{\sharp} \, (X_{3}^{\sharp}) & & & & & & \\ X_{4}^{\sharp} & = & X_{2}^{\sharp} [x \mapsto X_{2}^{\sharp} (x) \sqcap^{\sharp} [-\infty, -1]] & & \\ X_{4}^{\sharp} & = & X_{3}^{\sharp} [x \mapsto X_{2}^{\sharp} (x) \sqcap^{\sharp} [-\infty, -1]] & & \\ X_{4}^{\sharp} & = & X_{3}^{\sharp} [x \mapsto X_{2}^{\sharp} (x) \sqcap^{\sharp} [0, +\infty]] & & \\ X_{5}^{\sharp} & = & X_{2}^{\sharp} [x \mapsto X_{2}^{\sharp} (x) \sqcap^{\sharp} [0, +\infty]] & & \\ X_{5}^{\sharp} & = & X_{2}^{\sharp} [x \mapsto X_{2}^{\sharp} (x) \sqcap^{\sharp} [0, +\infty]] & & \\ X_{6}^{\sharp} & = & X_{2}^{\sharp} [x \mapsto X_{1}^{\sharp} (x) \sqcap^{\sharp} [0, +\infty]] & & \\ X_{7}^{\sharp} & = & X_{2}^{\sharp} [x \mapsto X_{1}^{\sharp} (x) \sqcap^{\sharp} [0, +\infty]] & & \\ X_{8}^{\sharp} & = & X_{2}^{\sharp} [y \mapsto [0, 0]] & & \\ X_{8}^{\sharp} & = & X_{2}^{\sharp} [y \mapsto [0, 0]] & & \\ X_{9}^{\sharp} & = & X_{6}^{\sharp} \sqcup^{\sharp} X_{8}^{\sharp} & & & \\ X_{9}^{\sharp} & = & X_{6}^{\sharp} \sqcup^{\sharp} X_{8}^{\sharp} & & \\ \end{array}$$

with

$$\operatorname{succ}^{\sharp}(\bot) = \bot$$
  
 $\operatorname{succ}^{\sharp}([a,b]) = [a+1,b+1]$ 

