

Quantum localization bounds Trotter errors in digital quantum simulation

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A fundamental challenge in digital quantum simulation (DQS) is the control of inherent errors. These appear when discretizing the time evolution generated by the Hamiltonian of a quantum many-body system as a sequence of quantum gates, called Trotterization. Here, we show that quantum localization—by constraining the time evolution through quantum interference—strongly bounds these errors for local observables. Consequently, for generic quantum many-body Hamiltonians, Trotter errors can become independent of system size and total simulation time. For local observables, DQS is thus intrinsically much more robust than what one might expect from known error bounds on the global many-body wave function. This robustness is characterized by a sharp threshold as a function of the Trotter step size. The threshold separates a regular region with controllable Trotter errors, where the system exhibits localization in the space of eigenstates of the time-evolution operator, from a quantum chaotic regime where the trajectory is quickly scrambled throughout the entire Hilbert space. Our findings show that DQS with comparatively large Trotter steps can retain controlled Trotter errors for local observables. It is thus possible to reduce the number of quantum gate operations required to represent the desired time evolution faithfully, thereby mitigating the effects of imperfect individual gate operations.

Introduction

Quantum computers promise to solve certain computational problems exponentially faster than any classical machine [1]. A particularly promising application is the solution of quantum many-body problems [2], with large potential impact on quantum chemistry, material science, and fundamental physics. The devices employed in this effort can be divided into two major classes [3]: analog quantum simulators, where the

Hamiltonian of interest is engineered to mimic the desired quantum many-body physics; and digital quantum simulators (DQSs), where a target time-evolution operator is represented by a sequence of elementary quantum gates. The digital approach is particularly flexible, since a universal DQS can be freely programmed to simulate the unitary evolution of any many-body Hamiltonian with local interactions [4] (Fig. 1a). Recent experiments have demonstrated remarkable progress in implementing DQS, e.g., by simulating simple molecules in quantum chemistry [5–7], condensed-matter models [8–13], and lattice gauge theories [14]. It is remarkable that in the regular region second-order perturbation theory remains valid even for long times. This feature makes the error on local observables well-controlled and enables a finite- τ extrapolation to the ideal limit.

The working principle of DQS is as follows. Suppose that the target Hamiltonian $H = \sum_{l=1}^M H_l$ can be decomposed into M terms whose time evolution operators $U_l(t) = \exp(-itH_l)$ can be implemented on the considered quantum computing device. Using the Suzuki–Trotter formula [15, 16], the full time-evolution operator $U(t) = \exp(-itH)$ can be approximated by discretizing it into $n \in \mathbb{N}$ repetitions of the fundamental gates U_l :

$$U^{(n)}(t) = \left[U_1 \left(\frac{t}{n} \right) U_2 \left(\frac{t}{n} \right) \cdots U_M \left(\frac{t}{n} \right) \right]^n. \quad (1)$$

This Trotterization comes inherently with an error that can be rigorously bounded via the accuracy of the global unitary time-evolution operator [4]

$$U(t) - U^{(n)}(t) = \frac{t^2}{2n} \sum_{l>m=1}^M [H_l, H_m] + \epsilon. \quad (2)$$

Here, ϵ subsumes terms of order t^3/n^2 and higher. Consequently, for the lowest order corrections the error grows quadratically with total simulation time t and (in generic quantum many-body systems) linearly in the number of simulated degrees of freedom N . It is possible to improve this bound, but an error bound that scales less than linear in t is not possible if one is concerned with the entire unitary operator [17]. Although the polynomial scaling with both t and N is efficient in a computational complexity sense, it poses a significant challenge for practical computations [18, 19], seemingly preventing current technology from simulating all but small instances. As we

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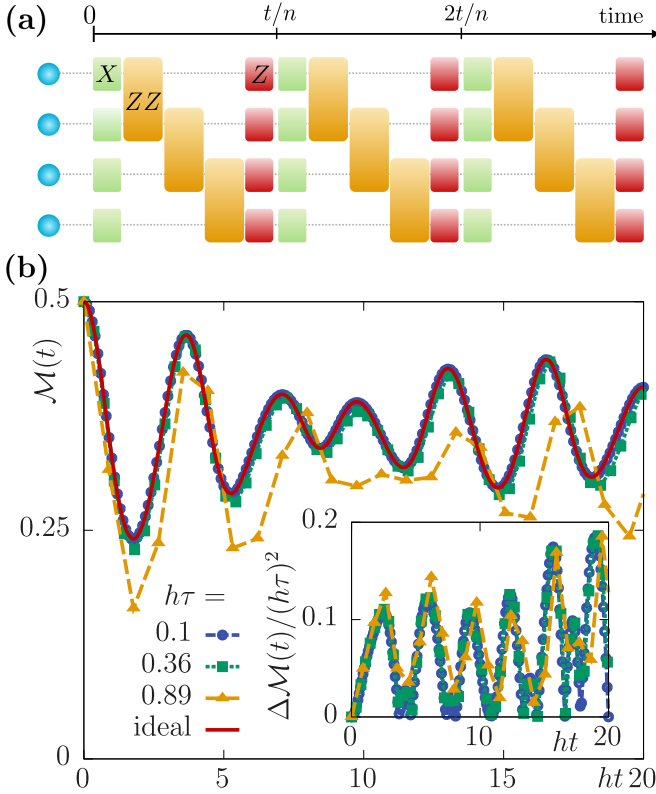


Figure 1: **Trotterized time evolution and resulting error on local observables.** (a) Gate sequence for the digital quantum simulation (DQS) of an Ising model. The desired evolution up to total simulation time t is split into n repeated sequences of length $\tau = t/n$, each decomposed into fundamental quantum gates. The example shows a gate sequence for a 4-qubit chain with Ising spin-spin interactions (ZZ) and transverse and longitudinal fields (simulated by single-qubit operations along the X and Z directions on the Bloch sphere). (b) Magnetization dynamics $\mathcal{M}(t) = N^{-1} \sum_{l=1}^N \langle S_l^z(t) \rangle$ in the DQS of the Ising model for $N = 20$ spins and different Trotter step sizes τ compared to the exact solution. The normalized deviation $\Delta\mathcal{M}(t)/(h\tau)^2$ with $\Delta\mathcal{M}(t) = |\mathcal{M}_{\tau=0}(t) - \mathcal{M}(t)|$ from the ideal dynamics $\mathcal{M}_{\tau=0}(t)$ shows a collapse of the error dynamics for sufficiently small τ .

show in this article, these generic bounds on the global many-body wave function overestimate by far the actual error on local observables such as magnetizations or low-order correlation functions. For example, in the DQS of a quantum Ising chain the deviation of the magnetization dynamics from the ideal evolution can be significantly smaller and remain bounded even at long times, see Figs. 1b,c. It is the purpose of this article, to explain this observation from physical grounds, and thus assign a physical interpretation to Trotter errors.

We achieve this by linking Trotterization errors to quantum localization. Localization is a ubiquitous phenomenon with many facets. Initially, it has been introduced to understand the absence of transport in systems of free particles with disorder [20]. Since then, the concept has been generalized to various contexts such as

many-body localization in Hilbert space as absence of quantum ergodicity [21, 22] or energy localization in periodic time-dependent quantum many-body systems as absence of heating in continuously driven systems [23]. As we show here, at small Trotter steps a related localization in Hilbert space occurs that bounds time-discretization errors on local observables.

Results

Trotter sequences as Floquet systems

In this work, we interpret the Trotterized evolution as a periodically time-dependent quantum many-body system with a period $\tau = t/n$, see Fig. 1. The desired stroboscopic dynamics is therefore governed by an associated Floquet Hamiltonian H_F , which we define for later convenience in the following form:

$$e^{-iH_F\tau} = U_1(\tau)U_2(\tau)\cdots U_M(\tau), \quad (3)$$

The starting point of our considerations is an analytical expression for H_F in the limit of sufficiently small Trotter steps τ ,

$$H_F = H + i\frac{\tau}{2} \sum_{l>m} [H_l, H_m] + \mathcal{O}(\tau^2). \quad (4)$$

This form, which can be obtained from Eq. (3) via a Magnus expansion, quantifies the Trotterization error on a Hamiltonian level. There remain, however, two fundamental questions that we aim to address in this work: (i) What is the radius of convergence τ^* of this expansion? (ii) What is the influence of corrections to H that appear in H_F on the long-time dynamics of observables? Recent theoretical predictions for heating in generic quantum many-body systems subject to a periodic drive might leave a rather pessimistic impression [24–26]. We show in this work that the errors on local observables can nevertheless be controlled for all practical purposes.

Benchmark model: quantum Ising chain

In the following, we illustrate our discussion with a generic, experimentally relevant model, the quantum Ising chain with Hamiltonian $H = H_Z + H_X$, with $H_Z = J \sum_{l=1}^{N-1} S_l^z S_{l+1}^z + h \sum_{l=1}^N S_l^z$ and $H_X = g \sum_{l=1}^N S_l^x$. Here, S_l^γ , $\gamma = x, y, z$, denote spin-1/2 operators at lattice sites $l = 1, \dots, N$. Such models are paradigmatic workhorses for DQS platforms such as nuclear magnetic resonance [27], trapped ions [8], and superconducting qubits [28]. As initial state, we choose $|\psi_0\rangle = \bigotimes_l |\uparrow\rangle_l$, which can be prepared with high fidelity [8, 28, 29]. In the remainder, we use the parameters $h/J = g/J = 2$. For details about the simulations including the used gate sequences, see Methods. Though we focus on this model, our findings also apply to various other model systems, and thus seem generic [30].

Quantum many-body chaos threshold

As the central result of this work, we connect Trotter errors in DQS with a threshold separating a many-body quantum chaotic region from a localized regime, thus linking the intrinsic accuracy of a DQS with a quantum many-body phenomenon. For that purpose, we first investigate the inverse participation ratio

$$\text{IPR} = \sum_{\nu} p_{\nu}^2, \quad p_{\nu} = |\langle \phi_{\nu} | \psi_0 \rangle|^2, \quad (5)$$

with $|\phi_{\nu}\rangle$ denoting a full set of eigenstates of the Floquet Hamiltonian H_F . The IPR measures the localization properties of the state $|\psi_0\rangle$ in the eigenbasis $|\phi_{\nu}\rangle$, which is well studied also in the single-particle context [31]. In a quantum chaotic delocalized regime, $|\psi_0\rangle$ is scrambled across the full eigenbasis implying a uniform distribution $p_{\nu} \rightarrow \mathcal{D}^{-1}$, with \mathcal{D} the number of available states in Hilbert space. Since \mathcal{D} grows exponentially with the number of degrees of freedom N , we introduce the rate function $\lambda_{\mathcal{D}} = N^{-1} \log(\mathcal{D})$, which exhibits a well-defined thermodynamic limit. Analogously, we define $\lambda_{\text{IPR}} = N^{-1} \log(\text{IPR})$. In Fig. 2a, we show numerical data for the ratio $\lambda_{\text{IPR}}/\lambda_{\mathcal{D}}$ for the considered benchmark example. For the data in this plot, we take into account the expected leading-order finite-size corrections $\lambda_{\mathcal{D}} = N^{-1}[\log(\mathcal{D}) - \log(2)]$ in the delocalized regime, which can be estimated using random matrix theory [32]. As one can see, there appears a sharp threshold separating a quantum chaotic regime at large Trotter steps, where λ_{IPR} tends to $\lambda_{\mathcal{D}}$ with increasing system size, from a regular region with $\lambda_{\text{IPR}}/\lambda_{\mathcal{D}} < 1$.

A strong fingerprint of quantum chaos can also be found in out-of-time ordered (OTO) correlators, which quantify how fast quantum information scrambles through a many-body system. A typical OTO correlator is of the form

$$\mathcal{F}(t) = \langle V^{\dagger}(t) W^{\dagger} V(t) W \rangle, \quad (6)$$

where $V(t)$ denotes the time evolution of the operator V in the Heisenberg picture. While quantum chaos via OTO correlators is conventionally diagnosed by considering a late-time exponential growth for operators V and W with finite support in real space [33], here we consider the asymptotic long-time value of the extensive operator $V = W = N^{-1} \sum_l S_l^z$ [34]. We estimate the corresponding long-time limit, $\mathcal{F} = \mathcal{F}(t \rightarrow \infty)$, via a stroboscopic average $\mathcal{F} = \lim_{n \rightarrow \infty} n^{-1} \sum_{l=1}^n \mathcal{F}(l\tau)$.

In Fig. 2b, we present numerical evidence that this quantity detects the many-body quantum chaos threshold that we have seen in the IPR. There is a clear threshold that separates a localized region at small Trotter steps τ , where $\mathcal{F} > 0$, from a quantum chaotic region at large τ , where $\mathcal{F} \rightarrow 0$. The vanishing OTO correlator in the many-body quantum chaotic regime can be understood directly from the results obtained for the IPR. Consider the spectral decomposition of a local Hermitian operator $V = \sum_{\alpha} \lambda_{\alpha} |\alpha\rangle\langle\alpha|$, with λ_{α} the eigenvalues and $|\alpha\rangle$

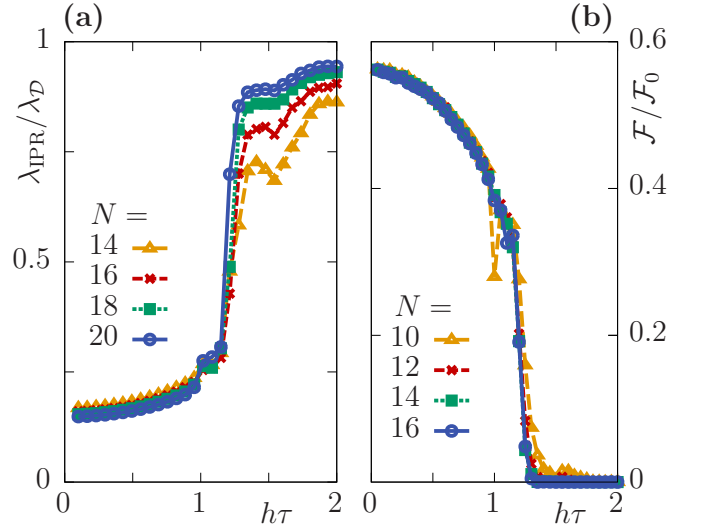


Figure 2: **Localization and quantum chaos in the Trotterized dynamics of the quantum Ising chain.** (a) Rate function λ_{IPR} of the inverse participation ratio, normalized to the maximally achievable value $\lambda_{\mathcal{D}}$ describing uniform delocalization over all accessible states. A sharp threshold as a function of the Trotter step size τ separates a localized regime at small τ from a quantum chaotic regime at large τ . (b) The long-time limit \mathcal{F} of the out-of-time ordered correlator also signals a sharp quantum chaos threshold. \mathcal{F} is normalized with respect to $\mathcal{F}_0 = 1/8$, the theoretical maximum. Full scrambling is only achieved for large Trotter steps.

the eigenvectors of V (for the considered magnetization, these are equivalent to the set of spin configurations). The effective Floquet dynamics yields after n periods

$$V(n\tau) = \sum_{\alpha} \sum_{\nu, \mu} \lambda_{\alpha} C_{\nu\alpha} C_{\mu\alpha}^* e^{-i(E_{\nu} - E_{\mu})n\tau} |\phi_{\nu}\rangle\langle\phi_{\mu}|, \quad (7)$$

with E_{ν} the Floquet quasi-energy corresponding to the eigenstate $|\phi_{\nu}\rangle$ and $C_{\nu\alpha} = \langle\phi_{\nu}|\alpha\rangle$. The behavior of the IPR suggests that for all spin configurations $p_{\nu\alpha} \equiv |C_{\nu\alpha}|^2 = \mathcal{D}^{-1}$ is uniformly distributed, such that the amplitudes $C_{\nu\alpha}$ are almost structureless and contain only a phase information, $C_{\nu\alpha} = \mathcal{D}^{-1/2} e^{i\varphi_{\nu\alpha}}$. After sufficiently many Floquet cycles, this phase information is randomized and scrambled by the unitary evolution, except when $\nu = \mu$, projecting the operator to the so-called diagonal ensemble [35]. Thus, for $n \rightarrow \infty$ one obtains $V(n\tau) \rightarrow \mathcal{D}^{-1} \sum_{\alpha} \lambda_{\alpha} \mathbb{1}$. Here, $\mathcal{D}^{-1} \sum_{\alpha} \lambda_{\alpha} = \mathcal{D}^{-1} \text{Tr } V$ is equivalent to the infinite-temperature average, which yields a vanishing value for the considered total magnetization. In other words, the operator becomes completely scrambled over the full Hilbert space.

Within the localized phase, the amplitudes $C_{\nu\alpha}$ contain more structure than only the phase information, which yields a nonzero value for the OTO correlator. For small systems, such as for $N = 10$ in Fig. 2b, one can observe additional structures in the crossover region, which vanish for larger N . We attribute these to individual quantum many-body resonances, which can

be resolved in small systems, but which merge for large N .

Robustness of local observables

While the corrections due to time discretization are weak on a Hamiltonian level, as seen in the Magnus expansion in Eq. (4), there is *a priori* no guarantee that the long-time dynamics is equally well reproduced. It is, e.g., well known for classical chaotic systems that even weak perturbations can grow quickly in time. Here, we provide numerical evidence that in the localized regime the dynamics of observables remains constrained and controlled, even in the long-time limit.

In Fig. 3a, we show the asymptotic long-time value \mathcal{M} of the magnetization, $\hat{\mathcal{M}}(t) = N^{-1} \sum_l S_l^z(t)$. One can clearly observe that the many-body quantum chaos threshold identified in the IPR and OTO correlator has a substantial influence on the long-time Trotter error of observables such as $\mathcal{M}(t)$. For large Trotter steps τ , the magnetization acquires its infinite-temperature value, perfectly consistent with the above analysis of the fully delocalized quantum chaotic phase. Remarkably, however, for small Trotter steps the error $\Delta\mathcal{M}$ relative to the targeted dynamics exhibits a quadratic dependence in τ , as we show in Fig. 3b. The origin of these weak Trotter errors can already be identified from the dynamical trajectories of the magnetization shown in Fig. 1c, where we plot the error $\Delta\mathcal{M}(t)$ for different Trotter steps normalized with respect to $(h\tau)^2$. We observe a collapse of trajectories corresponding to different τ , with the overall magnitude of the error remaining bounded in time. This finding suggests that in the localized phase the discretization error on observables itself behaves regular, in the sense that different perturbation strengths as measured by τ do not yield fast diverging expectation values.

Simulation accuracy

In the previous sections, we have provided evidence for a sharp threshold between a delocalized and a localized regime with controllable Trotter errors. We now aim to understand the influence of the regular regions onto the dynamics of observables. We identify as the underlying reason for the weak Trotter errors a dynamical constraint due to an *emergent* stroboscopic constant of motion in the effective time-periodic problem, which is the Floquet Hamiltonian H_F . Although this integral of motion is different from the desired energy conservation of the target Hamiltonian H , the perturbative expansion in Eq. (4) suggests a close connection. It is therefore natural to quantify the accuracy of a DQS by measuring how far the system deviates from the desired constant of motion H via

$$Q_E(n\tau) \equiv \frac{E_\tau(n\tau) - E_0}{E_{T=\infty} - E_0}. \quad (8)$$

Here, we have introduced $E_\tau(n\tau) = \langle H(n\tau) \rangle_\tau$ and $E_0 = E_{\tau \rightarrow 0}(n\tau) = \langle \psi_0 | H | \psi_0 \rangle$, where the subindex τ refers to

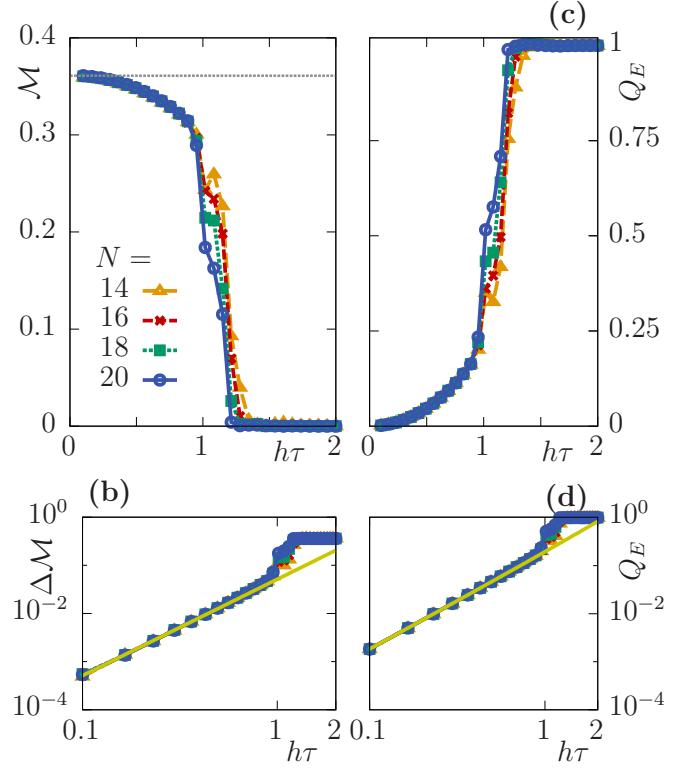


Figure 3: **Trotter errors for local observables in the infinite long-time limit for the Ising model.** Both the magnetization \mathcal{M} (a) and simulation accuracy Q_E (c) exhibit a sharp crossover from a regime of controllable Trotter errors for small Trotter steps τ to a regime of strong heating at larger τ . The dashed line in (a) refers to the desired case of the ideal evolution $\mathcal{M}_{\tau=0}$. The Trotter error exhibits a quadratic scaling at small τ for both the deviation of the magnetization, $\Delta\mathcal{M} = \mathcal{M} - \mathcal{M}_{\tau=0}$, (b) and Q_E (d). The solid lines in (b) and (d) represent analytical results obtained perturbatively in the limit of small Trotter steps τ . These results indicate the controlled robustness of digital quantum simulation against Trotter errors, in the long-time limit and largely independent of N .

the used Trotter step for the dynamics. In $Q_E(t)$, we normalize the errors using the system's energy at infinite-temperature, $E_{T=\infty} = \mathcal{D}^{-1} \text{Tr } H$. In the idealized limit $\tau \rightarrow 0$, where the integral of motion $H_F \rightarrow H$, one has $Q_E(t) = 0$. In the opposite limit of large Trotter steps, i.e., in the many-body quantum chaotic region, we expect full delocalization over all eigenstates, yielding $Q_E(t) \rightarrow 1$ in the long-time limit. Thus, $Q_E(t)$ defines a system-independent measure for the simulation accuracy. From an alternative perspective, $Q_E(t)$ quantifies heating in the effective periodically driven system, as it has been studied previously in the context of energy localization [23].

In Fig. 3c, we show numerical data for the long-time average Q_E . Again, we find a sharp threshold between the localized and quantum chaotic regimes. Importantly, for small Trotter steps Q_E acquires only a weak quadratic

dependence on τ , see Fig. 3d, yielding

$$Q_E \equiv Q_E(t \rightarrow \infty) = (\tau/\tau_E)^\alpha, \quad \tau \ll \tau_E, \quad (9)$$

with $\alpha = 2$. While τ_E depends on the microscopic details of the system, we find from our numerics that there is no notable dependence on N even in the asymptotic long-time limit, with potential corrections in the thermodynamic limit $N \rightarrow \infty$ that are discussed further below.

To obtain an analytical understanding for the observations of weak Trotter errors on local observables, let us start by considering the Magnus expansion for the Floquet Hamiltonian in Eq. (4), which quantifies the leading-order corrections due to time discretization on a Hamiltonian level. From our numerical results for Q_E , we anticipate that the target Hamiltonian H is an almost conserved quantity, which motivates us to study the perturbative corrections to strict energy conservation. Using time-dependent perturbation theory up to second order in the Trotter step size τ , we find

$$Q_E = q_E (h\tau)^2 + \mathcal{O}[(h\tau^3)]. \quad (10)$$

The explicit derivation and the final formula for q_E are given in the Methods. For the considered parameters, we estimate $q_E = 0.18$. As it can be seen in Fig. 3d, this analytical value matches well the numerical results.

To test whether the errors on other local observables are also controlled by the emergent constant of motion in the localized regime, we exemplarily study the corrections to the targeted magnetization dynamics. From time-dependent perturbation theory, we obtain $\Delta M = m(J\tau)^2 + \mathcal{O}[(J\tau^3)]$ with $m = 0.05$. This theoretical prediction is again very close to the numerical data (see Fig. 3b). As these findings indicate, in the regular region at small Trotter steps the discretization error on local observables can be captured by time-dependent perturbation theory in the Trotter step size τ — even in the asymptotic long-time limit.

Discussion

As we have shown, intrinsic Trotter errors in DQS are controllable for local observables, with a sharp threshold separating a localized from a many-body quantum chaotic regime. While we show data here for one specific model, we observe similar behavior also for other generic systems with sufficiently short-ranged interactions [30]. In addition, also certain systems with long-range interactions such as the recently experimentally realized Lattice Schwinger Model can exhibit controllable Trotter errors [30]. Our numerical studies are based on up to $N = 20$ qubits, which is within realized and expected size ranges of digital quantum simulators [5–14, 36–41].

For experiments, it is of particular interest to assess the precise value of the threshold scale τ^* . Theoretically predicting τ^* is in general as difficult as solving the desired time-evolution. Nevertheless, one can estimate τ^* as follows. Before running an experiment, one can numerically

calculate Q_E for small N , yielding a first estimate on τ^* . From this starting point, experiments can find an optimal Trotter step at larger N by decreasing τ until sufficient convergence is reached. Once in the perturbative regime, one can use data at non-zero τ to extrapolate to the ideal dynamics in a well-defined way.

While our results appear to be robust upon increasing the number of degrees of freedom, a quantitative extrapolation to $N \rightarrow \infty$ would require the numerical study of larger systems. In this context, recent works have argued that in the thermodynamic limit generic periodically driven systems will eventually heat up indefinitely [24–26]. This might leave a rather pessimistic impression, but, as we explain now, time discretization errors still remain controllable. Even in the worst-case scenario where such an indefinite heating takes place, the energy growth can still be bounded on general grounds via $|E(t) - E_0| \leq C e^{-\tau_0/\tau} t$ for $\tau \ll \tau_0$ [25, 26]. Here, C denotes a constant of dimension energy squared and τ_0 a constant of dimension time, both of which are independent of N . Thus, for a given total simulation time t , one can ensure a maximum allowed error Δ on the simulation accuracy $Q_E(t)$ by choosing τ according to $\tau = \tau_0 / \log(ct/\Delta)$ with $c = C|E_{T=\infty} - E_0|$. In this worst-case scenario, the Trotter step size to reach a given accuracy therefore acquires at most a logarithmic dependence on t but remains independent of N . This is still an exponential improvement over the global wave function bounds such as given in Eq. (2). In practice, since it is tunable via τ , this extremely slow intrinsic heating can always be adjusted such that the associated heating rate is smaller than that of other error sources, such that Trotter errors become insignificant.

Therefore, the accuracy of DQS experiments on local observables is limited mainly by extrinsic error sources. While these may in the future be eliminated by error correction [42, 43], for relevant system sizes to solve many-body problems full error correction is still out of reach with currently available resources. In the Supplementary Material, we discuss in detail two typical extrinsic error sources, timing errors on individual gates and slow drifts of gate couplings over various shots of the experiment. The slow drifts turn out to be relatively benign, leading only to an effective average over an ensemble of target Hamiltonians. Individual timing errors, however, induce in the limit of small τ a time scale beyond which the accuracy of the DQS is severely affected. In addition, a realistic system will suffer from qubit decoherence as well as faulty pulses such as imperfect swaps between internal levels. Both of these make it highly preferable to use as few gates as possible. In view of these, our results become particularly relevant: as they show, intrinsic errors in a DQS remain controlled even with relatively large Trotter steps. This makes it possible to reach a desired simulation time with a reduced number of gates, thus diminishing the influence of extrinsic errors and enhancing the accuracy of the DQS for local observables.

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The project has been devised jointly by all the authors. All authors discussed the results and wrote the manuscript. The numerical simulations have been performed by M. H.

Competing interests:

The authors declare no competing financial interests.

Data and materials availability:

All data needed to evaluate the conclusions in the paper are present in the paper and/or the Supplementary Materials. Additional data related to this paper may be requested from the authors.

Materials and Methods

Numerical methods and gate sequences

In the main text, we show numerical data for a quantum Ising chain with the Hamiltonian

$$H = H_Z + H_X, \quad (11)$$

where

$$H_Z = J \sum_{l=1}^{N-1} S_l^z S_{l+1}^z + h \sum_{l=1}^N S_l^z, \quad H_X = g \sum_{l=1}^N S_l^x. \quad (12)$$

Many of the involved contributions in this model Hamiltonian mutually commute. Therefore, only a small set of elementary quantum gates is required to simulate the Trotterized dynamics. We use the following sequence of two gates:

$$U^{(1)} = U_1 U_2, \quad U_1 = e^{-i\tau H_Z}, \quad U_2 = e^{-i\tau H_X}. \quad (13)$$

For the presented simulations of observables, we have computed the real-time evolution for $2 \cdot 10^4$ periods, except otherwise noted, using a Lanczos algorithm with full reorthogonalization. Because for a finite-size system observables still show remaining temporal fluctuations, we extract the asymptotic long-time limit of the presented quantities by performing a stroboscopic time average over the last 10^4 periods.

The inverse participation ratio shown in Fig. 2 can, in principle, be obtained either by exact diagonalization or

by use of a dynamical evolution. We have chosen the latter because it allows us to reach larger systems and is, in principle, an experimentally accessible approach. Dynamically, the inverse participation ratio can be obtained by a stroboscopic mean,

$$\text{IPR} = \lim_{n \rightarrow \infty} \frac{1}{n} \sum_{l=1}^n \mathcal{P}_l, \quad \mathcal{P}_l = \left| \langle \psi_0 | e^{-ilH_F\tau} | \psi_0 \rangle \right|^2, \quad (14)$$

as one can prove by expanding \mathcal{P}_l in the eigenbasis of H_F , followed by a summation of the resulting geometric series. Note that \mathcal{P}_l is nothing else than the Loschmidt echo, a common indicator for quantum chaotic behavior in single-particle systems [31].

For the computation of the OTO correlator $\mathcal{F}(t)$ defined in Eq. (6), we have decomposed $\mathcal{F}(n\tau)$ as

$$\mathcal{F}(n\tau) = \langle \psi_1(n\tau) | \psi_2(n\tau) \rangle, \quad (15)$$

where the two states

$$|\psi_1(n\tau)\rangle = W e^{iH_F n\tau} V e^{-iH_F n\tau} |\psi_0\rangle, \quad (16)$$

$$|\psi_2(n\tau)\rangle = e^{iH_F n\tau} V e^{-iH_F n\tau} W |\psi_0\rangle, \quad (17)$$

can be obtained from forward and backward evolving the quantum many-body state with appropriate insertions of the W and V operators. Since the backward evolution has to be performed for every Trotter step n , the overall runtime of this approach scales proportional to n^2 . This limits the accessible total simulation time $t = n\tau$, such that we have used $n = 10^3$ for the simulations shown in the main text, and we have performed a stroboscopic average over the last 300 periods to obtain an estimate for the asymptotic long-time value.

Trotter errors on local observables from perturbation theory

As mentioned in the main text, the Trotter errors for local observables can be captured using time-dependent perturbation theory in the limit of sufficiently small τ . In the following, we outline how to obtain the analytical expressions for the coefficients q_E and m for Q_E and \mathcal{M} , respectively. First, we consider the simulation accuracy Q_E and afterwards the Trotter errors on the magnetization \mathcal{M} .

For the derivation of the corrections appearing in Q_E , we can use that the energy of the target Hamiltonian H and therefore the simulation accuracy Q_E exhibit a substantial overlap with the emergent conserved quantity H_F :

$$\langle H_F(n\tau) \rangle_\tau = \langle H_F \rangle = \text{const.} \quad (18)$$

Here, $\langle \mathcal{O}(n\tau) \rangle_\tau = \langle \psi_0 | e^{iH_F n\tau} \mathcal{O} e^{-iH_F n\tau} | \psi_0 \rangle$ denotes the full Trotterized time evolution with Trotter step size τ as in the main text. Moreover, we define the expectation values in the initial state via $\langle \mathcal{O} \rangle = \langle \psi_0 | \mathcal{O} | \psi_0 \rangle$ and under the ideal time evolution as $\langle \mathcal{O}(t) \rangle = \langle \mathcal{O}(t) \rangle_{\tau=0}$.

In order to obtain all corrections to the desired order, we first have to express H_F using the Magnus expansion up to second order in the Trotter step size,

$$H_F = H + \tau \mathcal{C}_1 + \tau^2 \mathcal{C}_2 + \mathcal{O}(\tau^3), \quad (19)$$

with

$$\mathcal{C}_1 = \frac{i}{2}[H_X, H_Z], \quad \mathcal{C}_2 = -\frac{1}{12}[H_X - H_Z, [H_X, H_Z]]. \quad (20)$$

For convenience, we restrict the presentation from now on to a sequence of two elementary gates within one period, as we have for the case of the simulated quantum Ising chain. Using the above expansion for H_F in combination with the conservation of H_F , one obtains for the energy deviation

$$\begin{aligned} \Delta E(n\tau) &= \langle H(n\tau) \rangle_\tau - \langle H \rangle, \\ &= \tau \Delta \mathcal{C}_1(n\tau) + \tau^2 \Delta \mathcal{C}_2(n\tau). \end{aligned} \quad (21)$$

where

$$\Delta \mathcal{C}_\nu(n\tau) = \langle \mathcal{C}_\nu \rangle - \langle \mathcal{C}_\nu(n\tau) \rangle_\tau, \quad \nu = 1, 2. \quad (22)$$

As a next step, we use time-dependent perturbation theory to determine the leading order in τ corrections of $\Delta \mathcal{C}_\nu(n\tau)$. For this purpose, we write

$$e^{-iH_F t} = e^{-iHt} W(t), \quad W(t) = \mathcal{T} e^{-i \int_0^t dt' V(t')}, \quad (23)$$

with \mathcal{T} denoting the time-ordering prescription and

$$V(t) = e^{iHt} V e^{-iHt}, \quad V = \tau \mathcal{C}_1 + \tau^2 \mathcal{C}_2. \quad (24)$$

For the corrections to $\Delta E(n\tau)$ quadratic in τ , we need to perform time-dependent perturbation theory to first order in τ for \mathcal{C}_1 and can neglect any τ -dependent contributions for \mathcal{C}_2 .

Let us first consider $\Delta \mathcal{C}_1(n\tau)$, which gives

$$\Delta \mathcal{C}_1(n\tau) = \langle \mathcal{C}_1 \rangle - \langle \mathcal{C}_1(n\tau) \rangle - i\tau \int_0^{n\tau} dt' \langle [\mathcal{C}_1(t'), \mathcal{C}_1(n\tau)] \rangle. \quad (25)$$

The time integral can be conveniently evaluated by recognizing that

$$\mathcal{C}_1 = \frac{i}{2}[H_X, H_Z] = \frac{i}{2}[H, H_Z], \quad (26)$$

since $H = H_X + H_Z$, and thus

$$\mathcal{C}_1(t) = \frac{1}{2} \frac{d}{dt} H_Z(t). \quad (27)$$

This gives

$$\Delta \mathcal{C}_1(n\tau) = \langle \mathcal{C}_1 \rangle - \langle \mathcal{C}_1(n\tau) \rangle - \frac{i\tau}{2} \langle [H_Z(n\tau) - H_Z, \mathcal{C}_1(n\tau)] \rangle. \quad (28)$$

In the limit of $n \rightarrow \infty$, we can use the general property that expectation values of operators are governed by the so called diagonal ensemble [35]

$$\langle \mathcal{O}(n\tau) \rangle \xrightarrow{n \rightarrow \infty} \sum_\lambda p_\lambda \langle \lambda | \mathcal{O} | \lambda \rangle, \quad (29)$$

where $p_\lambda = |\langle \lambda | \psi_0 \rangle|^2$ and $|\lambda\rangle$ is a full set of eigenstates for the target Hamiltonian H . Using particular properties of the considered protocol, the above result for $\Delta \mathcal{C}_1(n\tau)$ can be simplified considerably. We can use, for example, that $\langle \mathcal{C}_1 \rangle = 0$ and $\langle [H_Z, \mathcal{C}_1(n\tau)] \rangle = 0$, because $|\psi_0\rangle$ is an eigenstate for H_Z , which finally yields

$$\Delta \mathcal{C}_1(n\tau) \xrightarrow{n \rightarrow \infty} -\frac{\tau}{4} \sum_\lambda p_\lambda \langle \lambda | [H_Z, [H_Z, H_X]] | \lambda \rangle. \quad (30)$$

For the contributions to $\Delta E(n\tau)$ that are second order in τ stemming from $\Delta \mathcal{C}_2(n\tau)$, we can restrict to the zeroth order in time-dependent perturbation theory for $\langle \mathcal{C}_2(n\tau) \rangle_\tau$, i.e., we can replace $\langle \mathcal{C}_2(n\tau) \rangle_\tau \rightarrow \langle \mathcal{C}_2(n\tau) \rangle$. This yields

$$\Delta \mathcal{C}_2(n\tau) \xrightarrow{n \rightarrow \infty} \langle \mathcal{C}_2 \rangle - \sum_\lambda p_\lambda \langle \lambda | \mathcal{C}_2 | \lambda \rangle. \quad (31)$$

Collecting all contributions, we finally obtain

$$Q_E = \frac{\Delta E}{E_{T=\infty} - E_0} = q_E (h\tau)^2 + \mathcal{O}[(h\tau)^3] \quad (32)$$

with

$$\begin{aligned} q_E &= \frac{1}{J^2 E_0} \left[\langle \mathcal{C}_2 \rangle - \sum_\lambda p_\lambda \langle \lambda | \mathcal{C}_2 | \lambda \rangle - \right. \\ &\quad \left. - \frac{1}{4} \sum_\lambda p_\lambda \langle \lambda | [H_Z, [H_Z, H_X]] | \lambda \rangle \right], \end{aligned} \quad (33)$$

where we have used that $E_{T=\infty} = 0$. This expression can be evaluated using full diagonalization, which provides access to all eigenstates $|\lambda\rangle$. For the considered parameters of our simulations, we find $q_E = 0.18$, which is consistent with the full dynamical calculation in the small Trotter step limit, see Fig. 3d.

For estimating the lowest-order corrections in τ for other observables such as the magnetization \mathcal{M} , we cannot make direct use of the emergent conserved quantity H_F as we could for the energy of the target Hamiltonian. Still, we can perform time-dependent perturbation theory, which we now have to carry out up to second order. Following the same steps as before, we obtain for the magnetization the following expression

$$\begin{aligned} \Delta \mathcal{M}(n\tau) &= \langle \mathcal{M}(n\tau) \rangle_\tau - \langle \mathcal{M}(n\tau) \rangle = \\ &= \frac{\tau^2}{12} [\langle \{H_Z^2(n\tau), \mathcal{M}(n\tau)\} \rangle - E_Z^2 \langle \mathcal{M}(n\tau) \rangle] \\ &\quad + i \frac{\tau^2}{6} \langle [\mathcal{C}_1(n\tau) - \mathcal{C}_1, \mathcal{M}(n\tau)] \rangle \\ &\quad - \frac{5\tau^2}{12} \int_0^{n\tau} dt \langle \mathcal{C}_1(t) H_Z(t) \mathcal{M}(n\tau) + \text{h.c.} \rangle. \end{aligned} \quad (34)$$

Here, $\{A, B\} = AB + BA$ denotes the anticommutator and E_Z is given by $H_Z|\psi_0\rangle = E_Z|\psi_0\rangle$. In the limit $n \rightarrow \infty$, we can again use that expectation values can be evaluated in the diagonal ensemble. In addition, the expression involving the time integral can be formally solved by using the Lehman representation. Finally, we obtain

$$\Delta\mathcal{M}(n\tau) \xrightarrow{n \rightarrow \infty} m(h\tau)^2 + \mathcal{O}[(h\tau)^3], \quad (35)$$

with

$$\begin{aligned} m = & \frac{1}{12J^2} \sum_{\lambda} p_{\lambda} \langle \lambda | \{H_Z^2, \mathcal{M}\} - E_Z^2 \mathcal{M} | \lambda \rangle \\ & - \frac{1}{6J^2} \sum_{\lambda} p_{\lambda} \text{Re}[\langle \lambda | [H_X, M] H_Z | \lambda \rangle] \\ & + \frac{1}{6J^2} \sum_{\lambda, \lambda'} \frac{p_{\lambda}}{E_{\lambda} - E_{\lambda'}} \text{Re}[\langle \lambda | [H_Z, H_X] H_Z | \lambda' \rangle \langle \lambda' | \mathcal{M} | \lambda \rangle] \\ & + \frac{1}{6J^2} \sum_{\lambda, \lambda'} \frac{\langle \lambda | \mathcal{M} | \lambda \rangle}{E_{\lambda} - E_{\lambda'}} \text{Re}[C_{\lambda} C_{\lambda'}^* \langle \lambda | [H_Z, H_X] H_Z | \lambda' \rangle], \end{aligned} \quad (36)$$

where $C_{\lambda} = \langle \lambda | \psi_0 \rangle$ and E_{λ} denotes the eigenenergies of the target Hamiltonian H corresponding to the eigenstate $|\lambda\rangle$. Using full diagonalization, we can again evaluate this expression yielding for our model a value of $m = 0.05$, which we have used in Fig. 3b for the asymptotic small τ prediction and which matches well the result from the full dynamics.

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Supplemental Material to

Quantum localization bounds Trotter errors in digital quantum simulation

In this supplementary material, we discuss the influence of two typical extrinsic sources for imperfections on digital quantum simulators.

S1. IMPERFECTIONS

As mentioned in the main text, realistic experimental realizations of DQS not only face imperfections due to Trotterization but are also subject to various other error sources. In this Section, we address two generic error sources and discuss their implications. First, a timing error which results from inaccurate gate lengths, and, second, an ensemble error originating from slow drifts of the gate couplings.

A. Timing error

Suppose that the gate length τ cannot be implemented perfectly but slightly fluctuates at each pulse. The gates performed at time step $p = 1 \dots n$ are then not the desired τH_l but rather gates of slightly different strength, $\tau(1 + \xi_l^p)H_l$, where ξ_l^p are independent random variables with vanishing mean and variance $\propto \eta$.

In Fig. S1, we show an example numerical simulation for the Ising model used in the main text, with such an additional timing noise drawn from a uniform distribution of width η . When rescaling the time axis with η^2 , we find a good collapse of the dynamics with slight deviations for large values of η . This finding implies that the accuracy of the DQS is not affected on a time scale proportional to η^{-1} but rather on a much longer time scale proportional to η^{-2} .

This scaling behavior can be understood by mapping the timing errors to a Master equation. With timing errors, the effective Hamiltonian of Eq. (3) of the main text depends on the time step p and reads $\mathcal{H}^p = \sum_l H_l + i\frac{\tau}{2} \sum_{l>m} [H_l, H_m] + \sum_l \xi_l^p H_l + \mathcal{O}((\tau + \xi)^2)$. Assuming the fluctuations to be uncorrelated between time steps and gates, $\langle \xi_l^p \xi_{l'}^{p'} \rangle = \delta_{l,l'} \delta_{p,p'} \eta^2$, and extending the definitions to continuous time $\xi_l(t) = \xi_l^p$, $t \in [p, p+1)\tau$, the

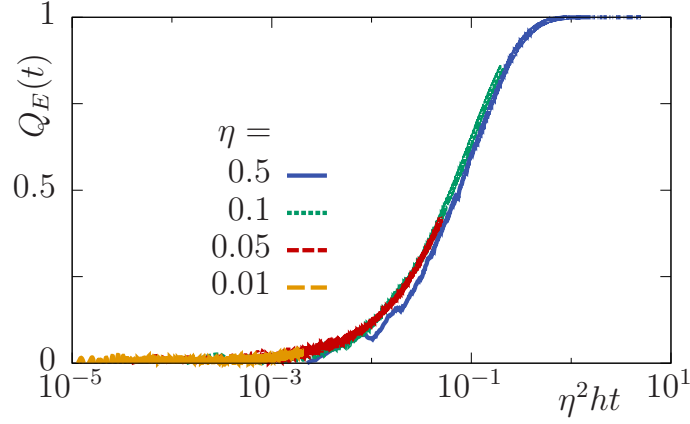


Figure S1: **Timing errors in the dynamics of the simulation accuracy $Q_E(t)$ for the Ising model.** This data has been obtained for $N = 18$ and varying noise strengths η by averaging over 100 noise realizations. The time axis has been rescaled with η^2 leading to a collapse of the data. As this shows, the time scale at which the timing error becomes relevant is proportional to η^{-2} .

fluctuating gates can be described as noise with power spectrum

$$\begin{aligned} S(\omega) &= \lim_{T \rightarrow \infty} \frac{1}{T} \int_0^T dt \int_0^T dt' e^{i\omega(t-t')} \langle \xi_l(t) \xi_{l'}(t') \rangle \\ &= \frac{2(1 - \cos(\omega\tau))}{(\omega\tau)^2} \eta^2 \tau. \end{aligned} \quad (\text{S1})$$

If the relevant frequencies in the many-body system are small compared to τ^{-1} , i.e., in the fast-driven regime that we are interested in, the power spectrum becomes flat, $S(\omega) = \eta^2 \tau (1 + \mathcal{O}((\omega\tau)^2))$, corresponding to white noise. In that regime, averaging over timing-error realizations, the time evolution of the system is to leading order described by an effective Markovian Master equation with Lindblad operators H_l , [44, 45]

$$\begin{aligned} \dot{\rho} &= -i[H + \tau \sum_{l>m} [H_l, H_m], \rho] \\ &\quad + \frac{\eta^2 \tau}{2} \sum_l (2H_l \rho H_l - H_l^2 \rho - \rho H_l^2). \end{aligned} \quad (\text{S2})$$

The first term describes the controlled time evolution under the effective Hamiltonian discussed in the main text, consisting of the time-averaged Hamiltonian H as well as the perturbation induced by Trotterization of strength $\sim \tau \|\sum_{l>m} [H_l, H_m]\|$. The fluctuating gate strengths, instead, lead to a heating of the system with a rate $\sim \eta^2 \tau \|\sum_l H_l^2\|$, i.e., suppressed by an additional factor η^2 . Thus, for times $t \ll 1/(\tau\eta^2)$ the influence of the timing error onto the dynamics is insignificant whereas for $t \gtrsim 1/(\tau\eta^2)$ it becomes severe.

B. Ensemble error

While the timing error leads to fast fluctuations of gate strengths, gate errors may also be correlated over long times due to slowly drifting experimental parameters. In the limit of very slow drifts, the gate strength can be taken as constant within one experimental run but as randomly changing between runs. Such errors can be taken into account by sampling the time evolution over a family of Hamiltonians $\tilde{H}_l = H_l + \Delta_l H_l$, where Δ_l are independent random variables with vanishing mean that are assumed constant for each run. Each of these Hamiltonians will generate a time evolution under slightly modified gates $\tilde{U}_l = \exp(-i\tilde{H}_l t)$. As opposed to the timing error, this ensemble error, however, does not lead to heating, but only averages the resulting expectation values over a range of slightly different Hamiltonians. In particular in the perturbative regime, this error will be rather benign, except when working in hypersensitive regimes where observables do not behave smoothly, such as close to quantum phase transitions.