Variational Characterization of Shapley Values

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Recap of Shapley values

Coalitional game¹

- Suppose there is a game played by a team (or "coalition") of players.
- A coalition game is
 - a set N consisting of n "players" and
 - a function $v: 2^N \to \mathbb{R}$, with $v(\emptyset) = 0$, assigning a value to any subset of players.
- Suppose the whole team plays and gets value v(N).
- Show should that value be allocated to the individuals on the team?
- Is there a fair way to do it that reflects the contributions of each individual?

¹Based on the Shapley value article in Wikipedia [Wik20] and [MP08].

- Where we're headed here is that we're going to apply this approach of "value allocation" to "coalitions" of feature "working together" to produce the final output.
- Of course, it's not really clear what it means to use a subset of features with a specific prediction function f(x).
- Various approaches to this will give us different feature interpretations.

Solutions to coalition games

- Let $\mathcal{G}(N)$ denote the set of all coalition games on set N.
 - i.e. a game for every possible $v: 2^N \to \mathbb{R}$.
- A solution to the allocation problem on the set $\mathfrak{G}(N)$ is a map $\Phi:\mathfrak{G}(N)\to\mathbb{R}^n$
 - gives the allocation to each of n players for any game $v \in \mathcal{G}(N)$.
- The Shapley value solution is $\Phi(v) = (\phi_i(v))_{i=1}^n$ where

$$\phi_i(v) = \sum_{S \subset (N-\{i\})} k_{|S|,n}(v(S \cup \{i\}) - v(S)),$$

where $k_{s,n} = s! (n-s-1)!/n!$.

The Shapley value solution is special

The Shapley value solution is the unique solution with the following properties:

- Efficiency: For any $v \in \mathcal{G}(N)$, $\sum_{i \in N} \phi_i(v) = v(N)$.
- Symmetry: For any $v \in \mathcal{G}(N)$, $\forall i, j \in N$, if $v(S \cup \{i\}) = v(S \cup \{j\})$ for every subset S of players that excludes i and j, then $\varphi_i(v) = \varphi_j(v)$.
- Linearity: For any $v, w \in \mathcal{G}(N)$, we have $\phi_i(v+w) = \phi_i(v) + \phi_i(w)$ for every player i in N. Also, for any $a \in \mathbb{R}$, $\phi_i(av) = a\phi_i(v)$ for every player i in N.
- Null: A player i is null in v if $v(S \cup \{i\}) = v(S)$ for all coalitions $S \subset N$. If player i is null in a game v, then $\phi_i(v) = 0$.
- That's all very nice... but doesn't give me much intuition on what the values are.
- Shapley values are the sum of exponentially many terms, with mysterious weights.

Reformulation of Shapley values

A set function from Shapley values

- Shapley values are defined for a given set function v(S).
- Turns out, we can use the Shapley values to define a new set function:

$$w(S) := \sum_{i \in S} \phi_i(v),$$

with the convention that an empty sum is 0.

- Is there a relation between w(S) and v(S)?
- At the extremes, they agree:
 - $w(\emptyset) = v(\emptyset) = 0$ by construction of w.
 - w(N) = v(N) by the efficiency property of Shapley values.
- Does w(S) approximate v(S) in general?
- If so, can we derive Shapley values as the solution to an optimization problem?

Fitting a set function

• Let's define a new set function on $S \subset N$:

$$w(S) := \sum_{i \in S} w_i,$$

for some $w \in \mathbb{R}^n$, with the convention that an empty sum is 0.

• Consider the following objective function on $w \in \mathbb{R}^n$:

$$J(w) = \sum_{S \subset N} [w(S) - v(S)]^2 q(|S|),$$

where $q:\{1,\ldots,n-1\}\to\mathbb{R}$ is an arbitrary weight function (but not identically 0).

- This is a weighted least squares fit of w(S) to v(S).
- Note that the weight corresponding to *S* depends only on the size of *S*.
- We've intentionally left q(0) and q(n) undefined, as they won't matter...

Generalized Shapley values

Theorem ([CGKR88, Thm 3])

The $w \in \mathbb{R}^n$ that minimizes

$$J(w) = \sum_{S \subset N} [w(S) - v(S)]^2 q(|S|),$$

subject to the constraint that w(N) = v(N) is

$$w_i = \frac{v(N)}{n} + \frac{1}{\beta} \left(\sum_{S \subset N: i \in S} v(S) q(|S|) - \frac{1}{n} \sum_{i=1}^n \sum_{S \subset N: i \in S} v(S) q(|S|) \right),$$

where $\beta = \sum_{s=1}^{n-1} q(s) \binom{n-2}{s-1}$, provided $\beta \neq 0$.

• The w_i 's are called generalized Shapley values.

- Note that q(0) and q(n) can take any values in the objective function without affecting the results since
 - $w(\emptyset) = v(\emptyset) = 0$ by construction of w(S) and w(N) = v(N) by the constraint.
- = v(v) = v(v) by the constraint.
- The notation in the paper is different, but here we've translated it to our notation.

A quadratic optimization for Shapley values

• If we take $q(s) = c\binom{n-2}{s-1}^{-1}$, for any $c \neq 0$, then

$$w_i = \sum_{S \subset (N-\{i\})} k_{|S|,n} [v(S \cup \{i\}) - v(S)],$$

where
$$k_{s,n} = \frac{1}{s+1} {n \choose s+1}^{-1} = s! (n-s-1)!/n!$$
 [CGKR88, Thm 4].

- That is, w_i are the Shapley values!
- So for the right choice of weight function q(s), we can find all n Shapley values by minimizing
 - the quadratic objective $J(w) = \sum_{S \subset N} [w(S) v(S)]^2 q(|S|)$,
 - subject to the constraint w(N) = v(N).
- Issue: The objective function has 2^n terms.

Theorem ([CGKR88, Thm 4])

If we choose $q(s) = c \binom{n-2}{s-1}^{-1}$ for any $c \neq 0$, then the solution to the constrained optimization problem stated above is

$$w_{i} = \frac{1}{n} \sum_{S \subset N: i \in S} {\binom{n-1}{|S|-1}}^{-1} [v(S) - v(S - \{i\})]$$

$$= \sum_{S \subset (N - \{i\})} k_{|S|,n} [v(S \cup \{i\}) - v(S)],$$

where
$$k_{s,n} = \frac{1}{s+1} {n \choose s+1}^{-1} = \frac{1}{n} {n-1 \choose s-1}^{-1} = s! (n-s-1)!/n!$$
. And so w_i are the Shapley values.

- The notation in [CGKR88, Thm 4] is different, but here we've translated it to our notation. There are many equivalent formulations of Shapley values, so we've tried to give a variety here. The last one matches our original definition.
- With a few lines of algebra and taking $c = \frac{1}{n}$, one can show this result is equivalent to [LL17, Thm 2].

Finding the Shapley values

Dropping the constraint

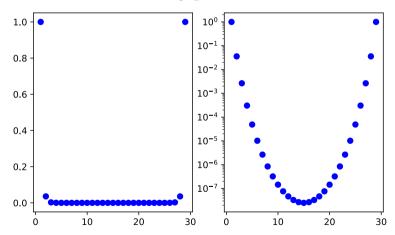
The generalized Shapley value objective is

$$J(w) = \sum_{S \subset N} [w(S) - v(S)]^2 q(|S|).$$

- We have the constraint that $w(N) = \sum_{i=1}^{n} w_i = v(N)$.
- An easy way to enforce the equality constraint is to eliminate a variable.
- Let's eliminate a variable by setting $w_n = v(N) \sum_{i=1}^{n-1} w_i$.
- With this substitution, we no longer need an explicit constraint that w(N) = v(N).
- We can take q(0) = q(n) = 0, without affecting the result.

The weights for the Shapley kernel

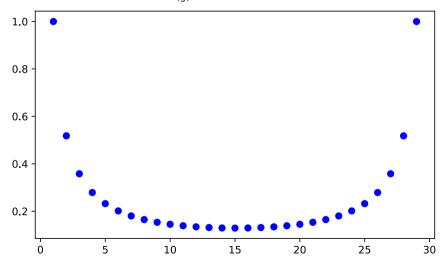
• For n = 30, let $q(s) = \binom{n-2}{s-1}^{-1}$ be the Shapley weight function.



- This is a plot of the weight function q(s) on $\{1, 2, ..., 29\}$. As noted, we can take q(0) = q(30) = 0 in our optimization.
- At first it seems like almost all the weight of the objective function is concentrated on the smallest and largest sets.
- This is true, but it's not immediate from these plots. Remember that there are also far more subsets of intermediate sizes than extreme sizes.

Total weight by subset size

• For n = 30, let $w(s) = \binom{n}{s} q(s)$ be the total weight for subsets of each size.



- This is a plot of the total weight for all subsets of each size s, on $\{1, 2, ..., 29\}$.
- That is, we're plotting $w(s) = \binom{n}{s} q(s) = \binom{n}{s} \binom{n-2}{s-1}^{-1}$

$$w(s) = \binom{n}{s} \binom{n-2}{s-1}^{-1} = \frac{n!}{s!(n-s)!} \frac{(s-1)!(n-s-1)!}{(n-2)!}$$
$$= \frac{n(n-1)}{s(n-s)}$$

• So most of the weight is on the small and large sets, but there is nontrivial weight throughout the range..

Approximate the objective function

- The objective function has 2^n terms,
 - which quickly becomes too large to handle exactly.
- We can approximate the objective function in many different ways.
- In SHAP, they use a combination of direct computation and random sampling.

Hybrid approach

We can compute

$$J_2(w) := \sum_{S: |S| \in \{1, 2, (n-2), n-1)\}} [w(S) - v(S)]^2 q(|S|).$$

• And then use random sampling to estimate the rest:

$$J_{-2}(w) := \sum_{S:3 \leqslant |S| \leqslant (n-3)} [w(S) - v(S)]^2 q(|S|).$$

How?

Using random sampling

- Define a probability mass function on $\{S: 3 \leq |S| \leq (n-3)\}$,
 - such that p(S) = kq(|S|) for some k > 0.
- Then

$$J_{-2}(w) = \frac{1}{k} \sum_{S:3 \leq |S| \leq (n-3)} [w(S) - v(S)]^2 p(S)$$
$$= \frac{1}{k} \mathbb{E}_{S \sim p} [w(S) - v(S)]^2$$

- We can now sample S_1, \ldots, S_r from p to get a Monte Carlo estimate of $J_{-2}(w)$.
- (This is just one approach to get the idea not exactly how SHAP does it.)

Optimizing our approximate objective

Our final objective function would be

$$J(w) = \sum_{S: |S| \in \{1, 2, (n-2), n-1)\}} [w(S) - v(S)]^2 q(|S|) + \frac{1}{kr} \sum_{i=1}^r [w(S_r) - v(S_r)]^2.$$

- Now we have a quadratic objective of manageable size.
- We can use a standard optimization method.
- Or we can differentiate, set to zero, and end up with a weighted least squares problem.
- This is the idea of Kernel SHAP.
- For the exact implementation details, see SHAP code. The details aren't in [LL17].

References

Resources

- The ideas in the reformulation of Shapley values and generalized Shapley values are from [CGKR88]. However, I found Yuchen Pei's blog post to be very helpful in understanding the proofs in the paper by Charnes et al [CGKR88].
- The approach to finding the Shapley values is based on the implementation of Kernel SHAP in the SHAP GitHub repo. Although this is not a fully faithful representation of what they do, it should capture the mathematical ideas involved. I also looked at the description of Kernel SHAP in [AJL21, p. 5], but their representation is even less faithful to the actual implementation, as best as I can tell.

References I

- [AJL21] Kjersti Aas, Martin Jullum, and Anders Løland, Explaining individual predictions when features are dependent: More accurate approximations to shapley values, Artificial Intelligence 298 (2021), 103502.
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- [MP08] Stefano Moretti and Fioravante Patrone, *Transversality of the shapley value*, TOP **16** (2008), no. 1, 1–41.
- [Wik20] Wikipedia contributors, Shapley value Wikipedia, the free encyclopedia, 2020, [https://en.wikipedia.org/wiki/Shapley_value; accessed 26-April-2021].