



# Self-Assembled Lipid Bilayer Membranes: Exploring a Single-Bead Model

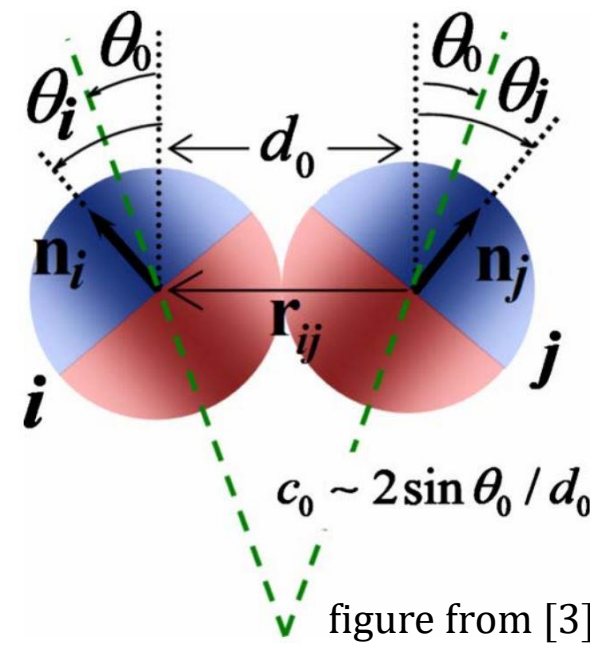
D.A. Rower, P. J. Atzberger,

Department of Mathematics, Department of Mechanical Engineering, UC Santa Barbara.

## Motivations

- **Kinetics** of lipid bilayer membranes are important in many biological processes.
  - raft formation
  - budding
  - endocytosis
- **Coarse-grained models** allow for computational efficiency for practical investigations.
- **Highly tunable models** allow for the exploration of different phases and kinetic regimes.
- **Many types** of coarse-grained models
  - represent atomic groups as CG units.
  - represent several lipid molecules as one bead.
  - implicitly handle solvent degrees of freedom.

## Pairwise Potential Function



### Overview

- Particle separation and relative orientation dictate interaction.
- Soft-Sphere potential used for translational separation.

### Interaction Potentials

$$U(\mathbf{r}_{ij}, \mathbf{n}_i, \mathbf{n}_j) = \begin{cases} u_R(r) + [1 - \phi(\hat{\mathbf{r}}_{ij}, \mathbf{n}_i, \mathbf{n}_j)]\epsilon, & r < r_{\min} \\ u_A(r)\phi(\hat{\mathbf{r}}_{ij}, \mathbf{n}_i, \mathbf{n}_j), & r_{\min} < r < r_c \end{cases}$$

$$u(r) = \begin{cases} u_R(r) = \epsilon \left[ \left( \frac{r_{\min}}{r} \right)^4 - 2 \left( \frac{r_{\min}}{r} \right)^2 \right], & r < r_{\min} \\ u_A(r) = -\epsilon \cos^2 \zeta \left[ \frac{\pi}{2} \frac{(r - r_{\min})}{(r_c - r_{\min})} \right], & r_{\min} < r < r_c \end{cases}$$

$$a = (\mathbf{n}_i \times \hat{\mathbf{r}}_{ij}) \cdot (\mathbf{n}_j \times \hat{\mathbf{r}}_{ij}) + \sin \theta_0 (\mathbf{n}_j - \mathbf{n}_i) \cdot \hat{\mathbf{r}}_{ij} - \sin^2 \theta_0$$

$$\phi = 1 + \mu[a(\hat{\mathbf{r}}_{ij}, \mathbf{n}_i, \mathbf{n}_j) - 1]$$

More details in [1,2].

## Langevin Dynamics

In order to run simulations in the canonical ensemble (NVT), modified equations of motion are used.

### Langevin Equations

$$m\ddot{\mathbf{r}} = -\nabla_r U - \zeta_r \dot{\mathbf{r}} + \mathbf{F}_r(t)$$

$$I\ddot{\mathbf{n}} = -\nabla_n U - \zeta_n \dot{\mathbf{n}} + \mathbf{F}_n(t)$$

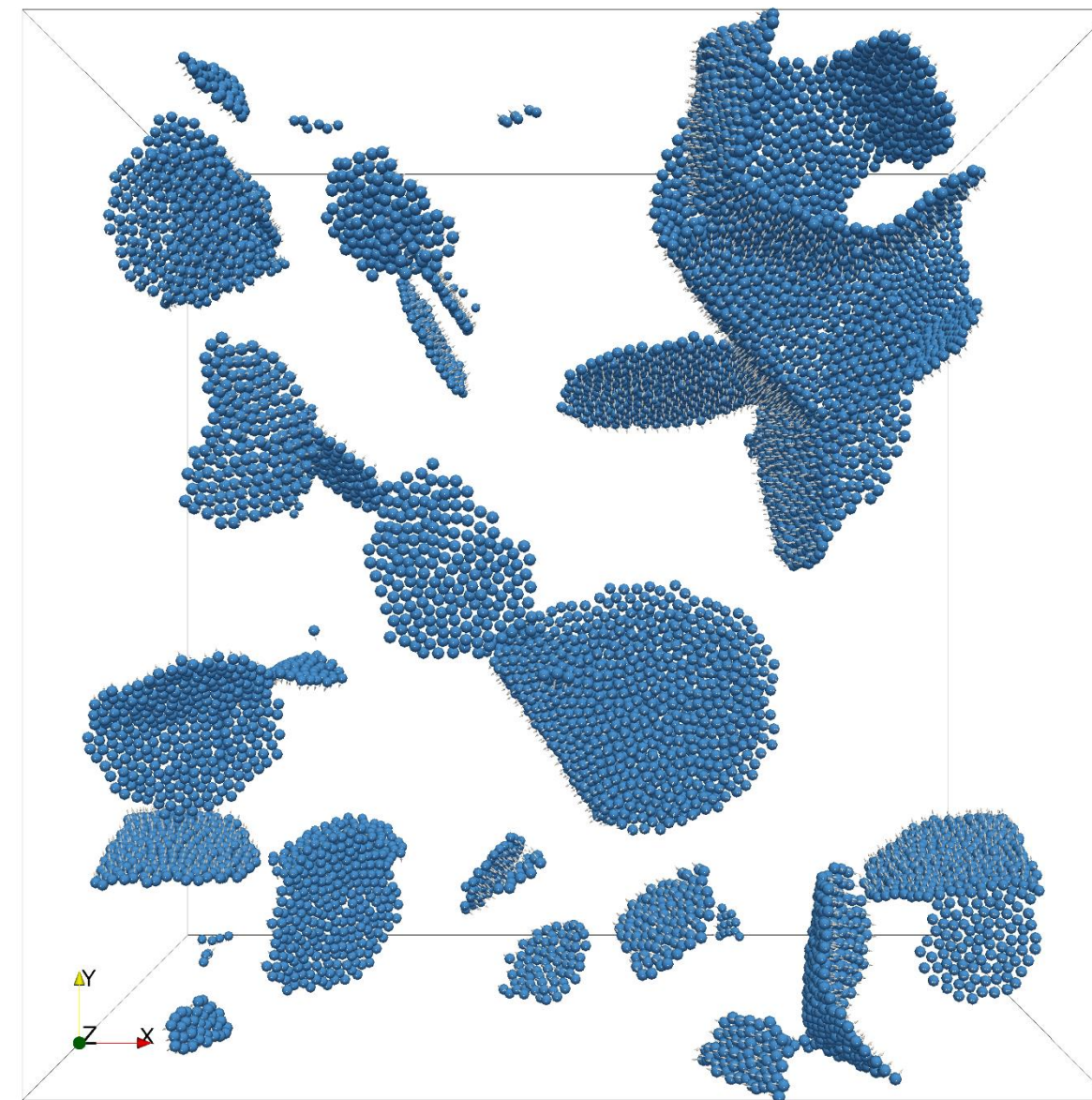
$$\langle \mathbf{F}_r(t) \mathbf{F}_r(t') \rangle = 2k_B T \zeta_r \delta(t - t')$$

$$\langle \mathbf{F}_n(t) \mathbf{F}_n(t') \rangle = 2k_B T \zeta_n \delta(t - t')$$

- Each particle experiences a stochastic force.
  - Random noise from the implicit solvent.
- The stochastic force is proportional to temperature and drag coefficient.

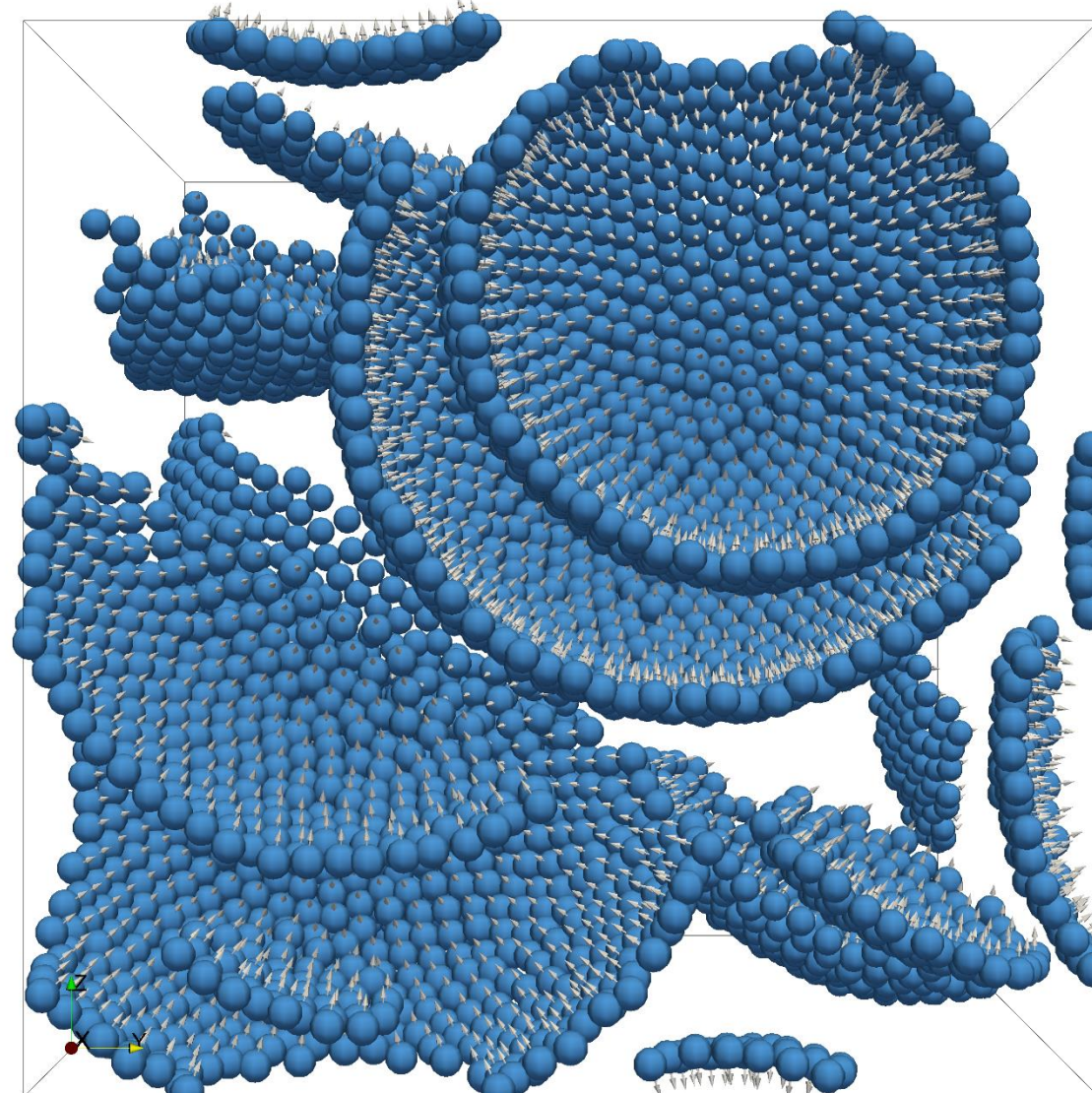
## Self-Assembling Sheets and Vesicles

### Sheets



- Sheets bend due to thermal forces and the edge effect
- Over time, sheets coalesce to form larger sheets

### Spherical Vesicles (imposed curvature)



## Parametrization

### Potential Parameters

$r_c$ : interaction cutoff distance  
 $\mu$ : penalty for non-preferred orientation  
 $\zeta$ : steepness of repulsive branch  
 $\theta_0$ : preferred relative orientation

### Simulation Parameters

$\zeta_{r,n}$ : dampening coefficients for Langevin Equation  
 $\Delta t$ : timestep for simulation  
 $k_B T$ : temperature of system

### Reduced Units

To keep all quantities in a reasonable numerical range, all values computed are unitless, and are given in terms of combinations of three physical scales. Units can be found by picking values for these characteristic scales.

$\epsilon$ : energy  
 $\sigma$ : length  
 $m$ : mass of a bead

## Velocity Verlet Integration Scheme

Translation: 
$$\begin{cases} \mathbf{v}^{n+\frac{1}{2}} = \mathbf{v}^n + \frac{\Delta t}{2} \mathbf{a}^n \\ \mathbf{r}^{n+1} = \mathbf{r}^n + \Delta t \mathbf{v}^{n+\frac{1}{2}} \end{cases}$$

Rotation: 
$$\begin{cases} \mathbf{l}^{n+\frac{1}{2}} = \mathbf{l}^n + \frac{\Delta t}{2} \boldsymbol{\tau}^n \\ \mathbf{l}^{n+\frac{1}{2}} \rightarrow \boldsymbol{\omega}^{n+\frac{1}{2}}, \quad \mathbf{q}^n \rightarrow \hat{\mathbf{n}}^n \\ \hat{\mathbf{n}}^{*,n+1} = \hat{\mathbf{n}}^n + \Delta t \boldsymbol{\omega}^{n+\frac{1}{2}}, \quad \hat{\mathbf{n}}^{n+1} = \frac{\hat{\mathbf{n}}^{*,n+1}}{|\hat{\mathbf{n}}^{*,n+1}|} \\ \hat{\mathbf{n}}^{n+1} \rightarrow \mathbf{q}^{n+1} \end{cases}$$

Forces are then recalculated on each particle, and the final velocity and angular velocity vectors are calculated with

$$\begin{cases} \mathbf{v}^{n+1} = \mathbf{v}^{n+\frac{1}{2}} + \frac{\Delta t}{2} \mathbf{a}^{n+1} \\ \mathbf{l}^{n+1} = \mathbf{l}^{n+\frac{1}{2}} + \frac{\Delta t}{2} \boldsymbol{\tau}^{n+1} \end{cases}$$

Global error for position and velocity is  $O(\Delta t^2)$ .

## Summary and References

### Summary

- Implemented model and Velocity Verlet integrator for orientations in LAMMPS.
- Self-assembling sheets in large parameter ranges.
- Forced spherical vesicle formation.
- Checking consistency between Nose-Hoover thermostat and Langevin equation for canonical ensemble simulations.
- Exploring properties of spherical vesicles.

### References

1. **Computer Simulations of Self-Assembled Membranes**, J.-M. Drouffe, A. C. Maggs and S. Leibler, Science, (1991).
2. **Fluid Membranes Can Drive Linear Aggregation of Adsorbed Spherical Nanoparticles**, An'ela S'aric' and Angelo Cacciuto, Phys. Rev. E., (2012).
3. **One-particle-thick, Solvent-free, Coarse-grained Model for Biological and Biomimetic Fluid Membranes**, Hongyan Yuan, Changjin Huang, Ju Li, George Lykotrafitis, and Sulin Zhang, Phys. Rev. E, (2010).