

## Basics

### Fundamental Assumption

Data is iid for unknown  $P$ :  $(x_i, y_i) \sim P(X, Y)$

### True risk and estimated error

True risk:  $R(w) = \int P(x, y)(y - w^T x)^2 dx dy = \mathbb{E}_{x, y}[(y - w^T x)^2]$

Est. error:  $\hat{R}_D(w) = \frac{1}{|D|} \sum_{(x, y) \in D} (y - w^T x)^2$

### Standardization

Centered data with unit variance:  $\tilde{x}_i = \frac{x_i - \hat{\mu}}{\hat{\sigma}}$

$\hat{\mu} = \frac{1}{n} \sum_{i=1}^n x_i$ ,  $\hat{\sigma}^2 = \frac{1}{n} \sum_{i=1}^n (x_i - \hat{\mu})^2$

### Cross-Validation

For all models  $m$ , for all  $i \in \{1, \dots, k\}$  do:

1. Split data:  $D = D_{train}^{(i)} \cup D_{test}^{(i)}$  (Monte-Carlo or k-Fold)

2. Train model:  $\hat{w}_{i,m} = \underset{w}{\operatorname{argmin}} \hat{R}_{train}^{(i)}(w)$

3. Estimate error:  $\hat{R}_m^{(i)} = \hat{R}_{test}^{(i)}(\hat{w}_{i,m})$

Select best model:  $\hat{m} = \underset{m}{\operatorname{argmin}} \frac{1}{k} \sum_{i=1}^k \hat{R}_m^{(i)}$

### Parametric vs. Nonparametric models

*Parametric*: have finite set of parameters. e.g. linear regression, linear perceptron

*Nonparametric*: grow in complexity with the size of the data, more expressive. e.g. k-NN

### Gradient Descent

1. Pick arbitrary  $w_0 \in \mathbb{R}^d$

2.  $w_{t+1} = w_t - \eta_t \nabla \hat{R}(w_t)$

### Stochastic Gradient Descent (SGD)

1. Pick arbitrary  $w_0 \in \mathbb{R}^d$

2.  $w_{t+1} = w_t - \eta_t \nabla_w l(w_t; x', y')$ , with u.a.r. data point  $(x', y') \in D$

### Regression

Solve  $w^* = \underset{w}{\operatorname{argmin}} \hat{R}(w) + \lambda C(w)$

### Linear Regression

$\hat{R}(w) = \sum_{i=1}^n (y_i - w^T x_i)^2 = \|Xw - y\|_2^2$

$\nabla_w \hat{R}(w) = -2 \sum_{i=1}^n (y_i - w^T x_i) \cdot x_i$

$w^* = (X^T X)^{-1} X^T y$

### Ridge regression

$\hat{R}(w) = \sum_{i=1}^n (y_i - w^T x_i)^2 + \lambda \|w\|_2^2$

$\nabla_w \hat{R}(w) = -2 \sum_{i=1}^n (y_i - w^T x_i) \cdot x_i + 2\lambda w$

$w^* = (X^T X + \lambda I)^{-1} X^T y$

### L1-regularized regression (Lasso)

$\hat{R}(w) = \sum_{i=1}^n (y_i - w^T x_i)^2 + \lambda \|w\|_1$

### Classification

Solve  $w^* = \underset{w}{\operatorname{argmin}} l(w; x_i, y_i)$ ; loss function  $l$

### Loss functions

•  $l_{0/1}(y, x) = 1$  if  $y \neq \operatorname{sign}(w^T x)$  else 0

•  $l_{\text{hinge}}(z) = \max(0, 1 - z)$

•  $l_{\text{squared}}(z) = (1 - z)^2$

•  $l_{\text{logistic}}(z) = \log(1 + e^{-z})$

•  $l_{\text{exp}}(z) = e^{-z}$

### Perceptron algorithm

Use  $l_P(w; y_i, x_i) = \max(0, -y_i w^T x_i)$  and SGD

$\nabla_w l_P(w; y_i, x_i) = \begin{cases} 0 & \text{if } y_i w^T x_i \geq 0 \\ -y_i x_i & \text{otherwise} \end{cases}$

Data lin. separable  $\Leftrightarrow$  obtains a lin. separator (not necessarily optimal)

### Support Vector Machine (SVM)

Hinge loss:  $l_H(w; x_i, y_i) = \max(0, 1 - y_i w^T x_i)$

$\nabla_w l_H(w; y, x) = \begin{cases} 0 & \text{if } y_i w^T x_i \geq 1 \\ -y_i x_i & \text{otherwise} \end{cases}$

$w^* = \underset{w}{\operatorname{argmin}} l_H(w; x_i, y_i) + \lambda \|w\|_2^2$

### Kernels

efficient, implicit inner products

### Properties of kernel

$k: \mathcal{X} \times \mathcal{X} \rightarrow \mathbb{R}$ ,  $k$  must be some inner product (symmetric, positive-definite, linear) for some

space  $\mathcal{V}$ . i.e.  $k(\mathbf{x}, \mathbf{x}') = \langle \varphi(\mathbf{x}), \varphi(\mathbf{x}') \rangle_{\mathcal{V}} \stackrel{\text{Eucl.}}{=} \varphi(\mathbf{x})^T \varphi(\mathbf{x}')$  and  $k(\mathbf{x}, \mathbf{x}') = k(\mathbf{x}', \mathbf{x})$

### Kernel matrix

$K = \begin{bmatrix} k(x_1, x_1) & \dots & k(x_1, x_n) \\ \vdots & \ddots & \vdots \\ k(x_n, x_1) & \dots & k(x_n, x_n) \end{bmatrix}$

Positive semi-definite matrices  $\Leftrightarrow$  kernels  $k$

### Important kernels

Linear:  $k(x, y) = x^T y$

Polynomial:  $k(x, y) = (x^T y + 1)^d$

Gaussian:  $k(x, y) = \exp(-\|x - y\|_2^2 / (2h^2))$

Laplacian:  $k(x, y) = \exp(-\|x - y\|_1 / h)$

### Composition rules

Valid kernels  $k_1, k_2$ , also valid kernels:  $k_1 + k_2$ ;  $k_1 \cdot k_2$ ;  $c \cdot k_1$ ,  $c > 0$ ;  $f(k_1)$  if  $f$  polynomial with pos. coeffs. or exponential

### Reformulating the perceptron

Ansatz:  $w^* \in \operatorname{span}(X) \Rightarrow w = \sum_{j=1}^n \alpha_j y_j x_j$

$\alpha^* = \underset{\alpha \in \mathbb{R}^n}{\operatorname{argmin}} \sum_{i=1}^n \max(0, -\sum_{j=1}^n \alpha_j y_i y_j x_i^T x_j)$

### Kernelized perceptron and SVM

Use  $\alpha^T k_i$  instead of  $w^T x_i$ ,

use  $\alpha^T D_y K D_y \alpha$  instead of  $\|w\|_2^2$

$k_i = [y_1 k(x_i, x_1), \dots, y_n k(x_i, x_n)]$ ,  $D_y = \operatorname{diag}(y)$

Prediction:  $\hat{y} = \operatorname{sign}(\sum_{i=1}^n \alpha_i y_i k(x_i, \hat{x}))$

SGD update:  $\alpha_{t+1} = \alpha_t$ , if mispredicted:

$\alpha_{t+1, i} = \alpha_{t, i} + \eta_t$  (c.f. updating weights towards mispredicted point)

### Kernelized linear regression (KLR)

Ansatz:  $w^* = \sum_{i=1}^n \alpha_i x_i$

$\alpha^* = \underset{\alpha}{\operatorname{argmin}} \|\alpha^T K - y\|_2^2 + \lambda \alpha^T K \alpha$

$= (K + \lambda I)^{-1} y$

Prediction:  $\hat{y} = \sum_{i=1}^n \alpha_i k(x_i, \hat{x})$

### k-NN

$y = \operatorname{sign}(\sum_{i=1}^n y_i [x_i \text{ among } k \text{ nearest neighbours of } x])$  – No weights  $\Rightarrow$  no training!

But depends on all data : (

### Imbalance

up-/downsampling

### Cost-Sensitive Classification

Scale loss by cost:  $l_{CS}(w; x, y) = c_{\pm} l(w; x, y)$

### Metrics

$n = n_+ + n_-$ ,  $n_+ = TP + FN$ ,  $n_- = TN + FP$

Accuracy:  $\frac{TP + TN}{n}$ , Precision:  $\frac{TP}{TP + FP}$

Recall/TPR:  $\frac{TP}{n_+}$ , FPR:  $\frac{FP}{n_-}$

F1 score:  $\frac{2TP}{2TP + FP + FN} = \frac{2}{\frac{1}{\text{prec}} + \frac{1}{\text{rec}}}$

ROC Curve:  $y = \text{TPR}$ ,  $x = \text{FPR}$

### Multi-class

one-vs-all ( $c$ ), one-vs-one ( $\frac{c(c-1)}{2}$ ), encoding

### Multi-class Hinge loss

$l_{MC-H}(w^{(1)}, \dots, w^{(c)}; x, y) =$

$\max(0, 1 + \max_{j \in \{1, \dots, y-1, y+1, \dots, c\}} w^{(j)T} x - w^{(y)T} x)$

### Neural networks

Parameterize feature map with  $\theta$ :  $\phi(x, \theta) = \varphi(\theta^T x) = \varphi(z)$  (activation function  $\varphi$ )  
 $\Rightarrow w^* = \underset{w, \theta}{\operatorname{argmin}} \sum_{i=1}^n l(y_i; \sum_{j=1}^m w_j \phi(x_i, \theta_j))$

$f(x; w, \theta_{1:d}) = \sum_{j=1}^m w_j \varphi(\theta_j^T x) = w^T \varphi(\Theta x)$

### Activation functions

Sigmoid:  $\frac{1}{1 + \exp(-z)}$ ,  $\varphi'(z) = (1 - \varphi(z)) \cdot \varphi(z)$

tanh:  $\varphi(z) = \tanh(z) = \frac{\exp(z) - \exp(-z)}{\exp(z) + \exp(-z)}$

ReLU:  $\varphi(z) = \max(z, 0)$

### Predict: forward propagation

$v^{(0)} = x$ ; for  $l = 1, \dots, L-1$ :

$v^{(l)} = \varphi(z^{(l)})$ ,  $z^{(l)} = W^{(l)} v^{(l-1)}$

$f = W^{(L)} v^{(L-1)}$

Predict  $f$  for regression,  $\operatorname{sign}(f)$  for class.

### Compute gradient: backpropagation

Output layer:  $\delta_j = l'_j(f_j)$ ,  $\frac{\partial}{\partial w_{ji}} = \delta_j v_i$

Hidden layer  $l = L-1, \dots, 1$ :

$\delta_j = \varphi'(z_j) \cdot \sum_{i \in \text{Layer}_{l+1}} w_{ij} \delta_i$ ,  $\frac{\partial}{\partial w_{ji}} = \delta_j v_i$

### Learning with momentum

$a \leftarrow m \cdot a + \eta_t \nabla_W l(W; y, x)$ ;  $W_{t+1} \leftarrow W_t - a$

### Clustering

#### k-mean

$\hat{R}(\mu) = \sum_{i=1}^n \min_{j \in \{1, \dots, k\}} \|x_i - \mu_j\|_2^2$

$\hat{\mu} = \underset{\mu}{\operatorname{argmin}} \hat{R}(\mu)$  ...non-convex, NP-hard

Algorithm (Lloyd's heuristic): Choose starting centers, assign points to closest center, update centers to mean of each cluster, repeat

### Dimension reduction

#### PCA

$D = x_1, \dots, x_n \subset \mathbb{R}^d$ ,  $\Sigma = \frac{1}{n} \sum_{i=1}^n x_i x_i^T$ ,  $\mu = 0$

$(W, z_1, \dots, z_n) = \underset{W, z}{\operatorname{argmin}} \sum_{i=1}^n \|W z_i - x_i\|_2^2$ ,

$W = (v_1 | \dots | v_k) \in \mathbb{R}^{d \times k}$ , orthogonal;  $z_i = W^T x_i$

$v_i$  are the eigen vectors of  $\Sigma$

#### Kernel PCA

Kernel PC:  $\alpha^{(1)}, \dots, \alpha^{(k)} \in \mathbb{R}^n$ ,  $\alpha^{(i)} = \frac{1}{\sqrt{\lambda_i}} v_i$ ,

$K = \sum_{i=1}^n \lambda_i v_i v_i^T$ ,  $\lambda_1 \geq \dots \geq \lambda_d \geq 0$

New point:  $\hat{z} = f(\hat{x}) = \sum_{j=1}^n \alpha_j^{(i)} k(\hat{x}, x_j)$

## Autoencoders

Find identity function:  $x \approx f(x; \theta)$

$$f(x; \theta) = f_{\text{decode}}(f_{\text{encode}}(x; \theta_{\text{encode}}); \theta_{\text{decode}})$$

## Probability modeling

Find  $h: X \rightarrow Y$  that min. pred. error:  $R(h) = \int P(x, y) l(y; h(x)) dy x \partial y = \mathbb{E}_{x, y} [l(y; h(x))]$

## For least squares regression

Best  $h$ :  $h^*(x) = \mathbb{E}[Y|X=x]$

Pred.:  $\hat{y} = \hat{\mathbb{E}}[Y|X=\hat{x}] = \int \hat{P}(y|X=\hat{x}) y \partial y$

## Maximum Likelihood Estimation (MLE)

$$\theta^* = \underset{\theta}{\operatorname{argmax}} \hat{P}(y_1, \dots, y_n | x_1, \dots, x_n, \theta)$$

E.g. lin. + Gauss:  $y_i = w^T x_i + \varepsilon_i, \varepsilon_i \sim \mathcal{N}(0, \sigma^2)$

i.e.  $y_i \sim \mathcal{N}(w^T x_i, \sigma^2)$ , With MLE (use  $\operatorname{argmin} -\log$ ):  $w^* = \underset{w}{\operatorname{argmin}} \sum (y_i - w^T x_i)^2$

## Bias/Variance/Noise

Prediction error =  $\text{Bias}^2 + \text{Variance} + \text{Noise}$

## Maximum a posteriori estimate (MAP)

Assume bias on parameters, e.g.  $w_i \in \mathcal{N}(0, \beta^2)$

$$\text{Bay.}: P(w|x, y) = \frac{P(w|x)P(y|x, w)}{P(y|x)} = \frac{P(w)P(y|x, w)}{P(y|x)}$$

## Logistic regression

Link func.:  $\sigma(w^T x) = \frac{1}{1 + \exp(-w^T x)}$  (Sigmoid)

$$P(y|x, w) = \text{Ber}(y; \sigma(w^T x)) = \frac{1}{1 + \exp(-y w^T x)}$$

Classification: Use  $P(y|x, w)$ , predict most likely class label.

MLE:  $\underset{w}{\operatorname{argmax}} P(y_{1:n} | w, x_{1:n})$

$$\Rightarrow w^* = \underset{w}{\operatorname{argmin}} \sum_{i=1}^n \log(1 + \exp(-y_i w^T x_i))$$

SGD update:  $w = w + \eta_t y x \hat{P}(Y = -y | w, x)$

$$\hat{P}(Y = -y | w, x) = \frac{1}{1 + \exp(y w^T x)}$$

MAP: Gauss. prior  $\Rightarrow \|w\|_2^2$ , Lap. p.  $\Rightarrow \|w\|_1$

SGD:  $w = w(1 - 2\lambda \eta_t) + \eta_t y x \hat{P}(Y = -y | w, x)$

## Bayesian decision theory

- Conditional distribution over labels  $P(y|x)$

- Set of actions  $\mathcal{A}$

- Cost function  $C: Y \times \mathcal{A} \rightarrow \mathbb{R}$

$$a^* = \underset{a \in \mathcal{A}}{\operatorname{argmin}} \mathbb{E}[C(y, a) | x]$$

Calculate  $\mathbb{E}$  via sum/integral.

Classification:  $C(y, a) = [y \neq a]$ ; asymmetric:

$$C(y, a) = \begin{cases} c_{FP}, & \text{if } y = -1, a = +1 \\ c_{FN}, & \text{if } y = +1, a = -1 \\ 0, & \text{otherwise} \end{cases}$$

Regression:  $C(y, a) = (y - a)^2$ ; asymmetric:

$$C(y, a) = c_1 \max(y - a, 0) + c_2 \max(a - y, 0)$$

E.g.  $y \in \{-1, +1\}$ , predict  $+$  if  $c_+ < c_-$ ,  $c_+ = \mathbb{E}(C(y, +1) | x) = P(y = 1 | x) \cdot 0 + P(y = -1 | x) \cdot c_{FP}$ ,  $c_-$  likewise

## Discriminative / generative modeling

Discr. estimate  $P(y|x)$ , generative  $P(y, x)$

Approach (generative):  $P(x, y) = P(x|y) \cdot P(y)$  - Estimate prior on labels  $P(y)$

- Estimate cond. distr.  $P(x|y)$  for each class  $y$

- Pred. using Bayes:  $P(y|x) = \frac{P(y)P(x|y)}{P(x)}$

$$P(x) = \sum_y P(x, y)$$

## Examples

MLE for  $P(y) = p = \frac{n_+}{n}$

MLE for  $P(x_i|y) = \mathcal{N}(x_i; \mu_{i,y}, \sigma_{i,y}^2)$ :

$$\hat{\mu}_{i,y} = \frac{1}{n_y} \sum_{x \in D_{x_i|y}} x$$

$$\hat{\sigma}_{i,y}^2 = \frac{1}{n_y} \sum_{x \in D_{x_i|y}} (x - \hat{\mu}_{i,y})^2$$

MLE for Poi.:  $\lambda = \text{avg}(x_i)$

$$\mathbb{R}^d: P(X=x|Y=y) = \prod_{i=1}^d \text{Pois}(\lambda_y^{(i)}, x^{(i)})$$

## Deriving decision rule

$$P(y|x) = \frac{1}{Z} P(y) P(x|y), Z = \sum_y P(y) P(x|y)$$

$$y^* = \underset{y}{\operatorname{amax}} P(y|x) = \underset{y}{\operatorname{amax}} P(y) \prod_{i=1}^d P(x_i|y)$$

## Gaussian Bayes Classifier

$$\hat{P}(x|y) = \mathcal{N}(x; \hat{\mu}_y, \hat{\Sigma}_y)$$

$$\hat{P}(Y=y) = \hat{p}_y = \frac{n_y}{n}$$

$$\hat{\mu}_y = \frac{1}{n_y} \sum_{i: y_i=y} x_i \in \mathbb{R}^d$$

$$\hat{\Sigma}_y = \frac{1}{n_y} \sum_{i: y_i=y} (x_i - \hat{\mu}_y)(x_i - \hat{\mu}_y)^T \in \mathbb{R}^{d \times d}$$

## Outlier Detection

$$P(x) \leq \tau$$

## Categorical Naive Bayes Classifier

MLE for feature distr.:  $\hat{P}(X_i=c|Y=y) = \theta_{c|y}^{(i)}$

$$\theta_{c|y}^{(i)} = \frac{\text{Count}(X_i=c, Y=y)}{\text{Count}(Y=y)}$$

$$\text{Prediction: } y^* = \underset{y}{\operatorname{argmax}} \hat{P}(y|x)$$

## Missing data

## Mixture modeling

Model each c. as probability distr.  $P(x|\theta_j)$

$$P(D|\theta) = \prod_{i=1}^n \sum_{j=1}^k w_j P(x_i|\theta_j)$$

$$L(w, \theta) = -\sum_{i=1}^n \log \sum_{j=1}^k w_j P(x_i|\theta_j)$$

## Gaussian-Mixture Bayes classifiers

Estimate prior  $P(y)$ ; Est. cond. distr. for each class:  $P(x|y) =$

$$\sum_{j=1}^{k_y} w_j^{(y)} \mathcal{N}(x; \mu_j^{(y)}, \Sigma_j^{(y)})$$

## Hard-EM algorithm

Initialize parameters  $\theta^{(0)}$

E-step: Predict most likely class for each

$$\text{point: } z_i^{(t)} = \underset{z}{\operatorname{argmax}} P(z|x_i, \theta^{(t-1)})$$

$$= \underset{z}{\operatorname{argmax}} P(z|\theta^{(t-1)}) P(x_i|z, \theta^{(t-1)});$$

M-step: Compute the MLE:  $\theta^{(t)} = \underset{\theta}{\operatorname{argmax}} P(D^{(t)}|\theta)$ , i.e.  $\mu_j^{(t)} = \frac{1}{n_j} \sum_{i: z_i=j} x_i$

## Soft-EM algorithm

E-step: Calc p for each point and cls.:  $\gamma_j^{(t)}(x_i)$

M-step: Fit clusters to weighted data points:

$$w_j^{(t)} = \frac{1}{n} \sum_{i=1}^n \gamma_j^{(t)}(x_i); \mu_j^{(t)} = \frac{\sum_{i=1}^n \gamma_j^{(t)}(x_i) x_i}{\sum_{i=1}^n \gamma_j^{(t)}(x_i)}$$

$$\sigma_j^{(t)} = \frac{\sum_{i=1}^n \gamma_j^{(t)}(x_i) (x_i - \mu_j^{(t)})^T (x_i - \mu_j^{(t)})}{\sum_{i=1}^n \gamma_j^{(t)}(x_i)}$$

## Soft-EM for semi-supervised learning

labeled  $y_i$ :  $\gamma_j^{(t)}(x_i) = [j = y_i]$ , unlabeled:

$$\gamma_j^{(t)}(x_i) = P(Z=j|x_i, \mu^{(t-1)}, \Sigma^{(t-1)}, w^{(t-1)})$$

## Useful math

## Probabilities

$$\mathbb{E}_x[X] = \begin{cases} \int x \cdot p(x) \partial x & \text{if continuous} \\ \sum_x x \cdot p(x) & \text{otherwise} \end{cases}$$

$$\text{Var}[X] = \mathbb{E}[(X - \mu_X)^2] = \mathbb{E}[X^2] - \mathbb{E}[X]^2$$

$$P(A|B) = \frac{P(B|A) \cdot P(A)}{P(B)}; p(Z|X, \theta) = \frac{p(X, Z|\theta)}{p(X|\theta)}$$

$$P(x, y) = P(y|x) \cdot P(x) = P(x|y) \cdot P(y)$$

## Bayes Rule

$$P(A|B) = \frac{P(B|A) \cdot P(A)}{P(B)}$$

## P-Norm

$$\|x\|_p = (\sum_{i=1}^n |x_i|^p)^{\frac{1}{p}}, 1 \leq p < \infty$$

## Some gradients

$$\nabla_x \|x\|_2^2 = 2x$$

$$f(x) = x^T A x; \quad \nabla_x f(x) = (A + A^T)x$$

$$\text{E.g. } \nabla_w \log(1 + \exp(-y w^T x)) =$$

$$\frac{1}{1 + \exp(-y w^T x)} \cdot \exp(-y w^T x) \cdot (-y x) =$$

$$\frac{1}{1 + \exp(y w^T x)} \cdot (-y x)$$

## Convex / Jensen's inequality

$g(x)$  convex  $\Leftrightarrow g''(x) > 0 \Leftrightarrow x_1, x_2 \in \mathbb{R}, \lambda \in [0, 1] : g(\lambda x_1 + (1 - \lambda)x_2) \leq \lambda g(x_1) + (1 - \lambda)g(x_2)$

## Gaussian / Normal Distribution

$$f(x) = \frac{1}{\sqrt{2\pi\sigma^2}} \exp(-\frac{(x-\mu)^2}{2\sigma^2})$$

## Multivariate Gaussian

$\Sigma$  = covariance matrix,  $\mu$  = mean

$$f(x) = \frac{1}{2\pi\sqrt{|\Sigma|}} e^{-\frac{1}{2}(x-\mu)^T \Sigma^{-1}(x-\mu)}$$

Empirical:  $\hat{\Sigma} = \frac{1}{n} \sum_{i=1}^n x_i x_i^T$  (needs centered data points)

## Positive semi-definite matrices

$M \in \mathbb{R}^{n \times n}$  is psd  $\Leftrightarrow$

$$\forall x \in \mathbb{R}^n : x^T M x \geq 0 \Leftrightarrow$$

all eigenvalues of  $M$  are positive:  $\lambda_i \geq 0$