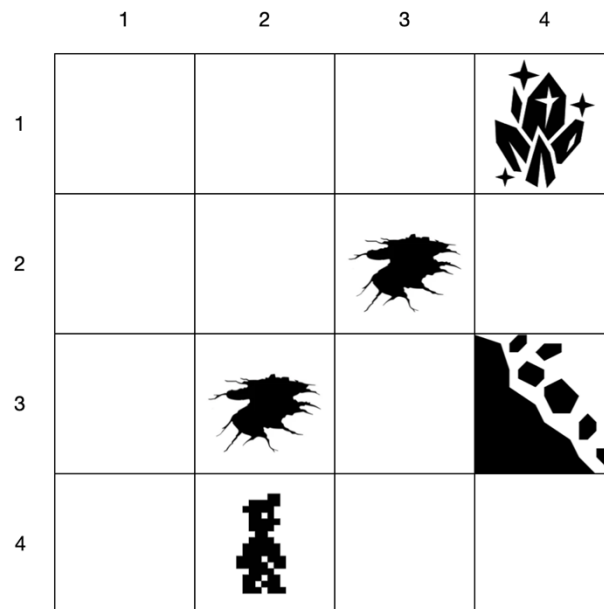


## MANIC MINER (100 Points)

A **Robotic Miner** navigates a subterranean grid to reach a high-value resource deposit (**G**). The terrain is unstable, and the robot's movement is **stochastic**.

A grid represents the  $4 \times 4$  mine. Each cell  $(r, c)$  is a **state**  $s$ .



- **Start State:**  $s_0 = (4, 2)$
- **Goal State:**  $s_G = (1, 4)$
- **Pothole (P) States:**  $(3, 2)$  and  $(2, 3)$ . Entering a pothole state incurs a higher penalty.
- **Rockfall (R) State:**  $(3, 4)$ . Entering a rockfall state has a high probability of failure.
- **Boundary:** The robot cannot move outside the  $4 \times 4$  grid.

In any non-goal state  $s$ , the robot can attempt four actions: **Up**, **Down**, **Left**, and **Right**. When the robot attempts an action  $a$  from a state  $s$ , the actual outcome is stochastic:

1. **Desired Outcome:** With probability  $p_a = 0.8$ , the robot moves to the desired state  $s_a$  (the neighbor in the direction of  $a$ ).
  - **Perpendicular Outcomes:** With probability  $p_f = 0.1$  each, the robot moves to one of the two states perpendicular to  $a$ . Example: If  $a$  is **Up**, the robot moves to  $s_{UP}$  with probability 0.8, and  $s_{LEFT}$  or  $s_{RIGHT}$  with probability 0.1.
  - **Boundary/Blocked:** If the desired, left, or right move leads outside the grid, the robot **stays in state**  $s$  instead. The probability mass is transferred to the

'stay' outcome. Example: From (4, 1), attempting **Left** means  $s_{LEFT}$  is off grid. The probability of moving to  $s_{LEFT}$  (0.1) is added to the probability of staying at (4, 1).

The cost is incurred for the action taken and depends on the resulting state  $s'$ . The goal is to **minimize total expected cost**.

- **Standard Move:**  $Cost = 1$
- **Move resulting in a Pothole (P) state:**  $Cost = 5$
- **Move resulting in a Rockfall (R) state:**  $Cost = 10$
- **Goal State (G):**  $Cost = 0$  (Terminal state, any action from the goal state results in the goal state with cost 0).
- **The initial heuristic values**  $V_0(s) = |s_x - s_{Gx}| + |s_y - s_{Gy}|$

1. Explicitly define the components of this problem as an MDP tuple  $M = (S, A, T, C, \gamma)$ , even if  $\gamma$  is not used in this assignment. Also, explain why  $\gamma$  is not used.

2. Implement the AO\* algorithm in Python to solve the Manic Miner problem.

## SUBMISSION

Python or C++ is the preferred implementation language. For Python, provide a plain PY file (no Jupyter Notebook). If you are writing in C++, please include a **CMakeLists.txt** file and any other compilation instructions. Your code should run immediately without any additional steps on our part.

Your solution may use any numerical libraries for pre-processing, fundamental calculations (e.g., linear algebra), and visualization. However, the core portion must be implemented from scratch. If you are unsure about a specific library, please ask the teaching staff for guidance first.

Submit your solution as a ZIP file with all the files via Canvas. Include a **README.txt** file that clearly explains all its assumptions.