

ML-Guided IBP Reduction

Neural Network Guided Integration-by-Parts Reduction of
Feynman Integrals

Two-Loop Triangle-Box Topology

The Problem

- ▶ **IBP reduction:** Express complex Feynman integrals as linear combinations of simpler “master” integrals
- ▶ **Challenge:** Exponential search space of IBP identities
- ▶ **Traditional approaches:** Laporta algorithm, Kira, FIRE

The Memory Wall

Traditional IBP codes hit **memory limits** as integrals grow more complex:

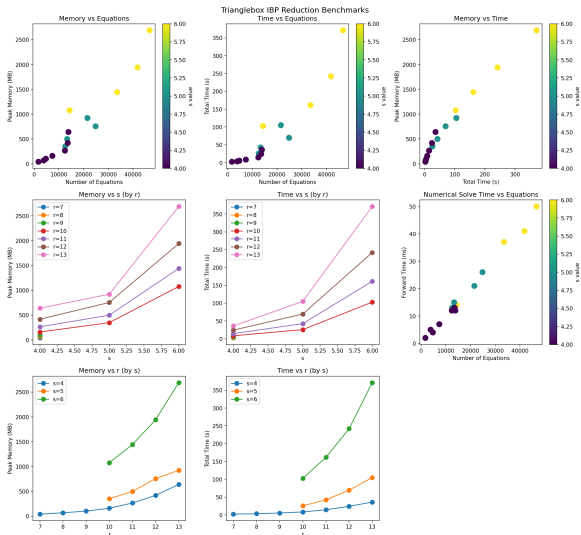


Figure 1: Kira Memory Scaling

Our Solution

- ▶ **ML-guided beam search:** Train a neural network to score IBP actions
- ▶ **Hierarchical reduction:** Process sectors from highest to lowest
- ▶ **Parallel execution:** Distribute across Condor cluster for $\sim 10\times$ speedup
- ▶ **Constant memory:** Each one-step reduction is independent - no system accumulation

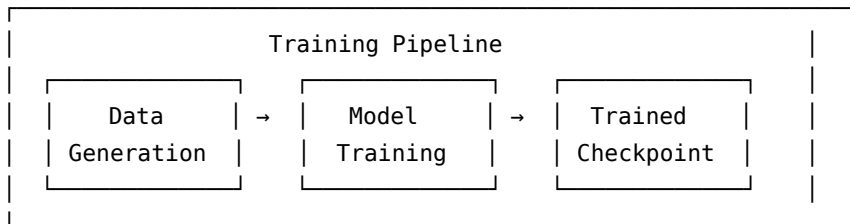
Key Results

Triangle-Box Topology (arXiv:2502.05121)

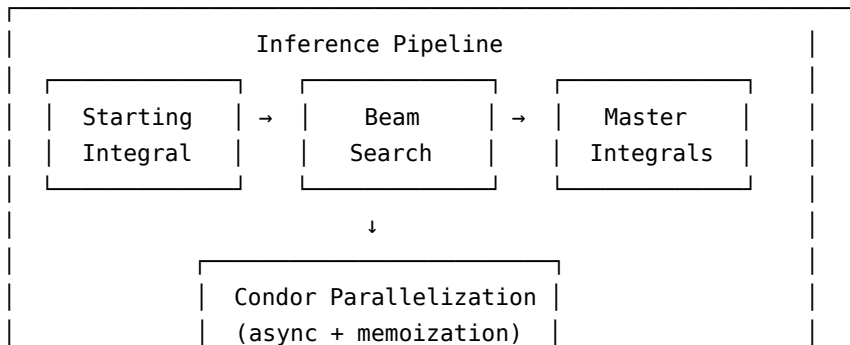
| Integral | Weight | Sequential | Parallel | Speedup | Maste |
|-------------------|--------|----------------|----------------|--------------|-------|
| I[2,0,2,0,1,1,0] | (6,0) | 5 min | - | - | 4 |
| I[1,1,1,1,1,1,-3] | (6,3) | 73 min | 12 min | 6x | 16 |
| I[3,2,1,3,2,2,-6] | (13,6) | ~ 20 hr | 115 min | ~ 10x | 16 |

- ▶ Results match Kira exactly
- ▶ Reduces to exact 16 paper masters from arXiv:2502.05121

System Architecture



↓



Part 1: Data Generation

Data Generation: Scrambling Approach

Key Insight

Instead of collecting reduction trajectories (expensive), **reverse the process**: 1. Start from master integrals 2. Apply random IBP identities to increase complexity 3. Record each step - becomes training data when reversed

Constraints During Scrambling

- ▶ Only apply IBPs that don't introduce higher-sector integrals
- ▶ Stay within target sector and subsectors
- ▶ Ensures training data reflects valid reduction paths

Data Generation: Coverage

Sector Coverage

- ▶ All 63 non-trivial sectors covered
- ▶ Uses 16 paper masters for their respective sectors
- ▶ Uses corner integrals for remaining sectors

Dataset Statistics

| Split | Samples | Size |
|------------|----------|--------|
| Train | 946,168 | 3.8 GB |
| Validation | 118,271 | 480 MB |
| Test | ~118,000 | 480 MB |

Data Format

Each training sample contains:

```
{
  'sector_mask': [1,0,1,0,1,1],  # 6-bit sector encoding
  'expr': [                        # Current expression
    ([1,0,2,0,1,1,0], 107),      # (integral, coefficient)
    ([1,0,1,0,1,1,0], 303),
    ...
  ],
  'subs': [                       # Substitution history
    (key_integral, [(repl_int1, coeff1), ...]),
    ...
  ],
  'target_integral': [1,0,2,0,1,1,0],  # Integral to eliminate
  'valid_actions': [(ibp_op, delta), ...],
  'label': 3  # Index of correct action
}
```

Part 2: Model Architecture

Model: IBPActionClassifierV5

Overview

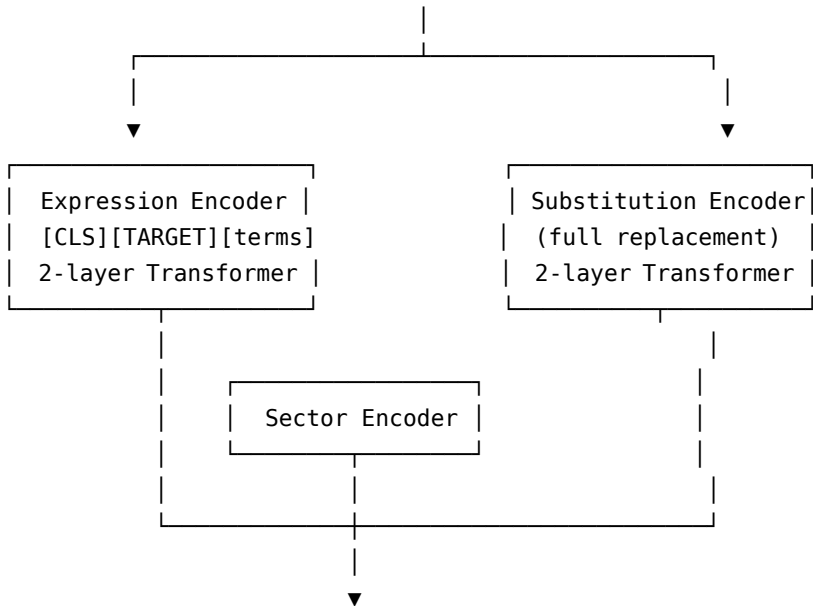
- ▶ **Task:** Score candidate IBP actions given current reduction state
- ▶ **Architecture:** Transformer-based with specialized encoders
- ▶ **Parameters:** 7.7M
- ▶ **Best validation accuracy:** 90.77%

Key Innovation (V5)

Full substitution encoding - encode not just the key integral but the complete replacement expression

Model Architecture Diagram

Inputs: Expression, Target, Substitutions, Sector, Actions



Component Details

| Component | Purpose | Architecture |
|-------------------------------|--|---|
| Expression Encoder | Encode current expression + target | 2-layer Transformer |
| Substitution Encoder | Encode reduction history | 2-layer Transformer + attention pooling |
| Sector Encoder | Condition on target sector | Embedding + projection |
| Cross-Attention Scorer | Score actions by attending to expression | 2-layer cross-attention |

Model Hyperparameters

- ▶ Embedding dimension: 256
- ▶ Attention heads: 4
- ▶ Total parameters: 7,696,709

Part 3: Training

Training Configuration

```
epochs = 30  
batch_size = 256  
learning_rate = 0.0004  
weight_decay = 1e-5  
optimizer = AdamW
```

Training Results

- ▶ **Best checkpoint:** Epoch 22
- ▶ **Validation accuracy:** 90.77% (top-1)
- ▶ **Top-5 accuracy:** ~98%
- ▶ **Training time:** ~800s per epoch on GPU

Training Curves

Key Observations

- ▶ Model converges by epoch 20-25
- ▶ Validation accuracy plateaus at ~91%
- ▶ No significant overfitting observed
- ▶ Top-5 accuracy very high (~98%) - beam search can recover from top-1 mistakes

Part 4: Beam Search Inference

Beam Search Algorithm

```
def beam_search(start_integral, beam_width=20):  
    beam = [start_state]  
  
    while not all_masters(beam[0]):  
        candidates = []  
        for state in beam:  
            for action in get_valid_actions(state):  
                score = model.score(state, action)  
                new_state = apply_action(state, action)  
                candidates.append((new_state, score))  
  
        # Keep top-k by score  
        beam = sorted(candidates, key=score)[:beam_width]  
  
    return beam[0]
```

Beam Search Optimizations

P1: Equation Caching (~3-10x speedup)

- ▶ IBP equation generation is expensive (sympy operations)
- ▶ Cache `get_raw_equation` results
- ▶ Reuse across beam states with shared history

P2: Batched Inference (~50x speedup)

- ▶ Prepare all action candidates as numpy arrays
- ▶ Single batched forward pass through model
- ▶ Eliminates per-action inference overhead

Combined Effect

- ▶ Per-step time: 10-90s \rightarrow 0.1-5s
- ▶ Makes deep reductions feasible

Hierarchical Reduction Strategy

Algorithm

1. Find highest-level sector with non-master integrals
2. Run beam search to eliminate all non-masters in that sector
3. Move to next highest sector
4. Repeat until only masters remain

Example: $I[2,0,2,0,1,1,0]$

| Sector | Level | Steps |
|--------------|-------|------------|
| 53 | 4 | 53 |
| 52 | 3 | 17 |
| 49 | 3 | 4 |
| 37 | 3 | 42 |
| 21 | 3 | 46 |
| ... | ... | ... |
| Total | - | 176 |

Beam Restart Strategy (V11+)

Problem

After weight improvement, beam often contains suboptimal states that will never succeed

Solution: Beam Restart

1. Run beam search until weight improves
2. **Stop and restart** with only the best state
3. Prunes dead ends, enables deeper exploration

Impact

- ▶ Essential for high-weight integrals
- ▶ I[1,1,1,1,1,1,-3]: 1,416 steps across 45 sectors
- ▶ I[3,2,1,3,2,2,-6]: 46,345 steps across 62 sectors

Part 5: Parallelization

Parallelization Motivation

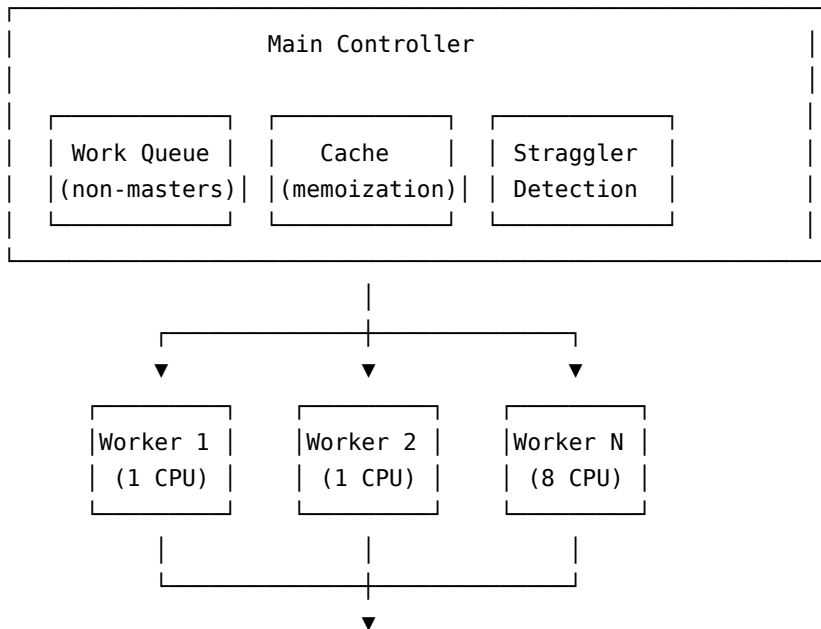
The Bottleneck

- ▶ Sequential reduction of $I[3,2,1,3,2,2,-6]$ takes ~20 hours
- ▶ Single-threaded beam search on CPU
- ▶ Many independent integrals could be processed in parallel

Key Insight

Each one-step reduction is independent - distribute across workers!

Async Parallel Architecture



Key Parallelization Features

1. Async Work Distribution

- ▶ Submit all pending non-masters immediately
- ▶ Don't wait for level synchronization
- ▶ Process results as they arrive

2. Memoization Cache

- ▶ Store: integral \rightarrow reduced expression
- ▶ Avoid redundant work (~55,000 cache hits!)
- ▶ Critical when stragglers produce already-cached results

3. Straggler Detection

- ▶ Jobs >30 min are killed and resubmitted
- ▶ Resubmit with 8 CPUs (parallel beam search)
- ▶ Prevents slow integrals from blocking progress

Parallel Performance

I[3,2,1,3,2,2,-6] Results

| Metric | Value |
|------------------------|--------------------|
| Time (sequential) | ~20 hours |
| Time (parallel) | 115 minutes |
| Speedup | ~10x |
| Jobs submitted | 21,096 |
| Stragglers resubmitted | 24 |
| Cache hits | 55,075 |
| Final masters | 16 |

Part 6: Results

Validation Against Kira

$I[2,0,2,0,1,1,0]$ (Sector 53)

| Method | Masters | Result |
|---------------|---------|-----------------|
| Kira | 4 | Reference |
| Our V5 | 4 | Matches exactly |

Our reduction produces the **exact same master basis** as professional IBP software.

Scaling Results

| Integral | Weight | Time | Steps | Masters |
|-------------------|--------|-----------------|---------|---------|
| I[2,0,2,0,1,1,0] | (6,0) | 5 min | 176 | 4 |
| I[1,1,1,1,1,1,-3] | (6,3) | 12 min* | 1,416 | 16 |
| I[3,2,1,3,2,2,-6] | (13,6) | 115 min* | 131,769 | 16 |

*With parallel execution

Final Reduction Example

$I[3,2,1,3,2,2,-6] \rightarrow 16$ Paper Masters

Final expression (mod 1009):

```
171 * I[1,0,1,1,1,1,0]
854 * I[1,1,0,1,1,1,0]
377 * I[1,1,1,1,1,0,0]
160 * I[-1,1,1,1,1,0,0]
100 * I[0,1,1,1,1,0,0]
647 * I[1,-1,1,0,1,1,0]
  9 * I[1,-1,1,1,1,0,0]
... (16 masters total)
```

Matches arXiv:2502.05121 basis exactly!

Part 7: Conclusions

Key Contributions

1. **ML-guided IBP reduction** that matches professional software (Kira)
2. **Constant memory usage** - avoids the memory wall of traditional approaches
3. **Hierarchical beam search** with restart strategy for deep reductions
4. **Async parallel execution** with $\sim 10\times$ speedup
5. **Straggler handling** for robust distributed computing
6. **Paper-masters-only mode** for clean minimal basis

Technical Innovations

Model

- ▶ Full substitution encoding (V5)
- ▶ Cross-attention action scoring
- ▶ Target-aware expression encoding

Inference

- ▶ Equation caching (3-10x speedup)
- ▶ Batched model inference (50x speedup)
- ▶ Beam restart strategy

Parallelization

- ▶ Async one-step distribution
- ▶ Memoization cache (~55k hits)
- ▶ Automatic straggler resubmission

Future Work

1. **GPU workers** for faster beam search
2. **Adaptive timeouts** based on sector statistics
3. **More integrals** - test on other two-loop families
4. **Training on successful paths** - use reduction results to improve model
5. **Path optimization** - shorten saved reduction paths

Code Availability

Repository: github.com/davidshih17/RL_IBPreduction_claude

Key Files

- ▶ `models/classifier_v5.py` - Model architecture
- ▶ `scripts/eval/hierarchical_reduction_async.py` - Parallel reduction
- ▶ `scripts/eval/reduce_integral_onestep_worker.py` - Condor worker
- ▶ `docs/parallelization.md` - Detailed documentation

Thank You

Questions?

Contact

- ▶ Repository:
`github.com/davidshih17/RL_IBPreduction_claude`
- ▶ arXiv: 2502.05121 (paper masters reference)