

OB1 - <offline>

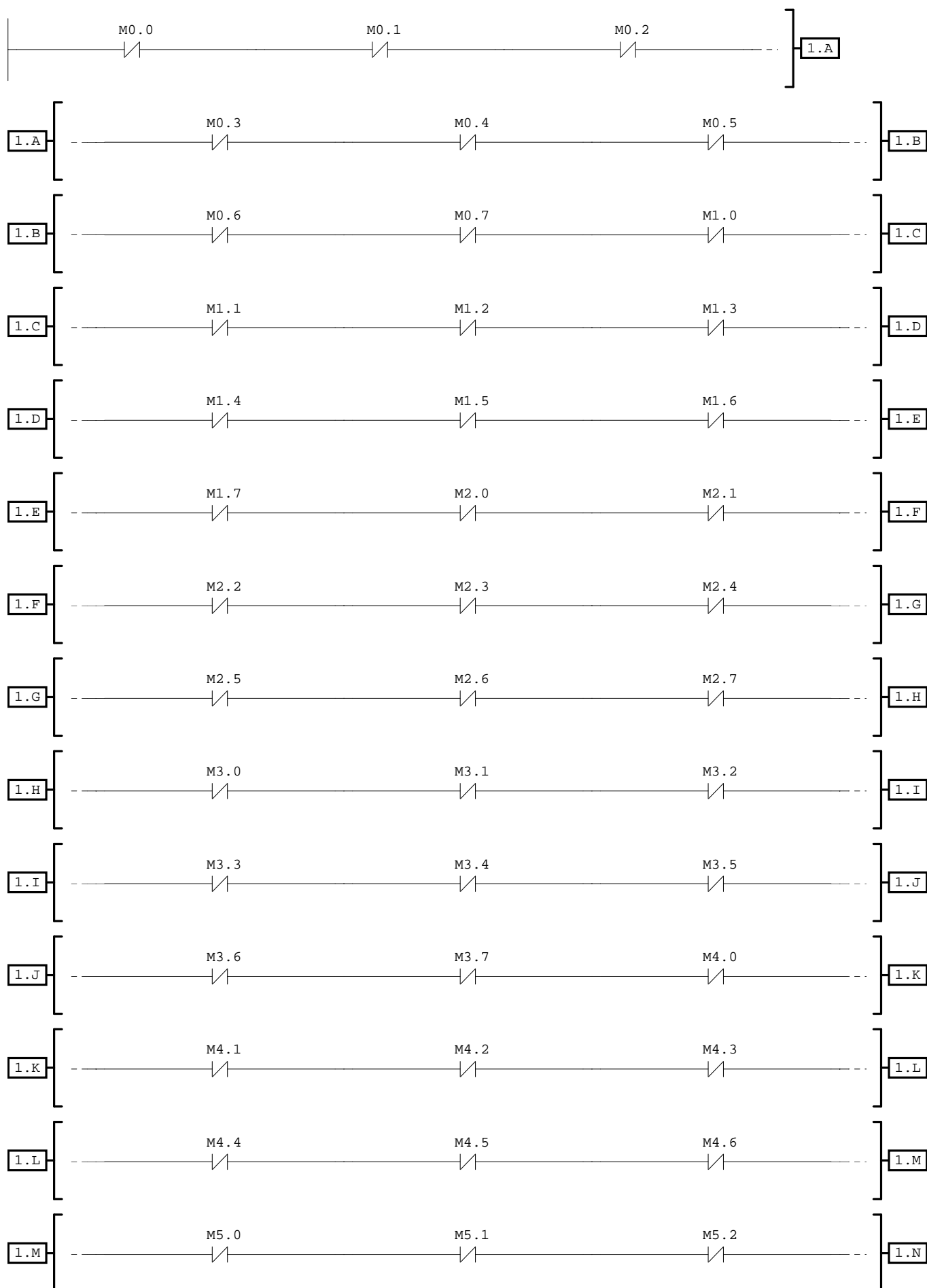
" "

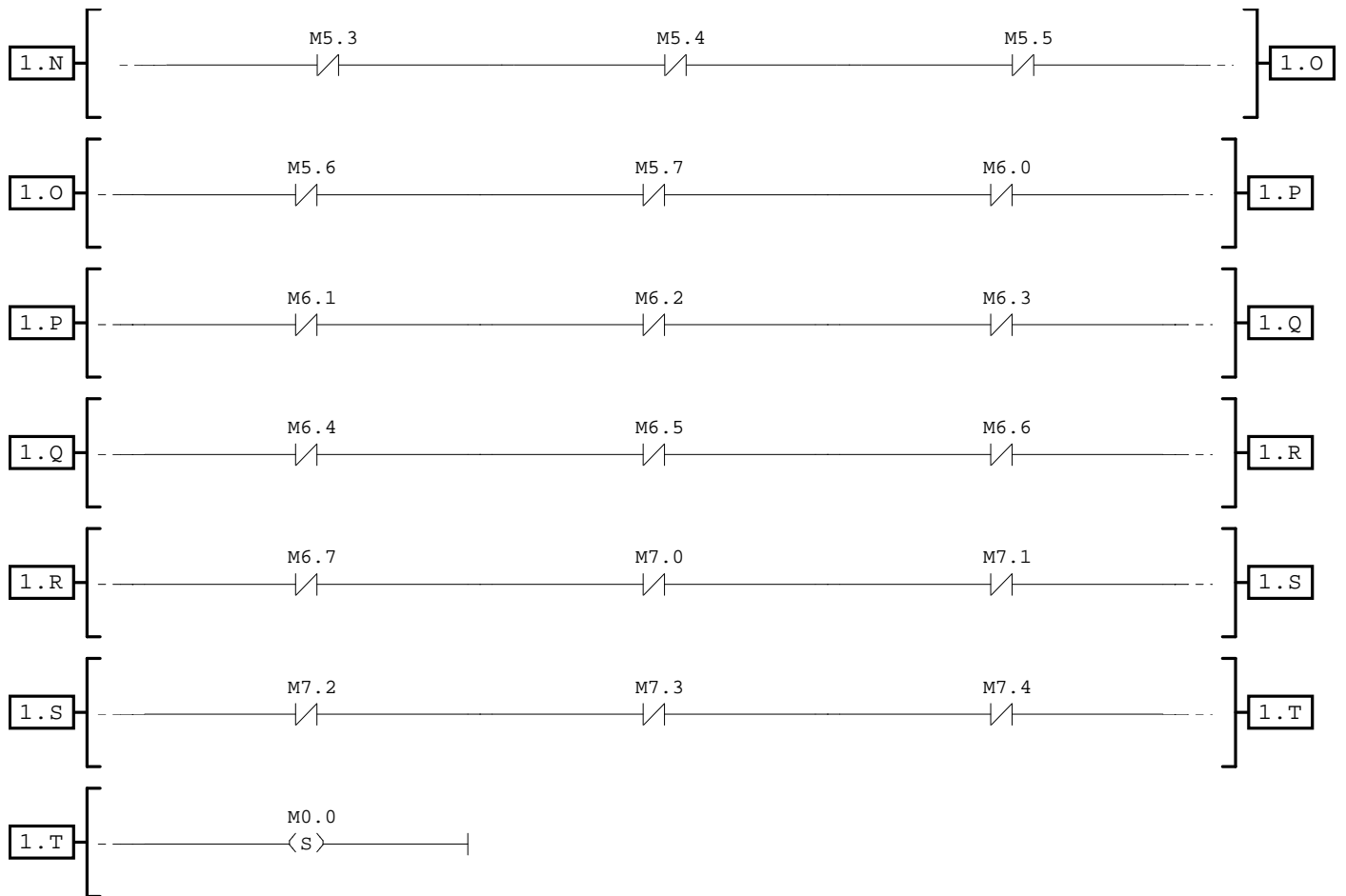
Nombre: **Familia:**
Autor: **Versión:** 0.1
Versión del bloque: 2
Hora y fecha Código: 29/04/2016 17:09:18
Interface: 15/02/1996 16:51:12
Longitud (bloque / código / datos): 04954 04600 00022

Nombre	Tipo de datos	Dirección	Comentario
TEMP		0.0	
OB1_EV_CLASS	Byte	0.0	Bits 0-3 = 1 (Coming event), Bits 4-7 = 1 (Event class 1)
OB1_SCAN_1	Byte	1.0	1 (Cold restart scan 1 of OB 1), 3 (Scan 2-n of OB 1)
OB1_PRIORITY	Byte	2.0	Priority of OB Execution
OB1_OB_NUMBR	Byte	3.0	1 (Organization block 1, OB1)
OB1_RESERVED_1	Byte	4.0	Reserved for system
OB1_RESERVED_2	Byte	5.0	Reserved for system
OB1_PREV_CYCLE	Int	6.0	Cycle time of previous OB1 scan (milliseconds)
OB1_MIN_CYCLE	Int	8.0	Minimum cycle time of OB1 (milliseconds)
OB1_MAX_CYCLE	Int	10.0	Maximum cycle time of OB1 (milliseconds)
OB1_DATE_TIME	Date_And_Time	12.0	Date and time OB1 started

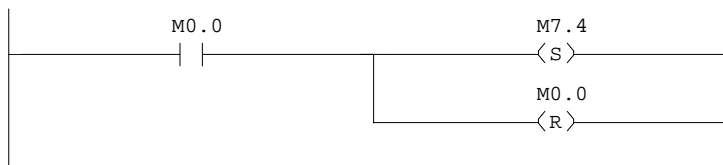
Bloque: OB1 "Main Program Sweep (Cycle)"
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Segm.: 1 INICIALIZACION

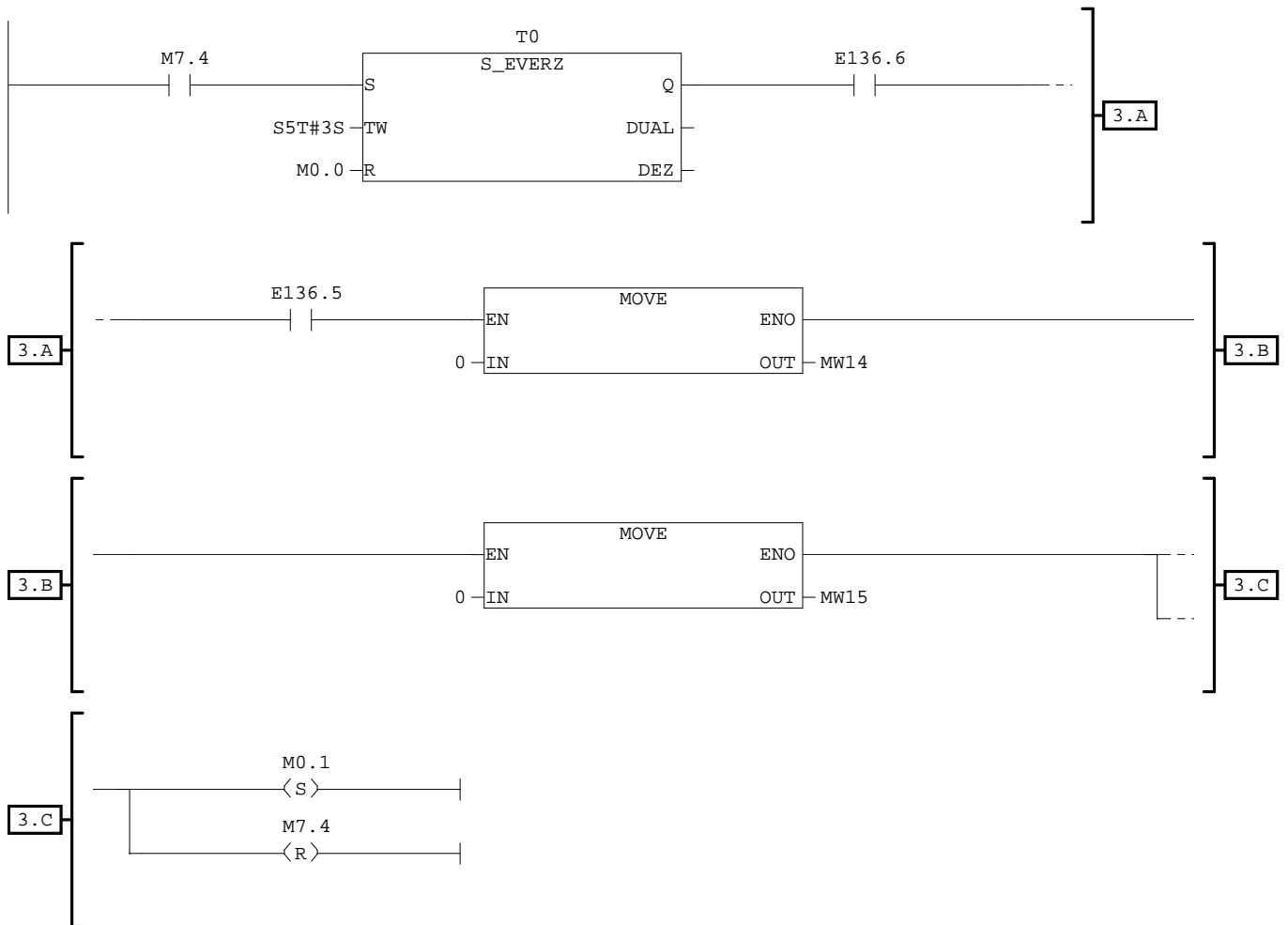




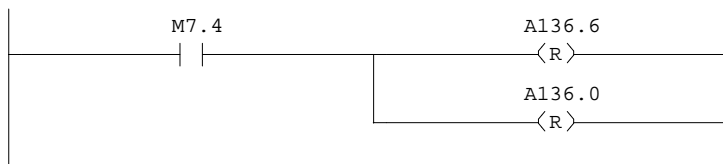
Segm.: 2 RESETEO INICIAL



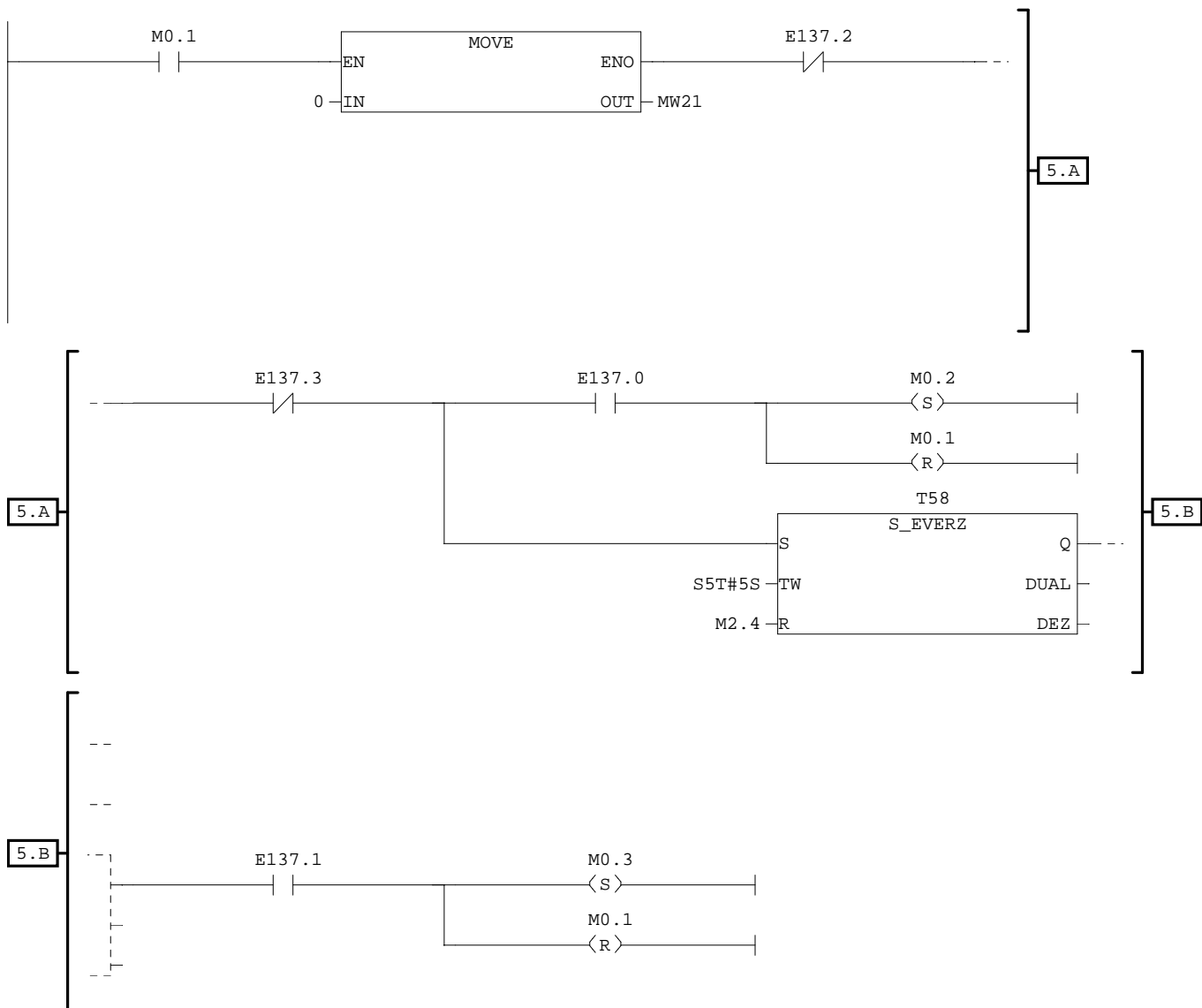
Segm.: 3 RESET PRUEBA



Segm.: 4 RESETEO INICIAL

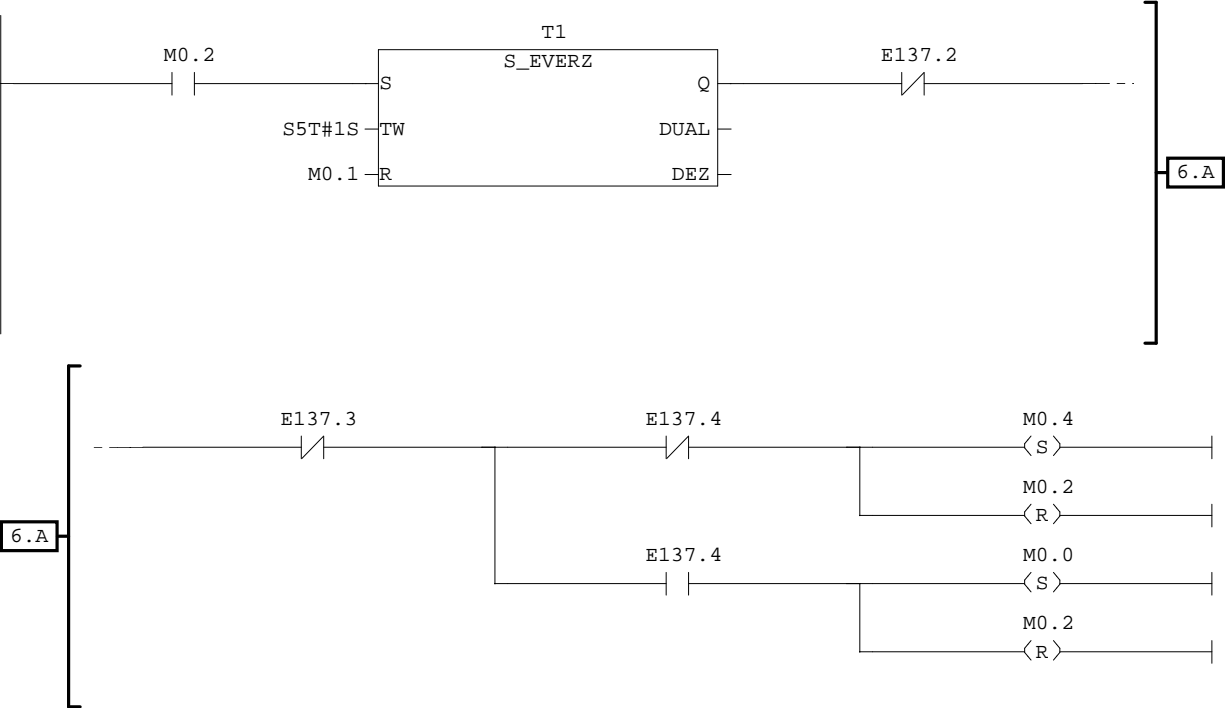


Segm.: 5 SELECCION ROBOT VS PRENSA



Segm.: 6

MOVER A LA IZQUIERDA

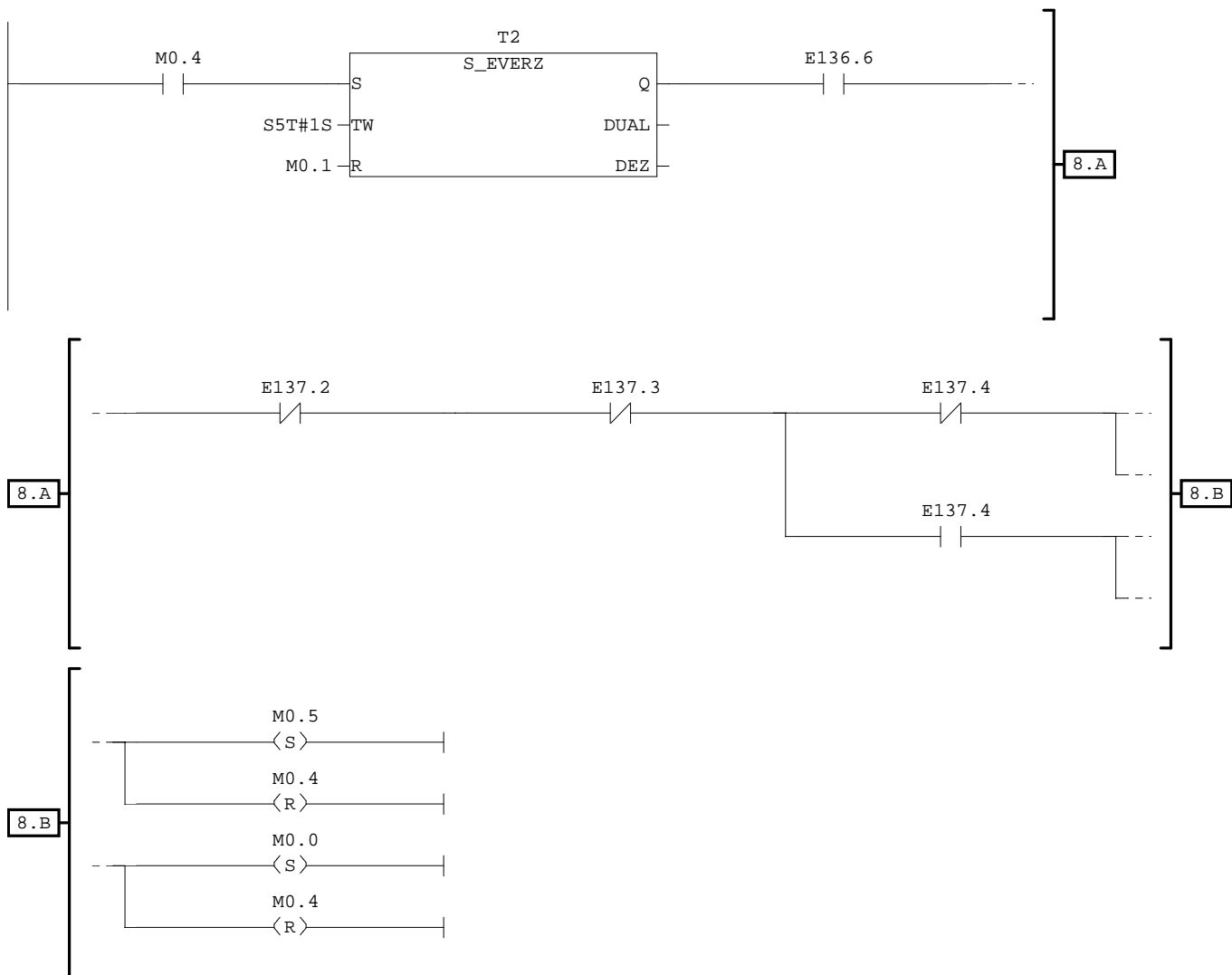


Segm.: 7

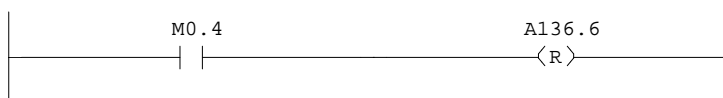
MOVER A LA IZQUIERDA



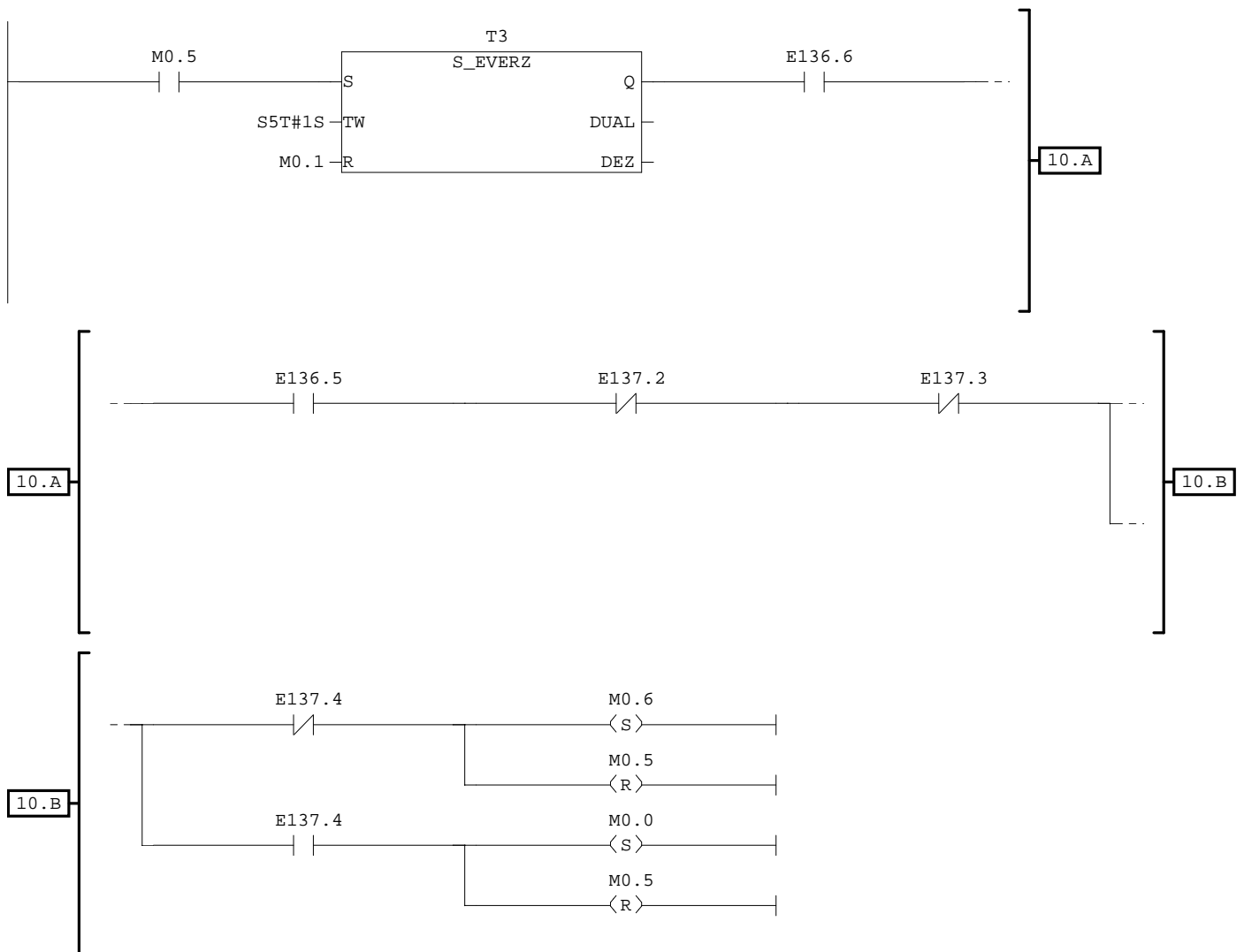
Segm.: 8 RESETEO MOTOR GIRO



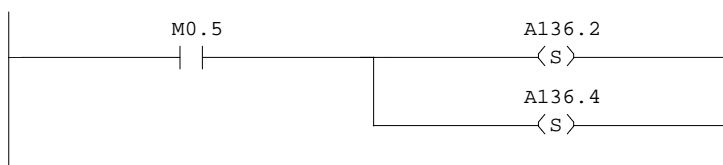
Segm.: 9 RESETEO MOTOR GIRO



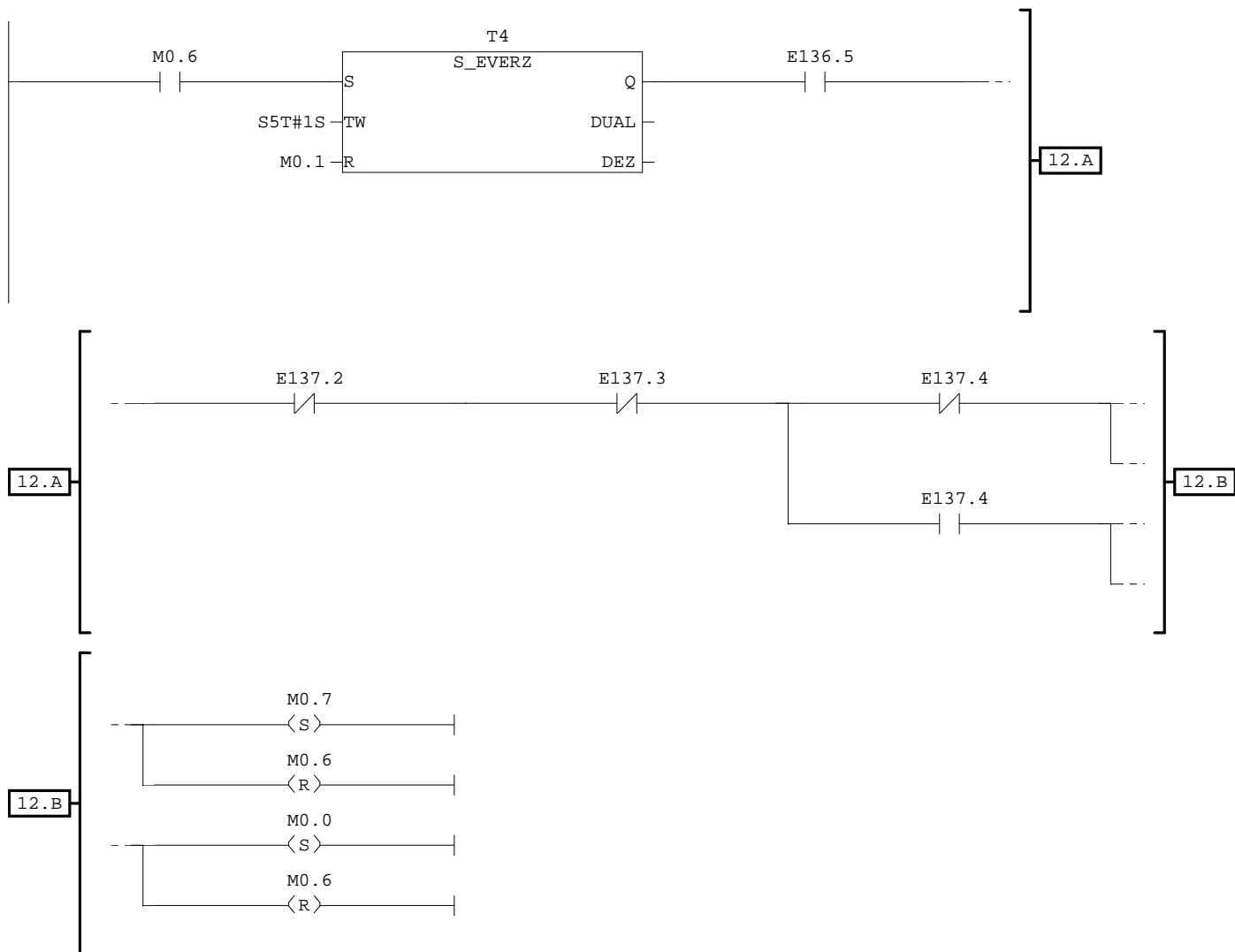
Segm.: 10 RECONOCIMIENTO



Segm.: 11 RECONOCIMIENTO



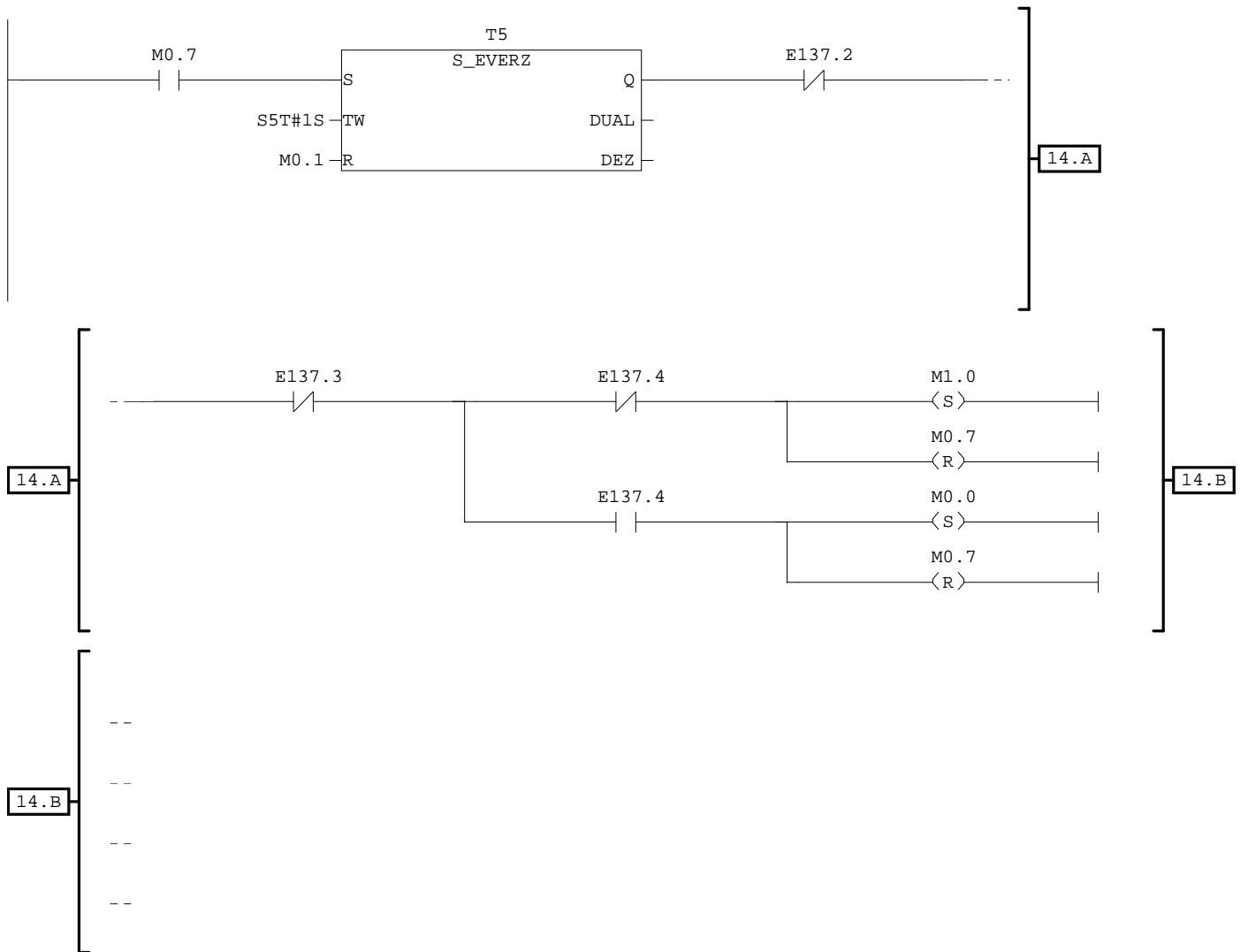
Segm.: 12 RECONOCIMIENTO 2



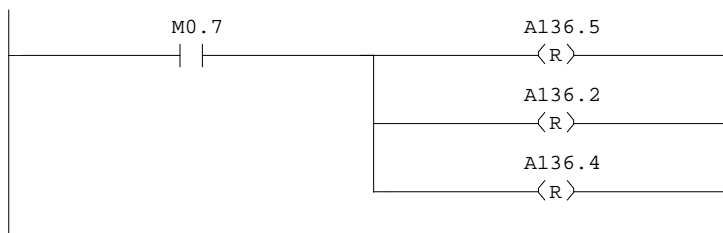
Segm.: 13 RECONOCIMIENTO 2



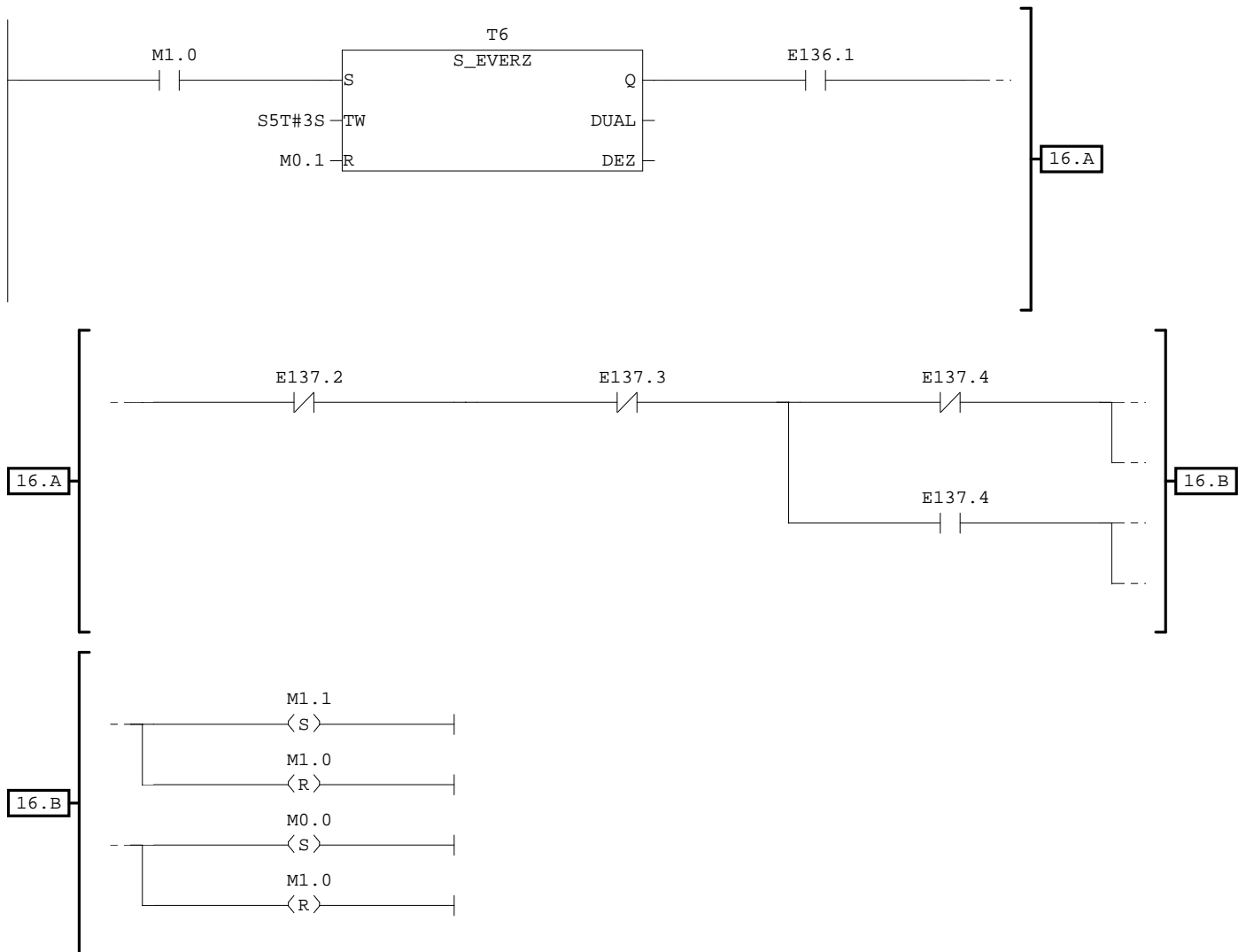
Segm.: 14 RESETEO



Segm.: 15 RESETEO



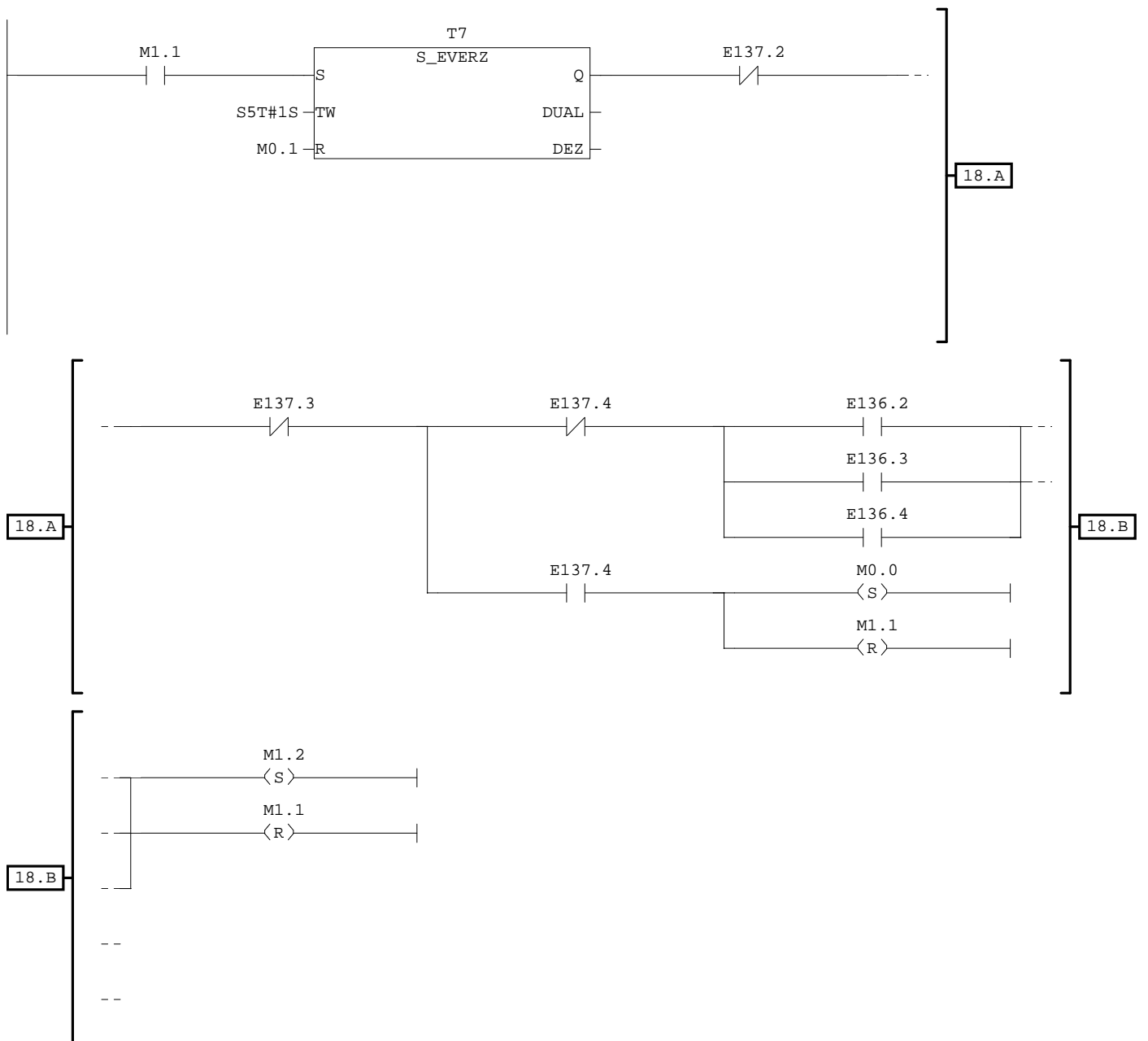
Segm.: 16 ALARGAR BRAZO



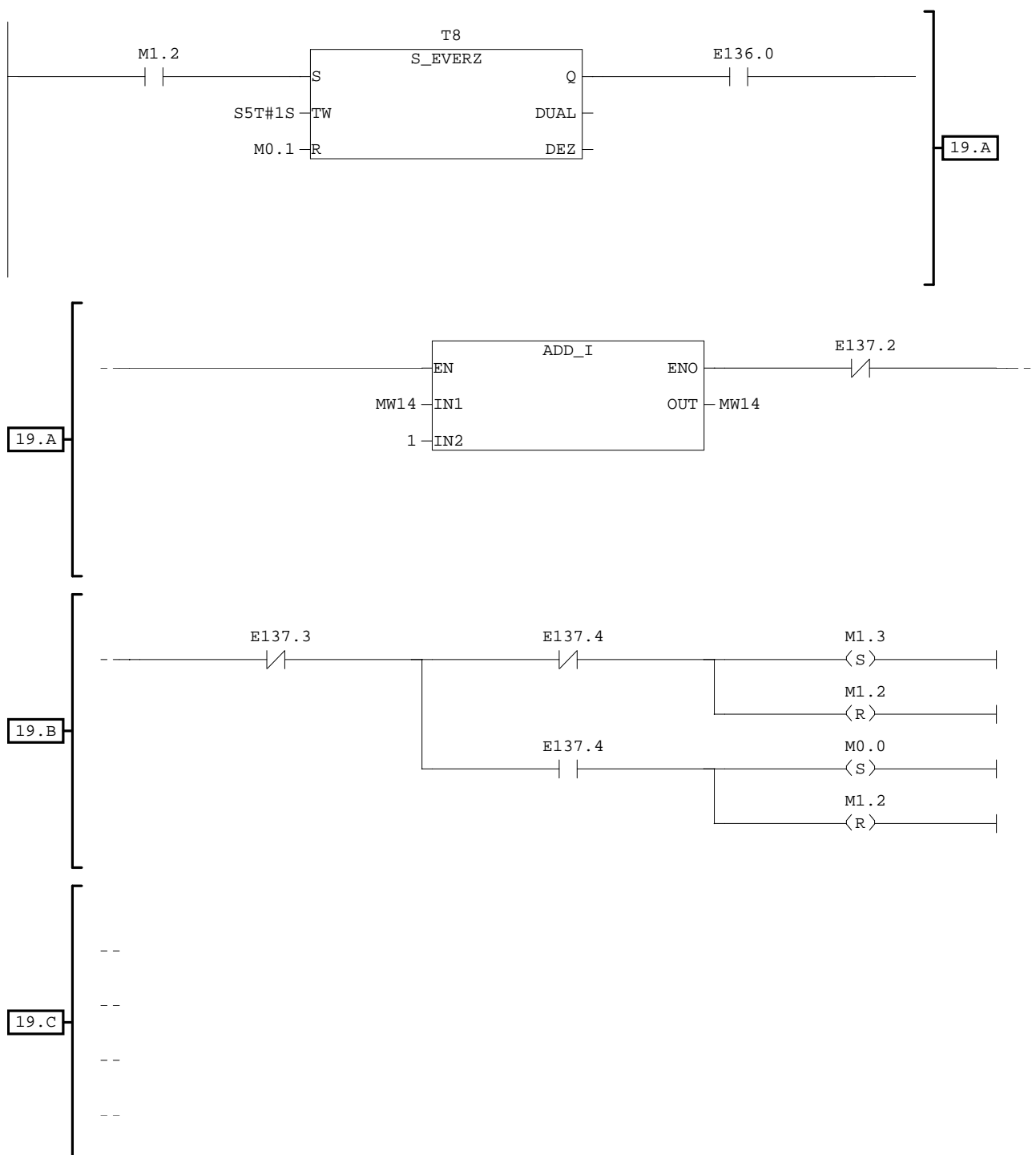
Segm.: 17 ALARGAR BRAZO



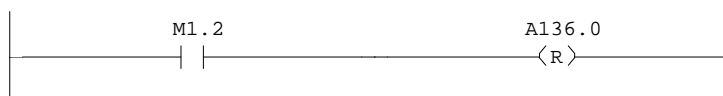
Segm.: 18 CONTAR



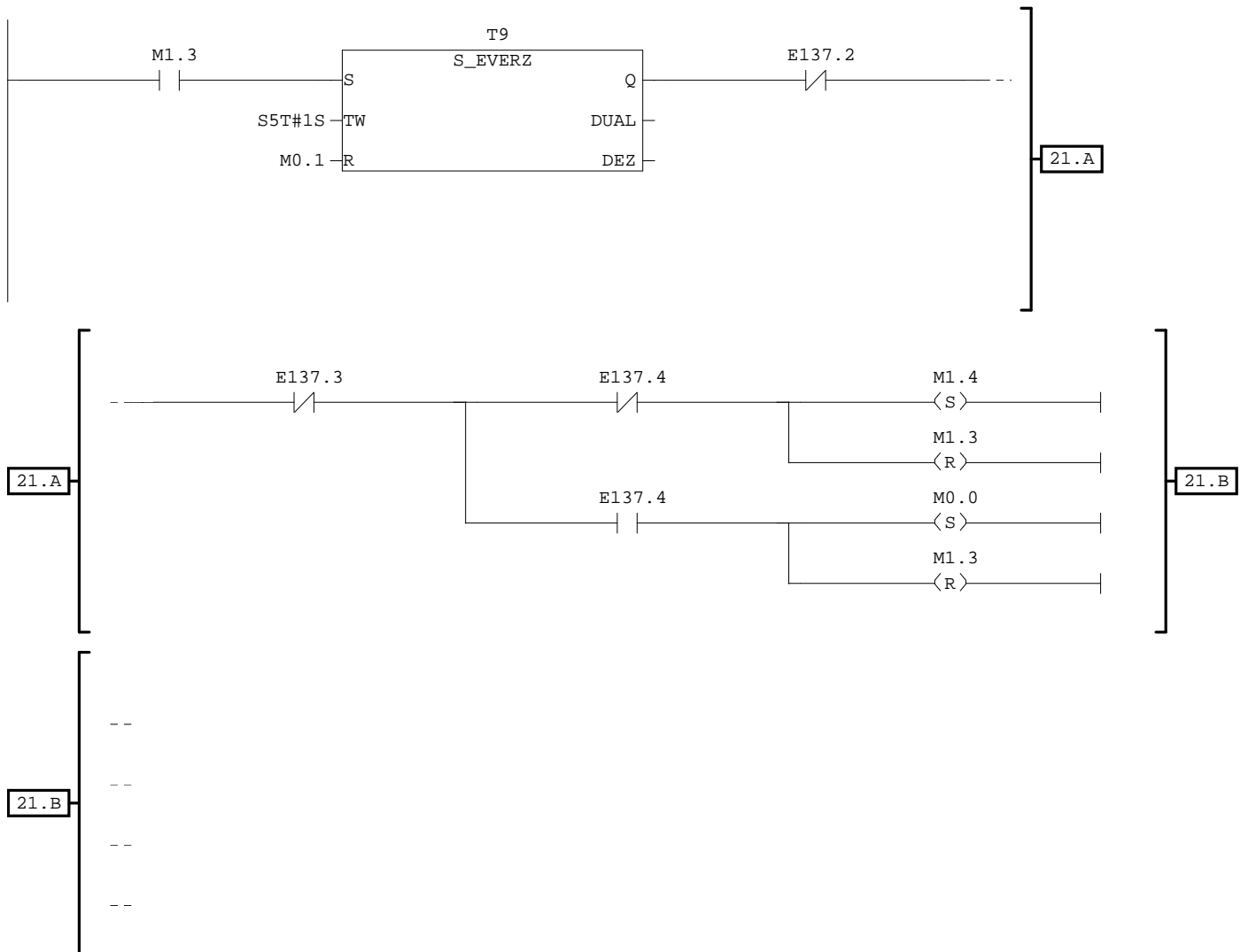
Segm.: 19 RECOGER BRAZO



Segm.: 20 RECOGER BRAZO



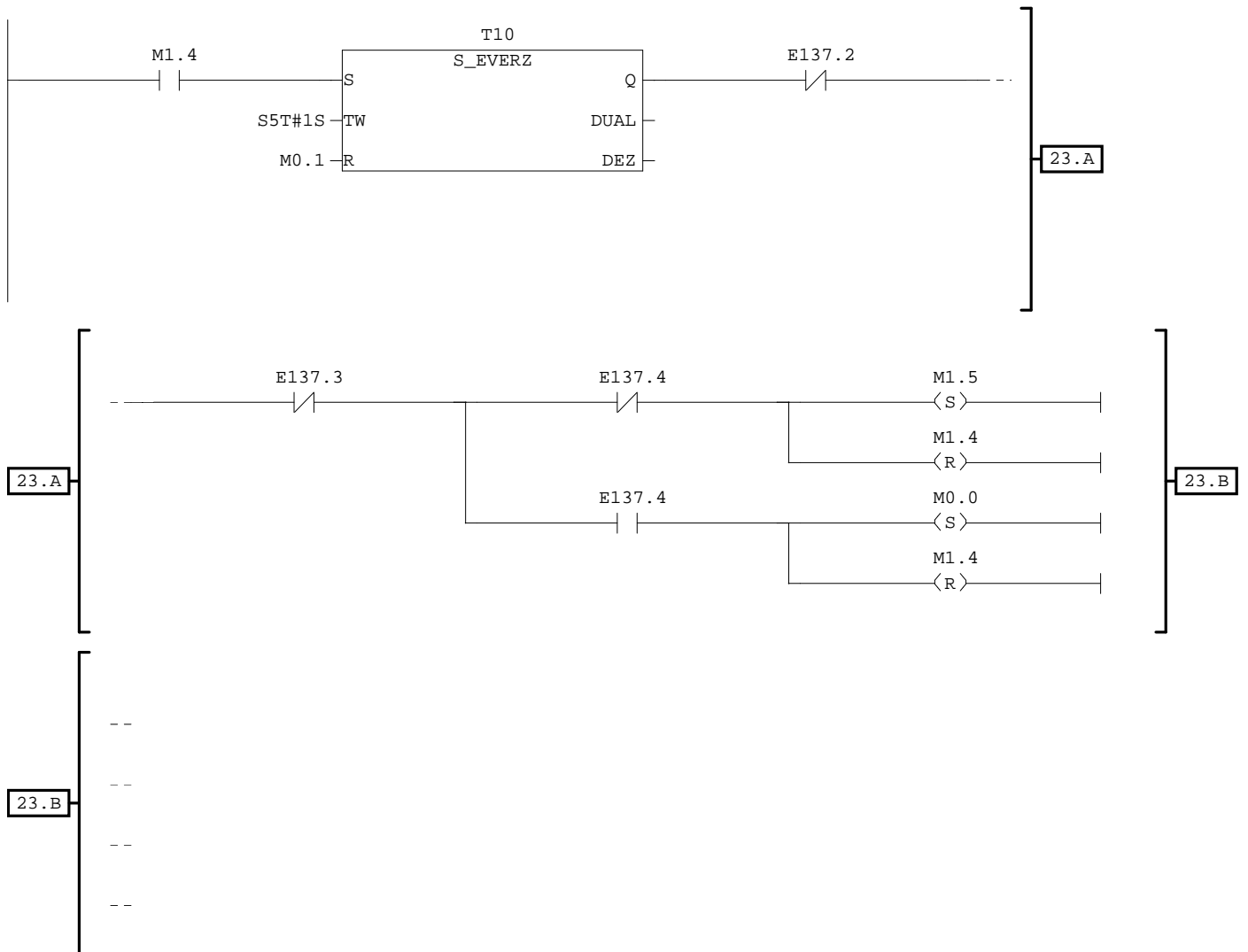
Segm.: 21 POSICION



Segm.: 22 POSICION



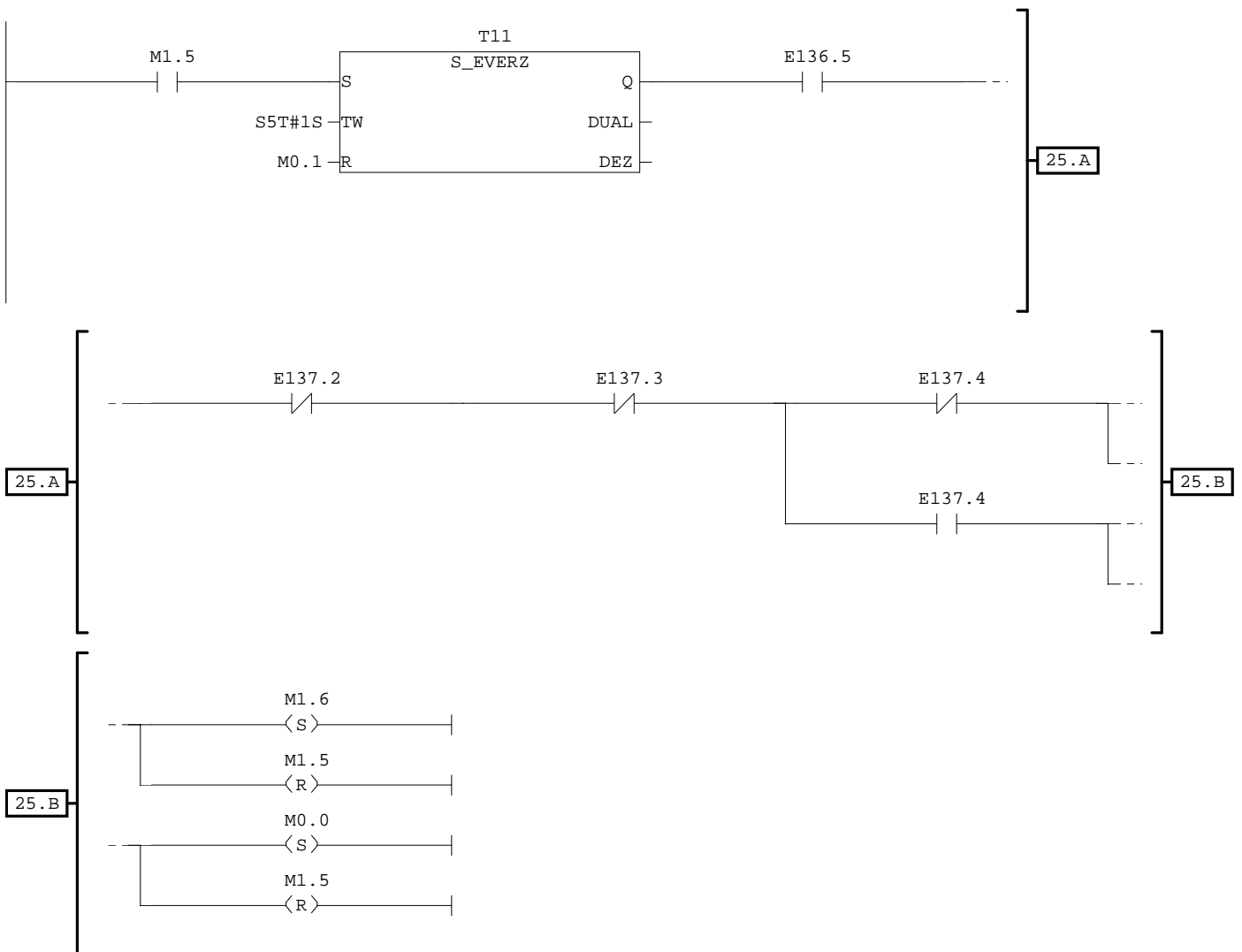
Segm.: 23 ALTURA COGER PIEZA



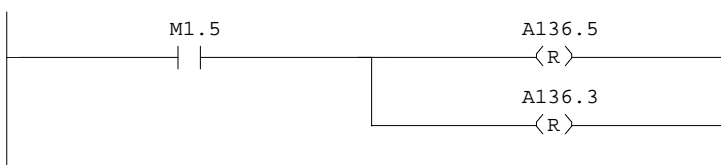
Segm.: 24 ALTURA COGER PIEZA



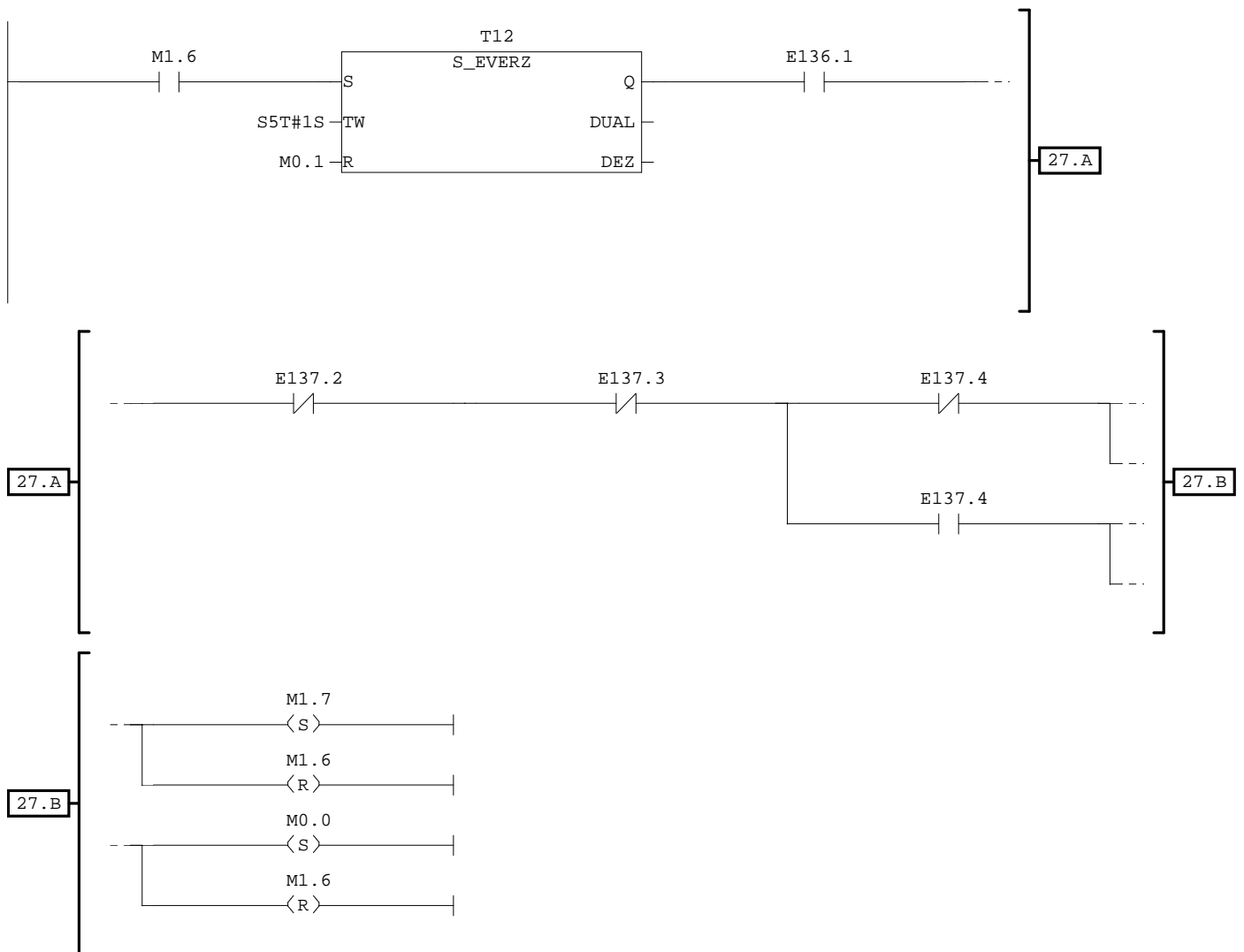
Segm.: 25	ALTURA COGER PIEZA
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Segm.: 26	ALTURA COGER PIEZA
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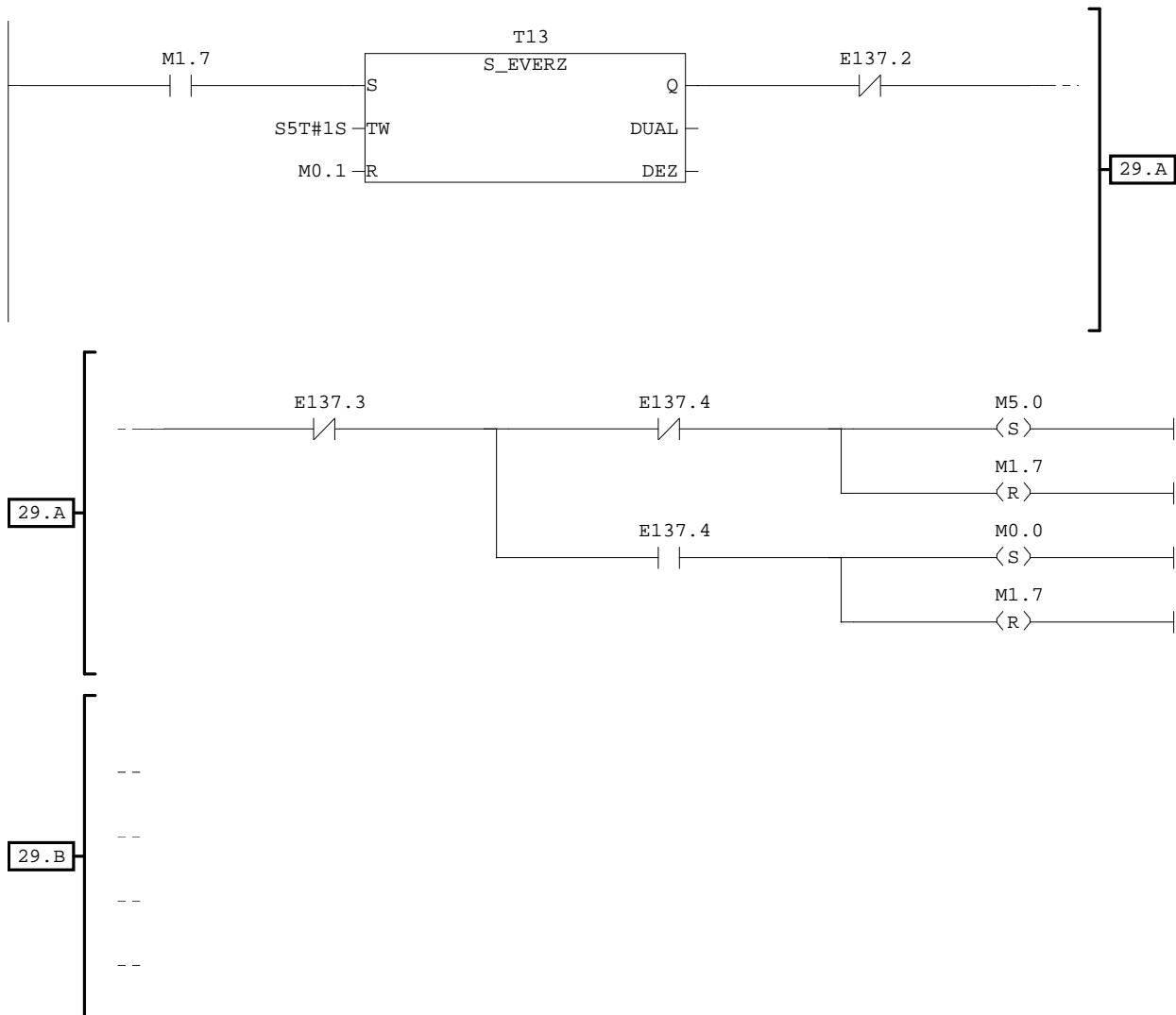
Segm.: 27 ALARGAR BRAZO



Segm.: 28 ALARGAR BRAZO



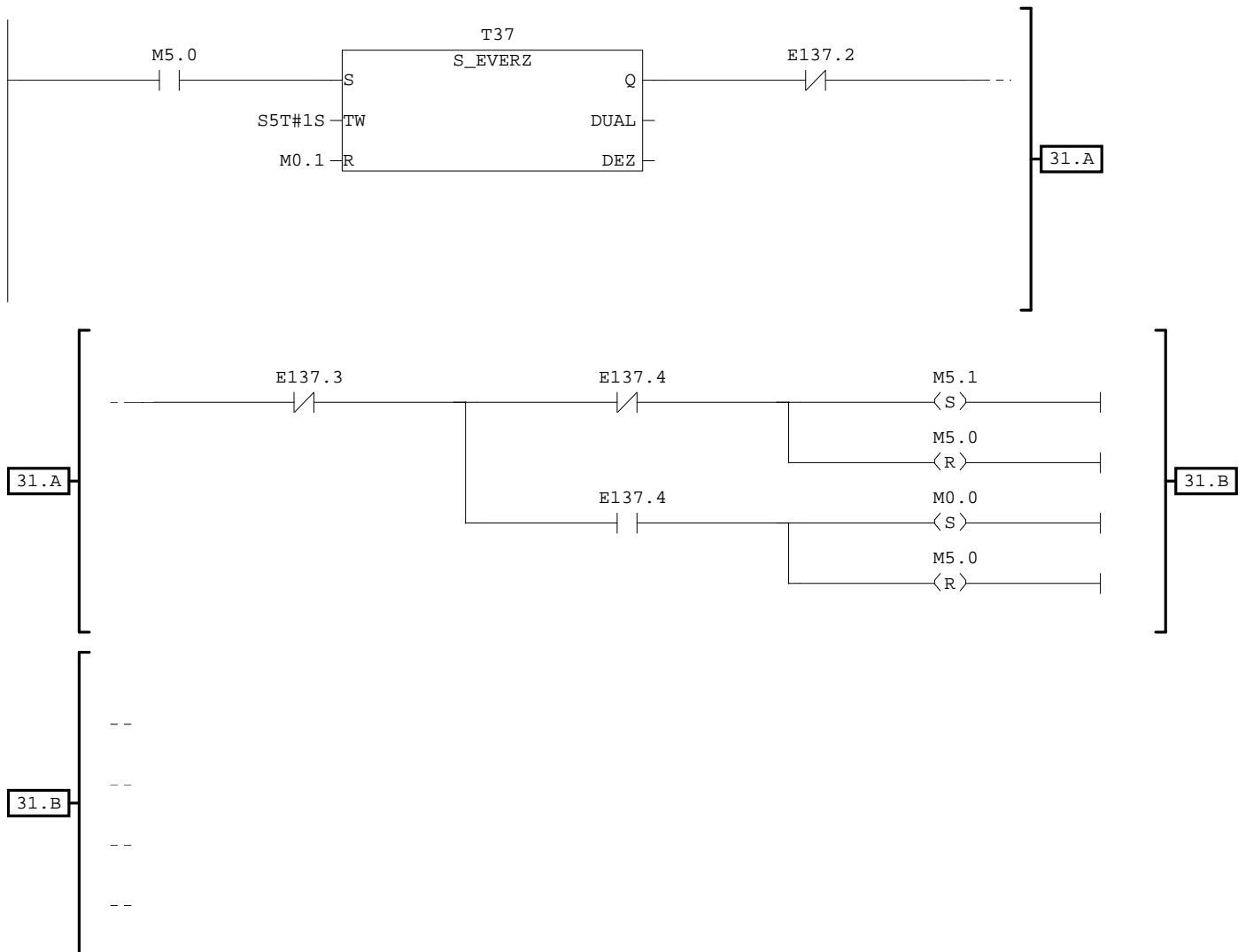
Segm.: 29 CERRAR PINZA



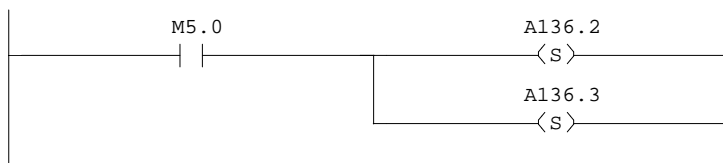
Segm.: 30 CERRAR PINZA



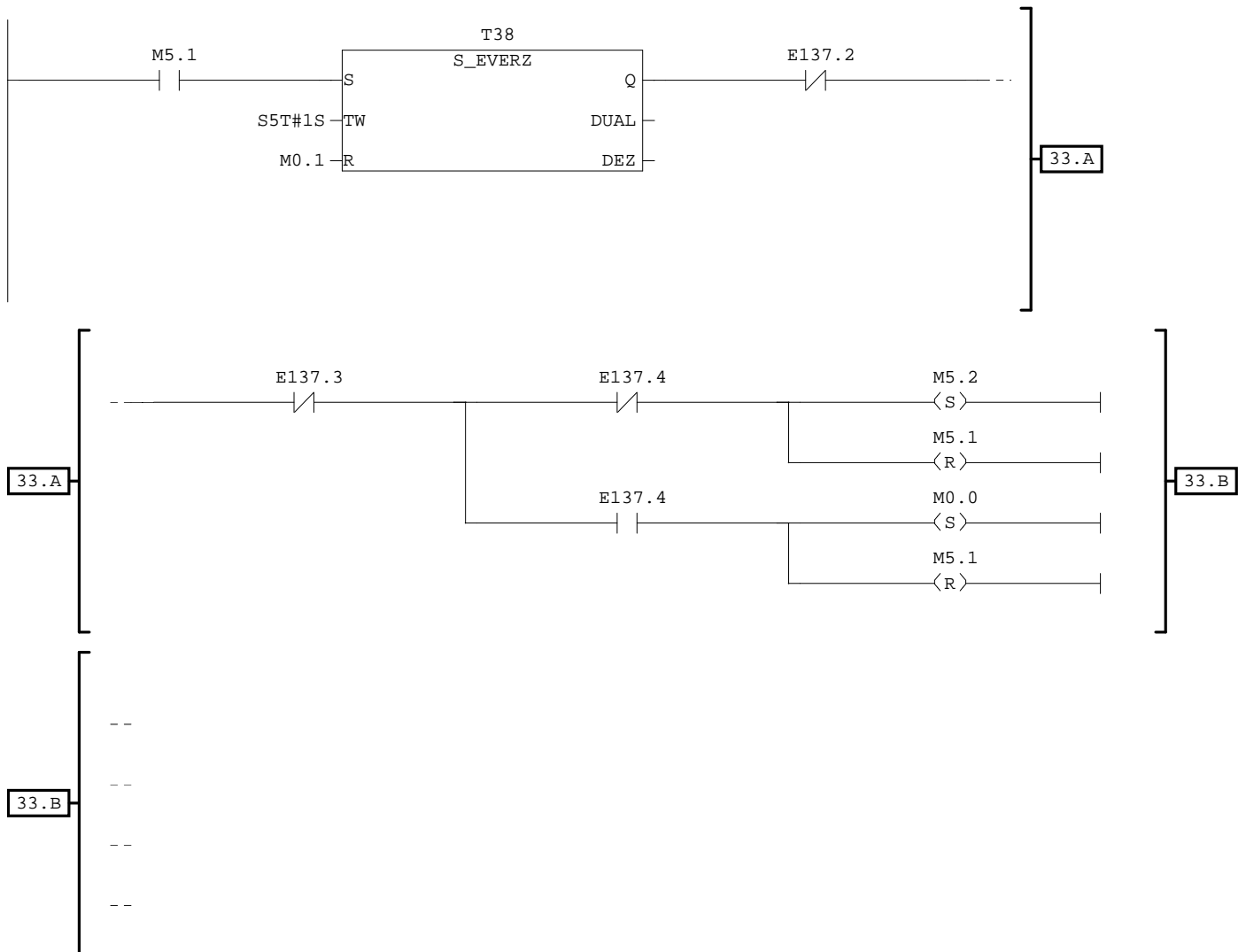
Segm.: 31 SUBIR UN POCO EL BRAZO PARA NO CHOCAR



Segm.: 32 SET POSICION PLANTA DOS



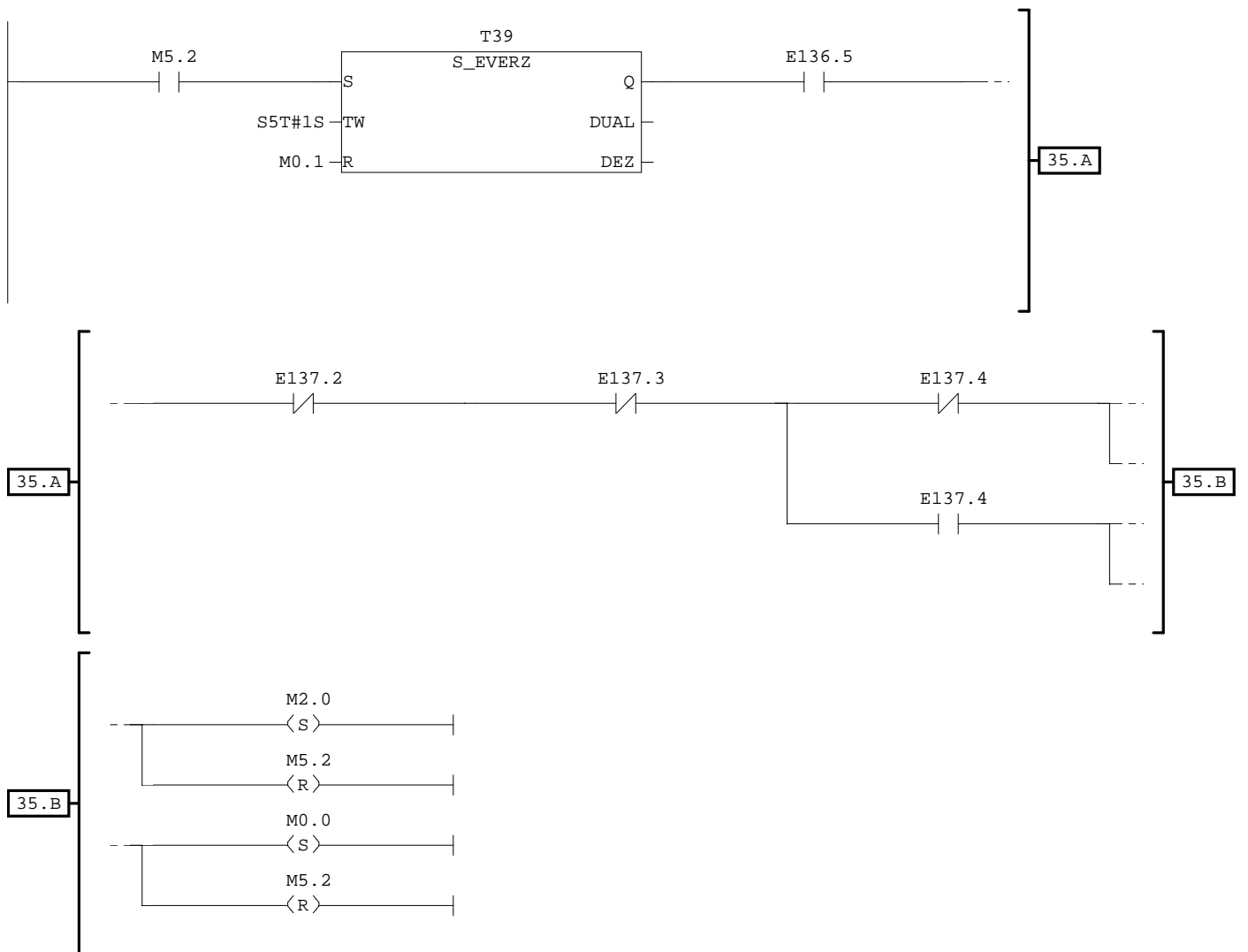
Segm.: 33 SET MOVIMIENTO PLANTA DOS



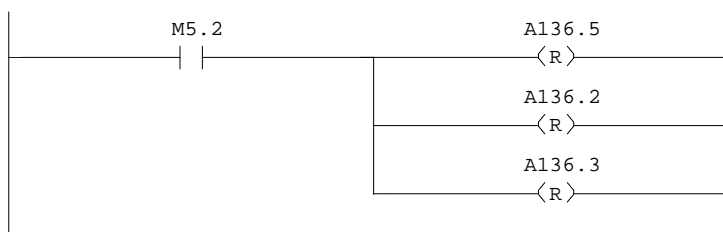
Segm.: 34 SET POSICION DETECCION



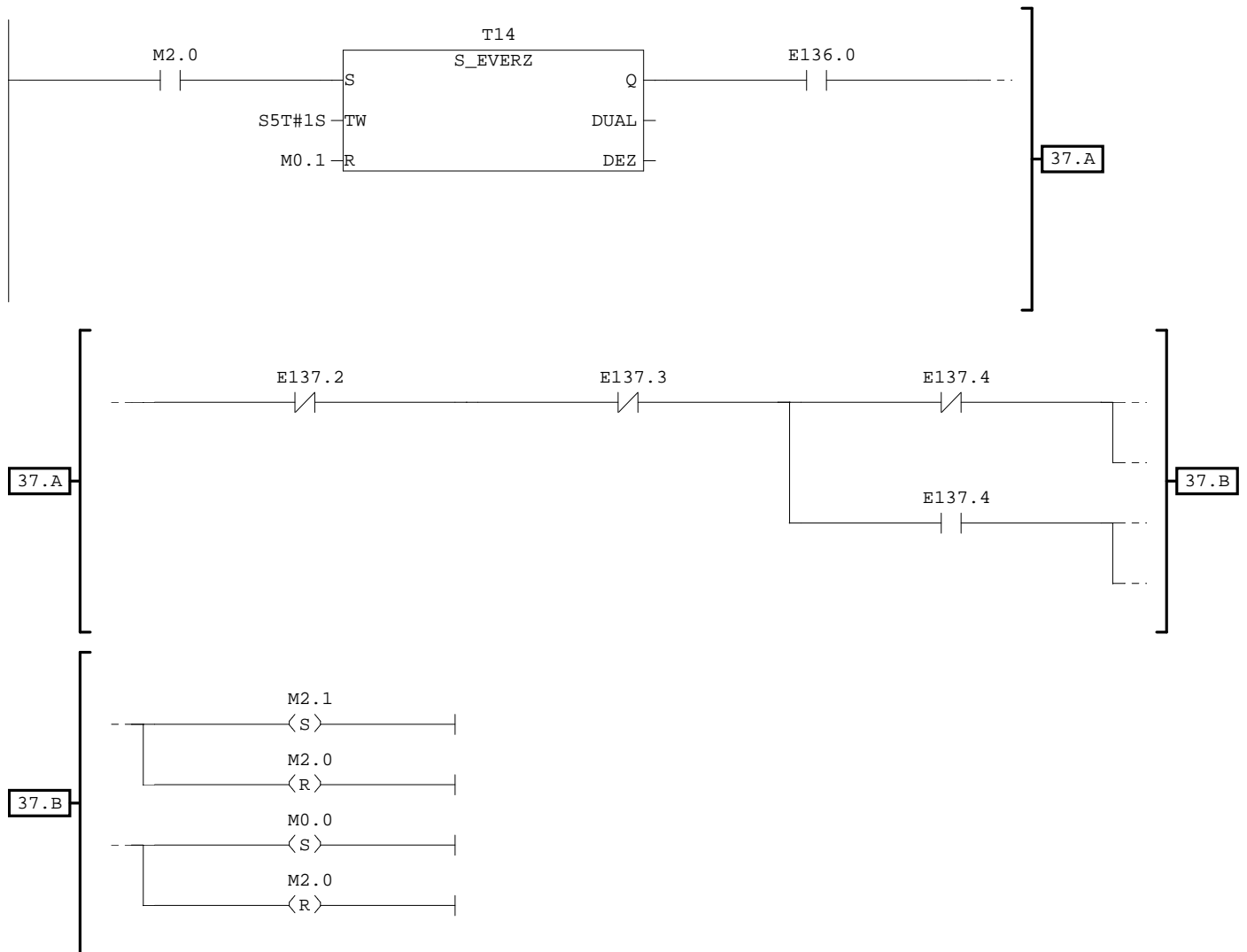
Segm.: 35 RESET



Segm.: 36 RESET



Segm.:	37	RECOGER BRAZO
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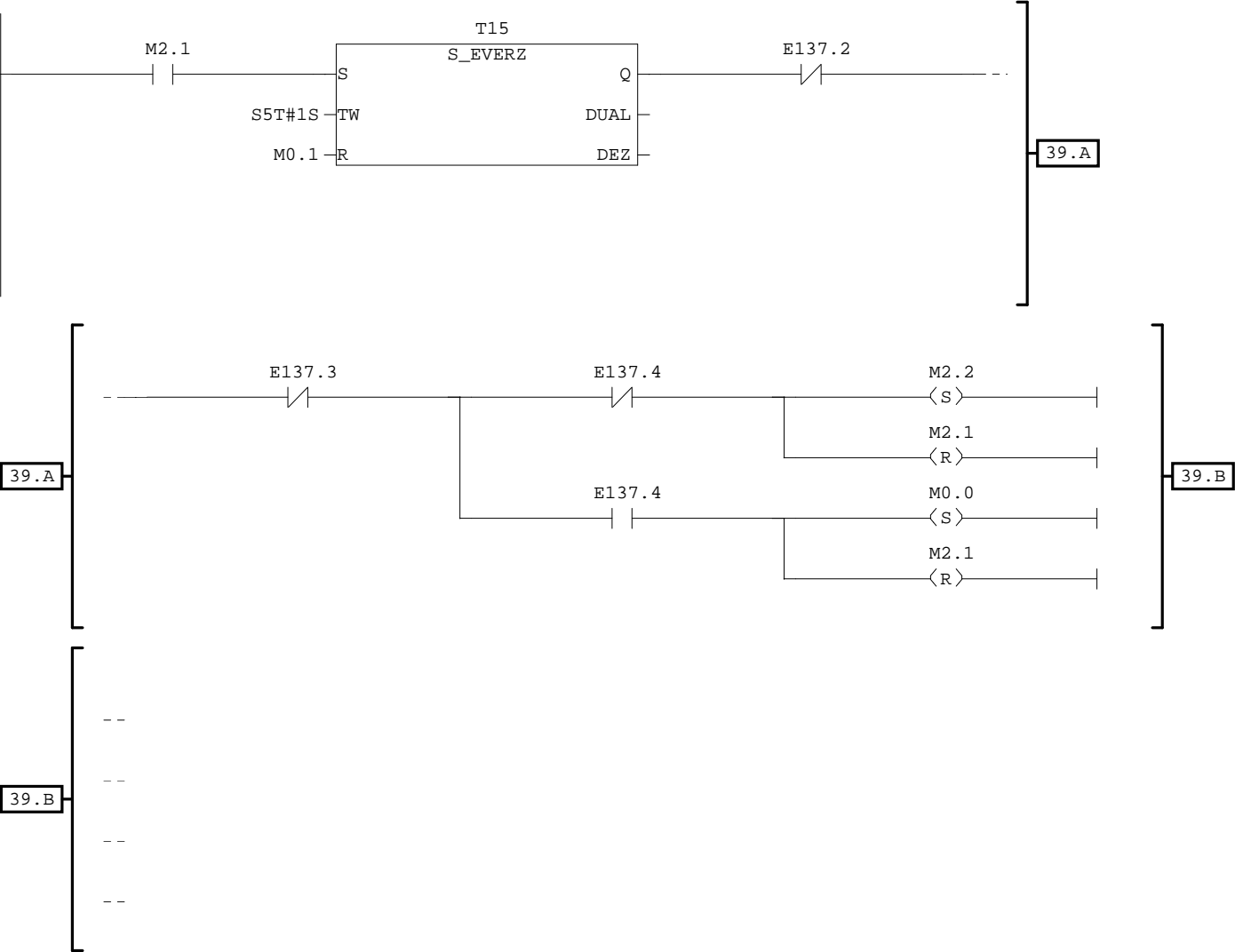


Segm.: 38	RECOGER BRAZO
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Segm.: 39

SET POSICION ARRIBA

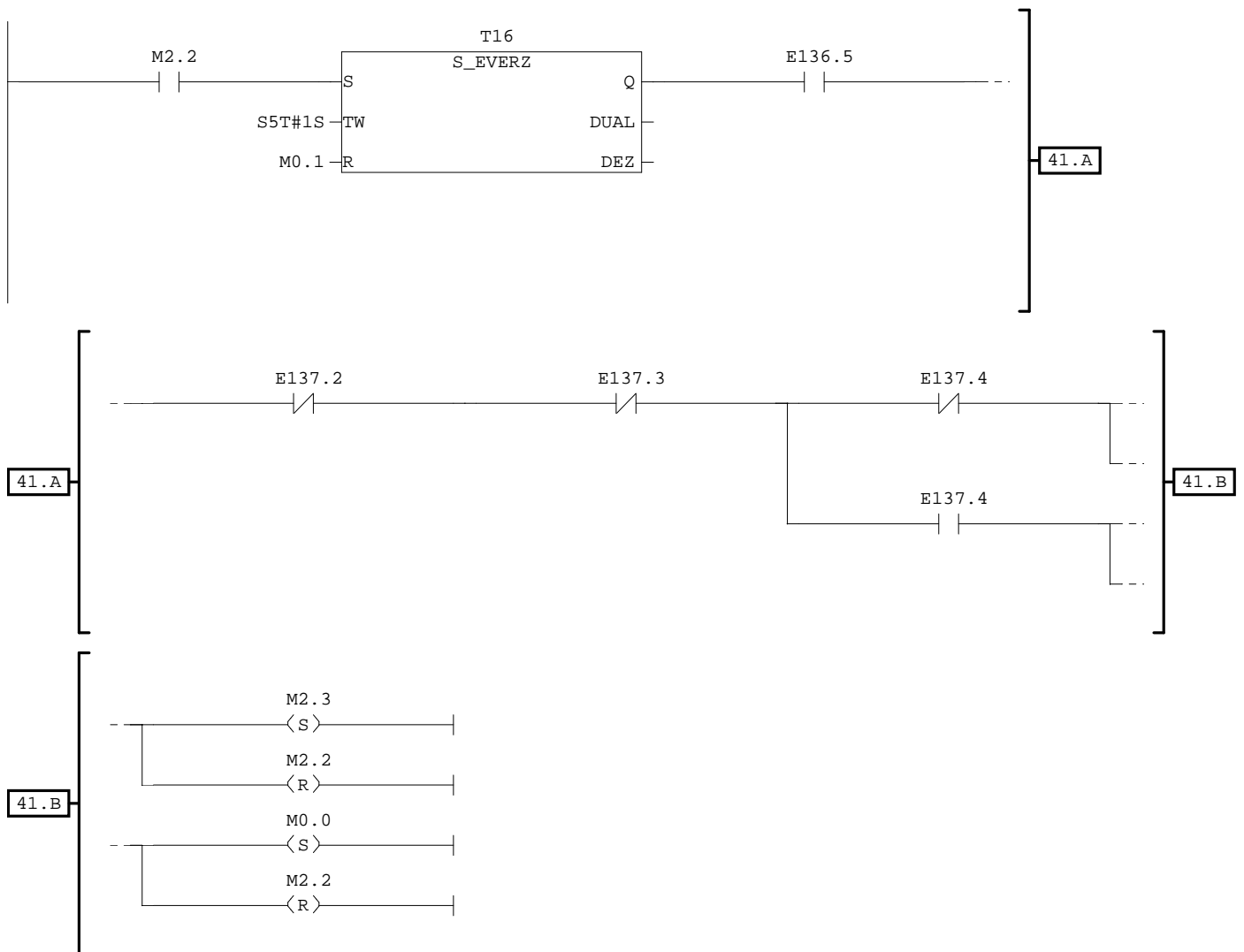


Segm.: 40

SET DE POSICION



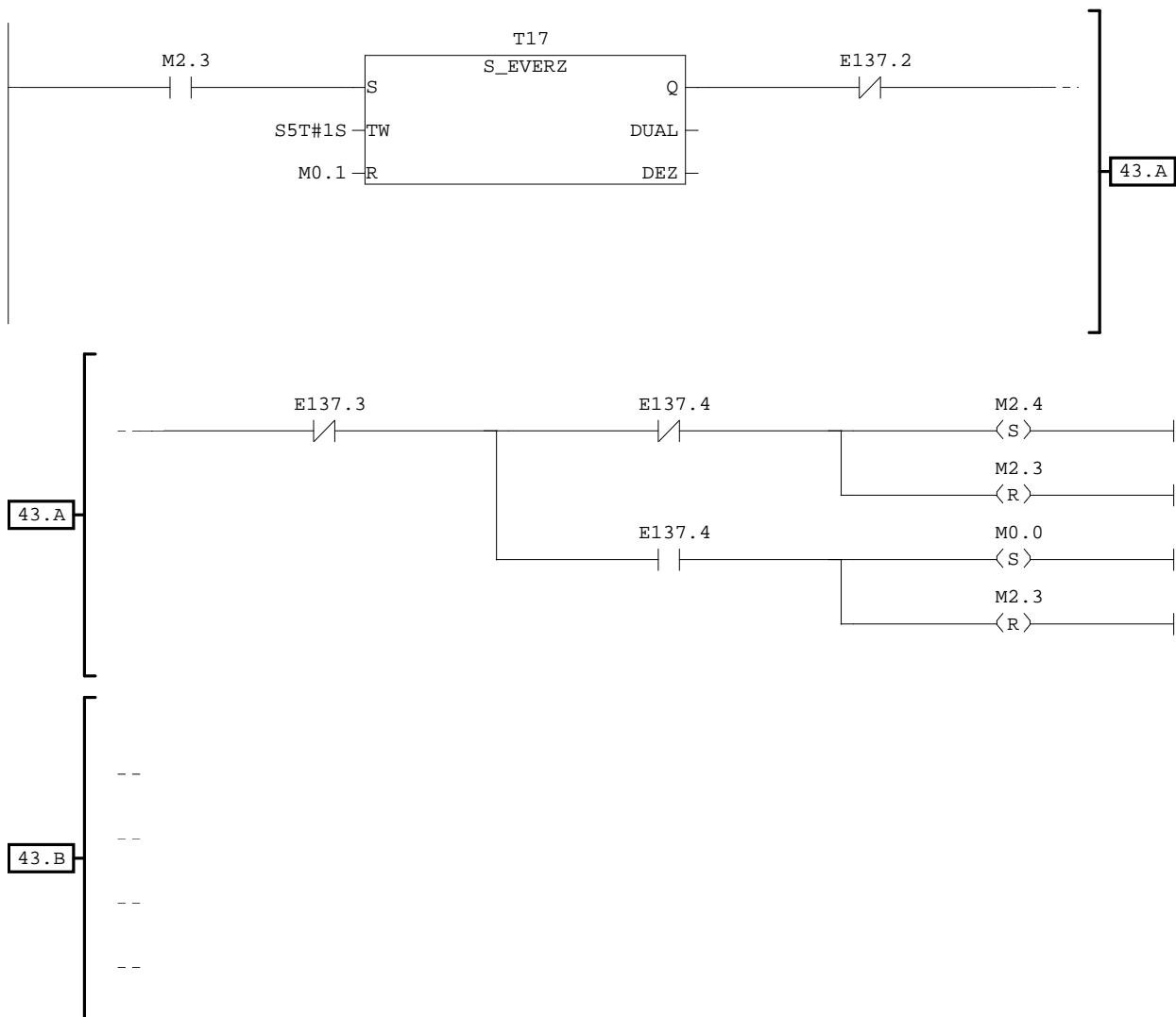
Segm.: 41 MOVER ARRIBA



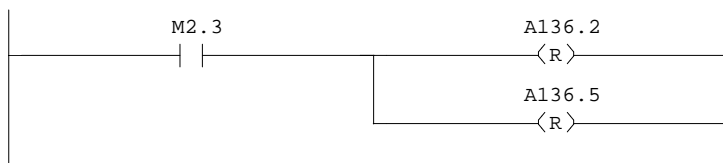
Segm.: 42 MOVER ARRIBA



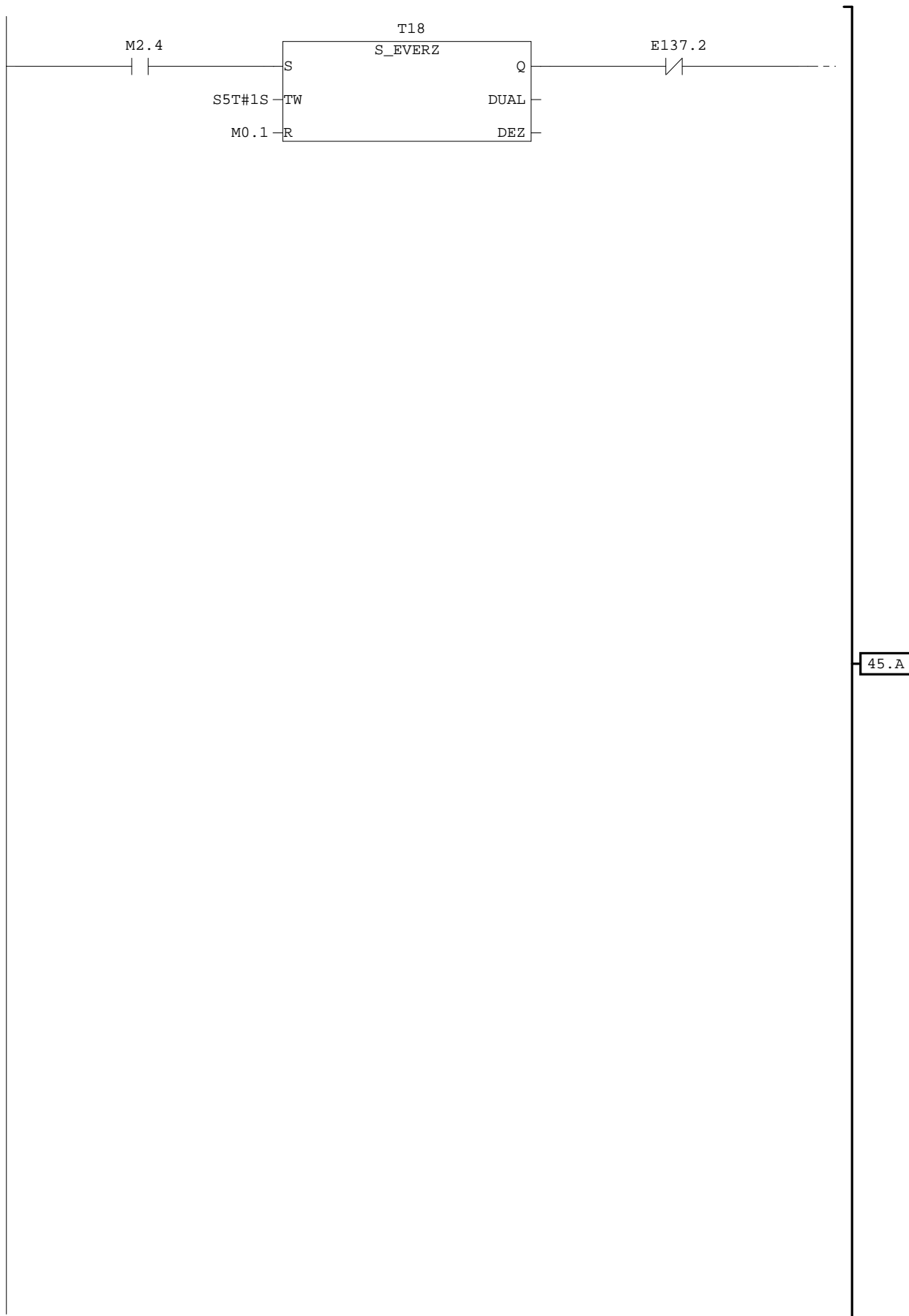
Segm.: 43 RESET



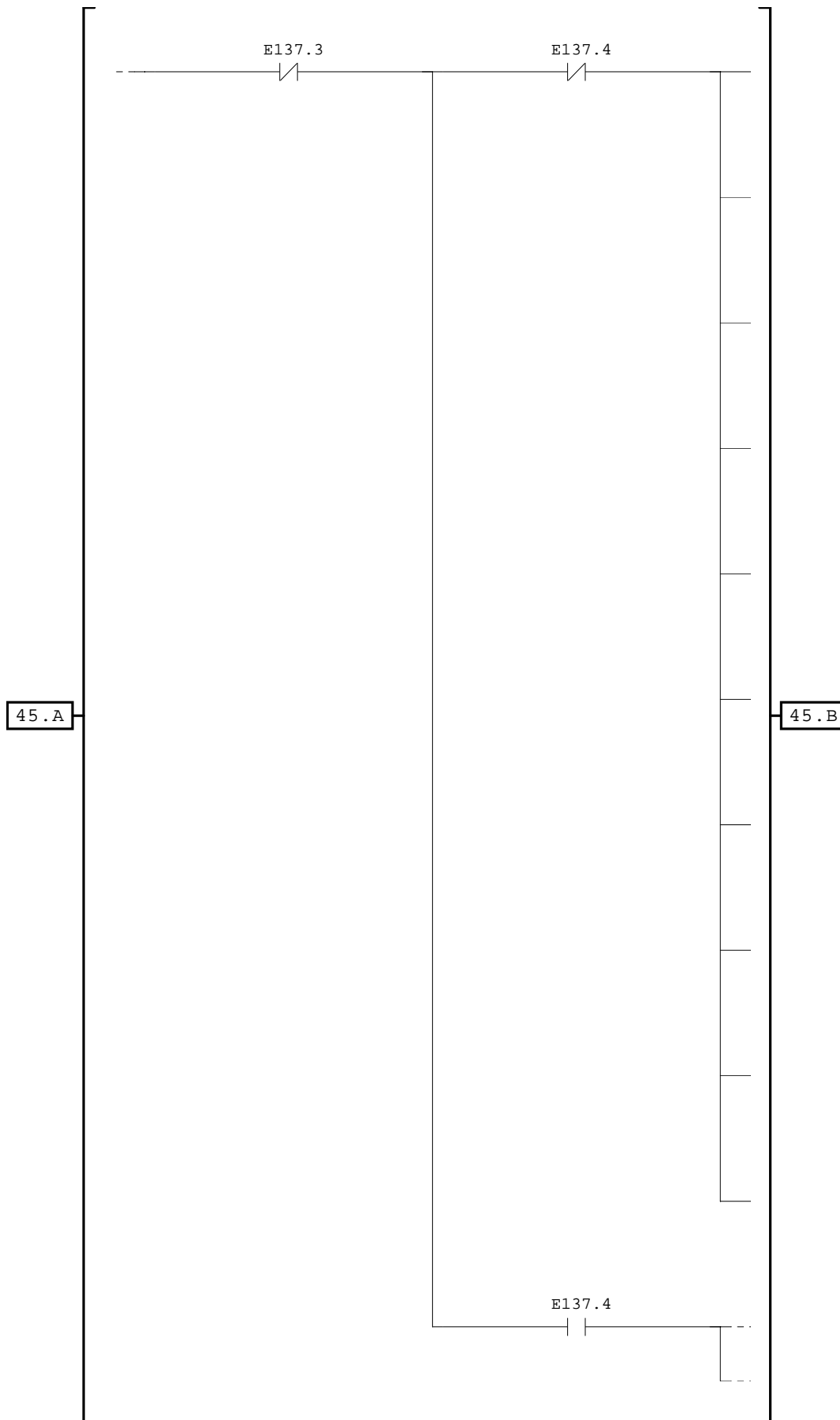
Segm.: 44 RESET

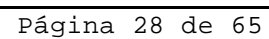


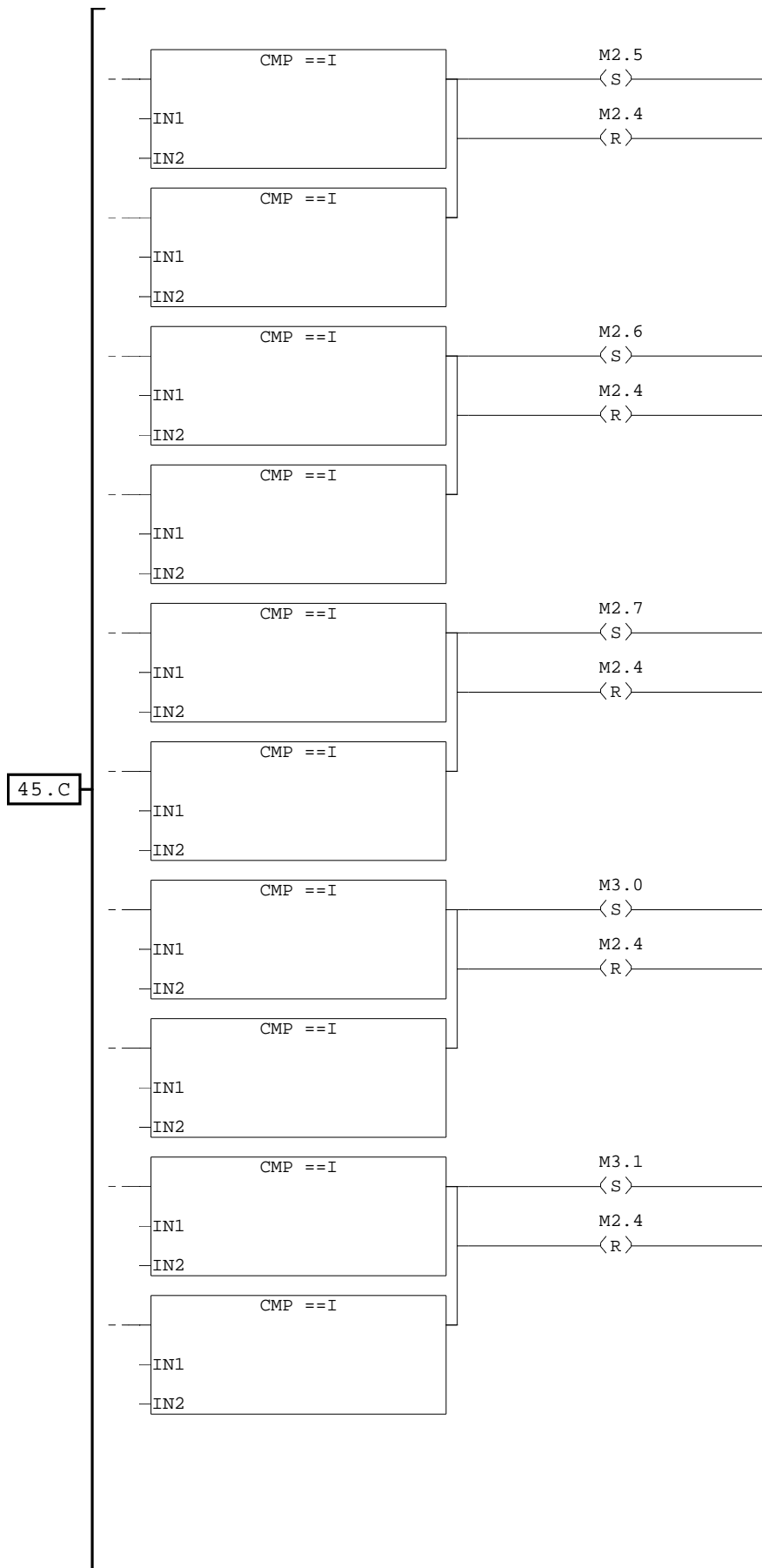
Segm.: 45 SELECCION DE POSICION



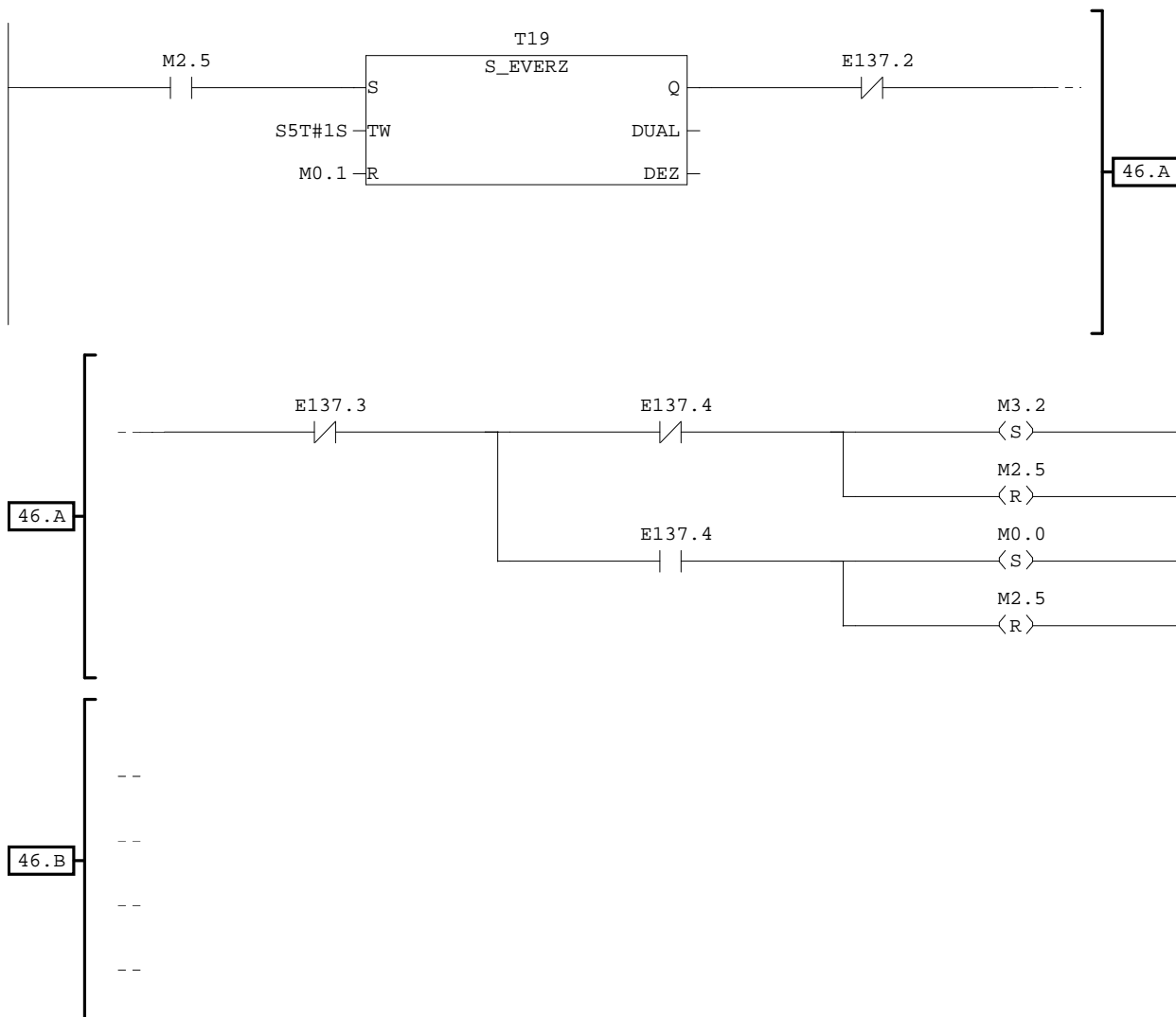
45.A



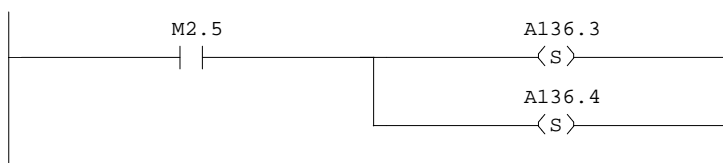




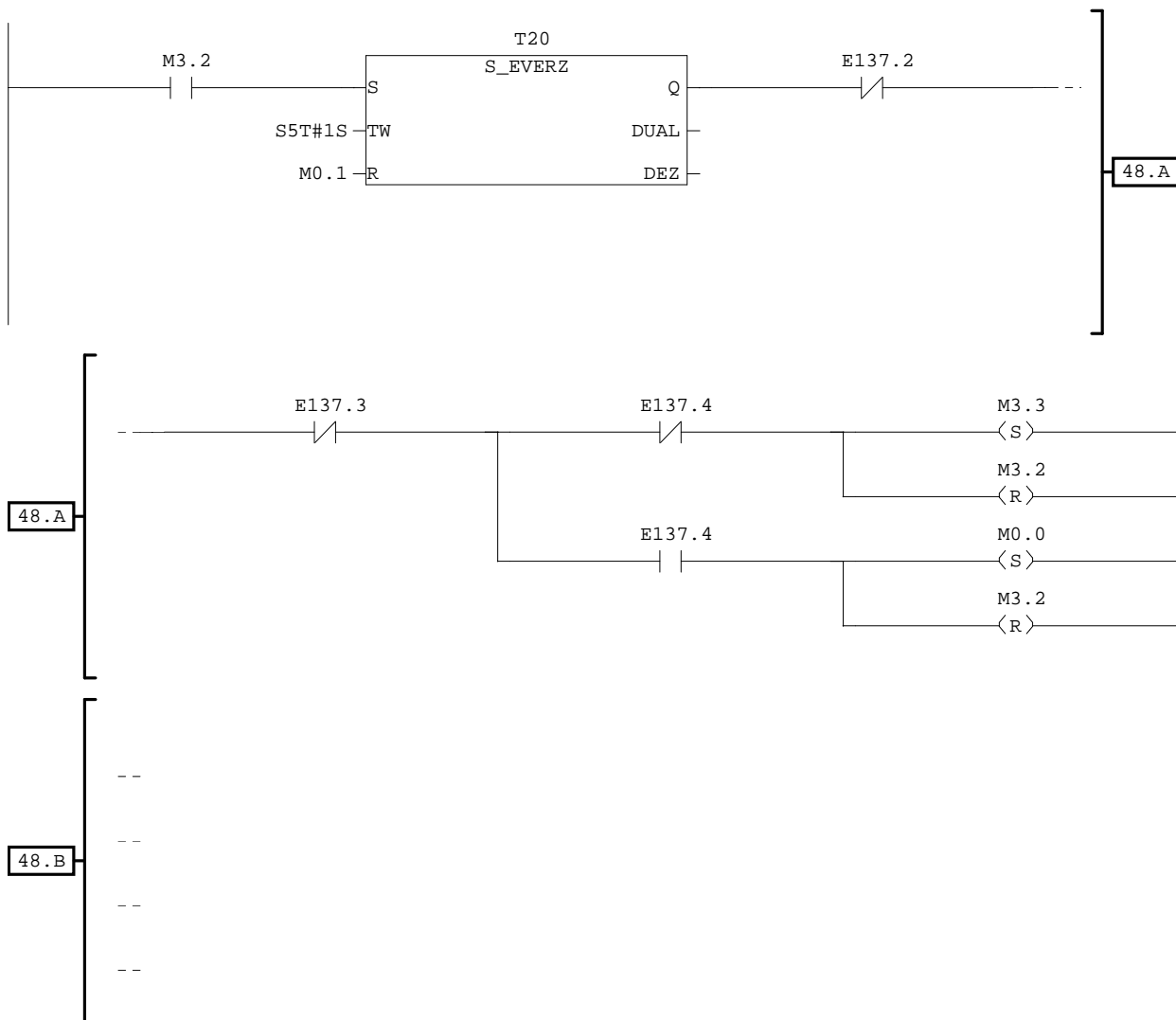
Segm.: 46 SET POSICION 1



Segm.: 47 SET POSICION 1



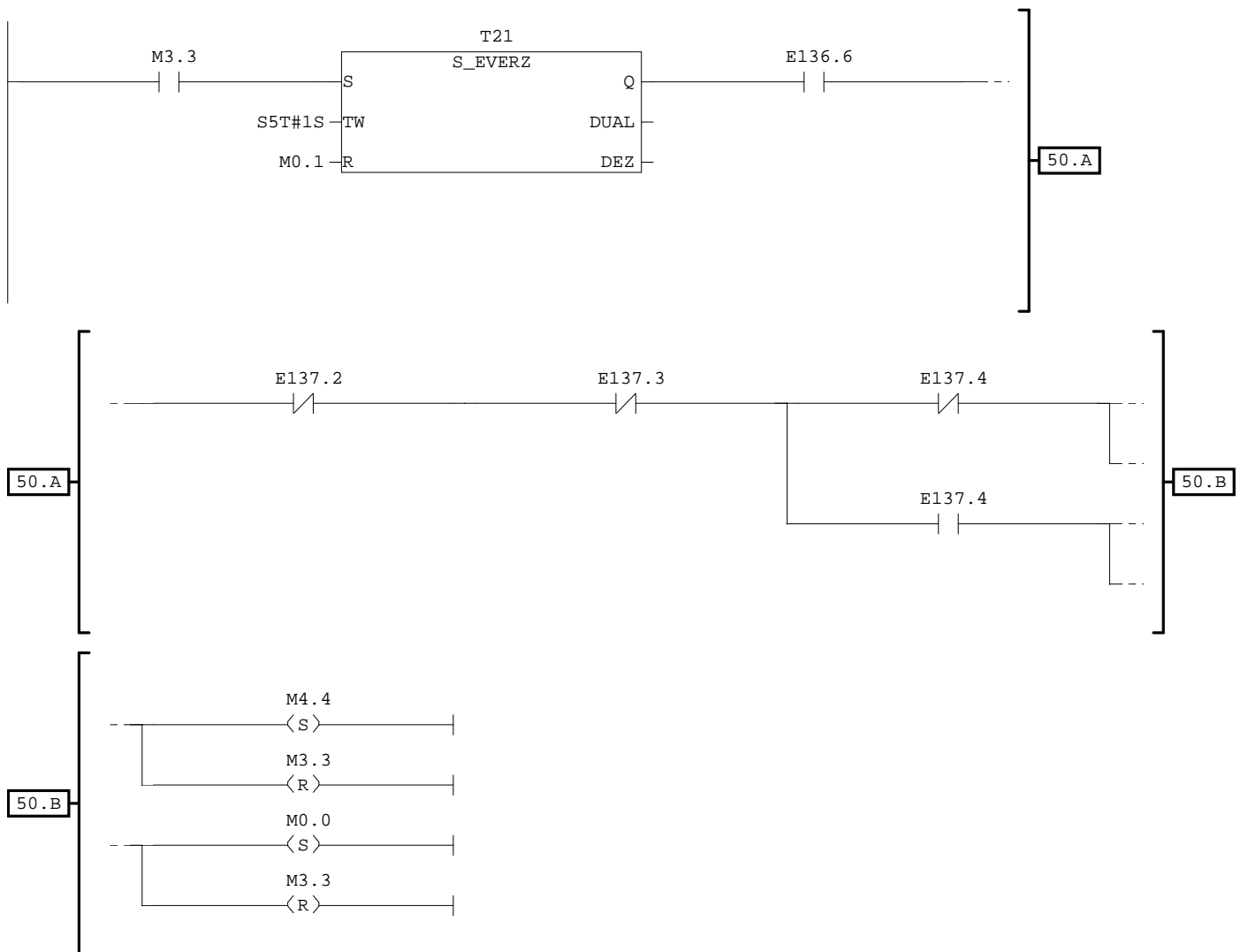
Segm.: 48 GIRO POSICION 1



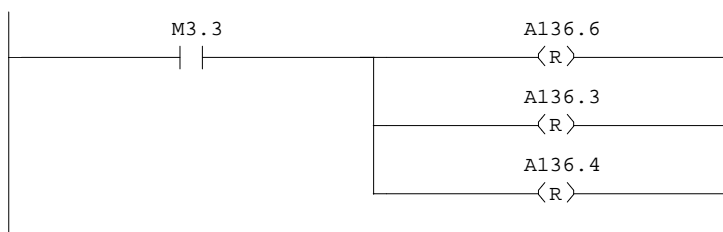
Segm.: 49 GIRO POSICION 1



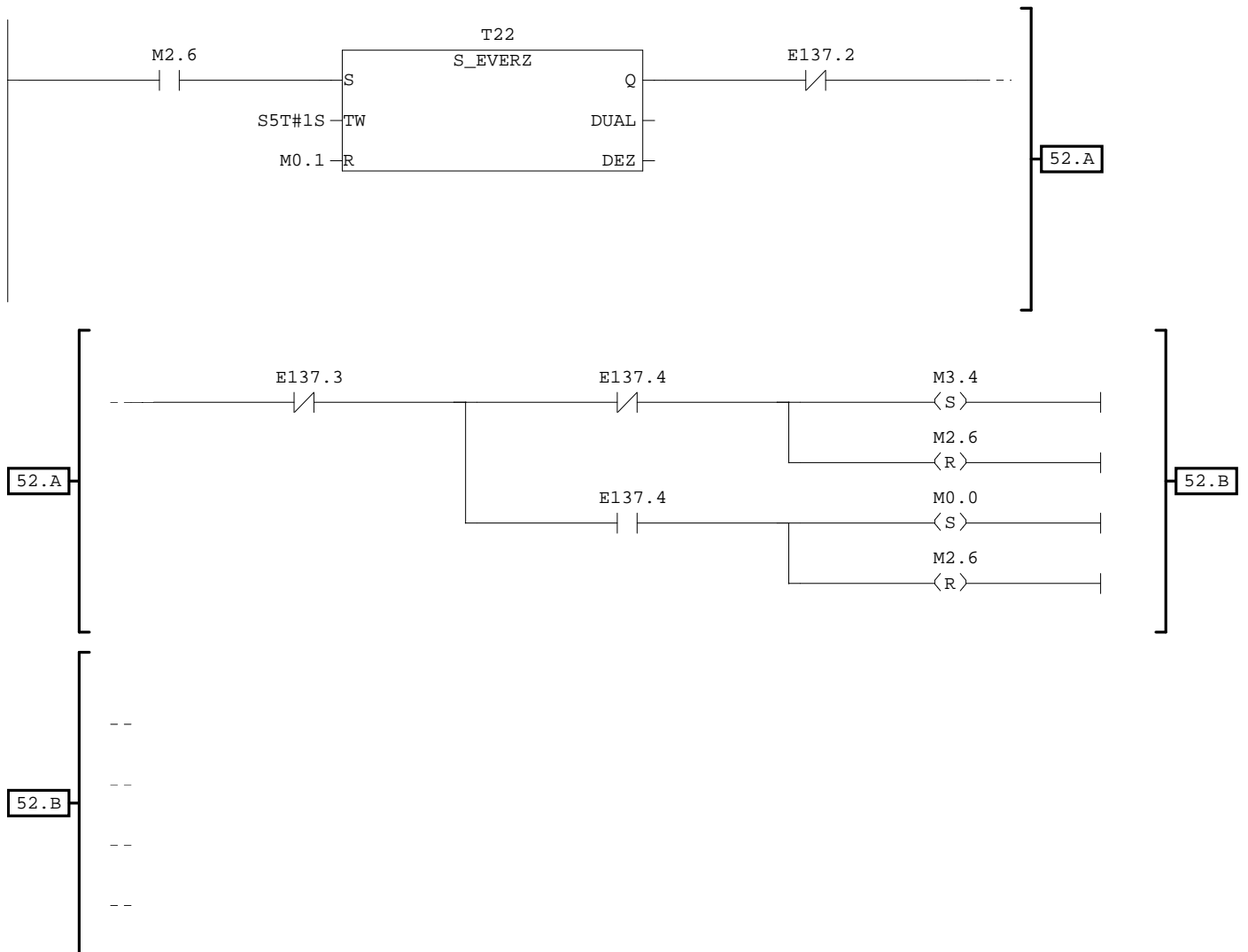
Segm.: 50 RESET



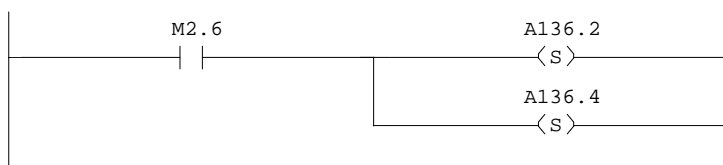
Segm.: 51 RESET



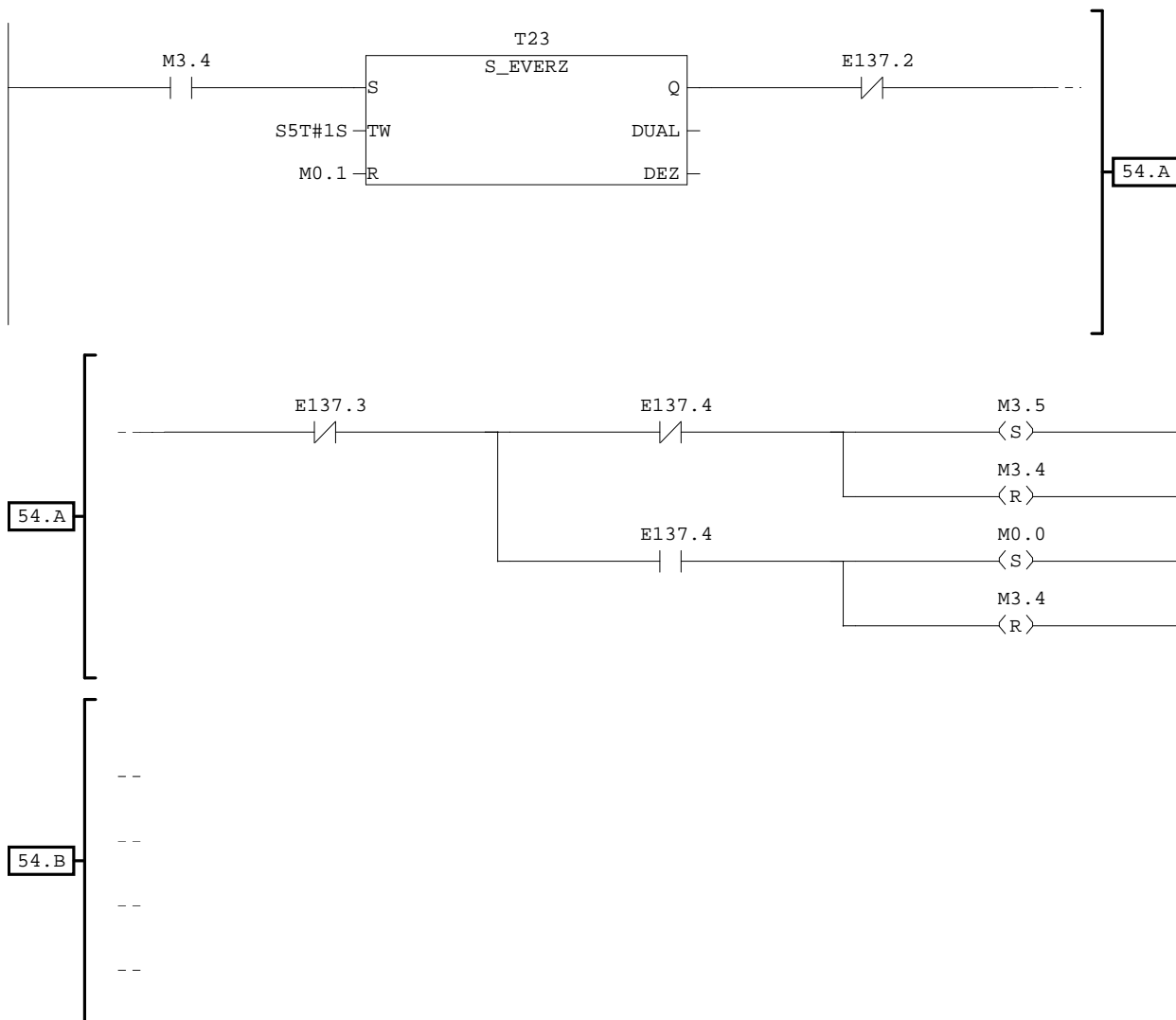
Segm.: 52 SET POSICION 2



Segm.: 53 SET POSICION 2



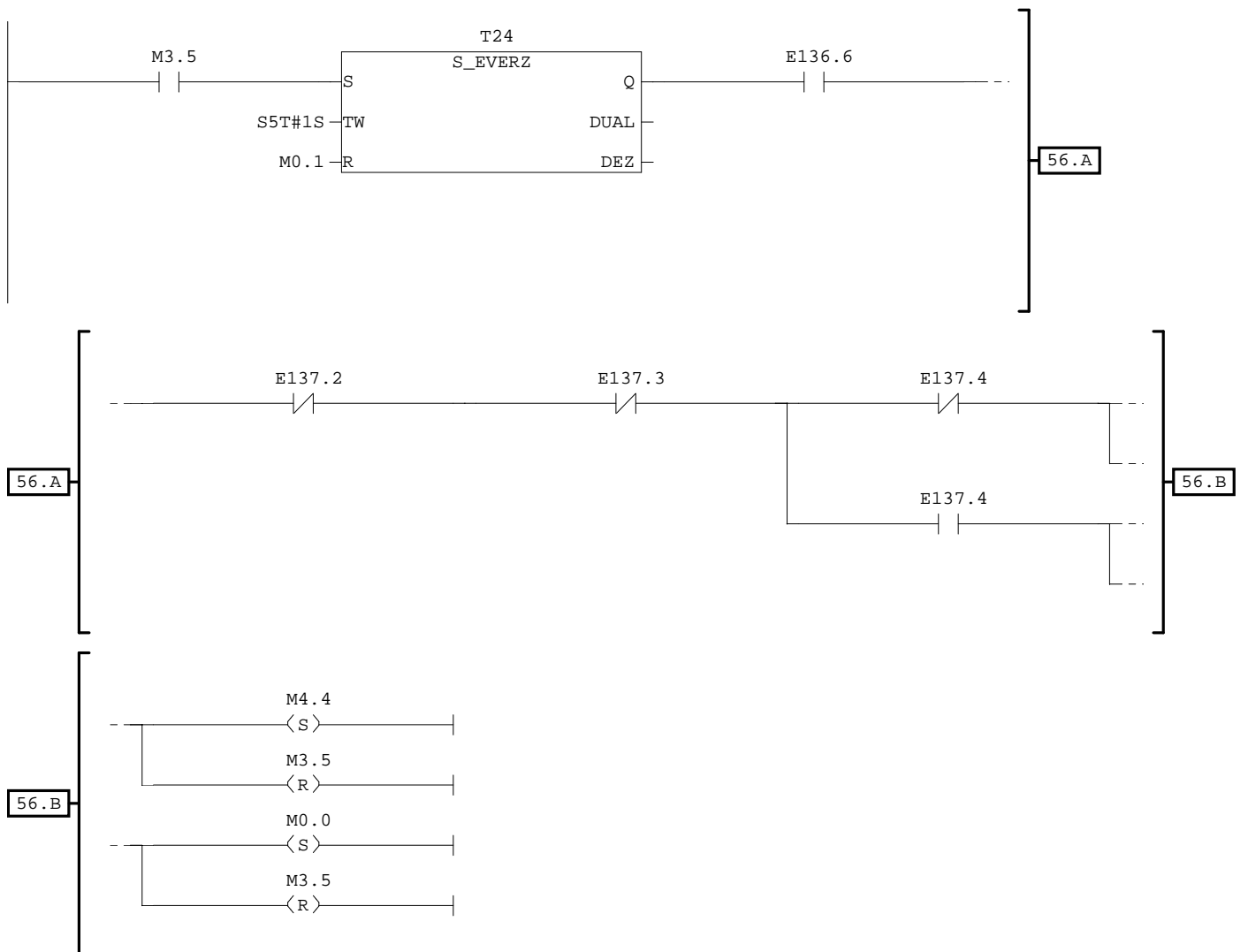
Segm.: 54 GIRO POSICION 2



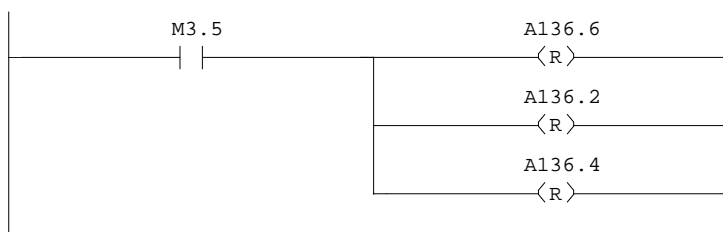
Segm.: 55 GIRO POSICION 2



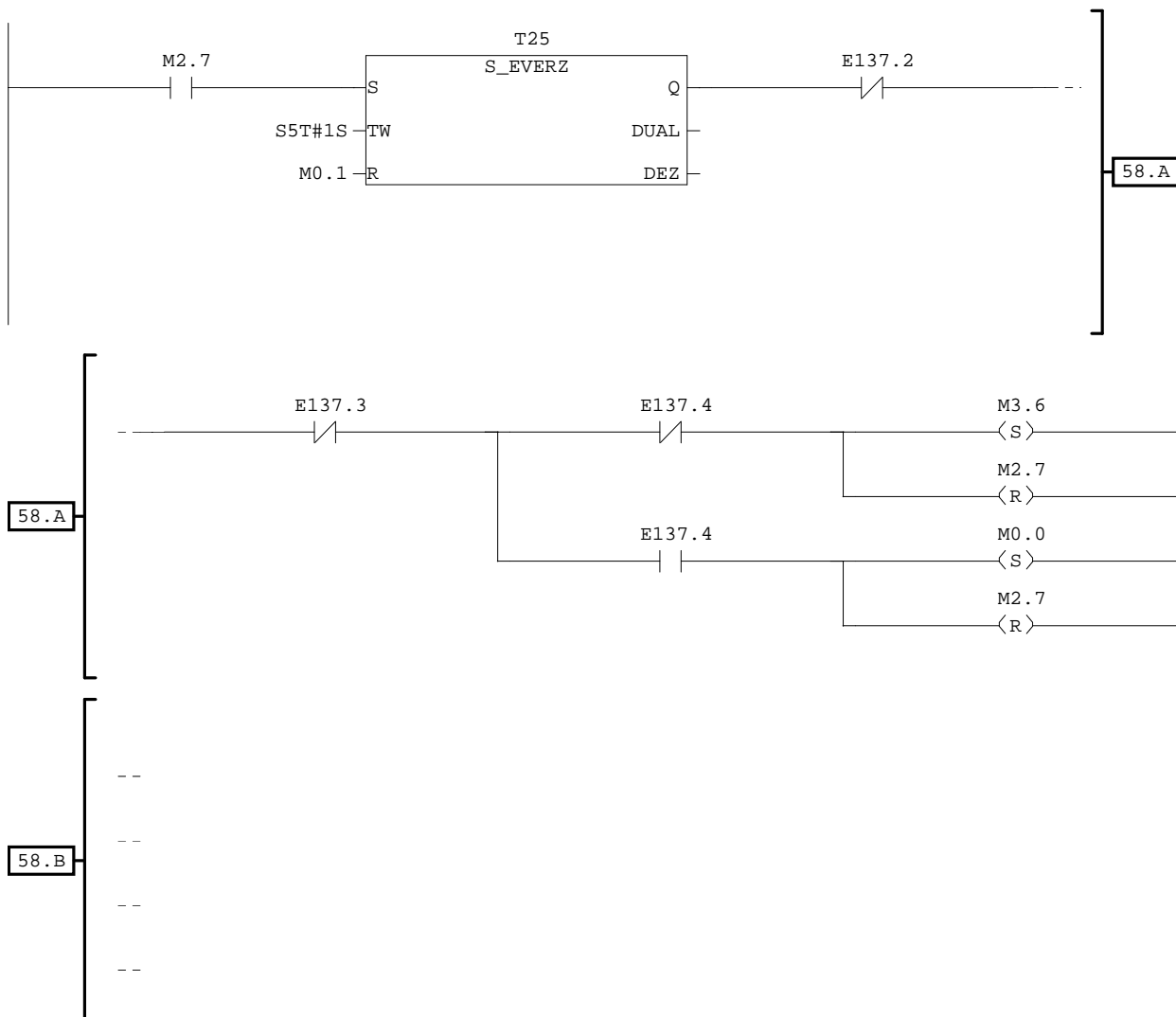
Segm.: 56 RESET



Segm.: 57 RESET



Segm.: 58 SET POSICION 3

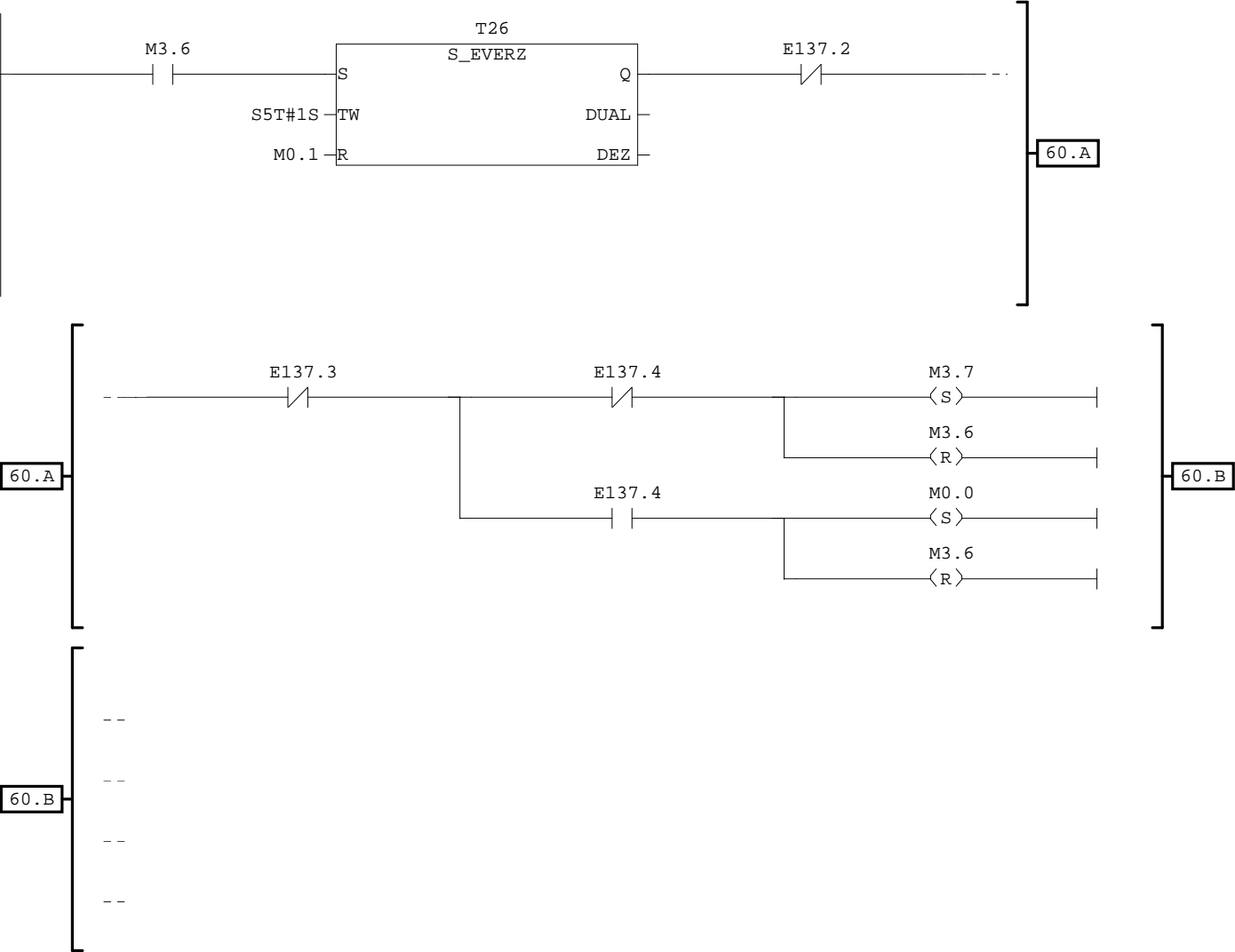


Segm.: 59 SET POSICION 3



Segm.: 60

GIRO POSICION 3

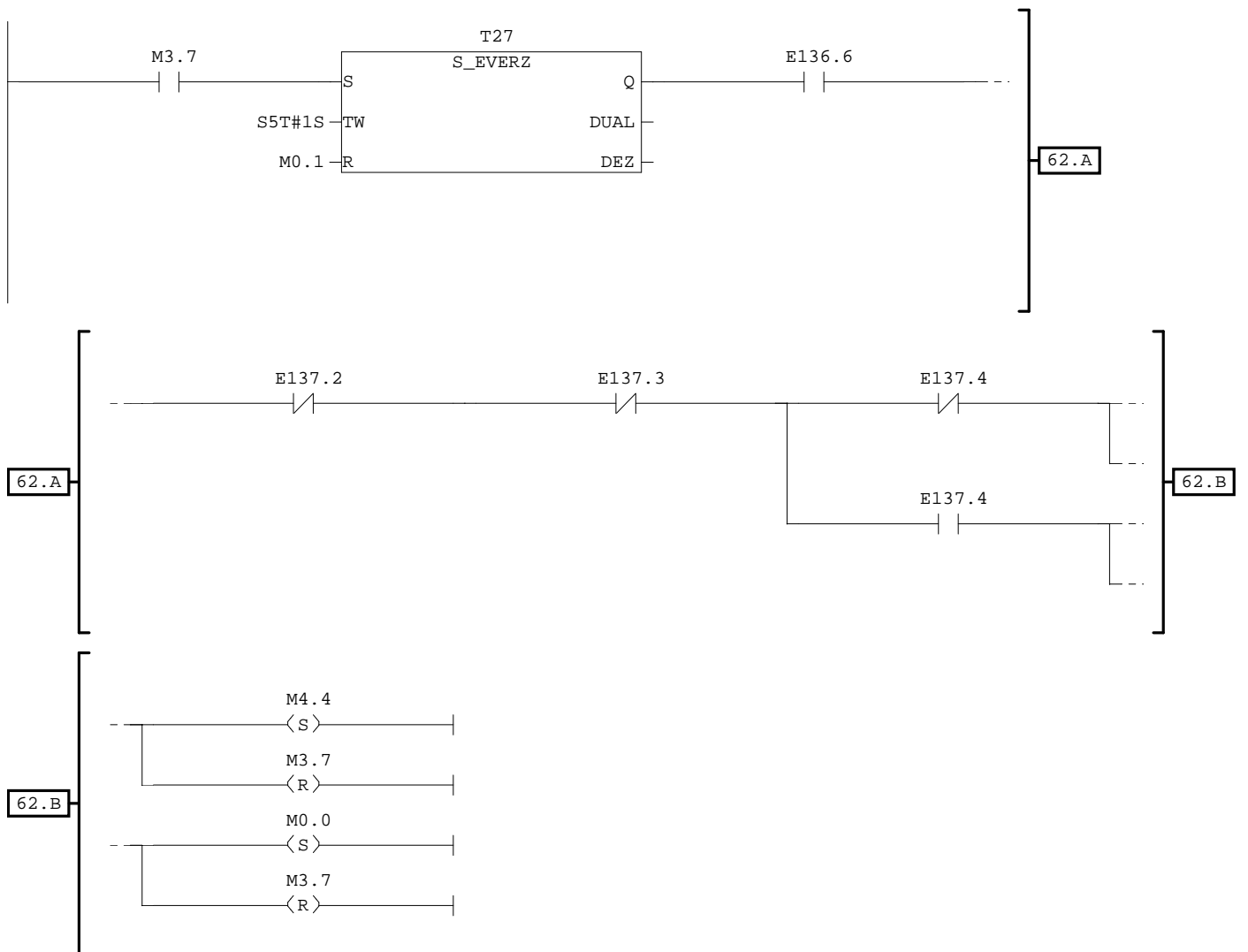


Segm.: 61

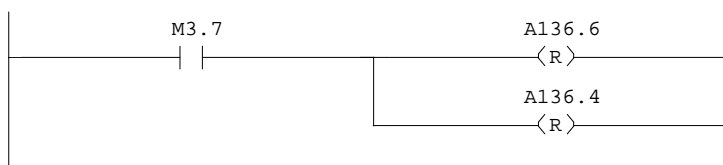
GIRO POSICION 3



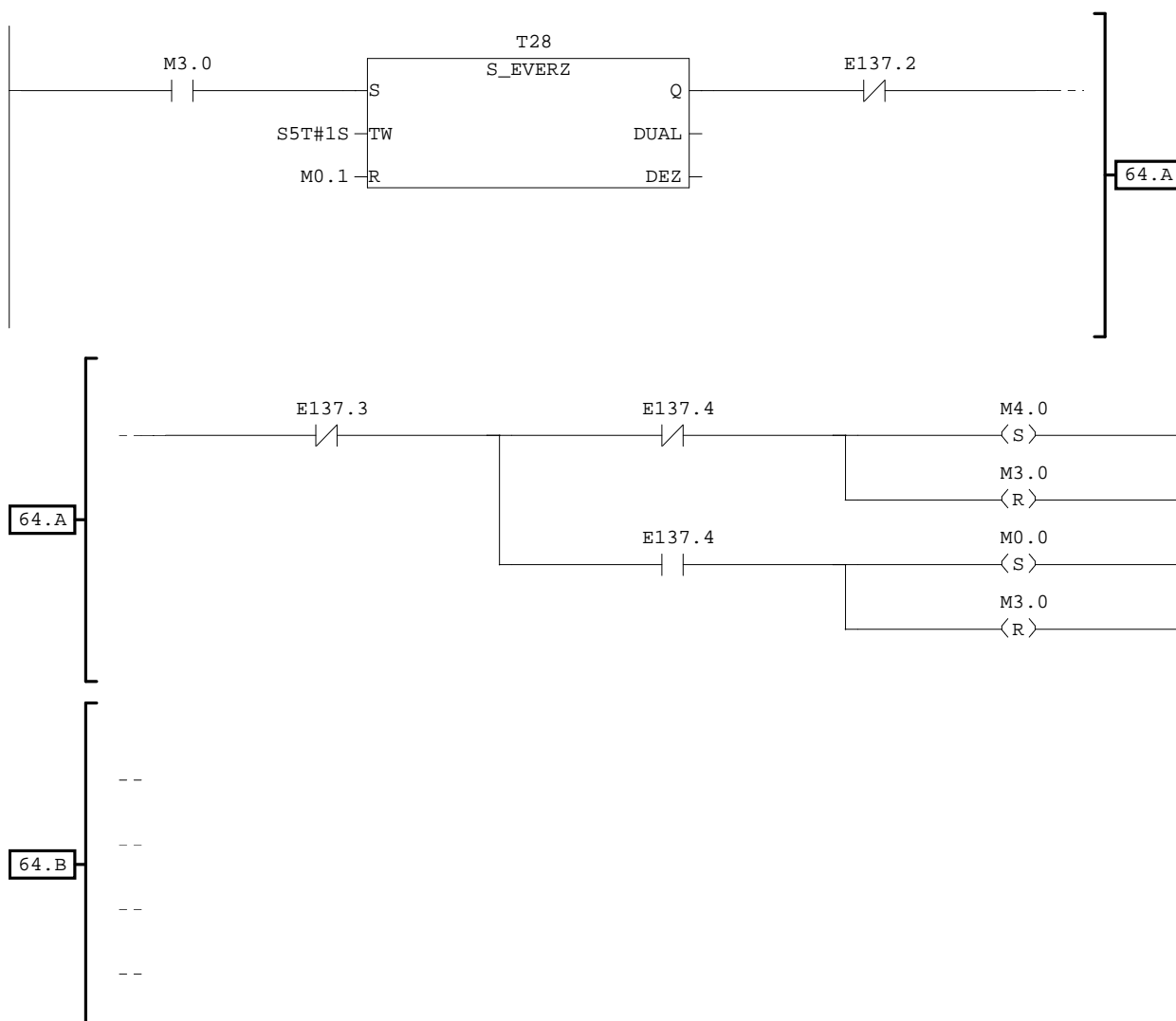
Segm.: 62 RESET



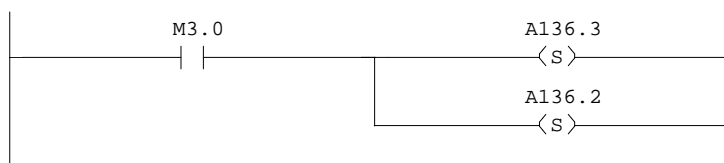
Segm.: 63 RESET



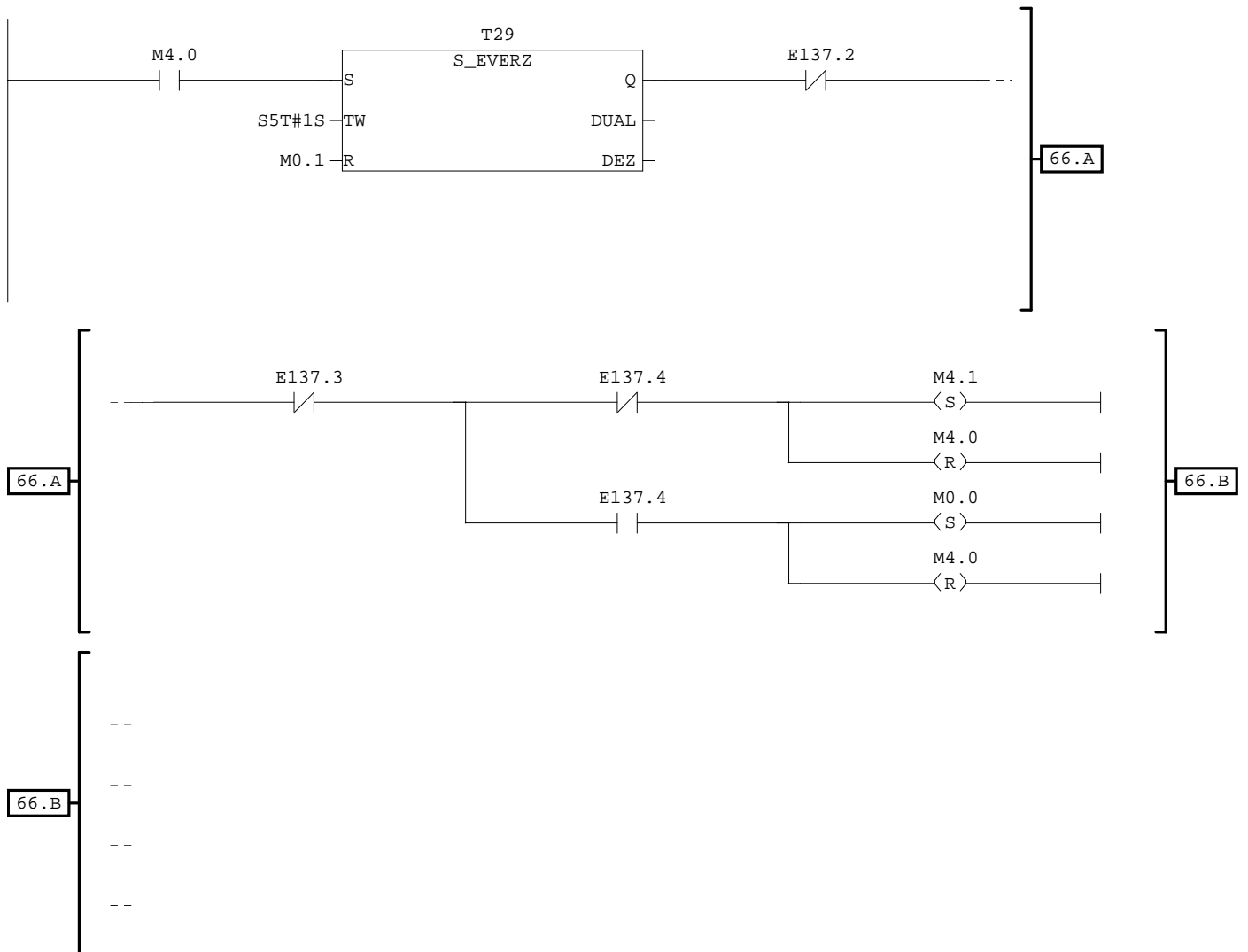
Segm.: 64 SET POSICION 4



Segm.: 65 SET POSICION 4



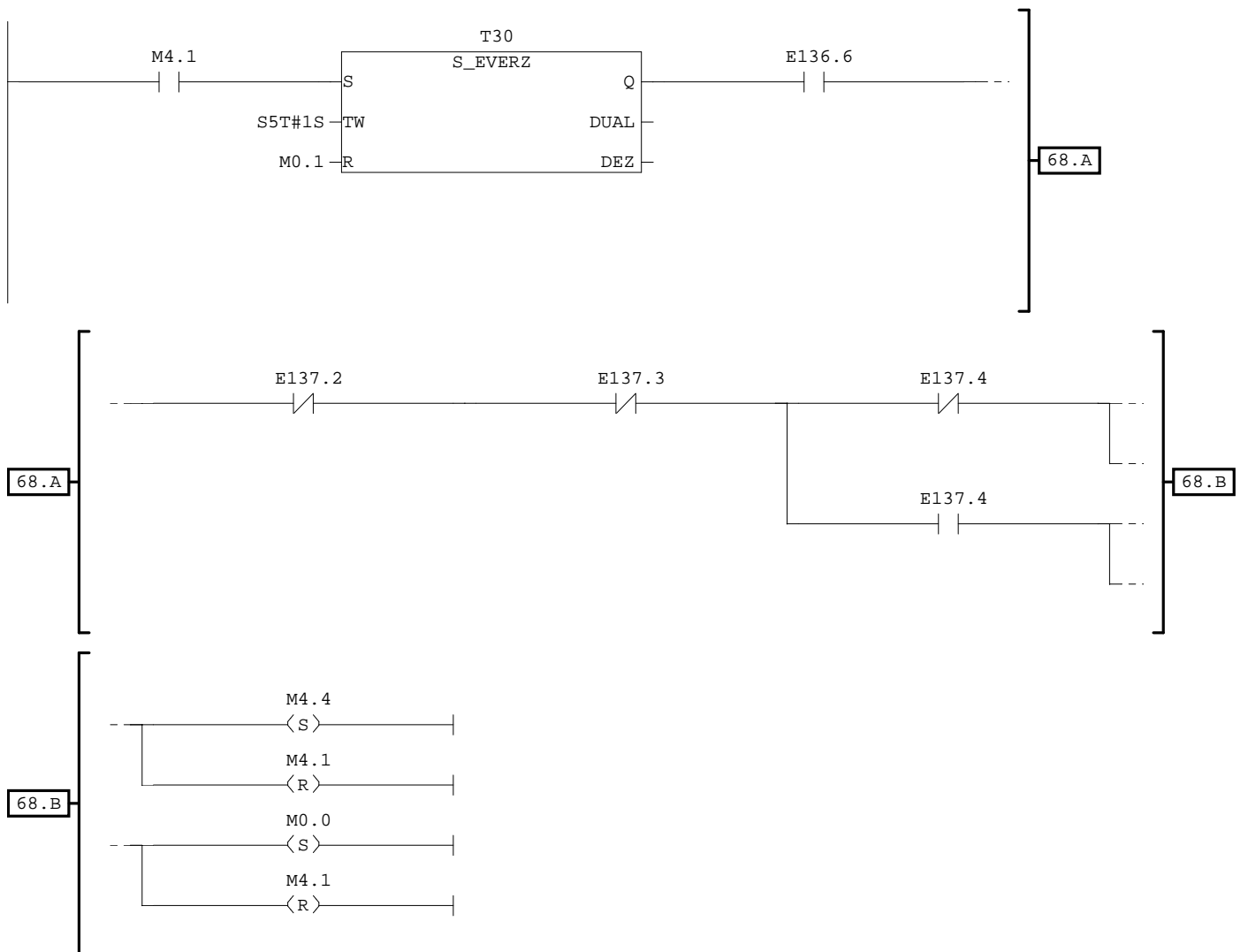
Segm.: 66 GIRO POSICION 4



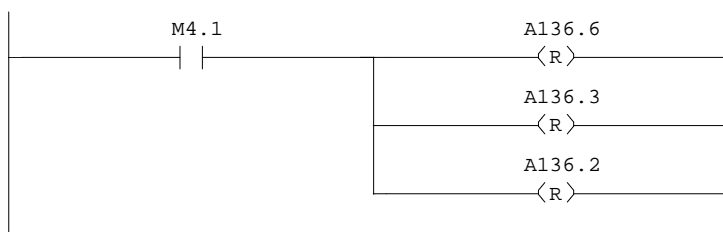
Segm.: 67 GIRO POSICION 4



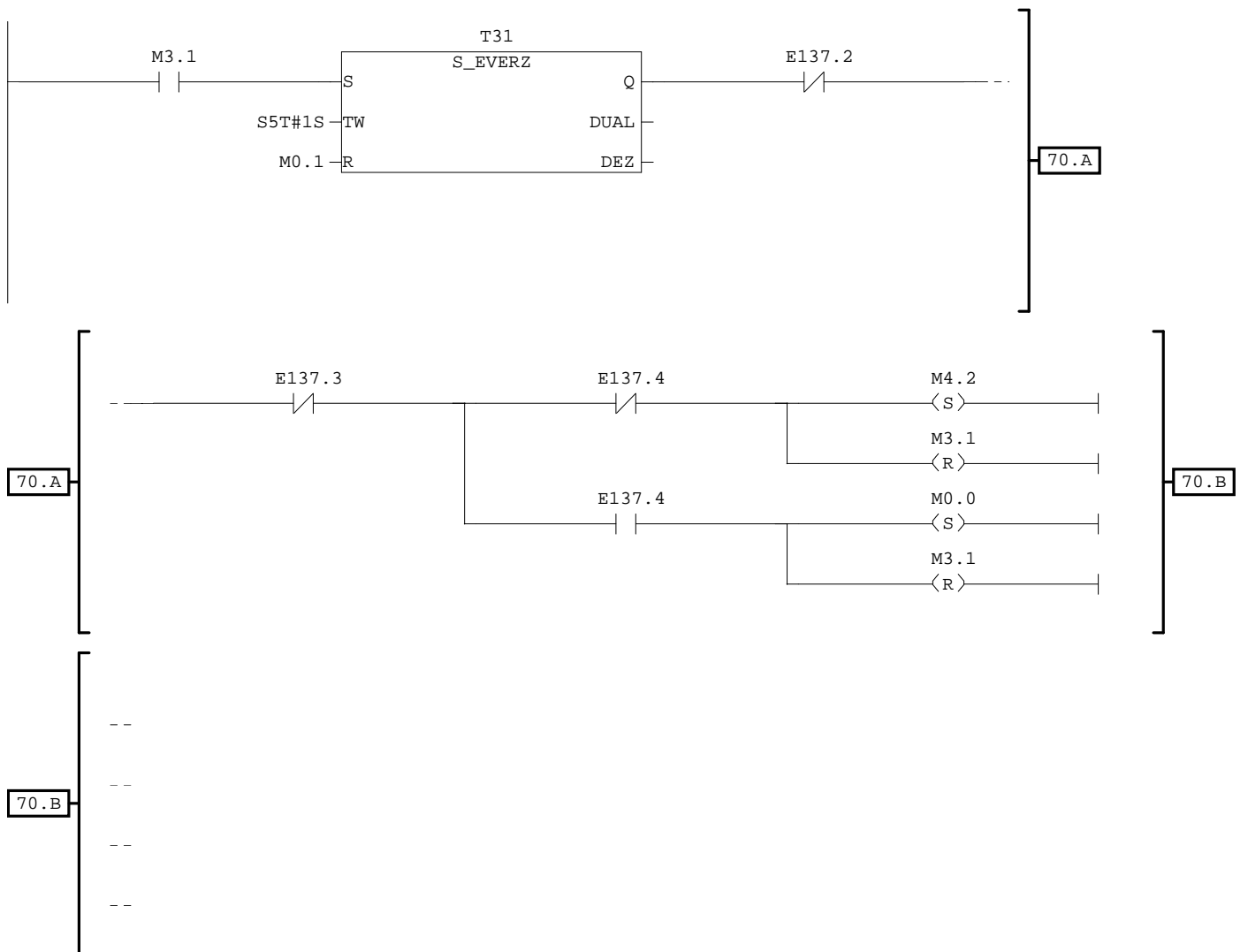
Segm.: 68 RESET



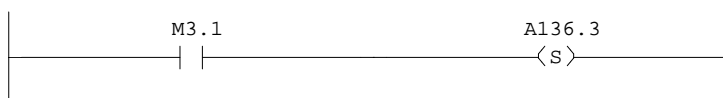
Segm.: 69 RESET



Segm.: 70 SET POSICION 5

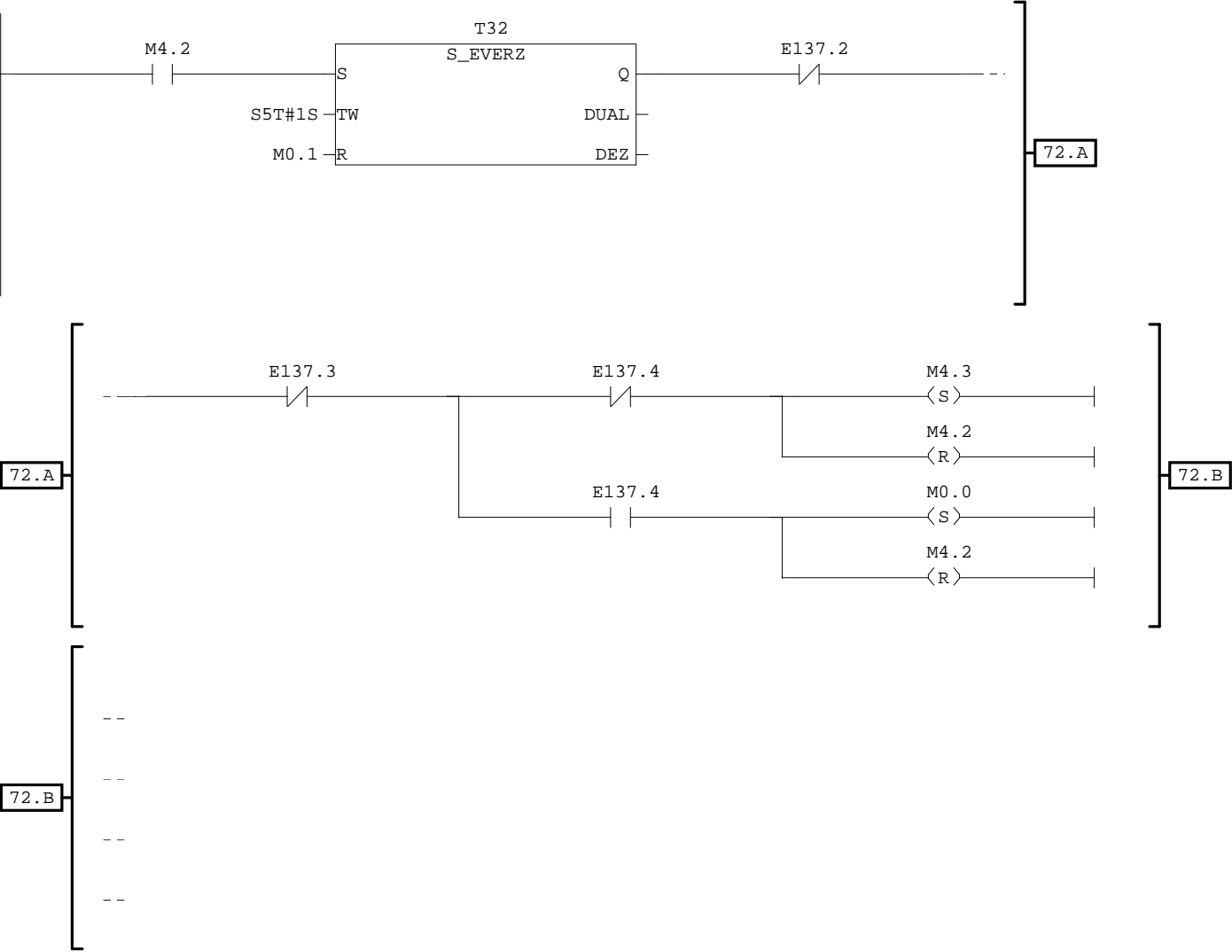


Segm.: 71 SET POSICION 5



Segm.: 72

GIRO POSICION 5

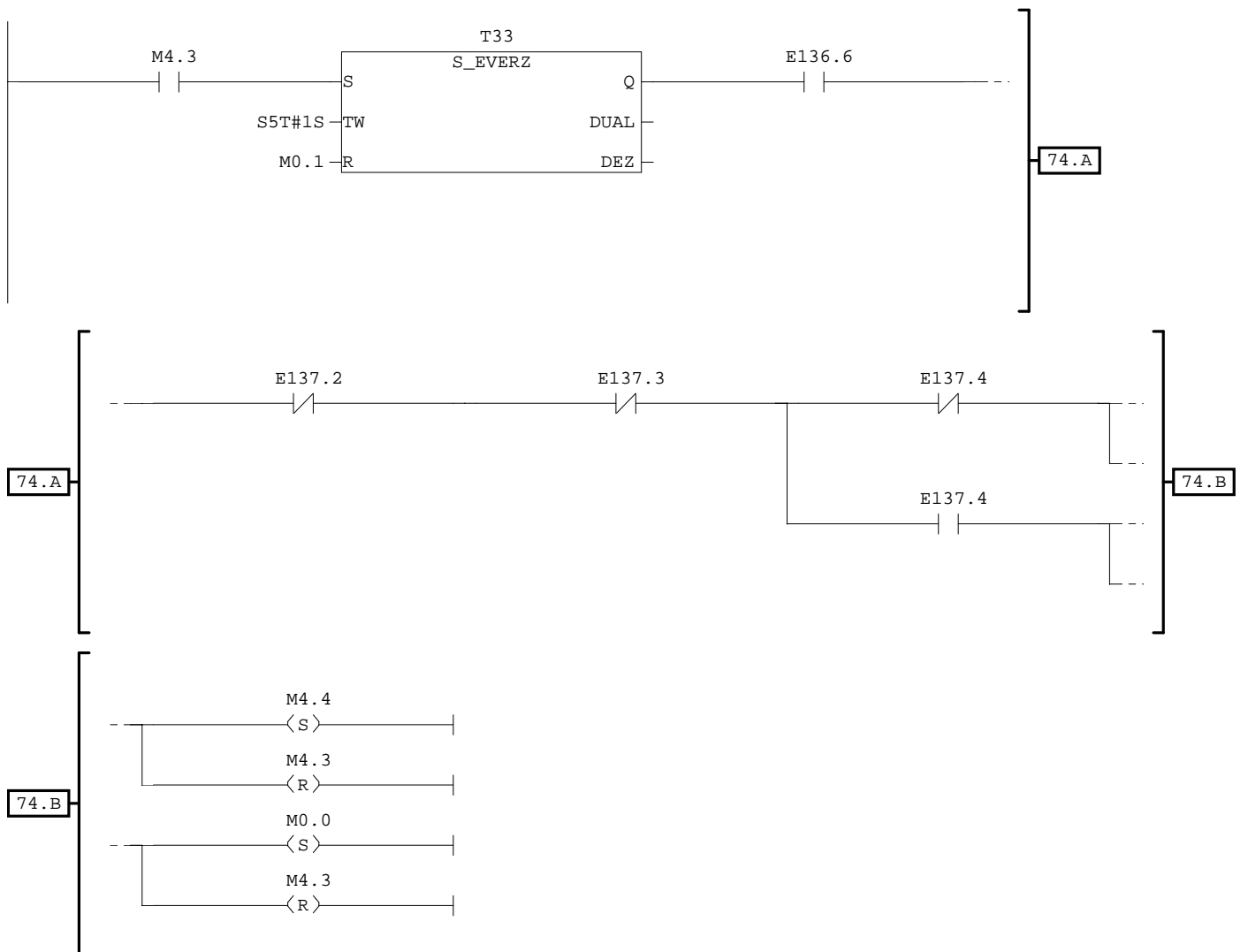


Segm.: 73

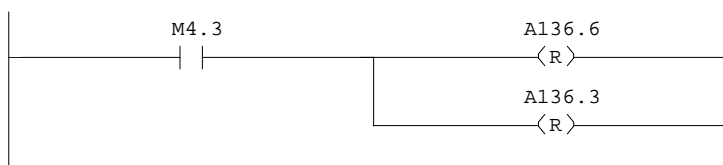
GIRO POSICION 5



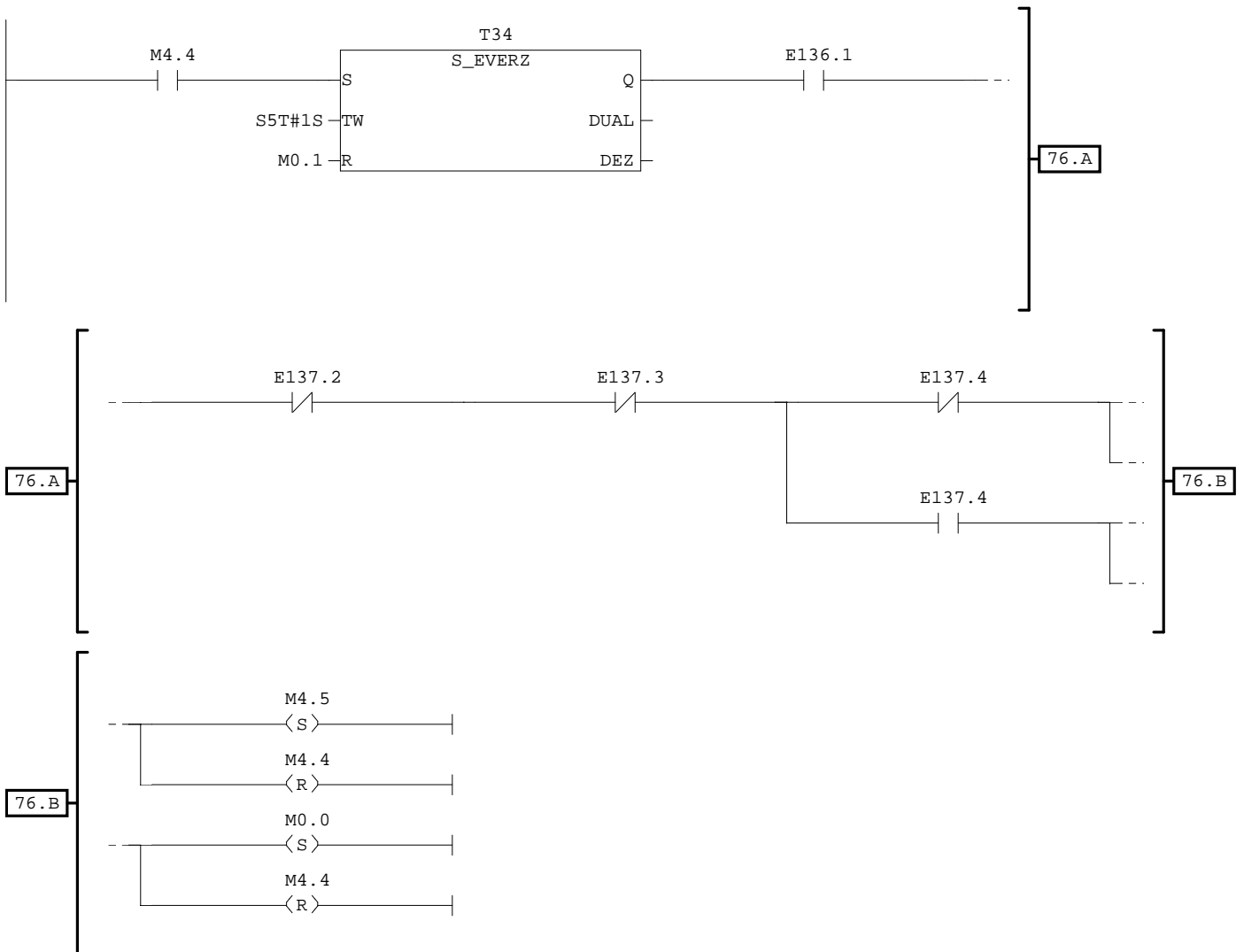
Segm.: 74 RESET



Segm.: 75 RESET



Segm.:	76	ALARGAR BRAZO
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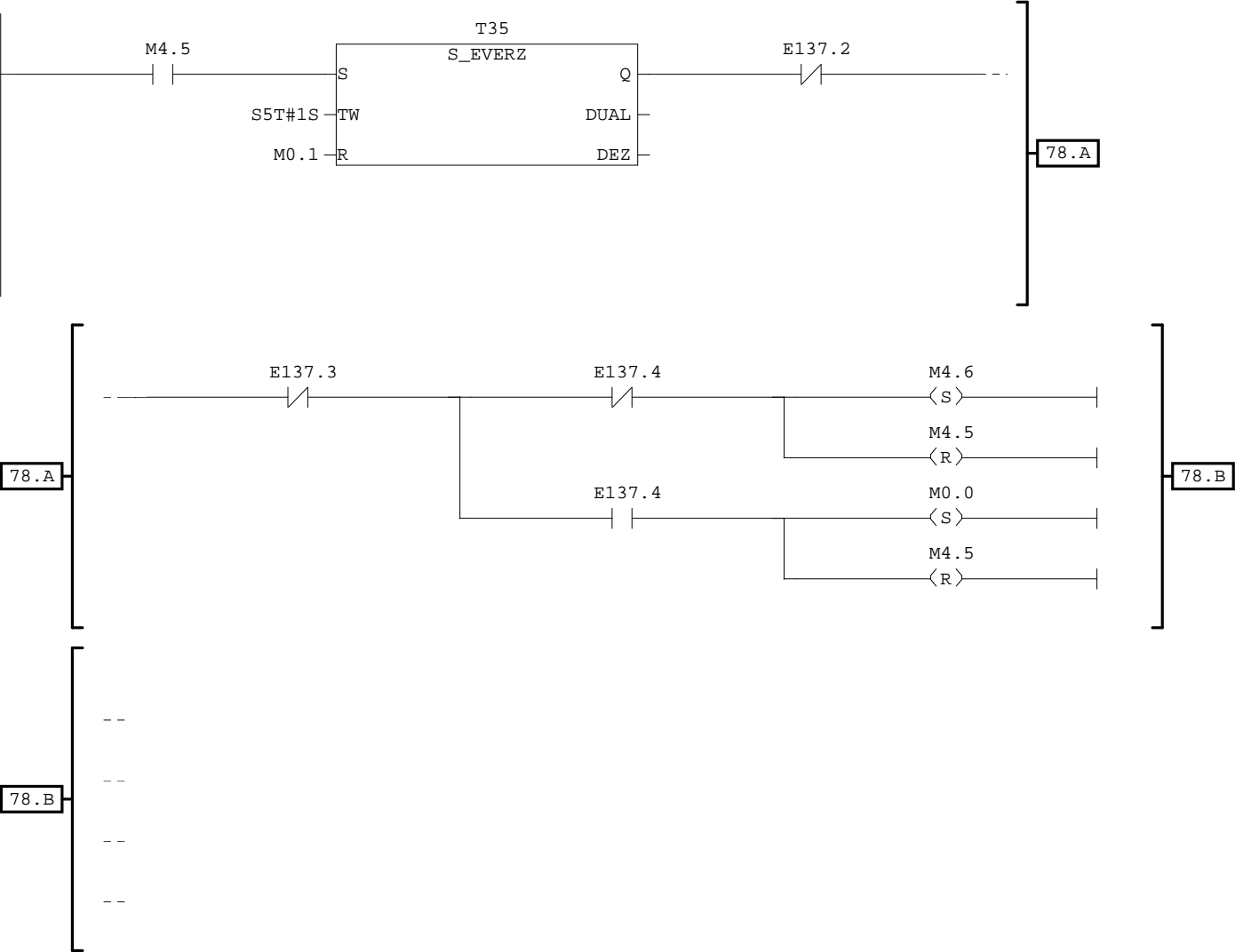


Segm.: 77	ALARGAR BRAZO
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Segm.: 78

ABRIR PINZA

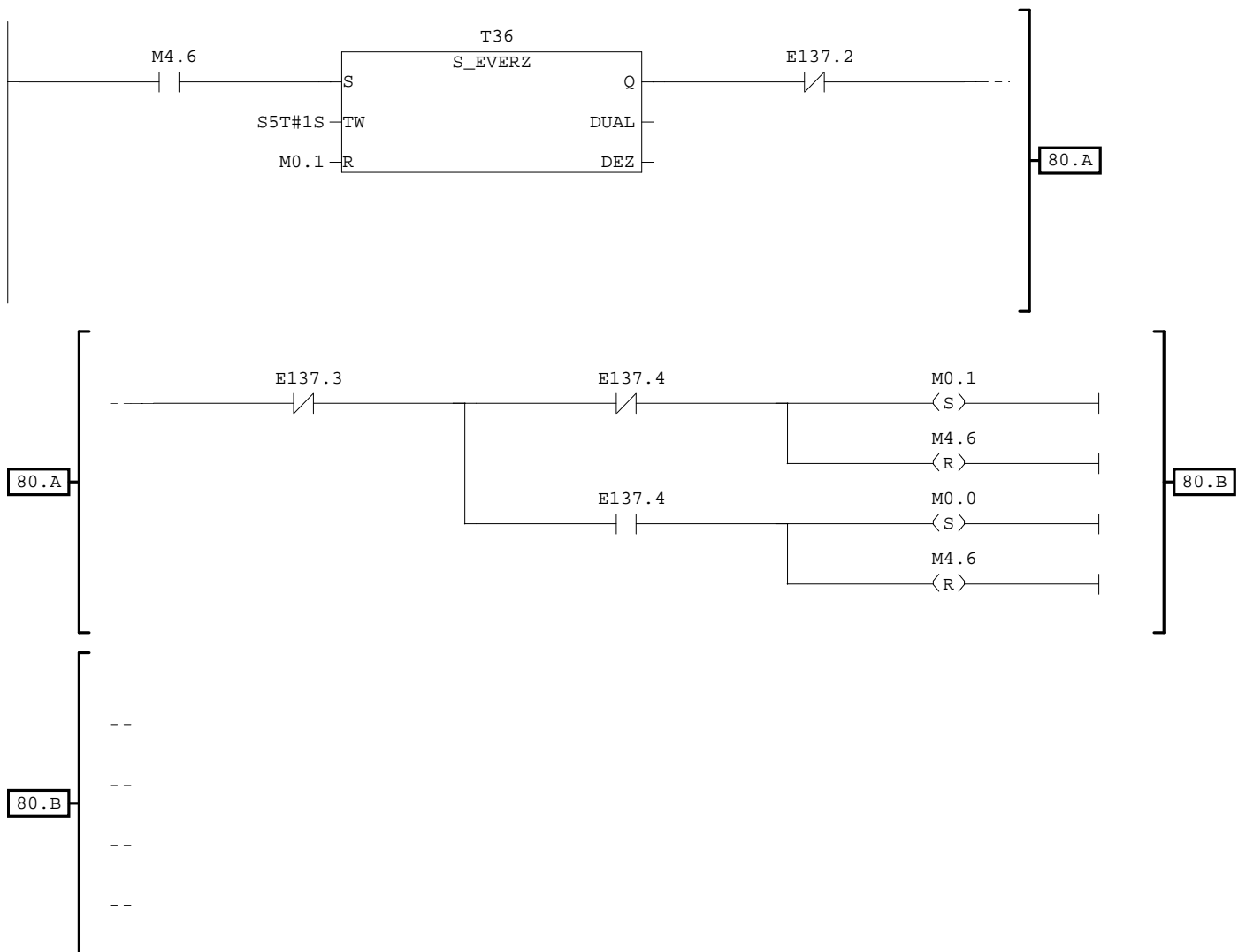


Segm.: 79

ABRIR PINZA



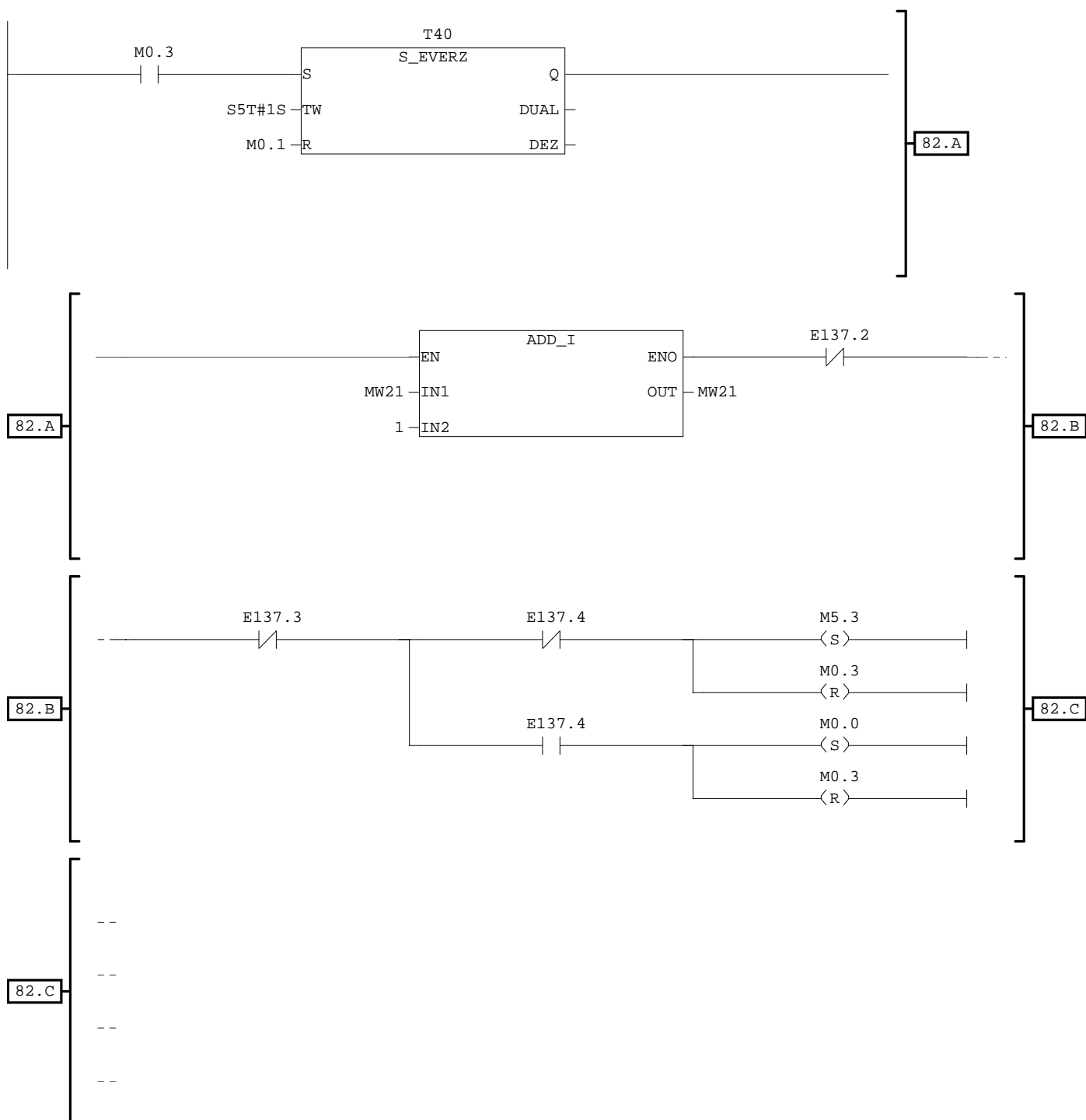
Segm.: 80 RECOGER BRAZO



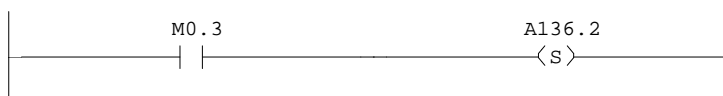
Segm.: 81 RECOGER BRAZO



Segm.: 82 SET POSICION RECOGIDA DERECHA

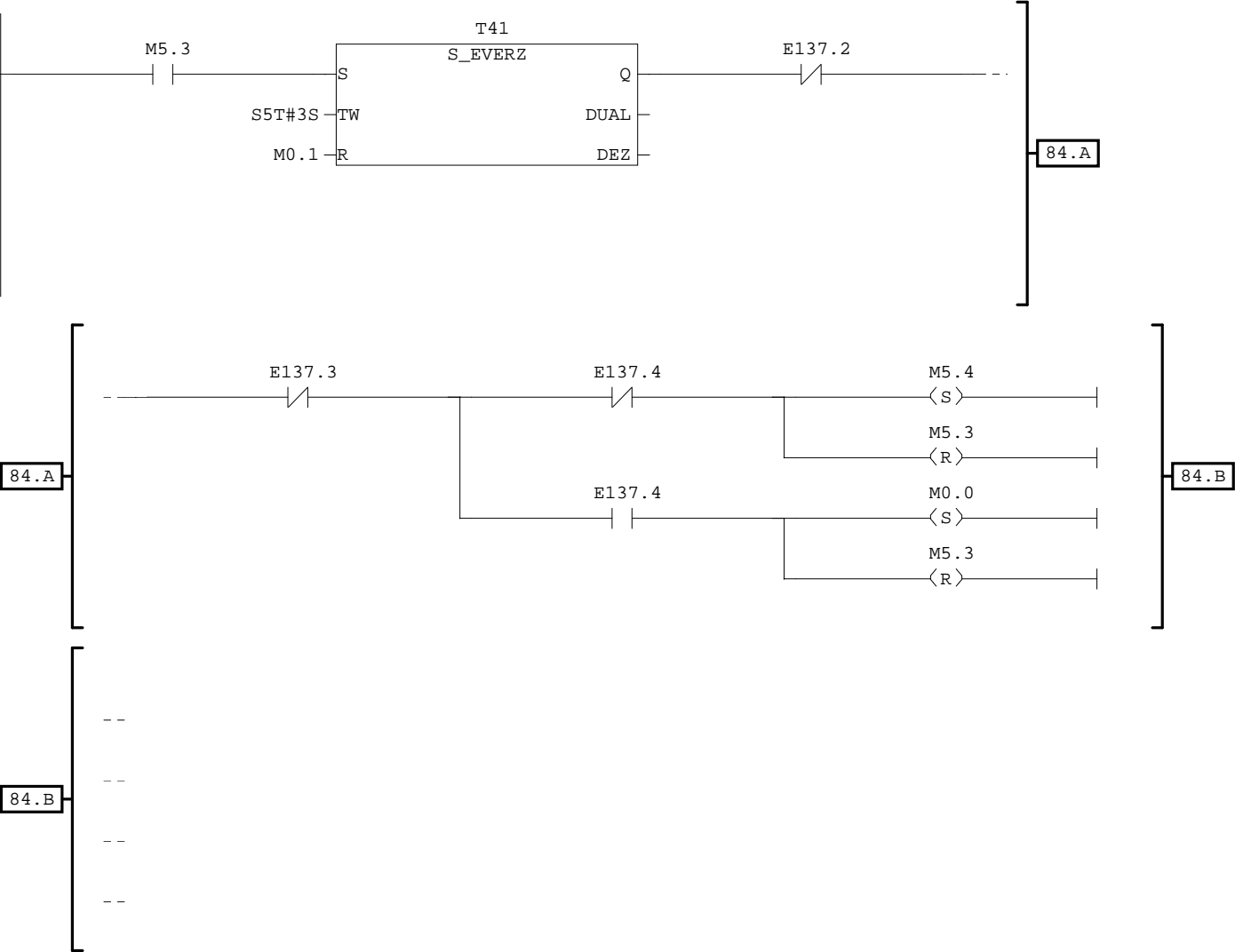


Segm.: 83 SET POSICION RECOGIDA DERECHA



Segm.: 84

GIRO A RECOGIDA DERECHA

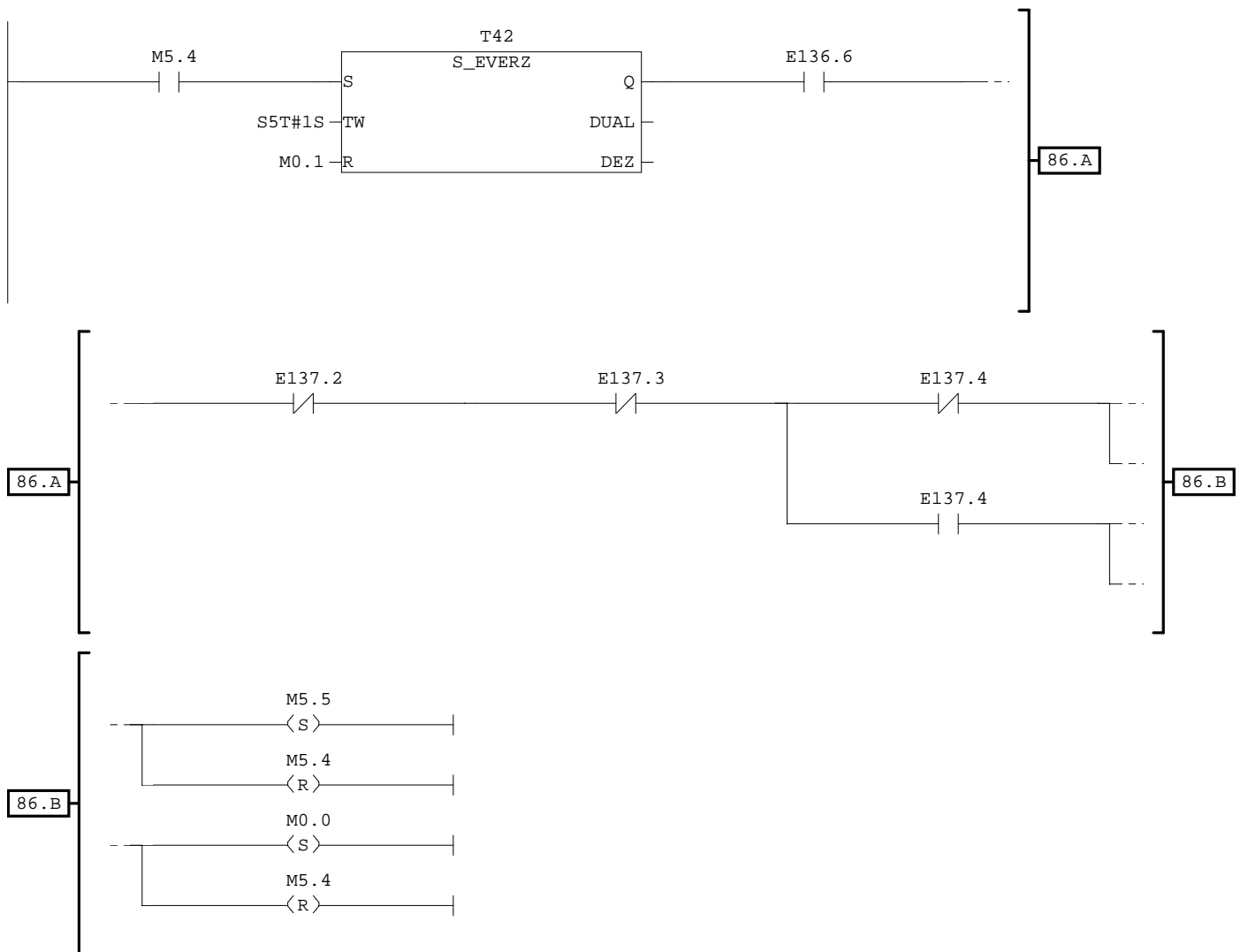


Segm.: 85

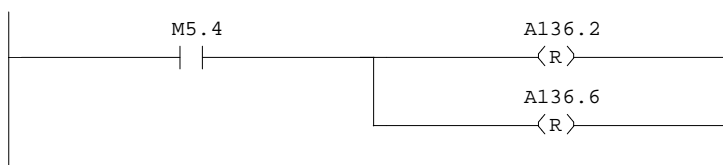
GIRO A RECOGIDA DERECHA



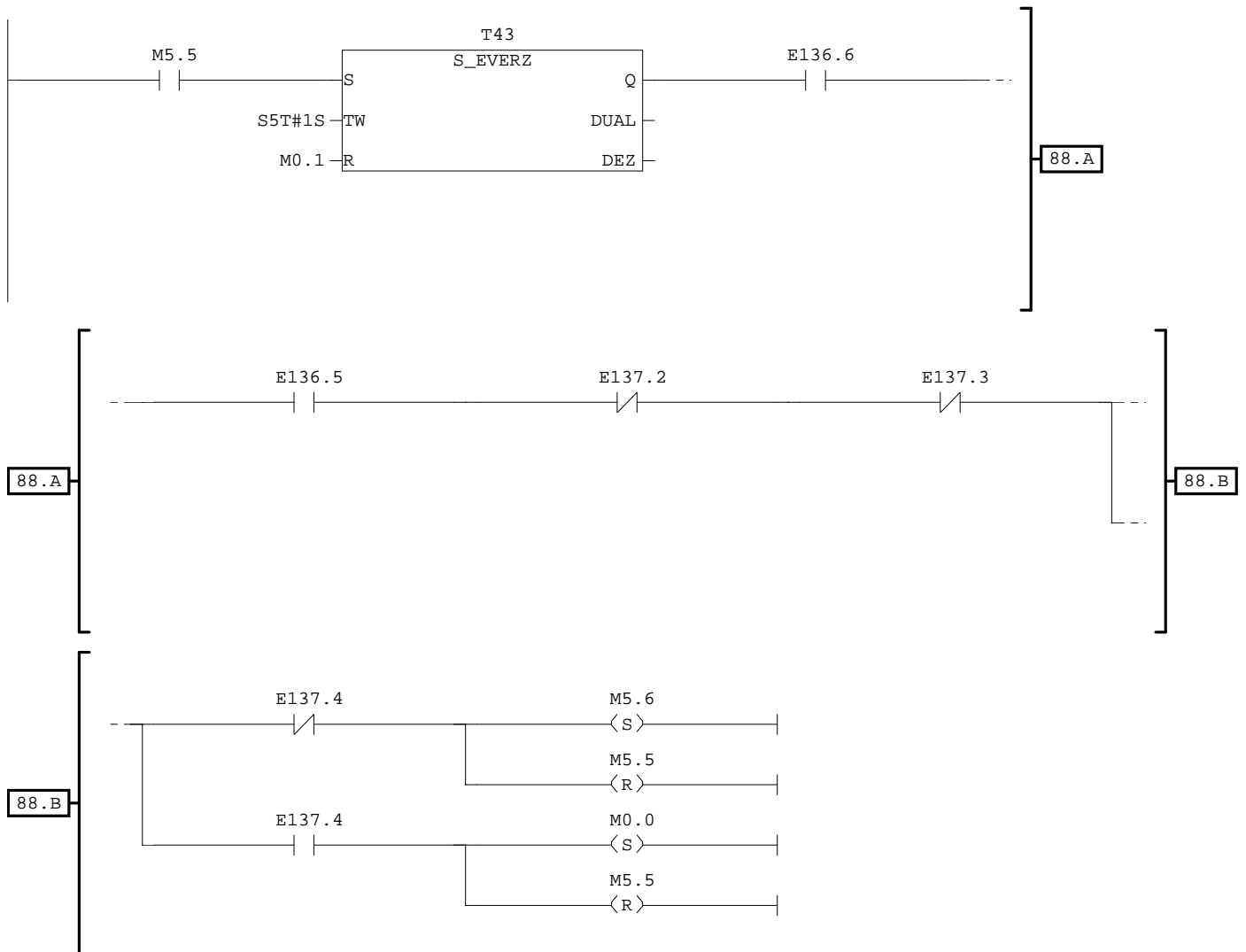
Segm.: 86 RESET



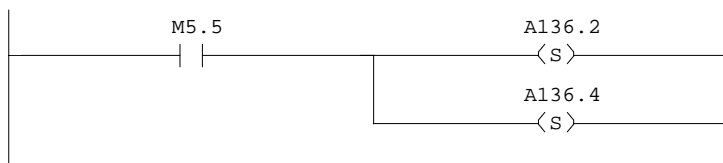
Segm.: 87 RESET



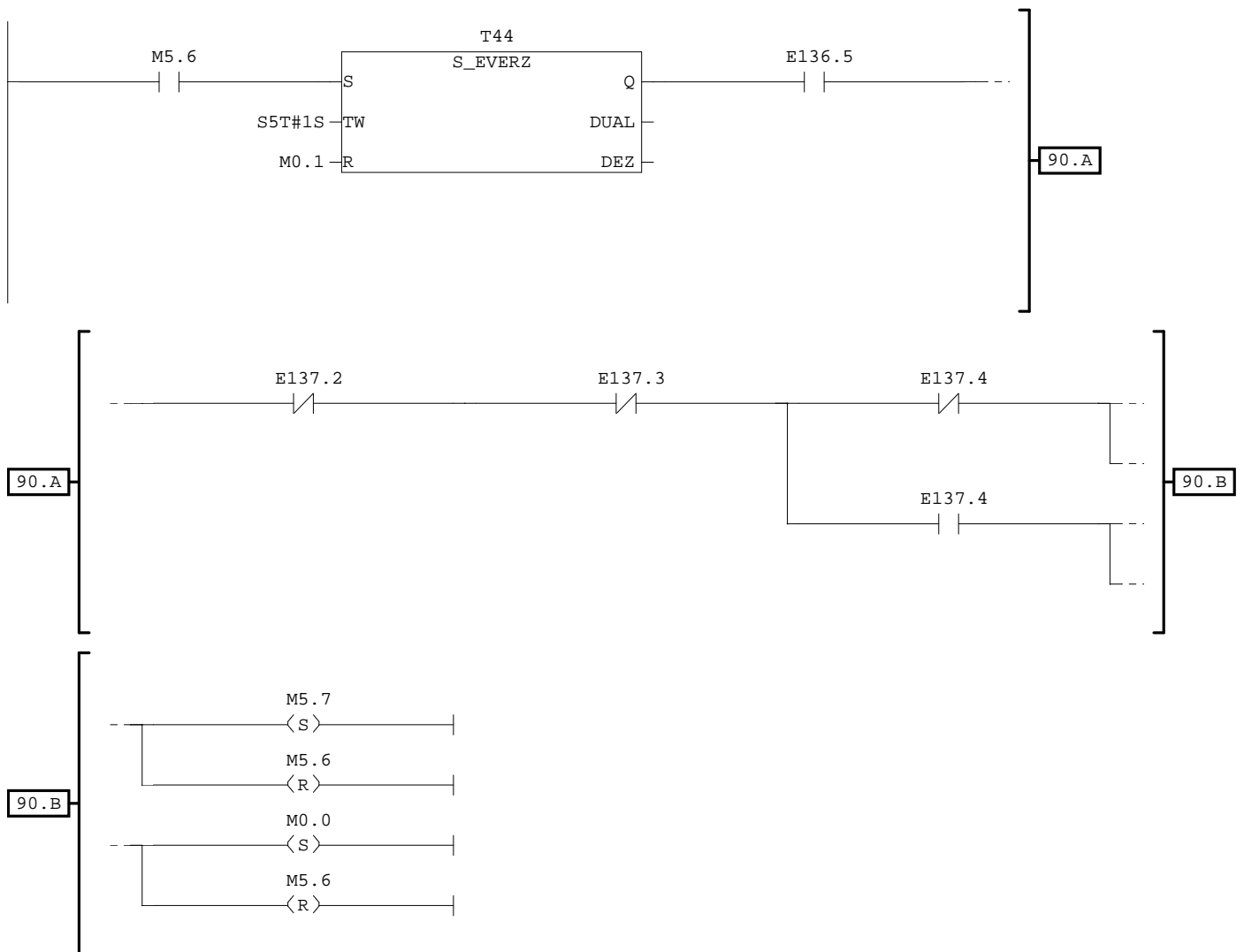
Segm.: 88 RECONOCIMIENTO



Segm.: 89 RECONOCIMIENTO



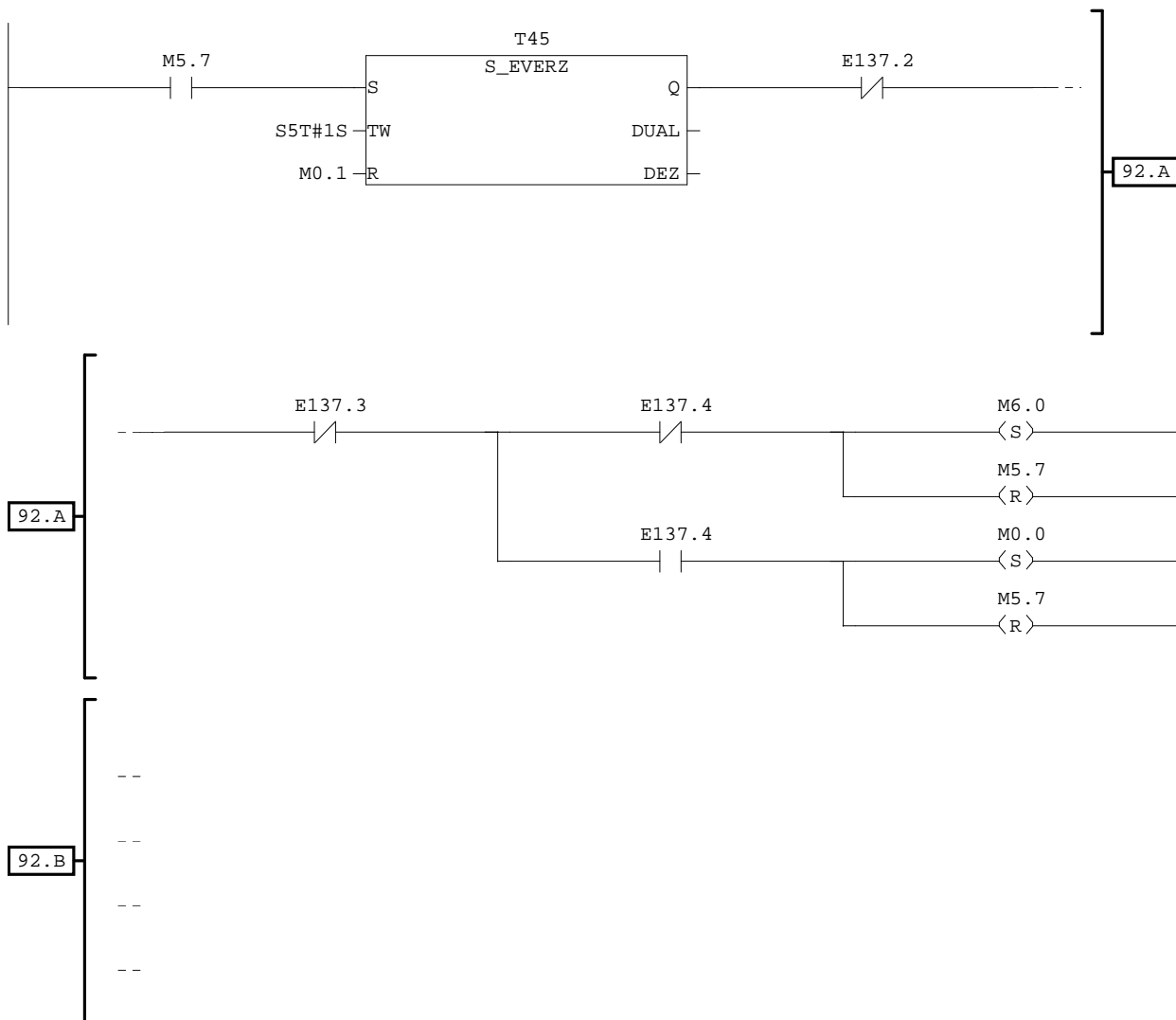
Segm.: 90 RECONOCIMIENTO 2



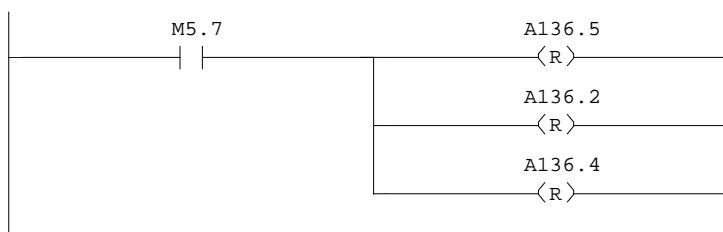
Segm.: 91 RECONOCIMIENTO 2



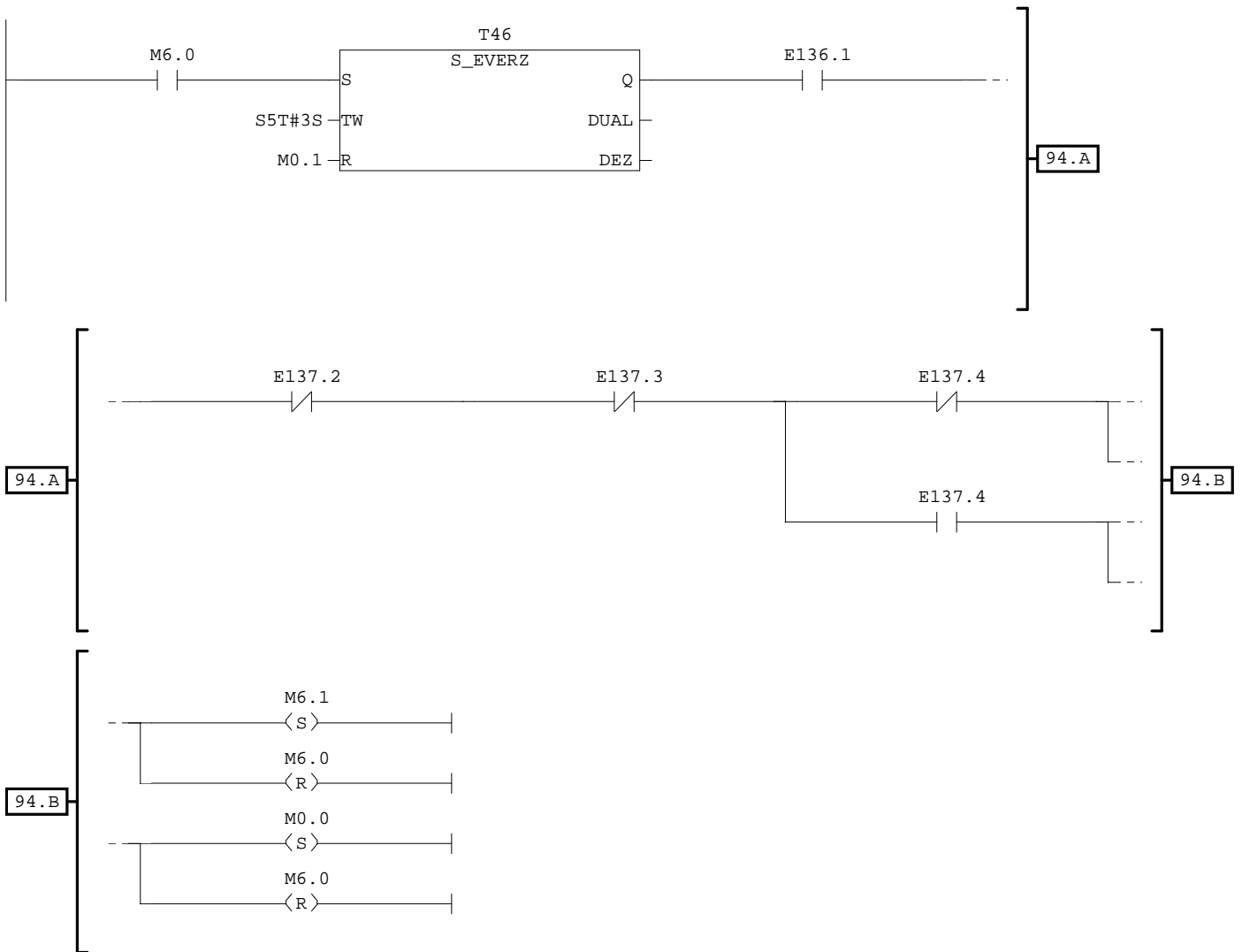
Segm.: 92 RESETEO



Segm.: 93 RESETEO



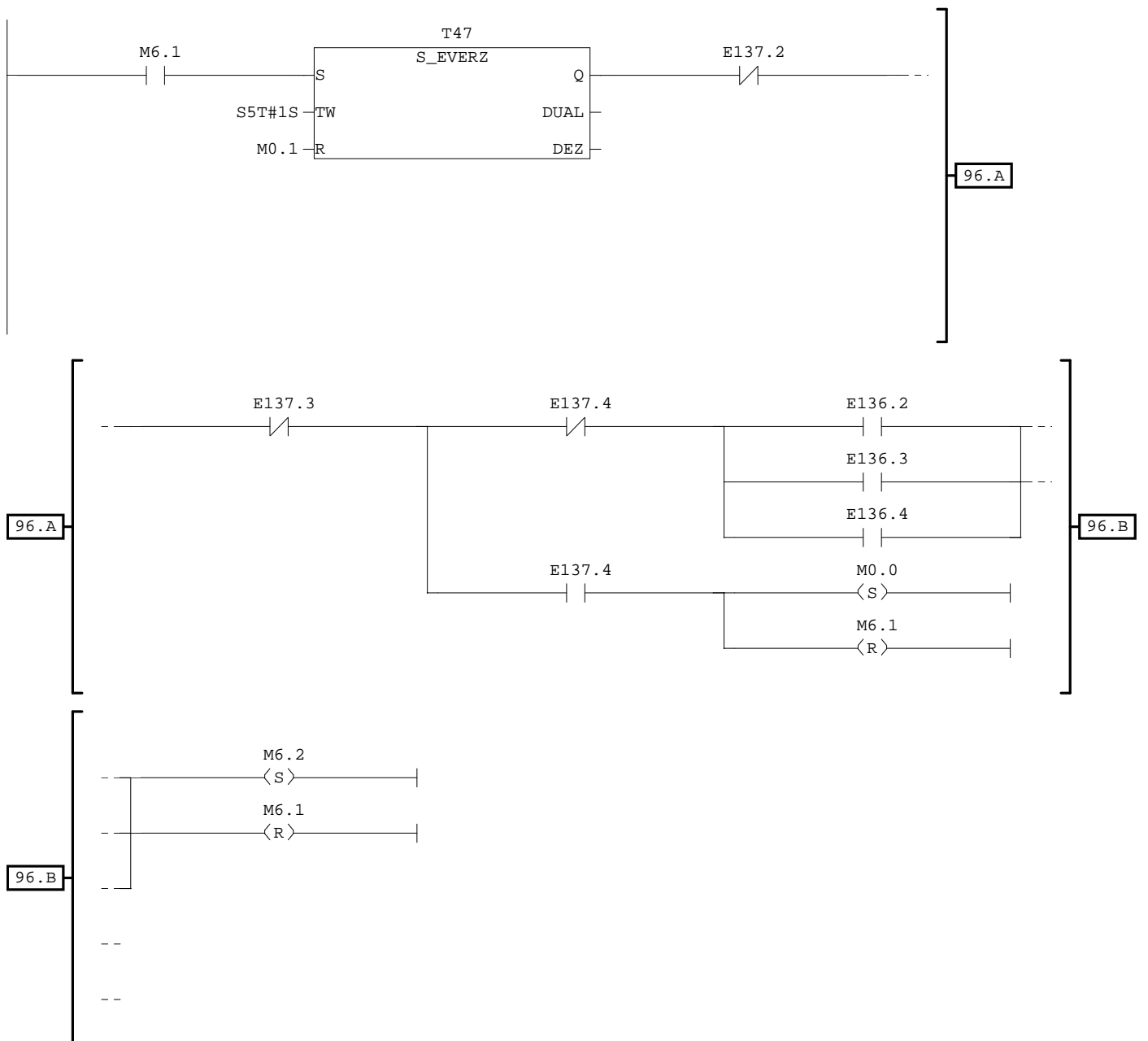
Segm.:	94	ALARGAR BRAZO
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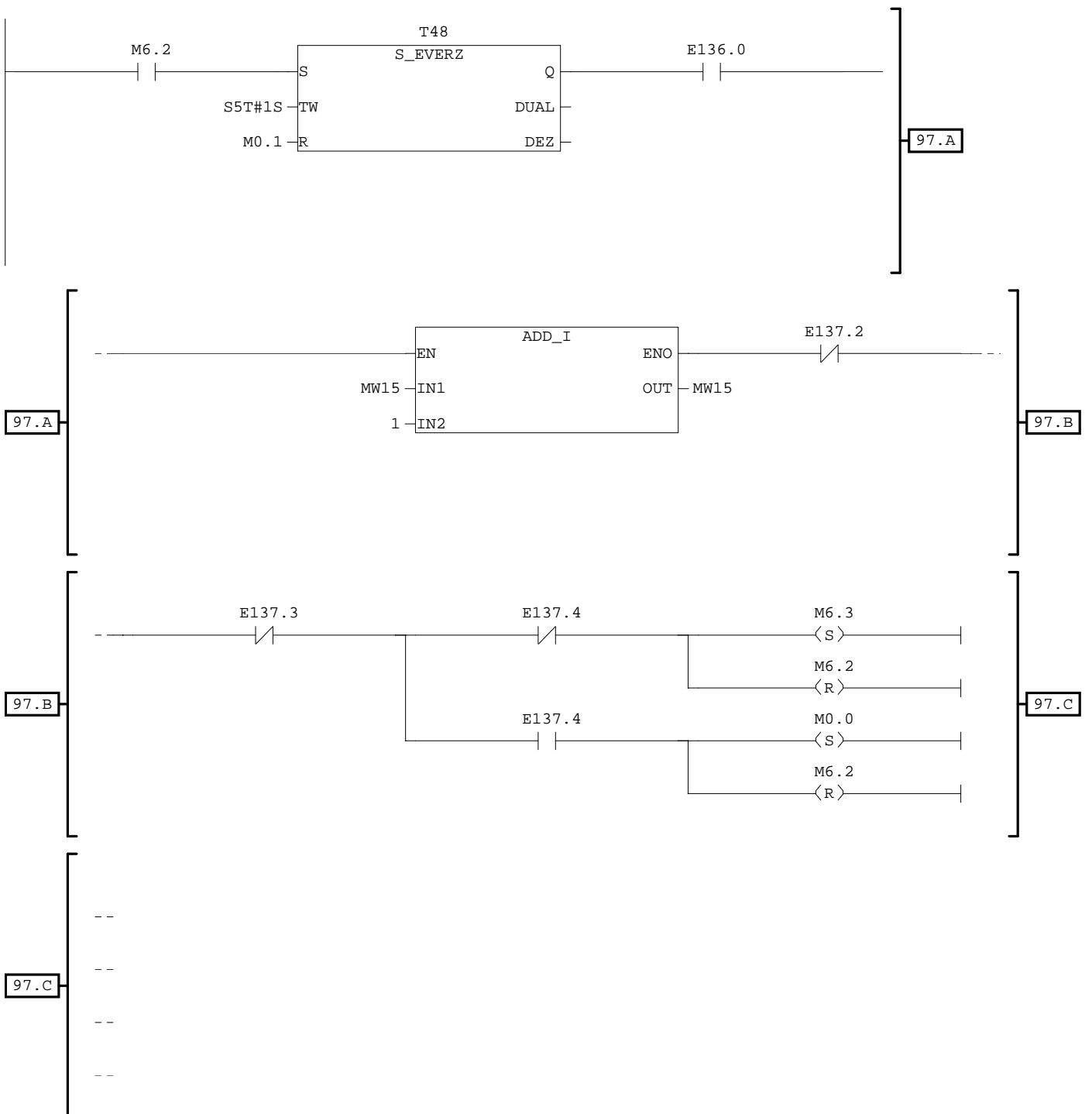
Segm. : 95	ALARGAR BRAZO
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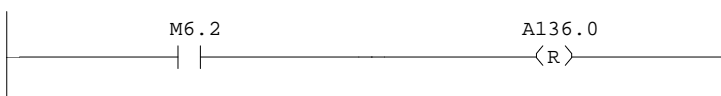
Segm.: 96 CONTAR



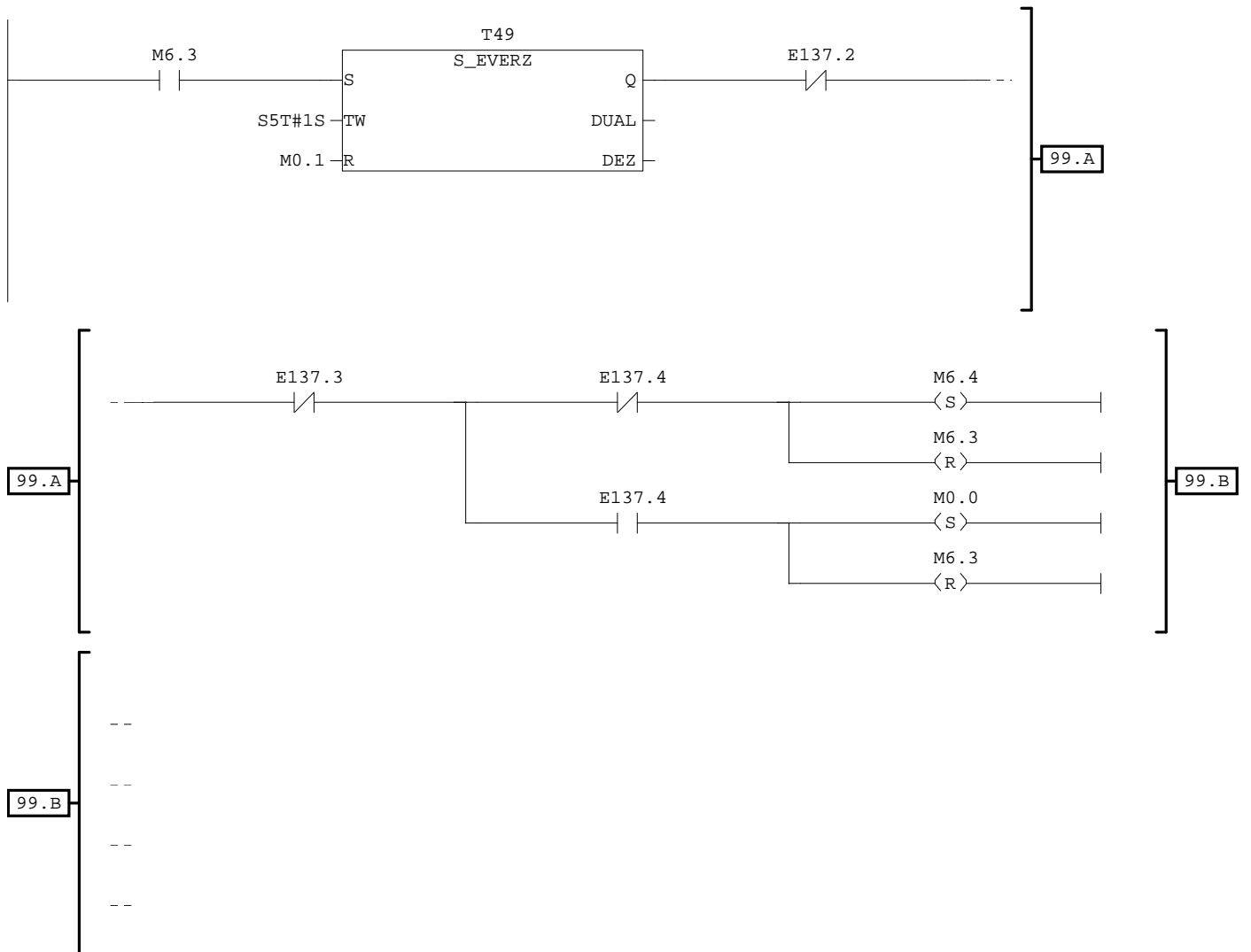
Segm. : 97	RECOGER BRAZO
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Segm. : 98	RECOGER BRAZO
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Segm.: 99 POSICION

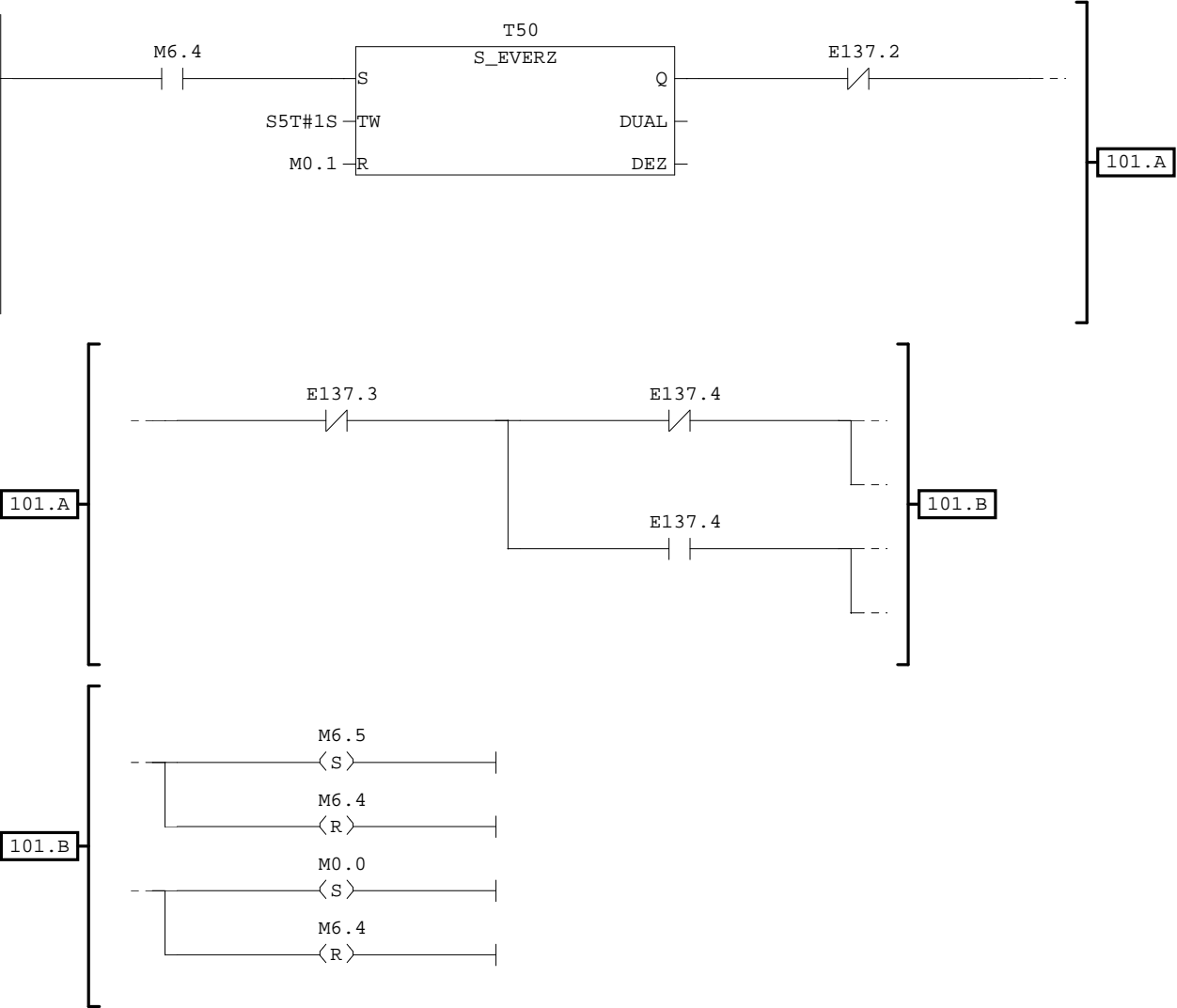


Segm.: 100 POSICION



Segm.: 101

ALTURA COGER PIEZA



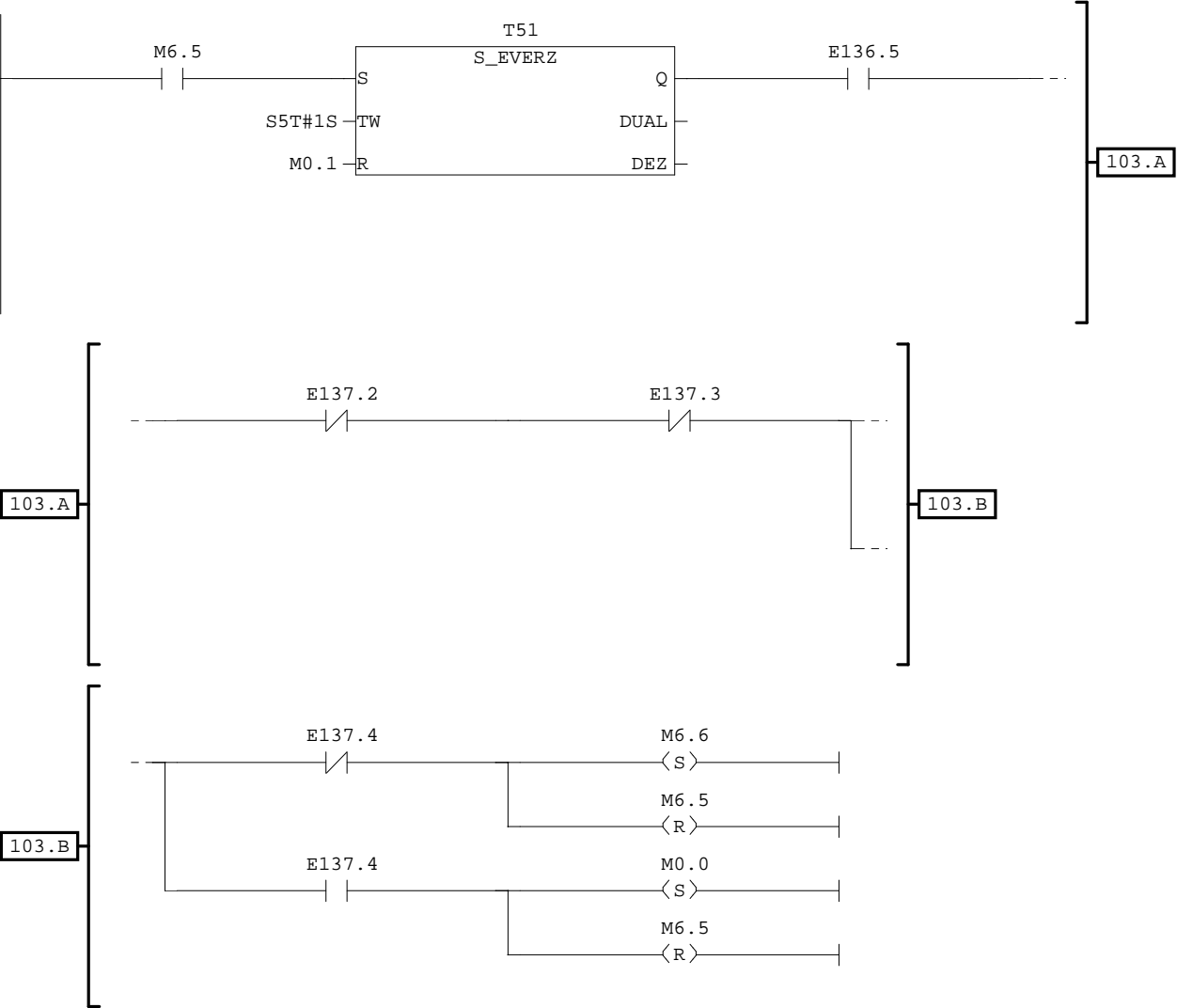
Segm.: 102

ALTURA COGER PIEZA



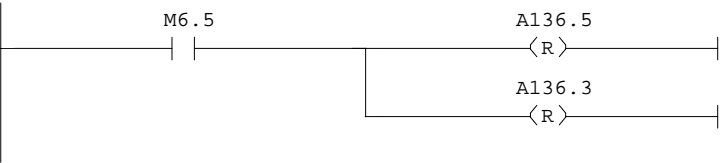
Segm.: 103

ALTURA COGER PIEZA

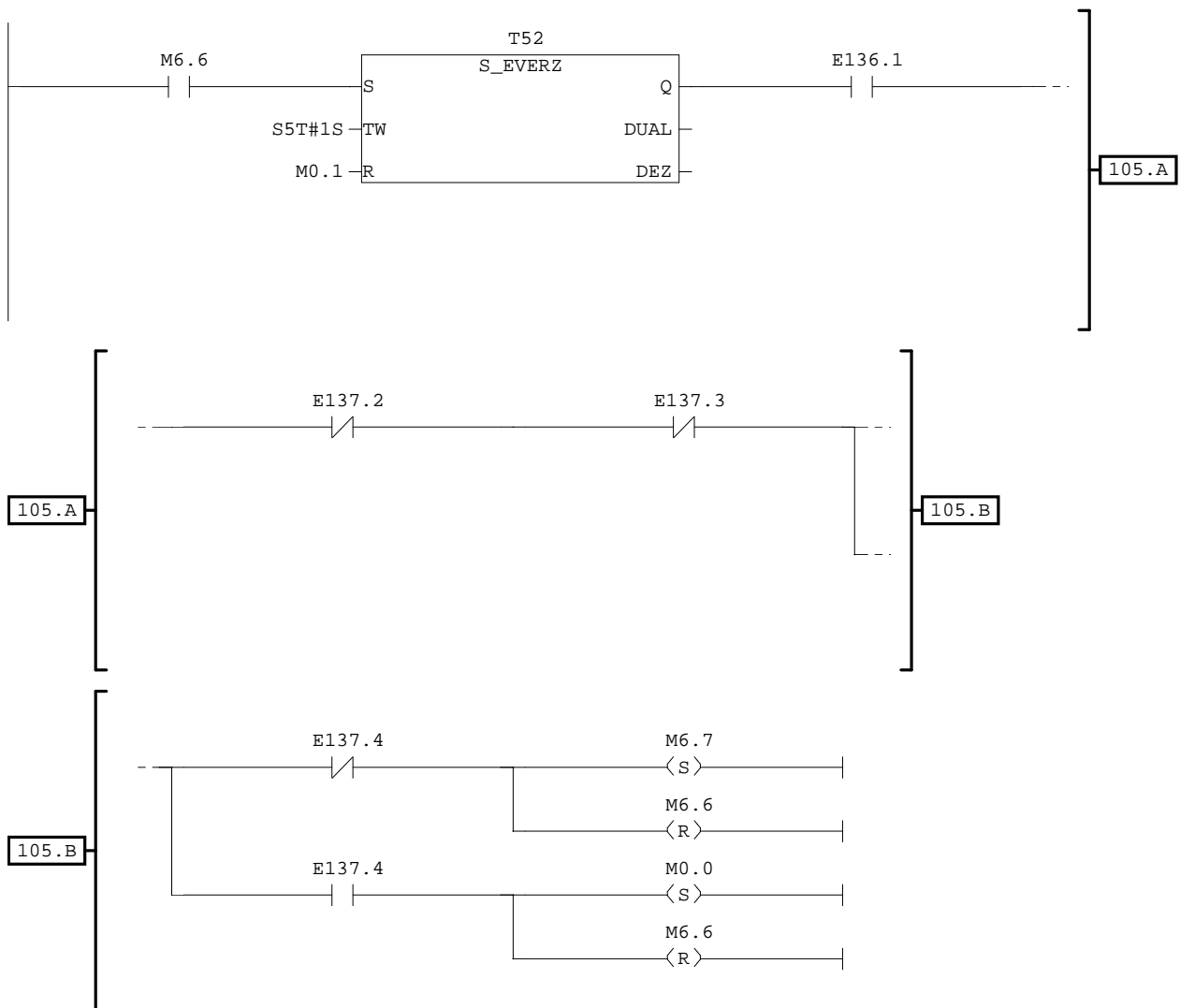


Segm.: 104

ALTURA COGER PIEZA



Segm.: 105 ALARGAR BRAZO

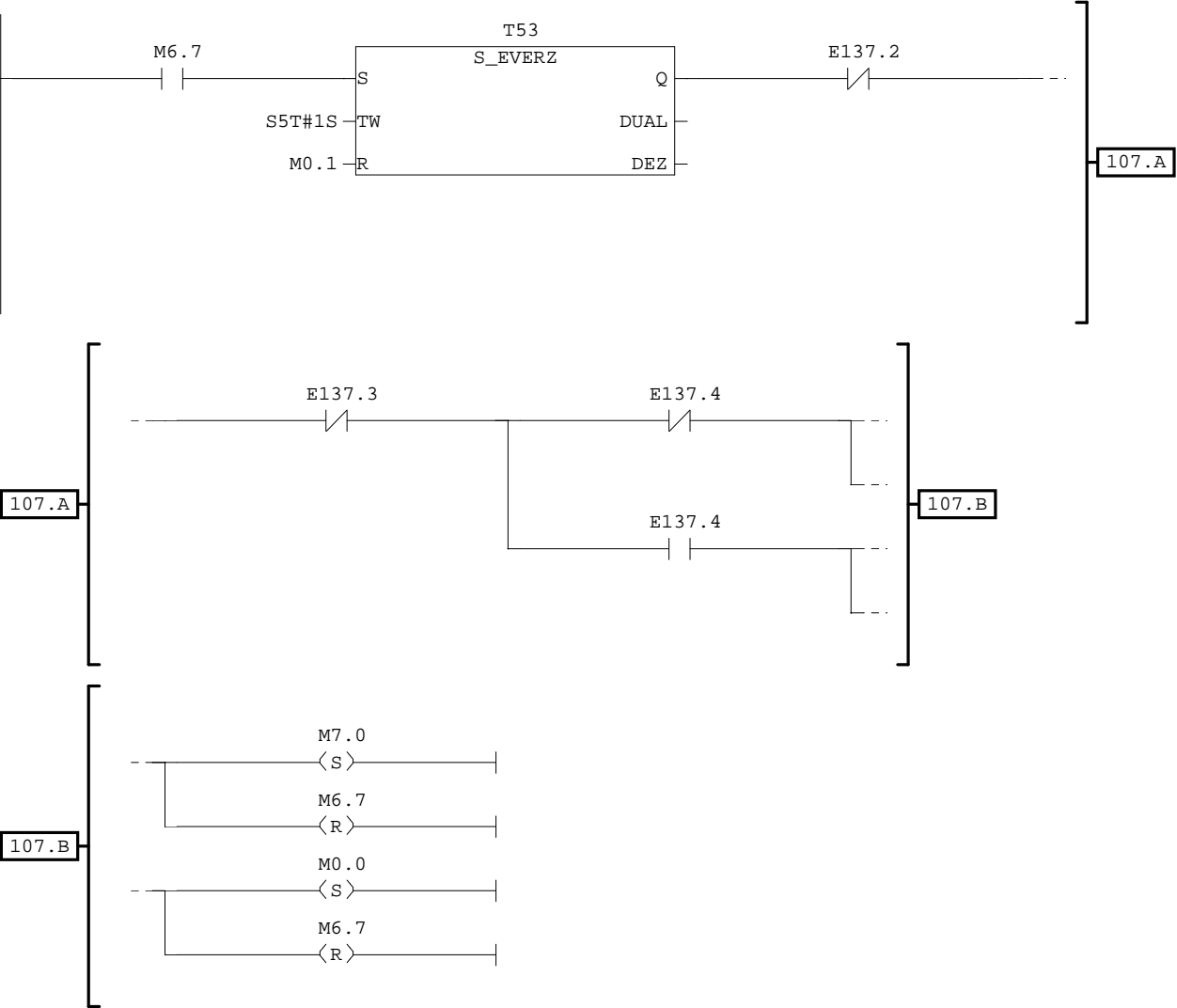


Segm.: 106 ALARGAR BRAZO



Segm.: 107

CERRAR PINZA



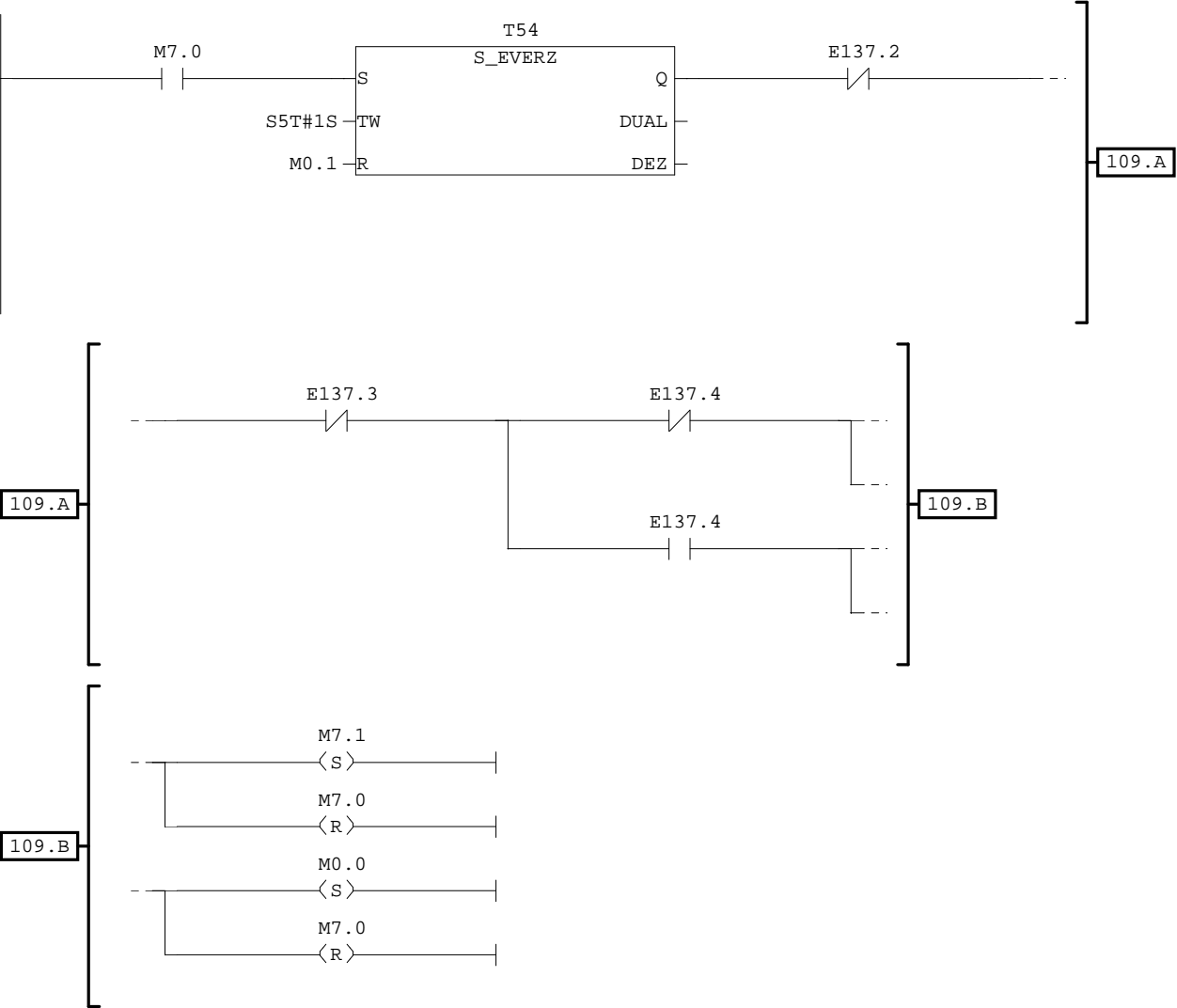
Segm.: 108

CERRAR PINZA



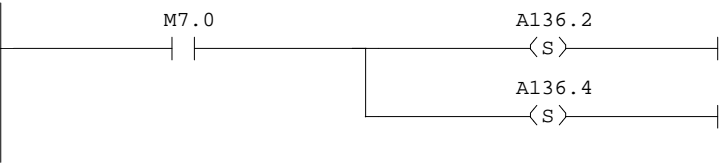
Segm.: 109

SUBIR UN POCO EL BRAZO PARA NO CHOCAR

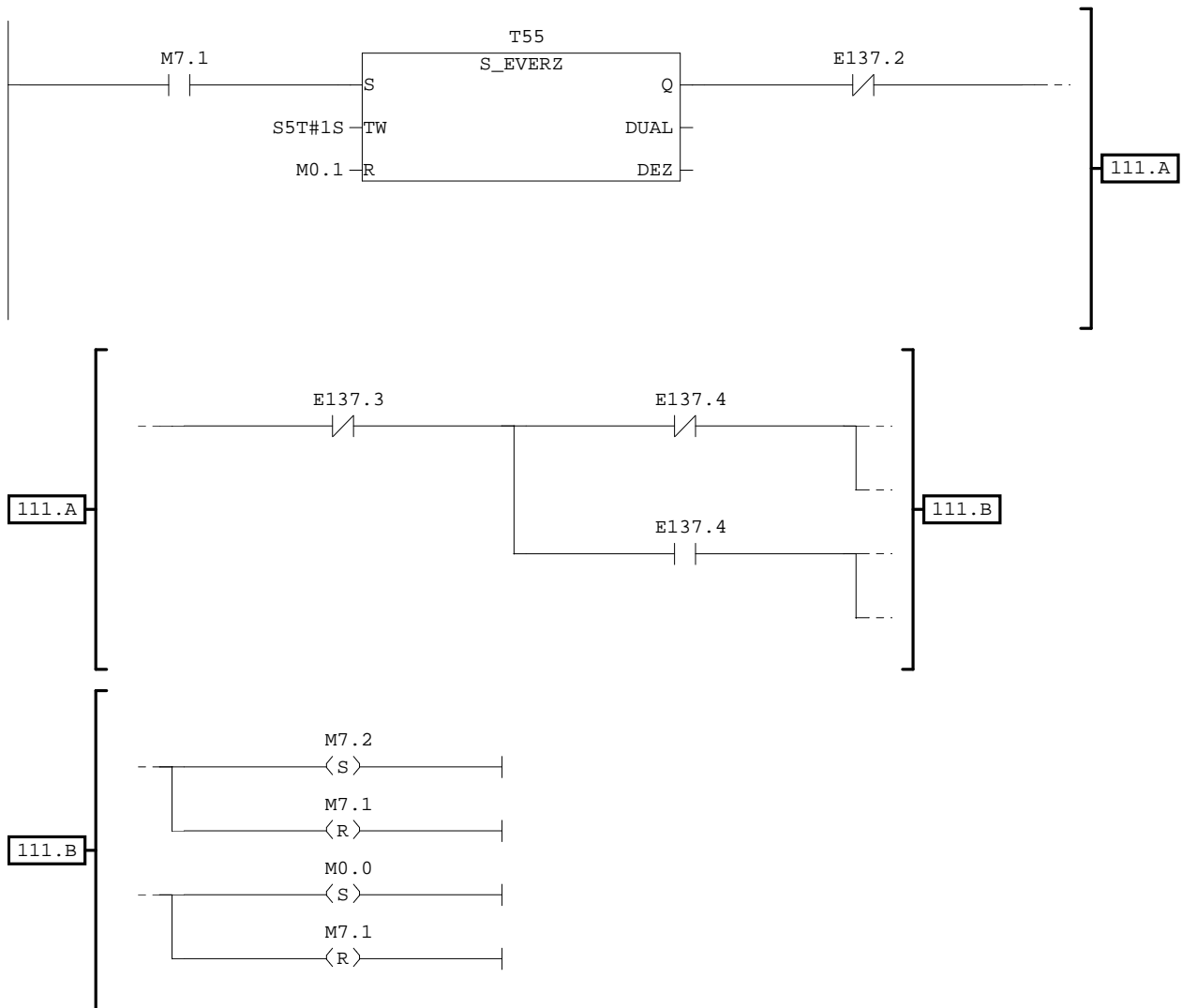


Segm.: 110

SET POSICION PLANTA DOS



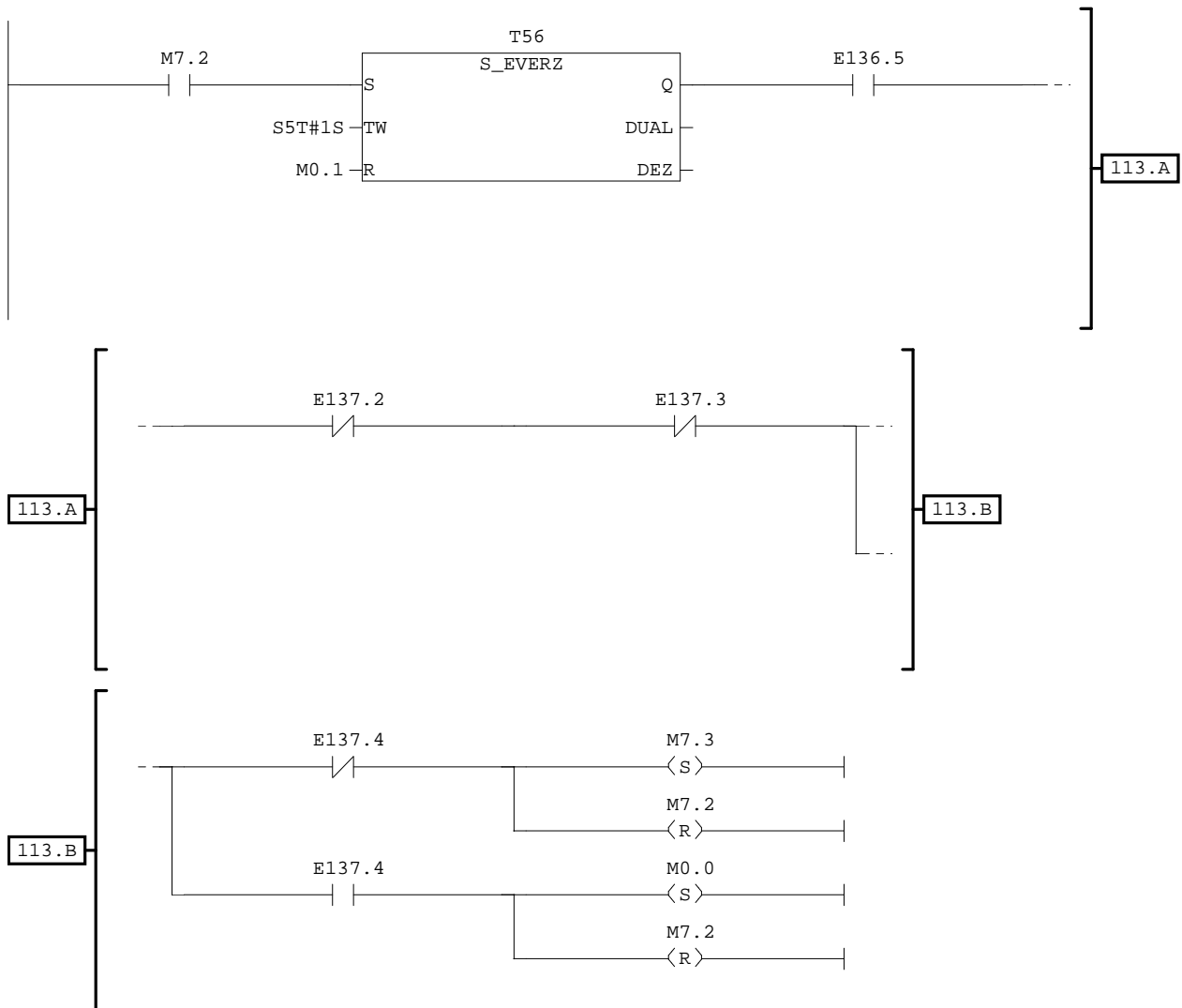
Segm.: 111 SET MOVIMIENTO PLANTA DOS



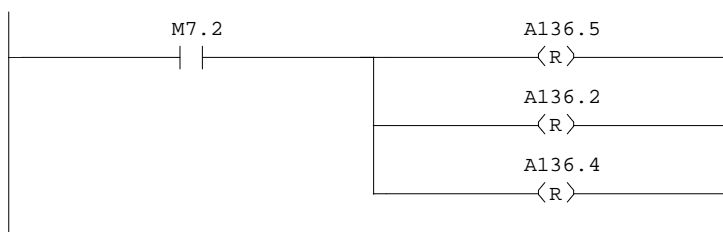
Segm.: 112 SET POSICION DETECCION



Segm.: 113 RESET

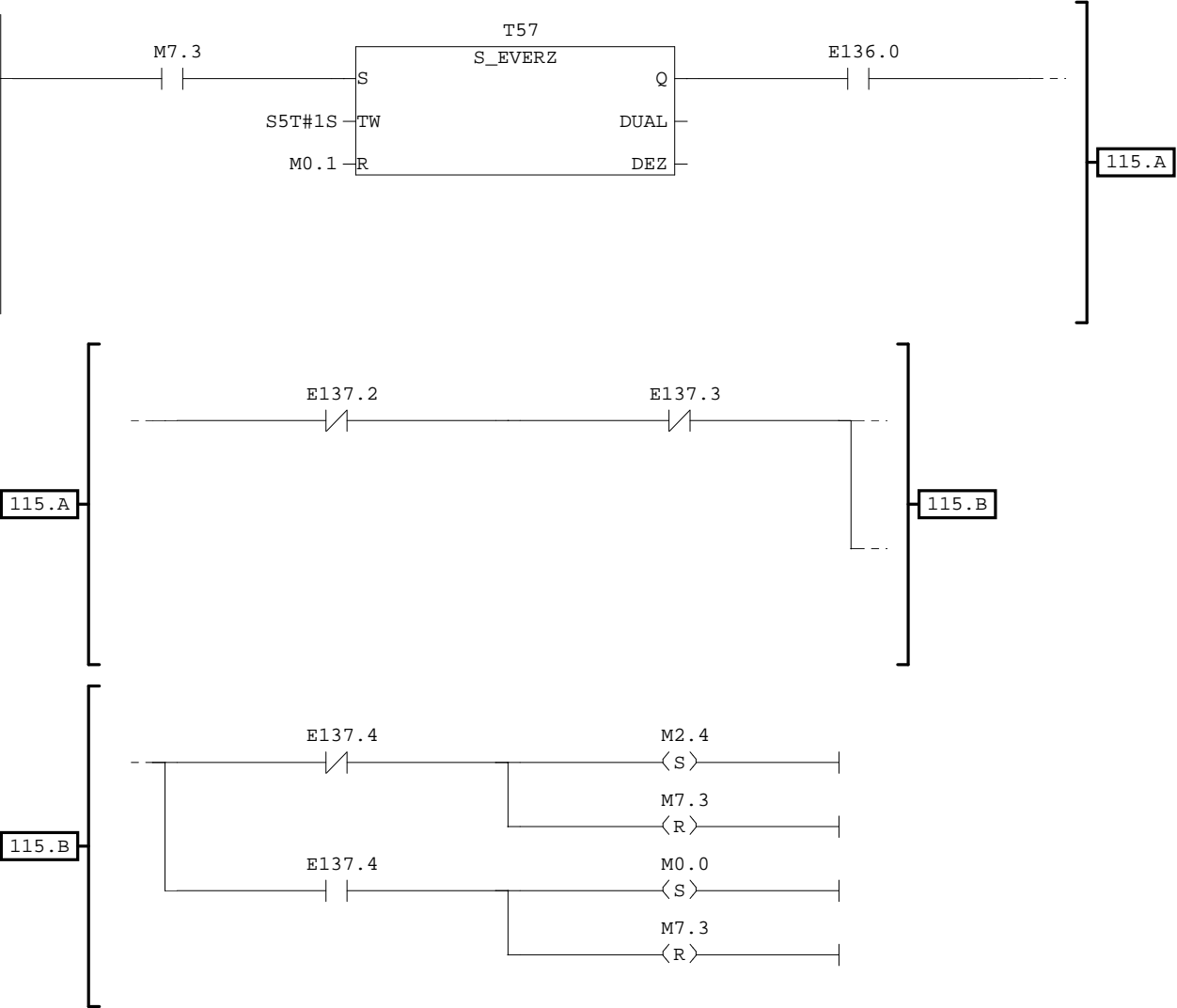


Segm.: 114 RESET



Segm.: 115

RECOGER BRAZO



Segm.: 116

RECOGER BRAZO

