

view_frames Result

Recorded at time: 215.370

odom

Broadcaster: /ekf_localization
Average rate: 50.362 Hz
Most recent transform: 215.360 (0.010 sec old)
Buffer length: 2.760 sec

base_link

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (215.370 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (215.370 sec old)
Buffer length: 0.000 sec

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Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher
Average rate: 50.365 Hz
Most recent transform: 215.355 (0.015 sec old)
Buffer length: 2.740 sec

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Most recent transform: 215.355 (0.015 sec old)
Buffer length: 2.740 sec

base_footprint

top_plate_link

front_bumper_link

imu_link

inertial_link

rear_bumper_link

top_chassis_link

user_rail_link

front_left_wheel_link

front_right_wheel_link

rear_left_wheel_link

rear_right_wheel_link

base_laser_mount

top_plate_front_link

top_plate_rear_link

base_laser

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (215.370 sec old)
Buffer length: 0.000 sec