

Introduction (I)

- ▶ Parametric models for classification/regression:
 - ▶ The objective is to learn a set of adaptive parameters \mathbf{w} which determine the mapping from the input \mathbf{x} to the target y:

$$\hat{y} = f(\mathbf{x}, \mathbf{w})$$

- ► Need of a training phase
- ▶ One example is linear regression:

$$\hat{y} = \mathbf{w}^T \boldsymbol{\phi}(\mathbf{x}) = \sum_{j=0}^{M-1} w_j \phi_j(\mathbf{x})$$

- ► Non-parametric models:
 - ► A subset of the input data points are used during classification
 - ► No training is needed, but methods are slow at making predictions
 - ► Examples: Parzen windows, Nearest Neighbors, etc.



Introduction (II)

- ► Some linear parametric models can be reformulated using a dual representation
- ► The predictions on the test data are based only on a linear combination of a *kernel* function which is evaluated on a subset of the training data
- ► Somehow we manage to express the parametric model as a non-parametric one
- ▶ One of such models is regularized linear regression



Regularized linear regression

- ▶ The attribute vectors are \mathbf{x}_i , i = 1, ..., N
- ▶ The targets are y_i , i = 1, ..., N
- ► The model (estimation of the target) is:

$$\hat{y}_i = \mathbf{w}^T \boldsymbol{\phi}(\mathbf{x}_i) = \sum_{j=0}^{M-1} w_j \phi_j(\mathbf{x}_i)$$

- ► The base functions $\phi(\mathbf{x}_i) = (\phi_0(\mathbf{x}_i), \phi_1(\mathbf{x}_i), ..., \phi_{M-1}(\mathbf{x}_i))^T$ represent the attributes
- We assume $\phi_0(\mathbf{x}_i) = 1$
- ▶ We minimize the following error function:

$$J(\mathbf{w}) = \frac{1}{2} \sum_{i=1}^{N} \{y_i - \mathbf{w}^T \phi(\mathbf{x}_i)\}^2 + \frac{\lambda}{2} \mathbf{w}^T \mathbf{w}$$



Minimization of $J(\mathbf{w})$

► We want to minimize:

$$J(\mathbf{w}) = \frac{1}{2} \sum_{i=1}^{N} \{y_i - \mathbf{w}^T \phi(\mathbf{x}_i)\}^2 + \frac{\lambda}{2} \mathbf{w}^T \mathbf{w}$$
$$= \frac{1}{2} \sum_{i=1}^{N} \{y_i - \sum_{j=0}^{M-1} w_j \phi_j(\mathbf{x}_i)\}^2 + \frac{\lambda}{2} \sum_{j=0}^{M-1} w_j^2$$

▶ With respect to the parameters w_k :

$$\frac{\partial J(\mathbf{w})}{\partial w_k} = 0$$



Minimization of $J(\mathbf{w})$

► Operating:

$$\frac{\partial J(\mathbf{w})}{\partial w_k} = -\sum_{i=1}^N y_i \phi_k(\mathbf{x}_i) + \sum_{i=1}^N \sum_{j=0}^{M-1} w_j \phi_j(\mathbf{x}_i) \phi_k(\mathbf{x}_i) + \lambda w_k$$

$$= -\sum_{i=1}^N y_i \Phi_{ik} + \sum_{i=1}^N \sum_{j=0}^{M-1} w_j \Phi_{ij} \Phi_{ik} + \lambda w_k$$

$$= -\sum_{i=1}^N \Phi_{ki}^T y_i + \sum_{j=0}^{M-1} \sum_{i=1}^N \Phi_{ki}^T \Phi_{ij} w_j + \lambda w_k$$

$$= -(\mathbf{\Phi}^T \mathbf{y})_k + \sum_{j=0}^{M-1} (\mathbf{\Phi}^T \mathbf{\Phi})_{kj} w_j + \lambda w_k$$

$$= -(\mathbf{\Phi}^T \mathbf{y})_k + (\mathbf{\Phi}^T \mathbf{\Phi} \mathbf{w})_k + \lambda w_k = 0$$



Minimization of $J(\mathbf{w})$

► Finally:

$$-\mathbf{\Phi}^T\mathbf{y} + \mathbf{\Phi}^T\mathbf{\Phi}\mathbf{w} + \lambda\mathbf{w} = \mathbf{0}$$

$$\mathbf{w} = (\mathbf{A} + \lambda I)^{-1} \mathbf{\Phi}^T \mathbf{y}$$

▶ Where Φ is the design matrix, $\Phi_{ij} = \phi_j(\mathbf{x}_i)$:

$$\mathbf{\Phi} = \begin{pmatrix} \phi_0(\mathbf{x}_1) & \phi_1(\mathbf{x}_1) & \dots & \phi_{M-1}(\mathbf{x}_1) \\ \phi_0(\mathbf{x}_2) & \phi_1(\mathbf{x}_2) & \dots & \phi_{M-1}(\mathbf{x}_2) \\ \dots & \dots & \dots & \dots \\ \phi_0(\mathbf{x}_N) & \phi_1(\mathbf{x}_N) & \dots & \phi_{M-1}(\mathbf{x}_N) \end{pmatrix}$$

▶ And $\mathbf{A} = \mathbf{\Phi}^T \mathbf{\Phi}$ is a $M \times M$ matrix



An example

- ► Four pairs (x; y): $\{(1; 0,8), (4; 4,1), (6; 6,2), (9; 8,5)\}$
- ▶ The vector of attributes is $\phi(x) = (1, x)^T$
- ► And the design matrix is:

$$\mathbf{\Phi} = \begin{pmatrix} 1 & x_1 \\ 1 & x_2 \\ 1 & x_3 \\ 1 & x_4 \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ 1 & 4 \\ 1 & 6 \\ 1 & 9 \end{pmatrix}$$

- ▶ Let us assume $\lambda = 1$
- ▶ ... full solution in the IPython Notebook



► Let's do it a different way:

$$\frac{\partial J(\mathbf{w})}{\partial w_k} = -\sum_{i=1}^N \Phi_{ki}^T y_i + \sum_{j=0}^{M-1} \sum_{i=1}^N \Phi_{ki}^T \Phi_{ij} w_j + \lambda w_k = 0$$

► So:

$$w_{k} = -\frac{1}{\lambda} \sum_{i=1}^{N} \left\{ \sum_{j=0}^{M-1} \Phi_{ki}^{T} \Phi_{ij} w_{j} - \Phi_{ki}^{T} y_{i} \right\}$$

$$= -\frac{1}{\lambda} \sum_{i=1}^{N} \Phi_{ki}^{T} \left\{ \sum_{j=0}^{M-1} \Phi_{ij} w_{j} - y_{i} \right\}$$

$$= -\frac{1}{\lambda} \sum_{i=1}^{N} \Phi_{ki}^{T} \left\{ \sum_{j=0}^{M-1} w_{j} \phi_{j}(\mathbf{x}_{i}) - y_{i} \right\}$$



► This leads to:

$$w_{k} = -\frac{1}{\lambda} \sum_{i=1}^{N} \Phi_{ki}^{T} \{ \sum_{j=0}^{M-1} w_{j} \phi_{j}(\mathbf{x}_{i}) - y_{i} \}$$

$$= -\frac{1}{\lambda} \sum_{i=1}^{N} \Phi_{ki}^{T} \{ \mathbf{w}^{T} \phi(\mathbf{x}_{i}) - y_{i} \}$$

$$= \sum_{i=1}^{N} \Phi_{ki}^{T} a_{i}$$

► Where:

$$a_i = -\frac{1}{\lambda} \{ \mathbf{w}^T \boldsymbol{\phi}(\mathbf{x}_i) - y_i \}$$



► In matrix form:

$$\mathbf{w} = \mathbf{\Phi}^T \mathbf{a}$$

Now we can substitute w_k into $J(\mathbf{w})$ to obtain an expression that depends only on \mathbf{a} :

$$J(\mathbf{a}) = \frac{1}{2} \sum_{i=1}^{N} \{y_i - \sum_{j=0}^{M-1} \sum_{k=1}^{N} \Phi_{jk}^T a_k \Phi_{ij} \}^2 + \frac{\lambda}{2} \sum_{j=0}^{M-1} (\sum_{k=1}^{N} \Phi_{jk}^T a_k)^2$$

► The dual problem consists of minimizing $J(\mathbf{a})$ with respect to a_k :

$$\frac{\partial J(\mathbf{a})}{\partial a_k} = 0$$



► After some algebra we obtain:

$$\mathbf{a} = (\mathbf{K} + \lambda I)^{-1} \mathbf{y}$$

▶ Where $\mathbf{K} = \mathbf{\Phi}\mathbf{\Phi}^T$ is a $N \times N$ matrix that satisfies that:

$$\mathbf{K}_{ij} = \boldsymbol{\phi}(\mathbf{x}_i)^T \boldsymbol{\phi}(\mathbf{x}_j) \equiv k(\mathbf{x}_i, \mathbf{x}_j)$$

▶ The function $k(\mathbf{x}_i, \mathbf{x}_j)$ is known as a kernel function



Conclusion

► In the primal formulation:

$$\hat{y} = \mathbf{w}^T \boldsymbol{\phi}(\mathbf{x}) = \sum_{j=0}^{M-1} w_j \phi_j(\mathbf{x})$$

To obtain **w** we have to invert the matrix $\mathbf{A} + \lambda I$, which is $M \times M$

► In the dual formulation:

$$\hat{y} = \mathbf{a}^T \mathbf{\Phi} \phi(\mathbf{x}) = \sum_{i=1}^N a_i k(\mathbf{x}_i, \mathbf{x})$$

To obtain **a** we have to invert the matrix $\mathbf{K} + \lambda I$, which is $N \times N$

► This technique is generalizable to other problems

