

## Improved TiKV Observability:

**How We Trace Events under Nanoseconds Latency** 

Wish & Zhenchi @ TiKV · KubeCon NA 2020



# An open source distributed transactional key-value database

### What is TiKV?



**CNCF Graduated** 

8K+

**GitHub Stars** 

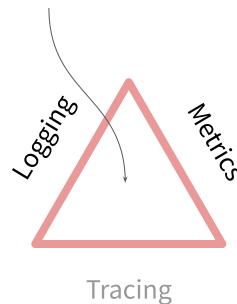
200+

Contributors



#### Why there is a write jitter?

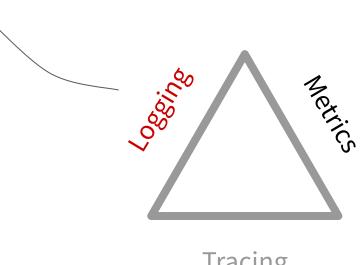






hard to **link** everything related to a request together

Why Tracing?

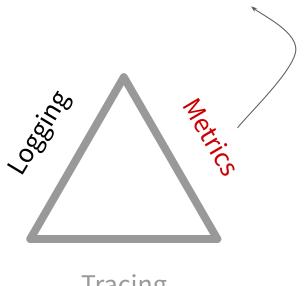


Tracing



## Why Tracing?

only aggregated information (like avg, P99, min, max)

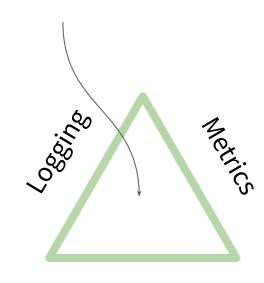


Tracing



#### Why there is a write jitter?





we want to use trace to know it!

**Tracing** 



#### OpenTracing / OpenTelemtry compatible in Rust



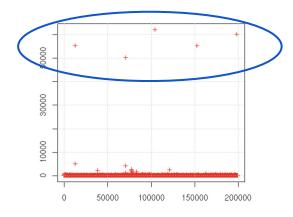
- Tokio Tracing
  - o github.com/tokio-rs/tracing
- Rustracing
  - github.com/sile/rustracing
- ...

**Tracing Library?** 



## Challenge 1/2

#### We want to catch *jitters*

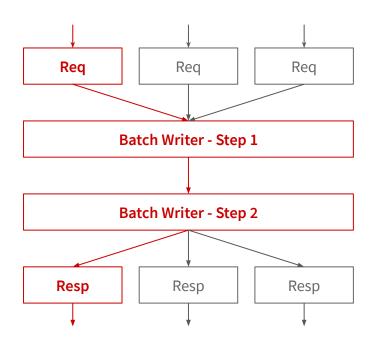


- All KV requests need to be traced.
- Each KV request may only take ~1μs.
- So tracing must be **super** efficient.



#### **batch** processing pattern?

## Challenge 2/2





#### **batch** processing pattern?

## Challenge 2/2



#### **Process Request 1**

Batch...?



#### **Process Request 1**

**Wait Batch** 

Batch Write Step 1

**Batch Write Step 2** 



#### OpenTracing / OpenTelemtry compatible in Rust



- Tokio Tracing
  - o github.com/tokio-rs/tracing
- Rustracing
  - o github.com/sile/rustracing
- ...





## Solution

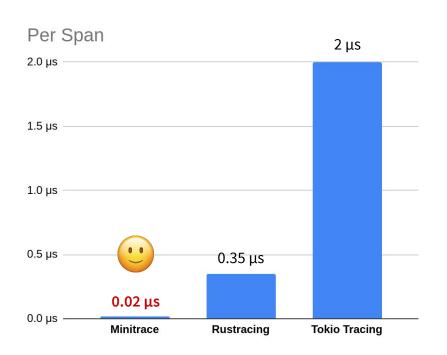
#### OpenTracing / OpenTelemtry compatible in Rust

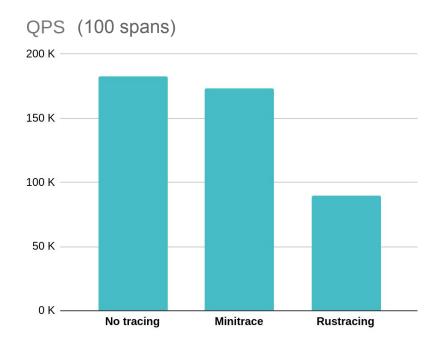


- Tokio Tracing
  - o github.com/tokio-rs/tracing
- Rustracing
  - github.com/sile/rustracing
- POC prototype: minitrace



### Performance: 20ns/span







### **Performance: Reduce Contention**

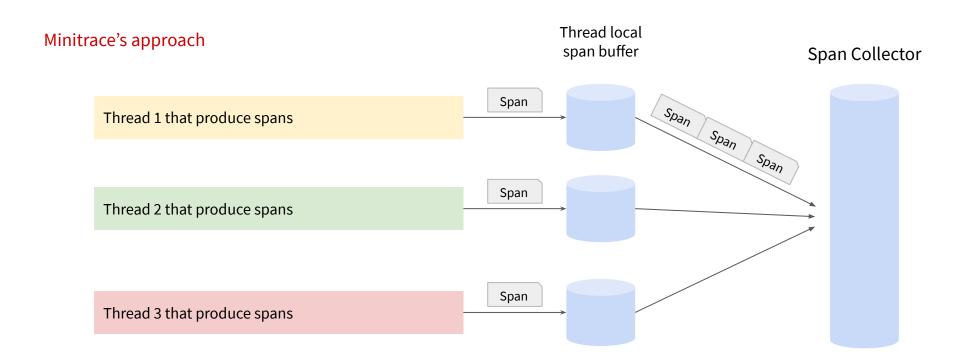
Thread 1 that produce spans

Thread 2 that produce spans

Thread 3 that produce spans



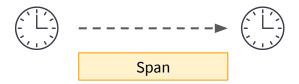
#### **Performance: Reduce Contention**





### **Performance: Faster Timing**

A basic span: when it is started, when it is ended.



- CLOCK\_MONOTONIC (with vDSO)?
  - × 25 ns ....... 16% overhead in KvGet with 10 spans
- CLOCK\_MONOTONIC\_COARSE?
  - $\sqrt{5}$  ns ........... 3% overhead in KvGet with 10 spans
  - × Precision can be as low as 4ms



### **Performance: Faster Timing**

• Minitrace: **TimeStampCounter register** (x86/x64) via *RDTSCP* instruction

```
√ 8 ns
```

√ Nanoseconds precision



### **Performance: Faster Timing**

- Minitrace: **TimeStampCounter register** (x86/x64) via *RDTSCP* instruction
  - √ 8 ns
  - √ Nanoseconds precision

#### Caution:

- Without CONSTANT\_TSC + NONSTOP\_TSC, TSC is not synced in different cores
- Even with these flags, TSC may be unsynced
  - VM, some CPU faults, ...
- Non x86: Fallback to CLOCK\_MONOTONIC\_COARSE

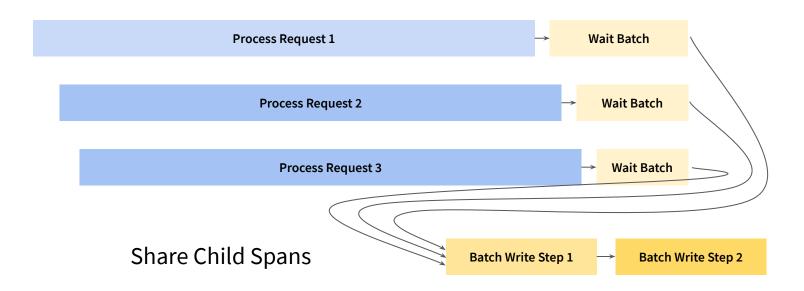


#### **Performance: Serialization**

- Memory spans ----(Serialization)---> Tracing Storage (e.g. Jaeger)
- Complete timing & collecting
- Selective reporting based on request latency



## **Trace Batch Systems**





### Community

- A **subset** of OpenTracing is implemented for performance.
- Built-in support: Spans can be reported to Jaeger.
- Early bird try out, you can use in your own projects:
  - https://github.com/tikv/minitrace-rust
- Some optimizations will be contributed to opentelemetry-rust.
  - We hope one day the official Rust client can adopt all optimizations!



#### **TiKV & Resources**

- Tracing will be available in the upcoming TiKV v5.0
- GitHub: <a href="https://github.com/tikv/tikv">https://github.com/tikv/tikv</a>
- Website: <a href="https://tikv.org/">https://tikv.org/</a>
- Twitter: <u>@tikvproject</u>
- Slack: <u>tikv-wg.slack.com</u>