

Empowering Cloud Native Networking with Arm Ecosystem

Trevor Tao (Zijin Tao), Hanyu Ding

Jianlin Lv, Song Zhu, Jingzhao Ni

Nov/2020

Agenda

- Introduction
- Reference Cloud Native Networking (CNN) Stack on Arm
- High Performance CNIs for CNN on Arm
- Multi-Interface Requirement with SRIOV support on Arm
- Performance Tests for various CNIs on Arm platform
- Cloud Native Networking Use Cases and Deployment on Arm
- Future Work(Provisional)



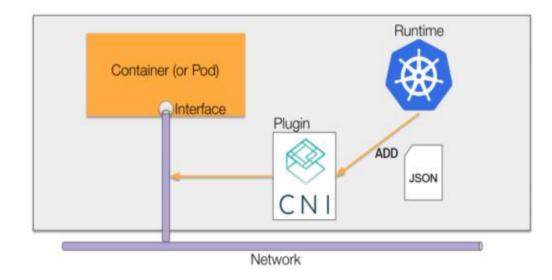
Introduction



Introduction

What is Cloud Native Networking

- Cloud native computing means to use containerized open source software stack, where each part of the app is packaged in its own container, dynamically orchestrated so each part is actively scheduled and managed to optimize resource utilization
- Cloud native networking is an approach to provide the networking environment for building and running applications that exploit the advantages of the cloud computing delivery model.
- So high performance, flexible and function rich container networking technology is the key to success of cloud native computing
- Various CNIs (Container Networking Interface) are emerging to support cloud native networking
 - <u>A Cloud Native Computing Foundation</u> project, consists of a specification and libraries for writing plugins to configure network interfaces in Linux containers, along with a number of supported plugins



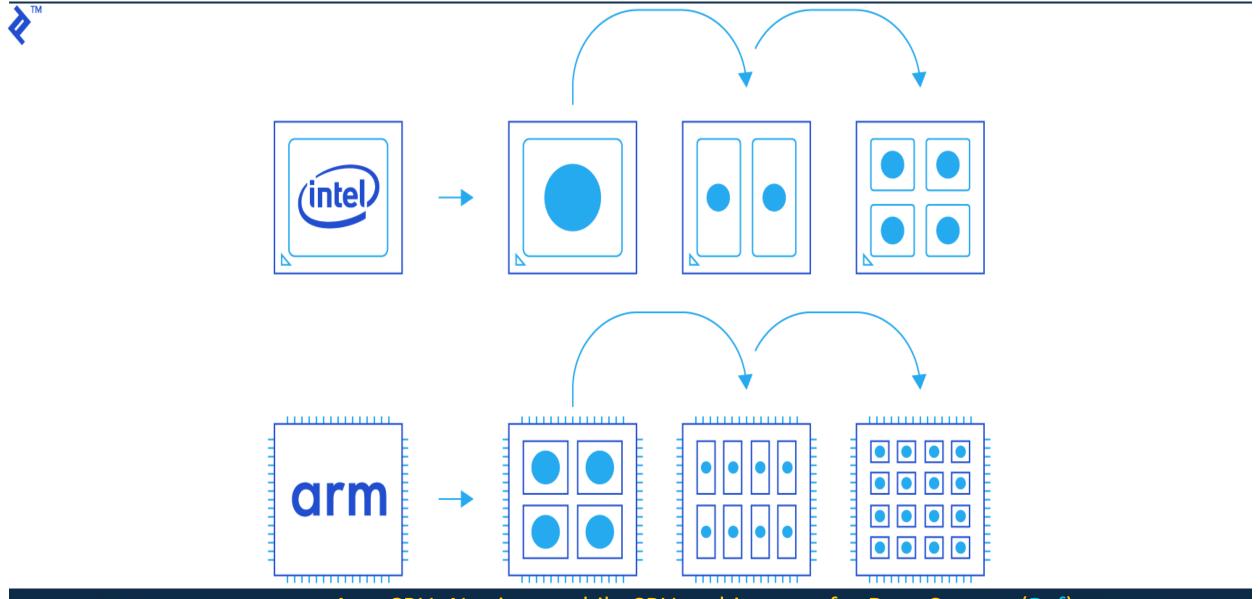
CNIs follows Kubernetes networking model:

- All Pods can communicate with all other Pods without using network address translation (NAT).
- All Nodes can communicate with all Pods without NAT.
- The IP that a Pod sees itself as is the same IP that others see it as.

- Networking objects
 - Container-to-Container networking
 - Pod-to-Pod networking
 - Pod-to-Service networking
 - Internet-to-Service networking



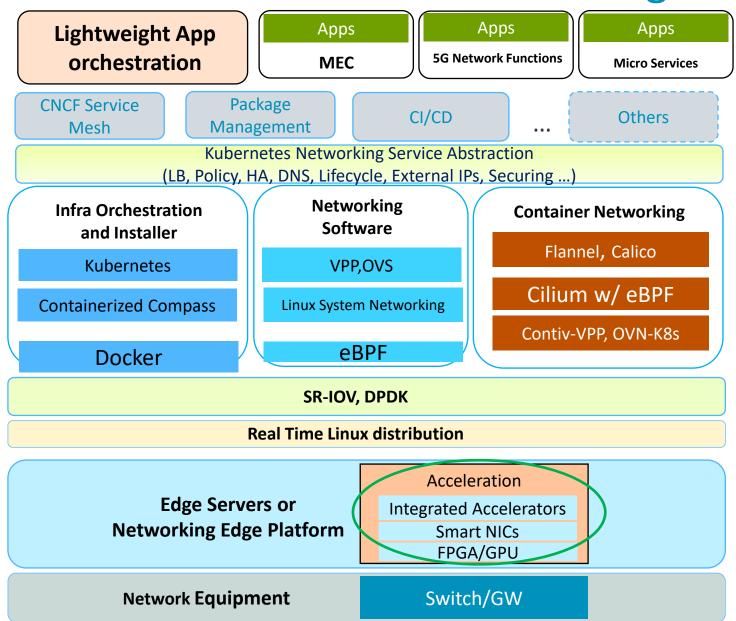
Cloud Native Computing with Arm



Reference Cloud Native Networking Stack on arm



Reference Cloud Native Networking Stack



- Cloud native oriented architecture
 - Container based
 - Servers and customized Cloud platforms
 - Containerized/Virtualized NFs vs Physical NFs
 - Accelerator interface
- Resource constraints
 - Kubernetes
 - CNIs for Kubernetes
- Supporting network technologies
 - L2: Linux ethernet driver, bridge, DPDK, virtual switching(OVS, VPP)
 - L3: IPtables
 - Overlay tunnel: IPIP, VXLAN, NVGRE
 - L2/3: Kernel JIT: eBPF (programs, maps, registers, helper functions, ...)
 - L7: HTTP Proxy(ENVOY)
- HW Accelerations
 - Integrated accelerators
 - PCIe/CCIX attached accelerator (Smart NICs...)
 - OVS/eBPF offload with SmartNIC

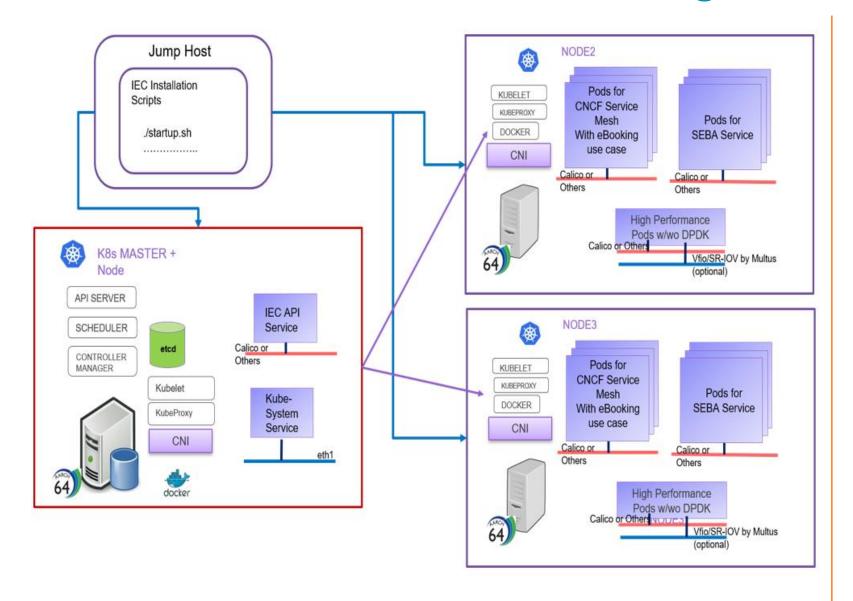


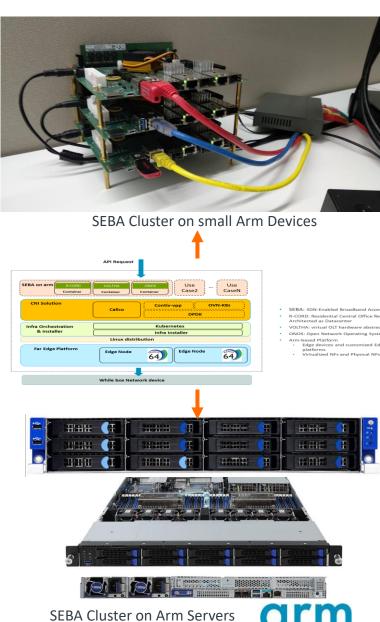






Reference Cloud Native Networking Cluster on Arm





High Performance CNIs for CNN on Arm



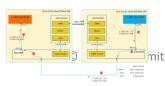
High Performance CNIs available for Arm Cloud Native Stack

Things now available in <u>Akraino IEC Blueprint</u> Arm edge stack as a ref:

IEC Arm Reference Stack

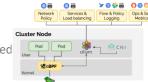
Calico

- pure IP networking fabric
- high-level network policy management by iptables
- Good scalability
- Support direct(non-overlay) and overlay(IPINIP, VxLAN) network connection
- Easy deployment
- Calico-VPP appears



Cilium

- Linux-Native, API-Aware Networking and Security for Containers
- Linux eBPF based network policy, load balance and security which is believed to be with incredible performance
- L3 networking between hosts
- Good scalability too



Contiv-VPP

- uses <u>FD.io VPP</u> to provide network connectivity between PODs
- Native DPDK interface support for phy NIC
- Native VPP
 ACL/NAT based
 network policy and
 access
- Good performance but with rather complex configuration
- DPDK based



OVN-K8s

- OVS/OVNcontroller based K8s networking solution
- Rather good performance with OVS inherited
- Use OVN logical switches/routers to connect Pods and for outside access
- No OVS-DPDK support now



Multus/ SRIOV

- Direct physical interfaces(**PF/VFs**) support for Pods
- High performance with direct Linux kernel eth driver or DPDK PMD driver
- Usually co-work with other CNIs, such as Flannel, Calico by Multus or other glue CNI
- Need resource description or annotation when do the configuration for CNI and Pod setup



Flannel

Widely used and almost easiest deployment for a simple K8s networking

Linux network bridge for pod connection and overlay based communication for inter-hosts access

Easy to be integrated into other container networking solution, e.g., Cilium

No good network policy support



Code Review / iec.git / tree

summary, | shortlog | log | commit | commitdiff | review | tree history | HEAD | snapshot

fix issue that deploy cilium on latest image

[iec.git] / src / foundation / scripts / cni /

drwxr-xr-x		<u></u>	
drwxr-xr-x	-	<u>calico</u>	tree history
drwxr-xr-x	-	<u>cilium</u>	tree history
drwxr-xr-x	-	<u>contivpp</u>	tree history
drwxr-xr-x	-	danm	tree history
drwxr-xr-x	-	<u>flannel</u>	tree history
drwxr-xr-x	-	<u>multus</u>	tree history
drwxr-xr-x	-	<u>ovn-kubernetes</u>	tree history

Repo:

https://gerrit.akraino.o
rg/r/admin/repos/iec



Status of CNIs on Arm Platform and Our Contributions (only a small part of)

- Calico officially announced to be supported on arm platform
 - announced on the Calico blog back: https://www.projectcalico.org/announcing-calico-v3-2/
 - https://docs.projectcalico.org/archive/v3.2/releases#multiple-architectures
 - https://github.com/projectcalico/calico/issues/3783

Multiple Architectures

Thanks to concerted efforts from the community, images are now available for all components for the arm64 and ppc64le architectures.

- Cilium CNI (v1.8 and above) are generally available on arm platform
 - Ported Cilium master version on Arm server and deployed Nginx to verify and test k8s cluster
 - Fix compiling and running issue on Arm64;
 - Added arm64 support for building cilium-related images(cilium-agent, cilium-operator, cilium-runtime, cilium-builer, cilium-proxy,...);
 - Add multi-arch support for cilium-related images;
 - Add arm64 support for cilium CI/CD.
- Contiv-VPP CNI
 - Add arm64 support for Contiv/VPP docker images building to the upstream
- OVN-Kubernetes CNI
 - Add arm64 support for daemonset image build
 - Add arm64 and multi-arch support for ubuntu image
 - Add scripts for daemonset installation

- **Upgrade ovs version in Dockerfile to 2.11**
- Remove the installation of containernetwork-cni
- Change the value for selecting the master node

Multus CNI

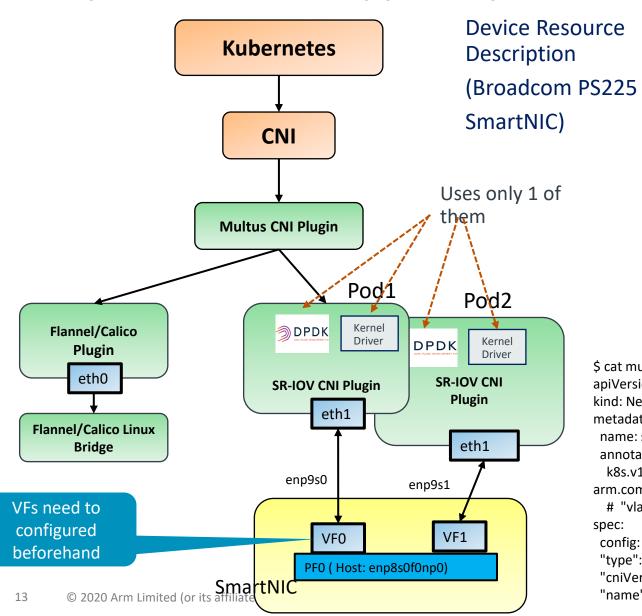
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Multi-Interface Requirement with SRIOV and SmartNIC support on Arm



Multiple Interfaces Support by SRIOV CNI

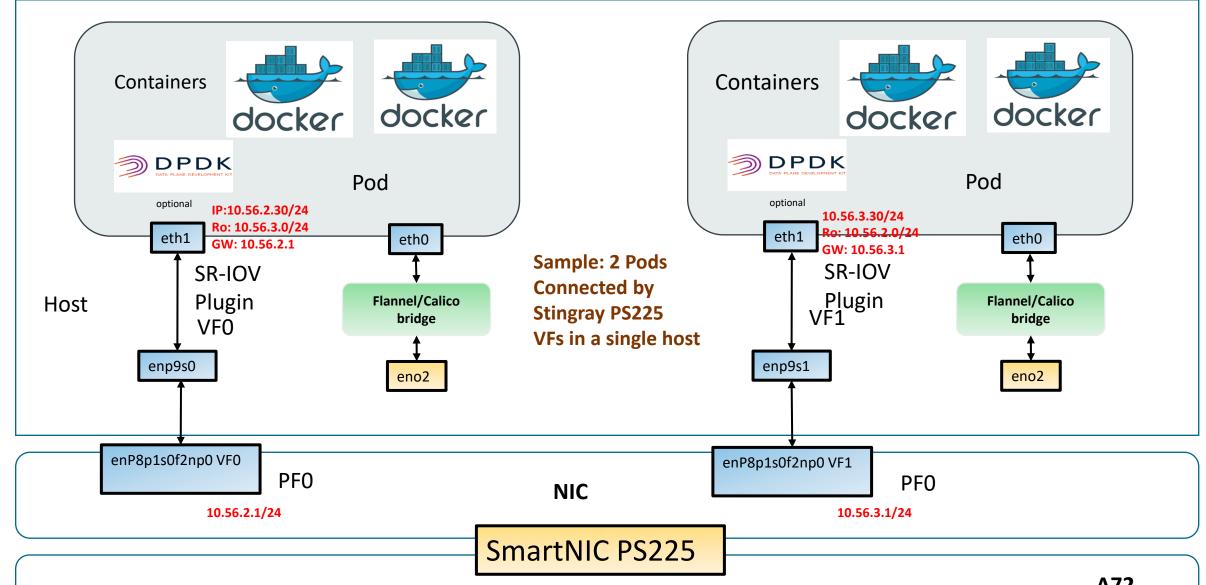


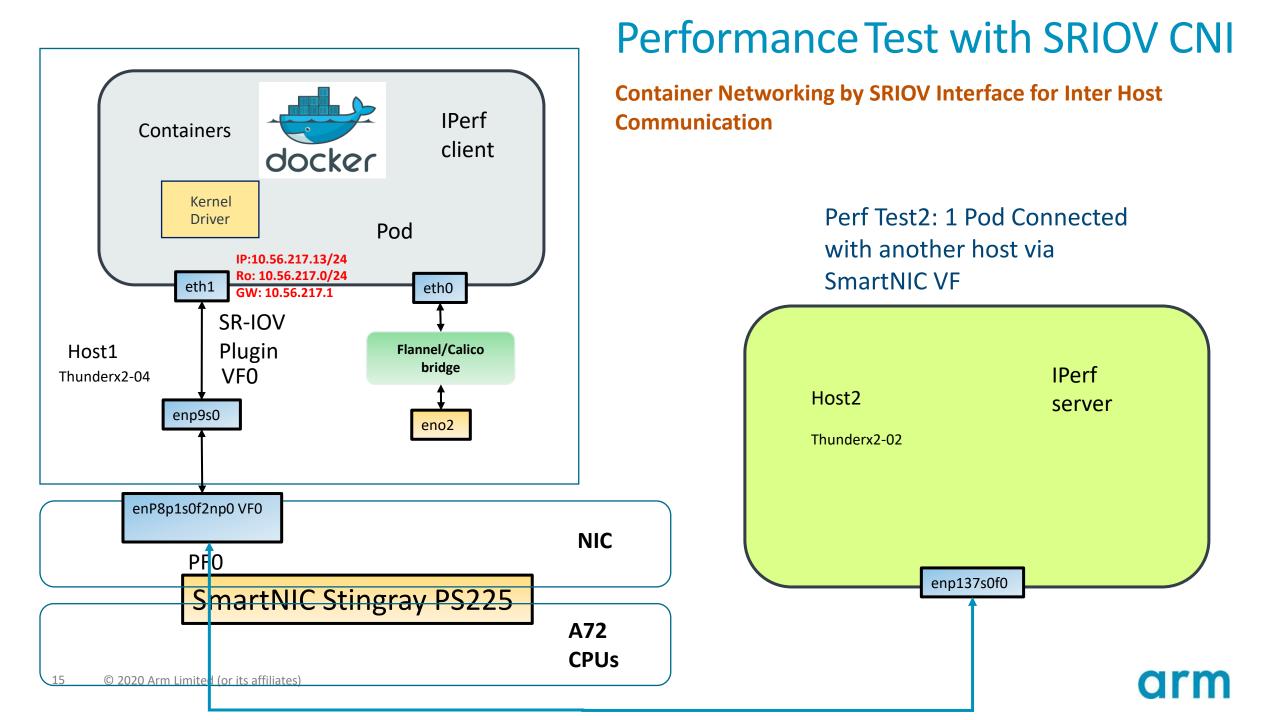
```
apiVersion: v1
                                          For DPDK device driver:
         An example of Pod spec using above SR-IOV CRD:
       apiVersion: v1
       kind: Pod
       metadata:
          name: testpod1
          labels:
            env: test
          annotations:
            k8s.v1.cni.cncf.io/networks: sriov-net1
       spec:
          containers:

    name: appcntr1

            image: iecedge/centos-tools-arm64
$ cat multu
            imagePullPolicy: IfNotPresent
apiVersion:
            command: [ "/bin/bash", "-c", "--" ]
kind: Netwo
metadata:
            args: [ "while true; do sleep 300000; done;" ]
name: sric
            resources:
annotation
 k8s.v1.cn
              requests:
arm.com/p
               arm.com/ps225_sriov_netdevice: '1'
 # "vlan":
              limits:
config: '{
               arm.com/ps225 sriov netdevice: '1'
"type": "sr
"cniVersion . U.S.I ,
"name": "sriov-network",
```

Networking Model for Containers in a Single Host by SRIOV CNI





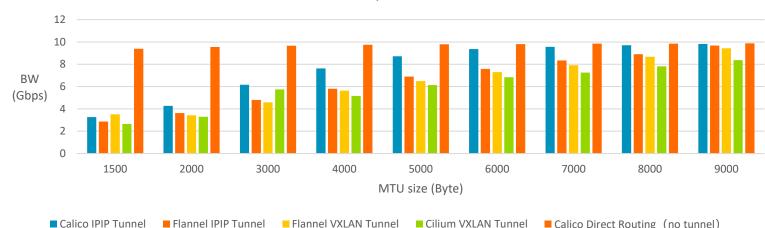
Performance Tests for various CNIs on Arm platform



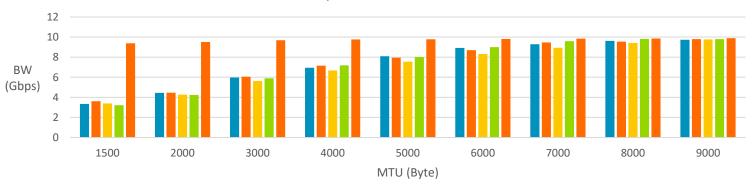
Benchmarking Results of TCP Throughput for CNIs with Different Backends

Node to Pod TCP Performance for IPIP(Calico), IPIP(Flannel), VXLAN(Flannel), VXLAN(Cilium) and Direct Routing(no Tunnel, Calico)

Inter-Hosts 10Gb/s ether connection



Pod to Pod Performance for IPIP(Calico), IPIP(Flannel), VXLAN(Flannel), VXLAN(Cilium) and Direct Routing(no Tunnel, Calico)
Inter Hosts 10Gb/s ether connection



Observation for TCP performance over CNIs

- The performance gap between CNIs are not so explicit when overlay tunnel is used;
- Calico and Flannel show a little bit better performance than Cilium for most MTUs here
- With IPIP/VXLAN overlay tunnel enabled, the larger MTU size, the throughput(BW) performance is better.
- When use direct routing(here by Calico, Cilium also support this mode), the throughput performance is not significantly affected by MTU size.
- The performance of direct routing here by Calico, Cilium also support this mode) is better than IPIP enabled.
- The IPIP tunnel is a little better than VXLAN tunnel
- In general, the node to pod TCP performance is better than that of pod 2 pod which flows one more step (of veth connection to the Linux kernel) .

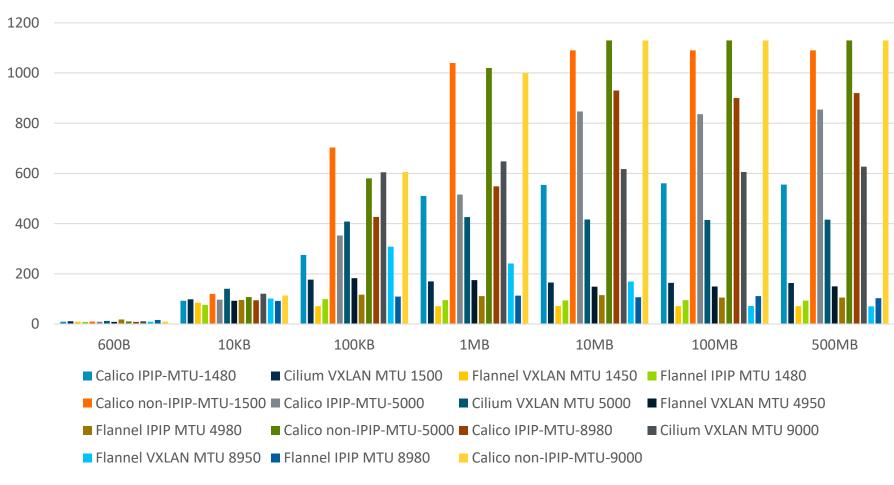
Finally, compared with different scenarios, it proves that IPIP/VXLAN overlay tunnel which are now implemented in the Linux kernel is the key factor which affects the performance of CNIs on arm

Question:

Why the node to pod performance is no better than that of pod to pod case for Cilium?

HTTP Performance Benchmarking for CNIs with various backends



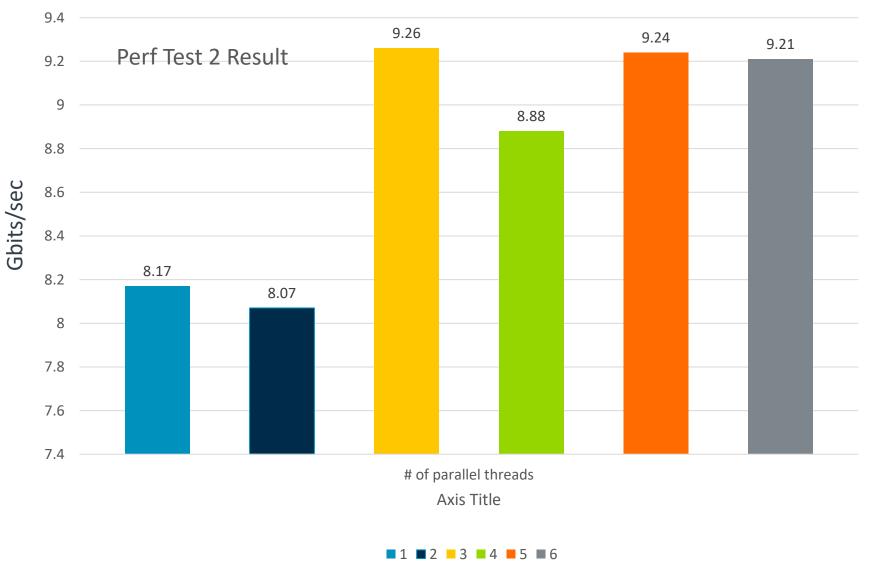


Observation:

- For 3 CNIs, the performance gap is minor when accessing small files
- As previous, the direct routing (no tunnel) mode shows the best performance with any other tunnel based approaches;
- For file size >= 100KB, the Calico shows explicitly the best performance over other 2 CNIs
- Flannel shows the worst host2service performance over other 2 CNIs, even with bigger MTUs, for either IPIP tunnel or VXLAN tunnel
- For large MTU and large file size, Cilium shows similar performance with the Calico CNI
- For non-IPIP, the performance gap between different MTU is not so explicit, so it's believed that the tunnel communication is actually the bottleneck, which is the same as previous

Performance Test Result

Pod Communication Performance by SRIOV CNI with another host via PS225 VF





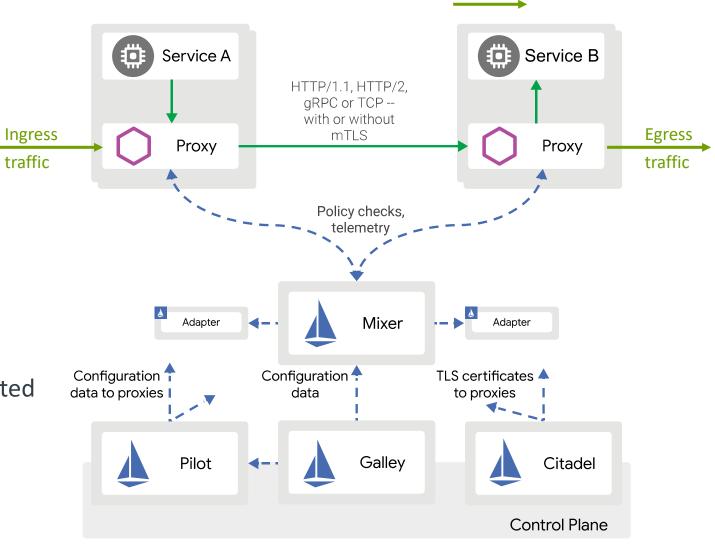
Cloud Native Networking Use Cases and Deployment on Arm

Service Mesh -- Istio Introduction

Istio Architecture

- Control plane
 - Mixer
 Policy enforcement and telemetry checks
 - Pilot
 Service communication policies configuration
 - Galley
 Control plane configuration
 - Citadel
 Security and credential management

 In latest version, those modules are integrated into one component -- istiod
- Data Plane
 - Proxy (Envoy)
 High-performance proxy developed in C++

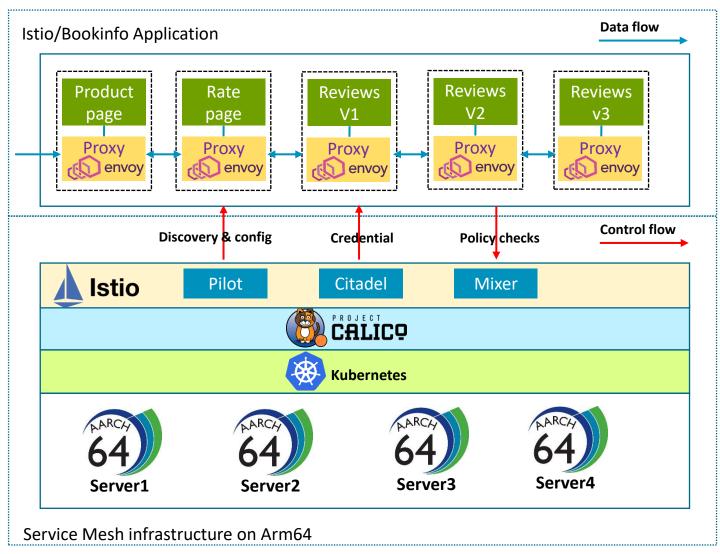


Control flow

Data flow

Service Mesh is the communication layer in a microservice setup. All requests, to and from each of the services go through the mesh.

Istio – A Robust Service Mesh – on Arm64









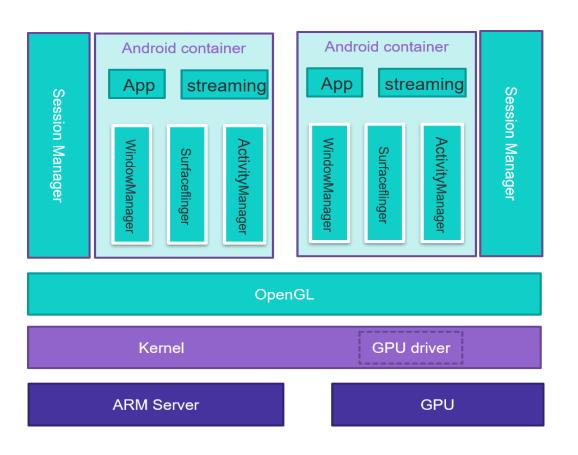
- Istio An open platform to connect, manage, and secure microservices
- Calico Simple, scalable and secure Container Network Interface
- Envoy High-performance edge/middle/service proxy





Use Case in China Mobile

China Mobile and its partners jointly initiated and to be PTL as two Akraino IEC BP projects, which have successfully released the R3 version of the community;



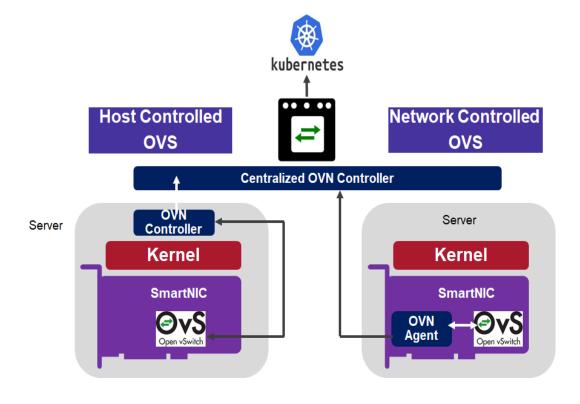
IEC Type 3:

Android cloud native applications on Arm servers in edge

- Mainly by deploying cloud game rendering, encoding and decoding, storage and distribution capabilities at edge nodes, the user interaction delay is reduced, so that users can enjoy the ultimate game experience without buying expensive game terminals;
- The project will provide Android cloud native running environment under arm architecture for mobile terminal applications at the edge, reduce the difficulty of deployment and development of applications on the edge cloud, and reduce the deployment cost of Android edge cloud;



Use Case in China Mobile



IEC Type 5: SmartNIC

- The first release of the integrated edge cloud type 5 blueprint is based on the arm SoC architecture, and OVS-DPDK is unloaded to the smart network card, which can enhance the throughput performance of the edge network VPC, reduce the packet loss rate, and enhance the management of network card resources to save more computing resources;
- In the future, the performance of 5G UPF network elements deployed in the edge cloud data center of operators can also be enhanced by realizing the uninstallation function of network cards;

China Mobile is willing to further promote the maturity, business innovation of the cloud native computing through active exploration and practice in the field of Cloud Native & Edge Computing open source.



Future Work(Provisional)



Future Work(Provisional)

- CNIs support enhancements on arm platform(CI/CD, performance, feature comparisons,...)
- Performance optimization of overlay tunnel communication on arm platform
- Further uses cases and deployments about cloud native networking on arm platform
 - AR/VR,
 - 5G
 - MEC
- Service mesh integration with high performance CNIs, such as Cilium/Proxy
- Further DPDK incorporated container networking usage model and performance evaluation
- Further CI for high performance container networking solutions on arm with up-to-date processes



Some References

- Cisco: Cloud-Native Network Functions
- INTRODUCTION TO KUBERNETES* NETWORKING AND ACCELERATION WITH DPDK
- Flannel CNI
- Overview of Calico CNI for Kubernetes
- Kubernetes: Flannel networking
- Network Service Mesh
- <u>Cilium</u>
- Istio and Service Mesh
- Multus CNI
- SRIOV CNI
- SRIOV Network Device Plugin



arm

Thank You

Danke

Merci

谢谢

ありがとう

Gracias

Kiitos

감사합니다

धन्यवाद

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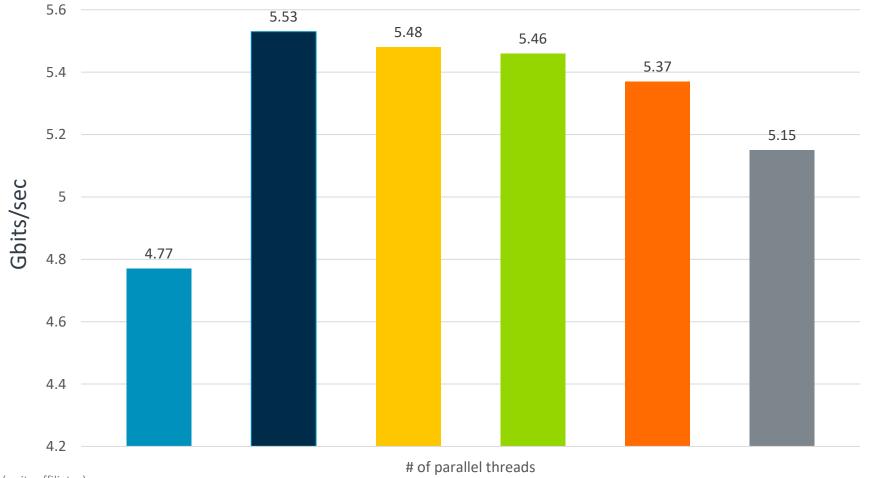
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Performance Test Result

Note: Here we choose iperf instead of iperf3 due to its multithreaded implementation

Perf Test 1 Result

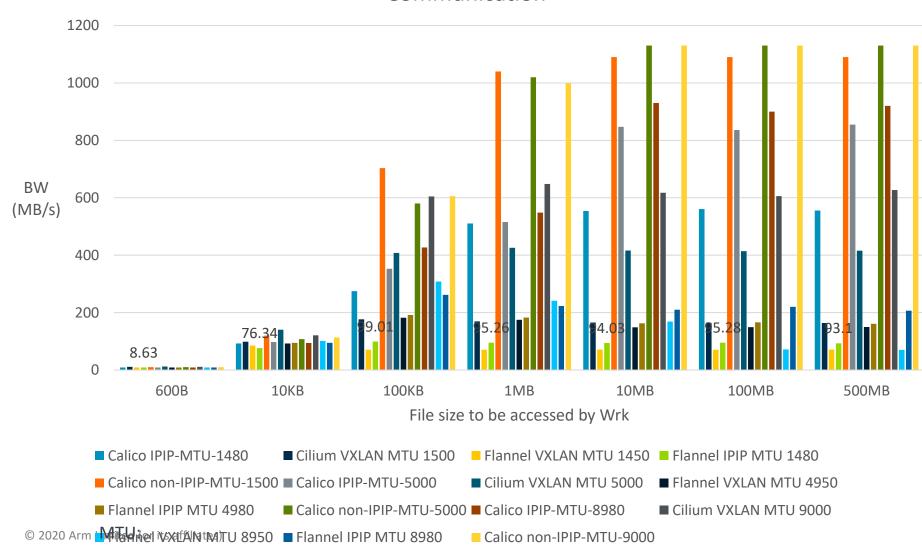
Pod Communicati on Performance with SRIOV CNI in the same host via PS225 VFs





HTTP Performance Benchmarking for CNIs with various backends

Pod2Pod HTTP Performance with Calico IPIP vs non-IPIP for Cross-Host Communication

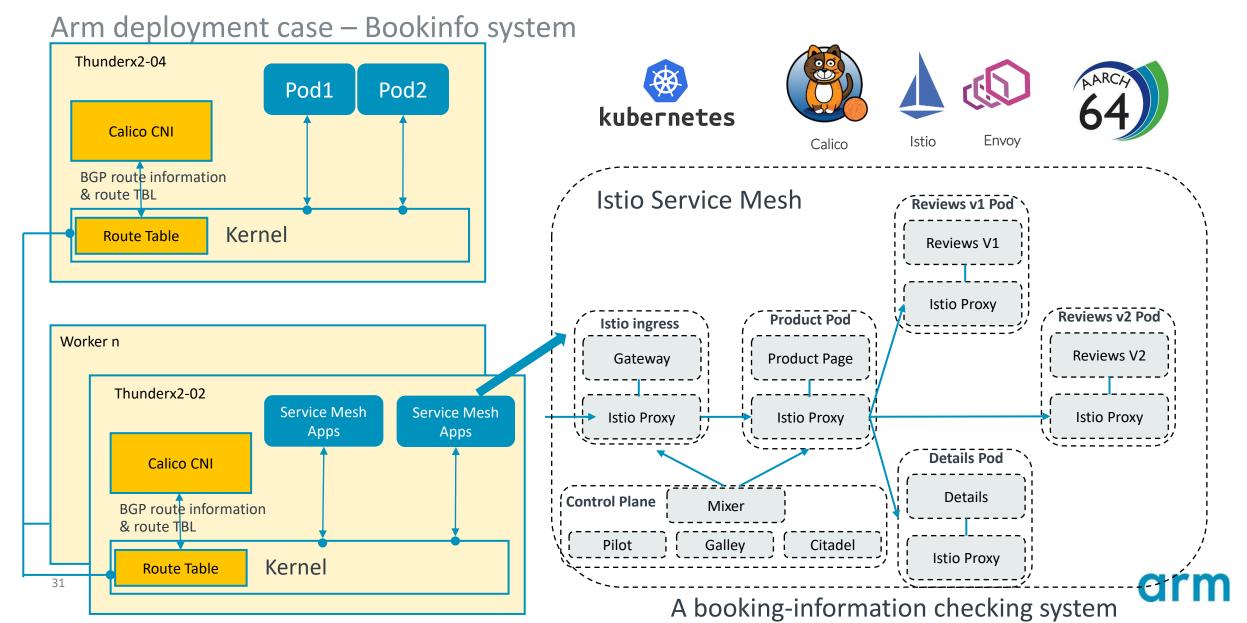


Initial observation:

- For file size >
 =10MB, the MTU
 has little effect to
 the final
 performance
- The performance is much higher than those of IPIP when file size >= 100KB
- When MTU is small, the performance gap between IPIP and non-IPIP is higher



Istio Simple Case on Arm64



Contiv/VPP on Arm

What We Have Done:

TrevorTaoARM commented on Jun 11

Add arm64 support for contiv/vpp docker images building The naming rules of the built docker images is given below: For a built image named as \${repo}:\${tag}, or \${repo}/\${component}:\${tag},

- 1. For x86_64 arch, it would be named as: \${repo}-amd64:\${tag}, or \${repo}/\${component}-amd64:\${tag}
- For arm64 arch, it would be named as: \${repo}-arm64:\${tag}, or \${repo}/\${component}-arm64:\${tag}
- Add arm64 support for Contiv/VPP docker images building to the upstream
- Built the needed docker images for Contiv/VPP on arm64
- Create the corresponding Kubernetes setup yaml file for arm64 platform
- Contiv/VPP pods are booted up for Kubernetes on arm64 platform
- Basic container networking with Contiv/VPP on 1 single host(Arm server)

```
oot@net-arm-thunderx-01:/home/trevor# kubectl get pod -n kube-system -o wide
                                                                              grep contiv
    /-etcd-0
                                                                                        10.169.40.76
                                                                                                       net-arm-thunderx-01
                                                        Running
     -ksr-5f29x
                                                                                        10.169.40.76
                                                                                                       net-arm-thunderx-01
                                                        Running
    /-vswitch-5c4bw
                                                        Running
                                                                                        10.169.40.64
                                                                                                       net-arm-d05-08
                                                                                        10.169.40.76
     -vswitch-qdgkm
                                                                              24s
                                                                                                       net-arm-thunderx-01
                                                        Running
oot@net-arm-thunderx-01:/home/trevor#
```

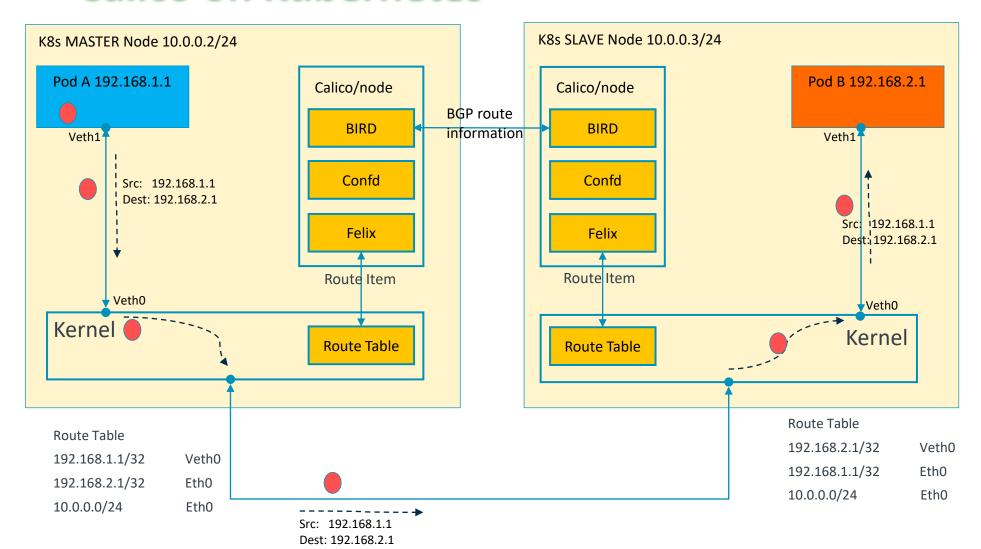
TBD:

- Tested: To be tested: container networking between 2 hosts(Arm servers)
- Further networking function verification/enhancement
- 2 Possible improvement work: functional enhancement with more network interfaces supported

 Contiv/VPP



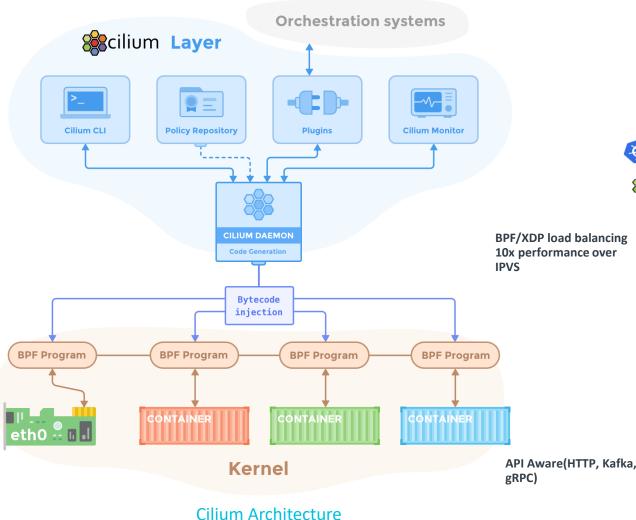
Calico on Kubernetes



- Pure IP networking fabric
- No encapsulation
 needed when simple L2
 connection available
 for nodes
- Easy deployment and debug
- Supporting Kubernetes
 Network Policy by
 iptables
- Good scalability withBGP based routing

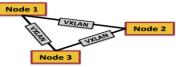


Cilium – API Aware Networking



Networking Model: Encapsulation or Direct Routing





No further dependencies

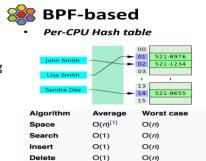
Mode II: Direct Routing



Integrations:

- Cloud routers
- kube-router, BIRD, ...

Kubernetes Services Implementation



iptables kube-proxy

- Linear List
- All rules have to be replaced as a whole



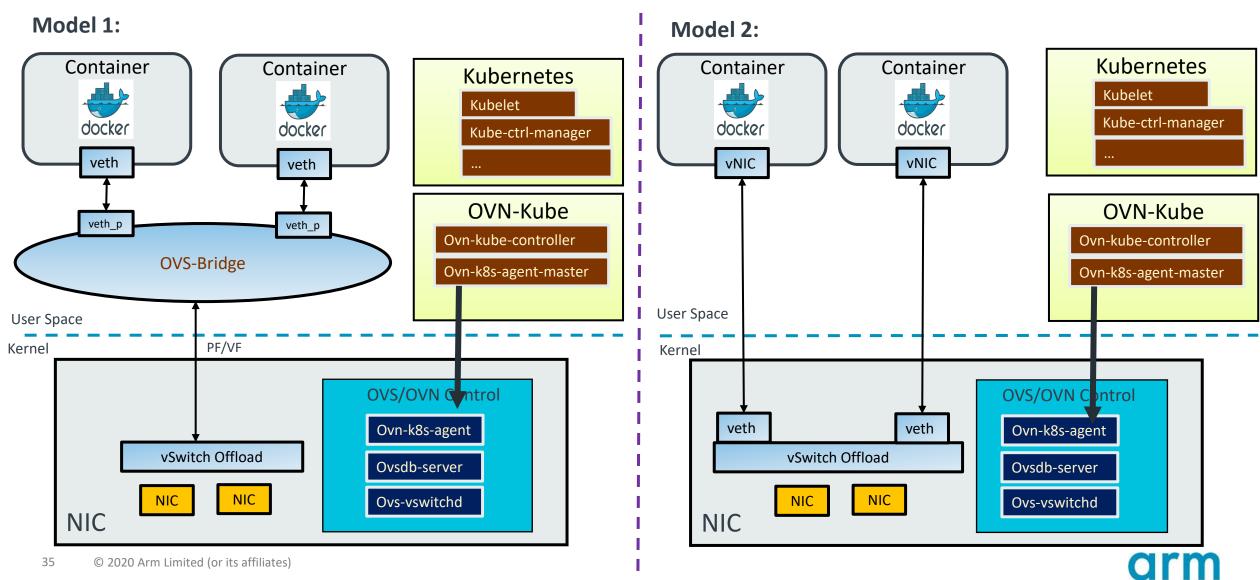
API Aware Security



Cilium: API Aware Netowrking & Network Security for Microservices using BPF & XDP

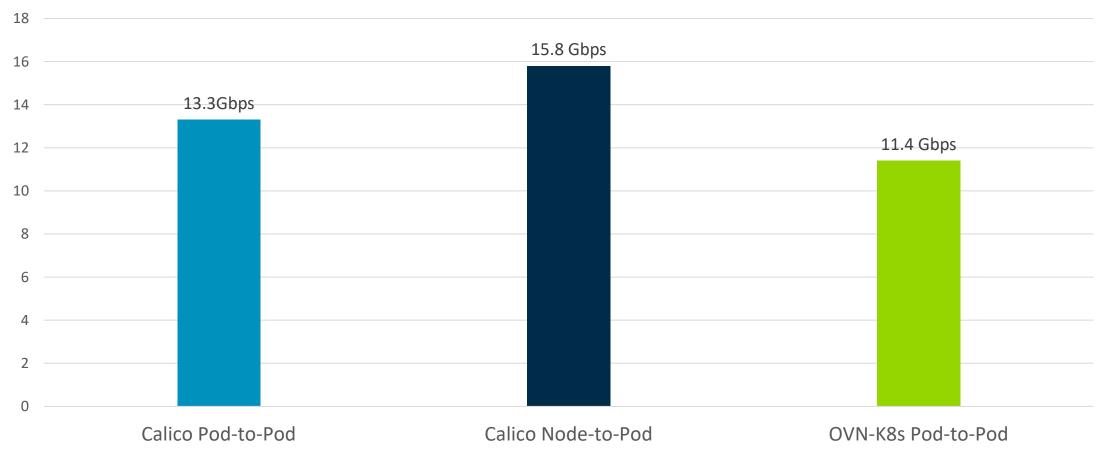


A Very Raw Thinking on the Possible Model for Container Networking with SmartNIC OVS offload support



Performance of Calico and OVN-Kubernetes

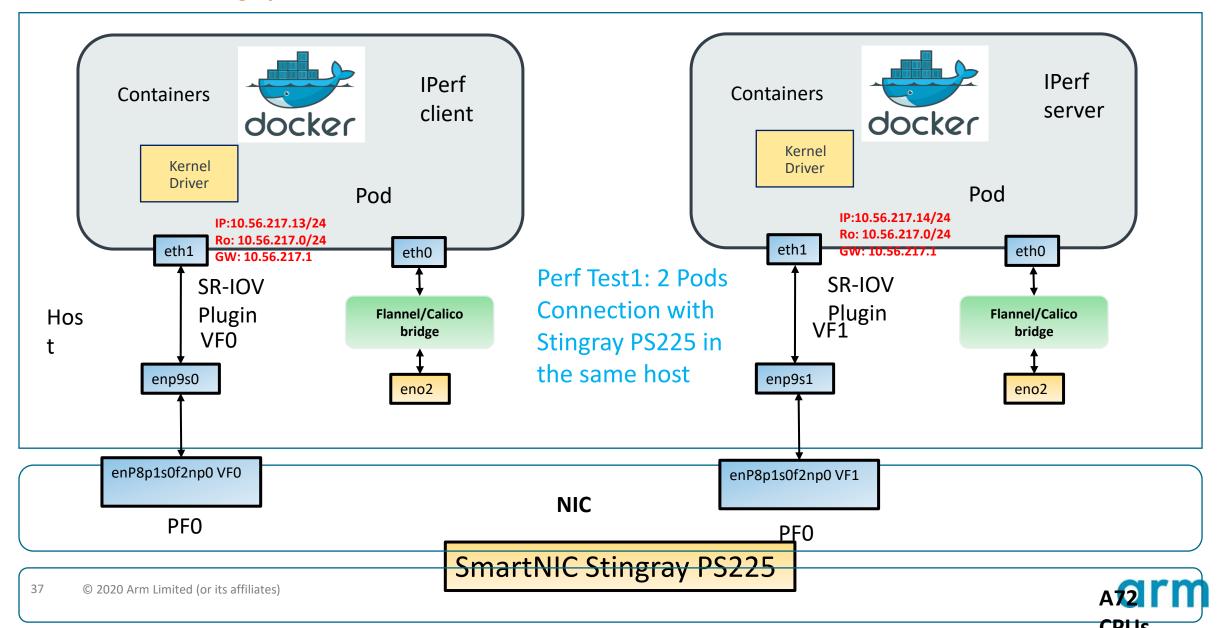
Performance of Calico and OVN-Kubernetes (tested by iperf3)





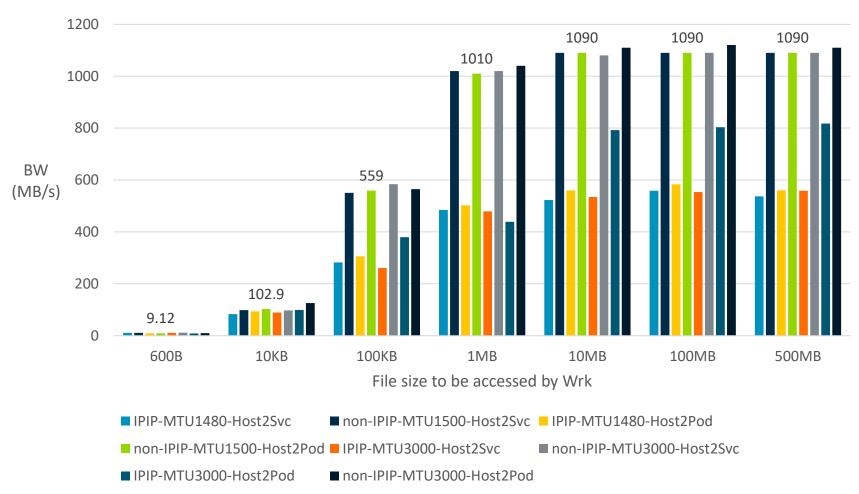
Performance Test with SRIOV CNI

Container Networking by SRIOV Interface for Intra Host Communication



HTTP Performance Benchmarking for Calico CNI

Host2Pod vs Host2Service HTTP Performance with Calico IPIP and non-IPIP for Cross-Host Communication



Observation:

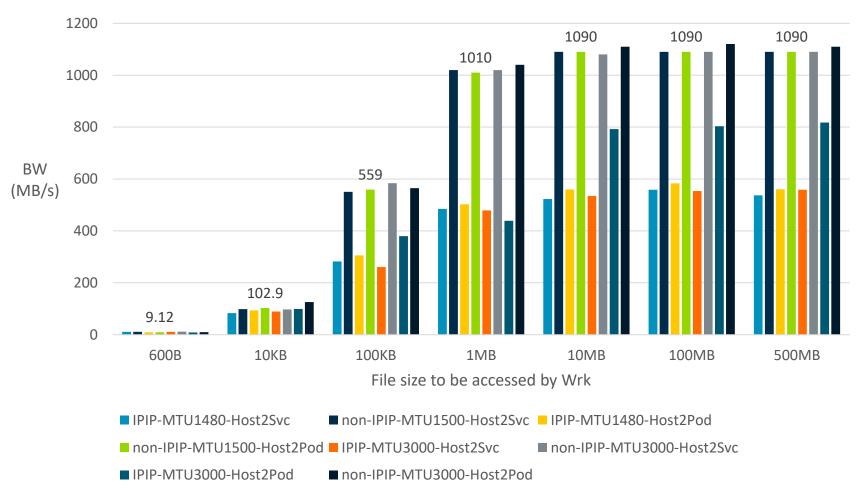
- The performance gap is minor when accessing small files
- For small file size, the host2pod and host2service performance is almost the same, which means the service access(by iptables configured by kube-proxy) is not the bottleneck for HTTP service
- The performance of non-IPIP is much higher than those of IPIP when file size >= 100KB
- For large MTU and large file size, the host2pod performance is better than host2svc.
- For non-IPIP, the performance gap between different MTU is not so explicit, so it's believed the IPIP is actually the bottleneck, which is the same as previous

Wrk: thread 5, connections: 10



HTTP Performance Benchmarking for Calico CNI

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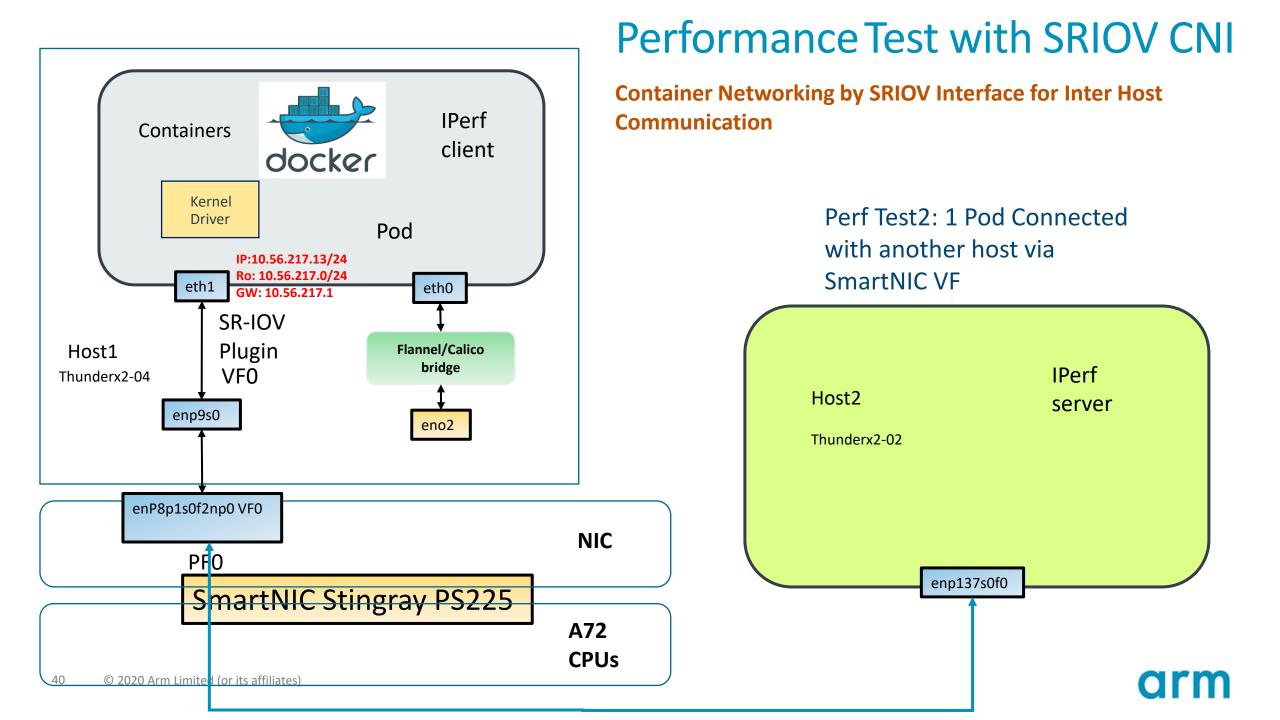


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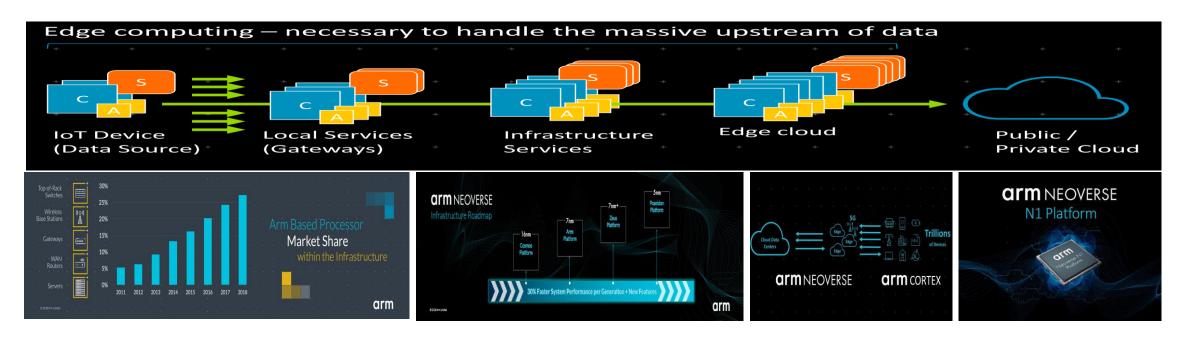
Wrk: thread 5, connections: 10





Introduction

- The purpose of edge computing and MEC is to bring real-time, high-bandwidth, low-latency access to latency-dependent applications, distributed at the edge of the network. Arm CPUs are cost effective, low power consumption and customize-allowable which are preferred to be used by edge cloud service vendors
- On the other side, a high performance, flexible and easy deployable container networking of edge software stack is the key to the success of using Arm platform on edge cloud.

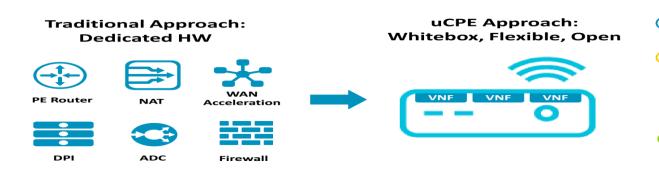




Introduction

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- On the other side, a high performance, flexible and easy deployable container networking of edge software stack is the key to the success of using Arm platform on edge cloud since the widely used VNFs are deployed by container-based orchestration engine, such as Kubernetes, OpenShift or others.

Universal CPE example of Edge compute



- Service providers looking to simplify customer site deployments
- Replace multiple dedicated appliances with VNFs running on a uCPE a single, universal platform
 - Customers can provision VNFs from different vendors on uCPE boxes via operator platforms
 - uCPE should leverage white box servers with no proprietary extensions

Arm ecosystem leverage price, power, acceleration advantages

