

# Hsiu-Tsu (David) Shui

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## EDUCATION

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### University of Michigan Ann Arbor

*M.S.E in Mechanical Engineering*

· Focusing Area: Vehicle Dynamics, Control, and Navigation

Sep. 2024 - present

Ann Arbor, USA

### National Cheng Kung University (NCKU)

*B.Eng. in Aeronautics and Astronautics Engineering*

· Coursework: Flight Mechanics | Control System Design | Introduction to Navigation and Guidance | Introduction to Image Processing, Computer Vision, and Deep Learning | Computer Vision in Deep Learning Implementation and its Applications

· GPA: 3.84/4.3, last 60 GPA: 4.01/4.3

Sep. 2018 - Jan. 2023

Tainan, Taiwan

### Polytechnique Montréal

*International Thematic Cluster in Dep. of Software Engineering*

· Coursework: Software Testing Engineering | Software Architecture and Advanced Design | Laboratory Internship

· GPA: 4.0/4.0

Sep. 2022 - Dec. 2022

Montréal, Canada

## RESEARCH EXPERIENCE

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### Intelligent Unmanned Aircraft System Laboratory, NCKU

*Research Assistant, supervisor: Prof. Ying-Chih, Lai*

· Researched an improved particle swarm optimization (PSO) applied to multiple UAV systems, **verifying the proposed method could find a global optimal free-collision path either in simulations or real world**

· Instructed the laboratory training focused on Python programming, image processing (Gaussian filter, Hough Transform, Convolution), machine learning (KNN, SVM), and deep learning (CNN frameworks, R-CNN)

· Developed embedded systems, combining with sensor fusion for autonomous aerial and ground vehicles

· *Skills: C++, Python, MATLAB, Ubuntu, ROS, TDA4VM, LaTeX*

Aug. 2023 - Apr. 2024

Tainan, Taiwan

### Mobile Robotics and Autonomous Systems Laboratory, Polytechnique Montréal

*Research Intern, supervisor: Prof. Jérôme Le Ny*

· **Validated the 2D-laser SLAM** by developing real-time platforms

· *Skills: C++, Ubuntu, ROS 2, Raspberry Pi 3, LiDAR, LaTeX*

Sep. 2022 - Dec. 2022

Montréal, Canada

### Department of Civil Engineering, National Taiwan University (NTU)

*Research Intern, supervisor: Prof. Lap-Loi Chung*

· Conducted stress analyses on 4-digit NACA airfoils, **verifying aerodynamic properties of NACA 2412 from previous studies**

· *Skills: Ansys, MATLAB, SOLIDWORKS*

Jul. 2020 – Sep. 2020

Taipei, Taiwan

## PROJECT EXPERIENCE

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### The Development of an In-Lane Level Vehicular Navigation System with Resilient MCRING Fusion Schemes for Smart Electric Vehicles

*Project commissioned by the National Science and Technology Council, Taiwan*

· Developed TDA4VM SoC, **implementing GNSS algorithms, inertia navigation algorithms, and multiple sensors for applications in autonomous vehicles**

· *Skills: C++, Python, Ubuntu, Docker, ROS 2, TDA4VM*

Aug. 2023 - Present

Tainan, Taiwan

### The Configuration before a Deployment of the 2D Laser SLAM

*Laboratory Internship Project*

· Developed the Create 3 iRobot by **integrating the system consisting of the Raspberry Pi 3, LiDAR, and 2D-Laser SLAM**

· Programmed customized ROS 2 subscribers and publishers, **facilitating data streaming**

· **Achieved multiple machine connections and synchronizations**

· *Skills: C++, Ubuntu, ROS 2, Raspberry Pi 3, LiDAR, Vicon Tracker, LaTeX*

Sep. 2022 – Dec. 2022

Montréal, Canada

## **Comparing NoSQL datastores: a Performance Evaluation of Redis, Cassandra, and MongoDB** Sep. 2022 – Dec. 2022

*Course Project for Software Architecture and Advanced Design*

Montréal, Canada

- Utilized the YCSB benchmarking tool to analyze comparatively three NoSQL datastores: Redis, Cassandra, and MongoDB
- Deployed clusters of databases, and YCSB tool through Docker Compose, **verifying the properties of various types of NoSQL databases**

· *Skills: NoSQL, Ubuntu, Docker, Shell Scripts, Git*

## **Jetbot Self-Driving Car**

Sep. 2021 – Jun. 2022

*Capstone Project*

Tainan, Taiwan

- Developed self-driving systems, **navigating Jetbot from waypoints to waypoints**
- **Integrated computer visions and control theories to achieve our system, including camera calibration, lane tracking, object detection, PID controller, and path planning**

· *Skills: Python, MATLAB, Jetson Nano, Monocular camera*

## **Satellite Mission: Laser Aircraft Charging (LAC)**

Sep. 2021 – Jan. 2022

*Special Research Topic in Space Science and Engineering*

Tainan, Taiwan

- Conceptualized a satellite capable of charging planes On Earth from space
- Calculated the satellite's orbit, designed payload systems, selected sub-systems, finalized the structure and exterior appearance of the satellite

· *Skills: SOLIDWORKS, STK*

## **The Application and Evaluation of ORB-SLAM 2**

March. 2021 – Jan. 2022

*Special Research Topic Contest*

Tainan, Taiwan

- Surveyed different categorizations of Visual Inertial Odometry (VIO) and Visual SLAM (vSLAM)
- Implemented ORB-SLAM 2 in a real-time experiment, evaluating the TUM RGB-D datasets
- Calculated absolute trajectory estimations and RMSEs, **concluding ORB-SLAM 2 is unsuitable for fast movements and environments with light occlusion**

· *Skills: Python, MATLAB, Ubuntu, ROS, RGB-D camera*

## **HONORS & AWARDS**

- 5th Place: Special Projects Contest, "*The Application and Evaluation of ORB-SLAM 2*", NCKU, Taiwan Jan. 2022

- Study in Canada Scholarship: short-term exchange for study, Canada Sep. 2022 - Dec. 2022

## **PUBLICATION**

- Cheng, Y. J., **Shui, H. T.**, Chen, C. C., & Lai, Y. C. (2024). "Path Planning and Collision Avoidance of Multiple UAV System Based on Particle Swarm Optimization with Kinematic Consideration," *Journal of Aeronautics, Astronautics, and Aviation*, 56(1), 65-75. [https://doi.org/10.6125/JoAAA.202403\\_56\(1\).07](https://doi.org/10.6125/JoAAA.202403_56(1).07)

- **Shui, H. T.**, & Lai, Y. C., "Collaborative Path Planning and Collision Avoidance for Multi-UAV Navigation based on Accelerated Improved Particles Swarm Optimization," *Proceedings of the 2024 International Technical Meeting of The Institute of Navigation*, Long Beach, California, January 2024, pp. 618-629. <https://doi.org/10.33012/2024.19519>

## **EXTRACURRICULAR EXPERIENCE**

### **Short-Term Mission of Tainan Holiness Church**

Jul. 2022 & Jul. 2023

*Summer Short-Term Mission Member*

- Supported rural communities by assisting local residents
- Held youth and kids camps, focusing on character education

### **Aeronautics and Astronautics Summer Camp**

Mar. 2020 – Jul. 2020

*Event General Coordinator*

- Managed the science camp for 120 high school students
- Coached students with basic aerospace and engineering knowledge, e.g. solid-propellant rockets, Arduino-driven drones

### **Soccer Team of Department of Aeronautics and Astronautics**

Sep. 2019 – Jun. 2020

*Captain*

- Managed the administrative events, and planned the training courses inside the team
- Won the runner-up in Departments Cup, NCKU