Hsiu-Tsu (David) Shui

Mywebsite \(\) Linkedin \(\) Google Scholar +1)-734-604-6639 \(\) hsiuts@umich.edu

EDUCATION

University of Michigan Ann Arbor

Sep. 2024 - present

M.S.E in Mechanical Engineering

Ann Arbor, USA

· Focusing Area: Pose Estimation, Control, and Navigation

National Cheng Kung University (NCKU)

Sep. 2018 - Jan. 2023

B.Eng. in Aeronautics and Astronautics Engineering

Tainan, Taiwan

 $\cdot \ Coursework: \ Flight \ Mechanics \ | \ Control \ System \ Design \ | \ Introduction \ to \ Navigation \ and \ Guidance \ | \ Introduction \ to \ Image \ Processing, \ Computer \ Vision, \ and \ Deep \ Learning \ | \ Computer \ Vision \ in \ Deep \ Learning \ Implementation \ and \ its \ Applications$

· GPA: 3.84/4.3, last 60 GPA: 4.01/4.3

Polytechnique Montréal

Sep. 2022 - Dec. 2022

International Thematic Cluster in Dep. of Software Engineering

Montréal, Canada

· Coursework: Software Testing Engineering | Software Architecture and Advanced Design | Laboratory Internship

· GPA: 4.0/4.0

RESEARCH EXPERIENCE

Intelligent Unmanned Aircraft System Laboratory, NCKU

Aug. 2023 - Apr. 2024

Research Assistant, supervisor: Prof. Ying-Chih, Lai

Tainan, Taiwan

- · Researched an improved particle swarm optimization (PSO) applied to multiple UAV systems, verifying the proposed method could find a global optimal free-collision path either in simulations or real world
- · Instructed the laboratory training focused on Python programming, image processing (Gaussian filter, Hough Transform, Convolution), machine learning (KNN, SVM), and deep learning (CNN frameworks, R-CNN)
- · Developed embedded systems, combining with sensor fusion for autonomous aerial and ground vehicles
- · Skills: C++, Python, MATLAB, Ubuntu, ROS, TDA4VM, LaTex

Mobile Robotics and Autonomous Systems Laboratory, Polytechnique Montréal

Sep. 2022 - Dec. 2022

Research Intern, supervisor: Prof. Jérôme Le Ny

Montréal, Canada

- · Validated the 2D-laser SLAM by developing real-time platforms
- · Skills: C++, Ubuntu, ROS 2, Raspberry Pi 3, LiDAR, LaTex

Department of Civil Engineering, National Taiwan University (NTU)

Jul. 2020 - Sep. 2020

Research Intern, supervisor: Prof. Lap-Loi Chung

Taipei, Taiwan

- · Conducted stress analyses on 4-digit NACA airfoils, verifying aerodynamic properties of NACA 2412 from previous studies
- · Skills: Ansys, MATLAB, SOLIDWORKS

PROJECT EXPERIENCE

The Development of an In-Lane Level Vehicular Navigation System with Resilient MCRING Fusion Schemes for Smart Electric Vehicles Aug. 2023 - Present

Project commissioned by the National Science and Technology Council, Taiwan

Tainan, Taiwan

- \cdot Developed TDA4VM SoC, implementing GNSS algorithms, inertia navigation algorithms, and multiple sensors for applications in autonomous vehicles
- · Skills: C++, Python, Ubuntu, Docker, ROS 2, TDA4VM

The Configuration before a Deployment of the 2D Laser SLAM

Sep. 2022 – Dec. 2022

Laboratory Internship Project

Montréal, Canada

- · Developed the Create 3 iRobot by integrating the system consisting of the Raspberry Pi 3, LiDAR, and 2D-Laser SLAM
- · Programmed customized ROS 2 subscribers and publishers, facilitating data streaming
- · Achieved multiple machine connections and synchronizations
- · Skills: C++, Ubuntu, ROS 2, Raspberry Pi 3, LiDAR, Vicon Tracker, LaTex

Comparing NoSQL datastores: a Performance Evaluation of Redis, Cassandra, and MongoDB Sep. 2022 – Dec. 2022

Course Project for Software Architecture and Advanced Design

Montréal, Canada

- · Utilized the YCSB benchmarking tool to analyze comparatively three NoSQL datastores: Redis, Cassandra, and MongoDB
- · Deployed clusters of databases, and YCSB tool through Docker Compose, verifying the properties of various types of NoSOL databases

· Skills: NoSQL, Ubuntu, Docker, Shell Scripts, Git

Jetbot Self-Driving Car

Sep. 2021 – Jun. 2022

Capstone Project

Tainan, Taiwan

- · Developed self-driving systems, navigating Jetbot from waypoints to waypoints
- · Integrated computer visions and control theories to achieve our system, including camera calibration, lane tracking, object detection, PID controller, and path planning
- · Skills: Python, MATLAB, Jetson Nano, Monocular camera

Satellite Mission: Laser Aircraft Charging (LAC)

Sep. 2021 - Jan. 2022

Special Research Topic in Space Science and Engineering

Tainan, Taiwan

- · Conceptualized a satellite capable of charging planes On Earth from space
- · Calculated the satellite's orbit, designed payload systems, selected sub-systems, finalized the structure and exterior appearance of the satellite
- · Skills: SOLIDWORKS, STK

The Application and Evaluation of ORB-SLAM 2

March. 2021 - Jan. 2022

Special Research Topic Contest

Tainan, Taiwan

- · Surveyed different categorizations of Visual Inertial Odometry (VIO) and Visual SLAM (vSLAM)
- · Implemented ORB-SLAM 2 in a real-time experiment, evaluating the TUM RGB-D datasets
- · Calculated absolute trajectory estimations and RMSEs, concluding ORB-SLAM 2 is unsuitable for fast movements and environments with light occlusion
- · Skills: Python, MATLAB, Ubuntu, ROS, RGB-D camera

HONORS & AWARDS

· 5th Place: Special Projects Contest, "The Application and Evaluation of ORB-SLAM 2", NCKU, Taiwan Jan. 2022

· Study in Canada Scholarship: short-term exchange for study, Canada

Sep. 2022 - Dec. 2022

PUBLICATION

- · Cheng, Y. J., **Shui, H. T.**, Chen, C. C., & Lai, Y. C. (2024). "Path Planning and Collision Avoidance of Multiple UAV System Based on Particle Swarm Optimization with Kinematic Consideration," *Journal of Aeronautics, Astronautics, and Aviation*, 56(1), 65-75. https://doi.org/10.6125/JoAAA.202403 56(1).07
- · Shui, H. T., & Lai, Y. C., "Collaborative Path Planning and Collision Avoidance for Multi-UAV Navigation based on Accelerated Improved Particles Swarm Optimization," *Proceedings of the 2024 International Technical Meeting of The Institute of Navigation*, Long Beach, California, January 2024, pp. 618-629. https://doi.org/10.33012/2024.19519

EXTRACURRICULAR EXPERIENCE

Short-Term Mission of Tainan Holiness Church

Jul. 2022 & Jul. 2023

Summer Short-Term Mission Member

- · Supported rural communities by assisting local residents
- · Held youth and kids camps, focusing on character education

Aeronautics and Astronautics Summer Camp

Event General Coordinator

- · Managed the science camp for 120 high school students
- · Coached students with basic aerospace and engineering knowledge, e.g. solid-propellant rockets, Arduino-driven drones

Soccer Team of Department of Aeronautics and Astronautics

Sep. 2019 – Jun. 2020

Mar. 2020 - Jul. 2020

Captair

- · Managed the administrative events, and planned the training courses inside the team
- · Won the runner-up in Departments Cup, NCKU