

# Deformation Theory

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# 1 Introduction

In the section, we will introduce the definitions and intuition for first order deformations.

## 1.1 Intuition

**Embedded Deformation:** Suppose we have a smooth submanifold  $X$  embedded in an ambient complex manifold  $Y$ . The embedding is equipped with a normal bundle  $N_Y X$ . By the tubular neighborhood theorem, we have an embedding of its total space:

$$\begin{array}{ccc} X & \hookrightarrow & Y \\ & \searrow \text{0-section} & \nearrow \\ & N_Y X & \end{array}$$

A smooth deformation of  $Y$  inside  $X$  is then a smooth section of  $N_Y X$ : at each point  $x \in X$ , the section gives you the normal direction along which to “infinitesimally” deform  $X$  inside  $Y$ . This definition offers some differential topological intuition, even though we no longer have an analog of the tubular neighborhood theorem in the holomorphic/algebraic setting.

More generally, we are given the data of

1. A morphism of objects  $f : X \rightarrow Y$  in some category (e.g. schemes, complex manifolds, etc).
2. An “infinitesimal thickening” of  $X$  and  $Y$ , which are prescribed injective morphisms  $X \rightarrow X'$  and  $Y \rightarrow Y'$ .

A deformation of  $f$  is then a lift of the morphism  $X \rightarrow Y$  to a morphism  $X' \rightarrow Y'$

$$\begin{array}{ccc} X & \longrightarrow & Y \\ \downarrow & & \downarrow \\ X' & \xrightarrow{\quad ? \quad} & Y' \end{array}$$

**Deformation of Complex Structure:** Viewing a complex manifold  $X$  as a real manifold with an integrable almost complex structure  $J$ , a deformation of the complex structure is a family of almost complex structures  $J_t$  parametrized by  $t \in (-\epsilon, \epsilon)$  such that  $J_0 = J$  and each  $J_t$  is integrable. Infinitesimally, we can think of this as a perturbation of the almost complex structure  $J$  by a small parameter  $t$  in the space of endomorphisms of the tangent bundle  $TX$  that satisfy  $J_t^2 = -\text{Id}$  and the integrability condition (vanishing of the Nijenhuis tensor).

The theory of Kodaira-Spencer describes how such deformations can be understood in terms of certain cohomology groups associated with the manifold. More precisely, first order deformations of the complex structure on  $X$  are classified by the cohomology group  $H^1(X, T_X)$ , where  $T_X$  is the holomorphic tangent bundle of  $X$ .

**Deformation and Moduli Problem** In relation to deformation of complex structure, suppose we have concretely constructed the moduli space  $\mathcal{M}_g$  parameterizing smooth projective curves of genus  $g$ . A point  $[C] \in \mathcal{M}_g$  corresponds to an isomorphism class of a smooth projective curve  $C$  of genus  $g$ . A deformation of the curve  $C$  can be thought of as a small perturbation of the complex structure on  $C$ , leading to a family of curves  $C_t$  parameterized by a small parameter  $t$ . Infinitesimally, this corresponds to moving along a tangent vector at the point  $[C]$  in the moduli space  $\mathcal{M}_g$ . The tangent space at  $[C]$  can be identified with the first cohomology group  $H^1(C, T_C)$ , where  $T_C$  is the holomorphic tangent bundle of the curve  $C$ .

Suppose we have a fine moduli space  $\mathcal{M}$  parameterizing certain objects, meaning any family of such objects over a base  $B$  is given by a morphism

$$B \rightarrow \mathcal{M}$$

Then an infinitesimal deformation of an object  $X$  corresponding to a point  $[X] \in \mathcal{M}$  is given by a family over the dual numbers  $\mathrm{Spec}(\mathbb{C}[\epsilon]/(\epsilon^2))$  (we can think of the dual numbers as a point equipped with a tangent vector), such that the fiber over 0 is isomorphic to  $X$ . Then, the classifying map

$$T_0 B \rightarrow T_{[X]} \mathcal{M}$$

precisely specifies a tangent vector at  $[X]$ .

## 2 First Order Deformation

**Definition 2.0.1.** The **dual numbers** over a field  $k$  is the ring

$$D := k[t]/(t^2)$$

Note that  $\text{Spec}(D)$  is the one-point space consisting of the prime ideal  $(t)$ . Its Zariski tangent space is given by

$$T_{(t)}D := \text{Hom}_k((t)/(t^2), k)$$

which is a one-dimensional  $k$ -vector space. In contrast,  $\text{Spec}(k)$  is also a one-point space, but its Zariski tangent space is zero-dimensional. Thus, we can think of  $\text{Spec}(D)$  as a point equipped with a tangent vector. The dual numbers will be our base space for first order deformations.

**Definition 2.0.2.** Let  $Y$  be a scheme over  $k$ , and  $X$  be a closed subscheme. A **first order embedded deformation** of  $X$  in  $Y$  is a closed subscheme  $X' \subset Y \times_k \text{Spec}(D)$  such that

1.  $X'$  is flat over  $D$
2. The fiber over the point is  $X$ , i.e

$$X' \times_{\text{Spec}(D)} \text{Spec}(k) = X$$

We would like to classify all such deformations. It is useful to characterize flatness over the dual numbers first:

**Lemma 2.1.** A module  $M$  over a commutative ring  $R$  is flat iff for every ideal  $I \subset R$ , the module homomorphism

$$I \otimes_R M \rightarrow M$$

is injective.

*Proof.* Follows directly from the fact that flatness is equivalent to the vanishing of  $\text{Tor}_1^R(R/I, M)$  for all ideals  $I \subset R$ .  $\square$

### 2.1 Embedded Deformation of Schemes

We first deal with the affine case. Suppose  $X = \text{Spec}(B)$  is affine, and  $Y$  is a closed subscheme defined by an ideal  $I \subset B$ . We see that first-order embedded deformations of  $Y$  in  $X$  correspond to ideals  $J \subset B' := B[t]/(t^2)$  such that

1.  $B'/J$  is flat over  $D$
2. The image of  $J$  under the quotient map

$$B[t]/(t^2) \rightarrow B$$

is  $I$ .

**Proposition 2.1.1.** There is a bijection between the set of first-order embedded deformations of  $Y$  in  $X$  and  $\text{Hom}_B(I, B/I)$ .

*Proof.* Suppose we are given an ideal  $J \subset B'$  such that the  $J \bmod t = I$ . By Lemma 2.1, flatness of  $B'/J$  over  $D$  is equivalent to the exactness of

$$0 \rightarrow B'/J \otimes_D (t) \rightarrow B'/J \rightarrow B'/J \otimes_D k \rightarrow 0$$

Viewing  $(t)$  as a  $k$ -module, we have

$$B/I \otimes_k (t) \cong (B'/J \otimes_D k) \otimes_k (t) \cong B'/J \otimes_D (t)$$

So we may rewrite the exact sequence as

$$0 \rightarrow B/I \xrightarrow{t} B'/J \rightarrow B/I \rightarrow 0$$

Since  $B' := B[t]/(t^2)$  splits as  $B \oplus tB$  as  $B$ -modules, for every  $f \in I$ , there exist lifts of the form  $f + tg \in J$ , where  $f, g \in B$ . By exactness of the sequence above, different lifts differ by an element in  $tI$ , so we may then define a function

$$\varphi : I \rightarrow B/I$$

by  $\varphi(f) = \bar{g}$ . It is easy to check this is well-defined and a  $B$ -module homomorphism. Conversely, given a  $B$ -module homomorphism  $\phi : I \rightarrow B/I$ , we may define an ideal:

$$J := \{f + tg \mid f \in I, g \in B, g \bmod I = \phi(f)\}$$

Flatness of  $B'/J$  over  $D$  can be checked by the same exact sequence as above: an element  $tb$  is in the ideal  $J$  iff  $b \in I$ . The two constructions are inverse to each other, and we have the desired bijection.  $\square$

**Definition 2.1.1.** The first order embedded deformations of  $Y$  in  $X$  is **trivial** if they correspond to the zero homomorphism in  $\text{Hom}_B(I, B/I)$ , which corresponds to the ideal  $J = I \oplus tI \subset B[t]/(t^2)$ .

**Example 2.1.1.** We are given curve  $C$  carved out by  $f(x, y)$ , embedded in  $\mathbb{A}^2$  via the canonical map

$$k[x, y] \rightarrow k[x, y]/(f)$$

By our above analysis, first order embedded deformations of  $C$  in  $\mathbb{A}^2$  correspond to elements of

$$\text{Hom}_{k[x, y]/(f)}((f), k[x, y]/(f)) \cong k[x, y]/(f)$$

In particular, each  $g \in k[x, y]/(f)$  gives rise to a first order deformation defined by the principal ideal  $J = (f + tg)$ . We can think of this as perturbing  $f$  by  $g$  infinitesimally.

Recall that for a closed embedding of schemes  $X \rightarrow Y$  defined by an ideal sheaf  $\mathcal{I} \subset \mathcal{O}_Y$ , the normal sheaf  $\mathcal{N}_{X/Y}$  is defined as the dual of the conormal sheaf  $\mathcal{I}/\mathcal{I}^2$ . Moreover,

$$\text{Hom}_Y(\mathcal{I}, \mathcal{O}_X) \cong \text{Hom}_X(\mathcal{I}/\mathcal{I}^2, \mathcal{O}_X)$$

Since flatness is a local property, and our construction above is natural and compatible with localization, we may globalize Proposition 2.1.1 to obtain:

**Theorem 2.2.** Let  $Y$  be a scheme over a field  $k$ , and let  $X$  be a closed subscheme of  $Y$ . Then the deformations of  $X$  over  $D$  in  $Y$  are in natural one-to-one correspondence with elements of  $H^0(X, \mathcal{N}_{X/Y})$ , with the zero element corresponding to the trivial deformation.

## 2.2 Deformation of Coherent Sheaves

Let  $X$  be a scheme over a field  $k$ , and  $\mathcal{F}$  be a coherent sheaf on  $X$ . A first order deformation of  $\mathcal{F}$  is a coherent sheaf  $\mathcal{F}'$  on  $X' := X \times_k \text{Spec}(D)$  that is

1. flat over  $D$ ;
2. equipped with a homomorphism  $\mathcal{F}' \rightarrow \mathcal{F}$  such that the induced map  $\mathcal{F}' \otimes_D k \rightarrow \mathcal{F}$  is an isomorphism.

**Theorem 2.3.** Let  $X$  be a scheme over a field  $k$ , and  $\mathcal{F}$  be a coherent sheaf on  $X$ . Then the set of first order deformations of  $\mathcal{F}$  is in natural one-to-one correspondence with elements of  $\text{Ext}_X^1(\mathcal{F}, \mathcal{F})$ , with the zero element corresponding to the trivial deformation.

*Proof.* By Lemma 2.1, a first order deformation  $\mathcal{F}'$  of  $\mathcal{F}$  fits into a short exact sequence of  $D$ -modules

$$0 \rightarrow \mathcal{F} \xrightarrow{t} \mathcal{F}' \rightarrow \mathcal{F} \rightarrow 0$$

$\square$

## References