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## HW 2: Time Command

**Task 1:** Implement a `time1` command that reports elapsed time

**Code:** Created `time1.c` in the user directory, and added the command to UPROGS in Makefile

**Results:** Running the `time1` command yields the elapsed time for a given command execution:

```
base ~
multipass shell robust-guppy
ubuntu@robust-guppy:~/xv6-riscv$ make qemu
qemu-system-riscv64 -machine virt -bios none -kernel kernel/kernel -m 128M -smp 3 -nographic -drive file=fs.img,if=none,format=raw,id=x0 -device virtio-blk-device,drive=x0,bus=virtio-mmio-bus.0

xv6 kernel is booting

hart 2 starting
hart 1 starting
init: starting sh
$ matmul
Time: 6 ticks
$ time1 matmul
Time: 6 ticks
elapsed time: 6 ticks
$ time1 sleep 10
elapsed time: 10 ticks
$
```

**Summary:** In Task 1, I implemented a basic `time1` command to measure elapsed time. It involved creating a new C file and adding the command to Makefile. The `time1` command successfully measures and reports elapsed time for a given task

**Difficulties:** There were no significant difficulties encountered in Task 1.

**Task 2:** Keep track of how much CPU time a process has used

**Changes:** Modified relevant parts of the kernel code to track and update CPU time in the `struct proc`.

**Summary:** In Task 2, I made changes to the kernel code to keep track of CPU time for processes. This involved modifying data structures and updating them during process execution. This task was important to accurately report CPU time for processes.

**Difficulties:** Understanding and locating the relevant parts of the kernel code for this task required careful examination. However, I was able to make the necessary changes successfully.

Task 3: Implement a `wait2()` system call that waits for a child to exit and returns the child's status and rusage:

**Changes:** Added a new system call, `wwait2()`, and modified related kernel files( `proc.c`, `syscall.c`, `syscall.h`, and `defs.h`)

**Summary:** Task 3 involved implementing a new system call, `wait2()`, to wait for a child process to exit and return its status and resource usage information. This task required changes to multiple kernel files to integrate the new system call.

**Difficulties:** The main challenge in this task was ensuring the proper integration of the new system call into the existing kernel code.

Task 4: Implement a `time` command that runs a command and reports elapsed time, CPU time, and %CPU used:

**Code:** Created `time.c` in the user directory, added the command to `Makefile`, and implemented the `time` command.

**Results:** Running the `time` command successfully reports elapsed time, CPU time, and %CPU usage for a given command

```

base ~
multipass shell robust-guppy
ubuntu@robust-guppy:~/xv6-riscv$ make qemu
qemu-system-riscv64 -machine virt -bios none -kernel kernel/kernel -m 128M -smp 3 -nographic -drive file=fs.img,if=none,format=raw,id=x0 -device virtio-blk-device,drive=x0,bus=virtio-mmio-bus.0

xv6 kernel is booting

hart 2 starting
hart 1 starting
init: starting sh
$ matmul
Time: 8 ticks
$ time matmul
Time: 8 ticks
elapsed time: 8 ticks, cpu time: 8 ticks, 100% CPU
$ time sleep 10
elapsed time: 10 ticks, cpu time: 0 ticks, 0% CPU
$ █

```

**Summary:** Task 4 involved implementing the time command, which measures and reports various time-related metrics for a specified command. This task required creating a new user-level command and ensuring it correctly calculates and displays the required metrics.

**Difficulties:** Task 4 was relatively straightforward since it built upon the knowledge gained from Task 1. However, understanding the internals of time measurement and formatting the output required careful attention to detail.

### Extra Credit Task:

**Lack of Precision:** The time command we implement in xv6 measures time in ticks, which could not be very precise for short-running processes.

**No Historical Data:** The time command implemented doesn't maintain any history, making it somewhat challenging to analyze how resource usage change