

PR-2B 418  
PART (C)

# GAUSS-MARKOV

$$\dot{x}(t) = A(t)x(t) + B(t)u(t) + w(t)$$

$$y(t) = C(t)x(t) + v(t)$$

$$\underline{X}_k = [x^T \quad v_x^T \quad y^T \quad v_y^T \quad z^T \quad v_z^T]^T$$

$$\underline{U}_k = [a_x^T \quad a_y^T \quad a_z^T]^T$$

$$\underline{Z}_k = [x^T \quad y^T \quad z^T]^T$$

$$\underline{E}_p = [E_x \quad E_y \quad E_z]^T$$

$$\underline{E}_a = [E_{ax} \quad E_{ay} \quad E_{az}]^T$$

$$R_p = \begin{bmatrix} 10^{-4} & 0 & 0 \\ 0 & 10^{-4} & 0 \\ 0 & 0 & 10^{-4} \end{bmatrix}$$

$$R_a = \begin{bmatrix} 0.025 & 0 & 0 \\ 0 & 0.025 & 0 \\ 0 & 0 & 0.025 \end{bmatrix} \quad \text{SG}$$

With,

$$A = \begin{bmatrix} 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

$$B = \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$W = \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\underline{E}_A = W \underline{E}_a$$

$$C = \begin{bmatrix} 1 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 \end{bmatrix}$$

$$V = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \quad \epsilon_p = V \epsilon_p$$

$\underbrace{\hspace{10em}}_V$

$$R_v = V R_p V^T$$

$$\& R_w = \omega R_a \omega^T$$

FOR THE RECURSIVE NAVIGATOR:

→ SEE CODE!

\* IN APPENDIX, PART C