# A Guide to Presentations in LATEX-beamer with a detour to Geometric Analysis

Eduardo Balreira



Major Seminar, Fall 2008

### Outline

- 1 Intro to LATEX
- 2 Intro to Beamer
- Geometric Analysis
- 4 A Proof

# Some Symbols

LaTeX is a mathematics typesetting program.

- Standard Language to Write Mathematics
- $(M^2,g) \leftrightarrow \$(M^2,g)\$$
- $\Delta u K(x) e^{2u} = 0 \leftrightarrow \text{Delta u -}K(x) e^{2u} = 0$
- $\bullet \inf_{n\in\mathbb{N}} \left\{ \frac{1}{n} \right\} = 0$

 $\ \int_{n\in\mathbb{N}}\left(\frac{1}{n}\right)=0$ 

# Compare displaystyle

• 
$$\sum_{n=1}^{\infty} \frac{1}{n^2} = \frac{\pi^2}{6}$$
 versus  $\sum_{n=1}^{\infty} \frac{1}{n^2} = \frac{\pi^2}{6}$ 

• 
$$\sum_{n=1}^{\int \int (n^2)=\frac{n^2}{6}}$$
  
and

$$\ \int_{n=1}^{\int \int_{n^2}=\frac{n^2}{6}}$$

### Common functions

•  $\cos x \rightarrow \$ \cos x\$$ 

•  $arctan x \rightarrow \$ arctan x \$$ 

- $f(x) = \sqrt{x^2 + 1} \rightarrow f(x) = \sqrt{x^2 + 1}$ \$
- $f(x) = \sqrt[n]{x^2 + 1} \rightarrow f(x) = \sqrt{n} \{x^2 + 1\}$

#### Theorems - code

#### Theorem (Poincaré Inequality)

If  $|\Omega| < \infty$ , then

$$\lambda_1(\Omega) = \inf_{u \neq 0} \frac{|\nabla u|_2^2}{\|u\|^2} > 0$$

is achieved.

```
\begin{thm}[Poincar\'{e} Inequality]
If $|\0mega| < \infty$, then
\[
  \lambda_1(\0mega) =
  \inf_{u\neq 0} \dfrac{|\nabla u|^2_2}{\|u\|^2} > 0
\]
is achieved.
\end{thm}
```

### Example - Arrays

```
\bullet \left\{ \begin{array}{ccc}
-\Delta u + \lambda u & = & |u|^{p-2}, & \text{in } \Omega \\
u & \geq & 0, & u \in H_0^1(\Omega)
\end{array} \right.
```

```
• $\left\{
   \begin{array}{cccc}
   -\Delta u +\lambda u &= & |u|^{p-2}, &\textrm{ in }
   \Omega \\
   u &\geq & 0, & u\in H_0^1(\Omega)
   \end{array}
\right.$
```

# Example - Arrays Change centering

```
\bullet \left\{ \begin{array}{ll} -\Delta u + \lambda u & = & |u|^{p-2}, & \text{in } \Omega \\ u & \geq & 0, & u \in H_0^1(\Omega) \end{array} \right.
```

```
• $\left\{
   \begin{array}{lcrr}
   -\Delta u +\lambda u &= & |u|^{p-2}, &\textrm{ in }
   \Omega \\
   u &\geq & 0, & u\in H_0^1(\Omega)
   \end{array}
\right.$
```

# Example - Arrays Change centering

```
\bullet \ \left\{ \begin{array}{rcl} -\Delta u + \lambda u & = & |u|^{p-2}, & \text{in } \Omega \\ u & \geq & 0, & u \in H^1_0(\Omega) \end{array} \right.
```

```
• $\left\{
   \begin{array}{rcll}
   -\Delta u +\lambda u &= & |u|^{p-2}, &\textrm{ in }
   \Omega \\
   u &\geq & 0, & u\in H_0^1(\Omega)
   \end{array}
\right.$
```

### More Examples

• 
$$\varphi(u) = \int_{\Omega} \left[ \frac{\|\nabla u\|^2}{2} + \lambda \frac{u^2}{2} - \frac{(u^+)^p}{p} \right] d\mu$$

\$\ds \varphi (u) = \int\_{\Omega} \left[
\dfrac{\|\nabla u\|^2}{2} +
\lambda\dfrac{u^2}{2} \dfrac{(u^+)^p}{p} \right] d\mu \$

### Even More Examples

De Morgan's Law

$$\bullet \left(\bigcup_{i=1}^n A_i\right)^c = \bigcap_{i=1}^n A_i^c$$

- \$\ds \left(\bigcup\_{i=1}^{n} A\_i\right)^c =
  \bigcap\_{i=1}^n A\_i^c\$
- $A \times B = \{(a, b) | a \in A, b \in B\}$
- $A\times B = \left(a,b\right) \mid A \in B$

### Equations

• Consider the equation of Energy below.

$$E(u) = \int |\nabla u|^2 dx \tag{1}$$

This is how we refer to (1).

\begin{equation}\label{eq:energy}
 E(u) = \int |\nabla u|^2 dx
 \end{equation}

This is how we refer to \eqref{eq:energy}.

### **Equations**

• Consider the equation without a number below.

$$E(u) = \int |\nabla u|^2 dx$$

\begin{equation}\label{eq:energy}
 E(u) = \int |\nabla u|^2 dx \nonumber
 \end{equation}

# Equations Tag an equation

• Consider the equation with a tag

$$E(u) = \int |\nabla u|^2 dx \tag{E}$$

If u is harmonic, (E) is preserved.

If \$u\$ is harmonic, \eqref{eq:energytag} is preserved.

# Equations in an array

Consider the expression below

$$(a+b)^2 = (a+b)(a+b)$$
  
=  $a^2 + 2ab + b^2$  (2)

#### **Environments**

In LaTeX, environments must match:

- begin{...}
  .
  .
  .
  .
  .
  .
  .
  .
  .
  .
- $\bullet$  \$ ...\$  $\rightarrow$  for math symbols
- $\bullet$  \[ ... \]  $\to$  for centering expressions
- ullet \left( \ldots \right) o match size of parentheses

# Environments delimiters

$$\bullet$$
  $(\int |\nabla u|^p d\mu)^p$  versus  $\left(\int |\nabla u|^p d\mu\right)^p$ 

- \$(\ds\int|\nabla u|^p d\mu)^p\$
- \$\left(\ds\int|\nabla u|^p d\mu\right)^p\$

### **Tables**

Consider the truth table:

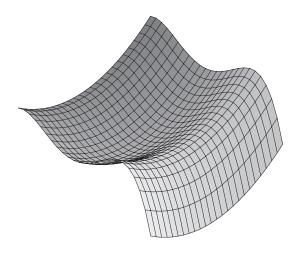
$$\begin{array}{c|cccc} P & Q & \neg P & \neg P \rightarrow (P \lor Q) \\ \hline T & T & F & T \\ T & F & F & T \\ F & T & T & F \\ F & F & T & F \\ \hline \end{array}$$

#### Tables - code

```
\begin{tabular}{c c c | c}
$P$ & $Q$ & $\neg P$ & $\neg P\to (P \vee Q)$ \\ \hline
T & T & F & T \\
T & F & F & T \\
F & T & T & T \\
F & F & T & F
\end{tabular}
```

Intro to LATEX Intro to Beamer Geometric Analysis A Proo

# Inserting Pictures Mountain Pass Landscape



```
\begin{center}
  \includegraphics{Mountain_Pass.eps}
\end{center}
```

A Proof

### Inserting Pictures

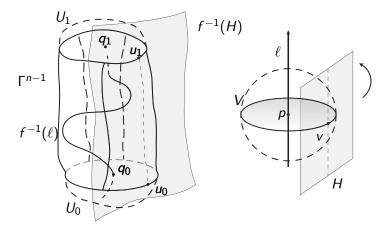


Figure: Construction of  $\Gamma^n$  by revolving affine hyperplanes

# A Final Remark on LaTeX

Preamble → "Stuff" on top of .tex file
 %For an article using AMS template:
 \documentclass[12pt]{amsart}
 \usepackage{amsmath,amssymb,amsfonts,amsthm}
 ...

- Don't worry about it!
- With practice you can figure it out.

# How a Slide is done in Beamer my subtitle

This is a slide

- First Item
- Second Item

A Proof

# How a Slide is done in Beamer my subtitle

The code should look like: \begin{frame} \frametitle{How a Slide is done in Beamer} \framesubtitle{my subtitle} % optional This is a slide \begin{itemize} \item First Item \item Second Item \end{itemize} \end{frame}

### How a Slide with pause is done in Beamer

This is a slide

- First Item
- Second Item

### How a Slide with pause is done in Beamer

The code should look like:

```
\begin{frame}
  \frametitle{How a Slide with pause is done in Beamer}
This is a slide
  \begin{itemize}
    \item First Item
    \pause
    \item Second Item
  \end{itemize}
\end{frame}
```

# Overlay example

- First item
- Second item
- Third item
- Fourth item

### Overlay example

The code should look like:

```
\begin{frame}[fragile]
  \frametitle{Overlay example}
  \begin{itemize}
    \only<1->{\item First item}
    \uncover<2->{\item Second item}
    \uncover<3->{\item Third item}
    \only<1->{\item Fourth item}
  \end{itemize}
\end{frame}
```

Need a plain slide?	
Add [plain] option to the slide.	

### Variational Calculus

A simple Idea to solve equations:

- Solve f(x) = 0
- Suppose we know that F' = f.
- Critical points of F are solutions of f(x) = 0.

#### Variational Calculus

An idea from Calculus I:

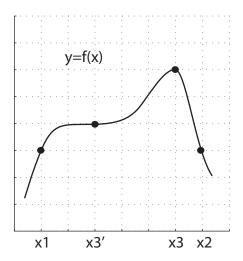
#### Theorem (Rolle)

Let  $f \in C^1([x_1, x_2]; \mathbb{R})$ . If  $f(x_1) = f(x_2)$ , then there exists  $x_3 \in (x_1, x_2)$  such that  $f'(x_3) = 0$ .

```
\begin{thm}[Rolle] \\ Let $f\in C^1([x_1,x_2];\mathbb{R})$. If $f(x_1)=f(x_2)$, then there exists $x_3\in (x_1,x_2)$ \\ such that $f'(x_3) = 0$. \\ \end{thm}
```

### Variational Calculus

Rolle's Theorem has the following landscape.

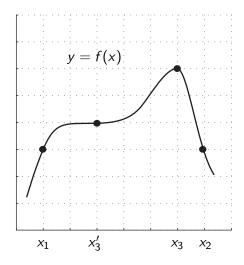


### Variational Calculus - Code

```
\begin{frame}
  \frametitle{Variational Calculus}
  \uncover<1->{
  Rolle's Theorem has the following landscape.
  \uncover<2->{\begin{center}
  \includegraphics{rolle.eps}
  \end{center}
  }
\end{frame}
```

### Variational Calculus - psfrags

Rolle's Theorem has the following landscape.



# Variational Calculus - psfrags - Code

```
\begin{frame}
  \frametitle{Variational Calculus - psfrags}
  \uncover<1->{Rolle's Theorem has the following landscape
  \uncover<2->{\begin{figure}[h]
\begin{center}
\begin{psfrags}
\psfrag{x1}{$x_1$}\psfrag{x2}{$x_2$}
\psfrag{x3}{$x_3$}\psfrag{x3'}{$x_3'$}
\proonup {\{y=f(x)\}}{\{y=f(x)\}}
\includegraphics{rolle.eps}
\end{psfrags}
\end{center}
\end{figure}
\end{frame}
```

# MPT - presentation A friendly introduction

#### Theorem (Finite Dimensional MPT, Courant)

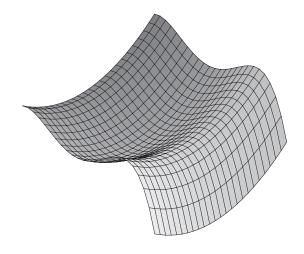
Suppose that  $\varphi \in C^1(\mathbb{R}^n, \mathbb{R})$  is coercive and possesses two distinct strict relative minima  $x_1$  and  $x_2$ . Then  $\varphi$  possesses a third critical point  $x_3$  distinct from  $x_1$  and  $x_2$ , characterized by

$$\varphi(x_3) = \inf_{\Sigma \in \Gamma} \max_{x \in \Sigma} \varphi(x)$$

where

 $\Gamma = \{\Sigma \subset \mathbb{R}^n; \Sigma \text{ is compact and connected and } x_1, x_2 \in \Sigma\}.$  Moreover,  $x_3$  is not a relative minimizer, that it, in every neighborhood of  $x_3$  there exists a point x such that  $\varphi(x) < \varphi(x_3)$ .

# Mountain Pass Landscape



### An Application of MPT

### Theorem (Hadamard)

Let X and Y be finite dimensional Euclidean spaces, and let  $\varphi: X \to Y$  be a  $C^1$  function such that:

- (i)  $\varphi'(x)$  is invertible for all  $x \in X$ .
- (ii)  $\|\varphi(x)\| \to \infty$  as  $\|x\| \to \infty$ .

Then  $\varphi$  is a diffeomorphism of X onto Y.

- Check that  $\varphi$  is onto.
- Prove injectivity by contradiction.
- Suppose  $\varphi(x_1) = \varphi(x_2) = y$ , then define

$$f(x) = \frac{1}{2} \left\| \varphi(x) - y \right\|^2$$

- Check the MPT geometry for f.
- $\exists x_3, \ f(x_3) > 0 \ (i.e., \|\varphi(x_3) y\| > 0.)$
- $f'(x_3) = \nabla^T \varphi(x_3) \cdot (\varphi(x_3) y) = 0$