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<https://github.com/davizjc/Embedded-System-Lab-Hw3.git>

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Homework 3 Serial Port and Audio Synthesis Report

1. SPI protocol

- a. Connect the pin like lab 7_1_SPI , for this homework pin d9 will be our digital out. Pin 9 - 12 will be connected to the SPI slave pin. I decided to use a for loop for each mode starting from mode 0 until mode 2. Firstly I initialize the value to be zero, so if mode equals zero, value is zero. If mode equal 1 then 1, mode equal 2, then value is 2. The master will send the mode 1 time and send the value 2 times. Then it will read the response from the slave. Cs will be set to zero and 1 to deselect and select the device.

```
Start.
mode = 0
Default reply to master: 0x00
Read from master: v = 0
recieve value = 0
Start.
mode = 1
Read from master: v = 0
recieve value = 1
Start.
mode = 2
Read from master: v = 0
recieve value = 2
█
```

2. I2C protocol

- a. Kinda the same as SPI but for I2C there were only Connect pins D15 to A5 and D14 to A4. There will only be two wires SDA and SCL. I use D14 and D15 for i2c_slave, A4 and A5 for mas(i2c_master). For each round each mode will be sent. For this one, the master will first send the mode. Then the Slave Read Addressed will send back a value and the mode, then the master will write the initial mode and value. The master has requested a read from this slave, so now depend on the mode the value will be the same , add one , or add two. In the end the master will read the mode. I did three rounds for three modes.

```
round 1 mode 0
mode send = 0
Slave Read Addressed: mode=0, value=1
master thread write: mode=0, value=1
Slave Write: mode=0, value=1
master thread read: mode=0, value=1
round 2 mode 1
mode send = 1
Slave Read Addressed: mode=1, value=1
master thread write: mode=1, value=1
Slave Write: mode=1, value=2
master thread read: mode=1, value=2
round 3 mode 2
mode send = 2
Slave Read Addressed: mode=2, value=1
master thread write: mode=2, value=1
Slave Write: mode=2, value=3
master thread read: mode=2, value=3
█
```

3. UART

- a. Connect pins D0 to D10 and D1 to D9. For our global variable we will use static BufferedSerial device1(D10, D9) and static BufferedSerial device2(D1, D0); .Basically two device, device 1 for master and device 2 for the slave. For this one i just put 6 number in a array (mode , value ,mode1 , value , mode2, value) kinda the same as the previous one and from the master I write to the slave. The slave will then read the mode and value that was send and write back. In the main set desired properties (9600-8-N-1) for each device.

```
start
Slave Read: mode=0, value=0
Slave Write: mode=0, value=0
Slave Read: mode=1, value=0
Slave Write: mode=1, value=1
Slave Read: mode=2, value=0
Slave Write: mode=2, value=2
```

4. capture and average 10 samples of accelerometer and gyro

- a. Inside the gyro and accelerometer from 8_4_Acc_Gyro instead of using 200 samples just change it to 10.

```
Average ACC= -0.018055, -0.073170, 0.966411
Average ACC= 0.043712, -0.093125, 1.034830
Average ACC= -0.052264, -0.277475, 0.899893
Average ACC= -0.026607, -0.306933, 0.988267
Average ACC= 0.003801, -0.311684, 0.916048
Average ACC= 0.002851, -0.280326, 0.894192
Average ACC= -0.006652, -0.251818, 0.937903
Average ACC= -0.001901, -0.240415, 0.944555
```

5. Please modify the MBED program in 3.2 (for keyboards and interrupt) in MBED lab 8 such that we can use the previously calculated pitch, roll and yaw from averaged samples to determine the length of a playing note. The length of a note will only be in 1/8, 1/4, 1/2, and 1 second.

- a. Set up the MBED board and circuit board like lab 8_2_Synthesizer, and connect it to the speaker. Remember to add the library from lab 8_4_Acc_Gyro so accelerometer.h and gyro will be able to be used. In this homework we generate pitch,roll and yaw. When the MBED board moves it will change these three numbers. I wrote that when pitch >10 or roll > 10 then the index pitch will increase.And since we only have 4 note lengths if(index_pitch>3) index_pitch=3, else index_pitch--. To make the three buttons play different notes I use a not really efficient way. The noteLength will be changed for each button but the note play will be the same. For example when keyboard0.fall(queue.event(startRecord)); inside record function “ idNote[indexNote]=queue_note.call(playNote, song3[index_pitch], noteLength[index_pitch] “ will be called and inside song3 i have G_4 sound play.

```
Average ACC= 0.019955, -0.058916, 0.973063
Init accelerometer and Gyro
0.487790/-0.487665/0.001817
Play 392 for 0.125000
-26.056656/23.797554/0.006521
Play 392 for 0.250000
-66.510276/40.577291/0.010690
Play 392 for 0.250000
nan/43.419330/0.013149
Play 392 for 0.250000
nan/44.959036/0.016356
Play 392 for 0.250000
-0.379602/0.379663/0.018815
Play 293 for 0.125000
-56.275157/36.892573/0.019991
Play 293 for 0.250000
nan/44.466985/0.018922
Play 293 for 0.250000
nan/44.282437/0.021915
Play 293 for 0.500000
-10.188652/10.063421/0.016784
Play 261 for 0.250000
-57.845203/37.519519/0.018494
Play 261 for 0.500000
nan/43.387657/0.019456
Play 261 for 1.000000
nan/43.488172/0.017318
Play 261 for 1.000000
█
```

Keyboard 2 was pressed, the note G will be play and as I tilted the length of each note play will be longer from $\frac{1}{8}$ until 1. When I press keyboard 1 it is the same but for D, and keyboard 0 for C.