

PRINCIPLES OF CIRCUIT SIMULATION

Lecture 8.

Nonlinear Device Stamping

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Outline

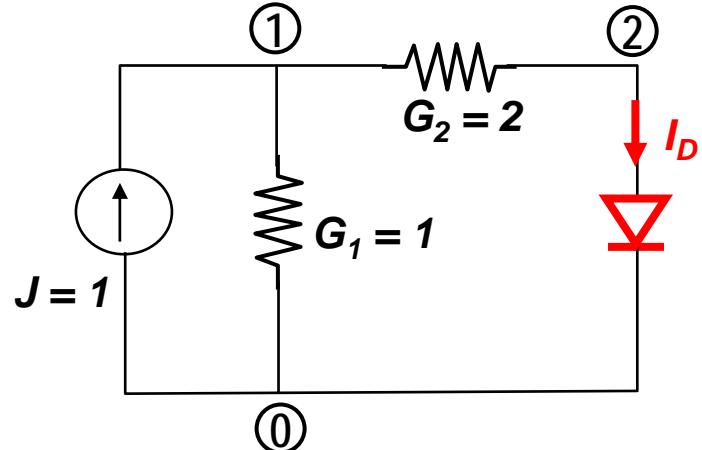
- Solving a nonlinear circuit
- Linearization and **Newton-Raphson**
- Jacobian
- **Stamping nonlinear elements**
 - Diode stamp
 - Nonlinear resistor stamp
 - MOS stamp
- Nonlinear transient simulation

A Nonlinear Circuit

The diode equation is **nonlinear**:

$$i_D = I_{sat} \left(e^{40V_D} - 1 \right)$$

assuming $I_{sat} = 1 \text{ A}$.



Write KCL equations at nodes
1 and 2:

$$\left\{ G_1 v_1 + G_2 (v_1 - v_2) = 1 \right. \quad (1)$$

$$\left. 2(v_2 - v_1) + (e^{40v_2} - 1) = 0 \right. \quad (2)$$

This part is nonlinear!

Solve the nodal voltages.

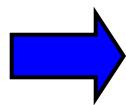
Solve by root-finding

$$\left\{ \begin{array}{l} G_1 v_1 + G_2 (v_1 - v_2) = 1 \\ 2(v_2 - v_1) + (e^{40v_2} - 1) = 0 \end{array} \right. \Rightarrow 3v_1 - 2v_2 = 1 \quad (1)$$

$$2(v_2 - v_1) + (e^{40v_2} - 1) = 0 \quad (2)$$

From eqn (1): $v_1 = \frac{1}{3} + \frac{2}{3}v_2$

Substitute it into eqn (2): $2(v_2 - v_1) + (e^{40v_2} - 1) = 0$



$$f(v_2) := \frac{2}{3}v_2 - \frac{5}{3} + e^{40v_2} = 0$$

We get one nonlinear equation.

Need to find a root for the nonlinear equation: $f(v_2) = 0$

Nonlinear Root Finder

- A general method for solving nonlinear $f(x) = 0$ is by **iteration**.
- The **iteration** is derived from “**linearization**.”

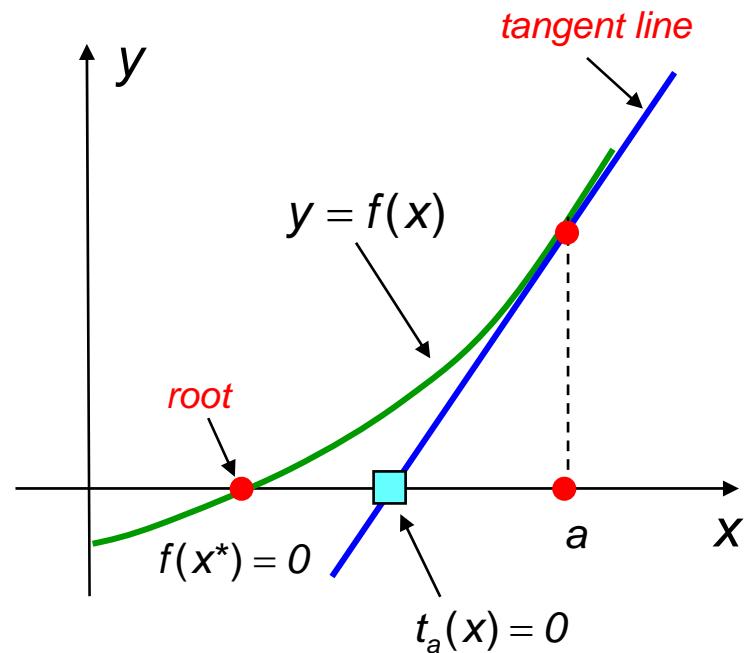
Taylor expand $f(x)$ at a point $x = a$:

$$f(x) = f(a) + f'(a)(x - a) + \dots$$

Ignoring the high-order terms,

$$y = t_a(x) = f(a) + f'(a)(x - a)$$

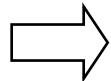
is a tangent line at $(a, f(a))$.



Nonlinear Root Finder

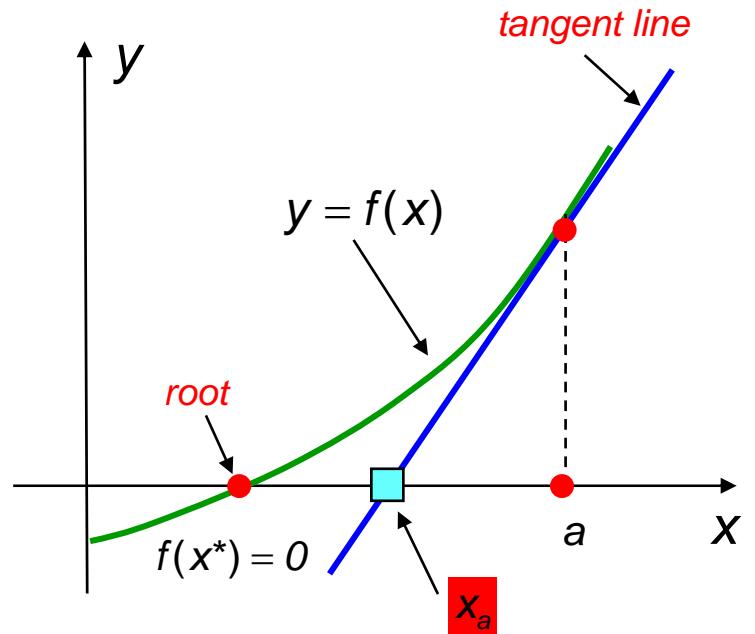
Find the point where the tangent line crosses the x-axis:

$$t_a(x) = f(a) + f'(a)(x - a) = 0$$



$$x_a = a - [f'(a)]^{-1} f(a)$$

Repeat this process.

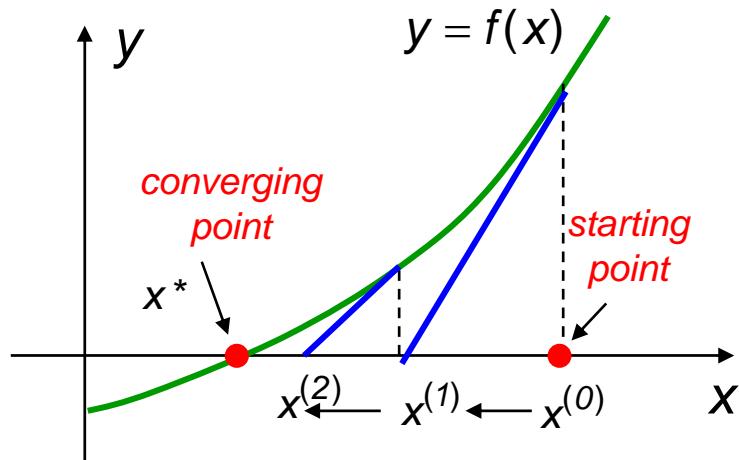


The Newton-Raphson Algorithm

For a scalar nonlinear equation $f(x) = 0$, the following iteration can find a root:

$$x^{(k+1)} = x^{(k)} - [f'(x^{(k)})]^{-1} f(x^{(k)})$$

The initial point $x^{(0)}$ is arbitrary.



We shall discuss the
convergence problem
later.

Go back to our example ...

We would like to solve : $f(v_2) = \frac{2}{3}v_2 - \frac{5}{3} + e^{40v_2} = 0$

by the iteration

$$v_2^{(k+1)} = v_2^{(k)} - [f'(v_2^{(k)})]^{-1} f(v_2^{(k)})$$

The derivative is: $f'(v_2) = \frac{2}{3} + 40e^{40v_2}$

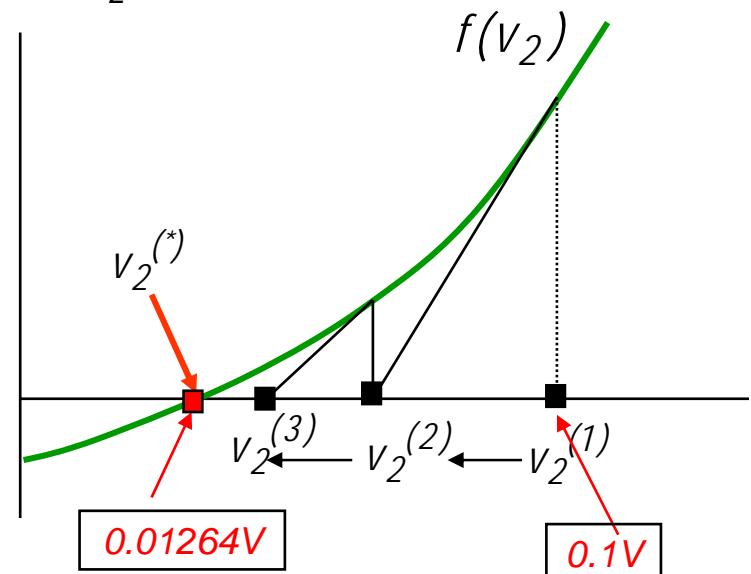
Choose $v_2^{(0)} = 0.1 V$

we get the following iterations:

$$v_2^{(1)} = 0.07574, \dots, v_2^{(4)} = 0.01883, \dots$$

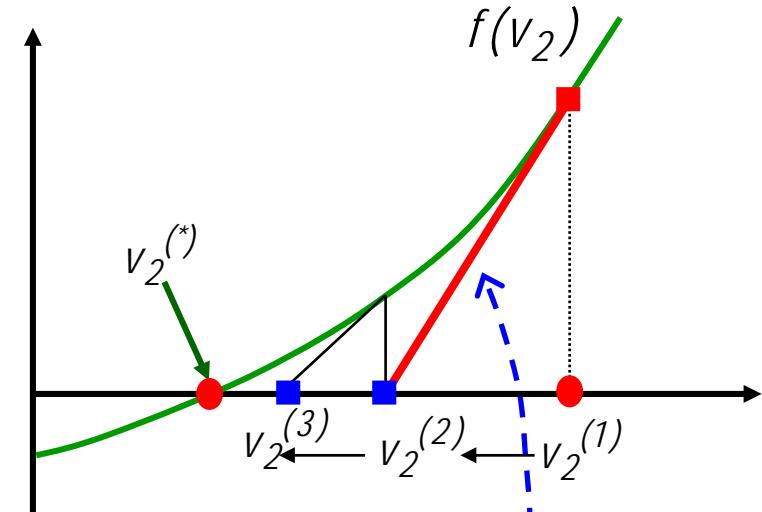
$$v_2^{(7)} \approx v_2^{(8)} = 0.012644, \dots$$

(converging ...)



Newton-Raphson Iteration (recap)

1. Choose an initial voltage;
2. Follow the tangent line to get the zero-crossing point;
3. Repeat the process.



Formal Algorithm:

Linearization→

$v_2^{(2)}$ satisfies

$$0 = f(v_2^{(1)}) + f'(v_2^{(1)})(v_2^{(2)} - v_2^{(1)})'$$

N.R. Iteration: →

$$v_2^{(2)} = v_2^{(1)} - [f'(v_2^{(1)})]^{-1} f(v_2^{(1)})$$

Multiple Nonlinear Equations

- How to solve n variables from n equations, with at least one nonlinear;
- i.e., how to solve $f(x) = 0$ where both f and x are vectors?

We have a system of nonlinear multivariate equations:

$$f_j(x_1, \dots, x_n) = 0;$$

$$j = 1, \dots, n$$

Use multivariate Taylor expansion for each $f_j(x)$:

$$f_j(x_1, \dots, x_n) = f_j(a_1, \dots, a_n) + \left(\frac{\partial f_j(a)}{\partial x_1}, \dots, \frac{\partial f_j(a)}{\partial x_n} \right) \begin{pmatrix} x_1 - a_1 \\ \vdots \\ x_n - a_n \end{pmatrix} + \dots$$



linearized part

Linearization

Putting n Taylor expansions together:

$$f_1(x_1, \dots, x_n) = f_1(a_1, \dots, a_n) + \left(\frac{\partial f_1(a)}{\partial x_1}, \dots, \frac{\partial f_1(a)}{\partial x_n} \right) \begin{pmatrix} x_1 - a_1 \\ \vdots \\ x_n - a_n \end{pmatrix} + \dots$$

•
•
•

$$f_j(x_1, \dots, x_n) = f_j(a_1, \dots, a_n) + \left(\frac{\partial f_j(a)}{\partial x_1}, \dots, \frac{\partial f_j(a)}{\partial x_n} \right) \begin{pmatrix} x_1 - a_1 \\ \vdots \\ x_n - a_n \end{pmatrix} + \dots$$

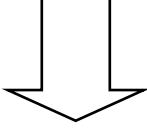
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$$f_n(x_1, \dots, x_n) = f_n(a_1, \dots, a_n) + \left(\frac{\partial f_n(a)}{\partial x_1}, \dots, \frac{\partial f_n(a)}{\partial x_n} \right) \begin{pmatrix} x_1 - a_1 \\ \vdots \\ x_n - a_n \end{pmatrix} + \dots$$

Linearization in Matrix-Vector Form

$$\begin{pmatrix} f_1(\mathbf{x}) \\ \vdots \\ f_n(\mathbf{x}) \end{pmatrix} = \begin{pmatrix} f_1(\mathbf{a}) \\ \vdots \\ f_n(\mathbf{a}) \end{pmatrix} + \underbrace{\begin{pmatrix} \frac{\partial f_1(\mathbf{a})}{\partial x_1} & \dots & \frac{\partial f_1(\mathbf{a})}{\partial x_n} \\ \vdots & \ddots & \vdots \\ \frac{\partial f_n(\mathbf{a})}{\partial x_1} & \dots & \frac{\partial f_n(\mathbf{a})}{\partial x_n} \end{pmatrix}}_{\text{Jacobian Matrix}} \begin{pmatrix} x_1 - a_1 \\ \vdots \\ x_n - a_n \end{pmatrix} + \dots$$

$\mathbf{x} = (x_1, \dots, x_n)^T$
 $\mathbf{a} = (a_1, \dots, a_n)^T$
are vectors.

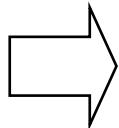


In compact form:

$$f(\mathbf{x}) = f(\mathbf{a}) + \frac{\partial f(\mathbf{a})}{\partial \mathbf{x}} (\mathbf{x} - \mathbf{a}) + \dots$$

Jacobian Matrix

$$y = f(x)$$

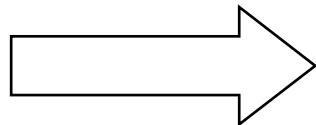


$$\frac{\partial \mathbf{f}(\mathbf{a})}{\partial \mathbf{x}} = \left(\frac{\partial f_i(\mathbf{a})}{\partial x_j} \right)_{n \times n}$$

$$\begin{pmatrix} \frac{\partial f_1(\mathbf{a})}{\partial x_1} & \dots & \frac{\partial f_1(\mathbf{a})}{\partial x_n} \\ \vdots & \ddots & \vdots \\ \frac{\partial f_n(\mathbf{a})}{\partial x_1} & \dots & \frac{\partial f_n(\mathbf{a})}{\partial x_n} \end{pmatrix}$$

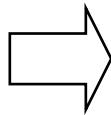
*Linearized equation
at $x = a$*

$$f(x) = 0$$



$$f(a) + \left[\frac{\partial \mathbf{f}(\mathbf{a})}{\partial \mathbf{x}} \right] (\mathbf{x} - a) = 0$$

Let $A = \frac{\partial \mathbf{f}(\mathbf{a})}{\partial \mathbf{x}}$; $\mathbf{b} = -f(\mathbf{a})$



$$A(\mathbf{x} - a) = \mathbf{b}$$

Solve $(x-a)$.

Multivariable Newton-Raphson

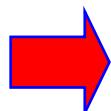
Given

$$f(x_1, \dots, x_n) = \begin{pmatrix} f_1(x_1, \dots, x_n) \\ \vdots \\ f_n(x_1, \dots, x_n) \end{pmatrix}$$

Denote the "Jacobian matrix"

$$J(x) = \frac{\partial f(x)}{\partial x} = \left(\frac{\partial f_i(x)}{\partial x_j} \right)_{n \times n} = \begin{pmatrix} \frac{\partial f_1}{\partial x_1} & \dots & \frac{\partial f_1}{\partial x_n} \\ \vdots & \ddots & \vdots \\ \frac{\partial f_n}{\partial x_1} & \dots & \frac{\partial f_n}{\partial x_n} \end{pmatrix}$$

$$f(x^{(k)}) + \left[\frac{\partial f(x^{(k)})}{\partial x} \right] (x^{(k)} - a) = 0$$



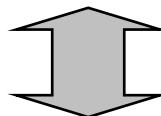
$$x^{(k+1)} = x^{(k)} - [J(v^{(k)})]^{-1} f(x^{(k)})$$

NR Iteration

Summary

- Nonlinear equations $f(\mathbf{x}) = \mathbf{0}$ are solved by *linearization*.
- Once again, we are solving $\mathbf{Ax} = \mathbf{b}$.
- But have solve $\mathbf{Ax} = \mathbf{b}$ for many times until convergence.

$$\mathbf{x}^{(k+1)} = \mathbf{x}^{(k)} - \left[J(\mathbf{v}^{(k)}) \right]^{-1} f(\mathbf{x}^{(k)})$$



$$\left[J(\mathbf{x}^{(k)}) \right] \left(\mathbf{x}^{(k+1)} - \mathbf{x}^{(k)} \right) = -f(\mathbf{x}^{(k)})$$

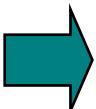
Simulator Perspective

- In a simulator implementation, we **do NOT formulate nonlinear equations then solve.**
- Rather, we do nonlinear element stamping following the principle of “Newton-Raphson Iteration”.
- In transient simulation, we’ll have two loops:
 - The outer loop is for **time advancing**;
 - The inner loop is for **NR iteration**.

Nonlinear Element Stamping

- Nonlinear devices are stamped by the principle of “linearization”.
- Recall the Newton-Raphson iteration:

$$\begin{bmatrix} J(v^{(k)}) \end{bmatrix} \left(\begin{array}{c} x^{(k+1)} - x^{(k)} \\ \end{array} \right) = -f(x^{(k)})$$

 $\underbrace{\begin{bmatrix} J(v^{(k)}) \end{bmatrix}}_{\mathbf{A}} x^{(k+1)} = \underbrace{\begin{bmatrix} J(v^{(k)}) \end{bmatrix} x^{(k)} - f(x^{(k)})}_{\mathbf{RHS}}$

In Spice simulator, matrix A and RHS are filled up dynamically via element-by-element stamping (both linear and nonlinear).

Back to our example again ...

We'll work it out again by stamping.

Idea: Linearize the diode equation
at the previously solved voltage:

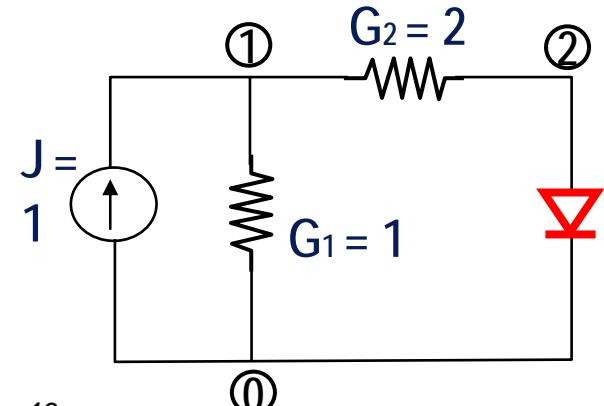
$$i_D = e^{40V_D} - 1 \quad \rightarrow \quad \frac{\partial i_D}{\partial V_D} = 40e^{40V_D}$$

$$i_D^{(k+1)} \approx i_D^{(k)} + \left(\frac{\partial i_D}{\partial V_D} \right)^{(k)} \left(V_D - V_D^{(k)} \right)$$

(linearization point)

$$= \underbrace{\left(\frac{\partial i_D}{\partial V_D} \right)^{(k)}}_{\text{equiv G}} V_D + \underbrace{\left[i_D^{(k)} - \left(\frac{\partial i_D}{\partial V_D} \right)^{(k)} V_D^{(k)} \right]}_{\text{equiv current}}$$

Linearized
current equation



Companion Network

$$i^{(k+1)} = i^{(k)} + \frac{\partial g(v^{(k)})}{\partial v} (v^{(k+1)} - v^{(k)})$$

$$= \boxed{G_0^{(k)}} v^{(k+1)} + \boxed{I_0^{(k)}}$$

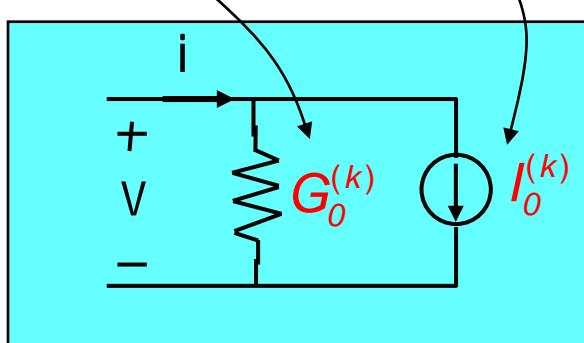
I-V relation: $i = g(v)$

where

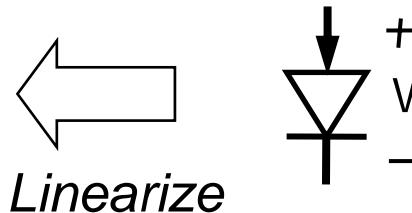
$$\boxed{G_0^{(k)}} = \frac{\partial g(v^{(k)})}{\partial v},$$

$$\boxed{I_0^{(k)}} = \boxed{i^{(k)} - G_0^{(k)} v^{(k)}}$$

This term is zero
for linear devices, .



Companion network
(linearized)



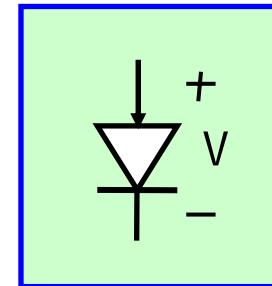
$$i^{(k)} = g(v^{(k)})$$

**G_0 and I_0 are updated
during iteration !**

Stamp for Diode

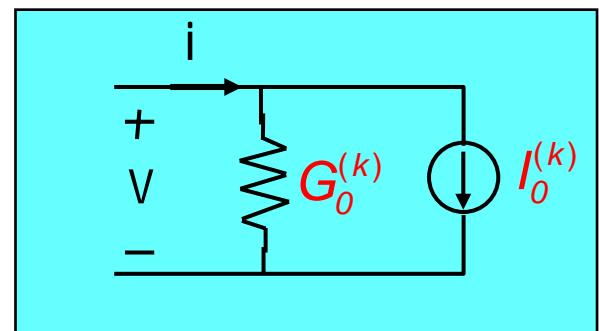
The companion network is used for stamping.

$$i^{(n+1)} = G_0^{(n)} v^{(n+1)} + I_0^{(n)}$$



The diode stamp:

	N+	N-	RHS
N+	$G_0^{(n)}$	$-G_0^{(n)}$	$-I_0^{(n)}$
N-	$-G_0^{(n)}$	$G_0^{(n)}$	$+I_0^{(n)}$



$$G_0^{(n)} = \frac{\partial g(v^{(n)})}{\partial v}, \quad I_0^{(n)} = i^{(n)} - G_0^{(n)} v^{(n)}$$

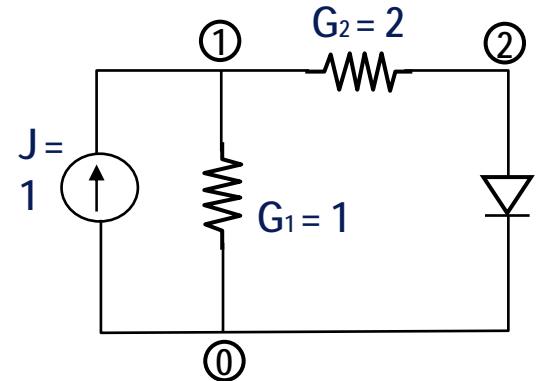
Diode Stamping - Look Closer

Solving nonlinear circuit by stamping

$$i_D^{(n+1)} = i_D^{(n)} + \frac{\partial i_D}{\partial u_2} (u_2^{(n+1)} - u_2^{(n)})$$

$$= [40e^{(40u_2^{(n)})}] u_2^{(n+1)}$$

$$- [40e^{(40u_2^{(n)})} u_2^{(n)} - (e^{(40u_2^{(n)})} - 1)]$$



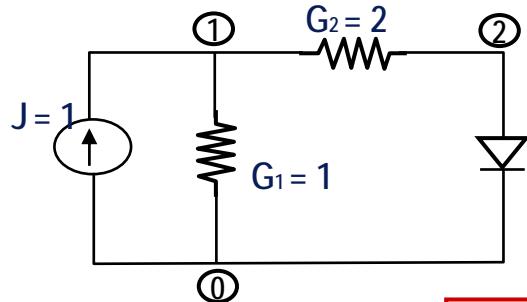
$$i_D = e^{40V_D} - 1$$

Matrix stamping:

$$\begin{bmatrix} 1+2 & -2 \\ -2 & 2+40e^{40u_2^{(n)}} \end{bmatrix} \begin{bmatrix} u_1^{(n+1)} \\ u_2^{(n+1)} \end{bmatrix} = \begin{bmatrix} 1 \\ 40e^{40u_2^{(n)}} u_2^{(n)} - (e^{40u_2^{(n)}} - 1) \end{bmatrix}$$

The diode “load” function does these updates at each iteration.

A closer look at Diode Stamping



Stamp for G_1 and Diode

$$\begin{bmatrix} 1 \\ 40e^{(40u_2^{(n)})} \end{bmatrix}$$

RHS

$$\left(\begin{array}{c} J \\ 40e^{40u_2^{(n)}} u_2^{(n)} - (e^{40u_2^{(n)}} - 1) \end{array} \right)$$

Stamp for G_2

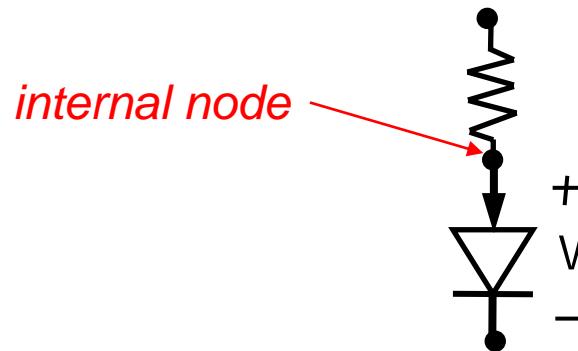
$$\begin{bmatrix} 2 & -2 \\ -2 & 2 \end{bmatrix}$$

putting
together

$$\begin{bmatrix} 1+2 & -2 \\ -2 & 2+40e^{(40u_2^{(n)})} \end{bmatrix}$$

Resistive Diode

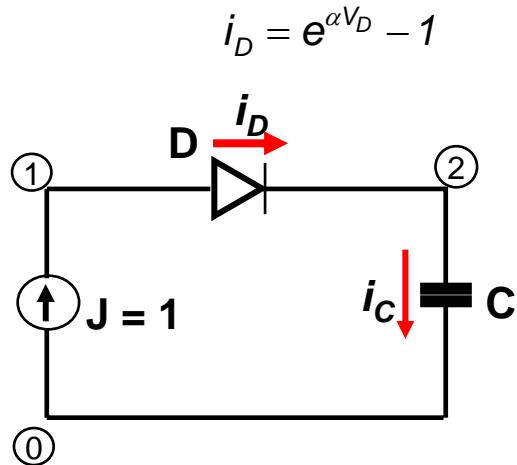
Exercise: Write down the stamp for this resistive diode.



Spice has such a diode model.

Nonlinear Transient Simulation

- How to do a transient simulation of a circuit with nonlinear elements?



Backward Euler + Newton-Raphson

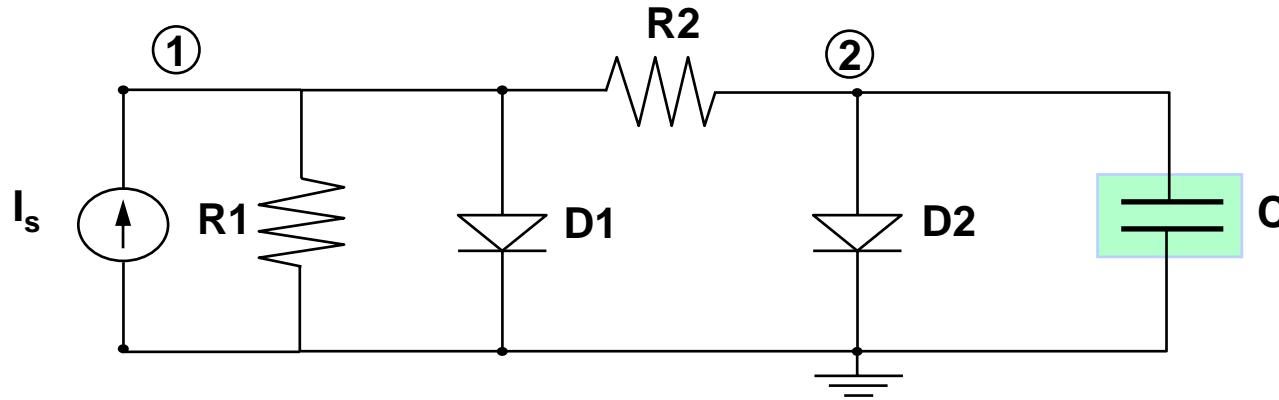
	0	1	2	RHS
0	$\frac{C}{h}$	0	$-\frac{C}{h}$	$-\frac{C}{h}v_c(t-h)$
1	0	$\alpha e^{\alpha v_D^{(n)}}$	$-\alpha e^{\alpha v_D^{(n)}}$	$J - I_D^{(n)}$
2	$-\frac{C}{h}$	$-\alpha e^{\alpha v_D^{(n)}}$	$\left(\alpha e^{\alpha v_D^{(n)}} + \frac{C}{h}\right)$	$\frac{C}{h}v_c(t-h) + I_D^{(n)}$

$$v_D^{(n)} = v_2^{(n)} - v_1^{(n)}$$

$$I_D^{(n)} = \alpha e^{\alpha v_D^{(n)}} v_D^{(n)} - (e^{\alpha v_D^{(n)}} - 1)$$

At time $t = t_k$, do NR-iteration until convergence, then advance time to $t = t_{k+1}$.

Simulate this circuit



Assume an appropriate model for the two diodes.

Nonlinear Resistor

$$V^{(n+1)} = r(i^{(n+1)}) \approx r(i^{(n)}) + \dot{r}(i^{(n)})(i^{(n+1)} - i^{(n)})$$

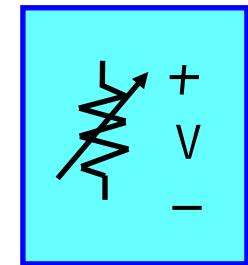
$$V^{(n+1)} = \dot{r}(i^{(n)})i^{(n+1)} + V_0^{(n)}$$

$$V = r(i)$$

$$V_0^{(n)} = \left[r(i^{(n)}) - \dot{r}(i^{(n)})i^{(n)} \right]$$

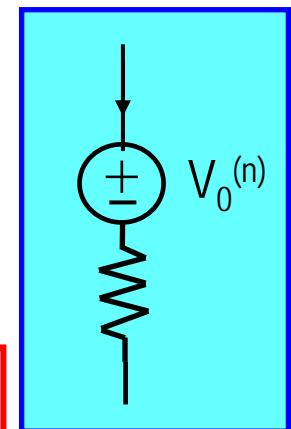
MNA stamp:

	N+	N-	i	RHS
N+			+1	
N-			-1	
	+1	-1	$-\dot{r}(i^{(n)})$	$V_0^{(n)}$



current
controlled
nonlinear
resistor

$$R^{(n)} = r'(i^{(n)})$$



MOSFET Model

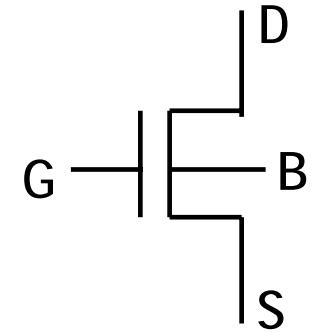
Level 1 Spice model (resistive region)

$$V_{gs} > V_t$$

$$V_{ds} < V_{gs} - V_t$$

$$I_{ds} = I_{ds}(V_{gs}, V_{ds})$$

$$= \left(\frac{W}{L} \right) K' \left[(V_{gs} - V_t)V_{ds} - \frac{1}{2} V_{ds}^2 \right]$$



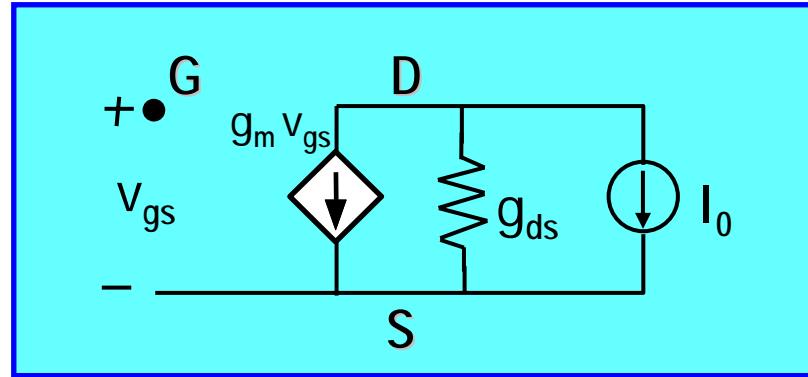
Assume V_t is independent of V_{bs}

Choose source (S) as the reference node.

$$\begin{cases} g_m = \frac{\partial I_{ds}}{\partial V_{gs}} = \frac{W}{L} K' V_{ds} \\ g_{ds} = \frac{\partial I_{ds}}{\partial V_{ds}} = \frac{W}{L} K' (V_{gs} - V_t - V_{ds}) \end{cases}$$

MOSFET Linearization

$$I_{ds} = I_{ds}(V_{gs}, V_{ds})$$



Linearization

$$I_{ds}^{(n+1)} = I_{ds}\left(V_{gs}^{(n+1)}, V_{ds}^{(n+1)}\right)$$

← (Bi-variate function)

$$= I_{ds}\left(V_{gs}^{(n)}, V_{ds}^{(n)}\right) + g_m^{(n)}\left(V_{gs}^{(n+1)} - V_{gs}^{(n)}\right) + g_{ds}^{(n)}\left(V_{ds}^{(n+1)} - V_{ds}^{(n)}\right)$$

$$= \boxed{g_m^{(n)}V_{gs}^{(n+1)}} + \boxed{g_{ds}^{(n)}V_{ds}^{(n+1)}} + \boxed{I_0^{(n)}}$$

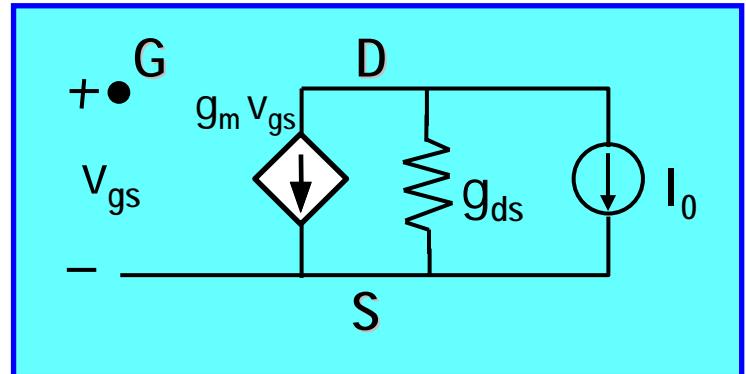
(two partial derivatives)

$$\boxed{I_0^{(n)}} \triangleq I_{ds}\left(V_{gs}^{(n)}, V_{ds}^{(n)}\right) - g_m^{(n)}V_{gs}^{(n)} - g_{ds}^{(n)}V_{ds}^{(n)}$$

MOSFET Stamp

$$I_{ds} = I_{ds}(V_{gs}, V_{ds})$$

$$I_{ds}^{(n+1)} = g_m^{(n)} V_{gs}^{(n+1)} + g_{ds}^{(n)} V_{ds}^{(n+1)} + I_0^{(n)}$$



	\mathbf{N}^d	\mathbf{N}^s	\mathbf{N}^g	RHS
\mathbf{N}^d	$g_{ds}^{(n)}$	$-g_{ds}^{(n)} - g_m^{(n)}$	$g_m^{(n)}$	$-I_0^{(n)}$
\mathbf{N}^s	$-g_{ds}^{(n)}$	$g_{ds}^{(n)} + g_m^{(n)}$	$-g_m^{(n)}$	$I_0^{(n)}$

$$g_m^{(n)} = \frac{\partial I_{ds} \left(V_{gs}^{(n)}, V_{ds}^{(n)} \right)}{\partial V_{gs}}$$

$$g_{ds}^{(n)} = \frac{\partial I_{ds} \left(V_{gs}^{(n)}, V_{ds}^{(n)} \right)}{\partial V_{ds}}$$

(entries depend on the iteration step)

Acknowledgement

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 - Prof. Albert Sangiovanni-Vincentelli's lecture at University of California, Berkeley (instructor Alessandra Nardi)