RRtoolbox Documentation

Release 1

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RRtoolbox package

1.1 Subpackages

1.1.1 RRtoolbox.lib package

Subpackages

RRtoolbox.lib.arrayops package

Submodules

RRtoolbox.lib.arrayops.basic module This module contains simple array operation methods

```
RRtoolbox.lib.arrayops.basic.angle (v1, v2, deg=False) Angle between two N dimmensional vectors.
```

Parameters

- **v1** vector 1.
- **v2** vector 2.
- deg if True angle is in Degrees, else radians.

Returns angle in radians.

Example:

```
>>> angle_between((1, 0, 0), (0, 1, 0))
1.5707963267948966
>>> angle_between((1, 0, 0), (1, 0, 0))
0.0
>>> angle_between((1, 0, 0), (-1, 0, 0))
3.141592653589793
```

Note: obtained from http://stackoverflow.com/a/13849249/5288758 and tested in http://onlinemschool.com/math/assistance/vector/angl/

RRtoolbox.lib.arrayops.basic.angle2D (v1, v2, deg=False, absolute=None)
Angle between two 2 dimensional vectors.

Parameters

- **v1** vector 1.
- **v2** vector 2.
- deg if True angle is in Degrees, else radians.
- absolute if None returns the angle (0 yo 180(pi)) between v1 and v2. if True returns the absolute angle (0 to 360(2pi)) from v1 as axis to v2. if False returns the angle (0 to 180 or 0 to -180) from v1 as axis to v2, where v2 angle relative to v1 is positive or negative if counter-clock or clock wise.

Returns angle in radians.

Note: implemented according to http://math.stackexchange.com/a/747992 and tested in http://onlinemschool.com/math/assistance/vector/angl/

 $\verb|RRtoolbox.lib.arrayops.basic.angleXY| (coorX, coorY, angle)|\\$

Rotate coordinate.

Parameters

- coorX x coordinate.
- coory y coordinate.
- angle radian angle.

Returns rotated x,y

RRtoolbox.lib.arrayops.basic.anorm(a)
 norm in array.

Parameters a -

Returns

RRtoolbox.lib.arrayops.basic.anorm2 (a)

Summation of squares (helper function for anorm ())

Parameters a -

Returns

RRtoolbox.lib.arrayops.basic.axesIntercept(coorSM, maxS, maxM)

Intercept static axis (S) and mobile axis (M) with a coordinate connecting both axes from minS to minM.



Parameters

- coorSM coordinate of vector from S=0 to M=0.
- maxS value representing end of estatic axis.
- maxM value representing end of mobile axis.

Returns S1,S2,M1,M2.

RRtoolbox.lib.arrayops.basic.boxPads(bx, points)
Get box pads to fit all.

Parameters

- **bx** box coordinates or previous boxPads [left_top, right_bottom]
- points array of points

Returns [(left,top),(right,bottom)] where bx and points fit.

RRtoolbox.lib.arrayops.basic.centerM(coor, maxM)
Center vector coor in M axis.

Parameters

- coor coordinate of vector from S=0 to M center
- maxM value representing end of mobile axis

Returns M centered coordinate

RRtoolbox.lib.arrayops.basic.centerS(coor, maxS)
Center vector coor in S axis.

Parameters

- coor coordinate of vector from S center to M=0
- maxS value representing end of estatic axis

Returns S centered coordinate

RRtoolbox.lib.arrayops.basic.centerSM(coorSM, maxS, maxM)
Center vector coorSM in both S and M axes.

Parameters

- coorSM coordinate of vector from S to M centers.
- maxS value representing end of estatic axis.
- maxM value representing end of mobile axis.

Returns SM centered coordinate.

RRtoolbox.lib.arrayops.basic.contours2mask(contours, shape=None, astype=<type 'bool'>)

Creates an array with filled polygons formed by contours.

Parameters

- contours list of contour or points forming objects
- **shape** (None) shape of array. If None it creates an array fitted to contours.
- astype ("bool") numpy type

Returns

RRtoolbox.lib.arrayops.basic.contoursArea (contours)
Accumulates areas from list of contours.

Parameters contours – list of contours or binary array.

Returns area.

RRtoolbox.lib.arrayops.basic.convertXY(x, y, backshape, foreshape, flag=0, quartile=0, angle=None)

Convert absolute XY 0,0 coordinates to new system WZ.

Parameters

- $\mathbf{x} \mathbf{x}$ coordinate.
- y y coordinate.
- backshape shape of background image.

:param foreshape:shape of foreground image. :param flag: flag for position (default=0).

- •flag==0: foreground to left up.
- •flag==1: foreground to left down.
- •flag==2 : foreground to right up.
- •flag==3: foreground to right down.
- •flag==4: foreground at center of background.
- •flag==5: XY 0,0 is at center of background.
- •flag==6: XY 0,0 is at center of foreground.
- •flag==7: XY 0,0 is at right down of foreground.

Parameters

- quartile place Mobile image at quartile 1,2,3,4. if left quartile=0 image won't be moved.
- angle angle in radians (defalut=None). if None it does not apply.

Returns W,Z

```
RRtoolbox.lib.arrayops.basic.convexityRatio(cnt, hull=None)
```

Ratio to test if contours are irregular

Parameters cnt - contour

:param hull:(None) convex hull :return: ratio

```
RRtoolbox.lib.arrayops.basic.entroyTest (arr)
```

Entropy test of intensity arrays. (Helper function for entropy ())

Parameters arr – array MxN of dim 2.

Returns entropy.

```
RRtoolbox.lib.arrayops.basic.find_near(m, thresh=None, side=None)
```

helper function for findminima and findmaxima :param m: minima or maxima points :param thresh: guess or seed point :param side: left or right :return: value

RRtoolbox.lib.arrayops.basic.findmaxima(hist, thresh=None, side=None)

Get nearest peak value to a thresh point from a histogram.

Parameters

- hist histogram
- thresh initial seed
- side find valley from left or right of thresh

Returns

RRtoolbox.lib.arrayops.basic.**findminima** (*hist*, *thresh=None*, *side=None*) Get nearest valley value to a thresh point from a histogram.

Parameters

- hist histogram
- thresh initial seed
- side find valley from left or right of thresh

Returns

RRtoolbox.lib.arrayops.basic.getOtsuThresh(hist)

From histogram calculate Otsu threshold value.

Parameters hist - histogram

Returns otsu threshold value

RRtoolbox.lib.arrayops.basic.getTransformedCorners (shape, H) from shape gets transformed corners of array.

Parameters

- **shape** H,W array shape
- **H** transformation matrix

Returns upper_left, upper_right, lower_right, lower_lef transformed corners.

RRtoolbox.lib.arrayops.basic.getTransparency(array)

Convert foreground to background.

Parameters array – image array.

Returns alfa (int or array)

RRtoolbox.lib.arrayops.basic.get_x_space (funcs, step=10, xleft=-300, xright=300)

get X axis space by brute force. This can be used to find the x points where the points in the y axis of any number of functions become stable.

Parameters

- funcs list of functions
- step-

10. step to close guess to maximum

- xleft maximum left limit
- xright maximum right limit

Returns linspace

RRtoolbox.lib.arrayops.basic.getdataVH(array, ypad=0, xpad=0, bgrcolor=None, alfa=None)

Get data from array according to padding (Helper function for padVH()).

Parameters

- array list of arrays to get data
- ypad how much to pad in y axis
- xpad how much to pad in x axis

Returns matrix_shapes, grid_div, row_grid, row_gridpad, globalgrid

RRtoolbox.lib.arrayops.basic.histogram(img)
Get image histogram.

Parameters img – gray or image with any bands

Returns histogram of every band

RRtoolbox.lib.arrayops.basic.im2imFormat(src, dst)

Tries to convert source image to destine image format.

Parameters

- **src** source image.
- **dst** destine image.

Returns reshaped source image.

RRtoolbox.lib.arrayops.basic.im2shapeFormat(im, shape)

Tries to convert image to intuited format from shape.

Parameters

- **im** image.
- **shape** shape to get format.

shapes: * (None, None): converts to gray * (None, None, 2): converts to GR555 * (None, None, 3): converts to BGR * (None, None, 4): converts to BGRA

Returns reshaped image.

RRtoolbox.lib.arrayops.basic.instability_bf (funcs, step=10, maximum=300, guess=0, tolerance=0.01)

Find the instability of function approaching value by brute force,

Parameters

- funcs list of functions
- step -

10. step to close guess to maximum

• maximum -

300. maximum value, if guess surpass this value then calculations are stopped.

- quess -
- 0. initial guess
- **tolerance** -(0.01) tolerance with last step to check instability.

Returns (state, updated guess). state is True if successful, else False.

RRtoolbox.lib.arrayops.basic.invertM(coorSM, maxM)
Invert M axis.

Parameters

- coorSM coordinate of vector for M inverted axes.
- maxS value representing end of estatic axis.
- maxM value representing end of mobile axis.

Returns SM coordinate on S axis and inverted M axis.

RRtoolbox.lib.arrayops.basic.invertSM(coorSM, maxS, maxM)
Invert S and M axes.

Parameters

- coorSM coordinate of vector for SM inverted axes.
- maxS value representing end of estatic axis.
- maxM value representing end of mobile axis.

Returns SM coordinate on inverted SM axes.

```
RRtoolbox.lib.arrayops.basic.isnumpy (arr)
```

Test whether an object is a numpy array. :param arr: :return: True if numpy array, else false.

RRtoolbox.lib.arrayops.basic.makeVis(globalgrid, bgrcolor=None)

Make visualization (Helper function for padVH())

Parameters

- globalgrid shape
- bgrcolor color of visualization

Returns array of shape globalgrid

RRtoolbox.lib.arrayops.basic.matrixIntercept(x, y, staticm, *mobilem)

Intercepts planes x and y of a static matrix (staticm) with N mobile matrices (mobilem) translated from the origin to x,y coordinates.

Parameters

- $\mathbf{x} \mathbf{x}$ coordinate.
- y y coordinate.
- staticm static matrix.
- mobilem mobile matrices.

Returns ROI of intercepted matrices [staticm,*mobilem].

RRtoolbox.lib.arrayops.basic.multiple_superpose (base, fore, H, foremask=None)
Superpose multiple foreground images to a single base image.

Parameters

- base backgraound, base or dipest level image (level -1)
- fore foreground image list (in order of level i = 0, ..., N)
- H transformation matrix of fore in level i to overlay in base
- foremask foreground alfa mask in level i

Returns generator of each overlay

```
RRtoolbox.lib.arrayops.basic.noisy(arr, mode)
Add noise to arrays
```

Parameters

- arr Input ndarray data (it will be converted to float).
- mode noise method:
 - 'gauss' Gaussian-distributed additive noise.

- 'poisson' Poisson-distributed noise generated from the data.
- 's&p' Replaces random pixels with 0 or 1.
- 'speckle' Multiplicative noise using out = arr + n*arr,where n is uniform noise with specified mean & variance.

:return noisy arr

RRtoolbox.lib.arrayops.basic.normalize (arr)
Normalize array to ensure range [0,1]

RRtoolbox.lib.arrayops.basic.normalize2 (arr)

Normalize with factor of absolute maximum value.

RRtoolbox.lib.arrayops.basic.normalizeCustom(arr, by=<function amax>, axis=None)
Normalize array with custom operations.

Parameters

- arr array (it does not correct negative values, use preferable NxM).
- by np,max, np.sum or any function that gets an array to obtain factor.
- axis if None it normalizes in all axes else in the selected axis.

Returns normalized to with factor.

RRtoolbox.lib.arrayops.basic.overlay(back, fore, alpha=None, alfainverted=False, under=False, flag=0)

Try to Overlay any dimension array.

Parameters

- back BGRA background image.
- fore BGRA foreground image.
- alpha transparency channel.
- alfainverted if True inverts alpha transparency.
- **under** if True, place back as fore and fore as back.
- flag (experimental)
- 0. Normally replace inverted transparency of alpha in back (N); superpose alpha in back (V).
- 1. Bloat and replace inverted transparency of alpha in back; superpose bgr in back (V).
- 2. Superpose inverted transparent COLOR of alpha in back.
- 3. Superpose inverted transparent COLOR of alpha in back.
- 4. **Superpose transparent of alpha in back**; superpose transparent COLOR of alpha in back.
- 5. **Superpose transparent of alpha in back**; superpose transparent COLOR of alpha in back.

Returns overlayed array

See also:

```
overlay2()
```

RRtoolbox.lib.arrayops.basic.overlay2(back, fore)

Overlay foreground to x,y coordinates in background image.

Parameters

- back background image (numpy array dim 3).
- **fore** foreground image (numpy array dim 4). the fourth dimension is used for transparency.

Returns back (with overlay).

#Example:

```
import cv2
import numpy as np
import time
a= time.time()
back = cv2.imread("t1.jpg")
temp = back.shape
bgr = np.zeros((temp[0],temp[1],4), np.uint8)
points = [(86, 162), (1219, 1112), (2219, 2112), (1277,3000),(86, 162)]
col_in = (0, 0, 0, 255)
thickness = 10
for i in range(len(points)-1):
    pt1 = (points[i][0], points[i][1])
    pt2 = (points[i+1][0], points[i+1][1])
    cv2.line(bgr, pt1, pt2, col_in, thickness)
overlay (back, bgr)
win = "overlay"
cv2.namedWindow(win,cv2.WINDOW_NORMAL)
cv2.imshow(win, back)
print time.time()-a
cv2.waitKey()
cv2.destroyAllWindows()
```

See also:

```
overlay()
```

RRtoolbox.lib.arrayops.basic.overlayXY (x, y, back, fore, alfa=None, alfainverted=False, under=False, flag=0)

Overlay foreground image to x,y coordinates in background image. This function support images of different sizes with formats: BGR background and BGRA foreground of Opency or numpy images.

Parameters

- **x** x position in background.
- y y position in background.
- back background image (numpy array dim 3).
- **fore** foreground image (numpy array dim 4). the fourth dimension is used for transparency.

Returns back (with overlay)

Example:

```
import cv2
back = cv2.imread("t1.jpg")
bgr = cv2.imread("mustache.png",-1)
x,y=convertXY(0,0,back.shape,bgr.shape,flag=1)
overlayXY(x,y,back,bgr)
```

```
win = "overlay"
cv2.namedWindow(win,cv2.WINDOW_NORMAL)
cv2.imshow(win, back)
cv2.waitKey()
cv2.destroyAllWindows()
```

RRtoolbox.lib.arrayops.basic.**overlaypng** (back, fore, alpha=None, alfainverted=False, under=False, flag=0)

Overlay only BGRA.

Parameters

- back BGRA background image.
- fore BGRA foreground image.
- alpha transparency channel.
- alfainverted if True inverts alpha transparency.
- under if True, place back as fore and fore as back.
- flag (experimental)
- 0. Normally replace inverted transparency of alpha in back (N); superpose alpha in back (V).
- 1. Bloat and replace inverted transparency of alpha in back; superpose bgr in back (V).
- 2. Superpose inverted transparent COLOR of alpha in back.
- 3. Superpose inverted transparent COLOR of alpha in back.
- Superpose transparent of alpha in back; superpose transparent COLOR of alpha in back.
- Superpose transparent of alpha in back; superpose transparent COLOR of alpha in back.

Returns overlayed array

See also:

```
overlay(), overlay2()
```

RRtoolbox.lib.arrayops.basic.padVH(imgs, ypad=0, xpad=0, bgrcolor=None, alfa=None)
Pad Vertically and Horizontally image or group of images into an array.

Parameters

- **imgs** image to pad or list of horizontal images (i.e. piled up horizontally as [V1,...,VN] where each can be a list of vertical piling VN = [H1,...,HM]. It can be successive like horizontals, verticals, horizontals, etc.
- ypad padding in axis y
- xpad padding in axis x
- bgrcolor color of spaces
- alfa transparency of imgs over background of bgrcolor color.

Returns visualization of paded and piled images in imgs.

```
RRtoolbox.lib.arrayops.basic.pad_to_fit_H (shape1, shape2, H) get boxPads to fit transformed shape1 in shape2.
```

Parameters

- shape1 shape of array 1
- **shape2** shape of array 2
- H transformation matrix to use in shape1

Returns [(left,top),(right,bottom)]

RRtoolbox.lib.arrayops.basic.points2mask (pts, shape=None, astype=<type 'bool'>) Creates an array with the filled polygon formed by points.

Parameters

- pts points.
- **shape** (None) shape of array. If None it creates an array fitted to points.
- astype ("bool") numpy type

Returns array.

Example:

```
pts = random_points([(-100, 100), (-100, 100)])
img = points2mask(pts)
plotim("filled",img).show()
```

```
RRtoolbox.lib.arrayops.basic.points_generator(shape=(10, 10), nopoints=None, convex=False, erratic=False, complete=False)
```

generate points.

Parameters

- shape enclosed frame
- nopoints number of points
- convex if True make points convex, else points follow a circular pattern.

Returns

```
RRtoolbox.lib.arrayops.basic.polygonArea (pts)
Area of points calculating polygon Area.
```

Parameters pts - points.

Returns area value.

..note::

- If polygon is incomplete (last is not first point) it completes the array.
- If the polygon crosses over itself the algorithm will fail.
- Based on http://www.mathopenref.com/coordpolygonarea.html

RRtoolbox.lib.arrayops.basic.polygonArea_calcule (pts)
Area of points calculating polygon Area.

Parameters pts - points.

Returns area value.

..note::

- If polygon is incomplete (last is not first point) it completes the array.
- If the polygon crosses over itself the algorithm will fail.
- Based on http://www.mathopenref.com/coordpolygonarea.html

RRtoolbox.lib.arrayops.basic.polygonArea_contour(pts)
Area of points using contours.

Parameters pts – points.

Returns area value.

..note:: if polygon is incomplete (last is not first point) it completes the array.

RRtoolbox.lib.arrayops.basic.polygonArea_fill (pts)
Area of points using filled polygon and pixel count.

Parameters pts - points.

Returns area value.

..note:: if polygon is incomplete (last is not first point) it completes the array.

RRtoolbox.lib.arrayops.basic.process_as_blocks (arr, func, block_shape=(3, 3), mask=None, asWindows=False) process with function over an array using blocks (using re-striding).

Parameters

- arr array to process
- func function to feed blocks
- block_shape (3,3) shape of blocks
- mask (None) mask to process arr
- **asWindows** (False) if True all blocks overlap each other to give a result for each position of arr, if False the results are given in blocks equivalent for each processed blocks of arr (faster).

Returns processed array.

RRtoolbox.lib.arrayops.basic.quadrant(coorX, coorY, maxX, maxY, quadrant=0)
Moves a point to a quadrant

Parameters

- coorX point in x coordinate
- coory point in y coordinate
- maxX max value in x axis
- maxY max value in y axis
- quadrant Cartesian quadrant, if 0 or False it leaves coorX and coorY unprocessed.

Returns

RRtoolbox.lib.arrayops.basic.random_points(axes_range=((-50, 50),), nopoints=4, complete=False)

Get random points.

Parameters

- axes_range [x_points_range, y_points_range] where points_range is (min,max) range in axis.
- nopoints number of points.
- complete last point is the first point (adds an additional point i.e. nopoints+1).

Returns numpy array.

RRtoolbox.lib.arrayops.basic.recursiveMap (function, sequence)

Iterate recursively over a structure using a function.

Parameters

- function function to apply
- sequence iterator

Returns

```
RRtoolbox.lib.arrayops.basic.relativeQuadrants(points)
```

Get quadrants of relative vectors obtained from points. :param points: array of points. :return: quadrants.

RRtoolbox.lib.arrayops.basic.relativeVectors (pts, all=True) Form vectors from points.

Parameters

- pts array of points [p0, ..., (x,y)].
- all (True) if True adds last vector from last and first point.

Returns array of vectors [V0, ..., (V[n] = x[n+1]-x[n],y[n+1]-y[n])].

RRtoolbox.lib.arrayops.basic.rescale(arr, max=1, min=0)
Rescales array values to range [min,max].

Parameters

- arr array.
- max maximum value in range.
- min minimum value in range.

Returns rescaled array.

RRtoolbox.lib.arrayops.basic.**separePointsByAxis** (pts, ptaxis=(1, 0), origin=(0, 0)) Separate scattered points with respect to axis (splitting line).

Parameters

- pts points to separate.
- ptaxis point to form axis from origin
- origin origin

Returns left, right points from axis.

RRtoolbox.lib.arrayops.basic.**splitPoints**(*pts*, *aslist=None*) from points get x,y columns

Parameters

- pts array of points
- aslist True to return lists instead of arrays

Returns x, y columns

RRtoolbox.lib.arrayops.basic.**standarizePoints**(pts, aslist=False)

converts points to a standard form :param pts: list or array of points :param aslist: True to return list instead of array :return: standard points

RRtoolbox.lib.arrayops.basic.superpose (back, fore, H, foreMask=None, grow=True)
Superpose foreground image to background image.

Parameters

- back background image
- fore foreground image
- H transformation matrix of fore to overlay in back
- **foreMask** (None) foreground alpha mask, None or function. foreMask values are from 1 for solid to 0 for transparency. If a function is provided the new back,fore parameters are provided to produce the foreMask. If None is provided as foreMask then it is equivalent to a foreMask with all values to 1 where fore is True.
- **grow** If True, im can be bigger than back and is calculated according to how fore is superposed in back; if False im is of the same shape as back.

Returns im, H_back, H_fore

RRtoolbox.lib.arrayops.basic.transformPoint (p, H)

Transform individual x,y point with Transformation Matrix.

Parameters

- $\mathbf{p} x,y$ point
- **H** transformation matrix

Returns transformed x,y point

RRtoolbox.lib.arrayops.basic.transformPoints(p, H)

Transform x,y points in array with Transformation Matrix.

Parameters

- p array of points
- **H** transformation matrix

Returns transformed array of x,y point

```
RRtoolbox.lib.arrayops.basic.unit_vector(vector)
```

Returns the unit vector of the vector.

RRtoolbox.lib.arrayops.basic.vectorsAngles (pts, ptaxis=(1, 0), origin=(0, 0), dtype=None, deg=False, absolute=None)

Angle of formed vectors in Cartesian plane with respect to formed axis vector.

i.e. angle between vector "Vn" (formed by point "Pn" and the "origin")

```
and vector "Vaxis" formed by "ptaxis" and the "origin". where pts-origin = (P0-origin ... Pn-origin) = V0 ... Vn
```

Parameters

- pts points to form vectors from origin
- ptaxis point to form axis from origin

- origin origin
- **dtype** return array of type supported by numpy.
- deg if True angle is in Degrees, else radians.
- absolute if None returns angles (0 yo 180(pi)) between pts-origin (V0 .. Vn) and Vaxis. if True returns any Vn absolute angle (0 to 360(2pi)) from Vaxis as axis to Vn. if False returns any Vn angle (0 to 180 or 0 to -180) from Vaxis as axis to Vn, where any Vn angle is positive or negative if counter-clock or clock wise from Vaxis.

Returns

RRtoolbox.lib.arrayops.basic.vectorsQuadrants(vecs)
Get quadrants of vectors.

Parameters vecs – array of vectors.

Returns quadrants.

RRtoolbox.lib.arrayops.basic.vertexesAngles (pts, dtype=None, deg=False)
Relative angle of vectors formed by vertexes (where vectors cross).

i.e. angle between vectors "v01" formed by points "p0-p1" and "v12" formed by points "p1-p2" where "p1" is seen as a vertex (where vectors cross).

Parameters

- pts points seen as vertexes (vectors are recreated from point to point).
- **dtype** return array of type supported by numpy.
- deg if True angle is in Degrees, else radians.

Returns angles.

RRtoolbox.lib.arrayops.basic.view_as_blocks(arr_in, block_shape=(3,3))

Provide a 2D block_shape view to 2D array. No error checking made. Therefore meaningful (as implemented) only for blocks strictly compatible with the shape of arr_in.

Parameters

- arr_in-
- block_shape -

Returns

RRtoolbox.lib.arrayops.basic.view as windows(arr in, window shape, step=1)

Provide a 2D block_shape rolling view to 2D array. No error checking made. Therefore meaningful (as implemented) only for blocks strictly compatible with the shape of arr_in.

Parameters

- arr_in-
- window_shape -
- step -

Returns

RRtoolbox.lib.arrayops.convert module This module unlike common and basic array operations classifies just the from-to-conversions methods

```
class RRtoolbox.lib.arrayops.convert.SimKeyPoint(*args)
```

Simulates opency keypoint (it allows manipulation, conversion and serialization of keypoints).

Note: Used for conversions and data persistence.

RRtoolbox.lib.arrayops.convert.apply2kp_pairs(kp_pairs, kp1_rel, kp2_rel, func=None)
Apply to kp_pairs.

Parameters

- **kp_pairs** list of (kp1,kp2) pairs
- **kp1_rel** x,y relation or function to apply to kp1
- **kp2_rel** x,y relation or function to apply to kp2
- func function to build new copy of keypoint

Returns transformed kp_pairs

```
RRtoolbox.lib.arrayops.convert.cnt2pts(contours)
```

Convert contours to points. (cnt2pts)

Parameters contours – array of contours (cnt) ([[x,y]] only for openCV)

Returns

Example:

```
contours = np.array([[[0, 0]], [[1, 0]]]) # contours
points = contour2points(contours)
print points # np.array([[0, 0], [1, 0]])
```

RRtoolbox.lib.arrayops.convert.contour2points(contours)

Convert contours to points. (cnt2pts)

Parameters contours – array of contours (cnt) ([[x,y]] only for openCV)

Returns

Example:

```
contours = np.array([[[0, 0]], [[1, 0]]]) # contours
points = contour2points(contours)
print points # np.array([[0, 0], [1, 0]])
```

RRtoolbox.lib.arrayops.convert.conv3H4H(M)

Convert a 3D transformation matrix (TM) to 4D TM.

Parameters M – Matrix

Returns 4D Matrix

```
RRtoolbox.lib.arrayops.convert.dict2keyPoint(d, func=<built-in function KeyPoint>)
KeyPoint([x, y, _size[, _angle[, _response[, _octave[, _class_id]]]]]) -> <KeyPoint object>
```

RRtoolbox.lib.arrayops.convert.getSOpointRelation(source_shape, destine_shape, as-Matrix=False)

Return parameters to change scaled point to original point.

destine_domain = relation*source_domain

Parameters

- source_shape image shape for source domain
- destine_shape image shape for destine domain
- asMatrix if true returns a Transformation Matrix H

Returns x, y coordinate relations or H if asMatrix is True

Note: Used to get relations to convert scaled points to original points of an Image.

```
RRtoolbox.lib.arrayops.convert.invertH(H)
Invert Transformation Matrix.
```

Parameters H –

Returns

```
RRtoolbox.lib.arrayops.convert.keyPoint2tuple(keypoint)
```

obj.angle, obj.class_id, obj.octave, obj.pt, obj.response, obj.size

```
{\tt RRtoolbox.lib.arrayops.convert.} \textbf{points2contour} \ (\textit{points})
```

Convert points to contours. (pts2cnt)

Parameters points – array of points ([x,y] for openCV, [y,x] for numpy)

Returns

Example:

```
points = np.array([[0, 0], [1, 0]]) # points
contours = points2contour(points)
print contours # np.array([[[0, 0]], [[1, 0]]])
```

RRtoolbox.lib.arrayops.convert.points2vectos (pts, origin=None)
Convert points to vectors with respect to origin.

Parameters

- pts array of points.
- origin point of origin.

Returns vectors.

```
RRtoolbox.lib.arrayops.convert.pts2cnt(points)
```

Convert points to contours. (pts2cnt)

Parameters points – array of points ([x,y] for openCV, [y,x] for numpy)

Returns

Example:

```
points = np.array([[0, 0], [1, 0]]) # points
contours = points2contour(points)
print contours # np.array([[[0, 0]], [[1, 0]]])
```

```
RRtoolbox.lib.arrayops.convert.sh2oh (sH, osrc_sh, sscr_sh, odst_sh, sdst_sh) Convert scaled transformation matrix (sH) to original (oH).
```

Parameters

- **sH** scaled transformation matrix
- osrc_sh original source's shape
- sscr_sh scaled source's shape
- odst_sh original destine's shape
- sdst sh scaled destine's shape

Returns

```
RRtoolbox.lib.arrayops.convert.spairs2opairs(kp_pairs, osrc_sh, sscr_sh, odst_sh, sdst_sh, func=None)
```

Convert scaled kp_pairs to original kp_pairs.

Parameters

- **kp_pairs** list of **kp_pairs**
- osrc_sh original source's shape
- sscr_sh scaled source's shape
- odst_sh original destine's shape
- **sdst sh** scaled destine's shape
- func function to build new copy of keypoint

Returns

RRtoolbox.lib.arrayops.convert.**spoint2opointfunc**(*source_shape*, *destine_shape*)
Return function with parameters to change scaled point to original point.

Parameters

- source_shape -
- destine_shape shape of

Returns

Example:

```
forefunc = scaled2realfunc(imgf.shape,bgr.shape)
backfunc = scaled2realfunc(imgb.shape,back.shape)
plfore = np.array([forefunc(i) for i in p1])
p2back = np.array([backfunc(i) for i in p2])
```

```
RRtoolbox.lib.arrayops.convert.toTupple(obj)
```

Converts recursively to tuple

Parameters obj – numpy array, list structure, iterators, etc.

Returns tuple representation obj.

```
RRtoolbox.lib.arrayops.convert.translateQuadrants (quadrants, quadrantmap={(0, 1): 'up', (-1, 1): 'left-up', (0, 0): 'ori-gin', (-1, 0): 'left', (-1, -1): 'left-down', (0, -1): 'down', (1, 0): 'right', (1, -1): 'right-down', (1, 1): 'right-up'})
```

Convert quadrants into human readable data.

Parameters

• quadrants – array of quadrants.

• quadrantmap – dictionary map to translate quadrants. it is of the form:

```
{(0,0):"origin",(1,0):"right",(1,1):"top-right",(0,1):"top",(-1,1):"top-left",
```

(-1,0):"left",(-1,-1):"bottom-left",(0,-1):"bottom",(1,-1):"bottom-right"}

Returns list of translated quadrants.

```
RRtoolbox.lib.arrayops.convert.tuple2keyPoint(points, func=<built-in function Key-
Point>)

KeyPoint([x, y, _size[, _angle[, _response[, _octave[, _class_id]]]]]) -> <KeyPoint object>
```

 ${\tt RRtoolbox.lib.arrayops.convert.} \textbf{vectos2points} \ (\textit{vecs}, \textit{origin=None})$

Convert points to vectors with respect to origin.

Parameters

- **vecs** array of vectors.
- origin point of origin.

Returns points.

RRtoolbox.lib.arrayops.filters module This module contains custom 1D adn 2D-array filters and pre-processing (as in filtering phase) methods

Bases: object

create instance to calculate bilateral parameters from image shape.

d -> inf then:

- · computation is slower
- filtering is better to eliminate noise
- images look more cartoon-like

Parameters

- **d** distance
- sigmaColor sigma in color
- sigmaSpace sigma in space

d = <RRtoolbox.lib.arrayops.filters.bilateraP object>

filters

list of filters

sigmaColor = <RRtoolbox.lib.arrayops.filters.bilateraP object>

sigmaSpace = <RRtoolbox.lib.arrayops.filters.bilateraP object>

base filter to create custom filters

alpha

beta1

beta2 class RRtoolbox.lib.arrayops.filters.bandpass(alpha, beta1, beta2) Bases: RRtoolbox.lib.arrayops.filters.FilterBase bandpass filter class RRtoolbox.lib.arrayops.filters.bandstop(alpha, beta1, beta2) Bases: RRtoolbox.lib.arrayops.filters.FilterBase bandstop filter class RRtoolbox.lib.arrayops.filters.bilateraP(scale, shift=33, name=None, alpha=100, beta1 = -400, beta2 = 200)Bases: RRtoolbox.lib.arrayops.filters.bandstop bilateral parameter RRtoolbox.lib.arrayops.filters.bilateralFilter(im, d, sigmaColor, sigmaSpace) Apply bilateral Filter. **Parameters** • im -• d-• sigmaColor -• sigmaSpace -Returns filtered image RRtoolbox.lib.arrayops.filters.filterFactory(alpha, beta1, beta2=None) Make filter. **Parameters** • alpha – steepness of filter • beta1 - first shift from origin • **beta2** – second shift from origin: alpha must be != 0 if beta2 = None: if alpha > 0: high-pass filter, if alpha < 0: low-pass filter else: **if beta2 > beta1:** if alpha > 0: band-pass filter, if alpha < 0: band-stop filter

Returns filter funtion with intup levels

Example:

```
alpha,beta1,beta2 = 10,20,100
myfilter = filter(alpha,beta1,beta2)
print myfilter,type(myfilter)
print myfilter.alpha,myfilter.beta1,myfilter.beta2
```

else: if alpha > 0: inverted-band-pass filter, if alpha < 0: inverted-band-stop filter

RRtoolbox.lib.arrayops.filters.getBilateralParameters (shape, mode=None) Calculate from shape bilateral parameters.

Parameters

- **shape** image shape
- mode -

Returns

class RRtoolbox.lib.arrayops.filters.highpass (alpha, betal)

Bases: RRtoolbox.lib.arrayops.filters.FilterBase

highpass filter

class RRtoolbox.lib.arrayops.filters.invertedbandpass(alpha, beta1, beta2)

Bases: RRtoolbox.lib.arrayops.filters.bandpass

inverted bandpass filter

class RRtoolbox.lib.arrayops.filters.invertedbandstop(alpha, beta1, beta2)

Bases: RRtoolbox.lib.arrayops.filters.bandstop

inverted bandstop filter

class RRtoolbox.lib.arrayops.filters.lowpass(alpha, betal)

Bases: RRtoolbox.lib.arrayops.filters.FilterBase

lowpass filter

RRtoolbox.lib.arrayops.filters.**normsigmoid**(*x*, *alpha*, *beta*)

Apply normalized sigmoid filter.

Parameters

- **x** data to apply filter
- alpha if alpha > 0: pass high filter, if alpha < 0: pass low filter, alpha must be != 0
- beta shift from origin

Returns filtered values normalized to range [-1 if x<0, 1 if x>=0]

RRtoolbox.lib.arrayops.filters.**sigmoid**(*x*, *alpha*, *beta*, *max*=255, *min*=0) Apply sigmoid filter.

Parameters

- \mathbf{x} data to apply filter
- alpha if alpha > 0: pass high filter, if alpha < 0: pass low filter, alpha must be != 0
- beta shift from origin
- max maximum output value
- min minimum output value

Returns filtered values ranging as [min,max]

Note: Based from http://www.itk.org/Doxygen/html/classitk_1_1SigmoidImageFilter.html

RRtoolbox.lib.arrayops.filters.**smooth** (*x*, window_len=11, window='hanning', correct=False)

Smooth the data using a window with requested size.

This method is based on the convolution of a scaled window with the signal. The signal is prepared by introducing reflected copies of the signal (with the window size) in both ends so that transient parts are minimized in the beginning and end part of the output signal.

input: x: the input signal window_len: the dimension of the smoothing window; should be an odd integer window: the type of window from 'flat', 'hanning', 'hanning', 'bartlett', 'blackman'

flat window will produce a moving average smoothing.

output: the smoothed signal

Example:

```
t=linspace(-2,2,0.1)
x=sin(t)+randn(len(t))*0.1
y=smooth(x)
```

See also:

numpy.hanning, numpy.hamming, numpy.bartlett, numpy.blackman, numpy.convolve, scipy.signal.lfilter

Note: length(output) != length(input), to correct this: return y[(window_len/2-1):-(window_len/2)] instead of just y.

RRtoolbox.lib.arrayops.mask module This module contains all basic masking and pre-processing (as in segmenting phase) methods

```
RRtoolbox.lib.arrayops.mask.background(gray, mask=None, iterations=3) get the background mask of a gray image. (this it the inverted of foreground())
```

Parameters

- **gray** gray image
- mask (None) input mask to process gray
- **iterations** (3) number of iterations to detect background with otsu threshold.

Returns output mask

```
RRtoolbox.lib.arrayops.mask.biggestCnt(contours)
```

Filters contours to get biggest contour.

Parameters contours -

Returns cnt

```
RRtoolbox.lib.arrayops.mask.biggestCntData(contours)
Gets index and area of biggest contour.
```

Parameters contours -

```
Returns index, area
```

```
\label{eq:RRtoolbox.lib.arrayops.mask.brightness} \ (\textit{img}) \\ \text{get brightness from an image :param img: BGR or gray image :return:}
```

```
RRtoolbox.lib.arrayops.mask.cnt_hist(gray)
```

Mask of a ellipse enclosing retina using histogram threshold.

Parameters

• gray - gray image

• invert – invert mask

Returns mask

RRtoolbox.lib.arrayops.mask.foreground(gray, mask=None, iterations=3) get the foreground mask of a gray image. (this it the inverted of background())

Parameters

- gray gray image
- mask (None) input mask to process gray
- **iterations** (3) number of iterations to detect foreground with otsu threshold.

Returns output mask

RRtoolbox.lib.arrayops.mask.**gethull**(contours)
Get convex hull.

Parameters contours – contours or mask array

Returns cnt

RRtoolbox.lib.arrayops.mask.hist_cdf(img, window_len=0, window='hanning')
Get image histogram and the normalized cumulative distribution function.

Parameters

- img imaeg
- window_len -
- window -

Returns histogram (int), normalized cdf (float)

RRtoolbox.lib.arrayops.mask.mask_watershed(BGR, GRAY=None)
Get retinal mask with watershed method.

Parameters

- BGR -
- GRAY -

Returns mask

RRtoolbox.lib.arrayops.mask.multiple_otsu(gray, mask=None, flag=0L, iterations=1) get the mask of a gray image applying Otsu threshold.

Parameters

- gray gray image
- mask (None) input mask to process gray
- iterations -
 - 1. number of iterations to detect Otsu threshold.

Returns thresh, mask

RRtoolbox.lib.arrayops.mask.thresh_biggestCnt(thresh)
From threshold obtain biggest contour.

Parameters thresh - binary image

Returns cnt

```
RRtoolbox.lib.arrayops.mask.thresh_hist (gray)
Get best possible thresh to threshold object from the gray image.

Parameters gray - gray image.

Returns thresh value.

RRtoolbox.lib.arrayops.mask.threshold_opening (src, thresh, maxval, type)
Eliminate small objects from threshold.

Parameters

• src -

• thresh -

• maxval -

• type -
```

Module contents

Submodules

RRtoolbox.lib.cache module

Returns

```
platform Unix, Windowssynopsis Serialize and Memoize.
```

Contains memoizing, caching, serializing and memory-mapping methods so as to let the package save its state (persistence) and to let a method "remember" what it processed in a session (with cache) or between sessions (memoization and serializization) of the same input contend once processed. It also wraps mmapping functions to let objects "live" in the disk (slower but almost unlimited) rather than in memory (faster but limited).

@cache is used as replacement of @property to compute a class method once. It is computed only one time after which an attribute of the same name is generated in its place.

@cachedProperty is used as replacement of @property to compute a class method depending on changes in its watched variables.

@memoize used as a general memoizer decorator for functions where metadata is generated to disk for persistence.

Made by Davtoh, powered by joblib. Dependent project: https://github.com/joblib/joblib

func

```
ignore
```

mmap mode

verbose

```
class RRtoolbox.lib.cache.Memoizer(ignore=(), ignoreAll=False)
    Bases: object
```

ignore

makememory (cachedir=None, mmap_mode=None, compress=False, verbose=0) Make memory for memoize() decorator.

Parameters

- **cachedir** path to save metadata, if left None function is not cached.
- mmap_mode {None, 'r+', 'r', 'w+', 'c'}, optional. The memmapping mode used when loading from cache numpy arrays. See numpy.load for the meaning of the arguments.
- **compress** (boolean or integer) Whether to zip the stored data on disk. If an integer is given, it should be between 1 and 9, and sets the amount of compression. Note that compressed arrays cannot be read by memmapping.
- verbose (int, optional) Verbosity flag, controls the debug messages that are issued as functions are evaluated.

Returns

 ${\tt memoize} \ (memory = None, ignore = None, verbose = 0, mmap_mode = False)$

Decorated functions are faster by trading memory for time, only hashable values can be memoized.

Parameters

- **memory** (Memory or path to folder) if left None function is not cached.
- ignore (list of strings) A list of arguments name to ignore in the hashing.
- verbose (integer) Verbosity flag, controls the debug messages that are issued as functions are evaluated.
- mmap_mode {None, 'r+', 'r', 'w+', 'c'}, optional. The memmapping mode used when loading from cache numpy arrays. See numpy.load for the meaning of the arguments.

Returns decorator

```
memoizers = {140007976996752: <weakref at 0x7f5625b78520; to 'Memoizer' at 0x7f5625bc0f90>}
```

 ${\bf class} \; {\tt RRtoolbox.lib.cache.Memory} \; ({\it cachedir, mmap_mode=None, compress=False, verbose=1}) \\$

Bases: joblib.memory.Memory

A wrapper to joblib Memory to have better control.

```
class RRtoolbox.lib.cache.NotMemorizedFunc(func)
    Bases: joblib.memory.NotMemorizedFunc
```

class RRtoolbox.lib.cache.cache (func)

Bases: object

Descriptor (non-data) for building an attribute on-demand at first use. @cache decorator is used for class methods without inputs (only self reference to the object) and it caches on first compute. ex:

```
class x(object):
    @cache
    def method_x(self):
        return self.data
```

Note: Cached data can be deleted in the decorated object to recalculate its value.

```
RRtoolbox.lib.cache.cachedProperty(watch=[], handle=[])
```

A memoize decorator of @property decorator specifying what to trigger caching.

Parameters

- watch (list of strings) A list of arguments name to watch in the hashing.
- handle (list of handles or empty list) Provided list is appended with the memo handle were data is stored for the method and where a clear() function is provided.

Returns

RRtoolbox.lib.cache.mapper (path, obj=None, mode=None, onlynumpy=False)
Save and load or map live objects to disk to free RAM memory.

Parameters

- path path to save mapped file.
- obj the object to map, if None it tries to load obj from path if exist
- mode {None, 'r+', 'r', 'w+', 'c'}.
- onlynumpy if True, it saves a numpy mapper from obj.

Returns mmap image, names of mmap files

```
class RRtoolbox.lib.cache.memoizedDict(path, mode=None)
    Bases: _abcoll.MutableMapping
```

memoized dictionary with keys and values persisted to files.

Parameters

- path path to save memo file
- mode loading mode from memo file {None, 'r+', 'r', 'w+', 'c'}

Warning: Some data structures cannot be memoize, so this structure is not save yet. Use at your own risk.

```
clear()
```

Remove all items from D.

```
exception RRtoolbox.lib.cache.notCallable
```

Bases: exceptions.Exception

Defines objectGetter error: given object is not callable.

```
exception RRtoolbox.lib.cache.notCreatable
```

Bases: exceptions. Exception

Defines objectGetter error: objectGetter cannot create new object.

```
class RRtoolbox.lib.cache.objectGetter(callfunc=None, obj=None, callback=None, **annota-
tions)
```

Bases: object

Creates or get instance object depending if it is alive.

```
create (throw=False)
```

Creates an object and keep reference.

Parameters throw – if there is not creation function throws error.

Returns created object.

Warning: previous object reference is lost even if it was alive.

Note: Recommended only to use when object from current reference is dead.

```
isAlive()
    test if object of reference is alive

isCreatable()
    test if can create object

isGettable()
    test if object can be gotten either by reference or creation.

raw()
    get object from reference. :return: None if object is dead, object itself if is alive.

update(**kwargs)

class RRtoolbox.lib.cache.resourceManager(maxMemory=None, margin=0.8, unit='MB', all=True)

Bases: RRtoolbox.lib.cache.retriever
```

keep track of references, create objects on demand, manage their memory and optimize for better performance.

Parameters

- maxMemory (None) max memory in specified unit to keep in check optimization (it does not mean that memory never surpasses maxMemory).
- margin (0.8) margin from maxMemory to trigger optimization. It is in percentage of maxMemory ranging from 0 (0%) to maximum 1 (100%). So optimal memory is inside range: maxMemory*margin < Memory < maxMemory
- unit (MB) maxMemory unit, it can be GB (Gigabytes), MB (Megabytes), B (bytes)
- all if True used memory is from all alive references, if False used memory is only from keptAlive references.

all

Returns all flag, if True: used memory is from all alive references, if False: used memory is only from keptAlive references.

```
bytes2units (value)
      converts value from bytes to user units
getSizeOf (item)
keepAlive (key, obj)
margin
```

Returns margin used for triggering memory optimization from maxMemory.

maxMemory

```
optimizeObject (key, getter, toWhiteList=False)
register (key, method=None, instance=None)
    Register object to retrieve.
```

Parameters

- **key** hashable key to retrieve
- method callable method to get object
- instance object instance already created from method

Note: This method is used in __setitem__ as self.register(key, value). Overwrite this method to change key assignation behaviour.

Example:

```
def mymethod():
    class constructor: pass
    return constructor()

ret = retriever()
ret["obj"] = mymethod # register creating method in "obj"
im = ret["obj"] # get object (created obj +1, with reference)
assert im is ret["obj"] # check that it gets the same object
# it remembers that "obj" is last registered or fetched object too
assert ret() is ret()
# lets register with better control (created obj2 +1, no reference)
ret.register("obj2", mymethod(), mymethod)
# proves that obj2 is not the same as obj (created obj2 +1, no reference)
assert ret() is not ret["obj"]
print list(ret.iteritems()) # get items
```

static resetGetter (getter)

Helper function to reset getter parameters.

Parameters getter – any instance of objectGetter

unit

Returns user defined units

```
units2bytes(value)
```

converts value from user units two bytes

usedMemory

Returns used memory in user units

```
class RRtoolbox.lib.cache.retriever
    Bases: _abcoll.MutableMapping
```

keep track of references and create objects on demand if needed.

```
\verb"register" (key, method=None, instance=None)"
```

Register object to retrieve.

Parameters

- **key** hashable key to retrieve
- method callable method to get object
- instance object instance already created from method

Returns

Example:

```
def mymethod():
    class constructor: pass
    return constructor()

ret = retriever()

ret["obj"] = mymethod # register creating method in "obj"

im = ret["obj"] # get object (created obj +1, with reference)

assert im is ret["obj"] # check that it gets the same object

# it remembers that "obj" is last registered or fetched object too

assert ret() is ret()

# lets register with better control (created obj2 +1, no reference)

ret.register("obj2",mymethod(),mymethod)

# proves that obj2 is not the same as obj (created obj2 +1, no reference)

assert ret() is not ret["obj"]

print list(ret.iteritems()) # get items
```

RRtoolbox.lib.config module

```
platform Unix, Windows
```

synopsis Looking for a reference? look here!.

This module contains all config data to the package.

```
class RRtoolbox.lib.config.ConfigTool
```

Manage the configured Tools.

static getTools (package)

Obtains the tools of a directory for the RRtoolbox.

Parameters package – path to the directory or package object.

Returns a dictionary of imported modules.

```
class RRtoolbox.lib.config.directoryManager(path=None, raiseError=True, autosave=False)
    Bases: object
```

Manage the configured variables, paths and files.

Parameters

- path (None) path to configuration file. If None uses default path.
- raiseError True to raise when not attribute in ConfigFile.
- **autosave** (True) if True saves at each change.

Note: Any attribute that is not in ConfigFile returns None. Use raiseError to control this behaviour.

default

get directories from dictionary representing environment variables.

Returns dictionary of directories.

Note: Only directories in the scope of the module are detected.

load()

loads the configuration file and update.

Returns loaded configuration file dictionary.

Warning: Unsaved instance variables will be replaced by configuration file variables.

reset()

Returns the configuration file to default variables.

Returns False, if error. Dictionary of new data, if successful.

Warning: All custom data is lost in configuration file.

Warning: ConfigFile is purposely not updated. Call manually method load()

save(mode=0)

saves configuration file.

Parameters mode – 0- delete and save, 1- update without replace, 2- update replacing variables.

Returns False, if error. Dictionary of new data, if successful.

RRtoolbox.lib.config.**findModules**(package, exclude=None)

Find modules from a package.

Parameters

- package imported packaged or path (str).
- **exclude** list of modules to exclude.

Returns dictionary containing importer, ispkg

RRtoolbox.lib.config.getModules(package, exclude=None)

Import modules from a package.

Parameters package – imported packaged or path (str).

Returns dictionary containing imported modules.

RRtoolbox.lib.config.getPackagePath(package)

Get the path of a package object.

Parameters package – package object or path (str).

Returns path to the package.

RRtoolbox.lib.descriptors module

```
RRtoolbox.lib.descriptors.ASIFT (feature_name, img, mask=None, pool=<multiprocessing.pool.ThreadPool object>) asift(feature_name, img, mask=None, pool=None) -> keypoints, descrs
```

Apply a set of affine transformations to the image, detect keypoints and reproject them into initial image coordinates. See http://www.ipol.im/pub/algo/my affine sift/ for the details.

ThreadPool object may be passed to speedup the computation.

Parameters

- **feature** name feature name to create detector.
- img image to find keypoints and its descriptors
- mask mask to detect keypoints (it uses default, mask[:] = 255)
- pool multiprocessing pool (dummy, it uses multithreading)

Returns keypoints, descriptors

RRtoolbox.lib.descriptors.**ASIFT_iter**(*imgs*, *feature_name='sift-flann'*)
Affine-SIFT for N images.

Parameters

- imgs images to apply asift
- feature_name eg. SIFT SURF ORB

Returns [(kp1,desc1),...,(kpN,descN)]

RRtoolbox.lib.descriptors.**ASIFT_multiple**(*imgs*, *feature_name='sift-flann'*)
Affine-SIFT for N images.

Parameters

- imgs images to apply asift
- feature_name eg. SIFT SURF ORB

Returns [(kp1,desc1),...,(kpN,descN)]

Bases: object

Class to manage detection and computation of features

Parameters

- pool multiprocessing pool (dummy, it uses multithreading)
- **useASIFT** if True adds Affine perspectives to the detector.
- **debug** if True prints to the stdout debug messages.

config (name, separator='-')

This function takes parameters from a command to initialize a detector and matcher.

Parameters

- name "[a-]<sift|surflorb>[-flann]" (str) Ex: "a-sift-flann"
- **features** it is a dictionary containing the mapping from name to the initialized detector, matcher pair. If None it is created. This feature is to reduce time by reusing created features.

Returns detector, matcher

```
detectAndCompute (img, mask=None)
```

detect keypoints and descriptors

Parameters

- img image to find keypoints and its descriptors
- mask mask to detect keypoints (it uses default, mask[:] = 255)

Returns keypoints, descriptors

RRtoolbox.lib.descriptors.**MATCH** (feature_name, kp1, desc1, kp2, desc2) Use matcher and asift output to obtain Transformation matrix (TM).

Parameters

- **feature_name** feature name to create detector. It is the same used in the detector which is used in init_feature function but the detector itself is ignored. e.g. if 'detector' uses BFMatcher, if 'detector-flann' uses FlannBasedMatcher.
- **kp1** keypoints of source image
- desc1 descriptors of kp1
- **kp2** keypoints of destine image
- desc2 descriptors of kp2

Returns TM

http://docs.opencv.org/3.0-beta/doc/py_tutorials/py_feature2d/py_feature_homography/py_feature_homography.html RRtoolbox.lib.descriptors.MATCH_multiple(pairlist, feature_name='sift-flann')

Parameters

- pairlist list of keypoint and descriptors pair e.g. [(kp1,desc1),...,(kpN,descN)]
- feature_name feature name to create detector

Returns [(H1, mask1, kp_pairs1),....(HN, maskN, kp_pairsN)]

RRtoolbox.lib.descriptors.affine_skew (*tilt*, *phi*, *img*, *mask=None*)

Increase robustness to descriptors by calculating other invariant perspectives to image.

Parameters

- tilt tilting of image
- **phi** rotation of image (in degrees)
- img image to find Affine transforms
- mask mask to detect keypoints (it uses default, mask[:] = 255)

Returns skew_img, skew_mask, Ai (invert Affine Transform)

Ai - is an affine transform matrix from skew_img to img

RRtoolbox.lib.descriptors.**filter_matches** (kp1, kp2, matches, ratio=0.75)
This function applies a ratio test.

Parameters

- **kp1** raw keypoints 1
- kp2 raw keypoints 2
- matches raw matches
- ratio filtering ratio of distance

Returns filtered keypoint 1, filtered keypoint 2, keypoint pairs

RRtoolbox.lib.descriptors.init_feature(name, features=None)

This function takes parameters from a command to initialize a detector and matcher.

Parameters

- name "<sift|surf|orb>[-flann]" (str) Ex: "sift-flann"
- **features** it is a dictionary containing the mapping from name to the initialized detector, matcher pair. If None it is created. This feature is to reduce time by reusing created features.

Returns detector, matcher

RRtoolbox.lib.descriptors.inlineRatio(inlines, lines, thresh=30)

Probability that a match was correct.

Parameters

- inlines number of matched lines
- lines number lines
- thresh threshold for lines (i.e. very low probability <= thresh < good probability)

Returns

RRtoolbox.lib.directory module

This module holds all path manipulation methods and a string concept called directory (referenced paths and strings) designed to support config and be used with session.

keywords:

path: it can be to a folder or file or url if specified *filename*: the file name without its path *filepath*: the path to a file *dirname*: the path to a folder *url*: Universal Resource Locator

```
{\bf class} \; {\tt RRtoolbox.lib.directory.} {\bf File Directory}
```

Bases: RRtoolbox.lib.directory.directory

Saves contents of a file as with directories.

Parameters

- data list, directory instance, dictionary or string.
- **filename** name of file.
- path path to folder where file is (it must finish in /).
- notes optional description string
- **kwargs** additional data to add in directory.

makeFile()

Makes a file with its contents to path/filename.

Returns True if successful

RRtoolbox.lib.directory.changedir(filepath, dirname, ext=True)
Change path to file with dirname.

Parameters

• **filepath** – path to file.

- **dirname** new path to replace in filepath.
- **ext** True to keep extension of file if any.

Returns directory object of changed path.

RRtoolbox.lib.directory.checkDir(dirname) checks if dirname exists.

Parameters dirname - path to folder

Returns True if exits, False if not

RRtoolbox.lib.directory.checkFile (path) checks if filepath or filename exists.

Parameters path – filepath or filename

Returns True if exits, False if not

RRtoolbox.lib.directory.checkPath(path) checks if path exists.

Parameters path – path to folder or file.

Returns True if exits, False if not

RRtoolbox.lib.directory.checkURL(url)

checks if url exists. :param url: path to url :return: True if exits, False if not

 ${\tt RRtoolbox.lib.directory.} \textbf{correctPath} \textit{ (path, relative)}$

Get path corrected from its relative path or level index.

Parameters

- path path or file name.
- relative pattern or level in directory.

Returns corrected path.

RRtoolbox.lib.directory.correctSep(path='/mnt/4E443F99443F82AF/Dropbox/PYTHON/RRtools/RRtoolbox/lib/direct separator='/')

Replaces the path separators by custom or OS standard separator.

Parameters

- path relative or absolute path (str). Default is __file__ or module's path.
- **separator** desired separators, By default uses system separator (os.path.sep).

Returns path with corrected separator.

RRtoolbox.lib.directory.decoratePath(relative, sep='/')

Decorated path is controlled to give absolute path from relative path.

Parameters

- relative int or path.
- **sep** path separator

Returns decorator

class RRtoolbox.lib.directory.directory

Bases: str

semi-mutable string representation of a inmutable string with support for path representations.

Parameters

- data list, directory instance, dictionary or string.
- ispath True to add support for paths.
- **copy** when data is a directory if copy is True then this instance data is independent of the passed directory otherwise both directories are a reference to the same dictionary data but they are not the same object.
- **kwargs** additional data to add in directory.

copy()

Creates copy of itself.

Returns non-referenced directory copy.

correctSTRBuiltin()

Decorate all the built-in functions of class directory.

Returns built-in decorated function.

static filterdata (data, ispath=None, kwargs=None)

Adequate data for dictionary creation.

Parameters

- data any supported object.
- **ispath** True to add support for paths.
- **kwargs** additional data to add in directory.

Returns dictionary

static repr2list (data, level=0)

Converts the representation of a directory.repr to pickleable.

Parameters data – directory.repr of the form ["string",directory,...,directory.repr].

Returns pickleable list.

static repr2str (data, ispath=True)

Converts the representation of a directory repr to string.

Parameters data – directory.repr of the form ["string",directory,...,directory.repr].

Returns converted string.

update (data=None)

Return an updated copy with provided data.

Parameters data – any supported object. If None return updated and referenced copy of itself.

Returns new directory referenced to itself.

update_left(other)

Updates representation a the left.

Parameters other – any supported object.

Returns new directory referenced to itself.

Note: Equivalent to self - other e.g. directory([other, self])

```
update_right (other)
```

Updates representation a the right.

Parameters other – any supported object.

Returns new directory referenced to itself.

Note: Equivalent to self + other e.g. directory([self, other])

RRtoolbox.lib.directory.getData (path='/mnt/4E443F99443F82AF/Dropbox/PYTHON/RRtools/RRtoolbox/lib/directory.p Get standard path from path.

Parameters path – it can be to a folder or file. Default is __file__ or module's path.

Returns [drive,dirname,filename,ext]. 1. drive or UNC (Universal Naming Convention) 2. dirname is path to folder. 3. filename is name of file. 4. ext is extension of file.

RRtoolbox.lib.directory.getFileHandle(path)

Gets a file handle from url or disk file.

Parameters path - filepath or url

Returns file object

RRtoolbox.lib.directory.getFileSize(path)

Gets a size from url or disk file.

Parameters path - filepath or url

Returns size in bytes

RRtoolbox.lib.directory.getPath (path='/mnt/4E443F99443F82AF/Dropbox/PYTHON/RRtools/RRtoolbox/lib/directory.pGet standard path from path.

Parameters path – it can be to a folder or file. Default is __file__ or module's path. If file exists it selects its folder.

Returns dirname (path to a folder)

Note: It is the same as os.path.dirname(os.path.abspath(path)).

RRtoolbox.lib.directory.getSep(path, pattern='\\')

Get path separator or indicator.

Parameters

- path relative or absolute path (str).
- pattern guess characters to compare path (str).

Returns sep (str).

Note: It is equivalent to os.path.sep but obtained from the given path and patterns.

RRtoolbox.lib.directory.getShortenedPath(path,comp)

Path is controlled to give absolute path from relative path or integer.

Parameters

• **path** – absolute path (str).

• comp – pattern or relative path (str) or integer representing level of folder determined by the separator Ex. "/level 1/level 2/.../level N or -1".

Returns path before matched to comp Ex: "C://level 1//comp -> C://level 1"

Example:

```
>>> path = 'LEVEL1/LEVEL2/LEVEL3/LEVEL4/LEVEL5'
>>> print getShortenedPath(path, -2) # minus two levels
LEVEL1/LEVEL2/LEVEL3
>>> print getShortenedPath(path, 2) # until three levels
LEVEL1/LEVEL2
>>> print getShortenedPath(path, 'LEVEL1/LEVEL2/LEVEL3/')
LEVEL1/LEVEL2/LEVEL3/
>>> print getShortenedPath(path, 'LEVEL4/REPLACE5/NEWLEVEL')
LEVEL1/LEVEL2/LEVEL3/LEVEL4/REPLACE5/NEWLEVEL
>>> print getShortenedPath(path, '.../.SHOULD_BE_LEVEL4')
LEVEL1/LEVEL2/LEVEL3/SHOULD_BE_LEVEL4
```

RRtoolbox.lib.directory.getSplitted(path='/mnt/4E443F99443F82AF/Dropbox/PYTHON/RRtools/RRtoolbox/lib/directory.getSplitted(path='/mnt/4E443F99443F82AF/Dropbox/PYTHON/RRtools/RRtoolbox/lib/directory.getSplitted(path='/mnt/4E443F99443F82AF/Dropbox/PYTHON/RRtools/RRtoolbox/lib/directory.getSplitted(path='/mnt/4E443F99443F82AF/Dropbox/PYTHON/RRtools/RRtoolbox/lib/directory.getSplitted(path='/mnt/4E443F99443F82AF/Dropbox/PYTHON/RRtools/RRtoolbox/lib/directory.getSplitted(path='/mnt/4E443F99443F82AF/Dropbox/PYTHON/RRtools/RRtoolbox/lib/directory.getSplitted(path='/mnt/4E443F99443F82AF/Dropbox/PYTHON/RRtools/RRtoolbox/lib/directory.getSplitted(path='/mnt/4E443F99443F82AF/Dropbox/PYTHON/RRtools/RRtoolbox/lib/directory.getSplitted(path='/mnt/4E443F99443F82AF/Dropbox/PYTHON/RRtools/RRtoolbox/lib/directory.getSplitted(path='/mnt/4E443F99443F82AF/Dropbox/PYTHON/RRtools/RRtoolbox/lib/directory.getSplitted(path='/mnt/4E443F99443F82AF/Dropbox/PYTHON/RRtools/RRtoolbox/lib/directory.getSplitted(path='/mnt/4E443F99443F82AF/Dropbox/PYTHON/RRtools/RR

Parameters path – it can be to a folder or file. Default is __file__ or module's path.

Returns splitted path.

RRtoolbox.lib.directory.increment_if_exits (fn, add='_{num}')

Generates new name if it exits.

Parameters

- fn absolute path or filename
- add if fn exists add pattern

Returns un-existent fn

RRtoolbox.lib.directory.joinPath (absolute, relative)
Joins an absolute path to a relative path.

Parameters

- absolute directory or path.
- relative directory or path.

Returns joined path.

Note: It is equivalent to os.path.join but works with directories.

```
RRtoolbox.lib.directory.mkPath (path)

Make path (i.e. creating folder) for filepath.
```

Parameters path – path to nonexistent folder or file.

Returns created path.

```
RRtoolbox.lib.directory.quickOps (path, comp)
(IN DEVELOPMENT) make quick matching operations in path.
```

Parameters

• path – path to folder

• comp – pattern

Returns

Requirements:

```
path = 'LEVEL1/LEVEL2/LEVEL3/LEVEL4/LEVEL5'
print quickOps(path,'../ROOT/../LEVEL1/../LEVEL2/LEVEL3/../../LEVEL4')
'LEVEL4'
print quickOps(path,'ROOT/../LEVEL1/LEVEL2/../../LEVEL4')
'LEVEL3/LEVEL4'
print quickOps(path,'../LEVEL2/../')
'LEVEL1/LEVEL3/LEVEL4/LEVEL5'
print quickOps(path,'../LEVEL2/..')
'LEVEL1/LEVEL3/LEVEL4/LEVEL5/'
print quickOps(path,'LEVEL2/../../LEVEL4/')
'LEVEL2/LEVEL3/LEVEL4/'
print quickOps(path,'ROOT/../LEVEL2/../../LEVEL4')
'ROOT/LEVEL3/LEVEL4'
print quickOps(path,'LEVEL-1/../NEW7/LEVEL8')
'LEVEL-1/LEVEL1/LEVEL2/LEVEL3/LEVEL4/LEVEL5/NEW7/LEVEL8'
print
```

RRtoolbox.lib.directory.resource_path(relative_path='')

Get absolute path to resource, works for dev and for PyInstaller

RRtoolbox.lib.directory.**rmFile**(filepath)

Remove file.

Parameters filepath - path to file.

Returns None

RRtoolbox.lib.directory.**rmPath** (path, ignore_errors=False, onerror=None)
Remove path from path.

Parameters path – path to nonexistent folder or file.

Returns None

See also:

shutil.rmtree

RRtoolbox.lib.directory.strdifference (s1, s2)

Get string differences.

Parameters

- **s1** string 1
- **s2** string 2

Returns (splitted string 1, splitted string 2, index). A splitted string is a list with the string parts. Index is a list containing the indexes of different parts of the two splitted strings.

RRtoolbox.lib.image module

Bundle of methods for handling images. Rather than manipulating specialized operations in images methods in this module are used for loading, outputting and format-converting methods, as well as color manipulation.

SUPPORTED FORMATS

see http://docs.opencv.org/2.4/modules/highgui/doc/reading_and_writing_images_and_video.html#imread

Windows bitmaps - *.bmp, *.dib (always supported) JPEG files - *.jpeg, *.jpg, *.jpe (see the Notes section) JPEG 2000 files - *.jp2 (see the Notes section) Portable Network Graphics - *.png (see the Notes section) Portable image format - *.pbm, *.pgm, *.ppm (always supported) Sun rasters - *.sr, *.ras (always supported) TIFF files - *.tiff, *.tif (see the Notes section)

RRtoolbox.lib.image.bgra2bgr(im, bgrcolor=(255, 255, 255))
Convert BGR to BGRA image.

Parameters

- **im** image
- **bgrcolor** BGR color representing transparency. (information is lost when converting BGRA to BGR) e.g. [200,200,200].

Returns

RRtoolbox.lib.image.checkLoaded(obj, fn='', raiseError=False)
Simple function to determine if variable is valid.

Parameters

- **obj** loaded object
- fn path of file
- raiseError if True and obj is None, raise

Returns None

RRtoolbox.lib.image.convertAs (fns, base=None, folder=None, name=None, ext=None, overwrite=False, loader=None, simulate=False)
Reads a file and save as other file based in a pattern.

Parameters

- **fns** file name or list of file names. It supports glob operations. By default glob operations ignore folders.
- base path to place images.
- **folder** (None) folder to place images in base's path. If True it uses the folder in which image was loaded. If None, not folder is used.
- name string for formatting new name of image with the {name} tag. Ex: if name is 'new_{name}' and image is called 'img001' then the formatted new image's name is 'new_img001'
- **ext** (None) extension to save all images. If None uses the same extension as the loaded image.
- **overwrite** (False) If True and the destine filename for saving already exists then it is replaced, else a new filename is generated with an index "{name}_{index}.{extension}"
- **loader** (None) loader for the image file to change image attributes. If None reads the original images untouched.
- **simulate** (False) if True, no saving is performed but the status is returned to confirm what images where adequately processed.

Returns list of statuses (0 - no error, 1 - image not loaded, 2 - image not saved, 3 - error in processing image)

RRtoolbox.lib.image.drawcoorarea (vis, points, $col_out=(0, 0, 0)$, $col_in=(0, 0, 255)$, radius=2) Function to draw interaction with points to obtain area.

Parameters

- vis image array.
- points list of points.
- col_out outer color of point.
- col_in inner color of point.
- radius radius of drawn points.

Returns

RRtoolbox.lib.image.drawcooraxes (vis, points, $col_out=(0, 0, 0)$, $col_in=(0, 255, 0)$, radius=2) Function to draw axes instead of points.

Parameters

- vis image array.
- points list of points.
- col_out outer color of point.
- col_in inner color of point.
- radius radius of drawn points.

Returns

RRtoolbox.lib.image.drawcoorperspective (vis, points, $col_out=(0, 0, 0)$, $col_in=(0, 0, 255)$, radius=2)
Function to draw interaction with points to obtain perspective.

Parameters

- **vis** image array.
- points list of points.
- col_out outer color of point.
- col_in inner color of point.
- radius radius of drawn points.

Returns

RRtoolbox.lib.image.drawcoorpoints (vis, points, $col_out=(0, 0, 0)$, $col_in=(0, 0, 255)$, radius=2)
Funtion to draw points.

Parameters

- **vis** image array.
- points list of points.
- col_out outer color of point.
- col_in inner color of point.
- radius radius of drawn points.

Returns

RRtoolbox.lib.image.drawcoorpolyArrow (vis, points, $col_out=(0, 0, 0)$, $col_in=(0, 0, 255)$, radius=2)
Function to draw interaction with vectors to obtain polygonal.

Parameters

- **vis** image array.
- points list of points.
- col_out outer color of point.
- col_in inner color of point.
- radius radius of drawn points.

Returns

RRtoolbox.lib.image.drawcoorpolyline (vis, points, $col_out=(0, 0, 0)$, $col_in=(0, 0, 255)$, radius=2)

Function to draw interaction with points to obtain polygonal.

Parameters

- **vis** image array.
- points list of points.
- col_out outer color of point.
- col_in inner color of point.
- radius radius of drawn points.

Returns

RRtoolbox.lib.image.fig2bgr(fig)

Convert a Matplotlib figure to a RGB image.

Parameters fig – a matplotlib figure

Returns RGB image.

RRtoolbox.lib.image.fig2bgra(fig)

Convert a Matplotlib figure to a RGBA image.

Parameters fig – a matplotlib figure

Returns RGBA image.

class RRtoolbox.lib.image.getCoors (im, win='get coordinates', updatefunc=<function drawcoorpoints>, unique=True, $col_out=(0,0,0)$, $col_out=(0,0,255)$)

Bases: RRtoolbox.lib.plotter.plotim

Create window to select points from image.

Parameters

- im image to get points.
- win window name.
- **updatefunc** function to draw interaction with points. (e.g. limitaxispoints, drawcoorperspective, etc.).
- prox proximity to identify point.
- radius radius of drawn points.
- unique If True no point can be repeated, else selected points can be repeated.
- col_out outer color of point.
- col_in inner color of point.

coors

```
drawstats (points, col_out=(0, 0, 0), col_in=(0, 255, 0), radius=2)
```

Parameters

- self -
- points -
- col out -
- col_in -
- radius -

Returns

mousefunc()

Parameters self -

Returns

updatecoors()

Parameters self -

Returns

RRtoolbox.lib.image.getcoors (im, win='get coordinates', updatefunc=<function drawcoor-points>, coors=None, prox=8, radius=3, unique=True, col_out=(0, 0, 0), col in=(0, 0, 255))

RRtoolbox.lib.image.getgeometrycoors(*data)

Get filled object coordinates. (function in progress)

RRtoolbox.lib.image.getrectcoors(*data)

Get ordered points.

Parameters data – list of points

Returns [Top_left,Top_right,Bottom_left,Bottom_right]

```
RRtoolbox.lib.image.gray2qi(gray)
```

Convert the 2D numpy array *gray* into a 8-bit QImage with a gray colormap. The first dimension represents the vertical image axis.

ATTENTION: This QImage carries an attribute *ndimage* with a reference to the underlying numpy array that holds the data. On Windows, the conversion into a QPixmap does not copy the data, so that you have to take care that the QImage does not get garbage collected (otherwise PyQt will throw away the wrapper, effectively freeing the underlying memory - boom!).

source from: https://kogs-www.informatik.uni-hamburg.de/~meine/software/vigraqt/qimage2ndarray.py

RRtoolbox.lib.image.hist_match (source, template, alpha=None)

Adjust the pixel values of an image to match those of a template image.

Parameters

- **source** image to transform colors to template
- template template image ()
- alpha -

Returns transformed source

```
class RRtoolbox.lib.image.imFactory (**kwargs)
```

image factory for RRToolbox to create scripts to standardize loading images and provide lazy loading (it can load images from disk with the customized options and/or create mapping images to load when needed) to conserve memory.

Warning: In development.

```
get_Func()
        gets the loading function

get_code()
        get the script code

get_convertionFunc(code)

get_errorFunc(path=None, throw=None)

get_loadFunc(flag=None)

get_mapFunc(flag=None, RGB=None, mpath=None, mode=None, func=None, dsize=None, dst=None, fx=None, fy=None, interpolation=None)

get_np2qi()

get_resizeFunc(dsize=None, dst=None, fx=None, fy=None, interpolation=None)

get_transposeFunc()

update(**kwargs)

class RRtoolbox.lib.image.imLoader(path, flag=0, dsize=None, dst=None, fx=None, fy=None, fy=None,
```

throw=True)
Class to load image array from path, url, server, string or directly from numpy array (supports databases).

interpolation=None,

Parameters

• **flag** – (default: 0) 0 to read as gray, 1 to read as BGR, -1 to read as BGRA, 2 to read as RGB, -2 to read as RGBA.

mmode=None,

mpath=None,

It supports openCV flags:

- cv2.CV_LOAD_IMAGE_COLOR
- cv2.CV_LOAD_IMAGE_GRAYSCALE
- cv2.CV_LOAD_IMAGE_UNCHANGED

value	openCV flag	output
	N/A	RGB
2.		
	cv2.CV_LOAD_IMAGE_COI	LOBINGR
1.		
	cv2.CV_LOAD_IMAGE_GRA	AYSCANLE
0.		
(-1)	cv2.CV_LOAD_IMAGE_UN	CIBANAED
(-2)	N/A	RGBA

• dsize - (None) output image size; if it equals zero, it is computed as:

exttt{dsize = Size(round(fx*src.cols), round(fy*src.rows))}

- dst (None) output image; it has the size dsize (when it is non-zero) or the size computed from src.size(), fx, and fy; the type of dst is uint8.
- fx scale factor along the horizontal axis; when it equals 0, it is computed as exttt{(double)dsize.width/src.cols}
- fy scale factor along the vertical axis; when it equals 0, it is computed as exttt{(double)dsize.height/src.rows}
- **interpolation** interpolation method compliant with opency:

flag	Operation	Description
0.	INTER_NEAREST	nearest-neighbor interpola- tion
1.	INTER_LINEAR	bilinear interpolation (used by default)
2.	INTER_CUBIC	bicubic interpolation over 4x4 pixel neighborhood
3.	INTER_AREA	resampling using pixel area relation. It may be a preferred method for image decimation, as it gives moire'-free results. But when the image is zoomed, it is similar to the INTER_NEAREST method.
4.	INTER_LANCZOS4	Lanczos interpolation over 8x8 pixel neighborhood

- mmode (None) mmode to create mapped file. if mpath is specified loads image, converts to mapped file and then loads mapping file with mode {None, 'r+', 'r', 'w+', 'c'} (it is slow for big images). If None, loads mapping file to memory (useful to keep image copy for session even if original image is deleted or modified).
- mpath (None) path to create mapped file. None, do not create mapping file "", uses path directory; "*", uses working directory; else, uses specified directory.

Note: If mmode is None and mpath is given it creates mmap file but loads from it to memory. It is useful to create physical copy of data to keep loading from (data can be reloaded even if original file is moved or deleted).

getConfiguration(**kwargs)

get Custom configuration from default configuration :param kwargs: keys to customize default configuration.

If no key is provided default configuration is returned.

Returns dictionary of configuration

```
temp(**kwargs)
```

loads from temporal loader created with customized and default parameters.

Parameters kwargs – keys to customize default configuration.

Returns loaded image.

```
class RRtoolbox.lib.image.imcoors (pts, dtype=<type 'numpy.float32'>, deg=False)
    Bases: object
```

Image's coordinates class. Example:

```
a = imcoors(np.array([(116, 161), (295, 96), (122, 336), (291, 286)]))
print a.__dict__
print "mean depend on min and max: ", a.mean
print a.__dict__
print "after mean max has been already been calculated: ", a.max
a.data = np.array([(116, 161), (295, 96)])
print a.__dict__
print "mean and all its dependencies are processed again: ", a.mean
```

dtype

pts

RRtoolbox.lib.image.interpretImage(toparse, flags)
Interprets to get image.

Parameters

- toparse string to parse or array. It can interpret:
 - *connection to server (i.e. host:port) *path to file (e.g. /path_to_image/image_name.ext) *URL to image (e.g. http://domain.com/path_to_image/image_name.ext) *image as string (i.g. numpy converted to string) *image itself (i.e. numpy array)
- **flags** openCV flags:

value	openCV flag	output
	cv2.CV_LOAD_IMAGE_COI	L OSIK GR
1.		
	cv2.CV_LOAD_IMAGE_GRA	AYSCANLE
0.		
(-1)	cv2.CV_LOAD_IMAGE_UN	CHANGED

Returns image or None if not successfull

```
RRtoolbox.lib.image.limitaxispoints(c, maxc, minc=0)
Limit a point in axis.
```

Parameters

- c list of points...
- maxc maximum value of point.
- minc minimum value of point.

Returns return limited points.

RRtoolbox.lib.image.loadFunc (flag=0, dsize=None, dst=None, fx=None, fy=None, interpolation=None, mmode=None, mpath=None, throw=True, keepratio=True)

Creates a function that loads image array from path, url, server, string or directly from numpy array (supports databases).

Parameters

• flag – (default: 0) 0 to read as gray, 1 to read as BGR, -1 to read as BGRA, 2 to read as RGB, -2 to read as RGBA.

It supports openCV flags:

- cv2.CV_LOAD_IMAGE_COLOR
- cv2.CV_LOAD_IMAGE_GRAYSCALE
- cv2.CV_LOAD_IMAGE_UNCHANGED

value	openCV flag	output
	N/A	RGB
2.		
	cv2.CV_LOAD_IMAGE_COI	LONGR
1.		
	cv2.CV_LOAD_IMAGE_GRA	AYBCXXLE
0.		
(-1)	cv2.CV_LOAD_IMAGE_UN	CHARAED
(-2)	N/A	RGBA

• dsize – (None) output image size; if it equals zero, it is computed as:

exttt{dsize = Size(round(fx*src.cols), round(fy*src.rows))}

If (integer, None) or (None, integer) it completes the values according to keep ratio parameter.

- **dst** (None) output image; it has the size dsize (when it is non-zero) or the size computed from src.size(), fx, and fy; the type of dst is uint8.
- fx scale factor along the horizontal axis
- fy scale factor along the vertical axis
- interpolation interpolation method compliant with opency:

flag	Operation	Description
0.	INTER_NEAREST	nearest-neighbor interpola- tion
1.	INTER_LINEAR	bilinear interpolation (used by default)
2.	INTER_CUBIC	bicubic interpolation over 4x4 pixel neighborhood
3.	INTER_AREA	resampling using pixel area relation. It may be a preferred method for image decimation, as it gives moire'-free results. But when the image is zoomed, it is similar to the INTER_NEAREST method.
4.	INTER_LANCZOS4	Lanczos interpolation over 8x8 pixel neighborhood

- mmode (None) mmode to create mapped file. if mpath is specified loads image, converts to mapped file and then loads mapping file with mode {None, 'r+', 'r', 'w+', 'c'} (it is slow for big images). If None, loads mapping file to memory (useful to keep image copy for session even if original image is deleted or modified).
- mpath (None) path to create mapped file. None, do not create mapping file "", uses path directory; "*", uses working directory; else, uses specified directory.
- **keepratio** True to keep image ratio when completing data from dsize,fx and fy, False to not keep ratio.

Note: If mmode is None and mpath is given it creates mmap file but loads from it to memory. It is useful to create physical copy of data to keep loading from (data can be reloaded even if original file is moved or deleted).

:return loader function

RRtoolbox.lib.image.loadcv (path, flags=-1, shape=None) Simple function to load using opency.

Parameters

- path path to image.
- flag openCV flags:

value	openCV flag	output
	cv2.CV_LOAD_IMAGE_COI	LOSIKGR
1.		
	cv2.CV_LOAD_IMAGE_GRA	AYSCANLE
0.		
(-1)	cv2.CV_LOAD_IMAGE_UN	CHANGED

• **shape** – shape to resize image.

Returns loaded image

 $\begin{array}{ll} \textbf{class} \; \texttt{RRtoolbox.lib.image.loaderDict} \; (\textit{loader=None}, & \textit{maxMemory=None}, & \textit{margin=0.8}, \\ & \textit{unit='MB'}, \textit{all=True}, \textit{config=None}) \end{array}$

Bases: RRtoolbox.lib.cache.resourceManager

Class to standardize loading objects and manage memory efficiently.

Parameters

- loader default loader for objects (e.g. load from file or create instance object)
- maxMemory (None) max memory in specified unit to keep in check optimization (it does not mean that memory never surpasses maxMemory).
- margin (0.8) margin from maxMemory to trigger optimization. It is in percentage of maxMemory ranging from 0 (0%) to maximum 1 (100%). So optimal memory is inside range: maxMemory*margin < Memory < maxMemory
- unit (MB) maxMemory unit, it can be GB (Gigabytes), MB (Megabytes), B (bytes)
- all if True used memory is from all alive references, if False used memory is only from keptAlive references.
- config (Not Implemented)

register (key, path=None, method=None)

RRtoolbox.lib.image.loadsfrom(path, flags=1L)

Loads Image from URL or file.

Parameters

- path filepath or url
- **flags** openCV flags:

value	openCV flag	output
	cv2.CV_LOAD_IMAGE_COI	L OSIG R
1.		
	cv2.CV_LOAD_IMAGE_GRA	AYSCANLE
0.		
(-1)	cv2.CV_LOAD_IMAGE_UN	CHAINGED

Returns

RRtoolbox.lib.image.myline (img, pt1, pt2, color, thickness=None) Funtion to draw points (experimental).

Parameters

- img -
- pt1 -
- pt2 -
- color -
- thickness -

Returns

```
{\tt RRtoolbox.lib.image.np2qi} \ (\textit{array})
```

Convert numpy array to Qt Image.

source from: https://kogs-www.informatik.uni-hamburg.de/~meine/software/vigraqt/qimage2ndarray.py

Parameters array -

Returns

```
RRtoolbox.lib.image.np2str(arr)
class RRtoolbox.lib.image.pathLoader(fns=None, loader=None)
    Bases: _abcoll.MutableSequence
```

Class to standardize loading images from list of paths and offer lazy evaluations.

Parameters

- fns list of paths
- **loader** path loader (loadev,loadsfrom, or function from loadFunc)

Example:

```
fns = ["/path to/image 1.ext","/path to/image 2.ext"]
imgs = pathLoader(fns)
print imgs[0] # loads image in path 0
print imgs[1] # loads image in path 1
```

insert (index, value)

```
RRtoolbox.lib.image.plt2bgr(image)
RRtoolbox.lib.image.plt2bgra(image)
RRtoolbox.lib.image.gi2np(gimage, dtype='array')
```

Convert QImage to numpy.ndarray. The dtype defaults to uint8 for QImage.Format_Indexed8 or *bgra_dtype* (i.e. a record array) for 32bit color images. You can pass a different dtype to use, or 'array' to get a 3D uint8 array for color images.

source from: https://kogs-www.informatik.uni-hamburg.de/~meine/software/vigraqt/qimage2ndarray.py

```
RRtoolbox.lib.image.quadrants(points)
```

Separate points respect to center of gravity point.

```
Parameters points – list of points
```

```
Returns [[Top_left],[Top_right],[Bottom_left],[Bottom_right]]
```

```
RRtoolbox.lib.image.rgb2qi(rgb)
```

Convert the 3D numpy array rgb into a 32-bit QImage. rgb must have three dimensions with the vertical, horizontal and RGB image axes.

ATTENTION: This QImage carries an attribute *ndimage* with a reference to the underlying numpy array that holds the data. On Windows, the conversion into a QPixmap does not copy the data, so that you have to take care that the QImage does not get garbage collected (otherwise PyQt will throw away the wrapper, effectively freeing the underlying memory - boom!).

source from: https://kogs-www.informatik.uni-hamburg.de/~meine/software/vigraqt/qimage2ndarray.py

```
RRtoolbox.lib.image.separe(values, sep, axis=0)
```

Separate values from separator or threshold.

Parameters

• values – list of values

- sep peparator value
- axis axis in each value

:return:lists of greater values, list of lesser values

```
RRtoolbox.lib.image.str2np(string, shape)
RRtoolbox.lib.image.transposeIm(im)
```

RRtoolbox.lib.image.try_loads (fns, func=<built-in function imread>, paths=None, debug=True) Try to load images from paths.

Parameters

- fns list of file names
- func loader function
- paths paths to try. By default it loads working dir and test path
- **debug** True to show debug messages

Returns image else None

RRtoolbox.lib.inspector module

This module is an all purpose intended for debugging, tracking, auto-documenting and self-introspecting the package Made by Daytoh. Powered partially by pycallgraph. Dependent project: https://github.com/gak/pycallgraph/#python-

Made by Davtoh. Powered partially by pycallgraph. Dependent project: https://github.com/gak/pycallgraph/#python-call-graph

```
class RRtoolbox.lib.inspector.Asyncronous (outputs, config)
    Bases: RRtoolbox.lib.inspector.Syncronous
    done()
    start()
    tracer(frame, event, arg)
class RRtoolbox.lib.inspector.Logger(**kwargs)
    Bases: object
```

Logger for decorated functions. Holds important information of an instanced object and can be used with @trace decorator for traceback purposes.

Parameters

- **func** object reference.
- funcname object name.
- inputs inputs pass to the object.
- **outputs** outputs given by the object execution.
- time initial time of execution.
- exectime time of execution in seconds.
- writer writer function where messages are passed.
- eventHandle event function where object is passed when Logger.broadcast() is called.
- msg_report message format to use in reports.

- msg_no_executed massage format to pass to writer when object has not been executed and Logger.report() is called.
- msg_executed massage format to use when object is executed and Logger.broadcast() is called.

```
Time
         returns formated time (str)
     Type_
         returns type name (str)
     broadcast()
         pass a notification message on object execution to the writer
     eventHandle = None
     file = <open file '<stdout>', mode 'w'>
     renew()
         renew Instance
     report()
         pass a report of the last executed object to the writer
     throwError()
         throw caught error :return:
     tracer
     writer (sender, *arg)
class RRtoolbox.lib.inspector.Syncronous (outputs, config)
     Bases: pycallgraph.tracer.SyncronousTracer
     start()
     stop()
RRtoolbox.lib.inspector.funcData(func)
class RRtoolbox.lib.inspector.graphTrace (output=None, config=None)
     Bases: pycallgraph.pycallgraph.PyCallGraph
     get_tracer_class()
     saveSource (file)
     source
class RRtoolbox.lib.inspector.graphTraceOutput (source=None, saveflag=True,
     Bases: pycallgraph.output.graphviz.GraphvizOutput
     done()
     save (file=None, source=None)
     saveSource (file, source=None)
RRtoolbox.lib.inspector.load(mod_name, obj_name)
     Convert a string version of a class name to the object.
     For example, get_class('sympy.core.Basic') will return class Basic located in module sympy.core
RRtoolbox.lib.inspector.reloadFunc(func)
```

RRtoolbox.lib.inspector.tracer(instance, broadcast=True, report=True)
Tracer for decorated functions

Parameters

- instance Logger instance
- broadcast -
- report -

Returns

RRtoolbox.lib.plotter module

This module holds the plotting and data-visualization tools. Motto: don't know how it is interpreted? i'll show you!

#plotim example filename = "t2.jpg" win = "test" img = cv2.resize(cv2.imread(filename), (400, 400)) # (height, width) plot = plotim(win,img) plot.show()

RRtoolbox.lib.plotter.background (color, x=1, y=1, flag=0)
Creates background rectangle.

Parameters

- color main color.
- $\mathbf{x} \mathbf{x}$ pixels in axis x.
- \mathbf{y} y pixels in axis y.
- flag Not implemented.

Returns image of shape y,x and ndim == color.ndim.

RRtoolbox.lib.plotter.convert2bgr (src, bgrcolor=None)
Tries to convert any image format to BGR.

Parameters

- **src** source image.
- **bgrcolor** background or transparent color.

Returns BGR array image.

RRtoolbox.lib.plotter.convert2bgra (src, bgracolor=None, transparency=None)
Tries to convert any image format to BGRA.

Parameters

- **src** source image.
- **bgracolor** background or transparent color.
- **transparency** mask or A channel. (typically source image has not A channel, so user can provide it)

Returns BGRA array image.

```
RRtoolbox.lib.plotter.echo(obj)
```

Printer (used when user wants to print an object from plotim) :param obj: object

class RRtoolbox.lib.plotter.edger(img, isSIZE=True, isEQUA=False, isCLAHE=False, isBFIL-TER=False)

Bases: RRtoolbox.lib.plotter.plotim

```
Test visualization for edges
     self.edge -> the edges in processed image self.img -> the processed image self.sample -> the rendered precessed
     image
     computeAll()
     computeEdge()
     getParameters (params=('d', 'sigmaColor', 'sigmaSpace', 'clipLimit', 'tileGridSize', 'isSIZE', 'isE-
                        QUA', 'isCLAHE', 'isBFILTER', 'th1', 'th2', 'size', 'apertureSize', 'L2gradient'))
     isActiveWindow()
     isBFILTER
     isCLAHE
     isEQUA
     isSIZE
     load (img, compute=True)
     maxth
     onTrackbar1 (*args)
     onTrackbar2 (*args)
     save (strname=None, ext='.png', name='img')
     showgray
     size
     th1
     th2
     windowfunc()
RRtoolbox.lib.plotter.fastplt(image, cmap=None, title='visualazor', win=None, block=False,
                                        daemon=False)
     Fast plot.
          Parameters
                • image – image to show
                • cmap – "gray" or None
                • title - title of subplot
                • win – title of window
                • block – if True it wait for window close, else it detaches (Experimental)
                • daemon – if True window closes if main thread ends, else windows must be closed to main
                  thread to end (Experimental)
          Returns plt
RRtoolbox.lib.plotter.graph_filter(filters, levels=None, titles=None, win=None, single=True,
                                              legend=True, annotate=True,
                                                                              cols=3, scale=0.07,
                                              show=True, lxp=None, lyp=None)
     Graph filter with standard data to watch response.
```

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Parameters

```
• filters - list of filters
                 • levels – numpy array with values. if None tries to fit data or assumes from 0 to 255
                 • titles – list of titles for each filter in filters. if None creates the titles
                 • win - window name
                 • single – True to plot all filters in one plot. else separate each filter in a plot.
                 • legend – True to add legends.
                 • annotate – True to add annotations.
                 • cols – number of columns to create plots
                 • scale – factor from maximum to draw annotations
                 • show – to show the figure
           Returns figure
class RRtoolbox.lib.plotter.imtester(img, win='imtester plot')
     Bases: RRtoolbox.lib.plotter.plotim
     Used to test some concepts as thresholds and filters
     static applythresh (img, type, adaptativetoggle, threshtoggle, th, blocksz, c, i='', ti='', info='', ti-
                            tle='')
     builtcmd()
     computefunc (image=None)
     detectType (type, i='', info='')
```

RRtoolbox.lib.plotter.limitaxis(c, maxc, minc=0)

Limit value in axis.

visualize() windowfunc()

Parameters

• c - value

static formatinfo(info, words=9)

- maxc max c value.
- minc min c value.

Returns limited c value c E [minc,maxc]

```
class RRtoolbox.lib.plotter.matchExplorer(win, img1, img2, kp_pairs=(), status=None,
                                             H=None, show=True, block=True, daemon=True)
    Bases: RRtoolbox.lib.plotter.plotim
```

updatevisualization (image, channel, th=None, items=None, thresh1=None, thresh2=None)

Draws a set of keypoint pairs obtained on a match method of a descriptor on two images imgf and imgb. (backend: plotim).

Parameters

- win window's name (str)
- img1 image1 (numpy array)

- img2 image2 (numpy array)
- **kp_pairs** zip(keypoint1, keypoint2)
- status obtained from cv2.findHomography
- **H** obtained from cv2.findHomography (default=None)
- **show** if True shows plotim using block and daemon, else do not show
- block if True it wait for window close, else it detaches
- daemon if True window closes if main thread ends, else windows must be closed to main thread to end

Returns plotim object with visualization as self.rimg (image with matching result) (default=None)

Note: It supports BGR and gray images.

```
drawline()
```

Draws background visualization without interaction

drawrelation()

Draw keypoints where pointer is placed and pressed

```
keyfunc()
```

```
mousefunc()
```

```
static randomColor()
```

updaterenderer (img=None, zoom=True)

update renderer when called.

Parameters

- img image to update in renderer, if None use self.img
- **zoom** True to enable zoom, else updates with original img.

Returns None

```
RRtoolbox.lib.plotter.plotPointsContour (pts, ax=None, lcor='k', pcor=None, deg=None, annotate=True, width=0.004, label='pt{pt}({x}, {y}, {a})', arrowprops=None)
```

Plots points and joining lines in axes.

Parameters

- **pts** points. [(x0,y0)...(xN,yN)]
- ax axes handle to draw points.
- lcor color of joining lines.
- pcor color of points. If specified uses lines, else vectors.
- deg angle of vertex, if True in degrees, if False in radians, if None do not add.

Returns ax.

Show and image with events, animations, controls, internal commands and highly customizable by code.

Parameters

- win window name
- im image of numpy array
- bgrcolor default color to use for transparent or background color.

Warning: plotim is deprecated and will be replaced in the future (it was made to test concepts). Originally it was made for windows but some functions were removed to let it be multi-platform.

builtincmd()

Internal cmd control

builtincontrol (control=False)

Internal control. use self.usecontrol = True to activate.

Parameters control – if True, use control key.

Returns

builtinplot (*pixel=None*, *useritems=None*, *flag=1*, *xpad=0*, *ypad=0*, *bgrcolor=None*, *alpha=None*) Internal plot.

Parameters

- pixel pixel color where mouse is placed (placed for better control). Color can be from real image, showed image, original image or rendered image, or any color.
- useritems items to show.
- **flag** flag for position (default=0).
 - flag==0: foreground to left up.
 - flag==1: foreground to left down.
 - flag==2: foreground to right up.
 - flag==3: foreground to right down.
 - flag==4: foreground at center of background.
 - flag==5: XY 0,0 is at center of background.
 - flag==6: XY 0,0 is at center of foreground.
 - flag==7: XY 0,0 is at right down of foreground.
- xpad padding in x
- **ypad** padding in y
- bgrcolor background color
- alpha alpha mask or value for transparency

Returns

builtinwindow()

loads windowfunc, showfunc, starts window thread and mousecallback.

clean()

Attempt to clean the plotter dictionary for an error in garbage collection. :return:

closefunc()

Decoupled close function for plotim (replace self.closefunc).

Parameters self - plotim instance

```
cmdfunc (execute=False)
```

command function and decoupled cmd solver for plotim. (repalce self.cmdfunc)

Parameters

- self -
- **execute** True, enable execution of commands, False, disable execution.

errorbackground

```
formatcmd (cmd, references=('+', '-', '*', '='), lmissing='self.')
```

Decoupled cmd formatter for cmdfunc and plotim.

Parameters

- **self** plotim instance
- cmd command
- references -
- lmissing assumed missing part in command

Returns

help (showAll=False)

function to print the quick help for the user with all the commands

init()

Pseudo __init__. it is used to restart default values without destroying configurations.

keyfunc()

Decoupled key function for plotim (replace self.keyfunc).

Parameters self - plotim instance

makeoverlay (*items*, *xpad*=0, *ypad*=0, *bgrcolor*=None, *alpha*=None) overlay items over image.

Parameters

- self instance
- items list of object to overlay
- xpad pad in x
- ypad pad in y
- bgrcolor background color
- alpha transparency color

Returns overlayed

mousefunc()

Decoupled mouse function for plotim (replace self.mousefunc).

Parameters self - plotim instance

static onmouse (event, x, y, flags, self)

Mouse event function for plotim. (replace self.mousefunc)

Parameters

- event mouse event
- $\mathbf{x} \mathbf{x}$ position

- y y postion
- flags mouse flag to use in control (it represents clicks)
- self plotim object

Returns

Parameters

- items list of items supported by self.makeoverlay()
- img image to place in items. If None it uses self.remg
- $\mathbf{x} \mathbf{x}$ position
- y y position
- **flag** flag for position (default=0).
 - flag==0: foreground to left up.
 - flag==1: foreground to left down.
 - flag==2: foreground to right up.
 - flag==3: foreground to right down.
 - flag==4: foreground at center of background.
 - flag==5 : XY 0,0 is at center of background.
 - flag==6: XY 0,0 is at center of foreground.
 - flag==7: XY 0,0 is at right down of foreground.
- xpad padding in x
- ypad padding in y
- bgrcolor background color
- alpha alpha mask or value for transparency
- pixel color to add as item im items,

Returns

plotatxy (items, img=None, x=0, y=0, flag=0, xpad=0, ypad=0, bgrcolor=None, alpha=None) Plot message in xy position.

Parameters

- items list of items supported by makeoverlay ()
- img image to place in items. If None it uses self.remg
- $\mathbf{x} \mathbf{x}$ position
- y y position
- **flag** flag for position (default=0).
 - flag==0: foreground to left up.
 - flag==1: foreground to left down.

```
- flag==2: foreground to right up.
               - flag==3: foreground to right down.
               - flag==4: foreground at center of background.
               - flag==5: XY 0,0 is at center of background.
               - flag==6: XY 0,0 is at center of foreground.
               - flag==7: XY 0,0 is at right down of foreground.
              • xpad – padding in x
              • ypad – padding in y
              • bgrcolor - background color
              • alpha – alpha mask or value for transparency
         Returns
plotintime (items=None, wait=2, img=None, bgrcolor=None)
     plots messages and events.
         Parameters
              • items – list of items supported by makeoverlay ()
              • wait - time of message.
              • img – image to place in items. If None it uses self.remg
              • bgrcolor – color of message.
         Returns
real2render (x, y, astype=None)
     from real coordinates get rendered coordinates.
         Parameters
              • x − real x
              • y – real y
              • astype – (np.int32) return as the specified type
         Returns rendered x, rendered y
render2real (rx, ry, astype=<type 'numpy.int32'>)
     from rendered coordinates get real coordinates.
         Parameters
              • rx - rendered x
              • ry - rendered y
              • astype – (np.int32) return as the specified type
```

Returns real x, real y

rx1 rx2 ry1 ry2

```
save (strname=None, ext='.png', name='img')
```

Save image (save image if not Qt backend is installed) :param strname: name to save, a label with {win} can be used to be replaced with the plot win name :param ext: (".png") extension. :param name: ("img") name of image object from self. default is "img" that is self.img

(it allows better control to get custom image)

Returns True if saved, False if not saved (possibly because folder does not exists)

```
show (frames=None, block=True, daemon=False, clean=True)
```

Show function. calls buildinwindow, handles key presses and close events.

Parameters

- **frames** show number of frames and close.
- block if True it wait for window close, else it detaches (Experimental)
- **daemon** if True window closes if main thread ends, else windows must be closed to main thread to end (Experimental)

Returns

showfunc(img=None)

Decoupled show function for plotim (replace self.showfunc).

Parameters

- self plotim instance
- img image to show

textbackground

```
updaterenderer (img=None, zoom=True)
```

update renderer when called.

Parameters

- img image to update in renderer, if None use self.img
- **zoom** True to enable zoom, else updates with original img.

Returns None

windowfunc()

Decoupled window function for plotim (replace self.windowfunc).

Parameters self – plotim instance

RRtoolbox.lib.root module

This module holds core-like methods for library modules but not for the hole package

```
class RRtoolbox.lib.root.Controlstdout(disable=True, buffer=None)
    Bases: object
```

Context manager to control output to stdout

Parameters

• **disable** – if True suppress output.

• **buffer** – (None) if True creates a buffer to collect all data printed to the stdout which can be retrieved with self.buffered. A file can be given but if it is write-only it cannot retrieve data to self.buffered so "w+" is recommended to be used with self.buffered.

Warning: If a references to sys.stdout is kept before the Controlstdout instance then output can be printed trough it and cannot be controlled by the Controlstdout context.

```
class RRtoolbox.lib.root.FactorConvert (factor=None, abbreviate=True)
```

Bases: object

Keep track of factor and converts to any available factor.

```
convert (factor, to=None)
```

Convert from actual factor to another factor.

Parameters

- factor number
- to factor to convert

Returns converted value, units

convert2sample (factor, to=None)

Convert to resemble sample.

Parameters

- factor number
- to sample factor.

Returns converted value, units

exactFactorIndex(key)

Find the index of a factor that contains a key.

Parameters key – anything to look in factors (i.e. factor name, factor value, abbreviation).

Returns factor structure, else None.

factor

factors

getFactor (key)

Tries to find factor value in factors.

Parameters key – anything to look in factors (i.e. factor name, factor value, abbreviation). If key is a factor value it will look for the nearest factor value.

Returns factor structure, else raises error.

nearFactorIndex (factor)

Find the index of nearest factor value.

Parameters factor – factor value.

Returns factor structure near factor value.

static parts (value, precision=4)

Get number parts.

Parameters

• value - number

```
• precision – decimal precision
```

Returns ([..., Hundreds, Tens, Ones], [Tenths, ...])

static split (value)

Get number fraction.

Parameters value - number

Returns integer, fraction

class RRtoolbox.lib.root.Magnitude (value=0, factor=None, unit=None, precision=None, abbreviate=False)

Bases: object

format value(value)

Bases: object

Context to profile code by printing a prelude and prologue with time.

Parameters

- msg prelude or description message
- factor factor supported by FactorConvert class
- precision number of digits after a float point
- abv if True prints "s", if False "seconds" for time
- endmsg prologue message
- enableMsg (True) A flag specifying if context should be printed or not.
- printfunc function to print messages. By default it is sys.stdout.write

time

time_end

RRtoolbox.lib.root.addto(instance, funcname=None)

Decorator: Add function as method to instance.

Parameters

- instance class instance.
- **funchame** name to register in instance.

Returns

RRtoolbox.lib.root.decorateInstanceMethods(self, decorator, excludeMth='__init__', in-cludeMth=None)

Decorate methods in an instance. It should be used in the __init__ method of a class.

Parameters

- **self** class instance.
- **decorator** decorator function to apply to self.
- excludeMth list of methods to exclude.

• **includeMth** – list of methods to include if not in exclude. if excludeMth is None then decorateInstanceMethods checks for includeMth list. if includeMth and excludeMth is None then all methods of self are decorated.

Returns self

```
Note: It must be used at instance initialization (i.e. inside init method)
```

```
RRtoolbox.lib.root.glob (path, contents='*', check=<function isfile>)
Return a list of paths matching a pathname pattern with valid files.
```

Parameters

- path path to process ing glob filter
- contents If path is a folder then looks for contents using
- **check** function to filter contents. it must receive the path and return True to let it pass and False to suppress it.

Returns return list of files

RRtoolbox.lib.root.lookinglob (pattern, path, ext=None, returnAll=False, raiseErr=False)

Parameters

- pattern look pattern in path
- path path to look pattern
- ext extension
- raiseErr If true raise Exception if patter not found in path

Returns fn or None

```
class RRtoolbox.lib.root.profiler (msg=None, tag=None)
    Bases: object

profiler for code points

param msg custom comment for profiling point

param tag classification tag

parameter space ("")

parameter format_line ("{space}{tag}{msg}{time}")

parameter format_structure ("

{space}[{tag}{msg}{time}{child}]{side}")

parameter points profile instaces which are divided in "side" or "children" points according if they are side by side or are inside of the profiler.

close()
```

Parameters

formatter (level, tag, msg, time)

• level -

close profiler and all their points

format profiling point arguments.

- tag classification tag
- msg custom comment of profiling point
- time time of profiling

Returns formatted (spacing, tag, msg, time)

lines formatted(collapse=None)

generate string lines

Parameters collapse – list for collapsing repeated tags or messages.

Returns list of lines

lines_unformatted(collapse=None)

generate structure lines

Parameters collapse – list for collapsing repeated tags or messages.

Returns generator with outputs (level, tag, msg, time)

open_point (msg=None, tag=None)

Open a profiling point to track time.

Parameters

- msg custom comment for profiling point
- tag classification tag

Returns

restructure (structure, collapse)

reprocess an already created structure.

Parameters

- structure structure.
- **collapse** list for collapsing repeated tags or messages.

Returns reprocessed structure

string_lines()

string with plain structure of profiling

string_structured(collapse=None, structure=None)

string with plain structure of profiling

Parameters

- **collapse** list for collapsing repeated tags or messages.
- **structure** (None) uses and already created structure. If None it creates the structure.

Returns string

structure (collapse=None)

profiling structure.

Parameters collapse – list for collapsing repeated tags or messages.

Returns structure with format [tag,msg,time,children]

time

Returns overall time of profiling

```
class RRtoolbox.lib.root.stdoutLOG(path, mode='w+', chain=False)
     simple logger to save stdout output so anything printed in the console is logged to a file.
          Parameters
                • path – path to logging file
                • mode – mode for opening the file.
                • chain – if True closes previous logs and continues with new log
     close(**kwargs)
     flush(**kwargs)
     printline (text, **kwargs)
     printlines (lines, **kwargs)
     write(text, **kwargs)
class RRtoolbox.lib.root.stdoutMULTI (filelist)
     Enclose several file-like objects.
     :param filelist = list of file-like objects
     close(**kwargs)
     flush(**kwargs)
     printline (text, **kwargs)
     printlines (lines, **kwargs)
     write(text, **kwargs)
class RRtoolbox.lib.root.stdoutSIM(disable=False, stdout=None)
     simple logger to simulate stdout output
     close()
     flush()
     printline (text, **kwargs)
     printlines (lines, **kwargs)
     write(text, **kwargs)
RRtoolbox.lib.serverServices module
class RRtoolbox.lib.serverServices.Conection(conn)
     represent a connection to interchange objects between servers and clients.
     getLen (timeout=None)
     rcv()
     recvall()
     send (obj)
     sendLen (length, timeout=None)
exception RRtoolbox.lib.serverServices.TimeOutException
     Bases: exceptions. Exception
```

```
exception RRtoolbox.lib.serverServices.TransferExeption
     Bases: exceptions. Exception
RRtoolbox.lib.serverServices.generateServer(host='localhost', to=63342)
     generates a simple Server in available address.
          Parameters to – until port.
          Returns socket, address
RRtoolbox.lib.serverServices.initClient (addr, timeout=None)
     Inits a simple client from address. :param addr: (host, port) :return: socket
RRtoolbox.lib.serverServices.initServer(addr)
     Inits a simple server from address.
          Parameters addr – (host, port)
          Returns socket
RRtoolbox.lib.serverServices.parseString(string, timeout=3)
               • string -
               • timeout -
          Returns
RRtoolbox.lib.serverServices.ping(host, port)
     Ping to.
          Parameters
               • host – IP address
               • port – port address
          Returns
RRtoolbox.lib.serverServices.rcvPickle (addr=('localhost', 50007), timeout=None)
     Receive potentially any data using sockets.
          Parameters

    addr – socket or address.

               • timeout - NotImplemented
          Returns data, else throws error.
```

RRtoolbox.lib.serverServices.recv_into(viewable, socket)
Receive from socket into viewable object.

Parameters

- viewable viewable object
- socket source socket

Returns None

RRtoolbox.lib.serverServices.scan_ports(host)
Scan opened ports in address.

Parameters host – host IP to filter opened ports.

Returns generator

RRtoolbox.lib.serverServices.**sendPickle** (obj, addr=('localhost', 50007), timeout=None, threaded=False)

Send potentially any data using sockets.

Parameters

- **obj** packable object.
- addr socket or address.
- timeout NotImplemented

Returns True if sent successfully, else Throw error.

RRtoolbox.lib.serverServices.**send_from**(*viewable*, *socket*)
Send from viewable object.

Parameters

- viewable viewable object
- socket destine socket

Returns None

RRtoolbox.lib.serverServices.string_is_socket_address(string)

RRtoolbox.lib.session module

This module have serializing methods for data persistence so to let the package "save" custom objects session module made by Davtoh and powered by dill Dependency project: https://github.com/uqfoundation/dill

RRtoolbox.lib.session.checkFromSession(filepath, varlist)

Check that variables exits in session file.

Parameters

- **filepath** path to session file.
- varlist list of variables to checkLoaded.

Returns list checkLoaded results

RRtoolbox.lib.session.deleteFromSession (filepath, varlist)
Delete variables from session file.

Parameters

- **filepath** path to session file.
- **varlist** list of variables to delete.

Returns None

RRtoolbox.lib.session.flushSession(filepath)
Empty session in file.

Parameters filepath – path to session file.

Returns

RRtoolbox.lib.session.getEnviromentSession (enviroment=None) Gets the filtered session from the global variables.

Returns dictionary containing filtered session.

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RRtoolbox.lib.session.readSession(filepath, helper=None)
Loads a dictionary session from file.

Parameters

- **filepath** path to load session file.
- helper function to pos-process session file

Returns session

RRtoolbox.lib.session.saveSession (filepath, session, helper=None) Saves dictionary session to file.

Parameters

- **filepath** path to save session file.
- session dictionary
- helper function to pre-process session

Returns filename of saved session

RRtoolbox.lib.session.updateSession(filepath, session, replace=True, rdhelper=None, svhelper=None)

Updates a dictionary session in file.

Parameters

- **filepath** path to session file.
- session dictionary.
- replace if True key values are replaced else old key values ar kept.
- rdhelper read helper.
- svhelper save helper.

Returns None

Module contents

This module contains core-like, too-much-used and too-much-referenced modules

1.1.2 RRtoolbox.tools package

Submodules

RRtoolbox.tools.lens module

RRtoolbox.tools.lens.drawCircle(array, cnt, color=0) project circle over array.

Parameters

- array array to draw circle
- cnt contours of segmentation to fit circle
- color color of lens

Returns array

RRtoolbox.tools.lens.drawEllipse(array, cnt, color=0) project ellipse over array.

Parameters

- array array to draw ellipse
- cnt contours of segmentation to fit ellipse
- color color of lens

Returns array

RRtoolbox.tools.lens.fitLens(img, mask, color=0, asEllipse=False, addmask=False)
Place lens-like object in image.

Parameters

- img image to place lens
- mask mask to fit lens
- color color of the lens
- **asEllipse** True to fit lens as a ellipse, False to fit circle.
- addmask return additional mask parameter

Returns image with simulated lens

RRtoolbox.tools.lens.simulateLens (img, threshfunc=None, pshape=(300, 300), color=0, asEllipse=True)

Place lens-like object in image.

Parameters

- img image to place lens.
- threshfunc function to segment retinal area and get its mask.
- **pshape** shape to resize processing image to increase performance.
- color color of the lens.
- asEllipse True to fit lens as a ellipse, False to fit circle.

Returns image with simulated lens.

RRtoolbox.tools.restoration module

RRtoolbox.tools.restoration.asif_demo (fn_back=None, fn_fore=None, **opts)
Demo to test ASIFT, Merge, Plotters.

Parameters

- fn_back file name of background image
- fn fore file name of foreground image
- **opts demo options flag options: flag_filter_scaled (False): filter scaled images flag_filter_original (False): filter original images flag_filter_out (False): filter pos-processed images flag_invertH (False): test inversion of Trasformation Matrix obtained from Homography flag_show_match (True): show match keypoint of scaled images flag_show_result (True): show restored image flag_save_perspective (False): save calculated perspective of foreground image flag_save_result (False): save restored image

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value obtions: fore_scale (400,400): tuple of W,H to convert original foreground to scaled image back_scale (400,400): tuple of W,H to convert original background to scaled image feature: ('sift-flann') use base descriptor

Returns

```
dictionary of results if there is not match the keys are:
```

```
['status', 'kp1', 'kp2', 'kp pairs', 'desc1', 'desc2','H']
```

if there is match then additional keys are: ['img_perspective', 'img_restored', 'H_original', 'kp_pairs_original']

if flag_invertH additional kes: ['H_inverted']

RRtoolbox.tools.restoration.asif_demo2 (fn_back=None, fn_fore=None, **opts)

Demo to test ASIFT, Merge, Plotters, etc while extending images.

Parameters

- fn back file name of background image
- fn_fore file name of foreground image
- **opts demo options flag options: flag_filter_scaled (False): filter scaled images flag_filter_original (False): filter original images flag_filter_out (False): filter pos-processed images flag_invertH (False): test inversion of Trasformation Matrix obtained from Homography flag_show_match (True): show match keypoint of scaled images flag_show_result (True): show restored image flag_save_perspective (False): save calculated perspective of foreground image flag_save_result (False): save restored image

value obtions: fore_scale (400,400): tuple of W,H to convert original foreground to scaled image back_scale (400,400): tuple of W,H to convert original background to scaled image feature: ('sift-flann') use base descriptor

Returns

dictionary of results if there is not match the keys are:

```
['status', 'kp1', 'kp2', 'kp_pairs', 'desc1', 'desc2','H']
```

if there is match then additional keys are: ['img_perspective', 'img_restored', 'H_original', 'kp_pairs_original']

if flag invertH additional kes: ['H inverted']

RRtoolbox.tools.restoration.extractCSV(data, saveTo=None)

RRtoolbox.tools.restoration.getDicDescriptor(path, loader, feature_name, dic=None)

Parameters

- path -
- loader -
- feature name -
- dic-

Returns

RRtoolbox.tools.restoration.qualifyData(data, loader=None, saveTo=None, auto-qualify=False, showOnlyPassedTest=False, clear=False)

Qualify data of format obtained from testRates.

Parameters

- data dictionary containing all data
- loader use loader for images
- saveTo save data to path
- autoqualify qualify all data without asking human intervention and using algorithm
- **showOnlyPassedTest** if True shows only the goods tests to qualify, else do not show.
- clear re-do all saved tests.

Returns

RRtoolbox.tools.restoration.stitch_multiple(images=None, **opts)

Parameters opts -

feature = 'sift-flann' loader = "400,400" saveTo = None, autoqualify = False, showOnlyPassedTest= False, clearAll = False, clearData = clearAll, clearQualification = clearAll :return:

RRtoolbox.tools.restoration.testRates(images=None, **opts)

Parameters opts -

feature = 'sift-flann' loader = "400,400" saveTo = None, autoqualify = False, showOnlyPassedTest= False, clearAll = False, clearData = clearAll, clearQualification = clearAll :return:

RRtoolbox.tools.restoration.watchData(request, loader, data, onlyTest=False)
Show data of format obtained from testRates

Parameters

- request (fore_name,back_name)
- loader image loader from path
- data dictionary containing requests (each request is a key).
- onlyTest if True show only test results, else also show stitched images and some other data.

Returns request data.

RRtoolbox.tools.segmentation module

RRtoolbox.tools.segmentation.find_optic_disc (img, P) find optic disk in image

Parameters

- img BGR image
- P gray image

Returns optic_disc, Crs, markers, watershed

RRtoolbox.tools.segmentation.getBrightAlpha (backgray, foregray, window=None)

Get alpha transparency for merging foreground to background gray image according to brightness.

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Parameters

- backgray background image. (as float)
- **foregray** foreground image. (as float)
- window window used to customizing alfa. It can be a binary or alfa mask, values go from 0 for transparency to any value where the maximum is visible i.e a window with all the same values does nothing. A binary mask can be used, where 0 is transparent and 1 is visible. If not window is given alfa is not altered and the intended alfa is returned.

Returns alfa mask

RRtoolbox.tools.segmentation.get_beta_params (P) automatically find parameters for bright alpha masks.

Parameters P – gray image

Returns beta1,beta2

RRtoolbox.tools.segmentation.layeredfloods(img, gray=None, backmask=None, step=1, connectivity=4, weight=False)

Parameters

- img -
- gray -
- · backmask -
- step -
- connectivity -
- weight -

Returns

RRtoolbox.tools.segmentation.retina_markers_thresh(P)

Retinal markers thresholds to find background, retinal area and optic disc with flares based in the histogram

Parameters P - gray image

Returns min,b1,b2,max

RRtoolbox.tools.segmentation.retinal_mask(img, biggest=False, addalpha=False)

Parameters

- img -
- biggest -
- addalpha -

Returns

RRtoolbox.tools.segmentation.retinal_mask_simple(img, parameters=(10, 30, None))

RRtoolbox.tools.selectors module

RRtoolbox.tools.selectors.entropy (imlist, loadfunc=None, invert=False)
Entropy function modified from:

Yan Liu, Feihong Yu, An automatic image fusion algorithm for unregistered multiply multi-focus images, **Optics** Communications, Volume 341, 15 April 2015,

```
Pages
               101-113,
                              ISSN
                                         0030-4018,
                                                         http://dx.doi.org/10.1016/j.optcom.2014.12.015.
     (http://www.sciencedirect.com/science/article/pii/S0030401814011559)
         Parameters imlist – list of path to images or arrays
         Returns sortedD,sortedImlist,D,fns
     where sortedD is the ranking of the Entropy test, D = [D0,...,DN] D0>DN sortedImlist is fins sorted to
         match sortedD, D is the list of the absolute difference between entropy and the root mean square, D =
         IE-RMS
class RRtoolbox.tools.selectors.entropyPlot(images, win='Entropy tests', func=None)
     Bases: RRtoolbox.lib.plotter.plotim
     Plot entropy test
     getData(im)
     getImage(im)
     keyfunc()
     nextim()
     previousim()
     selectlist(imlist)
RRtoolbox.tools.selectors.hist_comp(imlist, loadfunc=None, method='correlation')
     Histogram comparison
         Parameters imlist – list of path to images or arrays
         Returns comparison
RRtoolbox.tools.sticher module
RRtoolbox.tools.sticher.stich(**opts)
Module contents
1.2 Submodules
1.3 RRtoolbox.core module
RRtoolbox.core.f(*args, **kwargs)
```

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class RRtoolbox.core.rrbox (*args)

RRtoolbox.core.tools(instance, modules)
RRtoolbox.core.tools2(instance, modules)

Bases: object

asift(fn)

1.4 RRtoolbox.run module

1.5 RRtoolbox.shell module

```
exception RRtoolbox.shell.NoParserFound
     Bases: exceptions. Exception
RRtoolbox.shell.getDocParamLines(doc)
     gets each parameter line from reStructured doc.
         Parameters doc - documentation
         Returns lines
RRtoolbox.shell.getDocParameters(doc)
     gets param and comment from reStructured doc.
         Parameters doc - documentation
         Returns list of (param, comment) items.
class RRtoolbox.shell.shell
     generateParser(func)
     getParser(func)
     parse (func, args=None, namespace=None)
    parser_fastplt()
    parser_loadFunc()
RRtoolbox.shell.shell_processor(commands)
RRtoolbox.shell.shell_processor_parser(syslist, flags='', longopts=('feature=', 'nnn='))
```

1.6 Module contents

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