Phil/LPS 31 Introduction to Inductive Logic Lecture 15

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Topics

- ▶ Part 1: Decision Problems under Ignorance
 - Ordinal Utilities
 - Dominance Principles
 - Maximin
- Part 2: Decision Problems under Information
 - Cardinal Utilities
 - ► Expected Utility and Risk
 - Principles of Rational Choice under Information

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- Decision problems under information are also known as decision problems under certainty or risk. The relevant sense of "certainty" here is that one is certain about the probability distribution of states. So one can compute the risk associated with taking a decision.

Part 2: Decision Problems under Ignorance

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- ▶ Here we see that 4 > 3 > 2. So this utility function respects the preference ordering of the acts. 4, 3 and 2 are ordinal utilities.

▶ Suppose now that the host serves chicken, S₂. You think that if the host serves chicken you'd much rather bring white wine than either red wine or rosé. Assume also that if you can't find white wine at Trader Joe's you'd much rather bring rosé than red wine.

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- Exercise.
 - 1 Write down the preference ordering on the Acts.
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 - 3 Verify that your utility function respects your preference ordering.

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 - (4) Provide no information about the strength of preferences.

Making Decisions with Ordinal Utilities

From the previous exercises we obtain the following desirability table for acts based on our ordinal utility function.

3	
Fish	Chicken
4	5
2	1
3	3
	4

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 - Decide on the basis of the maximin principle.

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 - Does the strong dominance principle imply the weak dominance principle?

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 - How would you decide in this case?

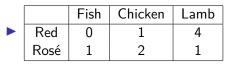
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- ► The maximin principle focuses on the worst possible outcome of each alternative act. Essentially, we're asking what's the worst that can happen?
- According to this principle, one should MAXimise the MINimal value obtainable with each act. If the worst possible outcome of one alternative is better than that of another, then the former should be chosen.



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•	Red	0	1	4
	Rosé	1	2	1

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 - ▶ What is the worst possible outcome for A_2 ? How about A_3 ?
 - ▶ Does $A_3 \succeq A_2$?
 - Why would an agent choose A_3 ?
- ► There are other principles of rational choice in the context of decisions under ignorance. But we shall not cover them in this introductory course. The book by Martin Peterson An Introduction to Decision Theory is highly recommended for this.

Part 1: Decision Problems under Information

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- ➤ This means that the agent can also calculate the expected value of functions of these states, namely, consequences of an act.
- However, not just any concept of utility will do. We have seen that because ordinal utilities cannot be added or multiplied, we cannot use them to calculate expected values. Further ordinal utilities do not quantify the strength of preference, they simply respect the ordering of our preferences.

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 - (3) From (2) we can calculate expected utilities using cardinal utilities.
 - (4) Provide information about the strength of preferences.

► The expected utility of an act is the weighted average of the consequences of that act where the weights on the consequences are determined by the probability distribution on states.

$$U(A) = u(A|S_1)P(S_1) + u(A|S_2)P(S_2) + \dots + u(A|S_n)P(S_n)$$

= $\sum_{i=1}^{n} u(A|S_i)P(S_i)$

- ► The expected utility of an act is the weighted average of the consequences of that act where the weights on the consequences are determined by the probability distribution on states.
- Suppose that the states in a decision problem are listed as $\{S_1, S_2, \ldots, S_n\}$ and that there is a probability distribution on the states that assigns them probabilities $\{P(S_1), P(S_2), \ldots, P(S_n)\}$. Then the expected utility of an act A

$$U(A) = u(A|S_1)P(S_1) + u(A|S_2)P(S_2) + \dots + u(A|S_n)P(S_n)$$

= $\sum_{i=1}^{n} u(A|S_i)P(S_i)$

- The expected utility of an act is the weighted average of the consequences of that act where the weights on the consequences are determined by the probability distribution on states.
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► In other words, take the utility of that action given each state of the world multiplied by the probability that the state obtains and sum everything up

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► Consider the dinner party example again. This time the entries are cardinal utilities.

Chicken

Fish White 4

Red Rosé

Consider the dinner party example again. This time the entries

are cardinal utilities.

	Fish	Chicken
White	4	5
Red	2	1
Rosé	3	3

► Exercise. Suppose you know that there are even odds that the host will serve fish or chicken calculate the expected value of A_1 , A_2 and A_3

➤ The risk is of an act is just like the expected value of the act, except that we're using a loss function to assign loss values to possible consequences of an act.

$$R(A) = L(A|S_1)P(S_1) + L(A|S_2)P(S_2) + \dots + L(A|S_n)P(S_n)$$

= $\sum_{i=1}^{n} u(A|S_i)P(S_i)$

- ➤ The risk is of an act is just like the expected value of the act, except that we're using a loss function to assign loss values to possible consequences of an act.
- More specifically, the weighted average of the unfavorable consequences of an act where the weights on the consequences are determined by the probability distribution on states.

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- ➤ The risk is of an act is just like the expected value of the act, except that we're using a loss function to assign loss values to possible consequences of an act.
- More specifically, the weighted average of the unfavorable consequences of an act where the weights on the consequences are determined by the probability distribution on states.
- Suppose that the states in a decision problem are listed as $\{S_1, S_2, \ldots, S_n\}$ and that there is a probability distribution on the states that assigns them probabilities $\{S(S_1), P(S_2), \ldots, P(S_n)\}$. Let the loss of an act A_i given a state S_i be denoted by $L(A_i \mid S_i)$. Then the risk of an act A denoted by R(A) is given by:

$$R(A) = L(A|S_1)P(S_1) + L(A|S_2)P(S_2) + \dots + L(A|S_n)P(S_n)$$

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- ► The risk is of an act is just like the expected value of the act, except that we're using a loss function to assign loss values to possible consequences of an act.
- More specifically, the weighted average of the unfavorable consequences of an act where the weights on the consequences are determined by the probability distribution on states.
- Suppose that the states in a decision problem are listed as $\{S_1, S_2, \ldots, S_n\}$ and that there is a probability distribution on the states that assigns them probabilities $\{S(S_1), P(S_2), \ldots, P(S_n)\}$. Let the loss of an act A_i given a state S_i be denoted by $L(A_i \mid S_i)$. Then the risk of an act A denoted by R(A) is given by:

$$R(A) = L(A|S_1)P(S_1) + L(A|S_2)P(S_2) + \dots + L(A|S_n)P(S_n)$$

= $\sum_{i}^{n} u(A|S_i)P(S_i)$

► Consider President Biden's *hypothetical* loss function.

	Deal	No Deal
Invoke ^c	0	-10
Invoke	-1	-1

Consider President Biden's hypothetical loss function.

	Deal	No Deal
Invoke ^c	0	-10
Invoke	-1	-1

▶ Exercise. Suppose you that President Biden knows that the odds are 3:5 that a deal will be reached with the U.S. House of Representative Majority Leader Kevin McCarthy. What is the risk of the possible acts that Biden can take to avoid having the Federal Government default on its debt?

► The cardinal principle (you see what I did there?) of decision problems under risk is the principle of maximizing expected utility if you're using a cardinal utility function.

- ► The cardinal principle (you see what I did there?) of decision problems under risk is the principle of maximizing expected utility if you're using a cardinal utility function.
- ➤ This means that in any decision problem, choose the act that maximizes expected utility with respect to your probability distribution on states.

► For the following exercise, refer to the following desirability table.

	Fish	Chicken	Lamb
White	3	4	1
Red	2	1	4
Rosé	3	4	4

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	Fish	Chicken	Lamb
White	3	4	1
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▶ Suppose you know that because of rising tariffs on fish imports from Canada and recent shortages of lamb, you host is likely to serve chicken with probability 0.8, fish with probability 0.15 and lamb with probability 0.05. What wine should you choose to bring to the dinner party according to the principle of maximizing expected utility?

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- Let us call a person risk averse if given a choice between two actions with risk, they will tend to choose the act that is less risky. That is, they choose to minimize the risk.
- ► There is an on-going debate about what the implications of risk for rationality. See Lara Buchak's *Risk and Rationality*.

Consider President Biden's modified *hypothetical* loss function modified in such a way that President Biden does nothing.

	Deal	No Deal
Invoke	-1	-1
Do Nothing	0	-10

Exercise. Suppose you that President Biden knows that the odds are 3:5 that a deal will be reached with the U.S. House of Representative Majority Leader Kevin McCarthy. What act would you advice President Biden to take in order to avoid having the Federal Government default on its debt?