

Efficient Maximum Defective Clique Search on Real-world Networks

ABSTRACT

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1 INTRODUCTION

2 PROBLEM DEFINITION

Consider an undirected and unweighted graph $G = (V, E)$, where V and E represent the sets of vertices and edges of the graph G , respectively. Let $n = |V|$ and $m = |E|$ denote the number of vertices and edges in G , respectively. For a vertex v of G , we define $N_v(G)$ as the set of neighbors of v in G , i.e., $N_v(G) = \{u \in V | (u, v) \in E\}$. The degree of v in G is the cardinality of $N_v(G)$, denoted by $d_v(G) = |N_v(G)|$. Given a vertex subset S of G , we let $G(S) = (S, E_S)$ be the subgraph of G induced by the subset S , where $E_S = \{(u, v) \in E | u \in S, v \in S\}$. In accordance with [9], the k -defective clique of G is defined as follows.

Definition 1 (k -defective clique). Given a graph G and a non-negative integer k , the subgraph $G(S)$ induced by the vertex set $S \subseteq V$ is a k -defective clique if there exists at least $\binom{|S|}{2} - k$ edges in $G(S)$.

For simplicity, in the rest of this paper, we directly refer the set S as the k -defective clique of G . A k -defective clique S of G is considered maximal if there does not exist any other k -defective clique S' of G such that $S \subset S'$. Furthermore, a k -defective clique S of G is designated as maximum if its size is largest among all maximal k -defective clique of G , where the size of k -defective clique S is defined as the number of vertices it contains. Then, two useful properties of the k -defective clique are described below, which are very helpful in designing the algorithms.

Property 1 (Hereditary [1]). Given a k -defective clique S of G , every subset of S is also a k -defective clique of G .

The hereditary property (Property 1) of a k -defective clique simplifies the maximality check process. Specifically, if a k -defective clique S of G is not the maximal, it implies the existence of a vertex in $V \setminus S$ that can form a larger k -defective clique when combined with S . Thus, this property forms the foundation for the design of our algorithms.

Property 2 (Small Diameter [2]). Given a k -defective clique S of G , the diameter of $G(S)$ is no larger than 2 if $|S| \geq k + 2$.

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Algorithm 1: Graph coloring

Input: The graph $G = (V, E)$
Output: The color number of each vertex in V

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1  Compute the degeneracy ordering of vertices in  $G$ ;
2   $\tau \leftarrow$  a positive number;  $\omega \leftarrow 0$ ;
3  for each  $v \in V$  in reverse order with the degeneracy ordering do
4       $color(v) \leftarrow 0$ ;
5      while  $\exists u \in N_v(G)$  with  $color(v) = color(u)$  do
6           $color(v) \leftarrow color(v) + 1$ ;
7      /* Recoloring */
8      if  $color(v) \geq \tau$  then
9          for  $c = 0$  to  $\tau - 1$  do
10             if  $|\{u \in N_v^+(G) | color(u) = c\}| = 1$  then
11                 Let  $u$  be the vertex in  $N_v^+(G)$  with  $color(u) = c$ ;
12                 if  $\exists c' \in [0, \tau - 1]$  s.t.  $\nexists w \in N_u(G)$  with
13                      $color(w) = c'$  then
14                      $color(u) \leftarrow c'$ ;  $color(v) \leftarrow c$ ;
15                     break;
14   $\omega \leftarrow \max\{\omega, color(v)\}$ 
15 return  $\omega$ ;
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Property 2 not only implies the internal density-connected nature (having a diameter of two with a size no less than $k + 2$) of the k -defective clique but also provides an acceleration for enumerating relatively-large maximal k -defective cliques [?]. However, the problem of enumerating maximal k -defective clique often suffers from excessively long computational times, as there can be an exponential number of maximal k -defective cliques compared to the number of vertices. To address this challenge, in this paper, we aim to the problem of finding a maximum k -defective clique of G , and the formal problem definition is shown below.

Problem definition. Given a graph G and a non-negative integer k , the goal of this paper is to compute a maximum k -defective clique of G .

2.1 Existing Solutions

As shown in [6, 8], the problem of finding the maximum k -defective clique of a given graph G is NP-complete, thus there is no algorithm with polynomial-time to solve this problem. To our knowledge, there are several solutions have been developed to address the problem [1, 3, 4, 6], which mainly consist of two categories.

Russian doll search based algorithms. The first algorithm for finding the maximum k -defective clique is developed by Trukhanov et al. [6], which is based on a Russian doll search technique [7]. The key idea of such an algorithm is summarized as follows. Let $\{v_1, v_2, \dots, v_n\}$ be a total ordering for the vertices in V of G . The problem of finding the maximum k -defective clique from a graph G can be divided into a series of n nested subproblems. Each subproblem represents finding the maximum k -defective clique that

includes v_i in the subgraph $G(\{v_i, v_{i+1}, \dots, v_n\})$, where $v_i \in V$. Then, the algorithm starts from $i = n$ and iterates down to $i = 1$, processing each subproblem along the way. The final maximum solution is obtained when $i = 1$. In addition, the algorithm employs the branch-and-bound technique, which can be accelerated using the pre-knowledge when solving the i -th subproblem. Specifically, based on the upper bound on the size of the maximum k -defective clique that has been detected by j -th subproblem (where $j > i$), it is possible to determine whether a larger k -defective clique is also likely to contain the vertex v_j . Recently, such the Russian doll search algorithm has also been improved by Gschwind et al. [4] based on some auxiliary information prior computed.

Branch-and-bound based algorithms. In order to enhance the efficiency of finding the maximum k -defective clique in a graph G , several new enumeration algorithms have been developed [1, 3] based on a branch-and-bound technique [5]. Notably, Chen et al. [1] propose a new branching rule and employ some reduction techniques to improve the search for the maximum k -defective clique. This proposed branching rule prioritizes the vertices that have non-neighbors within the current k -defective clique S to expand S , thus ensuring a maximum of $k + 1$ subbranches in each recursive call. Furthermore, the authors establish that the worst-case time complexity of this technique for finding maximum k -defective clique is bounded by $O(P(n)\gamma_k^n)$, where $P(n)$ is a polynomial function related to n and γ_k is a real-number less than 2. To further reduce unnecessary computations, an improved branch-and-bound enumeration algorithm is presented in [3] based on some newly developed branch pruning techniques. To our knowledge, this algorithm represents the current state-of-the-art for solving the problem of finding the maximum k -defective cliques.

Nevertheless, these existing solutions still suffer from significant computational time when applied to real-world graphs. This issue arises primarily due to the insufficient tightening of bounding techniques in these algorithms, which leads to a proliferation of unnecessary computations during the branch-and-bound procedure. Additionally, the efficiency of the employed branching rules in swiftly identifying the maximum k -defective clique is also limited. Furthermore, it is noteworthy that the worst-case time complexity of most existing solutions remains bounded by $O(P(n)2^n)$, and only one approach [1] achieves a worst-case time complexity of $O(P(n)\gamma_k^n)$, where $\gamma_k < 2$. However, even for small values of k , the value of γ_k is nearly equal to 2. For instance, as reported in [1], when $k = 2$ and 3, the corresponding values of γ_k are 1.996 and 1.999, respectively, which are unacceptably high for the problem of finding the maximum k -defective clique in graph G .

Hence, there is a pressing need to develop more efficient algorithms to finding the maximum k -defective clique of real-world graphs. In the subsequent sections, we first introduce some new bounding techniques and subsequently present our approaches that enable the efficient discovery of the maximum k -defective clique.

3 BOUNDING TECHNIQUES

Let κ and $\kappa(C)$ denote the sizes of maximum k -defective clique in graph G and the subgraph $G(C)$, respectively. In this section, we start to explore both typical and novel upper bounds for κ and $\kappa(C)$,

which play crucial role in accelerating the computations related to the maximum k -defective clique.

Degree-based upper bound. The first upper bound is simply derived from the degree information of vertices in G , and the detailed result is presented the following lemma.

Lemma 1. For a given graph G , the size of the maximum k -defective clique of G containing a vertex $v \in V$ is no larger than $d_v(G) + k + 1$. Consequently, we can establish $\kappa \leq \max_{v \in V} d_v(G) + k + 1$.

PROOF. This lemma is clearly established based on the definition of k -defective clique. \square

Core-based upper bound. Next, we introduce a tighter upper bound for κ and $\kappa(C)$ based on a well-established concept of k -core [?]. The formal definition of k -core is provided as follows.

Definition 2. Given a graph G , the subgraph $G(C)$ of G induced by the vertex set C is a k -core of G if $d_v(C) \geq k$ for every v in C .

Let C_k represent k -core subgraph of G . The core number of a vertex v in G , denoted by $core_v(G)$, is defined as the maximum value of k such that v belongs to the k -core subgraph C_k of G , i.e., $core_v(G) = \max\{k \mid v \in C_k\}$. Based on this concept, we can derive a core number based upper bound, as shown below.

Lemma 2. For a given graph G , the size of the maximum k -defective clique in G containing a vertex $v \in V$ is bounded by $core_v(G) + k + 1$. Consequently, we can establish $\kappa \leq \max_{v \in V} core_v(G) + k + 1$.

PROOF. It is evident that any k -defective clique S of G is also a $(|S| - k - 1)$ -core subgraph of G , as per the definitions provided in Definition 1 and Definition 2. Consequently, if a k -defective clique S in G includes a vertex v , it follows that the size of such a k -defective clique is bounded by $core_v(G) + k + 1$. Thus, this lemma is established. \square

To compute the core number for each vertex in a given graph G , the traditional peeling technique described in [?] can be employed. This technique follows an iterative process where the vertices are sequentially removed from the remaining subgraph based on their degree, in a non-decreasing order starting from $k = 0$ up to $k = n$. The core number of a vertex is assigned to the current value of k at the time of its removal. The total time-consuming for this technique is bounded by $O(m)$, indicating its high efficiency in generating the core number based upper bound.

Color-based upper bound. Furthermore, we present a method to refine the upper bound for κ and $\kappa(C)$ using a graph coloring technique. Here we begin by providing the fundamental definition of graph coloring below.

Definition 3. Given a graph G , the graph coloring is to assign a color number for each vertex v of G , denoted by $color_v(G)$, such that any two adjacent vertices have different colors. Formally, for every $(u, v) \in E$, it should hold that $color_v(G) \neq color_u(G)$.

Denote by ω and $\omega(C)$ the number of distinct colors in G and the subgraph $G(C)$ of G induced by C , respectively. Based on the concept of graph coloring, we can establish the following upper bound for κ and $\kappa(C)$.

Lemma 3. Given a coloring of the graph G and a subset C within G , the size of the maximum k -defective clique in G and $G(C)$ can be bounded by $\omega + k$ and $\omega(C) + k$, respectively.

PROOF. Given a k -defective clique S in G , we can partition it into two subsets, namely S_1 and S_2 , satisfying $S_1 \cap S_2 = \emptyset$ and $S_1 \cup S_2 = S$. We assume that every vertex in S_1 has a different color than the other vertices in S_1 , while every vertex in S_2 shares the same color with at least one vertex in S_1 . Formally, for each $v \in S_1$ (resp. $u \in S_2$), it is true that $\{w \in S_1 \mid \text{color}_v(G) = \text{color}_w(G)\} = \emptyset$ (resp. $\{w \in S_1 \mid \text{color}_u(G) = \text{color}_w(G)\} \neq \emptyset$). Based on the definition of graph coloring, it is evident that if two vertices u and v in G have the same color (i.e., $\text{color}_v(G) = \text{color}_u(G)$), there exists no edge connecting them (i.e., $(u, v) \notin E$). Consequently, we can deduce that $|S_2| \leq k$, as having more than k vertices in S_2 would violate the definition of k -defective clique. Moreover, the number of distinct colors in G is denoted as ω , it follows that $|S_1| \leq \omega$. Thus, the size of the maximum k -defective clique in G is bounded by $\omega + k$, establishing this lemma. \square

Lemma 3 highlights the importance of finding a smaller value for ω in order to achieve a better upper bound. However, it is worth noting that determining the smallest value of ω for graph coloring is a computationally challenging problem, known to be NP-hard [?]. Thus, many heuristic approaches have been extensively investigated to address graph coloring [?]. In this paper, we adopt a widely used degeneracy ordering to color the graphs. Specifically, the degeneracy ordering [?] is defined as follows.

Definition 4. Given a graph G with the vertex set V , the degeneracy ordering is a permutation (v_1, v_2, \dots, v_n) of vertices in V such that for each vertex v_i , its degree is smallest in the subgraph of G induced by $\{v_i, v_{i+1}, \dots, v_n\}$.

The degeneracy ordering, similar to the method for computing the k -core of a graph, can be acquired using the peeling technique [?]. In this method, the vertex removal ordering aligns with the degeneracy ordering, and it can be executed with a time complexity of $O(m)$. Then, we can systematically assign colors to each vertex v_i of graph G in a reverse order of the degeneracy ordering, commencing from $i = n$ and concluding at $i = 1$. Consequently, the upper bound based on graph coloring can be computed efficiently in $O(m)$ time.

Denote by δ the maximum core number of G , i.e., δ is the maximum value of k such that there exist a non-empty k -core in G . When combining with Lemma 1-3, we then have the following relations.

Lemma 4. Given a graph G , let κ be the size of the maximum k -defective clique of G . We can derive that $\kappa \leq \omega + k \leq \delta + k + 1 \leq d_{\max} + k + 1$, where d_{\max} is the maximum degree of vertices in G .

PROOF. It is evident that $d_{\max} \geq \delta$ and $d_{\max} \geq \omega - 1$ are clearly established. Thus, here we only prove the correctness of $\omega \leq \delta + 1$. Assume that the vertex ordering $\{v_1, v_2, \dots, v_n\}$ corresponds to the degeneracy ordering. Based on this ordering, we can obtain that for each vertex v_i , the degree of v_i is the smallest among all vertices in the subgraph $G(v_i, v_{i+1}, \dots, v_n)$ induced by the set v_i, v_{i+1}, \dots, v_n , where $i \in [1, n]$. Denote by $d_{v_i}^+$ the degree of v_i in $G(\{v_i, v_{i+1}, \dots, v_n\})$. It can be seen that the subgraph

$G(\{v_i, v_{i+1}, \dots, v_n\})$ also forms a $d_{v_i}^+$ -core, implying that $d_{v_i}^+ \leq \delta$. Moreover, once all vertices in $\{v_{i+1}, v_{i+2}, \dots, v_n\}$ have been colored, when it comes to coloring the vertex v_i , we can see that the color number assigned to v_i is at most $d_{v_i}^+ + 1$. Consequently, we establish $\omega \leq \delta + 1$. Hence, the lemma is proven. \square

The following example illustrates the above mentioned upper bounds.

Example 1. ...

Improved color-based upper bound. We observe that the proposed technique for obtaining the upper bound is still not sufficiently tight. For example, let us consider a graph G depicted in Fig. ??, which has been colored using the degeneracy ordering. Given a subset of vertices $C = \dots$ in G , it becomes apparent that the number of distinct colors utilized in the subgraph $G(C)$ is **. According to Lemma 3, we deduce that the upper bound for $\kappa(C)$ is *** when $k = 3$, which exceeds the size of the vertex set C . Furthermore, it is evident that the subgraph $G(C)$ itself is not a k -defective clique of G when $k = **$, implying that the upper bound for $\kappa(C)$ can be tightened to 5. To address this concern, we next develop a new color-based upper bound.

Given a vertex subset S of G , let $\kappa(S, C)$ be the size of the maximum k -defective clique in $G(S \cup C)$ that includes all vertices in S . We define $\bar{d}_v(S)$ as the number of non-neighbors of vertex v in S , given by $\bar{d}_v(S) = |S \setminus N_v(S)|$. Additionally, we define $c_v(S)$ as the number of other vertices in S that share the same color with vertex v , denoted as $c_v(S) = |\{u \in S \setminus \{v\} \mid \text{color}_v(G) = \text{color}_u(G)\}|$. With these definitions in place, we state the following lemma.

Lemma 5. Consider a graph G and a non-maximal k -defective clique S of G . If there exists a vertex set $D \in V \setminus S$ that can form a larger k -defective clique with S , then for each vertex $v \in D$, there are at least $\bar{d}_v(S) + c_v(D)$ non-neighbors of v in $G(S \cup D)$.

PROOF. This lemma is clearly established since each vertex in $D \setminus \{v\}$ that has the same color as v is not the neighbor of v . \square

Based on Lemma 4, we then have the following upper bound for $\kappa(S, C)$.

Lemma 6. Denote by $\bar{d}(S)$ the total number of missing edges in $G(S)$, i.e., $\bar{d}(S) = \frac{1}{2} \sum_{v \in S} (|S| - d_v(S) - 1)$. Given two sets S and C , let D be the largest subset of C satisfying $\sum_{v \in D} (\bar{d}_v(S) + \frac{1}{2} c_v(D)) \leq k - \bar{d}(S)$. When computing the maximum k -defective clique containing S in the subgraph $G(S \cup C)$, we can state that $\kappa(S, C) \leq |S| + |D|$.

PROOF. Given the subset D of C , we observe that there are at least $\frac{1}{2} \sum_{v \in D} c_v(D)$ missing edges in $G(D)$, as any pair of vertices with the same color in D must not have an edge between them. Moreover, each vertex v in D has $\bar{d}_v(S)$ non-neighbors in S . Consequently, when the set D is incorporated into the current k -deficient clique S , there will be a minimum of $\sum_{v \in D} (\bar{d}_v(S) + \frac{1}{2} c_v(D))$ additional missing edges. Given that D is the largest subset of C satisfying $\sum_{v \in D} (\bar{d}_v(S) + \frac{1}{2} c_v(D)) \leq k - \bar{d}(S)$, we can conclude that the size of maximum k -defective clique containing S in the subgraph $G(S \cup C)$ is at most $|S| + |D|$. This completes the proof of the Lemma. \square

Example 2. ...

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1  /* Supposing that each vertex in  $S \cup C$  is colored based
2     on the degeneracy ordering */
3  1  $D \leftarrow \emptyset$ ;  $s \leftarrow$  the missing edges in  $G(S)$ ;
4  2 while  $C \neq \emptyset$  do
5  3    $v \leftarrow$  a vertex in  $C$  with minimum  $\bar{d}_v(S) + c_v(D)$ ;
6  4   if  $s + \bar{d}_v(S) + c_v(D) > k$  then break;
7  5    $s \leftarrow s + \bar{d}_v(S) + c_v(D)$ ;
8  6    $D \leftarrow D \cup \{v\}$ ;  $C \leftarrow C \setminus \{v\}$ ;
9  7 return  $|S| + |D|$ ;

```

Based on Lemma 6, we can derive an algorithm, as shown in Algorithm 2, to compute the upper bound of $\kappa(S, C)$. This algorithm employs a heuristic approach to determine the largest subset D of C . Initially, the algorithm sets D as an empty set (line 1). Then, it iteratively selects a vertex v in C with the smallest value of $\bar{d}_v(S) + c_v(D)$ and adds it to the current subset D (lines 2-6). Once v is selected, the missing edges in $G(S \cup D)$ increase by $\bar{d}_v(S) + c_v(D)$, and v is moved from C to D (lines 5-6). The algorithm terminates and outputs $|S| + |D|$ as the upper bound of $\kappa(S, C)$ when either C becomes empty or the missing edges in $G(S \cup D)$ would violate the definition of a k -defective clique (lines 2 and 4). The following Theorem presents the correctness of Algorithm 2.

THEOREM 3.1. *Algorithm 2 correctly computes the upper bound of $\kappa(S, C)$.*

PROOF. On the contrary, we assume that there exist a subset D' of C with $|D'| > |D|$ that satisfies $\sum_{v \in D'} (\bar{d}_v(S) + \frac{1}{2} c_v(D')) \leq k - \bar{d}(S)$. Denote by $D_1 = D' \setminus D$. It is easy to see that there must exist two vertices $v \in D$ and $u \in D_1$ satisfying $\bar{d}_v(S) + c_v(D \setminus \{v\}) > \bar{d}_u(S) + c_u(D \setminus \{v\})$, or D is the largest result. If $color_v(G) = color_u(G)$, we obtain that $\bar{d}_v(S) > \bar{d}_u(S)$ and the vertex u must contain in D if $v \in D$ according to our algorithm. If $color_v(G) \neq color_u(G)$, we have $\bar{d}_v(S) + c_v(D) = \bar{d}_v(S) + c_v(D \cup \{u\})$ and the vertex u will be also prior to push into D compared to v . However, we note that $u \notin D$, which is contradictory. Thus, we proved this lemma. \square

THEOREM 3.2. *The time complexity of Algorithm 2 is bounded by $O(kn + \overline{m})$, where \overline{m} is the number of missing edges in $G(C)$.*

PROOF. Initially, each vertex v in C needs to be sorted with the size of $\bar{d}_v(S)$, which takes $O(kn)$ times using a bin sort. Moreover, when a vertex v in C is pushed into D , each vertex in $C \setminus D$ that have the same color with v , which takes at most $O(\bar{d}_v(C))$ time. Thus, the total time consumes of lines 2-6 in Algorithm 2 requires $O(\bar{m})$ time. Thus, this theorem is proved. \square

Note that by preprocessing of lemma 1-3, the subgraph $G(S \cup C)$ is usually relatively dense for real-world graphs. This means that the missing edges in $G(C)$ cannot be very large. Thus, Algorithm 2 is very time efficiency in computing the upper bound of $\kappa(S, C)$, which is further evidenced by our practical experiments (in Sec. ??).

```

Input: The graph  $G = (V, E)$  and a parameter  $k \geq 0$ 
Output: A near maximum  $k$ -defective clique  $S^*$  in  $G$ 
1  $v \leftarrow$  the vertex in  $V$  with the maximum core number;  $S^* \leftarrow \{v\}$ ;
2 Expanding  $S^*$  with vertices in  $N_v^2(G)$  in a degree ordering;
3  $G \leftarrow (|S^*| - s)$ -core of  $G$ ;
4  $V \leftarrow$  a total order of vertices in  $G$  (degree, degeneracy, and color);
5 for  $i = n$  to 1 s.t.  $\text{core}(v_i) \geq |S^*| - s$  do
6    $S \leftarrow \{v_i\}$ ;  $C_1 \leftarrow N_{v_i}^+(G)$ ;  $C_2 \leftarrow \emptyset$ ;
7   Removing all vertices in  $C_1$  with degree less than  $|S^*| - 1 - s$  in
      $G(C_1)$ ;
8   for each  $v_j \in N_{v_i}^{=2}(G)$  s.t.  $j > i$  do
9     if  $d_{v_j}(C_1) \geq |S^*| - s$  then
10       $C_2 \leftarrow C_2 \cup \{v_j\}$ 
11 while  $S \cup C_1 \cup C_2$  is not an  $s$ -defective clique do
12    $v \leftarrow$  a vertex in  $C_1 \cup C_2$  with maximum core number;
13    $S \leftarrow S \cup \{v\}$  and remove all vertices in  $C_1 \cup C_2$  that
     cannot form a larger  $s$ -defective clique with  $S \cup \{v\}$ ;
14   if  $\exists u \in C_1 \cup C_2$  with  $d_u(S \cup C_1) < |S^*| - s$  then
15      $\text{Remove } u \text{ from } C_1 \cup C_2$ ;
16   if  $\exists u \in S$  with  $d_u(S \cup C_1) < |S^*| - s$  then
17      $C_1 \leftarrow \emptyset$ ;  $C_2 \leftarrow \emptyset$ ; break;
18 if  $|S^*| < |S \cup C_1 \cup C_2|$  then  $S^* \leftarrow S \cup C_1 \cup C_2$ ;
19 return  $S^*$ ;

```

4 THE PROPOSED ALGORITHMS

In this section, we

Russian doll search.

THEOREM 4.1. *Let $\{v_1, v_2, \dots, v_n\}$ be an ordering of vertices in V . Assume that $|S^*|$ is the maximum size of the k -defective clique in $G(\{v_i, v_{i+1}, \dots, v_n\})$. Then the maximum size of the k -defective clique in $G(\{v_{i-1}, v_i, v_{i+1}, \dots, v_n\})$ is at most $|S^*| + 1$.*

THEOREM 4.2 (NEW PIVOTING). *Let $\mathcal{B}(S, C)$ be the recursive call to find the maximum k -defective clique in $G(S \cup C)$. Let v be a vertex in C with $\bar{d}_v(S) \leq 1$, then the maximum k -defective clique either contains v or a vertex in $C \setminus N_v(G)$.*

[illegible]

Pruning branches.

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Input: The graph  $G = (V, E)$  and a parameter  $k$ 
Output: The maximum  $k$ -defective clique  $S^*$  of  $G$ 
1 A heuristic search to compute a near maximum  $k$ -defective clique
    $S^*$  of  $G$ ;
2  $G \leftarrow (|S^*| - s)$ -core of  $G$ ;
3  $V \leftarrow$  a total order of vertices in  $G$  (degree, degeneracy, and color);
4 for  $i = n$  to 1 s.t.  $\text{core}(v_i) \geq |S^*| - s$  do
   if  $|S^*| < k + 1$  then  $\text{Branch}(\{v_i\}, V^+ \setminus \{v_i\}, \text{true})$ ;
5 else
6      $S \leftarrow \{v_i\}$ ;  $C_1 \leftarrow N_{v_i}^+(G)$ ;  $C_2 \leftarrow \emptyset$ ;
7     Remove vertices in  $C_1$  with degree less than  $|S^*| - s$  in
         $G(C_1)$ ;
8     for each  $v_j \in N_{v_i}^{=2}(G)$  s.t.  $j > i$  do
9         if  $d_{v_j}(C_1) > |S^*| - s$  then  $C_2 \leftarrow C_2 \cup \{v_j\}$ ;
10    Color vertices in  $G(S \cup C_1 \cup C_2)$  (Recoloring
         $\tau = |S^*| - s + 1$ );
11     $\text{Branch}(S, C_1 \cup C_2, \text{true})$ ;

```

(1) If $u \in C$ with $\bar{d}_u(S) \geq 1$ (or $w \in C$ with $\bar{d}_w(S) \geq 1$), $\kappa(S, C) \leq \kappa(S \cup \{v\}, C \setminus \{v\})$.
(2) If $\bar{d}_v(S) = 1$ and $u \in C$, $\kappa(S, C) \leq \max\{\kappa(S \cup \{v\}, C \setminus \{v\}), \kappa(S \cup \{u\}, C \setminus \{v\} \cap N_u(G))\}$.
(3) If $u, w \in C$ with $(u, w) \notin E$, $\kappa(S, C) \leq \kappa(S \cup \{v\}, C \setminus \{v\})$.
(4) If $u, w \in C$ with $(u, w) \in E$, $\kappa(S, C) \leq \max\{\kappa(S \cup \{v\}, C \setminus \{v\}), \kappa(S \cup \{u\}, C \setminus \{v\} \cap N_u(G) \cap N_w(G))\}$.

[illegible]

```

1  if  $falg = false$  then return;
2  if  $S \cup C$  is a  $k$ -defective clique then
3    if  $|S \cup C| > |S^*|$  then  $S^* \leftarrow S \cup C$ ;  $falg \leftarrow false$ ;
4    return;
5  if  $upper\ bound \leq |S^*|$  then return;
6   $C_1 \leftarrow \{v \in C | \bar{d}_v(S) \leq 1\}$ ;  $C_2 \leftarrow C \setminus C_1$ ;
7  for each  $v \in C_1$  s.t.  $\bar{d}_v(S \cup C) = 1$  do
8     $S \leftarrow S \cup \{v\}$ ;  $C \leftarrow C \setminus \{v\}$ ;  $C_1 \leftarrow C_1 \setminus \{v\}$ ;
9  if  $\exists v \in C_1$  s.t.  $\bar{d}_v(S \cup C) = 2$  then
10     $C \leftarrow \{u \in C | S \cup \{u, v\} \text{ is a } k\text{-defective clique}\}$ ;
11     $Branch(S \cup \{v\}, C \setminus \{v\}, falg)$ ;
12  else if  $\exists v \in C_1$  s.t.  $\bar{d}_v(S \cup C) = 3$  then
13     $Branch(S \cup \{v\}, C \setminus \{v\}, falg)$ ;
14    Denote by  $D \leftarrow C \cap \bar{N}_v(G)$ ;
15    if  $|D \cap C_1| = 2$  then
16      Let  $u, w$  be the vertices in  $D \cap C_1$ ;
17      if  $\bar{d}_u(S) + \bar{d}_w(S) = 0$  and  $(u, w) \in E$  then
18         $Branch(S \cup \{u, w\}, C \setminus \{v\} \cap N(\{u, w\}), falg)$ ;
19    else if  $\bar{d}_v(S) = 1$  and  $|D \cap C_1| = 1$  then
20      Let  $u$  be the vertex in  $D \cap C_1$ ;
21      if  $\bar{d}_u(S) = 0$  then
22         $Branch(S \cup \{u\}, C \setminus \{v\} \cap N(\{u\}), falg)$ ;
23  else if  $C_2 \neq \emptyset$  then
24    Let  $v$  be the vertex in  $C$  with maximum  $\bar{d}_v(S)$ ;
25     $Branch(S \cup \{v\}, C \setminus \{v\}, falg)$ ;
26     $Branch(S, C \setminus \{v\}, falg)$ ;
27  else
28    Let  $v$  be the vertex in  $C_1$  with maximum degree;
29    for each  $u \in C \setminus N_v(G)$  s.t.  $\bar{d}_v(S \cup C) > 3$  do
30       $C_1 \leftarrow C_1 \setminus \{u\}$ ;  $C \leftarrow C \setminus \{u\}$ ;
31       $Branch(S \cup \{u\}, C, falg)$ ;
32  Run lines 12-22;

```

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[1] Xiaoyu Chen, Yi Zhou, Jin-Kao Hao, and Mingyu Xiao. 2021. Computing maximum k -defective cliques in massive graphs. *Comput. Oper. Res.* 127 (2021), 105131.

Algorithm 6: Branch and reduction search

Input: The graph $G = (V, E)$ and a parameter k

Output: The maximum k -defective clique S^* of G

```
1 A heuristic search to compute a near maximum  $k$ -defective clique
   $S^*$  of  $G$ ;
2  $G \leftarrow (|S^*| - s)$ -core of  $G$ ;
3  $V \leftarrow$  a total order of vertices in  $G$  (degree, degeneracy, and color);
4 while  $|V| > |S^*|$  do
5    $v \leftarrow$  a vertex in  $V$  with the minimum degree;
6   if  $|S^*| < k + 1$  then  $\text{Branch}(\{v\}, V \setminus \{v\})$ ;
7   else
8     if  $d_v(G) \leq |S^*| - s$  or  $cn(N_v(G)) < |S^*| - s$  then
9       Remove  $v$  from  $V$  and  $G$ ; continue;
10     $S \leftarrow \{v_i\}$ ;  $C_1 \leftarrow N_v(G)$ ;  $C_2 \leftarrow \emptyset$ ;
11    Remove vertices in  $C_1$  with degree less than  $|S^*| - s$  in
       $G(C_1)$ ;
12    for each  $u \in N_v^{>2}(G)$  do
13      if  $d_u(C_1) > |S^*| - s$  then  $C_2 \leftarrow C_2 \cup \{u\}$ ;
14    Color vertices in  $G(S \cup C_1 \cup C_2)$  (Recoloring
       $\tau = |S^*| - s + 1$ );
15     $\text{Branch}(S, C)$ ;
16  Remove  $v$  from  $V$  and  $G$ ;
```

Table 1: Real-world graph datasets.

Datasets	n	m	d_{\max}	δ
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- [8] Mihalis Yannakakis. 1978. Node- and Edge-Deletion NP-Complete Problems. In *STOC*. 253–264.
- [9] Haiyuan Yu, Alberto Paccanaro, Valery Trifonov, and Mark Gerstein. 2006. Predicting interactions in protein networks by completing defective cliques. *Bioinform.* 22, 7 (2006), 823–829.