

C++20 Coroutines

What's next?

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Introduction



Introduction

Quick refresh about the coroutines.

Missing coroutines parts

RVO for the `co_await`

`return_value` or/and `return_void`

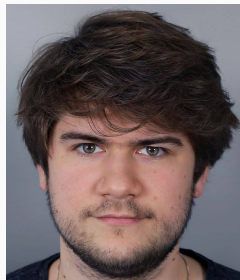


Time is rather tight.
Please hold your questions till the end.



Dawid Pilarski

- Senior Software Developer in TomTom
- Member of the ISO/JTC1/SC22/WG21
- Member of the PKN KT (programming languages)
- C++ blog writer



Quick refresh about the
coroutines.



Subroutine Is a sequence of program instructions that performs a specific task, packaged as a unit.

Function Is a subroutine

Coroutine Is generalization of the function.



Function can be:

- called
- returned from



Coroutine can be:

- called
- returned from
- suspended



Coroutine can be:

- called
- returned from
- suspended
- resumed from



Coroutine can be:

- called
- returned from
- suspended
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- created

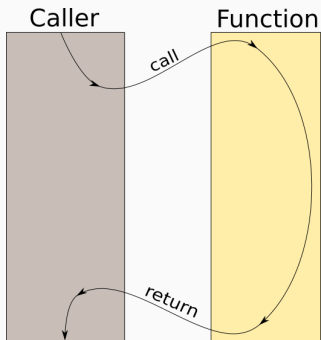


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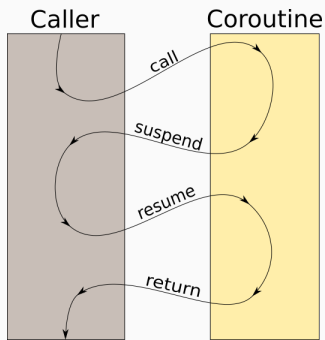
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- created
- destroyed



Function's flow:



Coroutine flow:





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- C++ provides keywords **only**.
- **Developer must implement** what keywords do.

This means:

- Implementation of `promise_type` (~6 functions)
- Implementation of the `co_await` keyword (~3 functions)

You need to remember to implement on average **9 functions**.



```
// returned-type    name        arguments  
//|-----| /-----| /-----|  
generator<int> fibonacci (int from_value);
```

- Whether the function is a coroutine depends on [it's definition](#).



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- Whether the function is a coroutine depends on *it's definition*.
- If function is a coroutine it's *return type must support coroutines*.



Type supports coroutines **if it has `promise_type`**.

`promise_type` can be:

- member of the class
- member of the specialization of the `coroutine_traits<returned_type>`



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 get_return_object();
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Promise_type controls coroutine's behavior.

- `awaitable initial_suspend();`
- `awaitable final_suspend();`
- `return_type`
`get_return_object();`
- `void unhandled_exception();`
- suspension at the beginning
- suspension at the end
- how to create
`return_type`
- handling unhandled exception



`Promise_type` is also responsible for keyword's actions:

- `co_return V;`
- `p.return_value(V);`



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- `co_return;`
- `p.return_value(V);`
- `p.return_void();`



Promise_type is also responsible for keyword's actions:

- `co_return V;`
- `co_return;`
- `co_yield V;`
- `p.return_value(V);`
- `p.return_void();`
- `co_await p.yield_value();`



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- have `awaiter` operator `co_await` defined, or



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 - `await_suspend(coroutine_handle<P>) returning`
 - `void`
 - `bool`
 - another `coroutine_handle`
 - `T await_resume()`

Missing coroutines parts





RAII - Resource Acquisition Is Initialization.

what does it mean in practice?

Release the resources in the destructor.



How do coroutines differ?



How do coroutines differ?

```
task<std::vector<char>>
read_file(const path& file_path){

    auto opened_file = co_await async_open(path);
    auto content = co_await async_read(opened_file);
    co_await async_close(opened_file);

    co_return content;
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No RAII to close the file!

Possible leak when `async_read` throws

Add solution



Consider following scenario:

```
generator<std::string> lines(const path& file_path) {  
    ifstream stream(file_path.string());  
    std::string line;  
    while(getline(stream, line)){  
        co_yield line;  
    }  
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```
for(const auto& line : lines("myfile.txt")){  
    if(starts_with(line, "string I am looking for"))  
        break;  
}
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issues:

- at the `break;` we are destroying coroutine
- not all lines from file might be consumed
- proper cleanup needs to be performed anyway on `coroutine_handle::destroy()`



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(on destroy

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async_generator<std::string> lines(const path& file_path) {  
    auto opened_file = co_await async_open(file_path);  
    while(getline(stream, line)){  
        co_yield co_await async_read_line(opened_file);  
    }  
  
    co_await async_close(opened_file);  
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↑ cleanup



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on early destroy - *no cleanup*

on loop finished

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async_generator<std::string> lines(const path& file_path) {  
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        // remember to resume coroutine before destroy!  
        auto cancellation_token =  
            co_yield co_await async_read_line(opened_file);  
        if(cancellation_token){  
            goto clean_up;  
        }  
    }  
  
    clean_up:  
    co_await async_close(opened_file);  
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}
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- make `co_await` create it's own scope.
- create special function in the awaiter : `~operator co_await`
- `~operator co_await` gets co-awaited at the end of the scope
- instead of `destroy()` you will invoke `set_done()`



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- Currently it's difficult to correctly implement asynchronous generators
 - coroutine bodies
 - coroutine type, because we cannot simply destroy the coroutine
- In the space of asynchronous operations we have got no RAII idiom
- With adoption of the proposal it will get better

RVO for the `co_await`



RVO - Return Value Optimization.

Allows to avoid unnecessary copy or move construction of the values returned from the function.



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For example:

```
std::vector<int> foo(){  
    return {1,2,3,4,5};  
}  
  
// ...  
  
// no copy or move construction  
// invoked  
auto _ = foo();
```




regular function

```
std::vector<int> foo(){  
    return {1,2,3,4,5};  
}
```

transformed by compiler into:

```
void foo(std::vector<int>* ptr){  
    new(ptr) std::vector<int>  
        {1,2,3,4,5};  
}
```



expression

```
co_await event;
```

transformed by compiler into:

```
{  
    auto&&awaiter = transform(event);  
    if(!awaiter.await_ready()){  
        <coroutine suspend>  
        awaiter.await_suspend();  
    }  
    <coroutine resume>;  
    awaiter.await_resume();  
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expression

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`await_suspend`

coroutine gets
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`await_suspend`

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2. On

`await_resume`

result is returned

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1. Remove
 `await_resume`
 function.

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1. Remove `await_resume` function.
2. `await_suspend` will will create return result
3. Remove `await_ready` function.

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2. `await_suspend` will will create return result
3. Remove `await_ready` function.



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- `set_exception(exception_ptr)`

On coroutine resumption the compiler will generate code to check whether the exception was saved with `set_exception` and will rethrow it when needed.

Example of the `yield_value`



```
template <typename T> class task<T>::promise_type{
// ....

template <typename U> requires ConvertibleTo<U, T>
void return_value(U&& value){
    handle.set_value<T>(std::forward<U>(value));
}

template <typename... Args>
    requires Constructible<T, Args...>
void return_value(std::in_place_construct<Args&&...>
    ctor_args){
    handle.set_value_from<T>(ctor_args);
}

};
```

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    handle.set_value<T>(std::forward<U>(value));
}

template <typename... Args>
    requires Constructible<T, Args...>
void return_value(std::in_place_construct<Args&&...>
                  ctor_args){
    handle.set_value_from<T>(ctor_args);
}

};
```

How do compiler know the result of the `co_await`?



With removal of the `await_ready` the compiler no longer knows about the `co_await` returned type.

We will need to guide the compiler. The proposal P1663R0 proposes to add member `await_result_type` to the Awaiter.



pros

- very simplified awaiter concept

cons



pros

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- savings in CPU cycles

cons



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 - Avoiding unnecessary move construction

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- removing `await_ready` makes `co_await` always suspend the coroutine (even if not needed)



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- removing `await_ready` makes `co_await` always suspend the coroutine (even if not needed)
- a need to support RVO manually (with the help of `construct_in_place`)



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- removing `await_ready` makes `co_await` always suspend the coroutine (even if not needed)
- a need to support RVO manually (with the help of `construct_in_place`)
- proposed RVO does not consider synchronous coroutines - only `co_await` keyword.

return _value or/and
return _void



right now it's not possible to implement both in the same scope.

- `return_value()`
- `return_void()`



right now it's not possible to implement both in the same scope.

- `return_value()`
- `return_void()`

Why would we even need that?



```
task<int> foo(){  
    co_return 42;  
}
```

```
task<void> start(){  
    std::cout << (co_await foo()) << std::endl;  
    // implicit co_return;  
}
```




```
task<int> foo(){  
    co_return 42; ← return_value(42);  
}
```

```
task<void> start(){  
    std::cout << (co_await foo()) << std::endl;  
    // implicit co_return;  
}
```



```
task<int> foo(){  
    co_return 42; ← return_value(42);  
}
```

```
task<void> start(){  
    std::cout << (co_await foo()) << std::endl;  
    // implicit co_return;  
} ← return_void()
```



```
template <typename T>
struct task<T>::promise_type{
    // ...
    void return_void()
        requires std::is_same<T, void>{}

    template <typename U>
    void return_value(U&& val)
        requires not std::is_same<T, void>{}
}
```



```
template <typename T>
struct task<T>::promise_type{
    // ...
    void return_void()
        requires std::is_same<T, void>{}

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template <typename T>
struct task<T>::promise_type{
    // ...
    void return_void()
        requires std::is_same<T, void>{}

    template <typename U>
    void return_value(U&& val)
        requires not std::is_same<T, void>{}
}
```

But that's not the way it works.

How implementors have to implement it?



```
template <typename T>
struct task<T>::promise_type{
    //...
    void return_value(){
        //...
    }
};
```

How implementors have to implement it?



```
template <typename T>
struct task<T>::promise_type{
    //...
    void return_value(){
        //...
    }
};
```

```
template <>
struct task<void>::promise_type{
    //...
    void return_void(){
        //...
    }
};
```



What's the tail recursive coroutines?

```
task<int> bar(){  
    co_return 42;  
}
```

```
task<int> foo(){  
    co_return co_await bar();  
}
```




What's the tail recursive coroutines?

```
task<int> bar(){  
    co_return 42;  
}
```

```
task<int> bar(){  
    co_return 42;  
}
```

```
task<int> foo(){  
    co_return co_await bar();  
}
```

```
task<int> foo(){  
    co_return bar();  
}
```

tail call / no tail call

How does tail call work?



First, how does regular call work?

foo

How does tail call work?



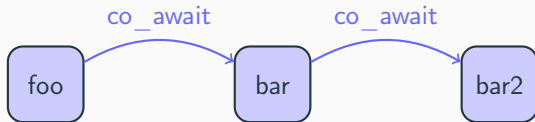
First, how does regular call work?



How does tail call work?



First, how does regular call work?



How does tail call work?



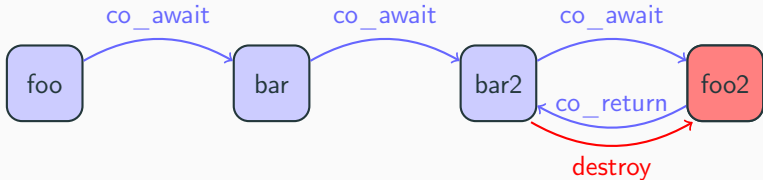
First, how does regular call work?



How does tail call work?



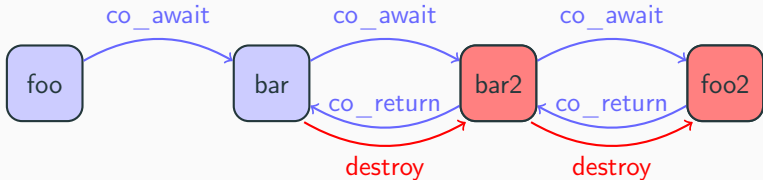
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How does tail call work?

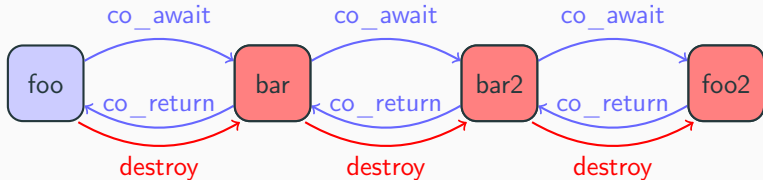


First, how does regular call work?





First, how does regular call work?



Conclusion:

- At peak 4 **coroutine frames** had to be allocated
- Only after returning to the calling coroutine, called one can be destroyed

How does tail-call work?



In case of tail-call we first destroy the coroutine and then call another one.

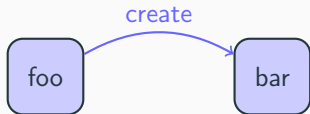


foo

How does tail-call work?



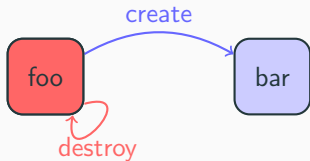
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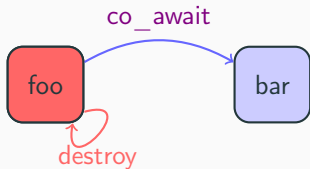
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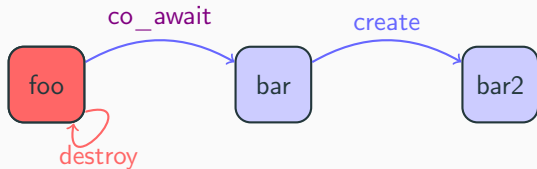
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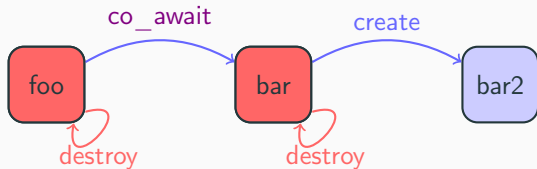
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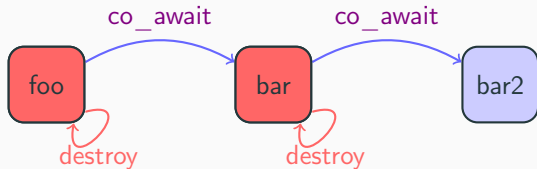
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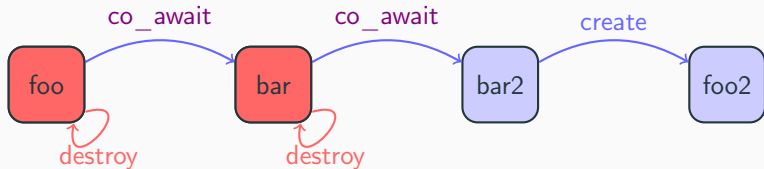
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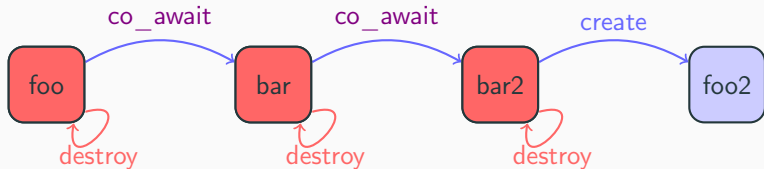
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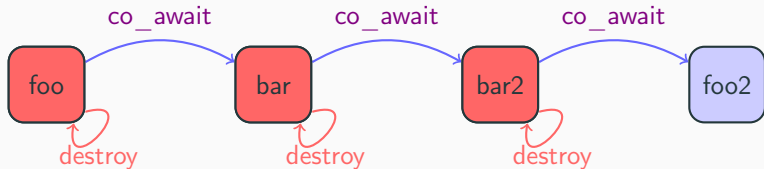
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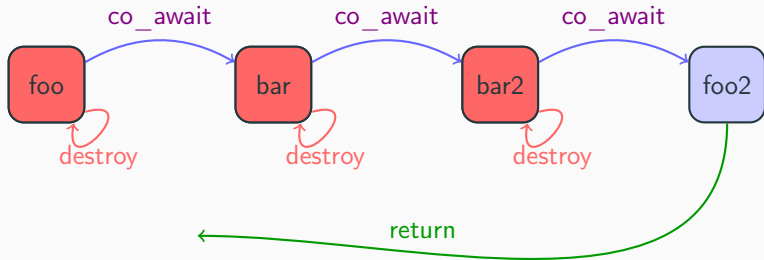
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How does tail-call work?



In case of tail-call we first destroy the coroutine and then call another one.



Thank you for your attention!

Special thank you! goes to:



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- Lewiss Baker

for making coroutines



- Lewiss Baker's Assymetric transfer blog
- newest C++ draft
- My blog - blog.panicsoftware.com
- James McNellis - "Introduction to the C++ Coroutines"
- Gor Nishanov - any video about the coroutines
- Toby Allsopp - "Coroutines: what can't they do?"



Questions?