C++20 Coroutines

What's next?

Dawid Pilarski

dawid.pilarski@panicsoftware.com blog.panicsoftware.com dawid.pilarski@tomtom.com

Introduction

Agenda



Introduction

Quick refresh about the coroutines.

Missing coroutines parts

RVO or the co_await

Questions...



Time is rather tight. Please hold your questions till the end.



Dawid Pilarski

- Senior Software Developer in TomTom
- Member of the ISO/JTC1/SC22/WG21
- Member of the PKN KT (programming languages)
- C++ blog writer



Quick refresh about the coroutines.



Subroutine Is a sequence of program instructions that performs a specific task, packaged as a unit.

Function Is a subroutine

Coroutine Is generalization of the function.



Function can be:

- called
- returned from



- called
- returned from
- suspended



- called
- returned from
- suspended
- resumed from



- called
- returned from
- suspended
- resumed from
- created

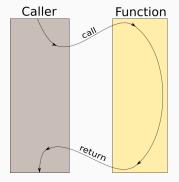


- called
- returned from
- $\bullet \ \ \text{suspended}$
- resumed from
- created
- destroyed

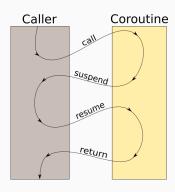
Coroutine flowchart



Function's flow:



Coroutine flow:





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- Implementation of the co_await keyword (~3 functions)



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- C++ provides keywords only.
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This means:

- Implementation of promise_type (~6 functions)
- Implementation of the co_await keyword (~3 functions)

You need to remember to implement on average 9 functions.

Coroutine declaration



```
// returned-type name arguments
///-----
generator<int> fibonacci (int from_value);
```

• Whether the function is a coroutine depends on it's definition.

Coroutine declaration



```
// returned-type name arguments
///-----
generator<int> fibonacci (int from_value);
```

- Whether the function is a coroutine depends on it's definition.
- If function is a coroutine it's return type must support coroutines.

Promise_type



Type supports coroutines if it has promise_type.

promise_type can be:

- member of the class
- member of the specialization of the coroutine_traits<returned_type>

Promise type



Promise_type controls coroutine's behavior.

```
• awaitable initial_suspend();
```

• suspension at the beginning

Promise_type



Promise type controls coroutine's behavior.

- awaitable initial_suspend();
- awaitable final_suspend();

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- suspension at the end

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- awaitable final_suspend();
- return_type
 get_return_object();

- \bullet suspension at the beginning
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- how to create return_type

Promise_type



Promise_type controls coroutine's behavior.

- awaitable initial_suspend();
- awaitable final_suspend();
- return_type
 get_return_object();
- void unhandled_exception();

- \bullet suspension at the beginning
- \bullet suspension at the end
- how to create return_type
- handling unhandled exception

Keywords and promise_type



Promise_type is also responsible for keyword's actions:

```
co_return V;
```

• p.return_value(V);

Keywords and promise type



Promise_type is also responsible for keyword's actions:

- co_return V;
- co_return;

- p.return_value(V);
- p.return_void();

Keywords and promise type



Promise_type is also responsible for keyword's actions:

- co_return V;
- co_return;
- co_yield V;

- p.return_value(V);
- p.return_void();
- co_await p.yield_value();



In order to support co_await expressions, the argument (awaitable) must:

• have awaiter operator co_await defined, or



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 - another coroutine_handle

co await



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 - T await_resume()

Missing coroutines parts

Type erasure



asynchronous RAII



RVO or the co_await

What is RVO?



RVO - Return Value Optimization.

Allows to avoid unnecessary copy or move construction of the values returned from the function.



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Allows to avoid unnecessary copy or move construction of the values returned from the function.

For example:

```
std::vector<int> foo(){
  return {1,2,3,4,5};
}

// ...

// no copy or move construction
// invoked
auto _ = foo();
```

RVO on regular functions



```
regular function
std::vector<int> foo(){
  return {1,2,3,4,5};
}
```

transformed by compiler into:

Why RVO is not possible with co await



```
expression
                              transformed by compiler into:
co_await event;
                            auto&& awaiter = transform(event);
                            if(!awaiter.await_ready()){
                              <coroutine suspend>
                              awaiter.await_suspend();
                            }
                            <coroutine resume>;
                            awaiter.await_resume();
                          }
```

Why RVO is not possible with co await



}

Why RVO is not possible with co await



```
expression
                               transformed by compiler into:
co_await event;
                             auto&& awaiter = transform(event);
 1. On
                             if(!awaiter.await_ready()){
    await suspend
                               <coroutine suspend>
    coroutine gets
                               awaiter.await_suspend();
    executed
 2. On
                             <coroutine resume>;
    await resume
                             awaiter.await_resume();
    result is returned
                          }
```



Remove await_resume function.



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```
{
  auto&& awaiter = transform(event);
  <coroutine suspend>
  awaiter.await_suspend();
  <coroutine resume>;
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```



Two additional functions in the coroutine_handle are needed.

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- set_value_from(Arg...)
- set_exception(exception_ptr)

On coroutine resumption the compiler will generate code to check whether the exception was saved with set_exception and will rethrow it when needed.



```
template <typename T> class task<T>::promise_type{
// ....
  template <typename U> requires ConvertibleTo<U, T>
  void return_value(U&& value){
    handle.set_value<T>(std::forward<U>(value));
  }
  template <typename... Args>
            requires Constructible<T, Args...>
  void return_value(std::in_place_construct<Args&&...>
                    ctor_args){
    handle.set_value_from<T>(ctor_args);
  }
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```

How do compiler know the result of the co_await?



With removal of the await_ready the compiler no longer knows about the co_await returned type.

We will need to guide the compiler. The proposal P1663R0 proposes to add member await_result_type to the Awaiter.



pros

cons

• very simplified awaiter concept



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- savings in CPU cycles



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 removing await_ready makes co_await always suspend the coroutine (even if not needed)



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- very simplified awaiter concept
- savings in CPU cycles
 - Avoiding unnecessary move construction
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 - no temporary variable created
 - allocated coroutine state is smaller

- removing await_ready makes co_await always suspend the coroutine (even if not needed)
- a need to support RVO manually (with the help of construct_in_place)
- proposed RVO does not consider synchronous coroutines - only co_await keyword.

return value [and|or] return void



Thank you for your attention!

Special thank you! goes to:



- Gor Nishanov
- Lewiss Baker

for making coroutines

Bibliography and further reading



- Lewiss Baker's Assymetric transfer blog
- newest C++ draft
- My blog blog.panicsoftware.com

- James McNellis "Introduction to the C++
 Coroutines"
- Gor Nishanov any video about the coroutines
- Toby Allsopp "Coroutines: what can't they do?"

Questions?



 ${\sf Questions?}$