Futuristic Error Handling

Error handling in C++ today and tomorrow

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Why am I here?

Why should we bother with error handling?

Recommendable error handling mechanism

Which error mechanism would you choose?

There exist two common strategies for error handling:

- error codes?
- exceptions?

Who am I?

- Senior Software Developer in TomTom
- Member of the ISO/JTC1/SC22/WG21
- C++ blog writer and C++ evangelist



Error codes nowadays

What are the error codes?

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- error code is an enumerated message,
- that corresponds to the status of a specific software application.
- They are typically used to identify faults, such as those in faulty hardware, software, or incorrect user input

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if(open_status == SQLITE_OK){
    // make use of opened database
} else if( open_status == SQLITE_CANTOPEN_ISDIR ) {
    // handle the error
}
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- take the error callback

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- std::terminate()
- take the error callback
- propagate the error to the caller

Error codes - propagation

Propagation

```
void foo_bar(int& errc /*...*/){
  errc = foo();
  // ...
  errc = bar();
  // ...
}
```

Propagation

```
void foo_bar(int& errc /*...*/){
errc = foo();
// ...
errc = bar();
// ...
}
```

Error translation

```
void foo_bar(foo_bar_errc errc&){
  foo_errc ferrc = foo();
  errc = translate_foo(ferrc);
  // ...
  bar_errc berrc = bar();
  errc = translate_foo(berrc);
}
```

C-style error codes summary

So we can see serious disadvantages (except for obvious advantages):

• success path same as error path

C-style error codes summary

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- boiler plate code

C-style error codes summary

So we can see serious disadvantages (except for obvious advantages):

- success path same as error path
- boiler plate code
- cluttering code with translations

Error codes - modern approach

Standard library support - what do we need?

- A way to define new error codes
- A way to distinguish domain of the error codes

Standard library support - what we get?

We get three new major types:

• std::error_code

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- std::error_category

Standard library support - what we get?

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- std::error_code
- std::error_category
- std::error_condition

std::error_code in action

```
std::error_code errcode;
is_regular_file("non_existent_directory", errcode);
std::cout << errcode << std::endl;
std::cout << errcode.value() << std::endl;
std::cout << errcode.message() << std::endl;
std::cout << errcode.category().name() << std::endl;</pre>
```

```
$ generic:2
$ 2
$ No such file or directory
$ generic
```

Acting upon error

```
std::error_code errcode;
is_regular_file("non_existent_file", errcode);

if(errcode == errc::no_such_file_or_directory){
    // creating a file
}
```

Let's define our own error code

Steps to create own error code:

• define custom enum with error codes

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 - inform the world about new error condition enum

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 - make conversion function from new error code to error condition

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- create custom error category (or use existing one)
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- define custom error condition
 - define error condition enum
 - inform the world about new error condition enum
 - make conversion function from new error code to error condition
- enjoy!

Error codes -

defining custom error codes

```
enum class open_file_error {
   SUCCESS, // zero means success
   NO_SUCH_FILE_OR_DIRECTORY,
   FILE_IS_DIRECTORY,
   LACK_OF_RESOURCES,
   FILE_BROKEN,
   NO_PERMISSIONS
};
```

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```

Step 2 - inform the world about new error code type

```
namespace std{
  template <> struct
  is_error_code_enum<open_file_error> : std::true_type{};
}
```

```
struct open_file_error_domain : std::error_category {
  const char *name() const noexcept override;
  std::string message(int errc) const override;
};
```

```
const char* open_file_error_domain::name() const noexcept{
  return "Open File Error";
}
```

```
std::string open_file_error_domain::message(int errc) const{
  if(errc < 0 or errc > 4) return "UNKNOWN ERROR";
  switch (static_cast<map_access_error>(errc)){
    case open_file_error::SUCCESS:
      return "Success.";
    case open_file_error::NO_SUCH_FILE_OR_DIRECTORY:
      return "File does not exist.";
    case open_file_error::FILE_IS_DIRECTORY:
      return "Cannot open directory.";
    case open_file_error::LACK_OF_RESOURCES:
      return "No available file descriptor";
    case open_file_error::FILE_BROKEN:
      return "File is corrupted."
    case open_file_error::NO_PERMISSIONS:
      return "Missing permissions to open the file."
```

```
std::string open_file_error_domain::message(int errc) const{
  if(errc < 0 or errc > 4) return "UNKNOWN ERROR";
  switch (static_cast<map_access_error>(errc)){
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      return "File does not exist.";
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    case open_file_error::NO_PERMISSIONS:
      return "Missing permissions to open the file."
```

Step 4 - factory function

```
namespace std{
  template <typename ErrorCode>
  error_code::error_code(typename std::enable_if<
                                   is_error_code_enum<
                                       ErrorCode>
                                   ::value, ErrorCode>
                          ::type errcode) noexcept
             : error_code(make_error_code(errcode))
 {}
```

Step 4 - factory function

```
std::error_code make_error_code(open_file_error errc){
  return {static_cast<int>(errc), open_file_error_domain};
}
```

```
enum class library_error_condition : int {
  SUCCESS,
  WRONG_ARGUMENT,
  OS_ERROR,
  PERMISSIONS_ERROR
};
```

```
bool library_error_domain::equivalent(
          const std::error_code &errc, int condition)
                                       const noexcept{
  switch (static_cast<library_error>(condition)){
    case library_error::SUCCESS:
      if(errc.value() == 0)
        return true;
    case library_error::WRONG_ARGUMENT:
      if(errc.category().name() == map_access_domain().name())
        return true;
   // other cases
  return false;
```

Step 6 - Enjoy - real life example

```
std::error_code errcode;
auto route = calculate_route({}, {}, {}, errcode);
if(!errcode)
  return route;
std::cout << errcode.category().name() << " : " <<</pre>
             errcode.message() << std::endl;
if(errcode == calculate_route_error::MAP_ERROR)
  reinstall_map();
else if (errcode == calculate_route_error::COULD_NOT_FIND_PATH)
  inform_user_no_path_found();
else if (errcode == calculate_route_error::WRONG_ARGUMENTS)
  std::terminate();
```

Step 6 - Enjoy - real life example

```
route calculate_route(point a, point b, route_options options,
                      std::error_code& errc){
  auto map_database = database(errc);
  if (errc) return {};
  auto a_handle = map_database.find(a, errc);
  if(errc) return {};
  auto b_handle = map_database.find(b, errc);
  if(errc) return {};
  route result_route = find_path(a_handle, b_handle,
                                 options, errc);
  if(errc) return {};
  return result_route;
```

Error codes - summary

Error codes summary

Pros

- Performance
 - speed
 - small (occupied memory)
 - · speed predictability
 - memory occupation predictability
 - C compatibility

Cons

- business logic cluttering
- massive amount of boilerplate code
- template magic in case of std::error_code

Exceptions to the rescue (?)

Brief look at the example

```
try{
   auto route = calculate_route(/*arguments*/);
} catch(map_error& err){
   // logic
} catch(path_not_found& err){
   // logic
} /* catch(std::invalid_argument){
} */
```

Brief look at the example

```
route calculate_route(point a, point b,
                      route_options options){
  auto map_database = database();
  auto a_handle = map_database.find(a);
  auto b_handle = map_database.find(b);
  route result_route = find_path(a_handle, b_handle, options);
  return result_route;
```

Defining custom exception

```
class map_error : public std::runtime_error{};
```

Dark side of the exceptions

• Still translation of exceptions is needed

Dark side of the exceptions

- Still translation of exceptions is needed
- For performance related reasons about 50% of projects have disabled exceptions

C++ - zero overhead rule

What is zero overhead?

• language features can introduce overhead

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- "you don't pay for what you don't use"

What is zero overhead?

- language features can introduce overhead
- "you don't pay for what you don't use"
- if you use a feature it should be as afficient as handcoded version.

Exceptions not to the rescue

Exceptions break the zero overhead rule.

But why?

Exceptions - how do they work?

Approaches towards implementation

Two major kinds of implementation:

additional data added to the frame stack

Approaches towards implementation

Two major kinds of implementation:

- additional data added to the frame stack
- additional data added to someplace on the heap

Implementations' consequences

implementation	performance		
	without throwing	with throwing	
frame-based	overhead	fast	
table-based	almost no overhead	slow	

No matter the strategy binaries with exceptions enabled result in a big binary.

Exceptions summary

Pros

- differentiated error and success paths
- automagical error propagation
- little/no boilerplate code

Cons

- Performance
 - slow
 - not deterministic speed
 - not deterministic storage occupation
 - not compatible with C
 - not usable in any safety standards (e.g. MISRA)

Possible future of error handling.

Perfect error handling mechanism

feature	exceptions	std::error_code
distinct error path	yes	no
distinct success path	yes	no
unhandled error propagation	yes	no
unhandled error is visible	no	yes
uncluttered business logic	yes	no
RTTI required	yes	no
deterministic space/time occupation	no	yes
time cost == return	no	yes
C compatibility	no	no

Key idea for improvement

Key ideas

• Let's use the return channel to return the std::error

Let's call those static exceptions

Key idea for improvement

Key ideas

- Let's use the return channel to return the std::error
- Let the compiler generate boilerplate code for error propagation

Let's call those static exceptions

What is std::error

- size of error_code is explicitly defined
- has same properties as std::error_code
- implements trivially relocatable semantics

How to use return channel for std::error

Static exceptions example

```
string f() throws {
  if (flip_a_coin()) throw arithmetic_error::something;
  return "xyzzy"s + "plover";
string g() throws { return f() + "plugh"; }
int main() {
  trv {
    auto result = g();
    cout << "success, result is: " << result;</pre>
  } catch(error err) {
    cout << "failed, error is: " << err.error();</pre>
```

Compiler's support in handling errors

```
int f1() throws;
int f2() throws;

int main(){
    // return f1() + f2(); // error
    try return f1() + f2(); // ok, covers both
    return try f1()+ f2();
}
```

Cool! But what about C compatibility

It is possible, that C will be ABI compatible with static exceptions! This implies:

- Exceptions could be thrown from C++, passed through C and catched again in C++
- We could handle C++ exceptions in C
- ullet We could handle C exceptions in C++

Short story about C language

```
_Either(int, std_error) somefunc(int a){ fixme
  return a > 5 ? _Expected(a) : _Unexpected(a);
// ...
_Either(int, std_error) ret = somefunc(a);
if(ret)
  printf("%d\n", ret.expected);
else
  printf("%f\n", ret.unexpected);
```

Static exceptions summary

feature	static exceptions
distinct error path	yes
distinct success path	yes
unhandled error propagation	yes
unhandled error is visible	yes
uncluttered business logic	yes
RTTI required	no
deterministic space/time occupation	yes
time cost == return	yes
C compatibility	maybe

Possible issue

We will end up having 3 ways to handle error codes:

- dynamic exceptions
- static exceptions
- old style error codes

std::error type can be treated as a next-gen std::error_code type.

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Bibliography

This presentation wouldn't be possible without:

- Herb Sutter author of the proposal (code examples, exception features taken from his proposal) - p0709r1
- Andrzej Krzemiński for his blog about error codes and error conditions - Your own error code

Thank you

Thank you for your attention!

Questions?

The END

Thanks for attention!