

# Error handling in C++

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- 1 Current state of error handling
  - Error codes
- 2 Introducing `std::expected`
  - Exceptions
- 3 New exception model
  - How can new exception handling look like

# Plan

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# Error handling and performance

There exist two common strategies for error handling:

- error codes
- exceptions

# Error codes - example fopen

```
/* fopen example */  
#include <stdio.h>  
int main ()  
{  
    FILE * pFile;  
    pFile = fopen ("myfile.txt","w");  
    if (pFile!=NULL)  
    {  
        //do stuff  
    } else {  
        //how do I know if everything is fine?  
  
        switch(errno){  
            //  
        }  
    }  
    return 0;  
}
```

# Error code - better approach

```
// declaration
int sqlite3_open( const char *filename,
                  sqlite3 **ppDb /* OUT: SQLite db handle */);

//usage
int open_status = sqlite3_open(/* ... */);
if(open_status == SQLITE_OK){
    // make use of opened database
} else if( open_status == SQLITE_CANTOPEN_ISDIR ) {
    // handle the error
}
```

## further improvements:

- enums
- error code taken as reference

# C++ 11 approach to the error codes

There are 3 types, that C++ 11 added to support error codes.

- `std::error_code`
- `std::error_condition`
- `std::error_category`

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# Going further

# But don't forget about exceptions

And so there are also exceptions.

How could things look like with exceptions:

```
#include <stdio.h>
int main ()
{
    try {
        FILE* pFile = fopen ("myfile.txt","w");
        //stuff here
    }
    catch(std::exception& e){
        //handle error
    }
    //so stuff
    return 0;
}
```

# "types" of exceptions

We can divide implementation of exceptions into 2 types:

- table-based implementation
- frame based implementation

# "You don't pay for what you don't use"

## table based exceptions

optimized for scenarios when usually exceptions are not thrown

## frame based exception

optimized for scenarios when exceptions are thrown often

## binary size

no matter which implementation is chosen the binary size grows significantly even when exceptions are not used.

# Let's stick to error codes or provide dual API

People from standardization committee tried to do that and failed :)

Example of such failure can be functions from filesystem library

```
directory_iterator& operator++();  
directory_iterator& increment( std::error_code& ec );
```

# Let's stick to error codes or provide dual API

People from standardization committee tried to do that and failed :)

Example of such failure can be functions from filesystem library

```
directory_iterator& operator++();  
directory_iterator& increment( std::error_code& ec );
```

The increment function even though is meant to return errors through `std::error_code` can return some of the errors through exceptions.

# Error codes continued

```
A::A(){           // a constructor here  
    /* some initialization happening */  
    /* but whoops an error occurs, what now?*/  
}
```

# Error codes continued

```
A::A(){ //a constructor here
    /* some initialization*/
    /* but whoops an error occurs */

    throw error;
}
```



# Error codes continued

```
A::A(){ //a constructor here
    /* some initialization*/
    /* but whoops an error occurs */

    throw error;
}
```

```
A::A(){ //a constructor here
    /* some initialization */
    /* but whoops an error occurs */
}

bool A::IsValid(){
    // was init successful?
}
```

# Current exception handling summary

feature	exceptions	error codes
constructors usability	✓	✗
concise code	✓	✗
performance	✗	✓
binary size	✗	✓
safety	✗	✓

Figure: comparison of error handling mechanisms' capabilities

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# New exception model - idea

Let's recall the comparison of exceptions and error codes:

feature	exceptions	error codes
constructors usability	✓	✗
concise code	✓	✗
performance	✗	✓
binary size	✗	✓
safety	✗	✓

# Learning from mistakes

Conclusion:

- exceptions gives nice code
- error codes provides performance and reliability

Next step:

Let's use exception syntax for error codes-like handling.

# Idea

## using return channel

Let's make throwing exceptions happen using return channels from functions

# using return channel

How to achieve that:

- Function needs to return some kind of a `std::variant<T, E>`
- The `sizeof(E)` in above needs to be known upfront
- Each exception must have same interface
- Compiler must know how to move the object

Other things to consider:

- co-existence with dynamic exceptions

# `std::error`

features of `std::error` includes:

- trivially-relocatable semantics
- the `error_category` is able to represent:
  - C++ standard library exceptions
  - POSIX system codes
  - Windows' `NTSTATUS`
  - and other common error domains

`std::error` type can be treated as a next-gen `std::error_code` type.



# The forgotten throws

Since we no longer need to know the type of the exception, we can notify about function throwing the static exception with `throws` static exception specifier

```
void foo() throws {  
    throw arithmetic_error::something;  
}
```

## more examples

```
string foo() throws {  
    //dynamic exception will be translated to static one  
    throw std::runtime_error;  
}
```

```
try {  
    auto result = g();  
    cout << "success, result is: " << result;  
}  
catch(error err) { // catch by value is fine  
    cout << "failed, error is: " << err.error();  
}
```

## more examples

```
int caller2(int i, int j) {  
    try {  
        return safe_divide(i, j);  
    } catch(error e) {  
        if (e == arithmetic_errc::divide_by_zero)  
            return 0;  
        if (e == arithmetic_errc::not_integer_division)  
            return i / j; // ignore  
        if (e == arithmetic_errc::integer_divide_overflows)  
            return INT_MIN;  
    }  
}
```