

Flight autonomy

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Chapter 1

Class Index

1.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

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Chapter 2

Class Documentation

2.1 FlightAutonomy Class Reference

The documentation for this class was generated from the following file:

- `include/FlightAutonomy.h`

2.2 ImageReceiver Class Reference

Image receiving class that supports different types of input video streams.

```
#include <ImageReceiver.h>
```

Public Member Functions

- **ImageReceiver** (`ros::NodeHandle &_nh`, `std::string topic`)

2.2.1 Detailed Description

Image receiving class that supports different types of input video streams.

The documentation for this class was generated from the following files:

- `include/ImageReceiver.h`
- `src/ImageReceiver.cpp`

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