Elementary Differential Equations and Boundary Value Problems

Twelfth Edition

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Chapter 3

Second-Order Linear Differential Equations

Section 3.4 Repeated Roots; Reduction of Order

Repeated Roots; Reduction of Order

• Recall our 2nd order linear homogeneous ODE

$$ay'' + by' + cy = 0$$

where a, b and c are constants

Assuming an exponential solution leads to characteristic equation:

$$y(t) = e^{rt} \implies ar^2 + br + c = 0$$

• Quadratic formula (or factoring) yields two solutions, r_1 and r_2 :

$$r = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

• When $b^2 - 4ac = 0$, then $r_1 = r_2 = \frac{-b}{2a}$, with both roots yielding the same solution:

$$y_1(t) = ce^{-bt/(2a)}$$

Finding the Second Solution Using Multiplying Factor v(t)

- We know that if $y_1(t)$ is a solution, then $y_2(t) = cy_1(t)$ is a solution.
- Since y_1 and y_2 are linearly dependent, we can generalize this approach and multiply by a function v(t), and determine conditions for which y_2 is a solution:

$$y_{1}(t) = e^{-bt/(2a)} \text{ a solution } \Box \text{ try } y_{2}(t) = v(t)e^{-bt/(2a)}$$

$$y_{2}(t) = v(t)e^{-bt/(2a)}$$

$$y'_{2}(t) = v'(t)e^{-bt/(2a)} - \frac{b}{2a}v(t)e^{-bt/(2a)}$$

$$y''_{2}(t) = v''(t)e^{-bt/(2a)} - \frac{b}{2a}v'(t)e^{-bt/(2a)} - \frac{b}{2a}v'(t)e^{-bt/(2a)} + \frac{b^{2}}{4a^{2}}v(t)e^{-bt/(2a)}$$

$$y''_{2} = v''(t)e^{-bt/(2a)} - \frac{b}{a}v'(t)e^{-bt/(2a)} + \frac{b^{2}}{4a^{2}}v(t)e^{-bt/(2a)}$$

Finding the Multiplying Factor v(t)

• Substituting derivatives into the original ODE, we can find and expression for *v*:

$$e^{-bt/(2a)} \left\{ a \left[v''(t) - \frac{b}{a} v'(t) + \frac{b^2}{4a^2} v(t) \right] + b \left[v'(t) - \frac{b}{2a} v(t) \right] + cv(t) \right\} = 0$$

$$av''(t) - bv'(t) + \frac{b^2}{4a} v(t) + bv'(t) - \frac{b^2}{2a} v(t) + cv(t) = 0$$

$$av''(t) + \left(\frac{b^2}{4a} - \frac{b^2}{2a} + c \right) v(t) = 0$$

$$av''(t) + \left(\frac{b^2}{4a} - \frac{2b^2}{4a} + \frac{4ac}{4a} \right) v(t) = 0 \iff av''(t) + \left(\frac{-b^2}{4a} + \frac{4ac}{4a} \right) v(t) = 0$$

$$av''(t) - \left(\frac{b^2 - 4ac}{4a} \right) v(t) = 0$$

$$v''(t) = 0 \implies v(t) = k_3 t + k_4$$

General Solution

• To find our general solution, we have:

$$y(t) = k_1 e^{-bt/(2a)} + k_2 v(t) e^{-bt/(2a)}$$

$$= k_1 e^{-bt/(2a)} + (k_3 t + k_4) e^{-bt/(2a)}$$

$$= c_1 e^{-bt/(2a)} + c_2 t e^{-bt/(2a)}$$

• Thus the general solution for repeated roots is

$$y(t) = c_1 e^{-bt/(2a)} + c_2 t e^{-bt/(2a)}$$

Wronskian

• The general solution is

$$y(t) = c_1 e^{-bt/(2a)} + c_2 t e^{-bt/(2a)}$$

Thus every solution is a linear combination of

$$y_1(t) = e^{-bt/(2a)}, y_2(t) = te^{-bt/(2a)}$$

• The Wronskian of the two solutions is

$$W(y_1, y_2)(t) = \begin{vmatrix} e^{-bt/(2a)} & te^{-bt/(2a)} \\ -\frac{b}{2a}e^{-bt/(2a)} & \left(1 - \frac{bt}{2a}\right)e^{-bt/(2a)} \end{vmatrix}$$
$$= e^{-bt/a}\left(1 - \frac{bt}{2a}\right) + e^{-bt/a}\left(\frac{bt}{2a}\right)$$
$$= e^{-bt/a} \neq 0 \quad \text{for all } t$$

• Thus y_1 and y_2 form a fundamental solution set for equation.

Example 3.4.1 (part one)

• Solve the differential equation:

$$y'' + 4y' + 4y = 0$$

Assuming an exponential solution leads to characteristic equation:

$$y(t) = e^{rt} \implies r^2 + 4r + 4 = 0 \iff (r+2)^2 = 0 \iff r = -2$$

• So one solution is $y_1(t) = e^{-2t}$ and a second solution is found:

$$y_{2}(t) = v(t)e^{-2t}$$

$$y'_{2}(t) = v'(t)e^{-2t} - 2v(t)e^{-2t}$$

$$y''_{2}(t) = v''(t)e^{-2t} - 4v'(t)e^{-2t} + 4v(t)e^{-2t}$$

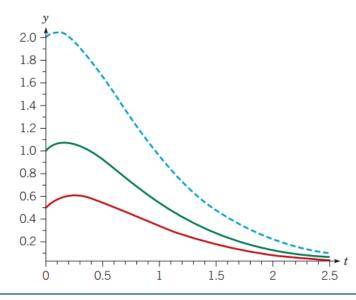
• Substituting these into the differential equation and simplifying yields v''(t) = 0, $v'(t) = k_1$, $v(t) = k_1t + k_2$ where k_1 and k_2 are arbitrary constants.

Example 3.4.1 (part two)

- Letting $k_1 = 1$ and $k_2 = 0$, v(t) = t and $y_2(t) = te^{-2t}$
- So the general solution is

$$y(t) = c_1 e^{-2t} + c_2 t e^{-2t}$$

- Note that both y_1 and y_2 tend to 0 as $t \to \infty$ regardless of the values of c_1 and c_2
- The figure shows three solutions of this equation with different sets of initial conditions.
 - y(0) = 2, y'(0) = 1 (top)
 - y(0) = 1, y'(0) = 1 (middle)
 - $y(0) = \frac{1}{2}, y'(0) = 1 \text{ (bottom)}$



Example 3.4.2 (part one)

• Find the solution of the initial value problem

$$y'' - y' + \frac{1}{4}y = 0$$
, $y(0) = 2$, $y'(0) = \frac{1}{3}$

• Assuming exponential solution leads to characteristic equation:

$$y(t) = e^{rt} \implies r^2 - r + \frac{1}{4} = 0 \iff (r - \frac{1}{2})^2 = 0 \iff r = \frac{1}{2}$$

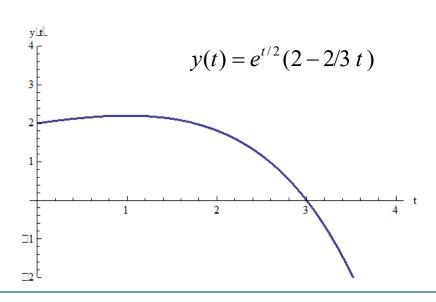
Thus the general solution is

$$y(t) = c_1 e^{t/2} + c_2 t e^{t/2}$$

Using the initial conditions:

$$\begin{vmatrix}
c_1 & = 2 \\
\frac{1}{2}c_1 + c_2 & = \frac{1}{3}
\end{vmatrix} \Rightarrow c_1 = 2, c_2 = -\frac{2}{3}$$

• Thus $y(t) = 2e^{t/2} - \frac{2}{3}te^{t/2}$



Example 3.4.2 (part two)

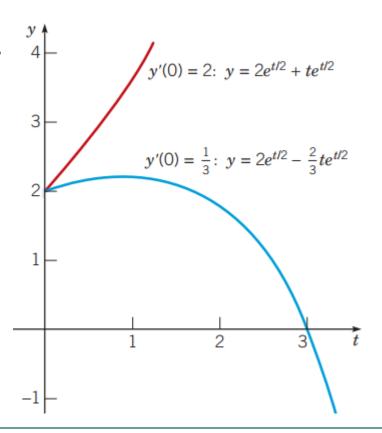
• Suppose that the initial slope in the previous problem was increased

$$y(0) = 2, y'(0) = 2$$

• The solution of this modified problem is

$$y(t) = 2e^{t/2} + te^{t/2}$$

• Notice that the coefficient of the second term is now positive. This makes a difference in the graph, since the exponential function is raised to a positive power.



Reduction of Order

• The method used so far in this section also works for equations with nonconstant coefficients:

$$y'' + p(t)y' + q(t)y = 0$$

• That is, given that y_1 is solution, try $y_2 = v(t)y_1$:

$$y_{2}(t) = v(t)y_{1}(t)$$

$$y'_{2}(t) = v'(t)y_{1}(t) + v(t)y'_{1}(t)$$

$$y''_{2}(t) = v''(t)y_{1}(t) + 2v'(t)y'_{1}(t) + v(t)y''_{1}(t)$$

Substituting these into the original ODE and collecting terms,

$$y_1v'' + (2y_1' + py_1)v' + (y_1'' + py_1' + qy_1)v = 0$$

• Since y_1 is a solution to the differential equation, this last equation reduces to a first order equation in v:

$$y_1v'' + (2y_1' + py_1)v' = 0$$

Example 3.4.3: Reduction of Order

• Given the variable coefficient equation and solution y_1 ,

$$2t^2y'' + 3ty' - y = 0$$
, $t > 0$; $y_1(t) = t^{-1}$,

use reduction of order method to find a second solution:

$$y_{2}(t) = v(t) t^{-1}$$

$$y'_{2}(t) = v'(t) t^{-1} - v(t) t^{-2}$$

$$y''_{2}(t) = v''(t) t^{-1} - 2v'(t) t^{-2} + 2v(t) t^{-3}$$

Substituting these into the original ODE and collecting terms,

$$2t^{2}(v''t^{-1} - 2v't^{-2} + 2vt^{-3}) + 3t(v't^{-1} - vt^{-2}) - vt^{-1} = 0$$

$$\Leftrightarrow 2v''t - 4v' + 4vt^{-1} + 3v' - 3vt^{-1} - vt^{-1} = 0$$

$$\Leftrightarrow 2tv'' - v' = 0$$

$$\Leftrightarrow 2tu' - u = 0, \text{ where } u(t) = v'(t)$$

Example 3.4.3: Finding v(t)

To solve

$$2tu' - u = 0$$
, $u(t) = v'(t)$

for u, we can use the separation of variables method:

$$2t\frac{du}{dt} - u = 0 \iff \int \frac{du}{u} = \int \frac{1}{2t} dt \iff \ln|u| = \frac{1}{2} \ln|t| + C$$

$$\Leftrightarrow |u| = |t|^{1/2} e^{C} \iff u = ct^{1/2}, \text{ since } t > 0.$$

• Thus $v' = ct^{1/2}$

and hence

$$v(t) = \frac{2}{3}ct^{3/2} + k$$

Example 3.4.3: General Solution

• Since $v(t) = \frac{2}{3}ct^{3/2} + k$

$$y_2(t) = \left(\frac{2}{3}ct^{3/2} + k\right)t^{-1} = \frac{2}{3}ct^{1/2} + kt^{-1}$$

- Recall $y_1(t) = t^{-1}$
- So we can neglect the second term of y_2 to obtain

$$y_2(t) = t^{1/2}$$

• The Wronskian of $y_1(t)$ and $y_2(t)$ can be computed

$$W[y_1, y_2](t) = \frac{3}{2}t^{-3/2} \neq 0 \text{ for } t > 0$$

• Hence the general solution to the differential equation is

$$y(t) = c_1 t^{-1} + c_2 t^{1/2}$$

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