

Vector Analysis .



Summary: Vectors and vector space.

$$c^2 = a^2 + b^2 - 2ab \cos \theta$$

If $\mathbf{x} = (x_1, x_2, x_3)$, $\mathbf{y} = (y_1, y_2, y_3)$

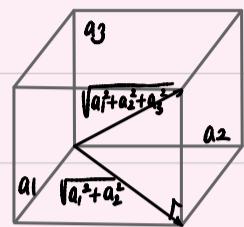
Thm 1.6) Norm of a vector

1. Vector equality : $\mathbf{x} = \mathbf{y} \Leftrightarrow x_i = y_i \ (i=1,2,3)$

Vector of \mathbb{R}^3 , $a = (a_1, a_2, a_3)$

2. Vector addition : $\mathbf{x} + \mathbf{y} = \mathbf{z} \Leftrightarrow x_i + y_i = z_i \ ("")$

$$\text{length of } a \quad \|a\| := \sqrt{a_1^2 + a_2^2 + a_3^2}$$



3. Scalar multiplication : $a\mathbf{x} \Leftrightarrow (ax_1, ax_2, ax_3) \quad a \in \mathbb{R}$

Thm 1.7) Norm Property (a, b : vector, α : scalar)

4. Negative of vector : $-\mathbf{x} = (-1)\mathbf{x} \Leftrightarrow (-x_1, -x_2, -x_3)$

$$(1) \|a\| = 0 \Leftrightarrow a = 0$$

5. Null vector : There exists a null vector $\mathbf{0} = (0, 0, 0)$

$$(2) |\alpha a\| = |\alpha| \|a\|$$

$$(3) \|a+b\| \leq \|a\| + \|b\|$$

Since our vector components are real num (or complex).

Def 1.7) Inner product

the followings hold.

$$\angle(a, b) = \theta \quad (0 \leq \theta \leq \pi),$$

1. addition of vector is commutative : $\mathbf{x} + \mathbf{y} = \mathbf{y} + \mathbf{x}$

$$\text{define } a \cdot b = \|a\| \|b\| \cos \theta$$

2. " associative : $(\mathbf{x} + \mathbf{y}) + \mathbf{z} = \mathbf{x} + (\mathbf{y} + \mathbf{z})$

$$= 0 \Leftrightarrow a \text{ or } b \text{ is zero vector}$$

3. Scalar multiplication is distribute : $a(\mathbf{x} + \mathbf{y}) = a\mathbf{x} + a\mathbf{y}$

Thm 1.8) Cosine Rule

4. Scalar multiplication is associative : $(ab)\mathbf{x} = a(b\mathbf{x})$

$$\forall a, b: \text{vector}, \quad a \cdot b = \frac{1}{2}(\|a\|^2 + \|b\|^2 - \|b-a\|^2)$$

Thm 1.9) Parallel and orthogonal Property

Def 1.6) Fundamental Unit Vectors.

a, b are not zero vector, e_i : unit vector

$$e_1 = (1, 0, \dots, 0), \quad e_2 = (0, 1, 0, \dots, 0) \dots, \quad e_n = (0, \dots, 1)$$

$$(1) e_i \cdot e_j = \delta_{ij}, \quad \delta_{ij} = \begin{cases} 0 & i \neq j \\ 1 & i = j \end{cases}$$

\rightarrow Fundamental unit vector of vector space \mathbb{R}^n .

$$(2) a \parallel b \Leftrightarrow a \cdot b = \pm \|a\| \|b\|$$

Thm 1.3) Linear combination

$$(3) a \perp b \Leftrightarrow a \cdot b = 0$$

Any vector of \mathbb{R}^n can be expressed by Linear combination

Thm 1.10) Inner product

of e_i .

$$a = (a_1, a_2, a_3) \quad b = (b_1, b_2, b_3)$$

$$\Rightarrow v = (v_1, \dots, v_n) \in \mathbb{R}^n, \quad v = \sum_{i=1}^n v_i e_i$$

$$\Rightarrow a \cdot b = a_1 b_1 + a_2 b_2 + a_3 b_3$$

1.2 Inner product (412)

Thm 1.11) Inner Product Property

Thm 1.5) Cosine Rule

$$(1) a \cdot b = b \cdot a \quad (2) a \cdot (b+c) = a \cdot b + a \cdot c$$

세 변 길이 a, b, c $\angle C = \theta$ 인 임의의 삼각형 $\triangle ABC$

$$(3) (\alpha a) \cdot b = a \cdot (\alpha b) = \alpha (a \cdot b) \quad (4) \|a\| = \sqrt{a \cdot a}$$



Thm 1.12) Schwartz Ineq.

$$a = (a_1, a_2, a_3), b = (b_1, b_2, b_3).$$

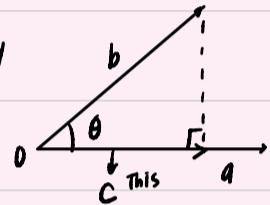
$$|a \cdot b| \leq \|a\| \|b\| \quad (\text{pf by def of inner product})$$

(Projection - 정사영)

Def 1.8) Orthogonal Projection

define) '벡터 b 를 벡터 a 가 놓여있는 직선에 수직으로 내린' 벡터 c 를

a 위로 b 의 정사영, $p_a b$ 로 표기



Thm 1.13) Orthogonal Projection

a, b are nonzero vector.

$$(1) \text{ 정사영} : p_a b = \frac{\overbrace{b \cdot a}^{\text{inner product}}}{a \cdot a} a$$

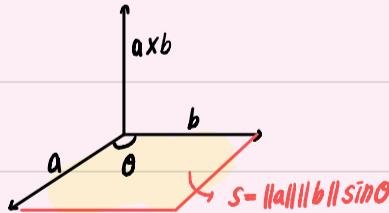
$$(2) \text{ length} : \|p_a b\| = \frac{|b \cdot a|}{\|a\|}$$

1.3 벡터 외적

Def 1.9) Cross Product

끼인 각이 θ 인 a, b 를 이용한 평행사변형의 넓이. 즉

$\|a\| \|b\| \sin \theta$ 을 크기로 하고 양의 방향을 갖는 벡터를 a, b 의 외적.



Thm 1.14) Cross Product Property

$$(1) a \times b = -b \times a$$

$$(2) (\alpha a) \times b = \alpha (a \times b) = a \times (\alpha b)$$

$$(3) a \times a = 0$$

$$(4) e_1 \times e_2 = e_3, e_2 \times e_3 = e_1, e_3 \times e_1 = e_2$$

$$(5) a \times (b+c) = a \times b + a \times c$$

Thm 1.15) 벡터 a, b, c 를 이용한 평행육면체 부피는 $|a \times b \cdot c|$

$$\text{Thm 1.16) } a \times b \cdot c = b \times c \cdot a = c \times a \cdot b$$

Rmk) 내적·외적 동시에 계산 시 외적 먼저 계산함.

Def 1.10) Triple Scalar Product.

$a \times b \cdot c$ 를 벡터 a, b, c 의 스칼라 3중적

Thm 1.17) Triple Scalar Product Property

$$(1) a \times b \cdot a = a \times b \cdot b = 0$$

$$(2) a \times b \cdot c = a \cdot b \times c$$

$$(3) a \cdot b \times c = b \cdot c \times a = c \cdot a \times b$$

Thm 1.18) $a = (a_1, a_2, a_3), b = (b_1, b_2, b_3), c = (c_1, c_2, c_3)$

$$(1) a \times b = (a_2 b_3 - a_3 b_2, a_3 b_1 - a_1 b_3, a_1 b_2 - a_2 b_1)$$

$$(2) a \times b \cdot c = (a_2 b_3 - a_3 b_2) \cdot c_1 + (a_3 b_1 - a_1 b_3) \cdot c_2 + (a_1 b_2 - a_2 b_1) \cdot c_3$$

EX3) $a = (1, 1, -2), b = (2, 2, 1)$ 에 동시에 주직인 unit vector?

$$a \times b = \begin{vmatrix} i & j & k \\ 1 & 1 & -2 \\ 2 & 2 & 1 \end{vmatrix} = (1+4, -(1+4), 2-2) = (5, -5, 0)$$

\Rightarrow a, b 에 동시에 수직이고 length $\sqrt{25+25} = 5\sqrt{2}$

$$\Rightarrow \pm \frac{a \times b}{5\sqrt{2}} = \pm \left(\frac{1}{\sqrt{2}}, -\frac{1}{\sqrt{2}}, 0 \right)$$

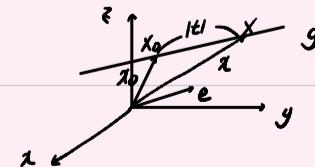
EX4) 벡터 a, b 를 이용한 삼각형의 넓이? $\frac{1}{2} \|a \times b\|$

EX5) 세점 P.Q.R을 있는 $\triangle PAR$ 의 넓이? put $a = \vec{PQ}, b = \vec{PR}$, "

1.4 공간의 직선과 평면

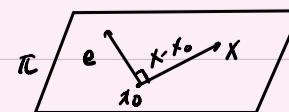
Thm 1.19) 한점 x_0 지나고 단위벡터 e 와 평행한 직선의 벡터방정식

$$: x = x_0 + te, t \in \mathbb{R}$$



Thm 1.20) 한점 x_0 지나고 단위벡터 e 에 수직인 평면 π 의 벡터방정식

$$: (x - x_0) \cdot e = 0$$





Ex 8) 동일직선상에 있지 않는 영 아닌 벡터 a, b, c 가 한 평면 위에 있을 때.

평면의 방정식? 두 벡터 $b-a, c-a$ 는 평행 \times

$(b-a) \times (c-a)$ 가 주어진 평면에 직교하는 영 아닌 벡터 \rightarrow 벡터

$$\Rightarrow (a-a) \cdot (b-a) \times (c-a) = 0$$

1.5 선형변환

Def 1.11) Linear Transform

$L: \mathbb{R}^n \rightarrow \mathbb{R}^m$, L 은 선형변환

$$L(x_1, \dots, x_n) = (a_{11}x_1 + \dots + a_{1n}x_n, \dots, a_{m1}x_1 + \dots + a_{mn}x_n)$$

Specially, $m=1$ 인 경우 선형함수.

Def 1.12) determinant

Square matrix $A = [a_{ij}]$ 를 표현행렬로 하는 선형변환 L 각각의

길이, 넓이 or 부피가 $a (> 0)$ 배로 늘어날 때,

$$\text{define } |A| = \begin{cases} a & : "+" \text{ oriented} \\ -a & : "-" \text{ oriented} \end{cases}$$

(Linear Algebra - Anton 11) Chapter 8 Linear Transformations

Def 1) If $T: V \rightarrow W$ is a ft from a vector space V to W ,

then T is called a linear transformation from V to W

If (i) $T(ku) = kT(u)$ [Homogeneity property]

(ii) $T(u+v) = T(u) + T(v)$ [Additivity property]

In the special case where $V=W$,

the linear transformation T is called a linear operator on V .

Rmk) $T(k_1v_1 + k_2v_2 + \dots + k_r v_r) = k_1T(v_1) + \dots + k_r T(v_r)$

Thm 8.1.1) If $T: V \rightarrow W$ is a linear transformation, then

$$(a) T(0) = 0$$

$$(b) T(u-v) = T(u) - T(v) \text{ for } \forall u, v \in V$$

Thm 8.1.2) Let $T: V \rightarrow W$ be a linear transformation, where

V is finite dimensional.

If $S = \{v_1, v_2, \dots, v_n\}$ is a basis for V , then the image of any vector $v \in V$

can be expressed as $T(v) = c_1T(v_1) + \dots + c_nT(v_n)$

where c_1, c_2, \dots, c_n are coefficients required to express v as a linear combination of vectors in S .

(EX 10) Computing with Images of Basis Vectors.

Consider the basis $S = \{v_1, v_2, v_3\}$ for \mathbb{R}^3 , where

$$v_1 = (1, 1, 1), v_2 = (1, 1, 0), v_3 = (1, 0, 0)$$

Let $T: \mathbb{R}^3 \rightarrow \mathbb{R}^2$ be the linear transformation for which

$$T(v_1) = (1, 0), T(v_2) = (2, -1), T(v_3) = (4, 3)$$

Find a formula for $T(\lambda_1, \lambda_2, \lambda_3)$, and then use that formula to compute $T(2, -3, 5)$.

(sol) We need to express $x = (\lambda_1, \lambda_2, \lambda_3)$ as a linear combination of v_1, v_2 , and v_3 .

$$(\lambda_1, \lambda_2, \lambda_3) = c_1(1, 1, 1) + c_2(1, 1, 0) + c_3(1, 0, 0)$$

$$c_1 + c_2 + c_3 = \lambda_1 \quad c_1 = \lambda_3, \quad c_2 = \lambda_2 - \lambda_3.$$

$$\begin{cases} c_1 + c_2 = \lambda_2 & \Rightarrow c_3 = \lambda_1 - \lambda_2 \\ c_1 = \lambda_3 \end{cases}$$

$$\text{So } (\lambda_1, \lambda_2, \lambda_3) = \lambda_3(1, 1, 1) + (\lambda_2 - \lambda_3)(1, 1, 0) + (\lambda_1 - \lambda_2)(1, 0, 0)$$

$$= \lambda_3 v_1 + (\lambda_2 - \lambda_3) v_2 + (\lambda_1 - \lambda_2) v_3$$

$$\text{Thus } T(\lambda_1, \lambda_2, \lambda_3) = \lambda_3 T(v_1) + (\lambda_2 - \lambda_3) T(v_2) + (\lambda_1 - \lambda_2) T(v_3)$$

$$= \lambda_3(1, 0) + (\lambda_2 - \lambda_3)(2, -1) + (\lambda_1 - \lambda_2)(4, 3)$$

$$= (4\lambda_1 - 2\lambda_2 - \lambda_3, 3\lambda_1 - 4\lambda_2 + \lambda_3)$$

From this formula, we obtain $T(2, -3, 5) = (9, 23)$



- kernel and Range

Def 2) If $T: V \rightarrow W$ is a linear transformation, then the set of vectors in V that T maps into 0 is called the kernel of T and is denoted by $\ker(T)$.

The set of all vectors in W that are images under T of at least one vector in V is called the range of T and is denoted by $R(T)$.

Thm 8.1.3) If $T: V \rightarrow W$ is a linear transformation, then

- (a) The kernel of T is a subspace of V .
- (b) The range of T is a subspace of W .

Def 3) Let $T: V \rightarrow W$ be a linear transformation.

If the range of T is finite-dimensional, then its dimension is called the rank of T ; and if the kernel of T is finite-dimensional, then its dimension is called the nullity of T . The rank of T is denoted by $\text{rank}(T)$ and the nullity of T by $\text{nullity}(T)$.

Thm 8.1.4) Dimension Thm for linear transformations

If $T: V \rightarrow W$ is a linear transformation from an n -dimensional vector space V to W , then $\text{rank}(T) + \text{nullity}(T) = n$.

"

Thm 1.21 Determinant of 2×2 matrix

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \Rightarrow |A| = ad - bc$$