$$\begin{split} R_{e} &= \left(\frac{n_{1}}{n_{2}}\right)^{2} \frac{8}{\pi^{2}} R_{L} \\ B(t) &= \frac{1}{n_{1} A_{e}} \int u_{1}(t) dt \\ \Delta B &= 2 B^{\max} = \frac{U_{1} t_{on}}{n_{1} A_{e}} \qquad n_{1} = \frac{U_{1} t_{on}}{2 B^{\max} A_{e}} \qquad L_{m} = \frac{n_{1}^{2} A_{e} \mu_{0} \mu_{r}}{l_{e}} \\ \frac{\Delta B}{2} &\rightarrow Steinmetz \ equation \rightarrow power \ losses \rightarrow B^{\max} \\ A_{p1} &= A_{w} A_{e} = \frac{L I_{pk} I_{rms}}{B_{pk} J k_{f}}; \qquad k_{f} \approx 0.5 \\ A_{p2} &= A_{w} A_{e} = \frac{L \Delta I I_{rms}}{\Delta B J k_{f}}; \qquad J_{2} \approx 1.0 \ A \ mm^{-2} \qquad (I_{2rms} \approx 1000 \ A) \\ A_{e} &= \frac{1}{n_{1}} \frac{U_{1}}{4 f_{sw} \Delta B} \qquad A_{p} = A_{w} A_{e} = 2 I_{1rms} \frac{U_{1} d_{on}}{f_{sw} \Delta B J k_{f}}; \\ A_{w} &= \frac{w_{A_{1}} \cdot n_{1} + w_{A_{2}} \cdot n_{2}}{k_{f}} \\ A_{p} &= I_{1rms} \frac{U_{1}}{2 f_{sw} \Delta B J k_{f}}; \qquad (d_{on} = 1/4) \\ w_{A_{1}} &= \frac{I_{1rms}}{J_{1}} \qquad \rho = 0.0175 \Omega \, mm^{2} / m \\ w_{A_{2}} &= \frac{I_{1rms}}{J} \qquad h = 5.5 \frac{W}{K m^{2}} \end{split}$$

Transformer Design

$$\begin{split} B_{pk} &= \frac{L \, I_{pk}}{n \, \mathsf{A}_e} \\ \Delta B &= \frac{L \, \Delta I}{n \, \mathsf{A}_e} \\ L &= \frac{\mu_{e\!f\!f} \, \mu_0 n^2 \mathsf{A}_e}{l_e} \\ \mu_{e\!f\!f} &= \frac{1}{\frac{1}{\mu_r} + \frac{1}{l_e}} \\ \mu_{e\!f\!f} &\approx \frac{l_e}{g} \\ \frac{1}{2} \, L \big( \hat{i} \big)^2 &= \frac{1}{2} \, \frac{A_e l_e}{\mu_{e\!f\!f} \, \mu_0} \, B_{\max}^2 \end{split}$$
Inductor Design airgap and energy stored

$$\delta[mm] = \frac{72}{\sqrt{f[Hz]}}$$

$$d = Q \cdot \delta \to 0.25 \cdot \delta$$

$$Q = \frac{d}{\delta}$$

$$R_{ac} = R_{dc} \left(1 + \frac{\left(r_{0}\right)^{4}}{48 + 0.8\left(r_{0}\right)^{4}}\right)$$

$$\frac{Q_{1}}{Q_{2}} = 4 \to \frac{R_{dc1}}{R_{dc2}} \approx 16 \to \frac{R_{ac1}}{R_{ac2}} \approx 60$$

$$\frac{R_{dc1}}{R_{dc2}} = \left(\frac{d_{2}}{d_{1}}\right)^{2}$$
Winding Design

Proximity and skin effects

 $\omega_0 = \frac{1}{\sqrt{L_r C_r}}$