# Pendulum on Cart

Davide Bagnara

January 31, 2022



### Contents

1	Model derivation	3
2	Control implementation	3
$\mathbf{L}^{i}$	ist of Figures  1 Pendulum on cart	3
$\mathbf{L}^{i}$	ist of Tables	9



### 1 Model derivation

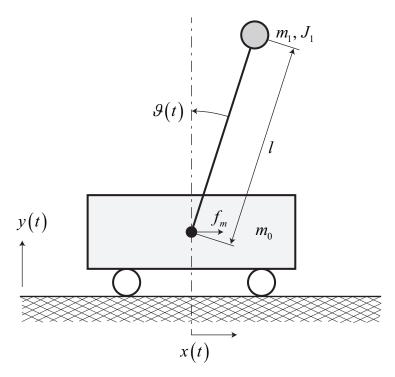


Figure 1: Pendulum on cart.

## 2 Control implementation



#### References

- [A. Mehrle, 2021] Andreas Mehrle Advanced Control Engineering. MCI 2021.
- [K. Ogata, 2009] Katsuhiko Ogata Modern Control Engineering. Pearson 2009.
- [K. Ogata, 1987] Katsuhiko Ogata Discrete-time Control Systems. Prentice-Hall 1987.