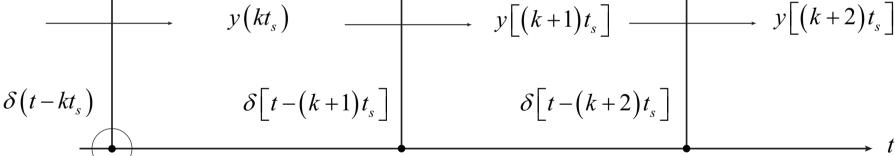
$$y[(k-1)t_s] y(kt_s) y[(k+1)t_s]$$

$$x(kt_s) x[(k+1)t_s] x[(k+2)t_s]$$

 $X(z) \rightarrow H(z)X(z) = Y(z)$



 $(k+1)t_s$

Acquisition ADC and

update data output registers

 kt_{s}

 $(k+2)t_s$