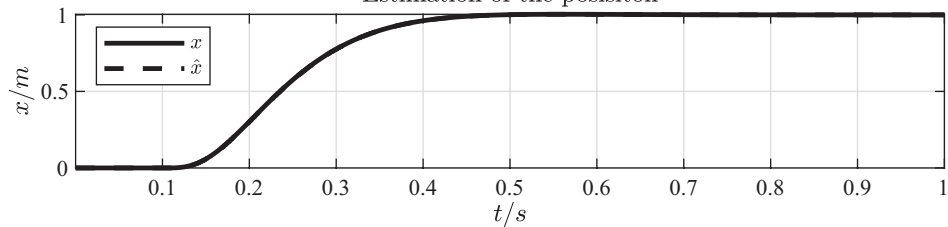
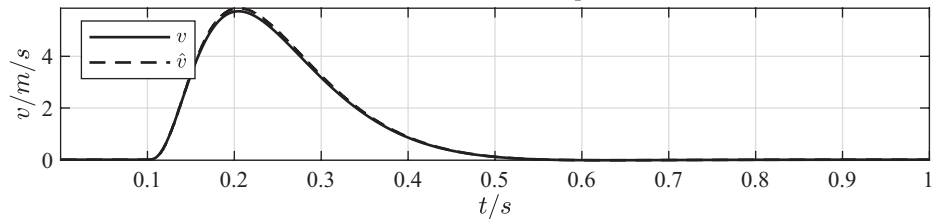


Estimation of the position



Estimation of the speed



Estimation of the current

