

Project 5 CMPT 412

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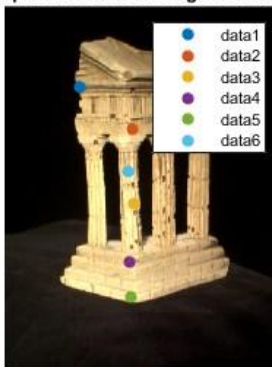
Student id : 301388030

3.1.1

$F =$

0.0000	-0.0000	0.0000
-0.0000	-0.0000	-0.0005
-0.0000	0.0005	-0.0018

Epipole is outside image boundary



Select a point in this image
(Right-click when finished)

Epipole is outside image boundary

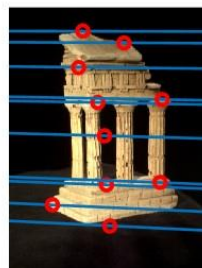


Verify that the corresponding point
is on the epipolar line in this image

3.1.2



Select a point in this image
(Right-click when finished)



Verify that the corresponding point
is on the epipolar line in this image

- I calculated the similarity metric using Euclidean distance between the pixel intensities of the two patches around the keypoints in the images.
- The search for the corresponding point in image 2 is performed within a small range of +/- 10 pixels along the horizontal direction around the initial point. If the true correspondence is outside this range, it might lead to a mismatch.

3.1.3

`E =`

```

0.0044    -0.1543   -0.0002
-0.0400   -0.0009   -0.7343
-0.0207    0.7253   -0.0013

```

3.1.4

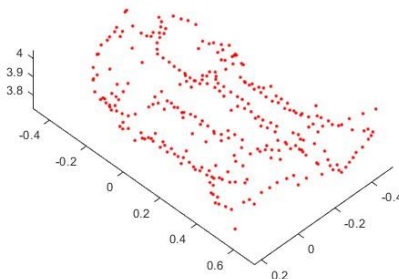
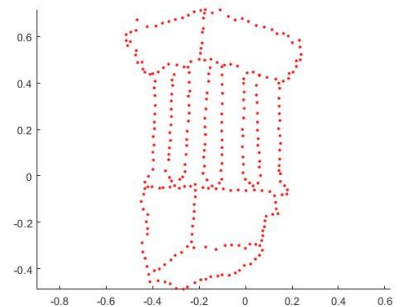
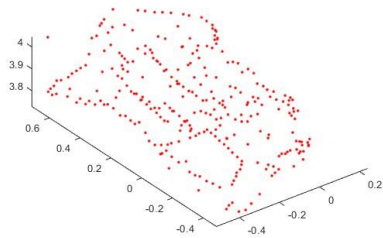
`dist1 =`

```
0.0450
```

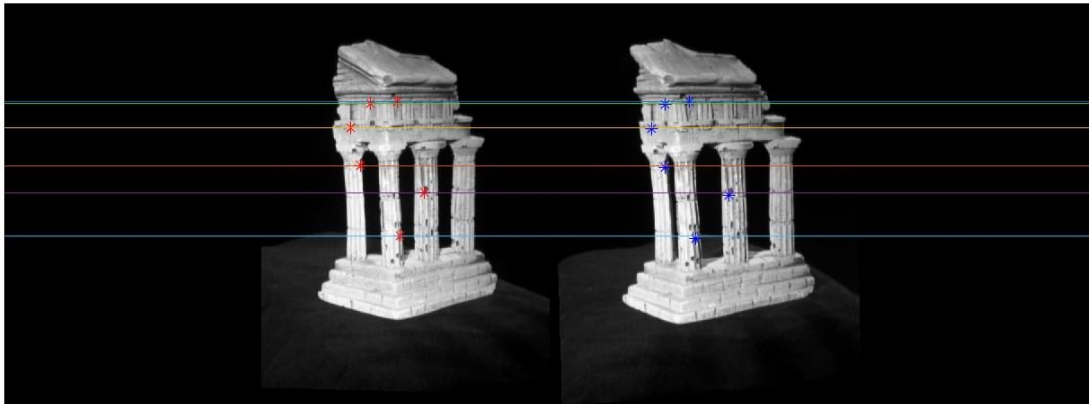
`dist2 =`

```
0.0446
```

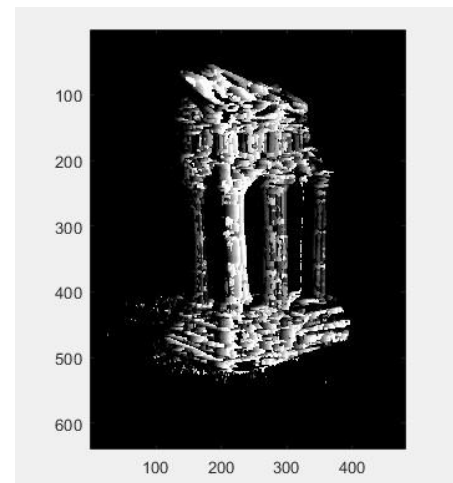
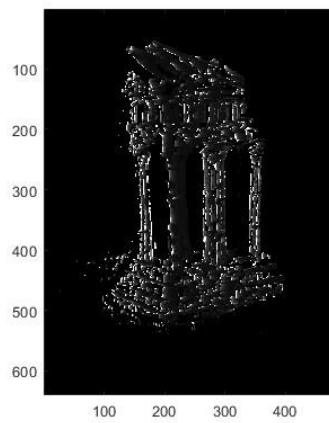
3.1.5



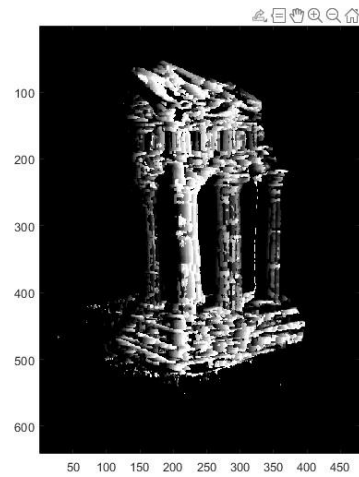
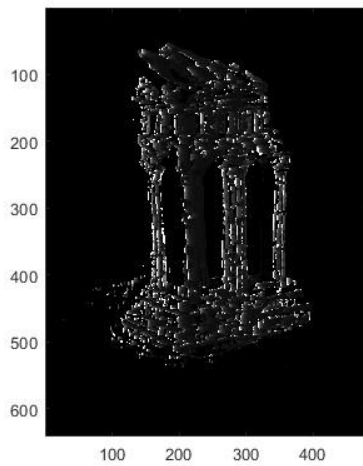
3.2.1



3.2.2



3.2.3



3.3.1

```
Reprojected Error with clean 2D points is 0.0000
Pose Error with clean 2D points is 0.0000
-----
Reprojected Error with noisy 2D points is 14.7967
Pose Error with noisy 2D points is 0.6467
```

3.3.2

```
Intrinsic Error with clean 2D points is 0.0000
Rotation Error with clean 2D points is 0.0000
Translation Error with clean 2D points is 0.0000
-----
Intrinsic Error with clean 2D points is 0.8419
Rotation Error with clean 2D points is 0.0755
Translation Error with clean 2D points is 0.1297
```