Homework Batch II: Trees and Algorithms

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Exercise 1

Let H be a Min-Heap containing n integer keys and let k be an integer value. Solve the following exercises by using the procedures seen during the course lessons:

(a) Write the pseudo-code of an in-place procedure RetrieveMax(H) to efficiently return the maximum value in H without deleting it and evaluate its complexity.

```
def RetrieveMax(H):
    mid <- floor(H.size/2)
    max <- mid
    for i <- mid + 1 to H.size:
        if max < H[i]:
            max <- i
        endif
    endfor
    return max
enddef</pre>
```

In this algorithm we are dealing with a Min-Heap represented thorugh an array. We know from theory that in this way root node will be placed in 1^{st} position and each left and right child of i-th node will be then respectively found 2i-th and 2i+1-th position. Basically what we are doing is to exclude a priori all the nodes that have children (and so that are \leq than other nodes due to the min-heap property) and then retrieve the maximum through a linear scan. The function returns the index of the maximum value.

In order to evaluate the complexity of this algorithm we just have to count the number of iterations performed by the for loop (all the operations inside it cost $\theta(1)$):

$$n-\lceil\frac{n}{2}\rceil \leq n$$

So we have that the algorithm belongs to $\theta(n)$.

(b) Write the pseudo-code of an in-place procedure DeleteMax(H) to efficiently delete the maximum value from H and evaluate its complexity.

```
def DeleteMax(H):
    max <- RetrieveMax(H)
    swap(H, max, H.size)
    H.size <- H.size-1</pre>
```

```
i <- max
while not (is_root(i) or H[parent(i)] <= H[i]):
    swap(H, H[i], H[parent(i)])
    i <- parent(i)
    endwhile
enddef</pre>
```

Maximum value will be for sure a leaf node, so in order to remove it we can swap it with the last element of the heap and decrease by 1 the heap size itself. However we need to be sure that the binary heap property is still satisfied. To do so we check if the parent is bigger than the newly changed child, if so we swap them and push the problem upwards until root is reached.

We can finally compute the overall complexity, which for sure will be strictly connected to RetrieveMax(H) one, and in fact it's equal to:

$$\theta(n) + O(\log(n))$$

where the second term is due to the bin-heap property checking (at most done height(H) = log(n) times).

(c) Provide a working example for the worst case scenario of the procedure DeleteMax(H) on a heap H consisting in 8 nodes and simulate the execution of the function itself.

Let's take H = [1,2,30,4,5,60,70,8]. By applying the previously defined algorithm we find out that the maximum is placed in position 7. Then the swap with the last element of the heap is operated. Now we have that H = [1,2,30,4,5,60,8] but bin-Heap property is no longer satisfied so the algorithm procedes with the swap between parent (30) and child node (8). Doing so the heap property is fixed and the final result is: H = [1,2,8,4,5,60,30].

Exercise 2

Let A be an array of n integer values (i.e., the values belong to \mathbb{Z}). Consider the problem of computing a vector B such that, for all $i \in [1; n], B[i]$ stores the number of elements smaller than A[i] in $A[i+1; \ldots; n]$. More formally:

$$B[i] = |\{z \in [i+1; n] : A[z] < A[i]\}|$$

- (a) Evaluate the array B corresponding to A=[2,-7,8,3,-5,-5,9,1,12,4]. The result is B=[4,0,5,3,0,0,2,0,1,0].
 - (b) Write the pseudo-code of an algorithm belonging to $O(n^2)$ to solve the problem. Prove the asymptoic complexity of the proposed solution and its correctness.

```
def smallerThan(A):
    B <- array[A.size, default = 0]
    counter <- 0
    for i <- 1 to A.size:
        for j <- i+1 to A.size:
            if A[j] < A[i]:
                  counter <- counter + 1
                  endif
            endfor
            B[i] <- counter
            counter <- 0
        endfor
    return B
enddef</pre>
```

Since requirements for this exercise state that the algorithm needs to $\in O(n^2)$ we can basically just operate, for each index of the array A, a linear scan of the elements placed after the index itself in order to check if any of those is smaller than the current element at position i.

The complexity, following this procedure and considering the fact that all assignment and increment operations cost $\theta(1)$, will be:

$$\sum_{i=1}^{n} \sum_{j=i+1}^{n} 1 = \frac{n(n-1)}{2} \implies \theta(n^2)$$

And this result actually satisfies the required complexity.

Correctness of the algorithm is pretty self explanatory and proved just by following all the described steps.

(c) Assuming that there is only a constant number of values in A different from 0, write an efficient algorithm to solve the problem, evaluate its complexity and correctness.

Let k be the total number of values in A that are different from 0. The strategy I opted to follow in order to enhance the complexity of the previously presented algorithm was to copy all the k elements different from 0 into an auxiliary array AUX and then to perform the very same algorithm on that specific array. The pseudocode here below shows the procedure:

```
def improved(A):
   AUX <- array(A.size, default = 0)
   for i <- 1 to A.size:
      if A[i] != 0:
         AUX[i] = A[i]
   endif
endfor</pre>
```

```
return smallerThan(AUX)
enddef
```

Complexity in this case is equal to $\theta(n) + O(k^2)$ (respectively related to the first for loop and *smallerThan* function execution) and we can immediately notice the benefits from this kind of approach. Since k is a constant number and independent from n, $O(k^2)$ becomes negligible and so the resulting complexity will be $\theta(n)$.

Exercise 3

Let T be a Red-Black Tree.

(a) Give the definition of Red-Black Trees.

Red Black trees are Binary Search Trees satisfying the following conditions:

- Each node is either a red or a black node
- The tree's root is black
- All the leaves are black nil nodes
- All the red nodes must have black children for each node x
- All the branches from a node x contain the same number of black nodes
- (b) Write the pseudo-code of an efficient procedure to compute the height of T. Prove its correctness and evaluate its asymptotic complexity.

In order to find the height of an RBT what I thought to do was to traverse it, starting from root node, and to compute recursively the height of the right and left subtree by taking the maximum of these two and adding 1 to it. In this way when leaves are reached the algorithm returns 0 but rolling back the recursion calls let's us retrieve the actual height of the tree.

This procedure is described below:

```
def height(node):
    if node = NULL:
        return 0
    endif
    left_H <- height(LEFT_CHILD(node))
    right_H <- height(RIGHT_CHILD(node))

    return max(left_H, right_H) + 1
enddef</pre>
```

Correctness and complexity of the algorithm can be proved by taking a look at the pseudocode. In fact as explained before, this approach consists in computing the height of each node in the RBT and so the expected time complexity will be:

$$T(n) = 2 * T(n/2) + \theta(1)$$

Since we are dealing with an RBT we can assume that the tree is almost balanced and so we can retrieve the precise final complexity:

$$T(n) \le \sum_{i=0}^{h-1} 2^i = 2^h - 1 \approx n \implies \in O(n)$$

(c) Write the pseudo-code of an efficient procedure to compute the black-height of T. Prove its correctness and evaluate its asymptotic complexity.

Differently from previous case, we can apply a smarter approach in order to compute the black-height of an RBT. In fact, due to the last property specified in point (a) of this exercise, we know that in each branch of the tree the number of black nodes is the same. So to reduce time complexity we can consider to traverse only one among all the branches (in this case only left-most one).

```
def black_height(node, counter):
    left_child <- LEFT_CHILD(node)

if color(left_child) = black:
    counter <- counter + 1
endif

if left_child = NULL:
    return counter
endif

black_height(left_child, counter)
enddef</pre>
```

Complexity in this case will be proportional to the height of the tree, since at each recursive step we are traversing in depth the tree itself and from theory we know that $h \leq 2\log(n+1), n = \{\#ofnodes\}$ we can state that time complexity $\in O(\log(n))$.

Exercise 4

Let $(a_1, b_1), \ldots, (a_n, b_n)$ be n pairs of integer values. They are lexicographically sorted if, for all $i \in [1; n-1]$, the following conditions hold:

a_i ≤ a_{i+1}
a_i = a_{i+1} implies that b_i ≤ b_{i+1}.

Consider the problem of lexicographically sorting n pairs of integer values.

(a) Suggest the opportune data structure to handle the pairs, write the pseudo-code of an efficient algorithm to solve the sorting problem and compute the complexity of the proposed procedure.

A possible data structure to handle properly the pairs and provide a solution to the sorting problem could be an array of pairs. To do so an implementation of Lexicographical ordering is needed in order to pass it as total order of a sorting algorithm that work through comparison. Practically, these are the steps to follow:

```
def lexicographical_order(a,b):
    return a[0] < b[0] || (a[0]=b[0] && a[1] <= b[1])
enddef

def soritng_lexicographically(A, lexicographical_order):
    return heapsort(A, total_order = lexicographical_order)
enddef</pre>
```

In the solution proposed above I used as sorting algorithm heapsort (or equivalently it can be used quicksort but there could be some problems concerning complexity in worst case scenarios) which has complexity $\in O(nlog(n))$, and actually is the best reachable time complexity for this kind of algorithms based on comparison (using *insertion sort* for example would have produced same results but with worse complexity, $O(n^2)$).

(b) Assume that there exists a natural value k, constant with respect to n, such that $a_i \in [1, k]$ for all $i \in [1, n]$. Is there an algorithm more efficient than the one proposed as solution of Exercise 4a? If this is the case, describe it and compute its complexity, otherwise, motivate the answer.

In this particular case we know a priori the range of values that a_i can assume. We can take advantage from this aspect by using Counting Sort algorithm for sorting first elements of the pairs, moreover doing this in linear time (since complexity of Counting Sort is O(n+k)). First of all we need to slightly change the algorithm previously described since we want to separate sorting procedure for a and b elements in the pairs, and this translates in basically define a new total order to sort pairs only w.r.t. a and b. Then we can procede with sorting first with respect to b and then with respect to a.

```
def pair_order_a(a,b):
    return a[0] <= b[0]
enddef

def pair_order_b(a,b):
    return a[1] <= b[1]
enddef

def new_sorting_lexicographically(A, pair_order_a, pair_order_b):
    heapsort(A, total_order = pair_order_b)
    counting_sort(A, total_order = pair_order_a)
enddef</pre>
```

It's clear that this additional information doesn't enhance complexity at all

because the algorithm will still be bounded by the complexity of *heapsort*. To take a look at this consideration more in detail:

$$T(n) = O(nlog(n)) + \theta(n+k) \in O(nlog(n))$$

(c) Assume that the condition of Exercise 4b holds and that there exists a natural value h, constant with respect to n, such that $b_i \in [1, h]$ for all $i \in [1, n]$. Is there an algorithm to solve the sorting problem more efficient than the one proposed as solution for Exercise 4a? If this is the case, describe it and compute its complexity, otherwise, motivate the answer.

Contrarly to previous case, Counting Sort can be used to sort both pairs' components. The updated algorithm will be:

```
def new_sorting_lexicographically(A, pair_order_a, pair_order_b):
    counting_sort(A, total_order = pair_order_b)
    counting_sort(A, total_order = pair_order_a)
enddef
```

Finally we can observe that in this case, time complexity is improved:

$$T(n) = \theta(n+h) + \theta(n+k) \in \theta(n)$$