

Introducing an AR Model

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Mathematical Decription of AR(1) Model

today value = mean + phi * yesterday's value + noise $R_t = \mu + \phi R_{t-1} + \epsilon_t$

- Since only one lagged value on right hand side, this is called:
 - AR model of order 1, or
 - AR(1) model
- AR parameter is ϕ =1 (random walk), =0(white noise)
- ullet For stationarity, $-1 < \phi < 1$ (to be stable and stationary)



Interpretation of AR(1) Parameter

R_t is a time series of stock returns

$$R_t = \mu + \phi R_{t-1} + \epsilon_t$$

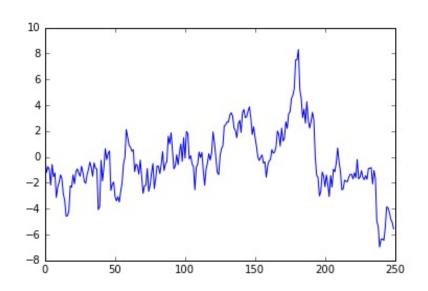
phi is negative, a positive return last period, at time t-1

- ullet Negative ϕ : Mean Reversion implies that this period's return is more likely to be negative
- Positive ϕ : Momentum a positive return last period implies that this period's return is expected to be positive

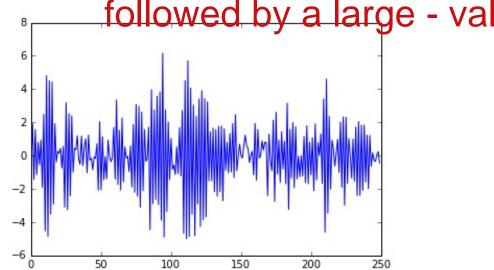


Comparison of AR(1) Time Series

ullet $\phi=0.9$ close to random walk

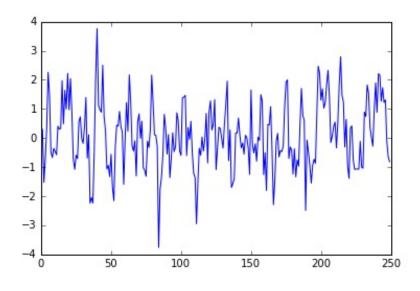


• $\phi = -0.9$ more erratic (a large + value is usually followed by a large - value)

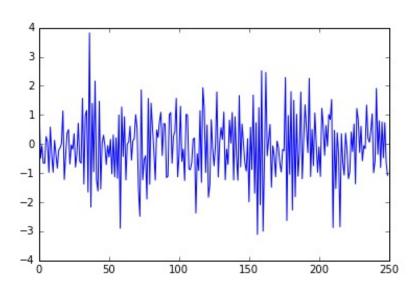


bottom two are similar, but are less exaggerated and closer to white noise

$$ullet$$
 $\phi=0.5$



•
$$\phi = -0.5$$

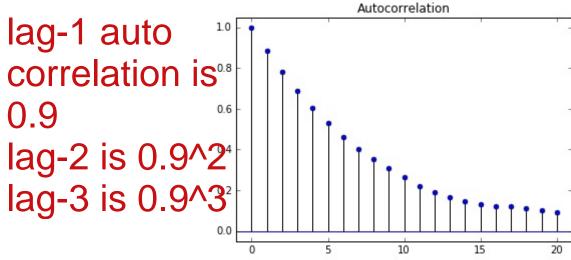


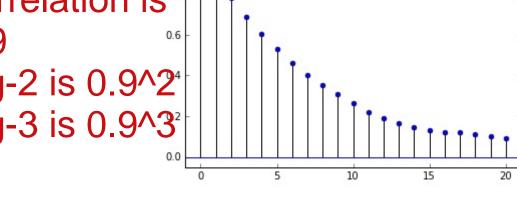


Comparison of AR(1) Autocorrelation Functions

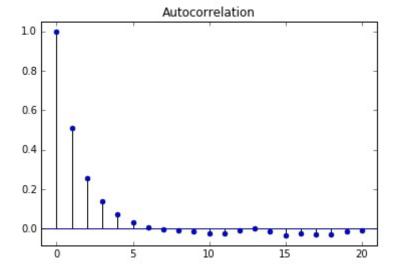
autocorrelation decays exponentially

• $\phi = 0.9$ of phi

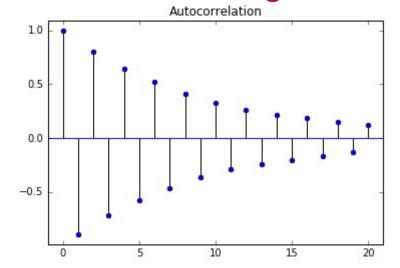




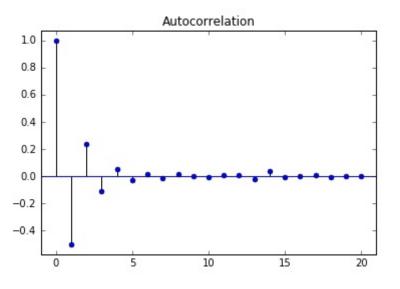
$$ullet$$
 $\phi=0.5$



autocorrelation function is still decays exponentialy, but the signs of acf reverse • $\phi = -0.9$ at each lag



•
$$\phi = -0.5$$



Higher Order AR Models

• AR(1)

can be extended to include more lagged values and more phi parameters.

$$R_t = \mu + \phi_1 R_{t-1} + \epsilon_t$$

• AR(2)

$$R_t = \mu + \phi_1 R_{t-1} + \phi_2 R_{t-2} + \epsilon_t$$

• AR(3)

$$R_t = \mu + \phi_1 R_{t-1} + \phi_2 R_{t-2} + \phi_3 R_{t-3} + \epsilon_t$$

• ...



Simulating an AR Process it is useful to work with simulated data

want to study and understand a pure AR process,

```
from statsmodels.tsa.arima process import ArmaProcess
ar = np.array([1, -0.9])
                              define order and parameters
ma = np.array([1])
AR object = ArmaProcess(ar, ma)
simulated data = AR object.generate sample(nsample=1000)
plt.plot(simulated data)
```

the convention is a little counterintuitive: must include the zero-lag coeff of 1, and sign of the other coeff is the opposite of what we have been using.

EX: AR(1) with phi=0.9 --> 2nd element of 'ar' array should be -0.9 this is consistent with the time series literature in the field of signal processing

also have to input MA parameters



Let's practice!





Estimating and Forecasting an AR Model

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Estimating an AR Model

• To estimate parameters from data (simulated)

```
from statsmodels.tsa.arima_model import ARMA
mod = ARMA(simulated_data, order=(1,0))
result = mod.fit()
.
```

```
create an instance of class called mod (data, order of the model) (1,0) mean --> fit the data to AR(1) (2,0) --> AR(2) 2nd part of order is MA part
```

.fit() to estimate model

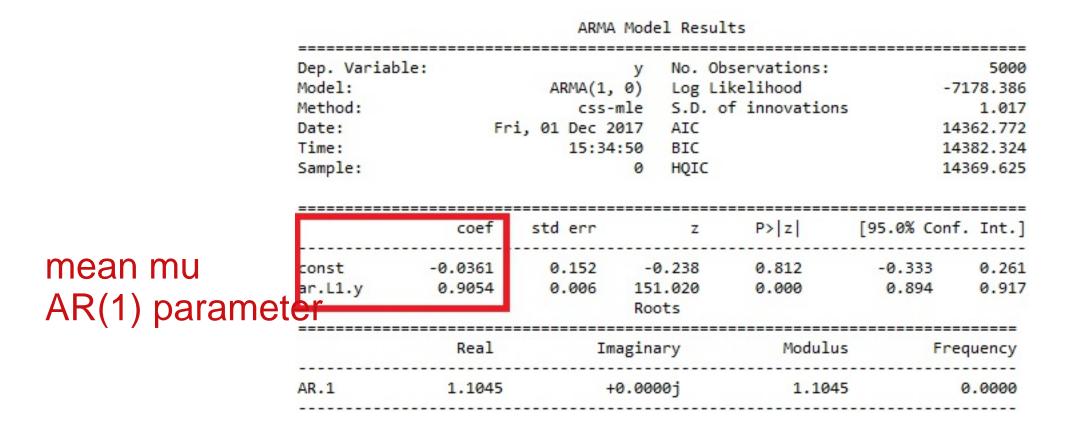


Estimating an AR Model

• Full output (true $\mu=0$ and $\phi=0.9$)

estimated parameters are very close to true parameters

print(result.summary())





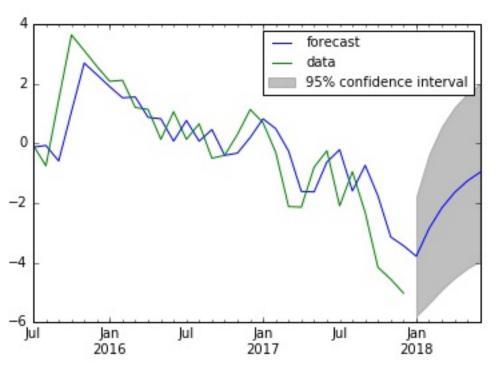
Estimating an AR Model

ullet Only the estimates of μ and ϕ (true $\mu=0$ and $\phi=0.9$)



Forecasting an AR Model

```
from statsmodels.tsa.arima_model import ARMA
mod = ARMA(simulated_data, order=(1,0))
res = mod.fit()
res.plot_predict(start='2016-07-01', end='2017-06-01') to do forecast
plt.show()
```



plot also gives confidence intervals around the out of sample forecasts.

notice how the confidence interval gets wider, the farther out the forecast is



Let's practice!





Choosing the Right Model

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in practice, you will ordinarily not be told the order of the model that you are trying to estimate



Identifying the Order of an AR Model

- The order of an AR(p) model will usually be unknown
- Two techniques to determine order
 - Partial Autocorrelation Function
 - Information criteria

Partial Autocorrelation Funcion (PACF)

measures the incremental benefit of adding another lag.

$$R_t = \phi_{0,1} + \phi_{1,1} R_{t-1} + \epsilon_{1t} \qquad \text{imagine running several regressions, where u regress} \\ R_t = \phi_{0,2} + \phi_{1,2} R_{t-1} + \phi_{2,2} R_{t-2} + \epsilon_{2t} \\ R_t = \phi_{0,3} + \phi_{1,3} R_{t-1} + \phi_{2,3} R_{t-2} + \phi_{3,3} R_{t-3} + \epsilon_{3t} \\ R_t = \phi_{0,4} + \phi_{1,4} R_{t-1} + \phi_{2,4} R_{t-2} + \phi_{3,4} R_{t-3} + \phi_{4,4} R_{t-4} + \epsilon_{4t} \\ R_t = \phi_{0,4} + \phi_{1,4} R_{t-1} + \phi_{2,4} R_{t-2} + \phi_{3,4} R_{t-3} + \phi_{4,4} R_{t-4} + \epsilon_{4t} \\ R_t = \phi_{0,4} + \phi_{1,4} R_{t-1} + \phi_{2,4} R_{t-2} + \phi_{3,4} R_{t-3} + \phi_{4,4} R_{t-4} + \epsilon_{4t} \\ R_t = \phi_{0,4} + \phi_{1,4} R_{t-1} + \phi_{2,4} R_{t-2} + \phi_{3,4} R_{t-3} + \phi_{4,4} R_{t-4} + \epsilon_{4t} \\ R_t = \phi_{0,4} + \phi_{1,4} R_{t-1} + \phi_{2,4} R_{t-2} + \phi_{3,4} R_{t-3} + \phi_{4,4} R_{t-4} + \epsilon_{4t} \\ R_t = \phi_{0,4} + \phi_{1,4} R_{t-1} + \phi_{2,4} R_{t-2} + \phi_{3,4} R_{t-3} + \phi_{4,4} R_{t-4} + \epsilon_{4t} \\ R_t = \phi_{0,4} + \phi_{1,4} R_{t-1} + \phi_{2,4} R_{t-2} + \phi_{3,4} R_{t-3} + \phi_{4,4} R_{t-4} + \epsilon_{4t} \\ R_t = \phi_{0,4} + \phi_{1,4} R_{t-1} + \phi_{2,4} R_{t-2} + \phi_{3,4} R_{t-3} + \phi_{4,4} R_{t-4} + \epsilon_{4t} \\ R_t = \phi_{0,4} + \phi_{1,4} R_{t-1} + \phi_{2,4} R_{t-2} + \phi_{3,4} R_{t-3} + \phi_{4,4} R_{t-4} + \epsilon_{4t} \\ R_t = \phi_{0,4} + \phi_{1,4} R_{t-1} + \phi_{2,4} R_{t-2} + \phi_{3,4} R_{t-3} + \phi_{4,4} R_{t-4} + \epsilon_{4t} \\ R_t = \phi_{0,4} + \phi_{1,4} R_{t-1} + \phi_{2,4} R_{t-2} + \phi_{3,4} R_{t-3} + \phi_{4,4} R_{t-4} + \epsilon_{4t} \\ R_t = \phi_{0,4} + \phi_{1,4} R_{t-1} + \phi_{2,4} R_{t-2} + \phi_{3,4} R_{t-3} + \phi_{4,4} R_{t-4} + \epsilon_{4t} \\ R_t = \phi_{0,4} + \phi_{1,4} R_{t-1} + \phi_{2,4} R_{t-2} + \phi_{3,4} R_{t-3} + \phi_{4,4} R_{t-4} + \epsilon_{4t} \\ R_t = \phi_{0,4} + \phi_{1,4} R_{t-1} + \phi_{2,4} R_{t-2} + \phi_{3,4} R_{t-3} + \phi_{4,4} R_{t-4} + \epsilon_{4t} \\ R_t = \phi_{0,4} + \phi_{1,4} R_{t-1} + \phi_{2,4} R_{t-2} + \phi_{3,4} R_{t-3} + \phi_{4,4} R_{t-4} + \epsilon_{4t} \\ R_t = \phi_{0,4} + \phi_{1,4} R_{t-1} + \phi_{2,4} R_{t-2} + \phi_{3,4} R_{t-3} + \phi_{4,4} R_{t-4} + \epsilon_{4t} \\ R_t = \phi_{0,4} + \phi_{1,4} R_{t-1} + \phi_{1,4} R_{t-2} + \phi_{1,4} R_{t-3} + \phi_{1,4} R_{t-4} + \phi$$

is the lag-4 value of the partial acf, it represent how significant adding a fourth lag is when u already have 3 lags

coefficients in red boxes represent values of the partial autocorrelation function for different lags.



Plot PACF in Python

- Same as ACF, but use plot_pacf instead of plt_acf
- Import module

```
from statsmodels.graphics.tsaplots import plot pacf
```

Plot the PACF

```
plot_pacf(x, lags= 20, alpha=0.05)
```

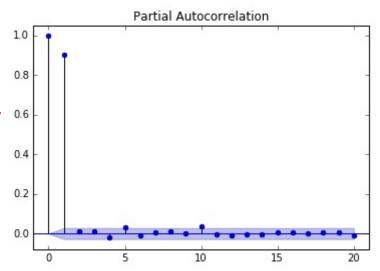
how many lags of pacf will be plotted alpha: set the width of the confidence interval



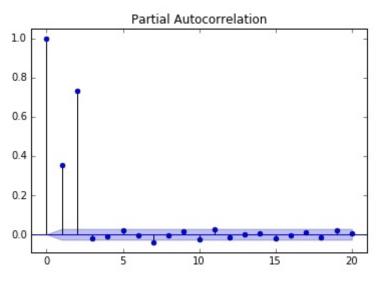
Comparison of PACF for Different AR Models

• AR(1)

only lag-1 pacf is significantly different from zero



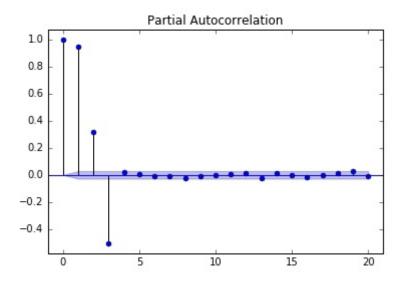
• AR(2)



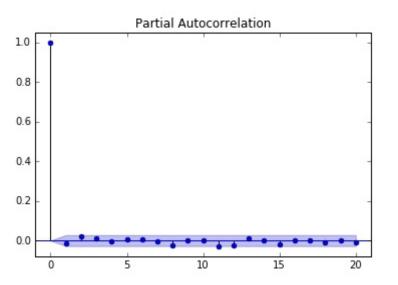
2 lags are different from zero

• AR(3)

3 lags are different from zero



• White Noise



no lags are significantly different from zero



Information Criteria

more parameters in a model, better the model will fit the data. but this can lead to overfitting of the data

- Information criteria: adjusts goodness-of-fit for number of parameters
- Two popular adjusted goodness-of-fit meaures
 - AIC (Akaike Information Criterion)
 - BIC (Bayesian Information Criterion)

by imposing a penalty based on the no of parameters used.



Information Criteria

Estimation output

		ARMA	Mode	l Res	ults		
Dep. Variable: Model: Method: Date: Time: Sample:	ARMA(2, 0)			No. Observations: Log Likelihood S.D. of innovations AIC BIC HQIC		2500 -3536.481 0.996 7080.963 7104.259 7089.420	
	coef	std err		z	P> z	[95.0% Con	f. Int.]
ar.L1.y		0.010 0.019 0.019	-32	.243		-0.015 -0.650 -0.348	-0.576
	Real	In	agina	ry Modulus		Frequency	
	-0.9859 -0.9859	+	1.498	_	1.7935 1.7935		-0.3426 0.3426



Getting Information Criteria From statsmodels

You learned earlier how to fit an AR model

```
from statsmodels.tsa.arima_model import ARMA
mod = ARMA(simulated_data, order=(1,0))
result = mod.fit()
```

And to get full output

```
result.summary()
```

• Or just the parameters

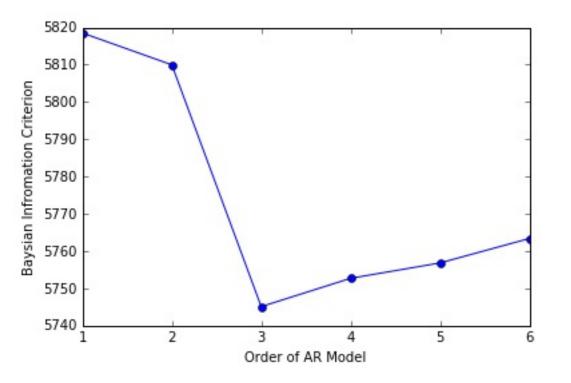
```
result.params
```

To get the AIC and BIC

```
result.aic
result.bic
```

Information Criteria

- Fit a simulated AR(3) to different AR(p) models
- Choose p with the lowest BIC



in practice, the way to use the info crieteria is to fit several models, each with a different no of parameters, and choose the one with the lowest BIC



Let's practice!